

Addressing Treatment Switching Bias with G-methods: Exploring the Impact of Model Specification

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Hazard

The following will specify the concepts of hazard ratio (HR), discrete hazard ratio (dHR) and cumulative hazard ratio (cHR) as used in this paper.

The hazard at time t of an event time T given covariates x is defined by Equation (1).

$$\lim_{\Delta \rightarrow 0} \frac{P(T \in [t, t + \Delta] | T > t, x)}{\Delta} = \lambda_x(t) \quad (1)$$

In case of a Proportional Hazards (PH) model it holds $\lambda_x(t) = \lambda_0(t) \cdot \text{HR}(x)$. Here, $\lambda_0(t)$ is the baseline hazards function and $\text{HR}(x)$ is a specific factor changing the hazard to a group of subjects with specific covariates x (e.g., indicator of assignment to experimental versus control group). In the PH model, it is assumed that $\lambda_0(t)$ holds for a well-defined baseline group (where all components of x are set to 0) and $\text{HR}(x)$ quantifies the change in hazard between a group of subjects defined by x and the baseline group.

Several of the approaches we apply model the expression $P(T \in [t, t + \Delta] | T > t, x)$ for small but fixed Δ by a logistic regression as shown in Equation (2).

$$P(T \in [t, t + \Delta] | T > t, x) = \frac{e^{LP(t, x)}}{1 + e^{LP(t, x)}} \quad (2)$$

Here the linear predictor $LP(t, x)$ depends on the time t and the covariates x (Equation (3)).

$$LP(t, x) = a_0 + a_1 \cdot t + a_2 \cdot t^2 + \sum_{i=1}^k b_i \cdot x_i \quad (3)$$

Given the small time interval $[t, t + \Delta]$ the probability that the event may happen is assumed to be quite small (Equation (4)),

$$P(T \in [t, t + \Delta] | T > t, x) \sim e^{LP(t, x)} = f(t) \cdot g(x) \quad (4)$$

The term $g(x)$ is called discrete hazard ratio (dHR) which is the product of odds ratios defined by the vectors b and x . It approximates the HR in case the proportional hazards assumption holds.

The cumulative hazard ratio (cHR) between two groups (defined by x and y) at time t is defined by Equation (5):

$$cHR_{t, x, y} = \frac{\log(P(T > t | x))}{\log(P(T > t | y))} \quad (5)$$

The expression is motivated by the structure of the PH model which implies (Equation (6))

$$P(T > t \mid x) = \exp \left(-HR(x) \int_0^t \lambda_0(s) ds \right) \quad (6)$$

In case of a PH model the $cHR_{t,x,y} = HR(x - y)$. It also holds that $dHR_{t,x,y} = g(x - y)$ which approximates the HR in case the PH assumption is fulfilled.