

## **Operating System**

**Prof. Vibhuti Patel,** Assistant Professor Parul Institute of Computer Application







#### **CHAPTER-3**

# **Memory Management**







#### **Needs for Memory Management**

- Memory is cheap today, and getting cheaper
  - But applications are demanding more and more memory, there is never enough!
- Memory Management, involves swapping blocks of data from secondary storage.
- Memory I/O is slow compared to a CPU
  - The OS must cleverly time the swapping to maximize the CPU's efficiency







### **Memory Management**

- Memory needs to be allocated to ensure a reasonable supply of ready processes to consume available processor time.
- Memory Management Requirements:
  - 1. Relocation
  - 2. Protection
  - 3. Sharing
  - 4. Logical organization
  - 5. Physical organization







#### 1. Relocation:

- programmer cannot know where the program will be placed in memory when it is executed
- a process may be (often) relocated in main memory due to swapping
- swapping enables the OS to have a larger pool of ready-to-execute processes
- memory references in code (for both instructions and data) must be translated to actual physical memory address







#### **Memory Management Terms**

Term	Description
Frame	Fixed-length block of main memory.
Page	Fixed-length block of data in secondary memory (e.g. on disk).
Segment	Variable-length block of data that resides in secondary memory.







#### 2. Protection:

- Processes should not be able to reference memory locations in another process without permission
- Impossible to check absolute addresses at compile time
- Must be checked at run time







#### 3. Sharing:

- must allow several processes to access a common portion of main memory without compromising protection
- Allow several processes to access the same portion of memory
- Better to allow each process access to the same copy of the program rather than have their own separate copy







#### 4. Logical Organization:

- users write programs in modules with different characteristics
- instruction modules are execute-only
- data modules are either read-only or read/write
- some modules are private others are public
- To effectively deal with user programs, the OS and hardware should support a basic form of module to provide the required protection and sharing







#### **5. Physical Organization:**

- secondary memory is the long term store for programs and data while main memory holds program and data currently in use
- moving information between these two levels of memory is a major concern of memory management (OS)
- it is highly inefficient to leave this responsibility to the application programmer







#### **Partitioning**

- A partition is a logical division of a hard disk that is treated as a separate unit by operating systems (OSes) and file systems.
- Types of Partitioning
  - 1. Fixed Partitioning
  - 2. Dynamic Partitioning
  - 3. Simple Paging
  - 4. Segmentation









- Partition main memory into a set of non overlapping regions called partitions
- Partitions can be of equal or unequal sizes

Operating System 8 M	
8 M	
8 M	
8 M	
8 M	
8 M	
8 M	
8 M	

Equal-size partitions

Operating System 8 M
2 M
4 M
6 M
8 M
8 M
12 M
16 M

Unequal-size partitions

Image source: Book





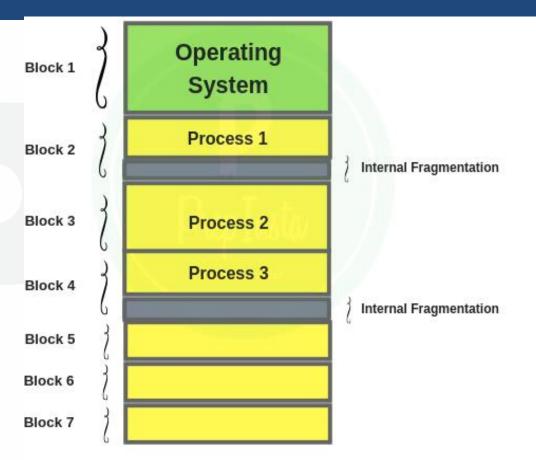
- any process whose size is less than or equal to a partition size can be loaded into the partition.
- if all partitions are occupied, the operating system can swap a process out of a partition.
- a program may be too large to fit in a partition. The programmer must then design the program with overlays.
- when the module needed is not present the user program must load that module into the program's partition, overlaying whatever program or data are there.







Main memory use is inefficient. Any program, no matter how small, occupies an entire partition. This is called internal fragmentation.









- To reduce internal fragmentation unequal size partition is used.
- Example: Programs up to 16M can be accommodated without overlay in figure.

Operating System 8M
2M
4M
6М
SM
SM
12M
16M







### Fixed Partitioning Placement Algorithms

#### **Equal-size Partitions:**

- If there is an available partition, a process can be loaded into that partition
- because all partitions are of equal size, it does not matter which partition is used
- If all partitions are occupied by blocked processes, choose one process to swap out to make room for the new process



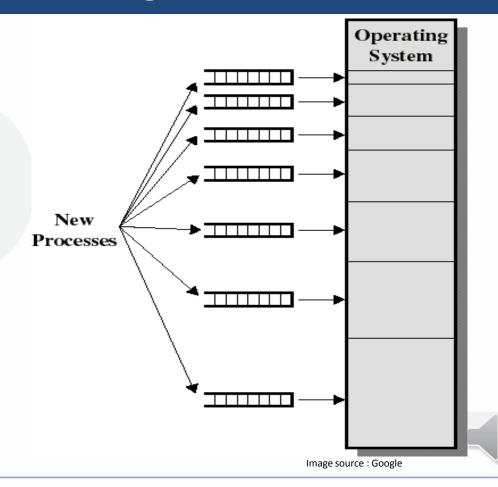




### **Fixed Partitioning Placement Algorithms**

# Unequal-size Partitions (Use of multiple queues):

- assign each process to the smallest partition within which it will fit
- A queue for each partition size
- tries to minimize internal fragmentation
- Problem: some queues will be empty if no processes within a size range is present



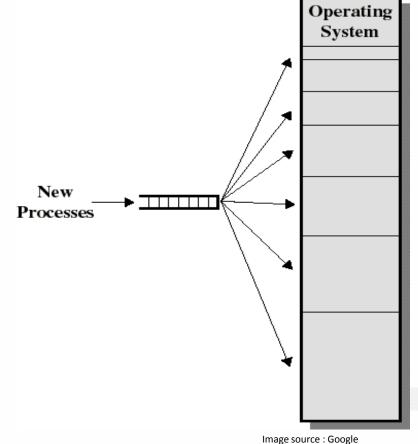




#### **Fixed Partitioning Placement Algorithms**

# Unequal-size Partitions (Use of single queue):

- When its time to load a process into main memory the smallest available partition that will hold the process is selected
- increases the level of multiprogramming at the expense of internal fragmentation



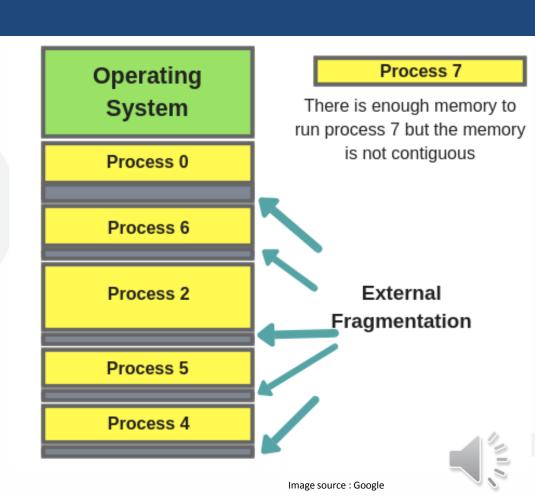






## **Dynamic Partitioning**

- Partitions are of variable length and number
- Each process is allocated exactly as much memory as it requires
- Eventually holes are formed in main memory. This is called external fragmentation.
- To reduce external fragmentation compaction is used.
- Must use compaction to shift processes so they are contiguous and all free memory is in one block.

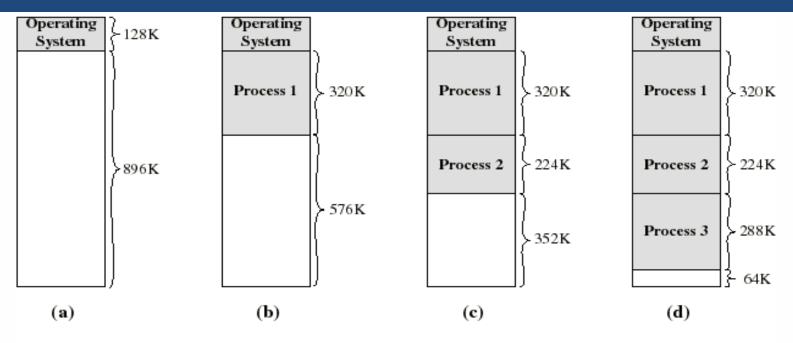








### **Dynamic Partitioning**



- A hole of 64K is left after loading 3 processes: not enough room for another process
- Eventually each process is blocked. The OS swaps out process 2 to bring in process 4









#### **Dynamic Partitioning**

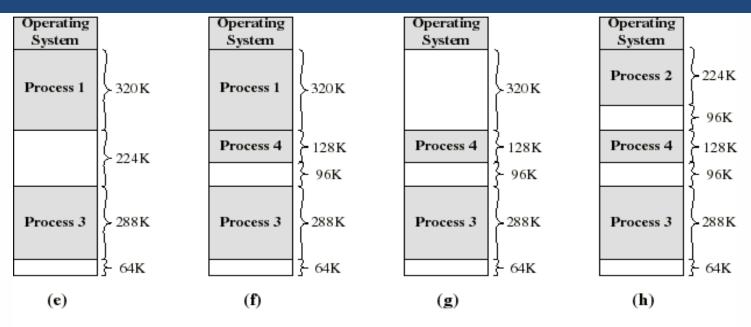


Image source : Google

- another hole of 96K is created
- Eventually each process is blocked. The OS swaps out process 1 to bring in again process 2 and another hole of 96K is created.
- Compaction would produce a single hole of 256K







### **Dynamic Partitioning Placement Algorithm**

- Used to decide which free block to allocate to a process
- Goal: to reduce usage of compaction (time consuming)
- Possible algorithms:
- Best-fit: choose smallest hole
- First-fit: choose first hole from beginning
- Next-fit: choose first hole from last placement

Example: Memory Configuration before & after allocation of 16 Kbytes Block

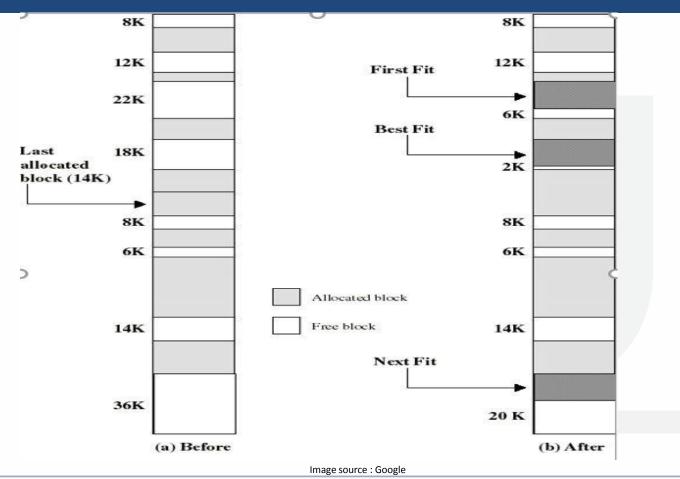








### **Dynamic Partitioning Placement Algorithm**







### **Buddy System**

- In a fixed partitioning scheme limits the number of active processes and may use space inefficiently if there is a poor match between available partition sizes and process sizes.
- A dynamic partitioning scheme is more complex to maintain and includes the overhead of compaction.
- An interesting compromise is the buddy system.







#### **Buddy System**

Example: 1-Mbyte initial block.

- The first request, A, is for 100 Kbytes, for which a 128K block is needed.
- The initial block is divided into two 512K buddies.
- The first of these is divided into two 256K buddies,
- and the first of these is divided into two 128K buddies,
- one of which is allocated to A.







### **Buddy System**

Example: 1-Mbyte initial block.

- The next request, B, requires a 256K block. Such a block is already available and is allocated.
- The process continues with splitting and coalescing occurring as needed.
- Note that when E is released, two 128K buddies are coalesced into a 256K block, which is immediately coalesced with its buddy





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## **Buddy System**

1 Mbyte block			1 N	M	
Request 100 K	A = 128K	128K	256K	512K	
Request 240 K	A = 128K	128K	B = 256K	512K	
Request 64 K	A = 128K	C = 64K 64K	B = 256K	512K	
Request 256 K	A = 128K	C = 64K 64K	B = 256K	D = 256K	256K
Release B	A = 128K	C = 64K 64K	256K	D = 256K	256K
Release A	128K	C = 64K 64K	256K	D = 256K	256K
Request 75 K	E = 128K	C = 64K 64K	256K	D = 256K	256K
Release C	E = 128K	128K	256K	D = 256K	256K
Release E		512K		D = 256K	256K
Release D			11	Л	

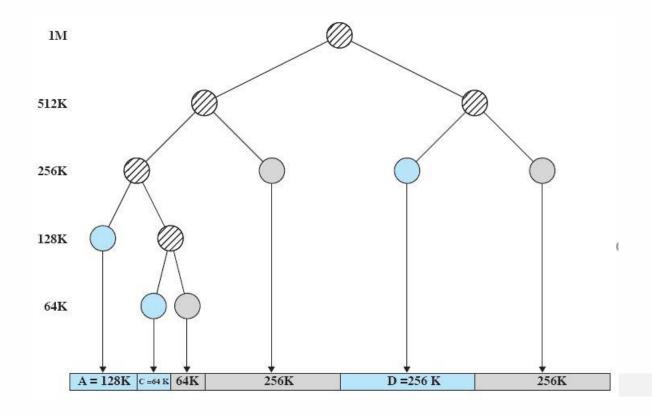








### **Tree Representation of Buddy System**









### **Simple Paging**

- Main memory is partition into equal fixed-sized chunks (of relatively small size)
- Track: each process is also divided into chunks of the same size called pages
- The process pages can thus be assigned to the available chunks in main memory called frames (or page frames)
- Consequence: a process does not need to occupy a contiguous portion of memory





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#### **Example of Process Loading – Simple Paging**

Frame number	Main memory
0	
1	
2	
3	
4	
5	
6	
7	
8	
9	
10	
11	
12	
13	
14	

(a) Fifteen	Available Pages
-------------	-----------------

	Main memory
0	A.0
1	A.1
2	A.2
3	A.3
4	
5	
6	
7	
8	
9	
10	
11	
12	
13	
14	

(b) Load Process A

	Main memory
0	A.0
1	A.1
2	A.2
3	A.3
4	B.0
5	B.1
6	B.2
7	
8	
9	
10	
11	
12	
13	
14	

(b) Load 1	Process E
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	Main memory
0	A.0
1	A.1
2	A.2
3	A.3
4	B.0
5	B.1
6	B.2
7	C.0
8	C.1
9	C.2
10	C.3
11	
12	
13	
14	

(d) Load Process C

Image source: Book

Now suppose that process B is swapped out





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### **Example of Process Loading – Simple Paging**

- When process A and C are blocked, the pager loads a new process D consisting of 5 pages
- Process D does not occupied a contiguous portion of memory
- There is no external fragmentation
- Internal fragmentation consist only of the last page of each process

	Main memory
0	A.0
1	A.1
2	A.2
3	A.3
4	
5	
6	
7	C.0
8	C.1
9	C.2
10	C.3
11	
12	
13	
14	

(0)	) Swap	out	В
(e	) Swap	out	D

0	A.0
1	A.1
2	A.2
3	A.3
4	D.0
5	D.1
6	D.2
7	C.0
8	C.1
9	C.2
10	C.3
11	D.3
12	D.4
13	_
14	

Main memory

(f) Load Process D







#### Page Table

0 0 1 1 2 2 3 3 Process A page table	0 — 1 — 2 — Process B page table	0 7 1 8 2 9 3 10 Process C page table	0 4 1 5 2 6 3 11 4 12 Process D page table	13 14 Free frame list
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Image source : Book

- The OS now needs to maintain (in main memory) a page table for each process
- Each entry of a page table consist of the frame number where the corresponding page is physically located
- The page table is indexed by the page number to obtain the frame number
- A free frame list, available for pages, is maintained





#### Segmentation

- Each program is subdivided into blocks of non-equal size called segments
- When a process gets loaded into main memory, its different segments can be located anywhere
- Each segment is fully packed with instructs/data: no internal fragmentation
- There is external fragmentation; it is reduced when using small segments







#### Segmentation

- In contrast with paging, segmentation is visible to the programmer
  - provided as a convenience to organize logically programs (ex: data in one segment, code in another segment)
  - must be aware of segment size limit
- The OS maintains a segment table for each process. Each entry contains:
  - the starting physical addresses of that segment.
  - the length of that segment (for protection)







#### **Virtual Memory**

- Virtual Memory: A computer can address more memory than the amount physically installed on the system. This extra memory is actually called virtual memory & it is a section of a hard disk that's set up to emulate the computer's RAM.
- Virtual Address: The address assigned to a location in virtual memory to allow that location to be accessed as though it were part of main memory.
- Virtual Address Space: The virtual storage assigned to a process.
- Address Space: The range of memory addresses available to a process.
- Real Address: The address of a storage location in a main memory.







### **Paging**

- Each process has its own page table
- Each page table entry contains the frame number of the corresponding page in main memory
- Two extra bits are needed to indicate:
  - whether the page is in main memory or not
  - Whether the contents of the page has been altered since it was last loaded
- (see next slide)

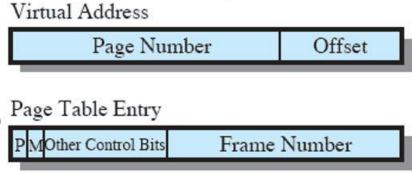






#### Page Table

- It is typical to associate a unique page table with each process.
- A bit is needed in each page table entry to indicate whether the corresponding page is present (P) in main memory or not.
- If the bit indicates that the page is in memory, then the entry also includes the frame number of that page.
- The page table entry includes a modify (M) bit, indicating whether the contents of the corresponding page have been altered since the page was last loaded







### Page Table

- Page tables are also stored in virtual memory
- When a process is running, part of its page table is in main memory







### **Replacement Policy**

• When all of the frames in main memory are occupied and it is necessary to bring in a new page, the replacement policy determines which page currently in memory is to be replaced.

#### Which page is replaced?

- Page removed should be the page least likely to be referenced in the near future
- How is that determined?
- Principal of locality again







#### **Replacement Algorithms**

There are certain basic algorithms that are used for the selection of a page to replace, they include

- Optimal
- Least recently used (LRU)
- •First-in-first-out (FIFO)







#### **Replacement Algorithms**

#### Example:

•An example of the implementation of these policies will use a page address stream formed by executing the program is

#### -232152453252

- •Which means that the first page referenced is 2,
- •the second page referenced is 3,
- •And so on.

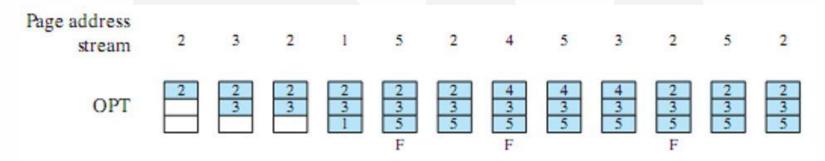






#### **Optimal Policy**

- Selects for replacement that page for which the time to the next reference is the longest
- But Impossible to have perfect knowledge of future events



F= page fault occurring after the frame allocation is initially filled

Image source : Book

 The optimal policy produces three page faults after the frame allocation has been filled.





#### **Least Recently Used (LRU) Policy**

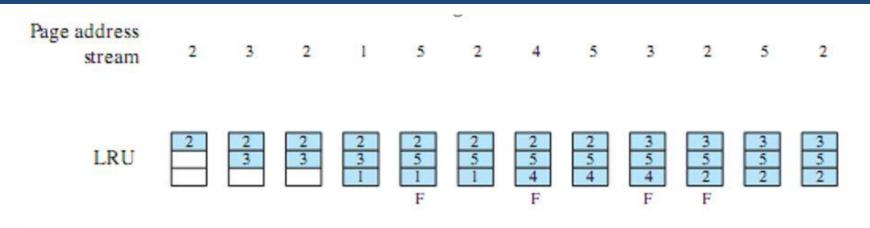
- Replaces the page that has not been referenced for the longest time
- By the principle of locality, this should be the page least likely to be referenced in the near future
- Difficult to implement
- One approach is to tag each page with the time of last reference.
- This requires a great deal of overhead.







#### **Least Recently Used (LRU) Policy**



F= page fault occurring after the frame allocation is initially filled

Image source : Book

- The LRU policy does nearly as well as the optimal policy.
- In this example, there are four page faults







#### First In First Out (FIFO) Policy

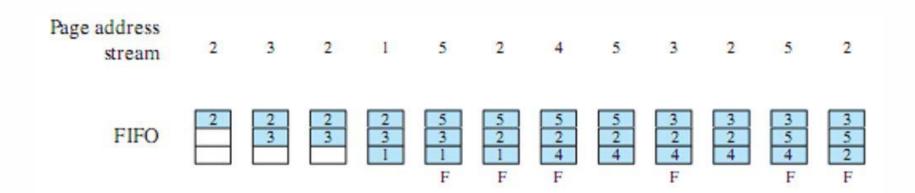
- Treats page frames allocated to a process as a circular buffer
- Pages are removed in round-robin style
  - Simplest replacement policy to implement
- Page that has been in memory the longest is replaced
  - But, these pages may be needed again very soon if it hasn't truly fallen out of use







#### First In First Out (FIFO) Policy



F= page fault occurring after the frame allocation is initially filled

Image source : Book

- The FIFO policy results in six page faults.
- Note that LRU recognizes that pages 2 and 5 are referenced more frequently than other pages, whereas FIFO does not.

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