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Multimodal Summarization and Beyond

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CERTIFICATE

This is to certify that the project titled "Multimodal Summarization and Beyond" is the bonafide work carried out by Aman Khullar (708/IT/15) student of B.E. (Information Technology) of Netaji Subhas Institute of Technology, Delhi (University of Delhi) in partial fulfillment of the requirements for the Bachelor Thesis Project (BTP) in the period of January 2019 to May 2019 of Bachelor of Engineering Information Technology.

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Declaration

This is to certify that the work which is hereby being presented by me in this project titled "Multimodal Summarization and Beyond" in partial fulfillment of the award of the degree of Bachelor of Engineering submitted to the Division of Information Technology, Netaji Subhas Institute of Technology Delhi, is a genuine account of my work carried out during the period from January 2019 to May 2019 under the guidance of Dr. Deepika Kukreja, Division of Information Technology, Netaji Subhas Institute of Technology, Delhi.

The matter embodied in the project report to the best of our knowledge has not been submitted for the award of any other degree elsewhere.

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Date:

ABSTRACT

The field of computer science was revolutionized in the year 1950 by a simple question posed by **A.M. Turing**, "Can machines think" and thought about the 'imitation game'. Since then the field of Artificial Intelligence has undergone several revolutionary reforms supported by the exponential hardware growth and improvement in the computation power. However giving machines the power to understand human language and allow it to generate required response is still a non trivial task. This thesis tackles the problem of multimodal summarization which is defined as the task of generating output summary taking into account the different multimedia data as input. The output summary may be presented in single modality or multiple modalities.

In this thesis, the foundations of natural language processing in general and multimodal summarization in specific have been explored. Since the field of Multimodal Summarization encompasses the textual, audio and visual dataset, the foundations of these modalities have been explored and further built upon. The baseline models have been implemented on our own dataset and the widely available dataset to explore the existent state of the art techniques.

The last part of this thesis presents the novel work of this thesis, the MultiModal Bidirectional Attention Flow Model (MMBiDAF). The architecture of the model has been carefully built to integrate all the modalities and draw similarity between them to carefully generate the text which is attentive of both image and audio which further receives an attention layer to select from the audio-aware or the image-aware text. The model is then able to generate a summary by extracting the most important sentences from the given source text. The results of the model have shown to outperform the existing state of the art models in the literature.

The thesis finally concludes by giving scope of the possible future work to further improve upon this model and achieve results to infinity and beyond!

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Lastly, I dedicate this thesis to my parents, sisters and Shona who have shown me light in the darkest of times and have helped me to find hope when I was stuck in problems in completing the project and life in general. I am grateful to their constant support and hope this thesis allows me to present the knowledge that I have gathered throughout my undergraduate life. I would again like to thank Shona who has been my companion throughout and whom I know for sure will remain by side forever. Thank you Shona.

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1. Introduction

The field of computer science was revolutionized in the year 1950 by a simple question posed by **A.M. Turing**, "Can machines think" and thought about the 'imitation game'[1]. Since then the field of Artificial Intelligence has undergone several revolutionary reforms supported by the exponential hardware growth and improvement in the computation power.

The field of **Natural Language Processing** is a relatively new task in the field of Artificial Intelligence. It requires the machine to understand human language and allow it to generate required response. This is not a trivial task since the machine needs to comprehend the human language which in itself is one of the most remarkable creations of human beings and is a gift which has been passed to us through generations.

To process a passage of text, the NLP community has put decades of efforts into solving different tasks for various aspects of text understating, including:

- (a) **Part-of-speech tagging.** It is the process of marking up a word in a text corpus as corresponding to a particular construct in linguistics. It is similar to identifying whether a word is a noun, verb, adjective, adverb or any other construct of the language.
- (b) **Named-entity recognition.** It is the task of entity recognition which encompasses entity identification, entity chunking and entity extraction. It allows the machine to recognize entities and categorize them in a sentence as the name of a person, organization, location or other proper nouns.
- (c) **Syntactic parsing.** It is the process of understanding the relationship between various parts of the sentence if the sentence conforms to the rules of the formal grammar. It is important for the language to conform to the rules of the grammar and hence the machine must understand the formal rules.
- (d) **Coreference resolution.** It is important for the machines to understand the entity about whom the text is talking about. The task of identifying the subject when a pronoun is used in place of the explicit definition of the subject in the sentence is referred to as coreference resolution. For example, the task of identifying who is subject in the sentence: "She is going to the research lab" when the corpus contains two subjects namely, Vega and Polaris.

Even though entire corpus containing natural language is important, it sometimes includes information that is not as important as other information and is rather an extension of the main parts used to make things clear. As a result in this age of quick access to information, it has become important for us to obtain the salient information of

text and understand the complete meaning of the text. This is the main goal of **text** summarization.

Multimodal summarization is a superset of text summarization and is defined as the task of generating output summary taking into account the different multimedia data as input. The output summary may be presented in single modality or multiple modalities. The ongoing research has proven that inclusion of audio and video elements as a part of the dataset may greatly improve the output summary. The output summary will be able to take into account the audio and the visual features along with text as input.

The motivation for this work was obtained in my Seventh semester while I was working on a project in machine comprehension. I wanted to build a system which could summarize documents for the people with special needs. I wanted to build a system which could summarize the text in such a manner that the people with special needs are able to understand any text without much difficulty. Though I tried to gain suggestions for this work through various Professors and psychology resources, I was unable to get the required dataset for this task. However, while I was working towards this goal, I was introduced to the problem of multimodal summarization and this allowed me to enhance my skills and explore more opportunities in the field of NLP while working towards the task of text summarization for social good.

Chapter I Multimodal Summarization: Foundations

2. Automatic Text Summarization

Automatic text summarization is the process of shortening the available information and presenting only the important parts of text to avoid information overload. This task has become increasingly important today because of the requirement of quick access and understating of the complete document or a list of documents. As a result this task has become an active area of research among the NLP community researchers. Automatic text summarization allows the machine to handle this task of shortening the document for human feasibility. The application of text summarization is being increasingly realized in fields beyond computer science including medicine, law and search results on the World Wide Web.

The literature defines two methods for obtaining the summary of the text which are namely:

- (a) **Extractive summarization.** Extractive summaries are those that are produced through a process where the text's most important sentences are concatenated together without altering the sentences in any way. In other words, this method of summary generation works by simply "extracting" the most relevant sentences from a text. This method is similar to human beings highlighting the most important sentences in a text. Similarly the machine performs the task of finding the most important sentences in the document or across documents through a defined algorithm and combines those sentences to produce an output summary.
- (b) Abstractive summarization. Abstractive summaries are those in which the important themes from a text are identified and then new sentences are generated based upon a deeper understanding of the material. In other words, abstractive summaries are those created using a more "abstract" understanding of the material to generate a new sentence representation of it. The technique of abstractive summarization is akin to the human beings generating notes from the given the text document. Hence similar to the task performed by humans, the machine first understands and comprehends the natural language and then generates sentences word by word from the output vocabulary. The output may hence sometimes contain words which are not present in the input data which is never possible in corresponding extractive summarization.

2.1 History

2.1.1 Early Approaches

The work in the field of automatics summarization has been going on for a long time now and is being actively improved upon with new state-of-the-art techniques replacing the traditional automatic summarization models. H.P. Luhn's seminal work[2] of automatically creating literature abstracts was based on the correlation of frequency with importance of a word in a sentence. The various traditional tasks for identification of important sentences sentences is as follows:

2.1.1.1 Identifying Important Sentences

The first task of extractive summarization is to be able to find a metric through which the computer shall be able to identify and rank the importance of various sentences occurring in the document. Several salience measurement techniques have been proposed in the literature and the earliest approaches regarded the frequency of a word's occurrence as a factor of significance of word and in his pioneer work [2], H.P. Luhn defined the significance of a sentence as being contingent with the significance of the contained words. He defined significance of a word as:

$$significance(w) = p(w) = \frac{c(w)}{N}$$

Where : p(w) = Probability of a word, w occurring

c(w) = Number of times a word w occurs in the input (frequency)

N = Total number of words in the input

2.1.1.2 TF * IDF Weighting

It is the Term Frequency * Inverse Document Frequency (TF * IDF) [3] metric which signifies the importance of the word. It is based on the idea that the most important words are those that occur frequently within given document but infrequently in other documents of same genre. It is calculated as follows:

$$TF * IDF = c(w) * \log \frac{D}{d(w)}$$

Where : c(w) = Number of times a word w occurs in the input (frequency)

d(w) = Size of background corpus

D = Size of document corpus

2.1.1.3 Graph Based Methods

These methods incorporate word-frequency into a formalized framework within which the sentence-to-sentence relationship is analyzed. The main assumption of these algorithms are that the sentences which are most similar to other sentences within a document or across various documents are the most salient sentences and need to be included summary. In order to find the most central sentences, graph-based models build a graph in which sentences are the vertices in the graph with edges connecting related sentences. The notion of "Related Sentences" is quantified by a similarity metric that is used as an edge weight between the two vertices. The cosine similarity is the most widely used metric which takes into account the vector representation of the sentences using the TF*IDF weights. In order to use this method, sentences are taken as N-dimensional vectors where N is the number of uniquely occurring words in the document. Each of the vector values are initialized to 0 and then for each word in the sentence, the corresponding element in the N-dimensional vector is set to that word's TF*IDF weight. [4]

$$V(s_i) = \langle f_{w_1}, f_{w_2}, ..., f_{w_n} \rangle$$

where:

$$f_{w_i} = \begin{cases} TF * IDF(w_j), & if \ w_j \in s_i \\ 0, & otherwise \end{cases}.$$

The cosine similarity between two sentences is then given by:

Cosine Similarity(s1,s2) =
$$\frac{V(s_1) \cdot V(s_2)}{||V(s_1)|| ||V(s_2)||}$$

2.1.1.4 Degree Centrality

This is a graph analytics technique. It is defined as the in-degree of its corresponding node in the similarity graph. Hence in order to calculate the degree centrality, a similarity graph must first be constructed and then only the sentences which have a similarity greater than a particular threshold must be selected.

2.1.1.5 Lex Rank

LexRank [5] is an unsupervised approach to text summarization based on graph-based centrality scoring of sentences and the PageRank algorithm[6]. The main idea is that sentences "recommend" other similar sentences to the reader. Thus, if one sentence is very similar to many others, it will likely be a sentence of great importance. The

importance of this sentence also stems from the importance of the sentences "recommending" it. Thus, to get ranked highly and placed in a summary, a sentence must be similar to many sentences that are in turn also similar to many other sentences. This makes intuitive sense and allows the algorithms to be applied to any arbitrary new text. The constructed graph included directed edges connecting sentences in a binary fashion; two sentences were connected only if their cosine similarity was greater than a given threshold value. After generating the graph, PageRank was applied to the graph which ranked and extracted the sentences on order of their PageRank scores. Erkan & Radev found that this method was able to extract the most important sentences of the document, in the best case, better than all other baselines of the time. Another algorithm very similar to Lex Rank is Text Rank[7] which uses a slightly different metric for sentence similarity and can only be applied for single-document summarization while Lex Rank can be applied for multi-document summarization.

2.1.2 Machine Learning Approaches

The advances in the field of machine learning have had a major impact on the task of automatic text summarization. With increasing number of features including word frequency, sentence location, sentence length, and title composition being suggested for use in identifying salience, having a statistical means to determine the best combination of such features is incredibly valuable. The main drawback for machine learning methods is however the unavailability of labeled data which needs to be generated in order to be able to produce good results and allow the algorithms to train on the labeled data and produce their own hypothesis.

2.1.2.1 Naive-Bayes Methods

Kupiec et al. described a method that is able to learn from data in 1995 [8] The features they were looking at included the following:

- Sentence length: Comparison of length of sentence with a specific threshold value.
- **Fixed-Phrase**: If the sentence contains a specific phrase.
- Location in Paragraph: Where does the sentence occur in the text (Only paragraphs that occur towards the beginning and end of the document are considered).
- Thematic Words: If the sentence contains many frequently occurring words.
- Uppercase Words: If the sentence includes many uppercased words.

Their results indicated that a combination of location in paragraph, fixed-phrase, and sentence length yielded the best results with the incorporation of thematic words actually leading to poorer performance. Even though they were able to achieve good results but their results were based on the Naive-Bayes assumption which states that the probability of occurrence of each sentence is independent of each other. However this assumption is not completely true since their exists sequential dependence in natural language.

2.1.2.2 Hidden Markov Model

In contrast with the existing feature based approaches for extracting the most important sentences, the Hidden Markov Model (HMM) Conroy and O'leary[9] modeled the problem of extracting sentences using HMM and to incorporate the sequential dependence of sentences and relax the assumption of independence required by the Naive Bayes Classifier. They predicted that the probability of one sentence being included in a summary is dependent upon whether or not the previous sentence was included. This hypothesis naturally motivates the use of an HMM, as the model does not require independence between sentence i and sentence i–1. They found that this model outperformed all the existing baseline models at that time since they took the sequential dependence of the sentences into account.

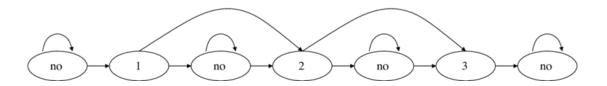


Figure 1: Markov Model to extract upto three sentences from a document.

2.1.3 A Resurgence : Deep Learning Era

Yan LeCun, Yoshua Bengio and Geoffrey Hinton were awarded the Turing Award for conceptual and engineering breakthroughs that have made deep neural networks a critical component of computing in March 2019. In their Review paper [10], they have defined Deep Learning methods as "representation learning methods with multiple levels of representation, obtained by composing simple but non-linear modules that each transform the representation at one level (starting from raw input) into a representation at a higher, slightly more abstract level." Representation learning is the set of methods that allow the machines to be fed with raw data and they then automatically discover the representations required for detection and classification. Rumelhart et al. [11] in their breakthrough paper on the experimental proof that backpropagation can generate useful internal representation of incoming data in the hidden layers of neural networks. Since then backpropagation (Figure 2) has been used extensively to calculate gradients of various loss functions with respect to various parameters in computationally efficient manner.

One of the most beautiful aspects of deep learning is that it does not require humans to design layers and incorporate features. The network learns the features itself with the help of data and greater the number of layers of artificial neurons, greater is the non linearity and the network is able to capture higher dimensional classification tasks with even more accuracy. This however comes at the cost of higher computation requirement.

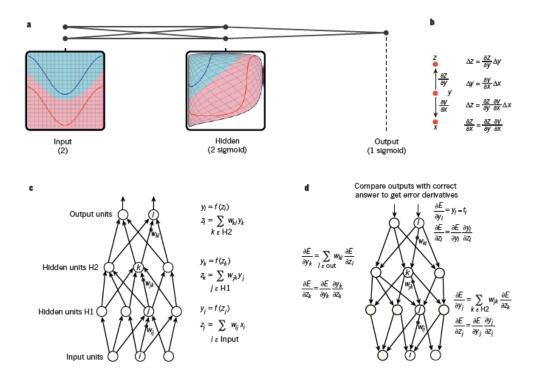


Figure 2: Multilayer neural networks and backpropagation. (a) A multilayer neural network can distort the input space to make the classes of data linearly separable. (b) Chain rule depicts how small changes are propagated. (c) The equations are used for computing the forward propagation in a neural network with two hidden laters and one output layer. (d) The equations used for computing the backward pass. At each hidden layer, the error derivatives are calculated with respect to the output of each hidden unit.

The field of Natural Language Processing went through a complete resurgence when the state of the deep learning techniques were applied to understand the text. The sequential learning required for understanding the natural language was obtained by the recurrent neural networks which remembered the previous hidden state of the neural network and computed the next hidden state as a linear transformation of the concatenated input and the previous hidden state. The recurrent neural networks gave the power of memory to the deep learning models.

2.1.3.1 Recurrent Neural Networks

Recurrent neural networks (RNNs) process the next hidden state taking into account the previous hidden state. They process an input sequence one element at a time, maintaining in their hidden units a 'state vector' that implicitly contains information about the history of all the past elements of the sequence. The unrolled version of the RNNs allow us to visualize how we consider the outputs of the hidden units at discrete time units.

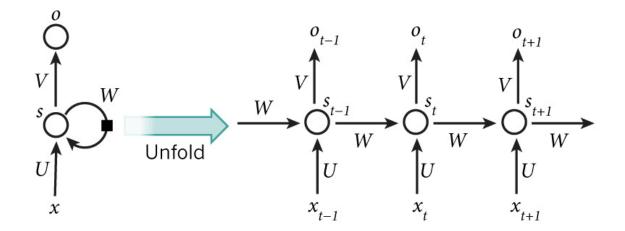


Figure 3: An unrolled recurrent neural network., where x corresponds to inputs at discrete time steps, s corresponds to hidden state at distinct time step and o corresponds to the output at discrete time step.

Because of the powerful memory elements and the efficient backpropagation techniques, the use of recurrent networks in language modeling has become ubiquitous however the problem there exists the problem of exploding or vanishing gradients over the various timesteps. Several reforms have been done with new recurrent units being introduced to tackle the problem of gradients over the time steps however this problem still exists in training the RNNs. These problems in training recurrent networks have been explained as follows:

- (a) **Vanishing gradient.** The gradients with respect to inputs occurring much earlier in the neural network become increasingly less with the increasing time steps. It can be visualized as the effect of a word which occurs much earlier in the text does not have any influence over the word that shall be predicted next in language modeling. This is a major problem since the number of timesteps over which this problem occurs is extremely less.
- (b) **Exploding gradient.** This is the other extreme of vanishing gradient. In this problem, the gradient of the function with respect to inputs occurring in the past keeps on increasing at each time step. This makes the word that is being predicted next, heavily dependent on the word that occurred a long time back. This is also a major problem during training time.

The RNN model is defined mathematically by the following equations:

$$\begin{split} s^{(t)} &= sigmoid(W_s s^{(t-1)} + W_x x^{(t)} + b_1) \\ \hat{y} &= softmax(U s^{(t)} + b_2) \\ P(x^{(t+1)} &= w_j | x^{(t)}, x^{(t-1)}, \dots, x^{(1)}) = \hat{y}_j^{(t)} \end{split}$$

Where s is the hidden state, x is the network input and y is the network output.

2.1.3.2 Long Short Term Memory

To counter the existing problem of vanishing gradient, the researchers in the NLP community came up with a special type of RNN cell called the Long Short Term Memory. Though this memory cell is much more complex than the Vanilla RNN but it captures the long-term language dependencies extremely well. They were introduced by Hochreiter & Schmidhuber [12] in 1997.

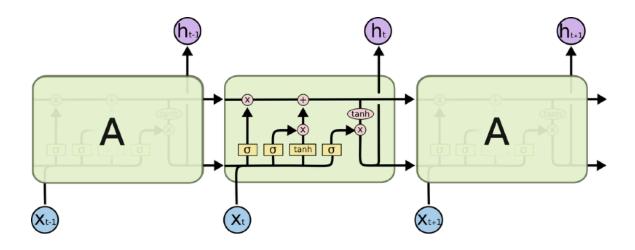


Figure 4: The repeating module in an LSTM contains four interacting layers [13].

The LSTMs are able to overcome the problem of vanishing gradients with the help of cell state which is the horizontal line running on top of the repeating modules. This cell state flows through all the time steps without much change. The gates in the cell unit allow the information to be added or subtracted in during the recurrent time steps. The LSTMs can be beautifully explained through mathematical equations in a manner similar to the recurrent neural networks. The step by step walkthrough over the various gates of the LSTM can be done as follows:

(a) Forget gate layer. This gate decides which information to keep and which information to discard. It is useful in language modeling when we encounter a new subject and wish to forget the information about the previous subject. This is mathematically described in the following manner.

Forget Gate:
$$f_t = \sigma(W^{(f)}x_{(t)} + U^{(f)}h_{(t-1)} + b_{(f)})$$

(b) **Input gate layer.** This decides which values need to be updated. The equation of the input gate can be mathematically described in the following manner.

Input Gate:
$$i_t = \sigma(W^{(i)}x_{(t)} + U^{(i)}h_{(t-1)} + b_{(i)})$$

(c) Candidate gate. The input value and the hidden state can be combined and passed through a tanh function to get new candidate values and this is described in following manner.

Candidate Gate:
$$\tilde{C}_t = \tanh(W^{(c)}x_{(t)} + U^{(c)}h_{(t-1)} + b_{(c)})$$

(d) **Update gate.** The new cell state is calculated by taking into account the information we needed to forget and the new information we decided to include in the cells state. The equation for the update gate is given in the following manner.

Update Gate:
$$o_t = \sigma(W^{(o)}x_{(t)} + U^{(o)}h_{(t-1)} + b_{(o)})$$

(e) **Output state.** The output state is a combination of the input that we need to include as well as the previous inputs that we need to forget. It is the addition operator which does the magic in this gate.

Cell State :
$$C_t = f_t \circ C_{t-1} + i_t \circ \tilde{C}_t$$

(f) **Output.** The output is a combination of the output state as well as the candidate gate and produces the combined result to produce the output.

$$Output : h_t = o_t \circ \tanh(C_t)$$

As a result we obtain the hidden state through the LSTM network and have thus resolved the vanishing gradient problem. The problem of gradient explosion is solved through **gradient clipping** in which the gradient is clipped as soon as it reaches a certain threshold value. This technique has been found to perform well in practice.

2.1.3.3 Encoder-Decoder Architecture with Attention

The various tasks of NLP are currently being completed with the encoder-decoder architecture which is extremely popular for the tasks involving sequences. The main aim of this architecture is to encode the input embedded sequence into an encoded vector representation and then to decode this vector representation using a decoder architecture. The encoder decoder architecture had been first performed for the task of neural machine translation and had then been applied to perform carious other tasks including text summarization and various current state of the art models use the Encoder-Decoder architecture as the baseline model.

The encoder is responsible for encompassing the sequential information of the source words and in turn creating a hidden representation of these input words which takes into account their dependence on the previous words. If a bidirectional encoder has been used, then the words encode information from both the directions namely forward and backward. The **encoder** can be mathematically described as follows:

Let T_x , T_y denote the lengths of the source and the target sentences. Then the words in the source sentence are embedded into a fixed size (K) representation using either pertained GloVE embeddings, Word2Vec embeddings or embeddings that can be learnt.

The input (x) and the target sentences (y) are then given as:

$$x = (x_1, ..., x_{T_x}); x_i \in \mathbb{R}^{K_x}$$

 $y = (y_1, ..., y_{T_y}); y_i \in \mathbb{R}^{K_y}$

where each word is a K-dimensional word vector.

Computing the forward state of the Bidirectional RNN:

$$\overrightarrow{h_i} = \begin{cases} (1 - \overrightarrow{z_i}) \odot \overrightarrow{h_{i-1}} + \overrightarrow{z_i} \odot \overrightarrow{h_i} & if \ i > 0 \\ 0 & if \ i = 0 \end{cases}$$

where:

$$\begin{split} \overrightarrow{h_i} &= tanh(\overrightarrow{W} \vec{E}_{x_i} + \overrightarrow{U} [\overrightarrow{r_i} \odot \overrightarrow{h_{i-1}}]) \\ \overrightarrow{z_i} &= \sigma(\overrightarrow{W_z} \vec{E}_{x_i} + \overrightarrow{U_z} \overrightarrow{h_{i-1}}]) \\ \overrightarrow{r_i} &= \sigma(\overrightarrow{W_r} \vec{E}_{x_i} + \overrightarrow{U_r} \overrightarrow{h_{i-1}}]) \end{split}$$

 $\bar{E} \in \mathbb{R}^{m \times k_z}$ is the word embedding matrix and \overrightarrow{W} , $\overrightarrow{W_z}$, $\overrightarrow{W_r} \in \mathbb{R}^{n \times m}$, \overrightarrow{U} , $\overrightarrow{U_z}$, $\overrightarrow{U_r} \in \mathbb{R}^{n \times n}$ are weight matrices. Where m is the word embedding dimensionality and n is the number of hidden units.

The hidden state of the **decoder** is given as follows:

$$s_i = (1 - z_i) \odot s_{i-1} + z_i \odot \tilde{s}_i$$

where:

$$\begin{split} \tilde{s}_i &= tanh(WE_{y_{i-1}} + U[r_i \odot s_{i-1}] + Cc_i) \\ z_i &= \sigma(W_zE_{y_{i-1}} + U_zs_{i-1} + C_zc_i) \\ r_i &= \sigma(W_rE_{y_{i-1}} + U_rs_{i-1} + C_rc_i) \end{split}$$

E is the word embedding matrix for the target language and the weight matrices are given by $W, W_z, W_r \in \mathbb{R}^{n \times m}, U, U_z, U_r \in \mathbb{R}^{n \times n}, C, C_z, C_r \in \mathbb{R}^{n \times 2n}$ are weight matrices. Where m is the word embedding dimensionality and n is the number of hidden units. The initial hidden state s_o is computed by $s_o = tanh(W_s \overrightarrow{h_1})$, where $W_s \in \mathbb{R}^{n \times n}$.

The normal encoder decoder architecture though is a major breakthrough for the sequence to sequence tasks however it has one major problem that is the inclusion of all the hidden states into a single encoder representation. This shortcoming has been overcome through the use of the **attention model** [14] which allows the decoder to specifically attend to specific regions of the encoder output to produce a result at each

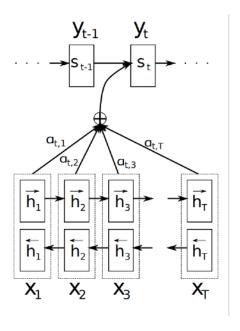


Figure 5: Attention vectors to specific encoder outputs.

time step. The architecture for the attention-based sequence model has been specified in Figure 5 and the calculation of the context vectors is described as follows:

 $c_i = \sum_{j=1}^{T_x} \alpha_{ij} h_j$

where

 $\alpha_{ij} = \frac{\exp(e_{ij})}{\sum_{K=1}^{T_x} \exp(e_{ik})}$

and

$$e_{ij} = v_a^T tanh(W_a s_{i-1} + U_a h_j)$$

 h_j is the j^{th} annotation in the source sentence and $V_a \in \mathbb{R}^{n'}$, $W_a \in \mathbb{R}^{n \times n}$, $U_a \in \mathbb{R}^{n' \times 2n}$ are the weight matrices.

Though sequence to sequence models with attention were introduced for machine translation, they are widely being used for abstractive as well extractive text summarization and are therefore very important in today's state of the deep learning era.

2.2 Task Definition

2.2.1 Problem Formulation

The task of text summarization can be formulated as a supervised learning problem: given a collection of training examples $\{(p_i, a_i)\}_{i=1}^n$, the goal is to learn a predictor f which takes a passage of text p as inputs and gives the summarized passage a as output.

$$f: p \rightarrow a$$

Where $p=(p_1,p_2,...,p_{l_p})$ is the passage and the length of the passage being l_p and $a=(a_1,a_2,...,a_{l_a})$ is the output summary of length l_a and $l_a \leq l_p$. Moreover, each word in the input and the output text are represented in the form of a fixed dimension embedding and the embedding can be either pre-trained or can be learnt during train time. The summary that is produced at the output may be extractive or abstractive depending on the problem formulation.

2.2.2 Evaluation

Evaluating the generated summary with respect to the reference summary is non trivial task and through great efforts an adequate means of assessing the performance of the summarization system has been developed. Moreover the task of evaluation of text summaries is even more challenging because it is very arbitrary for different individuals. A sentence seemingly important to one person may not sound very important to the other while both being correct in their own ways. The evaluation metrics that have been used developed to assess the generated summary are also improving with active research going on the area of development of new metrics.

2.2.2.1 Recall and Precision

Recall and precision are the two most commonly used metrics to compare the generated summary with the reference summary. Nenkova and McKeown have defined precision and recall as "Recall is the fraction of sentences chosen by the person that are also correctly identified by the system and precision is the fraction of system sentences that were correct" [15]. In other words, precision is the fraction of true positives over sum of true positives and false positives while recall is the fraction of true positives over the sum of true positives and false negatives. The F1 metric is the harmonic mean of precision and recall. The recall metric is considered to be slightly more preferable when the summary lengths are not equal because of the manner in which humans classify the importance of sentences. The F1 metric however which is the harmon mean of the two is mostly the preferred metric in case of contention between the selection of appropriate metric to evaluate the results.

2.2.2.2 ROUGE

The Recall-Oriented Understudy for Gisting Evaluation (ROUGE) is a set of evaluation procedures that are able to automatically determine the quality of a generated summary in comparison to the reference summary where the reference summary is usually human annotated summary.

The ROUGE metric includes multiple variants including ROUGE-N (n-gram recall), ROUGE-L (longest common subsequence), ROUGE-S (Skip-Bigram Co-Occurrence Statistics) and ROUGE-W (Weighted longest common subsequence). For each ROUGE-N, there is calculation of the overlap between the generated summary and the system summary. For each ROUGE ngram result, there is precision, recall and F1 metric result in order to give researcher the flexibly of closing the most appropriate metric for evaluation.

2.3 Datasets and Models

2.3.1 CNN/Daily Mail Dataset

The CNN/Daily Mail dataset as processed by Nallapati et al. (2016) [16] has been used for evaluating summarization. The dataset contains online news articles (781 tokens on average) paired with multi-sentence summaries (3.75 sentences or 56 tokens on average). The processed version contains 287,226 training pairs, 13,368 validation pairs and 11,490 test pairs. Models are evaluated with full-length F1-scores of ROUGE-1, ROUGE-2, ROUGE-L, and METEOR (optional). This dataset is actively being used by the research community to solve the problem of text summarization in new and interesting ways.

2.3.2 Pointer Generator Networks Model

The Pointer Generator Networks [17] is a hybrid network that can choose to copy words from the source via *pointing*, while retaining the ability to *generate* words from the fixed vocabulary. It is one of the state of the art abstractive text summarization techniques. The posting mechanism improves the accuracy and handles the OOV words, while it also retains the ability to generate new words with the help of decoder over the output vocabulary. The network is a combination of extractive as well as abstractive summarization technique.

The pointer generator model was able to overcome two widely persistent problems in the field of abstractive summarization :

- (a) **Problem 1.** Summaries sometimes produced factual inaccuracies.
- (b) **Problem 2.** The summaries sometimes repeat themselves.

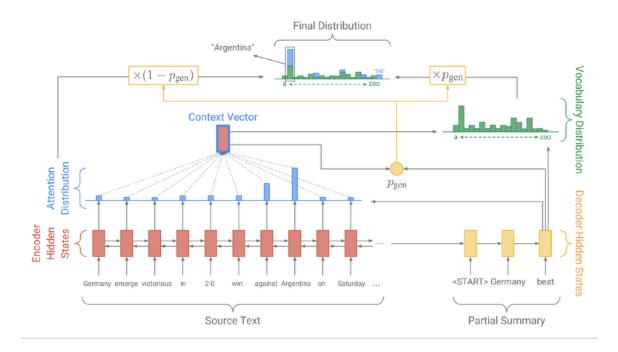


Figure 6: Pointer-generator model.

See et al. worked to solve these two problems and by producing the pointer-generator network a solution for the first problem of factual inaccuracies.

(a) **Solution 1.** Directly point to the source sentence rather than generating a word for that detail to maintain factual accuracy. The probability of generating or simply pointing can be defined in the following manner.

$$p_{gen} = \sigma(W_{h^*}^T h_t^* + W_s^T s_t + W_x^T x^t + b_{ptr})$$

Where:

 $h_t^* = \Sigma_i a_i^t h_i$ is the context vector calculated from the attention distribution a^t as defined in section 2.1.3.3, W_{h^*}, W_s, W_s and scalar b_{ptr} are learnable parameters or the weight matrices, σ is the activation function, s_t is the decoder state at timestep t and x_t is the decoder input at timestep t. The probability of generation, $p_{gen} \in [0,1]$ can therefore be calculated through these parameters.

This p_{gen} is used as a switch between generating a word from the vocabulary by sampling from P_{vocab} or copying a word from the input sequence by sampling from the attention distribution a^t . Hence the probability distribution over the extended vocabulary which is the union of the vocabulary and all the words given in the source document is given by P_w as described in the following equation.

$$P(w) = p_{gen}P_{vocab}(w) + (1 - p_{gen})\sum_{i:w_i = w} a_i^t$$

(b) **Solution 2.** Maintain a coverage vector to remember the sequence of words which have already arrived once in the summary and to reduce the probability of their repeated occurrence. The coverage vector is the sum all the attention distributions, which signifies the degree of coverage that those words have received from the attention mechanism so far and is given by the following equation:

$$c^t = \sum_{t'=0}^{t-1} a^{t'}$$

Where:

 c^t is the coverage vector and a^t is the attention distribution over each sentence at a single timestep.

2.3.3 Implementation Details of Pointer Generator Network

The pointer-generator network was implemented on both the CNN/Daily Mail dataset as well as our own dataset. The code originally implemented in Tensorflow version 1.0 has been trained on our own dataset after the suitable representation and preprocessing of the dataset. The dataset was first tokenized using the Stanford CoreNLP toolkit and then processed into .bin vocab files and the data was carefully chunked to meet the requirements for the dataset. The results obtained after training the pointer-generator network for 48hr on Nvidia TX2 server have been described as follows:

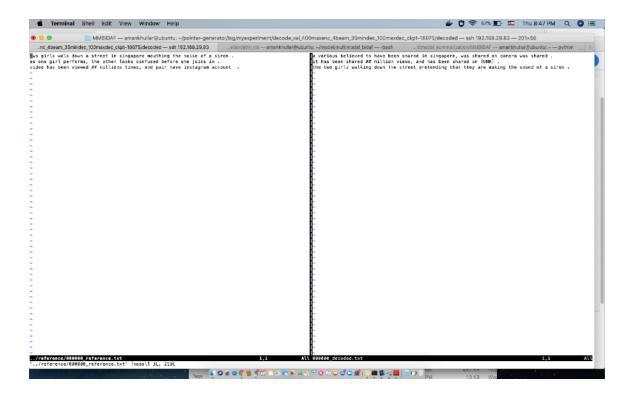


Figure 7: Decoded and reference summaries from the pointer-generator network.

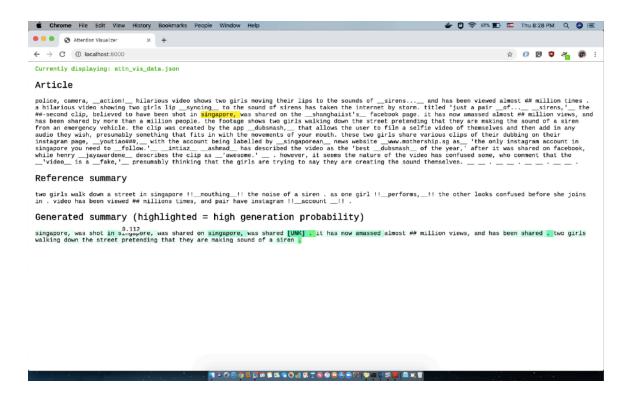


Figure 8: Attention visualization on CNN/Daily Mail dataset.

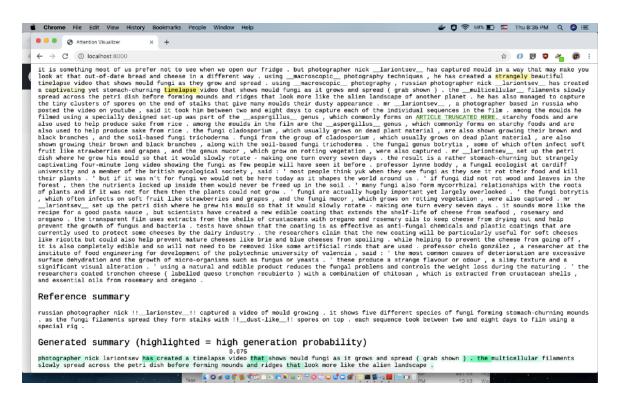


Figure 9: Attention visualization on our Dataset.

3. Speech Recognition

Speech recognition is the process of giving machines the power to understand natural language, process it and then comprehend it to present the result in the form of a text. This field is an interdisciplinary field which is a subfield of computational linguistics that develops techniques to allow machines to process and translate speech into text.

The task of multimodal summarization takes audio as one of the inputs from the dataset and it is therefore extremely necessary to process the audio in a form such that is is able to be matched with the synchronous text and and the correspond video keyframes. It is therefore necessary to extract the features from audio and then apply our recognition model to process it further more to achieve the required results.

3.1 History

3.1.1 Early Approaches

The work on speech recognition has been going on since half a century now with Bell Labs researchers, Stephen Balashek, R. Biddulph, and K. H. Davis building "Audrey" for single-speaker digit recognition in 1952 [18]. Though there was a lot of research on speech recognition and language understating in the following years but the major breakthrough came in the 1980s which saw the introduction of the n-gram language models. In the following years with the advancement in computing power, the speech recognition technology became more and more accurate.

3.1.2 Mel-Frequency Cepstral Coefficients

The mel-frequency cepstrum (MFC) is a representation of short-term power spectrum of sound and are very similar to the principle components of the log spectra. They are based on a linear cosine transform of a log power spectrum on a non linear mel scale of frequency.

The **mel-frequency cesptral coefficients** (MFCC) are the coefficients that together make up the MFC. They are derived from a non-linear or cepstral representation of an audio clip. The MFCCs are more commonly viewed as features for speech recognition systems. The MFCCs imitate the natural features that a human recognizes while listening to sound. They are therefore inspired from human auditory track.

3.2 Hidden Markov Models

The hidden Markov models are statistical models that take into account sequential input and output a sequence of symbols or quantities. They are widely used in speech recognition systems because speech can be visualized as a Markov model for many stochastic purposes.

The HMMs are also extremely popular because they can be trained automatically and are simple and computationally feasible to use. The output for the HMMs is obtained by taking into account the output of various previous timesteps where the number of previous outputs that need to be taken is a parameter than can be tuned. The vector input to the HMMs consist of the MFCC features and the output is generated by taking a probability distribution over each phoneme in the output.

3.3 End-to-End Speech Recognition

Since 2014, end-to-end speech recognition models have become the stalwarts in speech recognition technology. They are the current state of the art approach to solve the given problem statement. They are extremely powerful because they jointly learn all the components of a speech recognizer. As a result we do need to specify to the model any specific features that we think to be important to produce results. The model on the other hand self-learns the features it deems to be important through the provided data.

One of the major breakthroughs came with the "Listen, Attend and Spell" model [19] which applied the attention model used by Bahdanau et al. [14] for neural machine translation. The model has been described as follows:

3.3.1 Task Definition

Let $x = (x_1, x_2, ..., x_T)$ be the input sequence of filter bank spectra features (MFCCs) and $x = (y_1, y_2, ..., y_S)$ be the output sequence, a probability distribution over the output vocabulary. The task of the model is defined as the generation of probability of output y_i using the the outputs of the previous timesteps $y_{< i}$ and the input signal x_i for that timestep. It is formally defined as:

$$P(y|x) = \prod_{i} P(y_i|x, y_{< i})$$

3.3.2 Listen, Attend and Spell

This model was described in 2016 by Chan et al. [19] and is one of the state of the art models for end-to-end speech recognition task. It identifies the features for input audio signal on its own and selectively pays attention to those features using attention model.

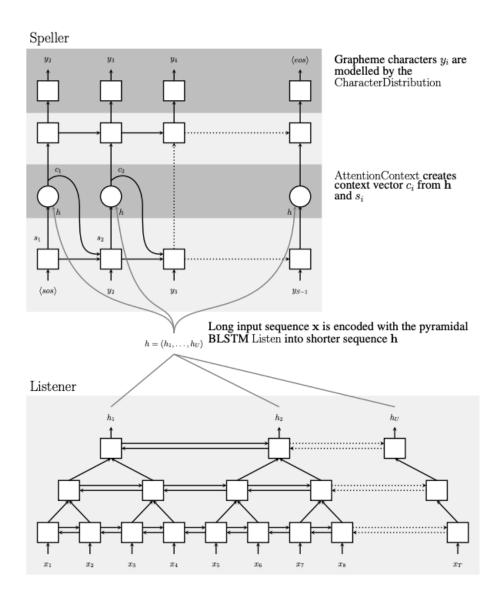


Figure 10: Listen, Attend and Spell (LAS) model.

The LAS model is based on the Encoder-Decoder architecture with attention. The Listener acts as the Encoder which is a pyramidal BiLSTM encoding of the input sequence \mathbf{x} into higher dimensional features \mathbf{h} , the speller is an attention-based decoder which generates the \mathbf{y} characters from \mathbf{h} . The result is obtained by producing a probability distribution over the output vocabulary and the experimental analysis of the LAS model has proven that it outperformed the state of the art models existing at that time including the HMM model for speech recognition.

As a result, model for multimodal summarization has been inspired from the LAS model and uses similar encoder structure to generate sequential encoding of input features.

4. Video Recognition

The third and the final task in order to achieve multimodal summarization the task of image recognition. This involves understanding the contents of an image and then relating them to the natural language. One of the most challenging tasks of **computer vision** is to recognize the images and perform tasks such as event detection, scene reconstruction, 3D pose restoration, image captioning and visual question answering. This is being extensively used today for self-driving cars and other autonomous vehicles like autonomous agricultural vehicles on Earth and autonomous Mars rovers.

The task of video recognition can be broken down into the task of identification of keyframe images and then applying the widely available image recognition algorithms to process and recognize the images. Therefore if we have a robust image recognition algorithm, we can extend it to video recognition as well.

4.1 History

4.1.1 Early Approaches

The task of video recognition as explained previously can be broken down to the task of image recognition which can further be broken down to solve the problem of pattern recognition. Images can be considered as patterns and can therefore be included in the main task of pattern recognition. The main task is to identify the particular patterns in images. The field of pattern recognition has been evolving for quite few decades with many sequence labeling algorithms as well as machine learning algorithms being applied for the same.

4.1.2 Machine Learning Approaches

The task of image recognition and classification has received major breakthrough with the application of various classification tasks being applied for images. The task of image classification can be solved through the state of the art machine learning models which allows more accurate results on the given dataset. One of the most popular classification techniques which have been applied for image classification are **support vector machines**.

Support Vector Machines (SVMs) are among the best supervised learning algorithms. They take into exhaustive consideration of vector representation of the training examples and divide the linearly separable labels with the help of margin and the greater the margin, the more accurate prediction there can be. Though they are defined for linearly separable classifiers, they are extended to non-linearly separable classifiers with the help of Kernels, which make the SVMs work like a charm for non-linearly separable data.

A single decision rule is defined which decides the class of label based on the decision rule. The decision rule is the median line of the gutter, which is defined as the vectors lying on the margins of the two types of labels. The width is defined as the width of the street.

The basic intuition of SVMs as stated earlier is that the greater the width of the street, the greater the accuracy of prediction. Hence the task is to maximize the width under a given set of constraints. This is beautifully accounted by the Lagrange's multipliers.

- **Decision Rule.** \overrightarrow{w} . $\overrightarrow{u} + b \ge 0$ for positive examples (a)
- Function. $\frac{1}{2}||\overrightarrow{w}||^2$ (b)
- Constraint. $y_i(\overrightarrow{x_i} \cdot \overrightarrow{w} + b) 1$ (c)

where:

 $y_i = +1$ and -1 for positive and negative examples respectively. $\overrightarrow{x_i}$ is the input data in vector space.

 \overrightarrow{w} is the vector perpendicular to the median line of the margin.

b is a positive constant.

Using Lagrange's Multipliers,

$$L = \frac{1}{2} ||\overrightarrow{w}||^2 - \sum_{i=1}^{m} \alpha_i [y_i(\overrightarrow{x_i} \cdot \overrightarrow{w} + b) - 1],$$

Differentiating to find the extremums, it can be proved that the decision rule depends only on the dot product of the unknown \overrightarrow{u} and the sample vectors $\overrightarrow{x_i}$.

Hence the decision rule becomes,

 $\sum_{i=0}^{m} \alpha_i y_i \overrightarrow{x_i} \overrightarrow{u} + b \ge 0 \text{ then it will belong to positive class else the unknown will belong to}$ the negative class.

SVM Optimization Problem. (d)

$$\left[\frac{1}{m}\sum_{i=1}^{m} max(0,1-y_{i}(\overrightarrow{w}.\overrightarrow{x}+b))\right] + \lambda ||\overrightarrow{w}||^{2}$$

where, λ is the tradeoff between increasing the margin-size and ensuring that \vec{x} lies on the correct side of the margin.

The SVM approach was able to achieve an accuracy of 97% for the task of hand digit recognition on the MNIST dataset and has therefore been a major state of the art approach in the field of image recognition.

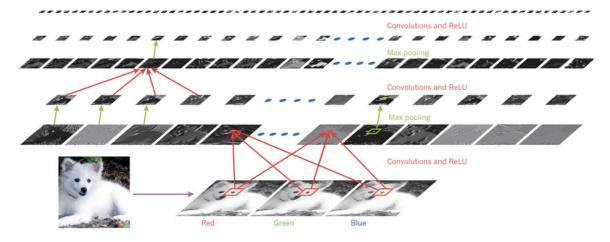


Figure 11: A typical CNN architecture. The outputs from each layer of a typical convolutional neural network applied to Samoyed dog where each rectangular image is a feature map.

4.2 Convolutional Neural Networks

ConvNets are deep, feedforward neural networks which are much easier to train and can be generalized much better than fully connected adjacent layers. They are widely used by the computer vision community to identify the various features in an image.

The ConvNets are designed to process data that comes in the form of multiple arrays. The architecture of ConvNets is a sequence of convolutional layers interspersed with activation functions and includes other layer including pooling layer, max-pooling layer and fully connected layer.

The convolutional layer essentially convolves (slides) over all the spatial locations in an image to carefully scrutinize the local features of images. A filter of appropriate size is selected and is maneuvered through the image with a specific stride.

The Pooling layer is responsible for making the image representation smaller and more manageable. It operates over each activation map independently. The pooling layer only reduces the spatial dimensions of the image and does not affect the depth of the image. Downsampling is an intermediate step involved to achieve pooling.

The maxpooling layer is used to achieve pooling. We take a filter of a fixed size and slide it over the entire image to take the max value of neuron in each filter area. The strides are designed to avoid overlap. Typically zero padding is not used. Finally the fully connected layer contains the entire network connecting input to produce the required output.

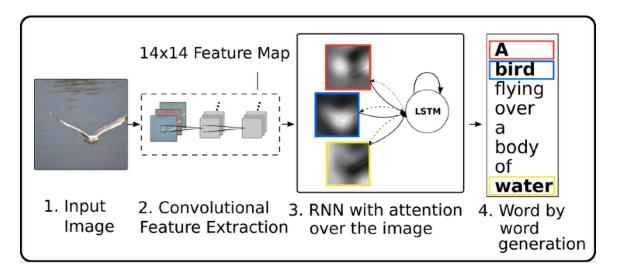


Figure 12: The Show, Attend and Tell image captioning model.

4.3 Show, Attend and Tell

Inspired by the work in machine translation and object detection, Xu et al. [20] introduced an attention based model that automatically learnt describe the contents of the image. Through the task of image captioning, Xu et al. ventured into the task of scene understating.

In order to understand the images, they also generated an encoder-decoder model with attention on particular parts of the images. The model essentially encoded the image using a convolutional neural network to extract the features and then applied an RNN layer over these extracted features by using an attention based decoder which selectively paid attention to important parts of the images to produce the output summary. The process has been shown in Figure 12. The decoder of the model is composed of LSTM cells which generate one word at every timestep conditioned on a context vector, the previous hidden state and the previously generated word.

5. Baseline Multimodal Summarization

The task of multimodal summarization as described previously encompasses the tasks previously described of text summarization, speech recognition and video recognition. The increase in the volume of multimedia-data has made it difficult for the users to extract meaningful content from the vast amount of data. This is where the task of multimodal summarization comes into picture. It is able to collect the multitude of multimedia data and then present a succinct summary out of it which shall allow the users to understand the context of the data with much ease and give a relatively better perspective of the data.

5.1 History

5.1.1 Early Approaches

The task of MMS has been applied in the fields of meeting record summarization, sport video summarization, movie summarization and social media summarization. These all tasks have the availability of multimedia data and therefore it is a reasonable assumption that the benefit of application of the various MMS techniques in these areas will have the maximum impact. Meeting record summarization has been performed by Erol et al. [21], Gross et al. [22], sports video summarization has been performed by Tjondronegoro et al. [23], movie summarization has been performed by Mademlis et al. [24] and social media summarization has been performed by Shah et al. [25]. Though a lot of work has been performed in this field, the work that has been performed does not necessarily take into account all the modalities of data as well as do not apply the state of the art deep learning approaches. Moreover, the task that they deal with are the tasks of synchronous data summarization however one of the baseline models that is explained in the models secant involves the multimodal summarization of the asynchronous data.

5.2 Task Definition

5.2.1 Problem Formulation

The input is a collection of Multimodal data $\mathbb{M} = \{D_1, ..., D_{|D|}\}, \{V_1, ..., V_{|V|}\}$ related to a dataset were the each document $D = \{T_i, I_i\}$ may or may not consist of an image along with the text in the document. V_i denotes the video and $| \circ |$ denotes the cardinality of the set. The objective of multimodal summarization is to automatically generate textual sugary to represent the principle content of \mathbb{M} .

5.2.2 Evaluation Metric

Since the multimodal summarization model produces a textual summary of the multimedia data, the same evaluation metrics namely, precision, recall and F1 scores can be used and most importantly the **ROUGE** scores can be used for the evaluation of the generated textual summary. This is able to measure the summary quality by matching the n-grams between the generated summary and the reference summary in the ROUGE-N evaluation metric.

Apart from the ROUGE scores which are essential for the evaluation of the generated textual summaries with respect to the reference summaries, researchers in the multimodal community have also introduced various metrics to evaluate the multimodal summaries. These summaries take into account the influence factor through the other media of data. These evaluation metric have been defined as follows:

- (a) Content F1. Libovicky et al. [26] introduced the Content F1 evaluation metric which recognized the fact that the task of summarization was being carried out over the HOW2 dataset and there were certain words which occurred at the start of almost all the videos. These words were also present in the reference summary hence they increase the ROUGE score even when the model does not completely understand the data. This was prevented by post processing the data to remove these frequently occurring words from the dataset and then calculate the F1 score. This metric was then named as Content F1.
- (b) Multimodal Automatic Evaluation (MMAE). This metric is used for the models which produce pictorial summary along with textual summary. Hence this becomes self in models having multimodal output for multimodal input data. The was introduced by Zhu et al. [27] and considered three aspects: salience of text, salience of image and relevance between text and image.

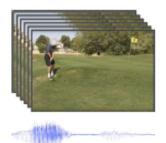
5.3 Dataset and Models

5.3.1 MSMO Dataset

Zhu et al. [27] collected a multimodal dataset similar to Hermann at al. [28]. They collected their large-scale multimodal dataset from Daily Mail website and annotated the pictorial summaries.

5.3.2 How2 Dataset

How2 is a large scale dataset for multimodal language understating [29]. The How2 dataset contains 79,114 instructional videos with English subtitles. The corpus can be recreated using the scripts and the metadata available at https://github.com/srvk/how2-dataset. The dataset has been collected from the YouTube instructional videos and the descriptions and the subtitles are taken as ground truth made available by the video creators.



I'm very close to the green but I didn't get it on the green so now I'm in this grass bunker.

Eu estou muito perto do green, mas eu não pus a bola no green, então agora estou neste bunker de grama.

In golf, get the body low in order to get underneath the golf ball when chipping out of thick grass from a side hill lie.

Figure 13: How2 dataset with utterance-level English subtitle with Portuguese translation and the reference summary available in the form of abstract.

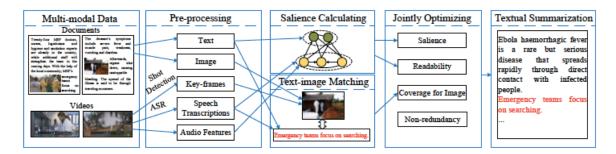


Figure 14: The framework for Asynchronous MMS Model

5.3.3 Extractive Asynchronous Multimodal Summarization

Li et al. [30] proposed a modern technique for extractive multimodal summarization for asynchronous collection of text, image, video and audio. The baseline experiments had been performed on their custom dataset which included asynchronous data. However, their work was extended in this project and evaluated on the synchronous dataset. In their paper, they proposed an approach to a generate textual summary from a set of asynchronous documents, images, audios and videos on the same topic. Since multimedia data are heterogeneous and contain more complex information than pure text does, MMS faces a great challenge in addressing the semantic gap between different modalities. The framework of their method is shown in Figure 14. For the audio information contained in videos, speech transcriptions is obtained through Automatic Speech Recognition (ASR) and designed a method to use these transcriptions selectively. For visual information, including the key-frames extracted from videos and the images that appear in documents, the joint representations of texts and images is learnt by using a neural network; then the text that is relevant to the image is identified. In this way, audio and visual information can be integrated into a textual summary. The model proposed by Li et al. has the following features:

- (a) **Readability Guidance Strategies.** The basic premise of this strategy is that if there is a sentence in the document which is related to the audio, then the text in the document would be preferred rather than the sentence obtained after the automatic speech recognition. The similarity is obtained with the help of cosine similarity and a threshold is used to determine is the sentences are appropriately similar.
- (b) Audio Guidance Strategies. For each adjacent speech transcription pairs, if audio score is smaller than a certain threshold value then the speech transcription should recommend the document text and the document text should not recommend speech transcription.
- (c) **Text-Image Matching.** The main idea of text image matching is that semantic analysis is performed between text and image to learn the joint representation for textual

and visual modalities by using a model trained on Flickr 30K dataset. The framework model by Wang et al. [31] is used to achieve the state of the art performance for textimage matching task on the Flickr 30K dataset.

(d) Budgeted optimization of submodular functions.
$$\max_{s \subseteq T} \{F(S) : \sum_{s \in S} l_s \le L\}$$

Where:

T is the set of sentences, S is the summary, l_s is the length (number of words) of sentence s, L is the maximum length of the summary and F(S) is the summary score.

(e) **Salience of text.**
$$Sa(t_i) = \mu \Sigma_j Sa(t_j) \cdot M_{ji} + \frac{1-\mu}{N}$$

Where:

 μ is the damping factor that is usually set at 0.85, N is the total number of text units, M_{ji} is the relationship between the text unit t_i and t_j which is computed as follows:

$$M_{ii} = sim(t_i, t_i)$$

The text unit t_i is represented by averaging the embeddings in t_i and $sim(\circ)$ denotes the similarity between the two texts.

(f) **Objective function.** The objective function considers all the modalities and is mathematically defines as follows:

$$F_m(S) = \frac{1}{M_s} \sum_{t_i \in S} Sa(t_i) + \frac{1}{M_c} \sum_{p_i \in S} Im(p_i) b_i - \frac{\lambda_m}{|S|} \sum_{t_i, t_j \in S} sim(t_i, t_j)$$

Where:

 M_s is the summary score obtained by text salience, M_c is the summary score obtained by image salience. This is a monotone submodular function and a greedy algorithm can be applied to obtain the optimum value for this function and the argument sentences for this value is generated multimodal summary.

5.3.3.1 Implementation Details

The entire algorithm has been implemented on our own dataset to evaluate the accuracy of the generated summary on the self generated dataset. The OpenCV framework has been used to extract salient key-frames from the videos and the these key-frames are then matched with the speech transcriptions and the document text. The similarity matrix has been produced by incorporating specific changes in the code for the LexRank algorithm. The submodular function has been optimized using the greedy algorithm described by Lin et al. [32]. The for the implementation of the paper on the our own dataset are as follows:

```
document_full.txt

image_encode_vgg19.py
image_encode_vgg1py
image_encode_vgg1py
image_encode_vgg1py
image_encode_vgg1py
image_encode_vgg1py
image_encode_vgg1py
image_encode_vgg1py
image_encode_vgg1py
image_encode_vgg1py
```

Figure 15: List of generated summaries.

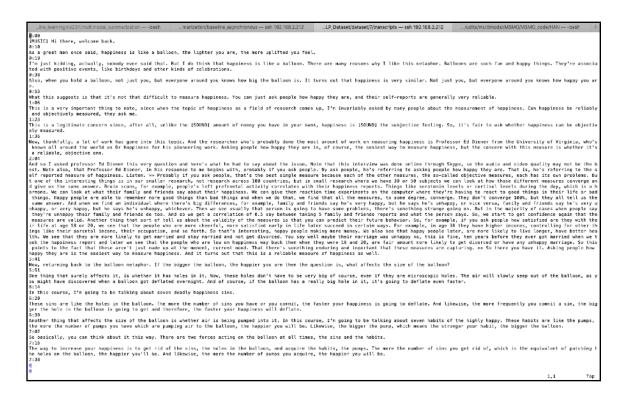


Figure 16: Source transcript in the dataset

```
The services of the service of the s
```

Figure 17: Generated summary from the source data.

```
| Destack|| Dest
```

Figure 18: ROUGE score evaluation of the generated summary.

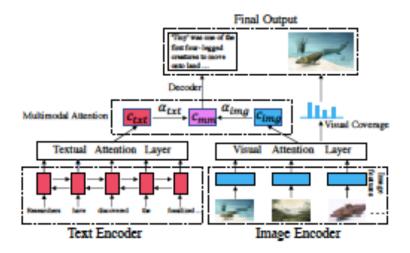


Figure 19: Architecture for the MSMO model

5.3.4 Multimodal Summarization with Multimodal Output

Multimodal Summarization with Multimodal Output (MSMO) [27] is a novel multimodal summarization task, which takes the news from the defined dataset with images as input, and finally outputs a pictorial summary. They constructed a large scale corpus for MSMO study. They proposed an abstractive multimodal summarization model to jointly generate summary and the most relevant image. They proposed a multimodal automatic evaluation (MMAE) method which has been described in section 5.3.1. The text encoder and the summary decoder have been inspired from the Pointer-Generator networks.

Multimodal attention layer has been placed on top of the textual and visual attention layer. This layer acts as a distribution between the text visual features of the data hence this layer is built on top of the previous attention layer which specifies the attention required to be given to specific words and images. The second level of attention layer is required to weigh the importance that needs to be give to the visual and textual features all together. Hence this hierarchal attention model is able to generate an output multimodal summary which performs well on their dataset and they were able to prove good results using the MMAE metric. The architect of the MSMO model has been described in figure 19. The model can further be described using the mathematical equations built on top of the pointer-generator model as described in section 2.3.2 as:

$$e_{txt}^{t} = v_{txt}^{T}(W_{txt}c_{txt}^{t} + U_{txt}s_{t})$$

$$e_{img}^{t} = v_{img}^{T}(W_{img}c_{img}^{t} + U_{img}s_{t})$$

$$\alpha_{txt}^{t} = softmax(e_{txt}^{t})$$

$$\alpha_{img}^{t} = softmax(e_{img}^{t})$$

$$c_{mm}^{t} = \alpha_{txt}^{t}c_{txt}^{t} + \alpha_{img}^{t}c_{img}^{t}$$

Where:

 α_{txt}^t is the attention weight for the text context vector and α_{img}^t is the attention weight for the image context vector. These two distributions are combined with the context vectors of the text and the image respectively to produce the combined multimodal context vector. This is passed to the decoder which then generates a probability distribution over the output vocabulary and output images to select the most accurate word and image at each timestep and in turn produce a good multimodal output summary.

5.3.4.1 Implementation Details

The MSMO model has been built on top of the pointer-generator network and hence most of the code has been reused from the pointer generator network and this too has been coded using the Tensorflow framework in version 1.0. The authors were kind enough to share the code with me for my research purpose and I implemented the code on our dataset to get the ROUGE score results for the same. The training step of the code in NVIDIA TX2 has been shown in figure 20.

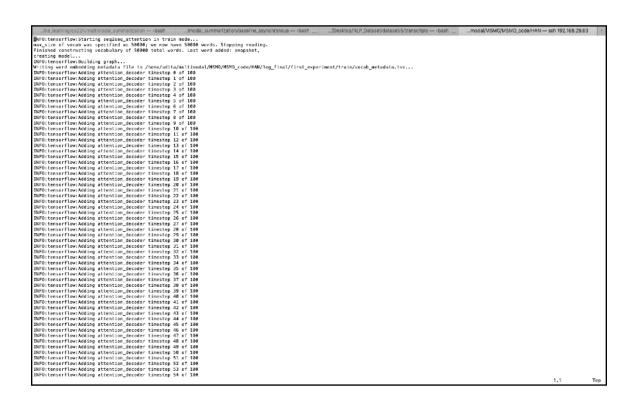


Figure 20: Training of the MSMO model on our dataset.

Chapter II MultiModal BiDirectional Attention Flow (MMBiDAF)

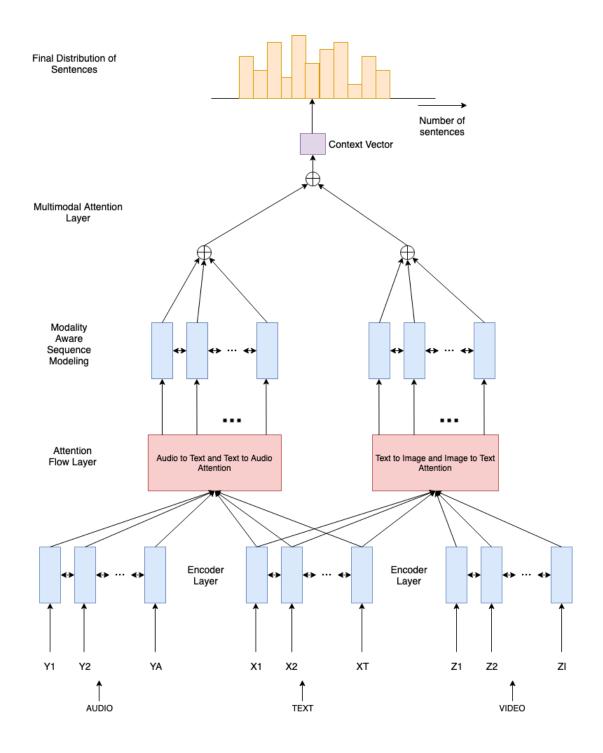


Figure 21: Architecture for MMBiDAF model.

6. MultiModal BiDirectional Attention Flow

The MMBiDAF model (figure 21) is the proposed model for carrying out the defined task of multimodal summarization which has been inspired from the various previous state of the art models existing in the literature. This model was chosen since it encompasses all the input modalities, calculates the similarity between them and then uses a multimodal attention later on top of image-aware and audio-aware texts to get an output distribution over the source document.

The model is used for extractive summarization in which at each timestep the most probable sentences are selected and chosen as part of the output summary. The summary terminates when the probability of a special <End Of Summary> token is the greatest. The proposed model is inherently a combination of Bidirectional Attention Flow [33] and Multimodal Attention models [34]. Our model follows the high-level structure of embedding layer, encoder layer, bidirectional attention layer, modality aware sequence modeling layer, multimodal attention layer and finally an output layer. The model is explained in complete detail in the following sections.

6.1 Model Explanation

6.1.1 Text Embedding Layer

Let the input document be described as $(X_1, X_2, ..., X_T)$ where X_i is the embedded sentence obtained by averaging the pertained **GloVE** embeddings of the words included in the sentence. 'T' is the number of sentences in the source document. Hence each sentence is now described as a vector with dimension equal to the embedding dimension (D). Hence $X_i \in \mathbb{R}^D \ \forall i$.

In order to further refine the generated embeddings, the embedded sentences are undergone through the following steps:

- Each Embedding is projected to have the dimensionality H. By making $W_{proj} \in \mathbb{R}^{H \times D}$ a learnable parameter, each embedding vector X_i is mapped to $h_i = W_{proj} X_i \in \mathbb{R}^H$.
- A **Highway Network** [35] is applied to refine the embedded representation. Given an input vector h_i , one-layer highway network computes

$$g = \sigma(W_g h_i + b_g) \in \mathbb{R}^H$$

$$t = ReLU(W_t h_i + b_t) \in \mathbb{R}^H$$

$$h'_i = g \odot t + (1 - g) \odot h_i \in \mathbb{R}^H$$

Where:

 $W_g, W_t \in \mathbb{R}^{H \times H}$ and $b_g, b_t \in \mathbb{R}^H$ are learnable parameters. The hidden vectors are therefore transformed using this Highway Network and this transformation.

6.1.2 Audio Embedding Layer

The audio embedding layer is basically the feature extraction layer input audio signals. The **MFCC** features of the input audio signals are extracted to generate audio envelopes of embedded dimension. The input audio signal is therefore obtained on parts where each part signifies a frequency envelop which have been extracted using the MFCC algorithm. The audio signal is therefore obtained in form of $(Y_1, Y_2, ..., Y_A)$ where A is the number of envelopes and each $Y_i \in \mathbb{R}^{D_1}$ where D_1 is the embedding dimension for the generated discrete audio signals.

In order to further refine the audio embeddings, the audio embeddings are passed through the same two steps of **projection** and **Highway Network** to refine the generated audio embeddings. After passing the audio embeddings through these steps, we obtain the embedded audios in the dimension equal to the dimension of the hidden state. Hence we now get the audio embeddings as $Y_i \in \mathbb{R}^H$ $\forall i$.

6.1.3 Image Embedding Layer

The third and the last input modality is the video in the dataset. The videos are first preprocessed to extract the key-frames from the video. The extraction of salient frames is an ongoing are of research and we have used a naive OpenCV key-frame extraction algorithm based on the change in the histograms of the adjacent frames.

The obtained images may be of different sizes and they are therefor first normalized and to obtain images of equal dimension. Hence the video is now available in the form of key-frame images where each image is of the form given by $(Z_1, Z_2, ..., Z_I)$ where $Z_i \in \mathbb{R}^{d_2 \times d_2}$ $\forall i$ where d_2 is the normalized image size.

The obtained images are then embedded using the ResNet [36] network which extracts the features from the input images to make them of suitable dimension. A linear layer is then passed through the obtained embedded images to represent every image with fixed size dimension.

In order to further refine the image embeddings, the image embeddings like the audio and the text embeddings are passed through the same two steps of **projection** and **Highway Network** to refine the generated image embeddings. After passing the image embeddings through these steps, we obtain the embedded images in the dimension equal to the dimension of the hidden state. Hence we now get the image embeddings as $Z_i \in \mathbb{R}^H \ \forall i$.

6.1.4 Encoder Layer

The generated text, audio and image embeddings are fed into the encoder layer which is composed of a Bidirectional LSTM network. This layer is responsible for incorporating temporal dependencies between the generated embeddings. The embeddings are therefore transformed into sequential encodings for all the three types of modalities of data. The encoded output is the LSTM's hidden state at each timestep:

$$\begin{aligned} h'_{i,fwd} &= LSTM(h'_{i-1}, h_i) \in \mathbb{R}^H \\ h'_{i,rev} &= LSTM(h'_{i+1}, h_i) \in \mathbb{R}^H \\ h'_{i} &= [h'_{i,fwd}; h'_{i,rev}] \in \mathbb{R}^{2H} \end{aligned}$$

The output from the Encoder layer is therefore of dimension 2H which is twice the hidden size of the network.

6.1.5 Attention Flow Layer

The attention flow layer is responsible for generating image-aware textual vectors and audio-aware textual vectors. This intuitively signifies that the text is now aware of the correspond audio and image dataset after it passes through this layer.

These are computed using the similarity matrix which is a trainable matrix between the separate modalities. The similarity between each textual sentence and all the audio vectors as well as the similarity between each textual sentence and every image is calculated.

This similarity matrix is then used to calculate attention weights each textual sentence shall give to the different modality.

The 2H dimensional images and text shall be passed through the similarity matrix whose dimension shall be $S \in \mathbb{R}^{T \times I}$ where T is the number of text sentences and I is the number of key-frame images. The similarity matrix shall be computed as :

$$S=\alpha(H_{:t},U_{:i})\in\mathbb{R}$$

where $H_{:t}$ represents the column vector of the H matrix which is the sentence embedding matrix and similarly $U_{:t}$ represents the column vector of U matrix which is the embedding matrix for each image. Hence $H \in \mathbb{R}^{2H \times T}$ and $U \in \mathbb{R}^{2H \times I}$.

Similarly the encoded text and audio are then passed through the another similarity matrix which calculates the similarity between the encoded text and the encoded audio.

The trainable **similarity function** needs to be calculated and is defined as $\alpha(h, u) = w_{sim}^T[h; u; h \odot u]$. These values are calculated each pair (h, u) in the similarity matrix where $w_{sim} \in \mathbb{R}^{6H}$

6.1.5.1 Text-to-Image Attention

The attention weights over all the key-frame images in the given dataset can then be calculated as $a_t = softmax(S_t) \in \mathbb{R}^I$. The text-to-image attention signifies which images are most relevant to each sentence. Hence a_t is a probability distribution over the complete set of images.

Now the attended image vectors for the entire text will be $\tilde{U} \in \mathbb{R}^{2H \times T}$ which signifies that for every sentence the attention given to each image has been incorporated. Hence the text that we now have is attentive to the images and knows which image it needs to pay attention to. This is calculated using the following equation:

$$\tilde{U}_{:t} = \Sigma_i a_{ti} U_{:i} \in \mathbb{R}^{2H}$$

Where:

 $\tilde{U} \in \mathbb{R}^{2H \times T}$ are the text vectors which are aware of the corresponding image.

6.1.5.2 Image-to-Text Attention

This signifies which of the sentences has the closest similarity to each keyframe image. For every image, the similarity score over all the sentences is calculated to understand which of the sentences are the closest to the given keyframe.

The attention weights are obtained using $b_t = softmax(max_{col}S) \in \mathbb{R}^T$ which tells the probability distribution of all the sentences over the given image.

The context vector for the images can then be calculated using:

$$\tilde{h} = \Sigma_t b_t H_{\cdot t} \in \mathbb{R}^{2H}$$

This indicates the image to text attention output. For each sentence, $i \in 1,...,T$, we obtain the output g_i of the Bidirectional Attention Flow layer by combing text hidden state X_i , the Text-to-Image attention output $\tilde{U}_{:i}$, the image-to-text attention \tilde{h} :

$$g_i = [X_i; \tilde{U}_i; X_i \odot \tilde{U}_i; \tilde{h}] \in \mathbb{R}^{8H} \quad \forall i \in \{1, ..., T\}$$

where \odot is the element wise multiplication.

6.1.6 Modality Aware Sequence Modeling Layer

The modality aware sequence modeling layer is responsible for refining the sequence of vectors after the attention layer. The audio-aware-text and the image-aware-text become sequentially encoded after passing through this layer. Similar to the encoder layer, a bidirectional LSTM is used. The input vector for this layer is the output from the attention layer, $g_i \in \mathbb{R}^{8H}$, the modeling layer computes

$$m_{i,fwd} = LSTM(m_{i-1}, g_i) \in \mathbb{R}^H$$

$$m_{i,rev} = LSTM(m_{i+1}, g_i) \in \mathbb{R}^H$$

$$m_i = [m_{i,fwd}; m_{i,rev}] \in \mathbb{R}^{2H}$$

We use a two-layer LSTM in the modeling layer rather than a single layer LSTM as in the Encoder Layer.

6.1.7 Multimodal Attention Layer

This attention layers is built on top of the modality aware aware sequential modeling layer to selectively weigh the appropriate amount of attention required to be given to each type of modality in order to generate the output from the source sentences at that particular timestep. For each timestep attention is calculated internally over image-aware as well as audio-aware text. In the same timestep multimodal attention is then calculated over generated context vectors after the internal attention calculation. This is the multimodal attention distribution and the multimodal context vector is then calculated. The attention weights over audio-aware text is $\alpha_{image} \in \mathbb{R}^T$ where T is the maximum text length. The context vector over audio-aware text is given by $c_{audio} \in \mathbb{R}^{2H}$ and the context vector over the image-aware text is given by $c_{img} \in \mathbb{R}^{2H}$. The multimodal attention distribution over the audio aware texts is a scalar and the multimodal attention distribution over the image-aware text is also a scalar. Finally the multimodal context vector given by $c_{mm} \in \mathbb{R}^{2H}$ is the generated output for this layer. The equations can be described in the same manner as in [27] and are given as follows:

$$\begin{split} e^t_{audio} &= v^T_{audio}(W_{audio}c^t_{audio} + U_{audio}s_t) \\ e^t_{img} &= v^T_{img}(W_{img}c^t_{img} + U_{img}s_t) \\ \alpha^t_{audio} &= softmax(e^t_{audio}) \\ \alpha^t_{img} &= softmax(e^t_{img}) \\ c^t_{mm} &= \alpha^t_{audio}c^t_{audio} + \alpha^t_{img}c^t_{img} \end{split}$$

6.1.8 Output Layer

The output layer takes as input the multimodal context vector produced by the Multimodal Attention layer, c_{mm} . This is then fed into a GRU cell which acts as a sequential layer before generating the final output to give a sequential encoding over the final output distribution. A softmax function is then applied over a fully connected linear layer over the output distribution. This gives us the probability of selecting each sentence at each timestep and the sentence with the maximum probability is chosen at that timestep. This can be quantified as follows:

$$\begin{aligned} o_t &= [y_t; z_t; c_{mm_t}] \\ o_t &= W_o o_t \\ o_t, h_t &= GRU(o_t, h_{t-1}) \\ o_t &= softmax(W_f o_t) \end{aligned}$$

Where:

 o_t is the output vector at timestep t, y_t, z_t are respectively the audio aware text and the image aware text at timestep t. c_{mm_t} is the multimodal context vector at timestep t. At every timestep the GRU cell receives the previous hidden state and the current output from the previous layers as its input and then it converts it into a temporal encoding which is important for sequence dependent output like the textual summary. It is also necessary to take linear transform using the trainable weight matrices $W_o \in \mathbb{R}^{6H \times 2H}$ and $W_f \in \mathbb{R}^{2H \times T}$ where T is the maximum length of the input text vectors.

Finally the softmax layer produces an output distribution over the source sentences in the document and at each timestep a probability distribution over the source sentences is calculated and the sentence with the maximum probability at a given timestep is selected to be a part of the output summar and trained using **negative log probability** of the target. The output summary is therefore generated from the given input multimodal data.

6.2 Multimodal Dataset

Resources of the corpus were driven from online courses provided by Coursera using coursera-dl, a python script to download course materials available on Coursera. Every lecture is accompanied by following resources: Videos (mp4), transcripts (txt), timed transcripts (srt), lecture notes (pdf, ppt). Out of 3000 courses, 25 courses were selected with a total of 965 videos and corresponding transcripts. Each directory contains 5 folders with each directory representing a course. The course contains several video lectures and the corresponding transcripts. The Audios have been extracted from the videos using the ffmpeg scripts. The audio-features are the Mel-frequency cepstral coefficients (MFCC) features which take human perception sensitivity with respect to frequency into consideration. These have been extracted for speech feature recognition. The Srt folder

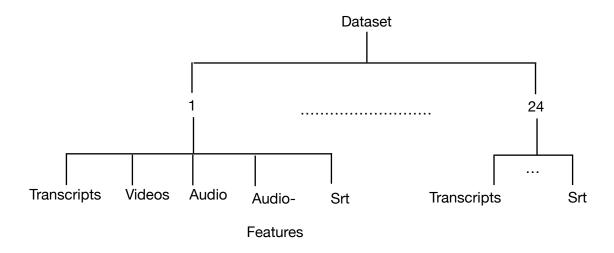


Figure 22: Directory structure of the multimodal dataset

contains the timed transcripts of each video and used for specific transcript for video frames. The directory structure of the dataset is shown in figure 22.

6.3 Evaluation Metric

Since the task that we are pursuing involves the generation of multimodal summary in a textual form, it is convenient to use the widely accepted **ROUGE** scores for determining the accuracy of the generated output summary with respect to the self annotated reference summary. Hence for this task, we have used the ROUGE as described in section 2.2.2.

6.4 Implementation Details

The complete model has been implemented using PyTorch machine learning framework in python 3.0 programming language. The Rouge library has been used to evaluate the Rouge scores. The pre-trained GloVE vectors have been used and the text embedding size is 300 features while the audio embedding size is 128 features and the image embedding size is of 2048 features. The hidden size is taken to be 100 while dropout is applied to counter the problem of overfitting and the dropout probability is taken to be 0.2. The maximum text length has been identified from the dataset and has been found out to be of size 405. The number of epochs have been set to 100. Seaborn library has been used to obtain the heat map to visualize the multimodal attention distribution. NLTK library has been used for sentence and word tokenization.

The complete dataset has been preprocessed to remove the stopwords and the extra words in the course transcripts for instance the occurrence of the word '[MUSIC]' in the source transcript has been removed while preprocessing the data. The gensim library has been used to extract the pertained GloVE vectors for the source words and the average of these embedded words is calculated to produce a sentence embedding. The PyTorch Data

loader has been used to automatically load data in batches and hence adding an extra dimension of batch size while taking input from data. The key-frames have been extracted as described earlier using OpenCV library.

The complete code will be open sourced at https://github.com/amankhullar/MMBiDAF. The complete training has been performed on the NVIDIA RTX 2080 Ti server and the results have been possible because of the availability of this computation power.

6.5 Results

The MMBiDAF model has found to beat the current state of the art models by achieving an ROUGE-f score of 49.9% which is better than the current state of the art models by 3%. The ROUGE-1 and ROUGE-f score of the various algorithms over the dataset have been compared in table 1.

Models	ROUGE	
	1	L
LexRank	44	37
Pointer-generator + coverage	39.53	36.38
Multimodal Summarization for Asynchronous Data	44.6	45
MSMO	40.86	37.74
MMBiDAF	49.99	50

Table 1 : Results for the MMBiDAF model in comparison to other state of the art models.

Through the results we have found that the MMBiDAF model achieves state of the art results for the task of extractive multimodal summarization.

The results on the dataset to generate the textual summary are as follows:



Figure 23: Source transcript.



Figure 24: One of the key frames extracted from the video.



Figure 25: Generated summaries of the first four videos.

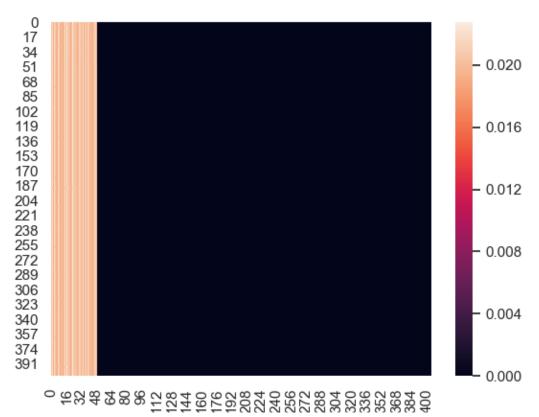
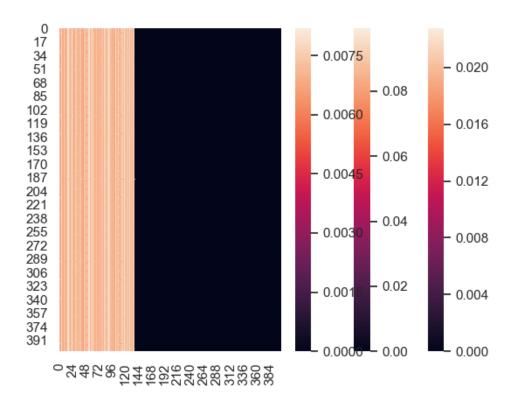


Figure 26: Attention visualization for first video.



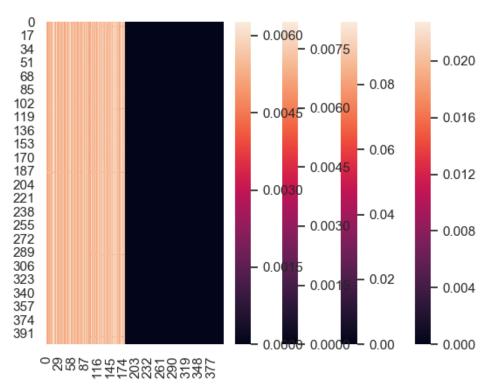


Figure 27 and 28 : Attention distribution over the various sentences in the course videos.

The results have been obtained by using the **Negative Log Likelihood.** The loss is therefore given by

$$loss_t = -\log P(s_i^*)$$

Where:

 (s_i^*) is the reference target sentence. This is inspired from the choice of the pointergenerator function and has proven to obtain good results.

Backpropagation algorithm is then applied to train the learnable parameters and get the result.

Chapter III Conclusion and Beyond

7. Conclusion

This thesis tackles the problem of multimodal summarization which is defined as the task of generating output summary taking into account the different multimedia data as input. The output summary may be presented in single modality or multiple modalities and this work presents the output in the form of textual modality.

In the thesis, the foundations of natural language processing in general and multimodal summarization in specific have been explored. Since the field of Multimodal Summarization encompasses the textual, audio and visual dataset, the foundations of these modalities have been explored and further built upon. The breakthrough models in the field of deep learning namely listen, attend and tell and show, attend and tell have also been described through which our model has been inspired. The explanation of these models has been listed in order to give the user a better understanding of the existing state of the art deep learning approaches. The baseline models have been implemented on our own dataset and the widely available dataset to explore the existent state of the art techniques. The datasets have been carefully preprocessed and chunked to suit the baseline model specifications.

The last part of this thesis presents the novel work of this thesis, the MultiModal Bidirectional Attention Flow Model (MMBiDAF). The architecture of the model has been carefully built to integrate all the modalities and draw similarity between them to carefully generate the text which is attentive of both image and audio which further receives an attention layer to select from the audio-aware or the image-aware text. The model is then able to generate a summary by extracting the most important sentences from the given source text. The results of the model have shown to outperform the existing state of the art models in the literature. MMBiDAF is compared with Lex Rank, pointer generator model, asynchronous summarization model and the MSMO model and it has been observed that MMBiDAF achieves a ROUGE-1 score of 49.9% and ROUGE-L score of 50.0%.

8. Beyond

Though MMBiDAF model beats the existing state of the art models in the field of extractive multimodal summarization, however there are a large number of areas where the proposed model can be modified and improved upon.

First of all, a new state of the art technique for NLP-training called Bidirectional Encoder Representation from Transformers (BERT) [37] can be applied which allows the model to be be built upon the existing pre-trained contextual representations. This gives NLP models the power to learn the context of the word occurring in the sentence. This is important for words like 'bank' which have completely different meaning when being used to describe river bank and when being used to describe the financial institution.

Secondly, the described work includes a vanilla approach for extracting the key-frame images however with the advancements in the techniques to extract the keyframe images from a given video.

Lastly, another interesting domain to build upon would be the same high-dimensional embedding space of the text, audio and video representation. The proposed work is able to perform well because the wearable weight matrix is able to learn the differences in the embedding space however other techniques for representing the modalities in a joint embedding space can be tried upon. This can be facilitated by including beam search at every timestep to extract a set of best sentences rather than a single sentence from the output distributions at each timestep.

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DOCUMENT

Thesis_doc_2

Inappropriate Colloquialisms

SCORE

60 of 100

ISSUES FOUND IN THIS TEXT

278

PLAGIARISM

7%

Contextual Spelling	47
Misspelled Words	29
Confused Words	7 —
Unknown Words	6
Mixed Dialects of English	5 =
Grammar	21
Determiner Use (a/an/the/this, etc.)	12
Faulty Subject-Verb Agreement	6
Incorrect Verb Forms	2 =
Wrong or Missing Prepositions	1
Punctuation	43
Punctuation in Compound/Complex Sentences	32
Comma Misuse within Clauses	9 —
Closing Punctuation	2
Sentence Structure	4
Incomplete Sentences	3 =
Misplaced Words or Phrases	1
Style	126
Passive Voice Misuse	45
Improper Formatting	27
Possible Dialectisms	26
Intricate Text	12
Wordy Sentences	11 —

Vocabulary enhancement

37

37

Word Choice

Thesis_doc_1

SCORE

56 of 100

ISSUES FOUND IN THIS TEXT

749

PLAGIARISM

7%

Contextual Spelling	82	
Misspelled Words	54	
Confused Words	12	
Mixed Dialects of English	9	
Unknown Words	6	
Commonly Confused Words	1	
Grammar	88	
Determiner Use (a/an/the/this, etc.)	56	_
Faulty Subject-Verb Agreement	12	-
Wrong or Missing Prepositions	6	
Incorrect Verb Forms	6	
Incorrect Noun Number	5	
Conjunction Use	1	
Pronoun Use	1	
Misuse of Quantifiers	1	
Punctuation	98	
Punctuation in Compound/Complex Sentences	83	
Comma Misuse within Clauses	15	-
Sentence Structure	10	
Misplaced Words or Phrases	6	
Incomplete Sentences	3	
Faulty Parallelism	1	
Style	317	
Passive Voice Misuse	124	

154

Grammarly Report generated on Monday, May 27, 2019, 12:06 PM

Word Choice

10. Appendix A

```
Code for models.py
```

```
import numpy as np
import torch
from layers.encoding import *
from layers.attention import *
import torch.nn as nn
class MMBiDAF(nn.Module):
```

The combination of the Bidirectional Attention Flow model and the Multimodal Attention Layer model.

Follows a high-level structure inspired from the BiDAF implementation by Chris Chute.

- Embedding layer: Embed the text, audio and the video into suitable embeddings using Glove, MFCC and VGG respectively.
 - Encoder layer: Encode the embedded sequence.
- Attention Flow layer : Apply the bidirectional attention mechanism for the multimodal data.
 - Modality aware encoding: Encode the modality aware sequence
- Multimodal Attention : Apply the attention mechanism for the separate modality of data.
- Ouput layer : Simple Softmax layer to generate the probability distribution over the textual data for extractive summary.

```
Args:
```

```
word_vectors (torch.Tensor) : Pre-trained word vectors (GLoVE).
image_vectors (torch.Tensor) : Pre-trained image features (ResNet).
audio_vectors (torch.Tensor) : Pre-trained audio features (MFCC).
hidden_size (int) : Number of features in the hidden state at each layer.
drop_prob (float) : Dropout probability.
"""

def __init__(self, hidden_size, text_embedding_size, audio_embedding_size,
drop_prob=0., max_text_length=405):
super(MMBiDAF, self).__init__()
self.emb = Embedding(embedding_size=text_embedding_size,
hidden_size=hidden_size,
drop_prob=drop_prob)
```

```
self.a emb = Embedding(embedding size=audio embedding size,
                                                                     # Since audio
embedding size is not 300, we need another highway encoder layer
                    hidden size=hidden size,
                                                       # and we cannot increase the
hidden size beyond 100
                 drop prob=drop prob)
    self.text enc = RNNEncoder(input size=hidden size,
                    hidden size=hidden_size,
                    num layers=1,
                    drop prob=drop prob)
    self.audio enc = RNNEncoder(input size=hidden size,
                     hidden size=hidden size,
                     num layers=1,
                     drop prob=drop prob)
    self.image enc = RNNEncoder(input size=hidden size,
                    hidden size=hidden size,
                    num layers=1,
                    drop prob=drop_prob)
    self.image keyframes emb = ImageEmbedding(encoded image size=2)
    self.bidaf att audio = BiDAFAttention(2*hidden size,
                          drop prob=drop prob)
    self.bidaf att image = BiDAFAttention(2*hidden size,
                          drop prob=drop prob)
    self.mod t a = RNNEncoder(input size=8*hidden size,
                       hidden size=hidden size,
                       num layers=2,
                       drop prob=drop prob)
    self.mod t i = RNNEncoder(input size=8*hidden size,
                       hidden size=hidden size,
                       num layers=2,
                       drop prob=drop prob)
    self.multimodal att decoder = MultimodalAttentionDecoder(hidden size,
                                     max text length,
                                     drop prob)
```

```
def forward(self, embedded text, original text lengths, embedded audio,
original audio lengths, transformed images, original image lengths,
hidden gru=None):
     text emb = self.emb(embedded text)
                                                                                #
(batch size, num sentences, hidden size)
     text encoded = self.text enc(text emb, original_text_lengths)
                                                                                #
(batch size, num sentences, 2 * hidden size)
     audio emb = self.a emb(embedded audio)
                                                                                #
(batch size, num audio envelopes, hidden size)
                audio encoded = self.audio enc(audio emb, original audio lengths)
# (batch size, num audio envelopes, 2 * hidden size)
     original images size = transformed images.size()
(batch size, num keyframes, num channels, transformed image size,
transformed image size)
     # Combine images across videos in a batch into a single dimension to be embedded
by ResNet
                     transformed images = torch.reshape(transformed images, (-1,
transformed images.size(2), transformed images.size(3), transformed images.size(4)))
# (batch size * num keyframes, num channels, transformed image size,
transformed image size)
                     image emb = self.image keyframes emb(transformed images)
# (batch size * num keyframes, encoded image size, encoded image size, 2048)
                  image emb = torch.reshape(image emb, (image emb.size(0), -1))
# (batch size * num keyframes, encoded image size * encoded image size * 2048)
     image linear layer = nn.Linear(image emb.size(-1), 300)
Linear layer for linear transformation
     image emb = image linear layer(image emb)
                                                                                #
(batch size * num keyframes, 300)
                  image emb = torch.reshape(image emb, (original images size[0],
original images size[1], -1)) # (batch size, num keyframes, 300)
     image emb = self.emb(image emb)
                                                                                #
(batch size, num keyframes, hidden size)
              image encoded = self.image enc(image emb, original image lengths)
# (batch size, num keyframes, 2 * hidden size)
    # TODO: This will only work for batch size = 1. Add support for larger batches
    ones = torch.ones(1, 1, int(original_text_lengths[0]))
    zeros = torch.zeros(1, 1, embedded text.size(1) - int(original text lengths[0]))
```

```
text mask = torch.cat((ones, zeros), 2)
                                                                       # (batch size,
padded seq length)
     audio mask = torch.ones(1, embedded audio.size(1))
                                                                                   #
(batch size, padded seg length)
     image mask = torch.ones(1, original images size[1])
                                                                                   #
(batch size, padded seq length)
        text audio att = self.bidaf att audio(text encoded, audio encoded, text mask,
audio mask) # (batch size, num sentences, 8 * hidden size)
       text image att = self.bidaf att image(text encoded, image encoded, text mask,
image mask) # (batch size, num sentences, 8 * hidden size)
                mod text audio = self.mod t a(text audio att, original text lengths)
# (batch size, num sentences, 2 * hidden size)
               mod text image = self.mod t i(text image att, original text lengths)
# (batch size, num sentences, 2 * hidden size)
    # if hidden gru is None:
        hidden gru = self.multimodal att decoder.initHidden()
                                     hidden gru, final out, sentence dist =
self.multimodal att decoder(mod text audio, mod text image, hidden gru, text mask)
# (batch size, num sentences, )
    # else:
                                     hidden gru, final out, sentence dist =
self.multimodal att decoder(mod text audio, mod text image, hidden gru, text mask)
     out distributions = self.multimodal att decoder(mod text audio, mod text image,
hidden gru, text mask)
#
      print(len(out distributions))
      print(out distributions[0].size())
    return out distributions
```

11. Appendix B

Code for Datasets.py

```
import json
import os
import pickle
import re
import sys
import logging
import numpy as np
import torch
from PIL import Image
from torch.utils.data import Dataset
from nltk.tokenize import sent_tokenize
class TextDataset(Dataset):
  A Pytorch dataset class to be used in the Pytorch Dataloader to create text batches
  def __init__(self, courses_dir, max_text_length=405):
    Args:
                courses dir (string): The directory containing the embeddings for the
preprocessed sentences
    self.courses dir = courses dir
    self.text embeddings path = self.load sentence_embeddings_path()
    self.max text length = max text length
  def load sentence embeddings path(self):
     transcript embeddings = []
    # Get sorted list of all courses (excluding any files)
    dirlist = []
    for fname in os.listdir(self.courses dir):
       if os.path.isdir(os.path.join(self.courses dir, fname)):
         dirlist.append(fname)
     for course number in sorted(dirlist, key=int):
```

```
course transcript path = os.path.join(self.courses dir, course number,
'sentence features/')
        text embedding path = [self.courses dir + course number + '/sentence features/'
+ transcript path for transcript path in sorted(os.listdir(course transcript path),
key=self.get num)]
       transcript embeddings.append(text embedding path)
     return [val for sublist in transcript embeddings for val in sublist] #Flatten the list
of lists
  def get num(self, str):
    return int(re.search(r'\d+', str).group())
  def len (self):
    return len(self.text embeddings path)
  def getitem (self, idx):
    self.embedding path = self.text embeddings path[idx]
    self.embedding dict = torch.load(self.embedding path)
    word vectors = torch.zeros(self.max text length, 300)
    for count, sentence in enumerate(self.embedding dict):
       word vectors[count] = self.embedding dict[sentence]
      word vectors[len(self.embedding dict)] = torch.zeros(1, 300) - 1 # End of
summary token embedding
     return word vectors, len(self.embedding dict) + 1
                                                                      # Added EOS to
the original data
class ImageDataset(Dataset):
  A PyTorch dataset class to be used in the PyTorch DataLoader to create batches.
  Member variables:
  self.image paths (2D list): A 2D list containing image paths of all the videos.
                   The first index represents the video, and the
                   second index represents the keyframe.
  self.num videos (int): The total number of videos across courses in the dataset.
  def __init__(self, courses_dir, transform = None):
    Args:
       courses dir (string): Directory with all the courses
```

```
transform (torchvision.transforms.transforms.Compose): The required
transformation required to normalize all images
    self.courses dir = courses dir
    self.transform = transform
    self.num videos = 0
    self.image paths = self.load image paths()
  def get num(self, str):
    return int(re.search(r'\d+', re.search(r'\d+', str).group()).group())
  def load image paths(self):
    images = []
    # Get sorted list of all courses (excluding any files)
    dirlist = []
    for fname in os.listdir(self.courses dir):
       if os.path.isdir(os.path.join(self.courses dir, fname)):
         dirlist.append(fname)
     for course dir in sorted(dirlist, key=int):
                        keyframes dir path = os.path.join(self.courses dir, course dir,
'video key frames/')
       for video dir in sorted(os.listdir(keyframes dir path), key=int):
         self.num videos += 1
         video dir path = os.path.join(keyframes dir path, video dir)
                            keyframes = [os.path.join(video dir path, img) for img in
os.listdir(video dir path) \
                 if os.path.isfile(os.path.join(video dir path, img))]
         keyframes.sort(key = self.get num)
         images.extend([keyframes])
    return images
  def len (self):
    return self.num videos
  def getitem (self, idx):
     transformed images = []
     for image path in self.image paths[idx]:
       image = Image.open(image_path)
       if self.transform is not None:
         image = self.transform(image)
```

```
transformed images.append(image)
     return torch.stack(transformed images)
class AudioDataset(Dataset):
  A PyTorch dataset class to be used in the PyTorch DataLoader to create batches of the
Audio.
  ******
  def __init__(self, courses dir):
    Args:
       courses dir (String): Director containing the MFCC features for all the
                    audio in a single course
     self.courses dir = courses dir
     # self.audios paths = sorted(os.listdir(self.courses_dir), key = self.get_num)
     self.audios_paths = self.load_audio path()
  def load audio path(self):
     audio embeddings = []
     # Get sorted list of all courses (excluding any files)
     dirlist = []
     for fname in os.listdir(self.courses dir):
       if os.path.isdir(os.path.join(self.courses dir, fname)):
          dirlist.append(fname)
     for course number in sorted(dirlist, key=int):
              course audio path = os.path.join(self.courses dir, course number, 'audio-
features/')
       audio embedding path = [self.courses dir + course number + '/audio-features/' +
audio path for audio path in sorted(os.listdir(course audio path), key=self.get num)]
       audio embeddings.append(audio embedding path)
      return [val for sublist in audio embeddings for val in sublist] #Flatten the list of
lists
  def get num(self, str):
     return int(re.search(r'\d+', str).group())
  def len (self):
     return len(self.audios paths)
```

```
def getitem (self, idx):
     with open(self.audios paths[idx], 'rb') as fp:
       audio vectors = pickle.load(fp)
     audio vectors = np.transpose(audio vectors)
     audio_vectors = torch.from numpy(audio vectors)
     return audio vectors
class TargetDataset(Dataset):
  A Pytorch dataset class to be used in loading target dataset for training and evaluation
purpose.
  ,,,,,,
  def __init__(self, courses_dir):
    Args:
        courses dir (string): The directory containing the entire dataset.
     self.courses dir = courses dir
     self.target sentences path = self.load target sentences path()
     self.source sentences path = self.load source sentences path()
  def load target sentences path(self):
     target sentences = []
     dirlist = []
     for fname in os.listdir(self.courses dir):
       if os.path.isdir(os.path.join(self.courses dir, fname)):
          dirlist.append(fname)
     for course number in sorted(dirlist, key=int):
       target path = os.path.join(self.courses dir, course number, 'ground-truth/')
            target_sentence_path = [target path + target sentence for target sentence in
sorted([item for item in os.listdir(target path) if os.path.isfile(os.path.join(target path,
item)) and '.txt' in item and ' 'not in item], key=self.get num)]
       target sentences.append(target sentence path)
     return [val for sublist in target sentences for val in sublist] #Flatten the list of lists
  def load source sentences path(self):
     source sentences = []
     # Get sorted list of all courses (excluding any files)
     dirlist = []
     for fname in os.listdir(self.courses dir):
```

```
if os.path.isdir(os.path.join(self.courses dir, fname)):
          dirlist.append(fname)
     for course number in sorted(dirlist, key=int):
       source path = os.path.join(self.courses dir, course number, 'transcripts/')
            source sentence path = [source path + transcript path for transcript path in
sorted([item for item in os.listdir(source path) if os.path.isfile(os.path.join(source path,
item)) and '.txt' in item], key=self.get num)]
       source sentences.append(source sentence path)
     return [val for sublist in source sentences for val in sublist] #Flatten the list of lists
  def get num(self, str):
     return int(re.search(r'\d+', str).group())
  def len (self):
     return len(self.target sentences path)
  def getitem (self, idx):
    lines = []
     try:
       with open(self.source sentences path[idx]) as f:
          for line in f:
            if re.match(r'\d+:\d+', line) is None:
               line = line.replace('[MUSIC]', ")
               lines.append(line.strip())
     except Exception as e:
       logging.error('Unable to open file. Exception: ' + str(e))
       source_text = ' '.join(lines)
     source text = source text.lower()
     source sentences = sent tokenize(source text)
    lines = []
     try:
       with open(self.target sentences path[idx]) as f:
          for line in f:
            if re.match(r'\d+:\d+', line) is None:
               line = line.replace('[MUSIC]', ")
               lines.append(line.strip())
     except Exception as e:
```

```
logging.error('Unable to open file. Exception: ' + str(e))
    else:
       target_text = ' '.join(lines)
    # target text = target text.lower()
    target sentences = sent tokenize(target_text)
    for idx2 in range(len(target sentences)):
       target sentences[idx2] = target sentences[idx2].lower()
    target indices = []
    for target sentence in target sentences:
       # target indices.append(torch.Tensor([source sentences.index(target sentence)]))
       try:
                   target indices.append(torch.Tensor([self.get_index(source_sentences,
target sentence)]))
       except Exception as e:
         if False:
            print("Exception: " + str(e))
            print(self.target sentences path[idx])
            print(target sentence)
            print('\n\n----\n\n')
            print(source sentences)
            print('\n----\n')
         continue
      target indices.append(torch.Tensor([len(source sentences)]))
                                                                                       #
Appended the EOS token
                    return torch.stack(target indices), self.source sentences path[idx],
self.target sentences path[idx]
  def get index(self, source sentences, target sentence):
    for idx, sent in enumerate(source sentences):
       if target sentence in sent:
         return idx
```

12. Appendix C

Code for encoding.py

```
import numpy as np
import torch
import torchvision
import torch.nn as nn
import torch.nn.functional as F
from torch.nn.utils.rnn import pack padded sequence, pad packed sequence
class Embedding(nn.Module):
  Text Embedding layer used by MMBiDAF.
  This implementation is based on the BiDAF implementation by Chris Chute.
  Args:
    word vectors (torch.Tensor): Pre-trained word vectors.
    hidden size (int): Size of hidden activations.
    drop prob (float): Probability of zero-in out activations.
  def init (self, embedding size, hidden size, drop prob):
    super(Embedding, self). init ()
    self.drop prob = drop prob
    self.proj = nn.Linear(embedding size, hidden size, bias = False)
    self.hwy = HighwayEncoder(2, hidden size)
  def forward(self, x):
            emb = F.dropout(x, self.drop prob, self.training) # (batch size, seq len,
embed size)
    emb = self.proj(emb) # (batch size, seq len, hidden size)
    emb = self.hwy(emb) # (batch size, seq len, hidden size)
    return emb
class HighwayEncoder(nn.Module):
  """Encode an input sequence using a highway network.
  Based on the paper:
  "Highway Networks"
  by Rupesh Kumar Srivastava, Klaus Greff, Jürgen Schmidhuber
```

```
(https://arxiv.org/abs/1505.00387).
  Args:
    num layers (int): Number of layers in the highway encoder.
    hidden size (int): Size of hidden activations.
  ** ** **
  def init (self, num layers, hidden size):
    super(HighwayEncoder, self). init ()
    self.transforms = nn.ModuleList([nn.Linear(hidden_size, hidden_size)
                         for in range(num layers)])
    self.gates = nn.ModuleList([nn.Linear(hidden size, hidden size)
                      for in range(num layers)])
  def forward(self, x):
    for gate, transform in zip(self.gates, self.transforms):
       # Shapes of g, t, and x are all (batch size, seq len, hidden size)
       g = torch.sigmoid(gate(x))
       t = F.relu(transform(x))
       x = g * t + (1 - g) * x
    return x
class RNNEncoder(nn.Module):
  General-purpose layer for encoding a sequence using a bidirectional RNN.
  This encoding is for the text input data.
  The encoded output is the RNN's hidden state at each position,
  which has shape (batch size, seq len, hidden size * 2).
  Args:
       input size (int): Size of a single timestep in the input (The number of expected
features in the input element).
    hidden size (int): Size of the RNN hidden state.
    num layers (int): Number of layers of RNN cells to use.
    drop prob (float): Probability of zero-ing out activations.
  ,,,,,,
  def init (self, input size, hidden size, num layers, drop prob = 0.):
    super(RNNEncoder, self). init ()
    self.drop prob = drop prob
    self.rnn = nn.LSTM(input size, hidden size, num layers,
                batch first = True, bidirectional = True,
```

```
def forward(self, x, lengths):
    # Save the original padded length for use by pad packed sequence
    orig len = x.size(1)
    # Sort by length and pack sequence for RNN
    lengths, sort idx = lengths.sort(0, descending = True)
    x = x[sort idx] # (batch size, seq len, input size)
    x = pack padded sequence(x, lengths, batch first = True)
    # Apply RNN
    x_1 = self.rnn(x) \# (batch size, seq len, 2 * hidden size)
    # Unpack and reverse sort
    x, = pad packed sequence(x, batch first = True, total length = orig len)
    _, unsort_idx = sort_idx.sort(0)
    x = x[unsort idx] \# (batch size, seq len, 2 * hidden size)
    # Apply dropout (RNN applies after all but the last layer)
    x = F.dropout(x, self.drop prob, self.training)
    return x
class ImageEmbedding(nn.Module):
  This is the encoder layer for the images.
  The reference code has been taken from:
       https://github.com/sgrvinod/a-PyTorch-Tutorial-to-Image-Captioning/blob/master/
models.py
  This is from the paper Show, Attend and Tell.
  def init (self, encoded image size = 14):
     super(ImageEmbedding, self). init ()
     self.enc image size = encoded image size
    # I have used ResNet to extract the features, I could probably experiment with VGG
        resnet = torchvision.models.resnet101(pretrained = True) #Pretrained ImageNet
ResNet-101
```

dropout = drop prob if num layers > 1 else 0.)

```
# Remove linear and pool layers (since we are not doing classification)
    modules = list(resnet.children())[:-2]
     self.resnet = nn.Sequential(*modules)
    # Resize image to fixed size to allow input images of variable sizes
                    self.adaptive pool = nn.AdaptiveAvgPool2d((encoded image size,
encoded image size))
    self.fine tune()
  def forward(self, images):
    Forward propagation of the set of key frames extracted from the video.
    Args:
               images (torch. Tensor): The input image with dimension (batch size, 3,
image size, image size)
    Return:
       Encoded images
    out = self.resnet(images) # (batch size, 2048, image size/32, image size/32)
            out = self.adaptive pool(out) # (batch size, 2048, encoded image size,
encoded image size)
                out = out.permute(0, 2, 3, 1) # (batch size, encoded image size,
encoded image size, 2048)
    return out
  def fine tune(self, fine tune = True):
     Allow or prevent the calculation of gradients for convolutional blocks 2 through 4 of
the encoder.
    Args:
       fine tune (bool): Predicate to allow or prevent the gradient calculation.
    for p in self.resnet.parameters():
       p.requires grad = False
    # If fine-tuning, only fine-tune convolutional blocks 2 through 4
    for c in list(self.resnet.children())[5:]:
       for p in c.parameters():
         p.requires grad = fine tune
```

```
class AudioEncoder(nn.Module):
  This is the Audio encoding layer which encodes the audio features using BiLSTM.
   The code is inpired from the implementation of the paper Listen, Attend and Spell by
Alexander-H-Liu.
  https://github.com/Alexander-H-Liu/End-to-end-ASR-Pytorch/blob/master/src/asr.py
  Args:
    enc type: The encoder architecture available with - VGGBiRNN, BiRNN, RNN.
    sample rate: Sample rate for each RNN layer, concatenated with . For each layer,
             the length of ouput on time dimension will be input/sample rate.
        sample style: The down sampling mechanism, concat will concatenate multiplt
time steps,
                 according to sample rate into one vector, drop will drop the unsampled
timesteps.
     dim: Number of cells for each RNN layer (per direction), concatenated with.
    dropout: Dropout between each layer, concatenated with.
    rnn cell: RNN Cell of all layers.
   def init (self, example input, enc type, sample rate, sample style, dim, dropout,
rnn cell):
    super(AudioEncoder, self). init ()
    # Setting
    input dim = example input.shape[-1]
     self.enc type = enc type
    self.vgg = False
    self.dims = [int(v) for v in dim.split(' ')]
    self.sample rate = [int(v) for v in sample rate.split(' ')]
     self.dropout = [float(v) for v in dropout.split(' ')]
    self.sample style = sample style
    # Parameters checking
    assert len(self.sample rate)==len(self.dropout), 'Number of layer mismatch'
    assert len(self.dropout)==len(self.dims), 'Number of layer mismatch'
     self.num layers = len(self.sample rate)
     assert self.num layers>=1,'AudioEncoder should have at least 1 layer'
    # Construct AudioEncoder
    if 'VGG' in enc type:
       self.vgg = True
```

```
self.vgg extractor = VGGExtractor(example input)
                    input dim = self.vgg extractor.out dim
             for 1 in range(self.num layers):
                    out dim = self.dims[1]
                    sr = self.sample rate[1]
                    drop = self.dropout[1]
                    if "BiRNN" in enc type:
                             setattr(self, 'layer'+str(l), RNNLayer(input dim, out dim, sr, rnn cell=rnn cell,
dropout rate=drop,
                                                                                            bidir=True,sample style=sample style))
                    elif "RNN" in enc type:
                             setattr(self, 'layer'+str(l), RNNLayer(input dim, out dim, sr, rnn cell=rnn cell,
dropout rate=drop,
                                                                                            bidir=False, sample style=sample style))
                    else:
                           raise ValueError('Unsupported Encoder Type: '+enc type)
                   # RNN ouput dim = default output dim x direction x sample rate
                                     rnn out dim = out dim*max(1,2*('Bi' in enc type))*max(1,sr*('concat'==
sample style))
                    setattr(self, 'proj'+str(l),nn.Linear(rnn out dim,rnn out dim))
                    input dim = rnn out dim
      def forward(self,input x,enc len):
             if self.vgg:
                    input x,enc len = self.vgg extractor(input x,enc len)
             for 1 in range(self.num layers):
                                         input x, ,enc len = getattr(self, 'layer'+str(l))(input x, state len=enc len, len = getattr(self, 'layer'+str(l))(input x, state len = getattr(self, 'layer'+state len = getattr(self, 'layer'+s
pack input=True)
                    input x = torch.tanh(getattr(self, proj'+str(l))(input x))
             return input x,enc len
```

13. Appendix D

Code for Attention.py

```
import numpy as np
import torch
import torchvision
import torch.nn as nn
import torch.nn.functional as F
from torch.nn.utils.rnn import pack padded sequence, pad packed sequence
class BiDAFAttention(nn.Module):
  Bidirectional attention computes attention in two directions:
  The text attends to the modality (image/audio) and the modality attends to the text.
  The output of this layer is the concatenation of:
   [text, text2image attention, text * text2image attention, text * image2text attention]
or
  [text, text2audio attention, text * text2audio attention, text * audio2text attention]
  based on the modality used.
      This concatenation allows the attention vector at each timestep, along with the
embeddings
  from previous layers, to flow through the attention layer to the modeling layer.
  The output has shape (batch size, text length, 8 * hidden size)
  Args:
    hidden size (int): Size of hidden activations.
    drop prob (float): Probability of zero-ing out activations.
  def init (self, hidden size, drop prob=0.1):
     super(BiDAFAttention, self). init ()
    self.drop prob = drop prob
    self.text weight = nn.Parameter(torch.zeros(hidden size, 1))
    self.modality weight = nn.Parameter(torch.zeros(hidden size, 1))
    self.text modality weight = nn.Parameter(torch.zeros(1, 1, hidden size))
     for weight in (self.text weight, self.modality weight, self.text modality weight):
       nn.init.xavier uniform (weight)
     self.bias = nn.Parameter(torch.zeros(1))
  def forward(self, text, modality, text mask, modality mask):
```

```
batch size, text length, = text.size()
    modality length = modality.size(1)
    s = self.get similarity matrix(text, modality) # (batch size, text length,
modality length)
        text mask = text mask.view(batch size, text length, 1)
                                                                          # (batch size,
text length, 1)
          modality mask = modality mask.view(batch size, 1, modality length)
(batch size, 1, modality length)
      s1 = masked softmax(s, modality mask, dim=2)
                                                                          # (batch size,
text length, modality length)
       s2 = masked softmax(s, text mask, dim=1)
                                                                          # (batch size,
text length, modality length)
          # (batch size, text length, modality length) x (batch size, modality length,
hidden size) => (batch size, text length, hidden size)
    a = torch.bmm(s1, modality)
      # (batch size, text length, text length) x (batch size, text length, hidden size) =>
(batch size, text length, hidden size)
    b = torch.bmm(torch.bmm(s1, s2.transpose(1,2)), text)
     x = \text{torch.cat}([\text{text}, a, \text{text} * a, \text{text} * b], \text{dim} = 2) # (batch size, text length, 4)
* hidden size)
    return x
  def get similarity matrix(self, text, modality):
    Get the "similarity matrix" between text and the modality (image/audio).
       Concatenate the three vectors then project the result with a single weight matrix.
This method is more
    memory-efficient implementation of the same operation.
    This is the Equation 1 of the BiDAF paper.
    text length, modality length = text.size(1), modality.size(1)
     text = F.dropout(text, self.drop prob, self.training) # (batch size, text length,
hidden size)
      modality = F.dropout(modality, self.drop prob, self.training)
                                                                          # (batch size,
modality length, hidden size)
    # Shapes: (batch size, text length, modality length)
```

```
s0 = torch.matmul(text, self.text weight).expand([-1, -1, modality length])
          s1 = torch.matmul(modality, self.modality weight).transpose(1,2).expand([-1,
text length, -1])
    s2 = torch.matmul(text * self.text modality weight, modality.transpose(1,2))
    s = s0 + s1 + s2 + self.bias
    return s
def masked softmax(logits, mask, dim=-1, log softmax=False):
  """Take the softmax of `logits` over given dimension, and set
  entries to 0 wherever 'mask' is 0.
  Args:
    logits (torch. Tensor): Inputs to the softmax function.
    mask (torch. Tensor): Same shape as 'logits', with 0 indicating
       positions that should be assigned 0 probability in the output.
    dim (int): Dimension over which to take softmax.
    log softmax (bool): Take log-softmax rather than regular softmax.
       E.g., some PyTorch functions such as `F.nll loss` expect log-softmax.
  Returns:
    probs (torch. Tensor): Result of taking masked softmax over the logits.
  mask = mask.type(torch.float32)
  masked logits = mask * logits + (1 - mask) * -1e30
  softmax fn = F.log softmax if log softmax else F.softmax
  probs = softmax fn(masked logits, dim)
  return probs
class MultimodalAttentionDecoder(nn.Module):
  Used to calculate the hierarchical attention of the image/audio aware text vectors
  The code is inspired from the PyTorch tutorials:
  https://pytorch.org/tutorials/intermediate/seq2seq translation tutorial.html
  Args:
    hidden_size (int): The hidden size of the input features
  def init (self, hidden size, max text length, drop prob=0.1):
    super(MultimodalAttentionDecoder, self). init ()
    self.hidden size = hidden size
    self.drop_prob = drop prob
```

```
self.max text length = max text length
    self.gru = nn.GRU(hidden size * 2, hidden size * 2, batch first=True)
    self.att audio = nn.Linear(self.hidden size * 4, self.max text length)
    self.att img = nn.Linear(self.hidden size * 4, self.max text length)
#
      self.att mm = nn.Linear(self.hidden size * 6, self.max text length)
    self.att mm audio = nn.Linear(self.hidden size * 4, 1)
    self.att mm img = nn.Linear(self.hidden size * 4, 1)
    self.att combine = nn.Linear(self.hidden size * 6, self.hidden size * 2)
    self.out = nn.Linear(self.hidden size * 2, self.max text length)
  def forward(self, audio aware text, image aware text, hidden gru, text mask):
    out distributions = []
    for idx in range(self.max text length):
       if hidden gru is None:
         hidden gru = self.initHidden()
        audio aware text curr = audio aware text[:, idx:idx+1, :] # (batch size, 1, 2 *
hidden size)
        print(type(audio aware text curr))
       image aware text curr = image aware text[:, idx:idx+1,:] # (batch size, 1, 2 *
hidden size)
                                          attention weights audio
F.softmax(self.att audio(torch.cat((audio aware text curr, hidden gru), 2)), dim=2)
(batch size, 1, max text length)
       # print('attention weights audio {}'.format(attention weights audio.size()))
                       attention applied audio = torch.bmm(attention weights audio,
audio aware text) # (batch size, 1, 2 * hidden size)
       # print('attention applied audio {}'.format(attention applied audio.size()))
                                             attention weights img
F.softmax(self.att img(torch.cat((image aware text curr, hidden gru), 2)), dim=2)
(batch size, 1, max text length)
        attention applied img = torch.bmm(attention weights img, image aware text)
# (batch size, 1, 2 * hidden size)
                                              attention_weights_mm =
F.softmax(self.att mm(torch.cat((attention applied audio, attention applied img,
hidden gru), 2)), dim=1)
                                    attention weights mm audio =
F.softmax(self.att mm audio(torch.cat((attention applied audio, hidden gru), 2)),
dim=2) # (batch size, 1, 1)
```

```
# print('attention weights mm audio
{}'.format(attention weights mm audio.size()))
                                    attention weights mm img =
F.softmax(self.att mm img(torch.cat((attention applied img, hidden gru), 2)), dim=2)
# (batch size, 1, 1)
                                # print('attention weights mm audio
{}'.format(attention weights mm audio.size()))
                         attention applied mm = torch.bmm(attention weights mm,
attention applied audio) + torch.bmm(attention weights mm, attention applied img)
                   attention applied mm = torch.bmm(attention weights mm audio,
attention applied audio) + torch.bmm(attention weights mm img,
attention applied img) # (batch size, 1, 2 * hidden size)
      # print('attention applied mm {}'.format(attention applied mm.size()))
                                         final attention weights =
attention weights mm audio[0]*attention weights audio[0] +
attention weights mm img[0]*attention weights img[0]
  #
        print('final attention weights: {}'.format(final attention weights.size()))
                final out = torch.cat((audio aware text curr, image aware text curr,
                          # (batch size, 1, 6 * hidden size)
attention applied mm), 2)
      final out = self.att combine(final out) # (batch size, 1, 2 * hidden size)
      final out = F.relu(final out)
        final out, hidden gru = self.gru(final out, hidden gru)
                                                             # (batch size, 1, 2 *
hidden size)
        final out = masked softmax(self.out(final out), text mask, log softmax=False)
# (batch size, 1, max text length)
      final out = final out.squeeze(1)
      out distributions.append(final out)
    return out distributions
  def initHidden(self):
    return torch.zeros(1, 1, self.hidden size * 2)
```

14. Appendix E

Code for train.py

```
,,,,,,
Train a model on the MMS Dataset.
import copy
import logging
import os
import pickle
import random
from collections import OrderedDict
from json import dumps
import numpy as np
import seaborn as sns
import torch
import torch.nn as nn
import torch.nn.functional as F
import torch.optim as optim
import torch.optim.lr scheduler as sched
import torch.utils.data as data
import torchvision
import torchvision.transforms as transforms
from datasets import *
from models import MMBiDAF
from PIL import Image
from rouge import Rouge
# from tensorboardX import SummaryWriter
from tgdm import tgdm
from ujson import load as json load
from nltk.tokenize import sent tokenize
def main(course dir, text embedding size, audio embedding size, hidden size,
drop prob, max text length, out heatmaps dir, num epochs=100):
  # Get sentence embeddings
          train text loader = torch.utils.data.DataLoader(TextDataset(course dir,
max text length), batch size = 1, shuffle = False, num workers = 2)
  # Get Audio embeddings
```

```
train audio loader = torch.utils.data.DataLoader(AudioDataset(course dir), batch size
= 1, shuffle = False, num workers = 2)
  # Preprocess the image in prescribed format
    normalize = transforms.Normalize(mean=[0.485, 0.456, 0.406], std=[0.229, 0.224,
0.225
          transform = transforms.Compose([transforms.RandomResizedCrop(256),
transforms.RandomHorizontalFlip(), transforms.ToTensor(), normalize,])
          train image loader = torch.utils.data.DataLoader(ImageDataset(course dir,
transform), batch size = 1, shuffle = False, num workers = 2)
  # Load Target text
          train target loader = torch.utils.data.DataLoader(TargetDataset(course dir),
batch size = 1, shuffle = False, num workers = 2)
  # Create model
      model = MMBiDAF(hidden size, text embedding size, audio embedding size,
drop prob, max text length)
  # Get optimizer and scheduler
  optimizer = optim.Adadelta(model.parameters(), 1e-4)
  scheduler = sched.LambdaLR(optimizer, lambda s: 1.) # Constant LR
  # Let's do this!
  step = 0
  model.train()
  model.float()
  hidden state = None
  epoch = 0
  loss = 0
  eps = 1e-8
          with torch.enable grad(), tqdm(total=max(len(train text loader.dataset),
len(train image loader.dataset), len(train audio loader.dataset))) as progress bar:
                  for (batch text, original text length), batch audio, batch images,
(batch target indices, source path, target path) in zip(train text loader,
train audio loader, train image loader, train target loader):
      loss = 0
       # Setup for forward
       batch size = batch text.size(0)
       optimizer.zero grad()
       epoch += 1
       # Required for debugging
```

```
batch text = batch text.float()
       batch audio = batch audio.float()
       batch images = batch images.float()
       # Forward
               out distributions = model(batch text, original text length, batch audio,
torch.Tensor([batch audio.size(1)]), batch images, torch.Tensor([batch images.size(1)]),
hidden state)
       for batch, target indices in enumerate(batch target indices):
          for timestep, target idx in enumerate(target indices.squeeze(1)):
#
              print(target idx)
            prob = out distributions[timestep][batch, int(target idx)]
#
              print("Prob = {}".format(prob))
            loss += -1 * torch.log(prob + eps)
#
              print("Loss = {}".format(loss))
       # Generate summary
       print('Generated summary for iteration {}: '.format(epoch))
            summary = get generated summary(out distributions, original text length,
source path)
       print(summary)
       # Evaluation
       rouge = Rouge()
       rouge scores = rouge.get scores(source path, target path, avg=True)
       print('Rouge score at iteration {} is {}: '.format(epoch, rouge scores))
       # Generate Output Heatmaps
       sns.set()
       for idx in range(len(out distributions)):
             out distributions[idx] = out distributions[idx].squeeze(0).detach().numpy()
# Converting each timestep distribution to numpy array
         out_distributions = np.asarray(out distributions) # Converting the timestep list
to array
       ax = sns.heatmap(out distributions)
       fig = ax.get figure()
       fig.savefig(out heatmaps dir + str(epoch) + '.png')
       # Backward
       loss.backward(retain graph=True)
       optimizer.step()
       scheduler.step()
```

```
print('Loss for Epoch {} : '.format(epoch))
       print(loss)
#
         break
def get generated summary(out distributions, original text length, source path):
           out distributions = np.array([dist[0].cpu().detach().numpy() for dist in
out distributions]) # TODO: Batch 0
  generated summary = []
  for timestep, probs in enumerate(out distributions):
     if(probs[int(original text length)] == np.argmax(probs)):
       break
    else.
       max prob idx = np.argmax(probs, 0)
                       generated summary.append(get source sentence(source path[0],
max prob idx-1))
            # Setting the generated sentence's prob to zero in the remaining timesteps -
coverage?
       out distributions[:, max prob idx] = 0
  return generated summary
def get source sentence(source path, idx):
  lines = []
  try:
    with open(source path) as f:
       for line in f:
            if re.match(r'\d+:\d+', line) is None:
              line = line.replace('[MUSIC]', ")
              lines.append(line.strip())
  except Exception as e:
    logging.error('Unable to open file. Exception: ' + str(e))
  else:
    source text = ''.join(lines)
    source sentences = sent tokenize(source text)
     for i in range(len(source sentences)):
       source sentences[i] = source sentences[i].lower()
    return source sentences[idx]
if name == ' main ':
  course dir = '/home/anish17281/NLP Dataset/dataset/'
```

```
text_embedding_size = 300
audio_embedding_size = 128
hidden_size = 100
drop_prob = 0.2
max_text_length = 405
num_epochs = 100
out_heatmaps_dir = '/home/amankhullar/model/output_heatmaps/'
main(course_dir, text_embedding_size, audio_embedding_size, hidden_size, drop_prob, max_text_length, out_heatmaps_dir, num_epochs)
```