

[Return to "Self-Driving Car Engineer" in the classroom](#)

Finding Lane Lines on the Road

REVIEW

CODE REVIEW

HISTORY

Meets Specifications

Hello, Congratulations, on meeting all of the specifications. keep this up!

I must tell you I enjoyed reviewing your project and this was one of the best projects I have reviewed so far!!

Just a suggestion with the more possible improvements:

1. Image from infrared camera.
2. Adding a outlier reduction approach like RANSAC on the hough lines.
3. Using curve fitting to plot the curve instead of straight lines

For further reference :

Ransac: https://udacity-reviews-uploads.s3.us-west-2.amazonaws.com/_attachments/50281/1516262752/RANSAC.pdf

Good luck with with your Self Driving Car Nanodegree. I hope you will put all the effort in learning about self driving cars further on as well!

Thanks!

Required Files

The project submission includes all required files:

- Ipython notebook with code

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