

# Edge: Canny

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Dr. Tushar Sandhan

# Introduction

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- Single point thick edges

input



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Canny edges



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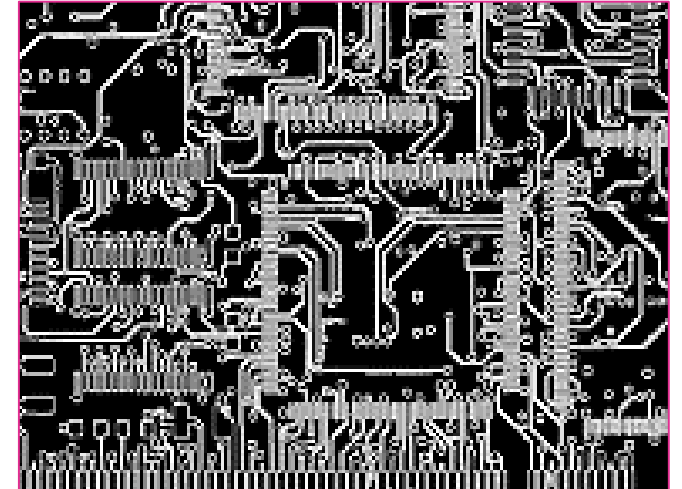
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Canny edges



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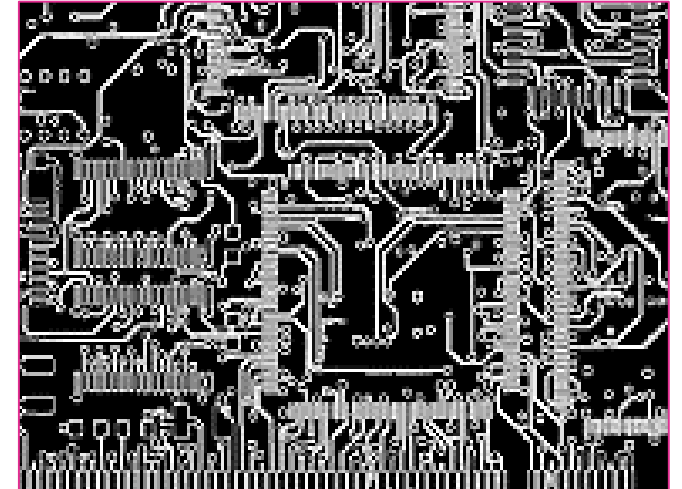
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Canny edges



Canny PCB edges



# Edge

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- What would be important steps in edge det.

# Edge

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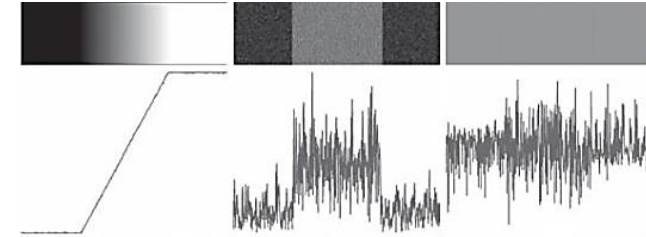
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  - Smooth derivatives



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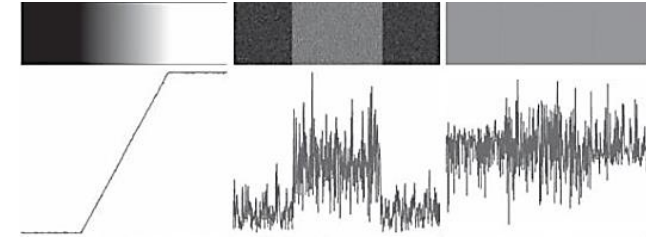
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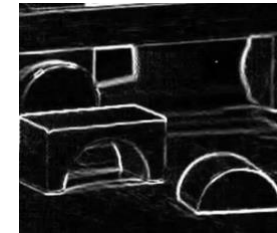
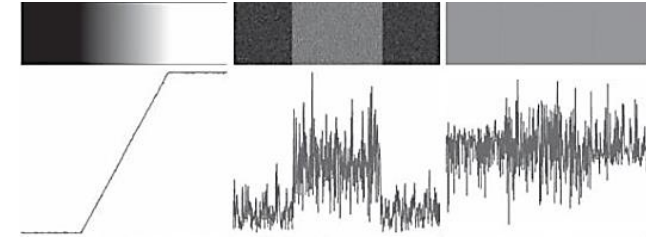
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- What would be important steps in edge det.
  - Smooth derivatives
  - Thresholding



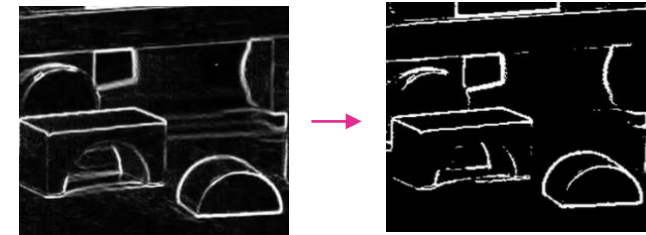
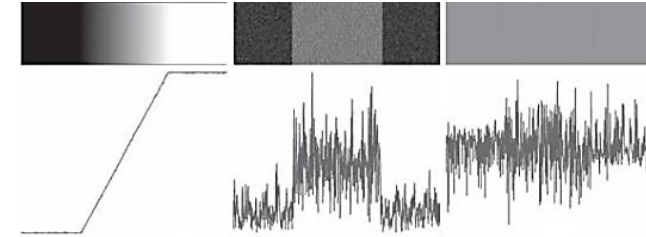
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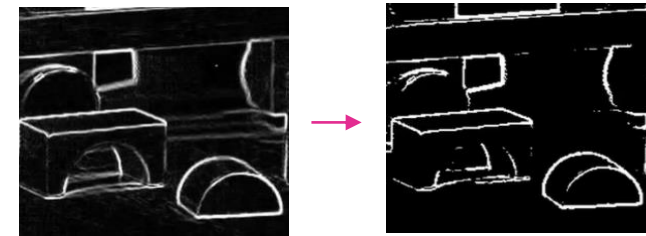
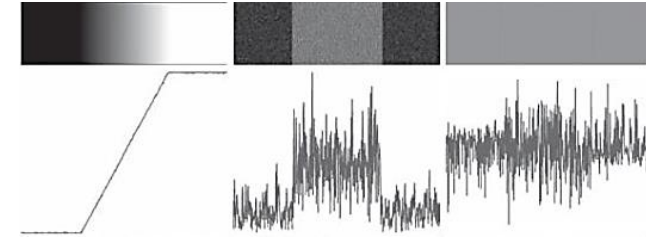
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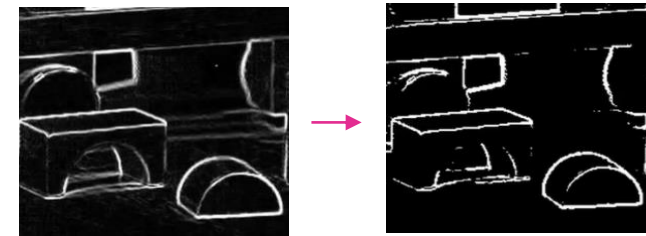
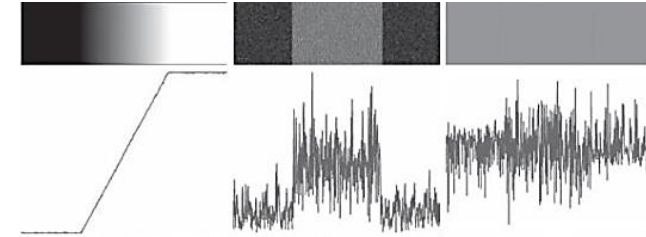
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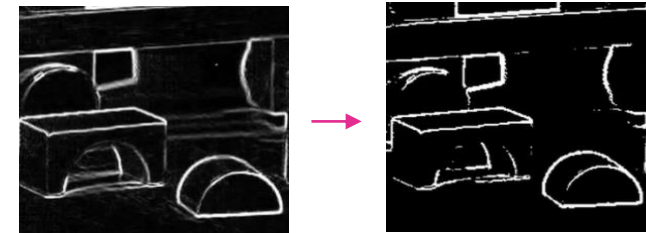
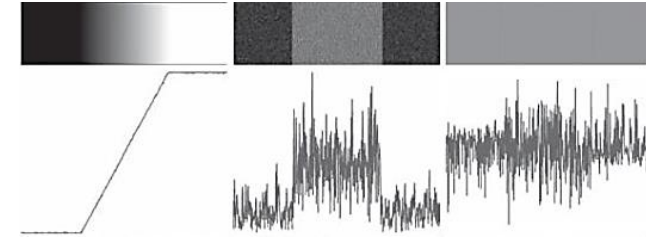
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  - Thinning
  - Linking



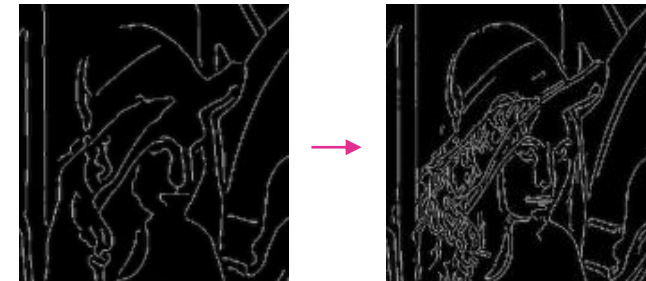
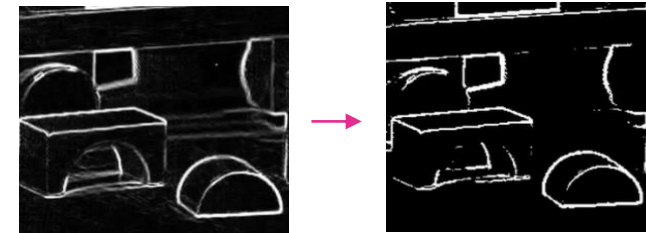
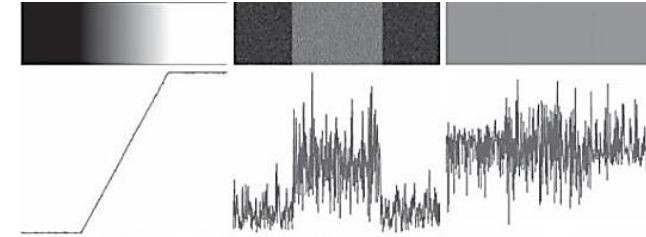
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# Canny edge detector

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# Canny edge detector

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    - all edges should be found

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  - all edges should be found
- good localization of edges
  - centre of true edge at  $i^{th}$  pixel :  $c_i$
  - obtained edge point at  $i^{th}$  pixel:  $e_i$
  - minimize the distance  $\|c_i - e_i\|_2$

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  - minimize the distance  $\|c_i - e_i\|_2$
- single point edge response
  - 1 point for each true edge point

# Canny edge detector

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- Image derivatives
  - input image  $f(x, y)$
  - smoothed  $f_s(x, y)$
  - any operator can be used to get  $g_x(x, y)$ ,  $g_y(x, y)$

$$G(x, y) = e^{-\frac{x^2 + y^2}{2\sigma^2}}$$

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  - $M_s(x, y)$  wide ridges around local maxima
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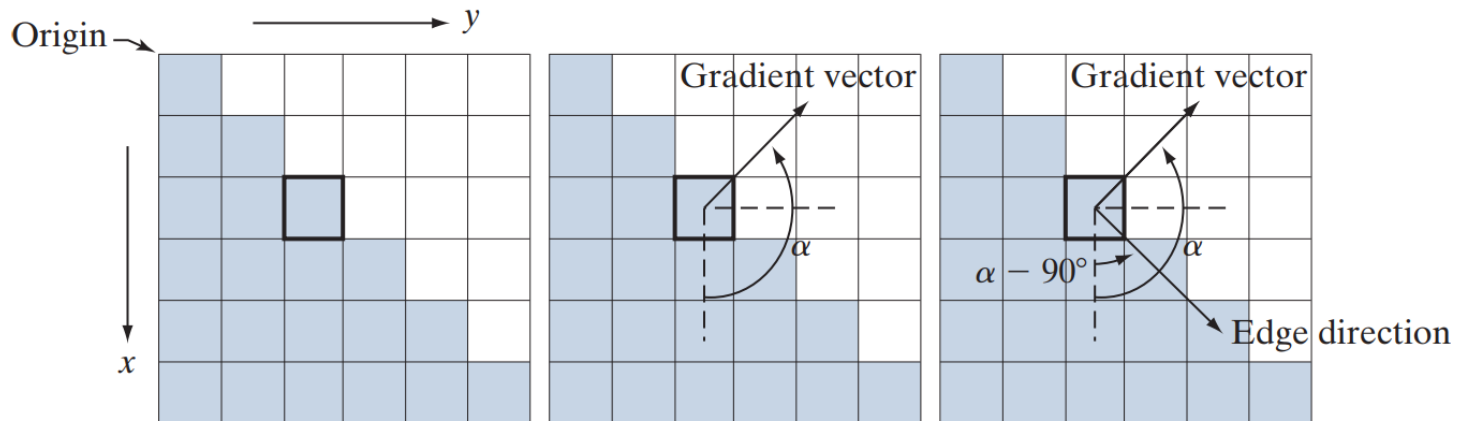
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checks whether pixel is local maxima  
in grad direction
  - linear interpolation for missing  
locations e.g. r, p

# Canny edge detector

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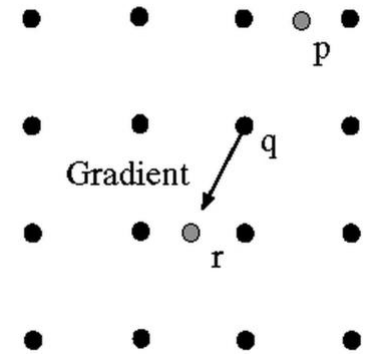
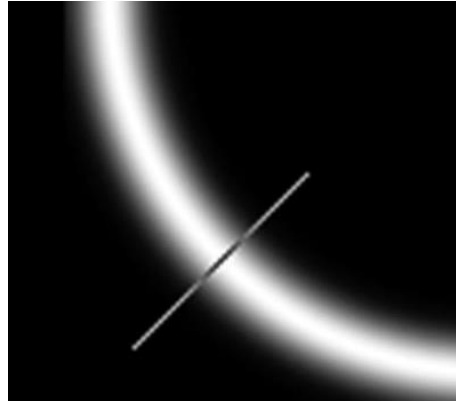
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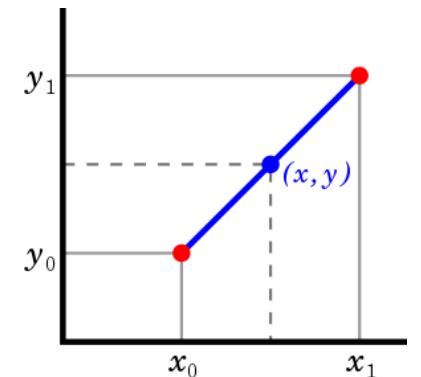
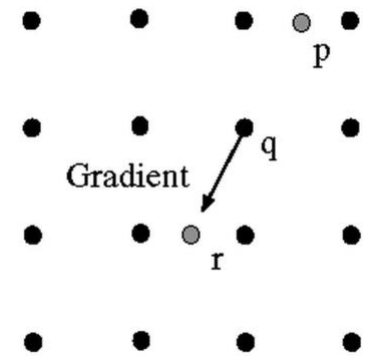
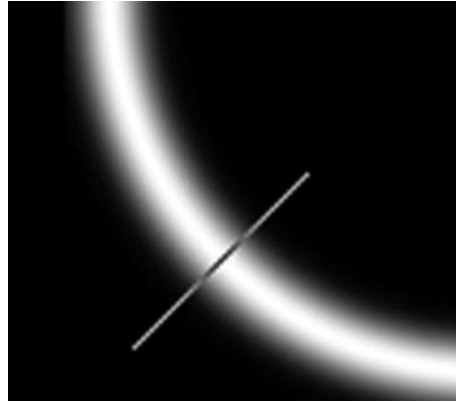
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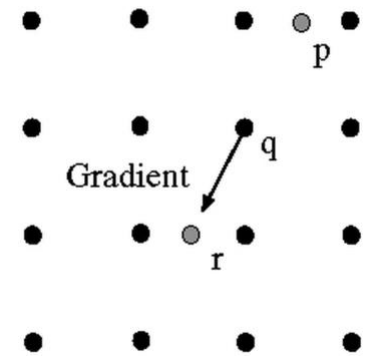
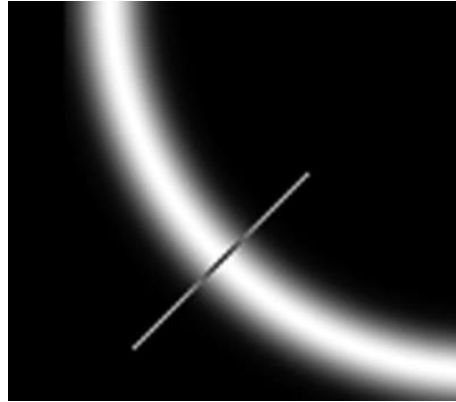
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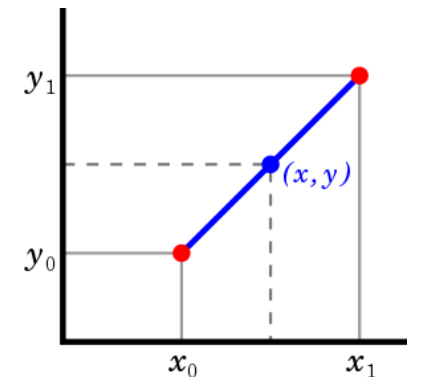


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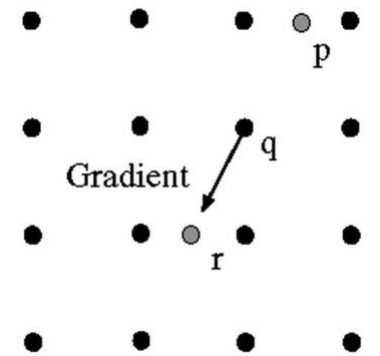
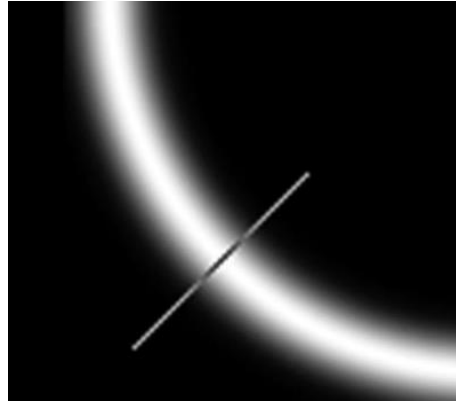


$$\frac{y - y_0}{x - x_0} = \frac{y_1 - y_0}{x_1 - x_0}$$



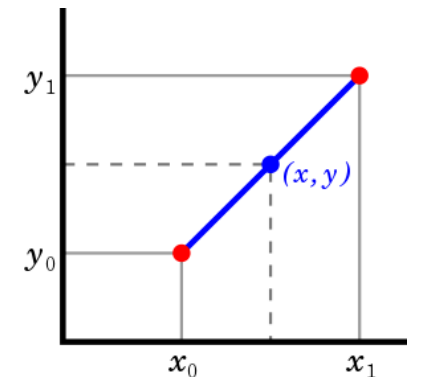
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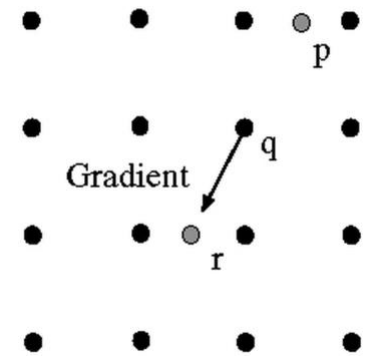
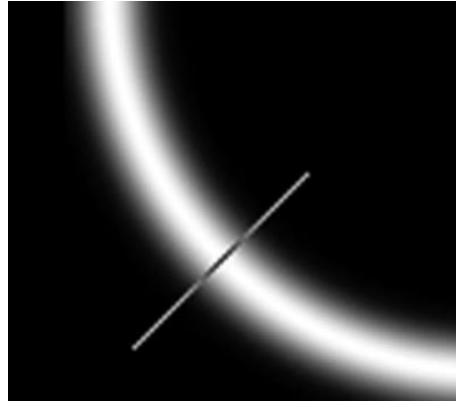
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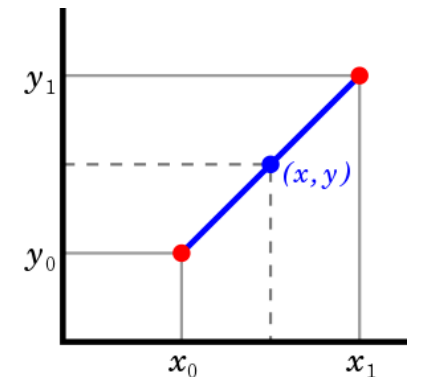
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$$= y_0 \left( 1 - \frac{x - x_0}{x_1 - x_0} \right) + y_1 \left( \frac{x - x_0}{x_1 - x_0} \right)$$



# Canny edge detector

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# Canny edge detector

---

- LINKING Points
  - Canny edge detector
    - It starts with one thing: gradients
    - In the end, it doesn't even matter: which operators have been used
  - at last we have to link the non-suppressed ones!



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  - two instruments of thresholds: Hysteresis



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    - It starts with one thing: gradients
    - In the end, it doesn't even matter: which operators have been used
  - at last we have to link the non-suppressed ones!
- two instruments of thresholds: Hysteresis
  - a. find all edge points using  $TH^{high}$
  - b. from each strong point follow the both side direction  $\perp$  to the edge normal
  - c. in that directions, construct the contours of connected edge points
  - d. mark all points greater than  $TH_{low}$



# Canny edge detector

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- Entire algorithm composition:

# Canny edge detector

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- Entire algorithm composition:
  1. Filter image with derivatives of Gaussian
  2. Get  $M, \alpha$
  3. Non-max suppression
    - thin multi-pixel wide edges to a single pixel widths
  4. Linking: the hysteresis
    - 2 thresholds:  $TH_{low}$  ,  $TH^{high}$
    - $TH^{high}$ : to start an edge
    - $TH_{low}$  : continue started edge

# Canny edge detector

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# Canny edge detector

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- Speeding up the beats of operations
  - binning the  $\alpha$  (angles)
  - 4 directions

# Canny edge detector

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Horizontal

+45 degrees

Vertical

-45 degrees



# Canny edge detector

- Speeding up the beats of operations

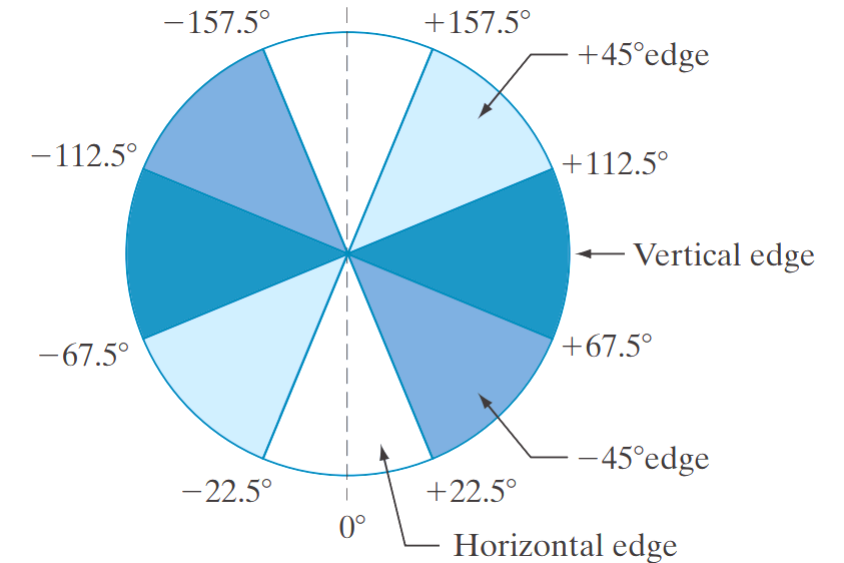
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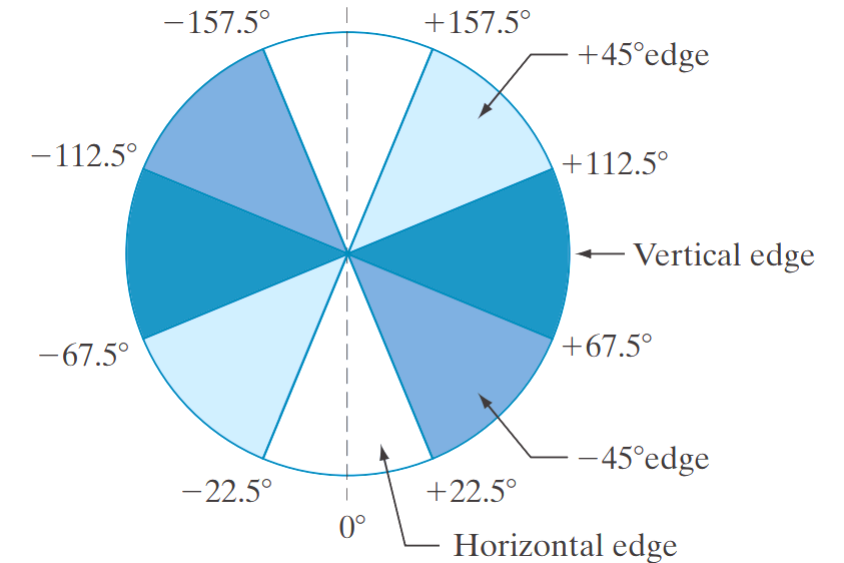
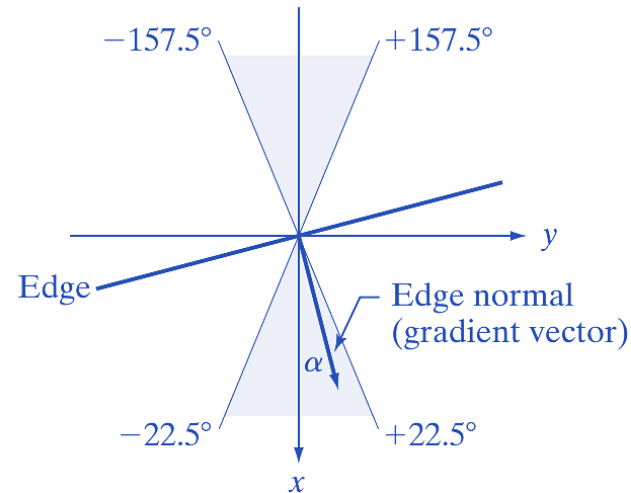
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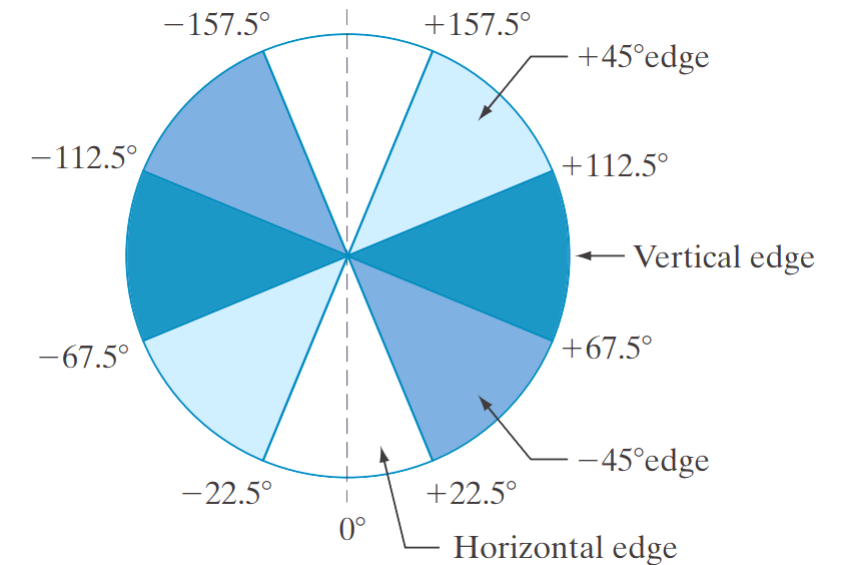
Vertical

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# Canny edge detector

- Speeding up the beats of operations
  - binning the  $\alpha$  (angles)
    - get the directional bin  $Bin()$  closest to  $\alpha$
    - from previous operations edge:  $M(x, y)$
    - suppression
      - If  $M(x', y') > M(x, y)$  then  $M(x, y) \rightarrow 0$
      - where neighbors  $x', y' \leftarrow Bin(x, y)$



# Canny edge detector

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- Varying  $\sigma$

input



# Canny edge detector

---

- Varying  $\sigma$

input



# Canny edge detector

- Varying  $\sigma$

input



# Canny edge detector

- Varying  $\sigma$

input



$\sigma$  small





# Canny edge detector

- Varying  $\sigma$

input



$\sigma$  small



$\sigma$  large





# Canny edge detector

---

- Comparing other edge detectors

input



# Canny edge detector

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- Comparing other edge detectors

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Sobel with TH



# Canny edge detector

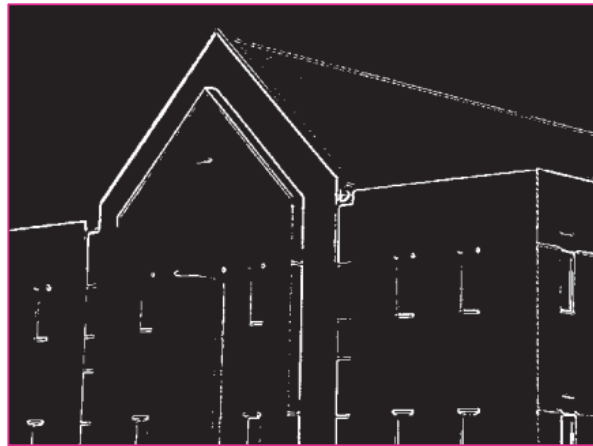
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- Comparing other edge detectors

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Sobel with TH



LoG zero crossings



# Canny edge detector

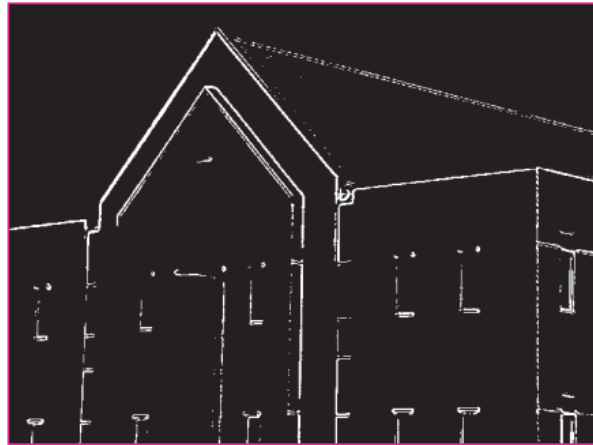
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Sobel with TH



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Canny

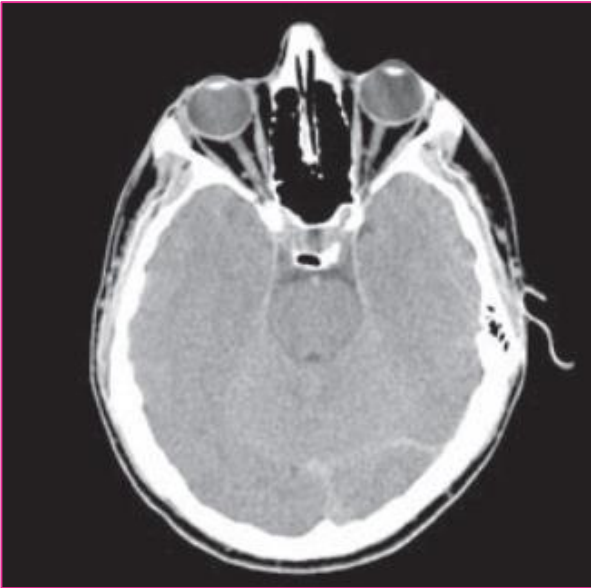


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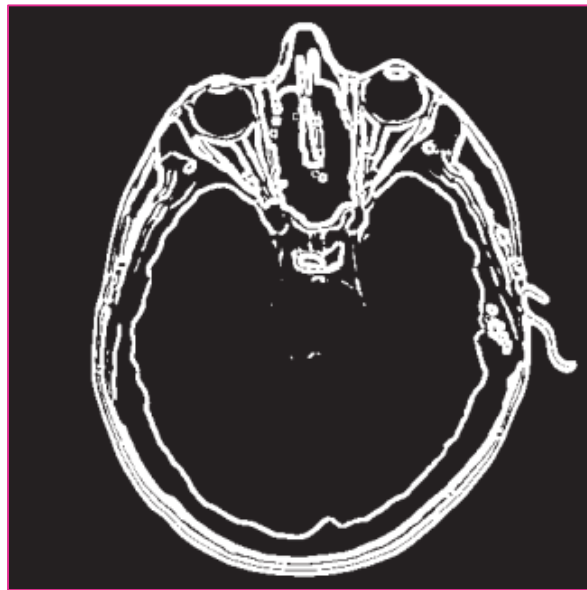
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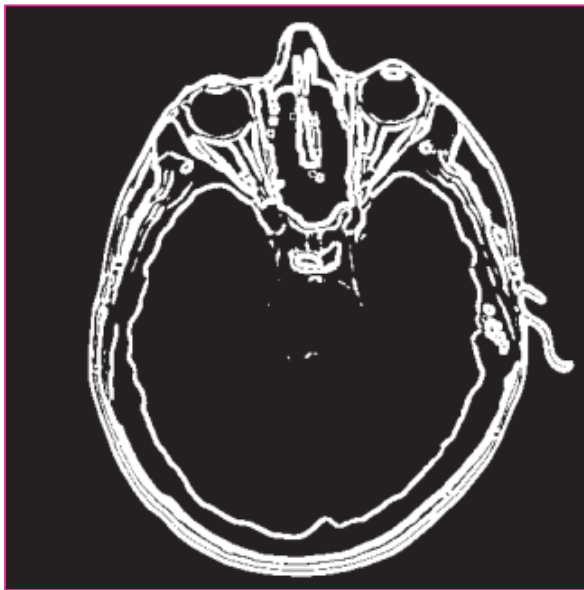
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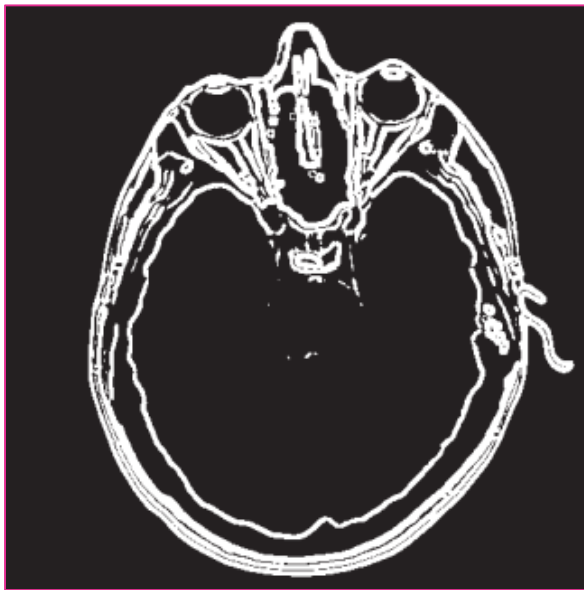
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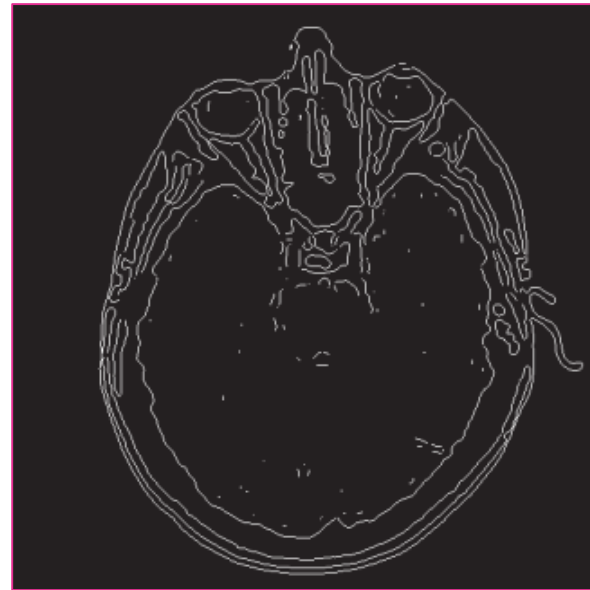
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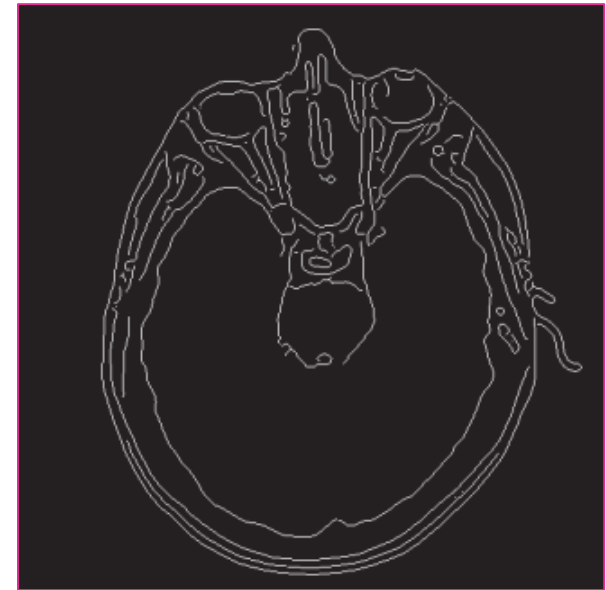
Sobel with TH



LoG zero crossings



Canny





# A canny player with a Canny edge!

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# A canny player with a Canny edge!

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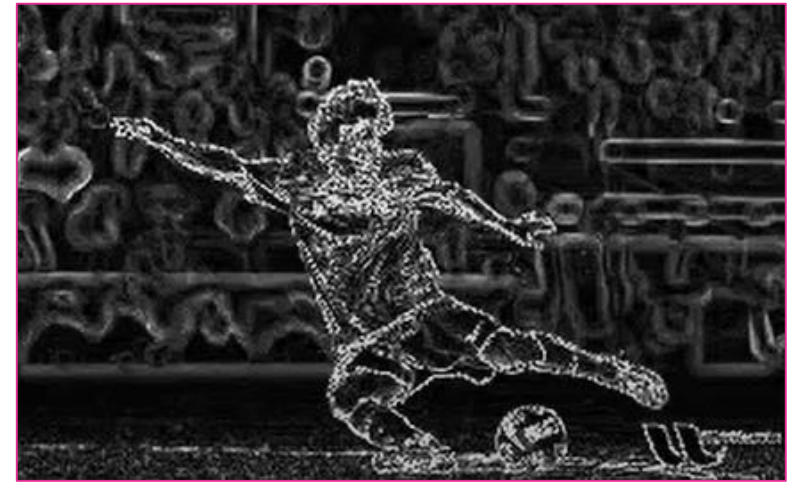
Messi

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Messi

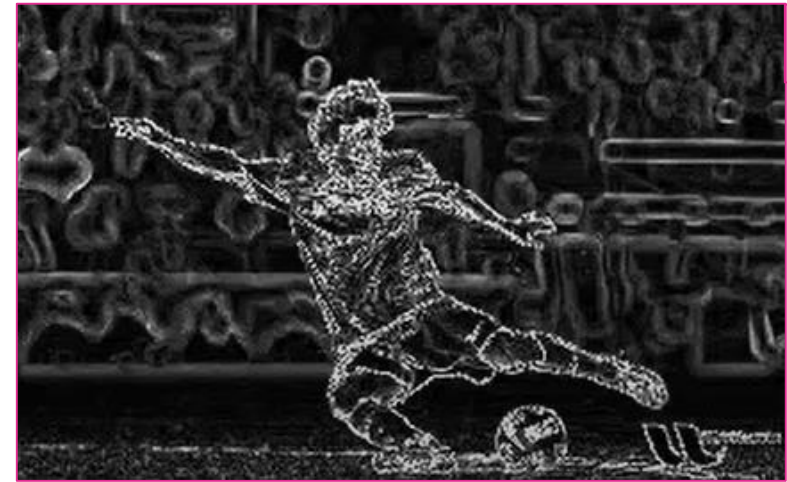


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Messi

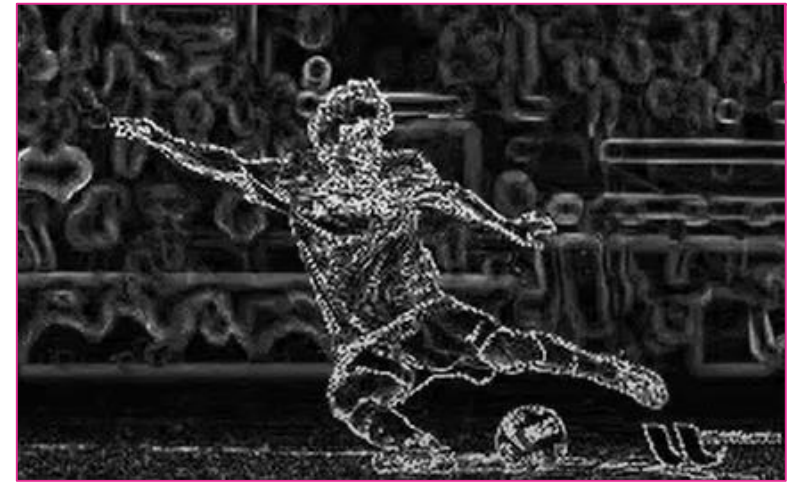


Sobel

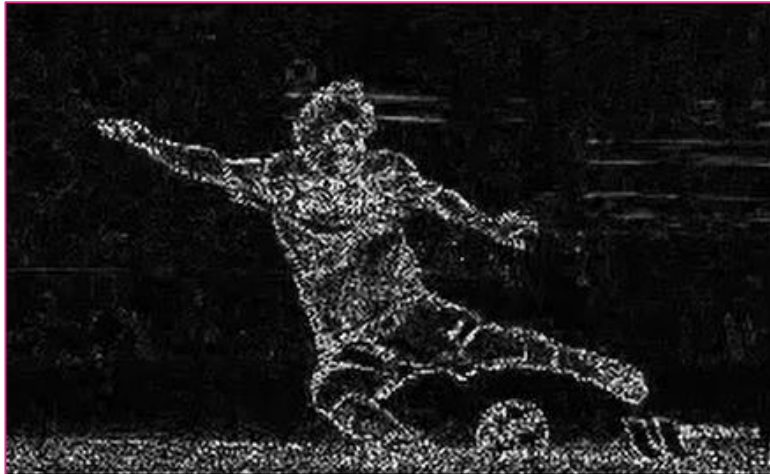
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Messi



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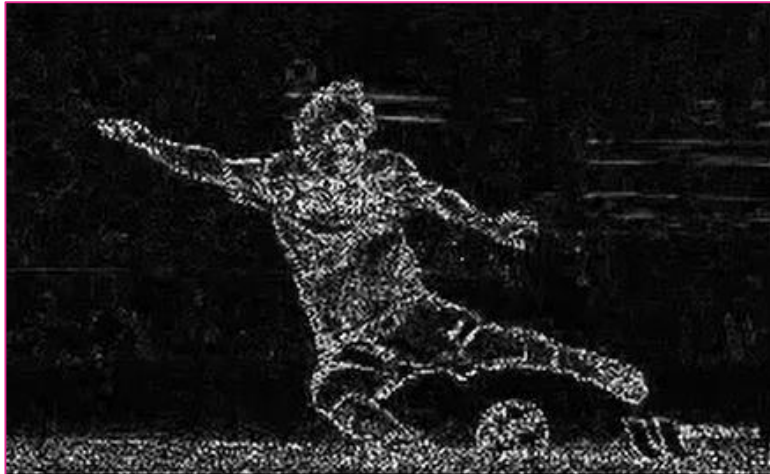
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Messi



Sobel



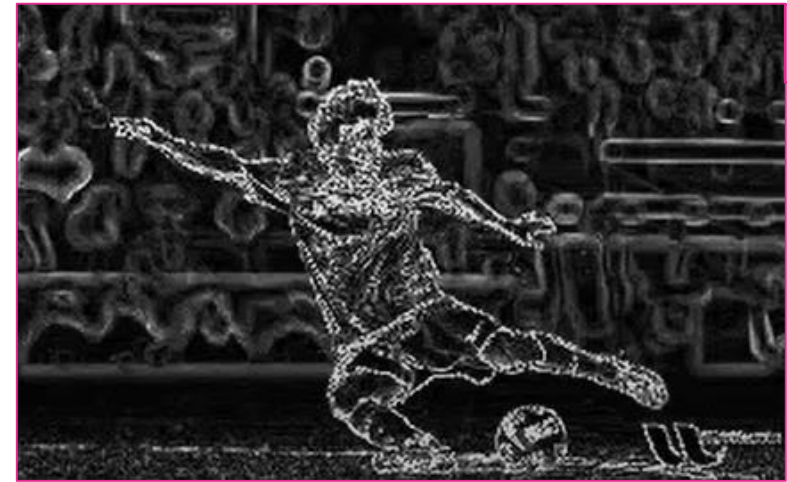
Laplacian



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Messi



Sobel



Laplacian



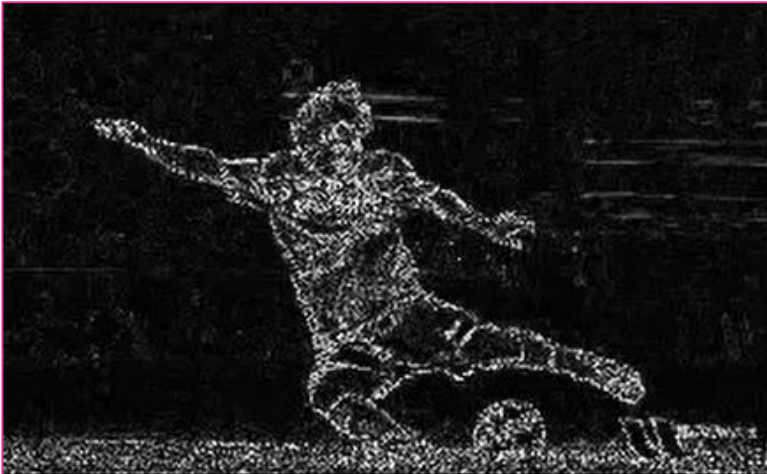
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Messi



Sobel



Laplacian



Canny

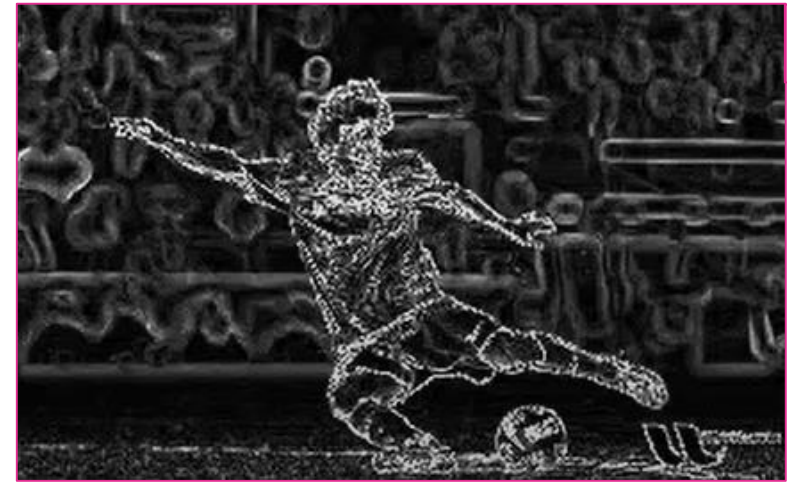


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Messi

who will you  
go with?



Sobel



Laplacian



Canny

# Conclusion

- Canny edge detector

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❑ Single point thick edges

❑ Canny operations

- Thinning: non-max suppression
- Linking: double TH hysteresis
- High accuracy is paid via computational expenses

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Go with a 'canny' player, for accuracy



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