

Segmentation:

Regions & K-means

Dr. Tushar Sandhan

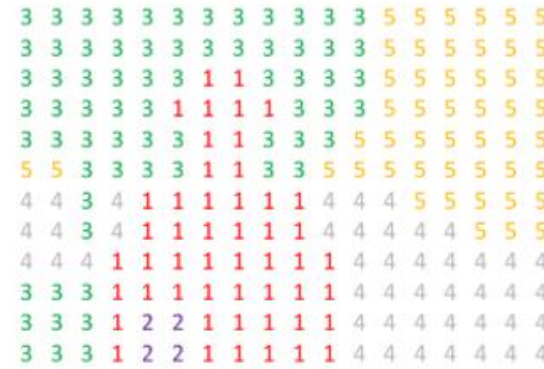
Introduction

- Goal of segmentation



segmented →

1: Person
2: Purse
3: Plants/Grass
4: Sidewalk
5: Building/Structures



Introduction

- Goal of segmentation

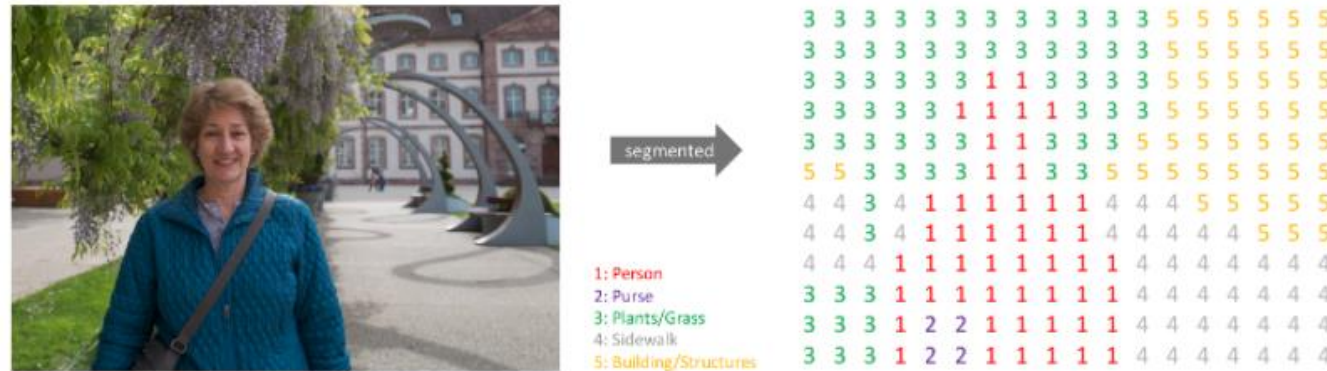


Image credit: J. Jordan

Region growing

- Partition the image I into m regions
 - every pix belong to some region
 - each pix is assigned to only one region
 - all pix in a region, share similar property
 - all pix in diff. regions have distinct properties
 - Prerequisites:
 1. seed points
 2. similarity measures
 3. stopping criterion

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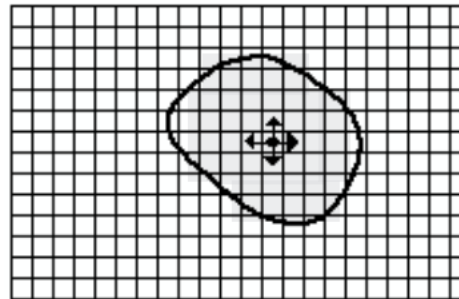
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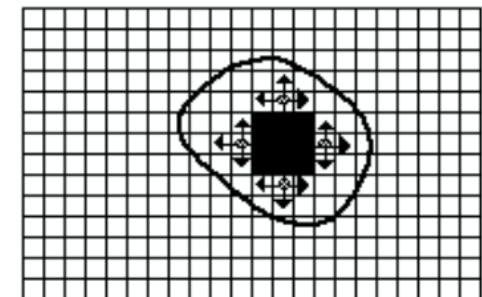
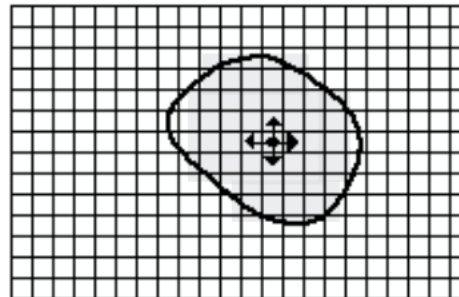


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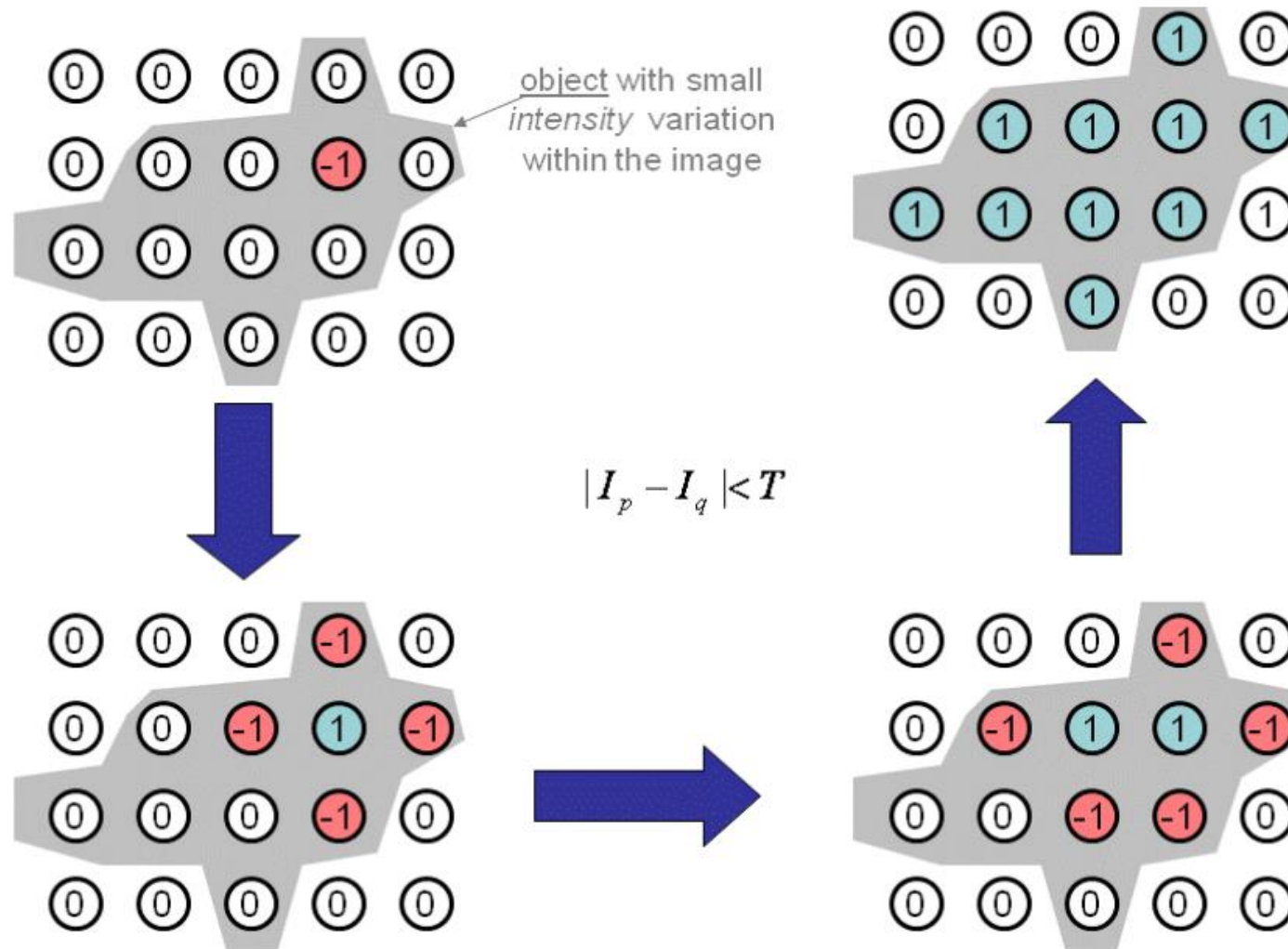
after few iterations

Region growing

■ Partition and grow

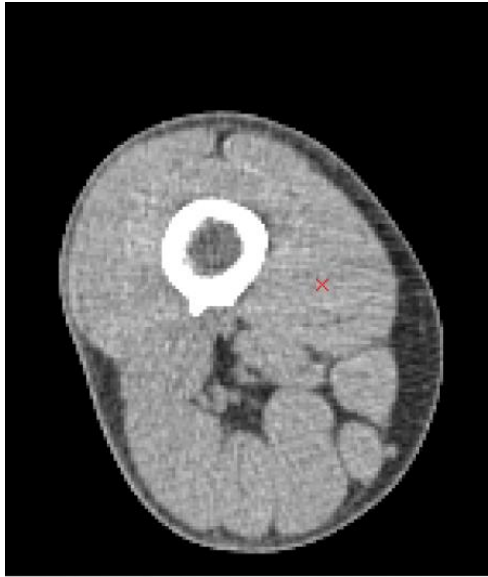
- Start with a seed point s_j for region R_j
 - For every s_j
 - Initialize mean intensity of each region: $\mu_j = s_j$
 - Initialize region: $R_j = \{s_j\}$
 - For each point p in R_j
 - Get its 4-connect neighborhood: $\mathcal{N}_i(p)$, $i = 1, 2, 3, 4$
 - If $|\mathcal{N}_i(p) - \mu_j| < \tau$, $\mathcal{N}_i(p) \notin \mathcal{R}_k$ $j \neq k$
 - $\mathcal{R}_j \leftarrow \mathcal{R}_j \cup \mathcal{N}_i(p)$
 - update μ_j
 - Stop growing when no neighborhood pixel matches
 - Move to the next seed point, until the whole image is partitioned.
-

Region growing



Region growing: CT scan

- Seed-1

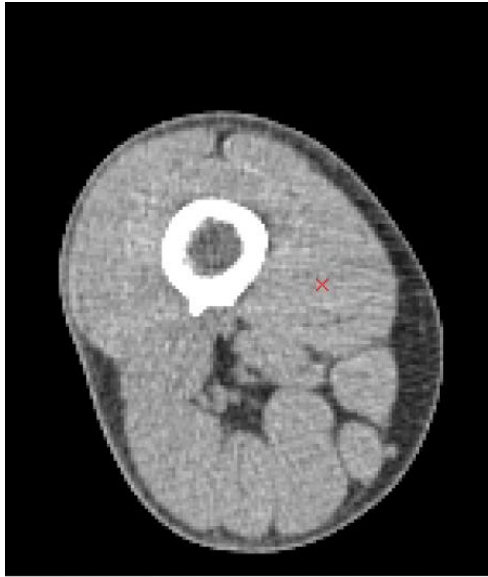


stricter
similarity

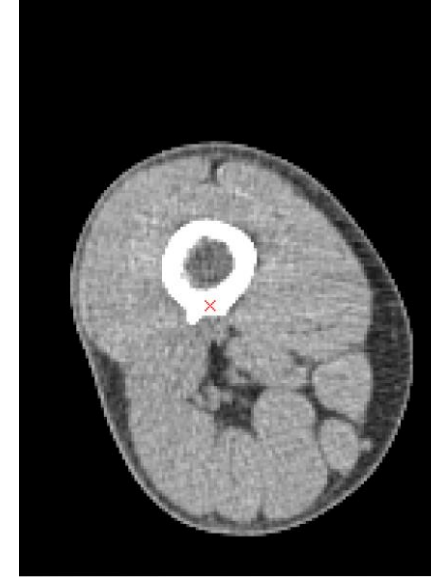


Region growing: CT scan

■ Seed-1



■ Seed-2



stricter
similarity



Comparative example

3	5	7	3	4	2	1
2	4	9	10	22	9	3
3	5	12	11	15	10	3
5	6	11	9	17	19	1
2	3	11	12	18	16	2
3	6	8	10	18	9	5
4	6	7	8	3	3	1

3	5	7	3	4	2	1
2	4	9	10	22	9	3
3	5	12	11	15	10	3
5	6	11	9	17	19	1
2	3	11	12	18	16	2
3	6	8	10	18	9	5
4	6	7	8	3	3	1

threshold $T \geq 10$

3	5	7	3	4	2	1
2	4	9	10	22	9	3
3	5	12	11	15	10	3
5	6	11	9	17	19	1
2	3	11	12	18	16	2
3	6	8	10	18	9	5
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threshold $T \geq 11$

3	5	7	3	4	2	1
2	4	9	10	22	9	3
3	5	12	11	15	10	3
5	6	11	9	17	19	1
2	3	11	12	18	16	2
3	6	8	10	18	9	5
4	6	7	8	3	3	1

threshold $T \geq 12$

3	5	7	3	4	2	1
2	4	9	10	22	9	3
3	5	12	11	15	10	3
5	6	11	9	17	19	1
2	3	11	12	18	16	2
3	6	8	10	18	9	5
4	6	7	8	3	3	1

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region growing with variance of 2 in respect to value 11 with reference to threshold $T \geq 11$

Region splitting & merging

- Split
 - sub-quadrants
 - e.g. 4 parts: quadregions
 - quadtree (having leaves as quadregions or quadimages)
 - continuous splitting
 - adjacent quadimages will be having identical properties

Region splitting & merging

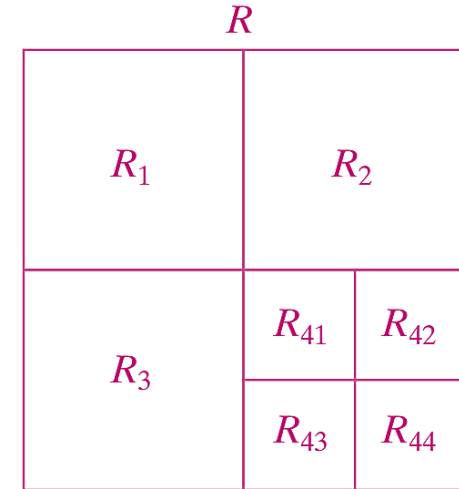
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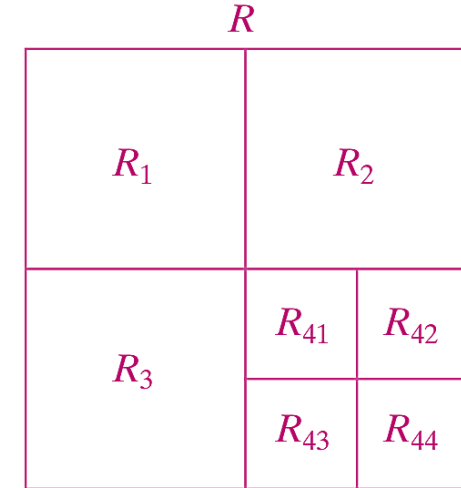
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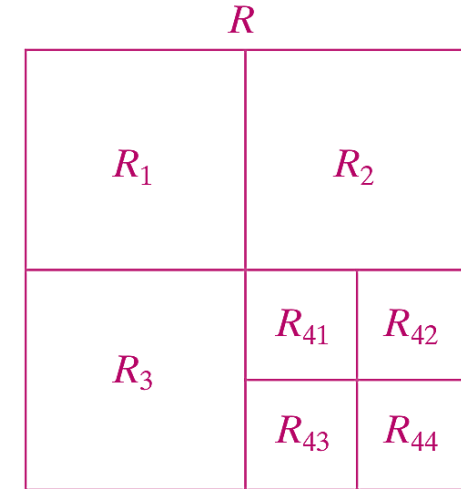
■ Merging

- quadimages that satisfy closeness in similarity criterion
 - quadimages to be merged should be adjacent
 - merging begins when no further splitting is possible

Region splitting & merging

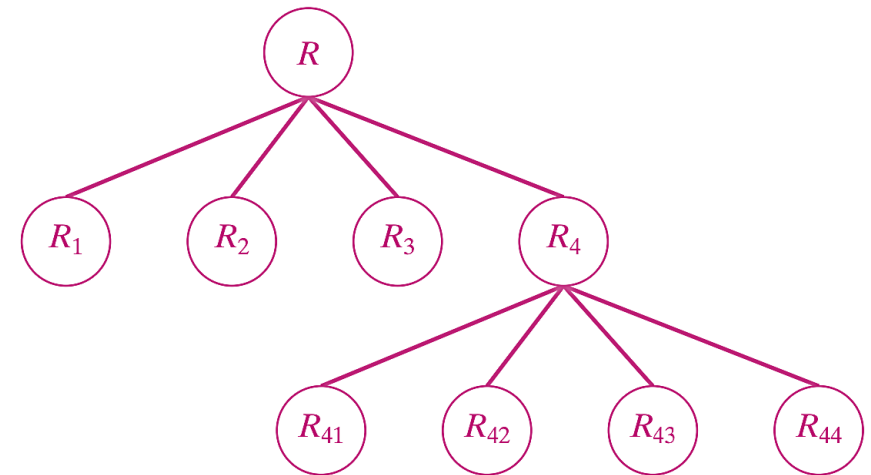
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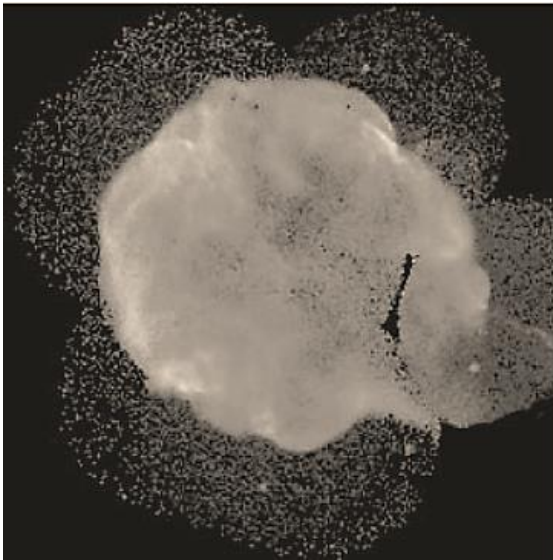
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Region splitting & merging

- Segment the ring of supernova
 - quadimages size 32x32, 16x16 & 8x8
 - variance and mean of quadimages can be used as merging criterion

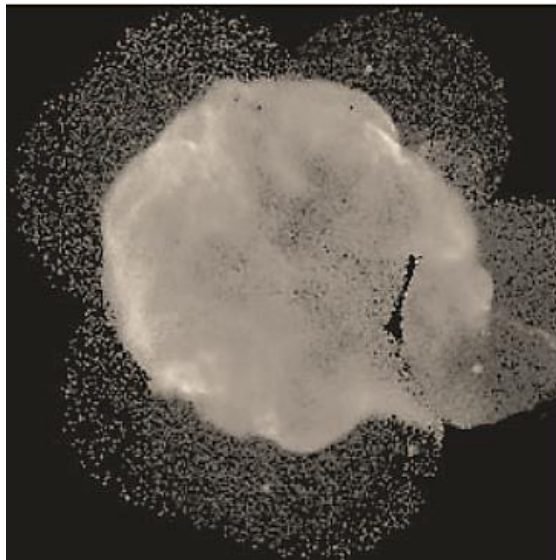
X-ray band image



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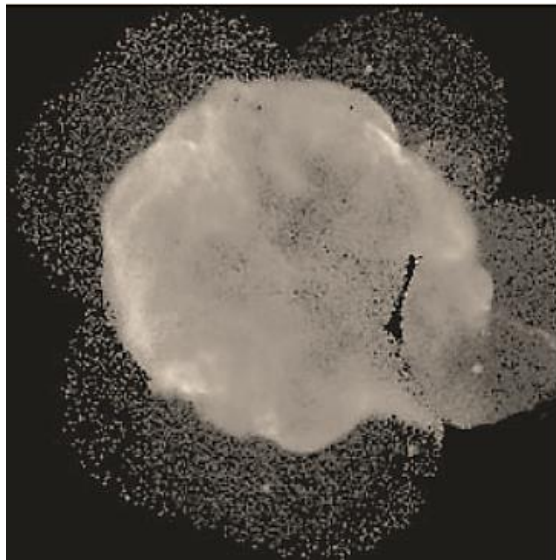
32x32



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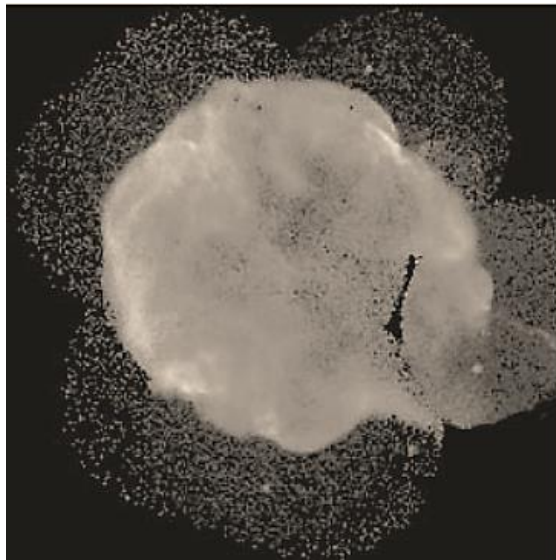
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32x32



16x16



8x8



Clustering



Clustering

- Organizing data into multiple (#clusters) classes s.t.:
 - intra-class variance is low (high similarity)
 - inter-class variance is high (low similarity)
- Unsupervised learning paradigm
 - finding class labels directly from data
 - training data labels are not available
- What are similarity measures:
 - distance
 - e.g. euclidian, cosine
 - density
 - e.g. amount of neighbourhood

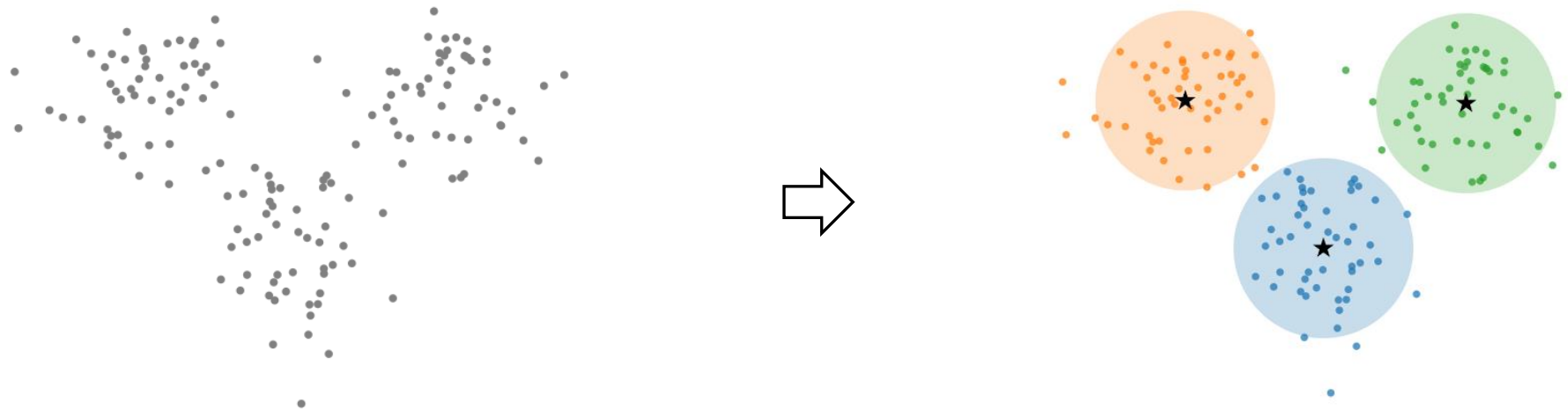
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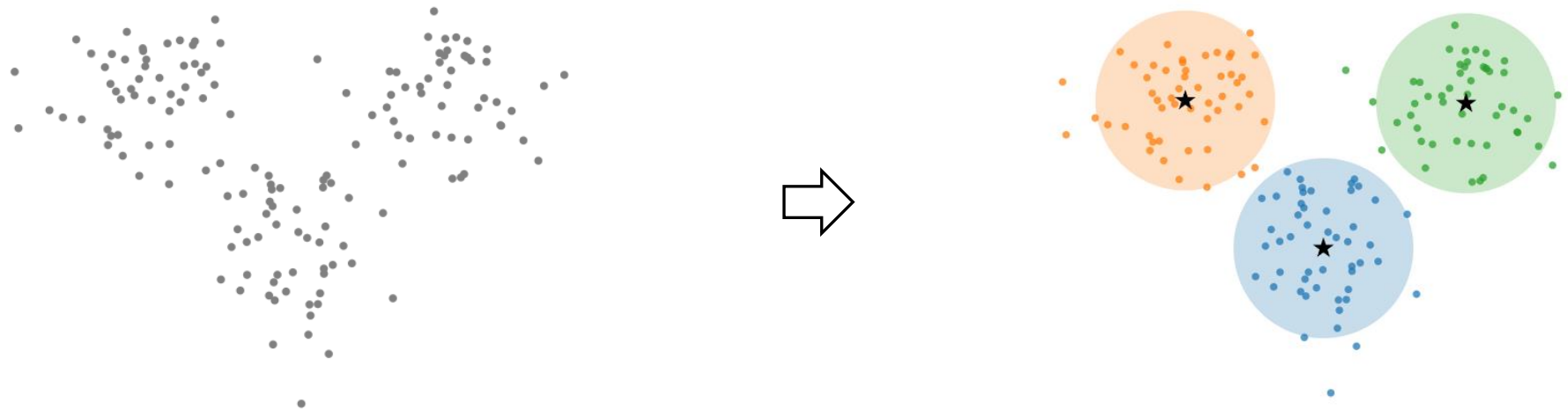
K-Means

- K-means clustering
 - unsupervised learning method: requires data but not labels
 - useful for pattern recognition, when we don't know what to look for
 - detects united patterns e.g. groups of text topics, regions of images
 - pros: simple iterative
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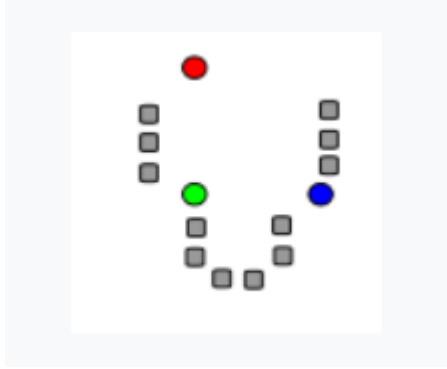


K-Means

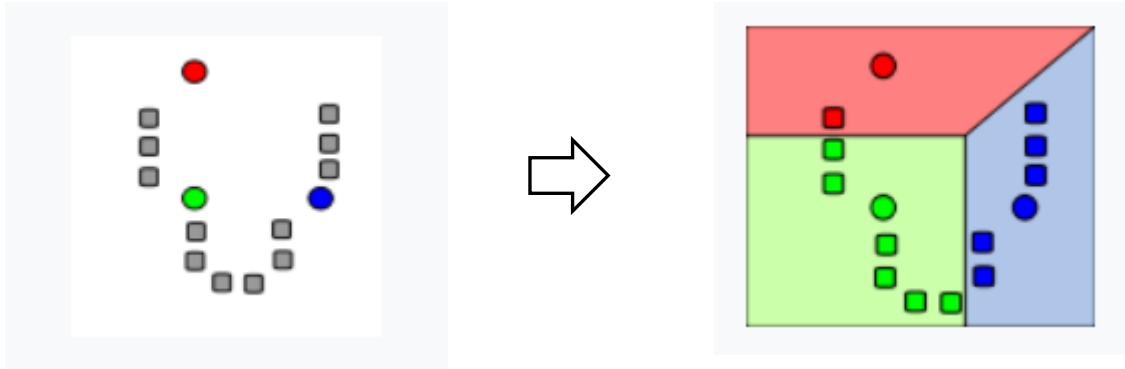
- **Input:** $x^{(1)}, x^{(2)}, \dots, x^{(n)}$
- **Output:** Set of clusters C_1, C_2, \dots, C_k
- **Initialization:** Randomly pick k centroids $z^{(1)}, z^{(2)}, \dots, z^{(k)}$
- **Iterate** until convergence or up to iterations T
 - **Assignment:** Assign each point to its closest centroid
for each $j = 1, \dots, k$
 $C_j = \{i | \text{s.t. } x^{(i)} \text{ is closest to } z^{(j)}\}$
 - **Update:** Recompute centroids with newly assigned points

$$z^{(j)} = \frac{1}{|C_j|} \sum_{i \in C_j} x^{(i)}$$

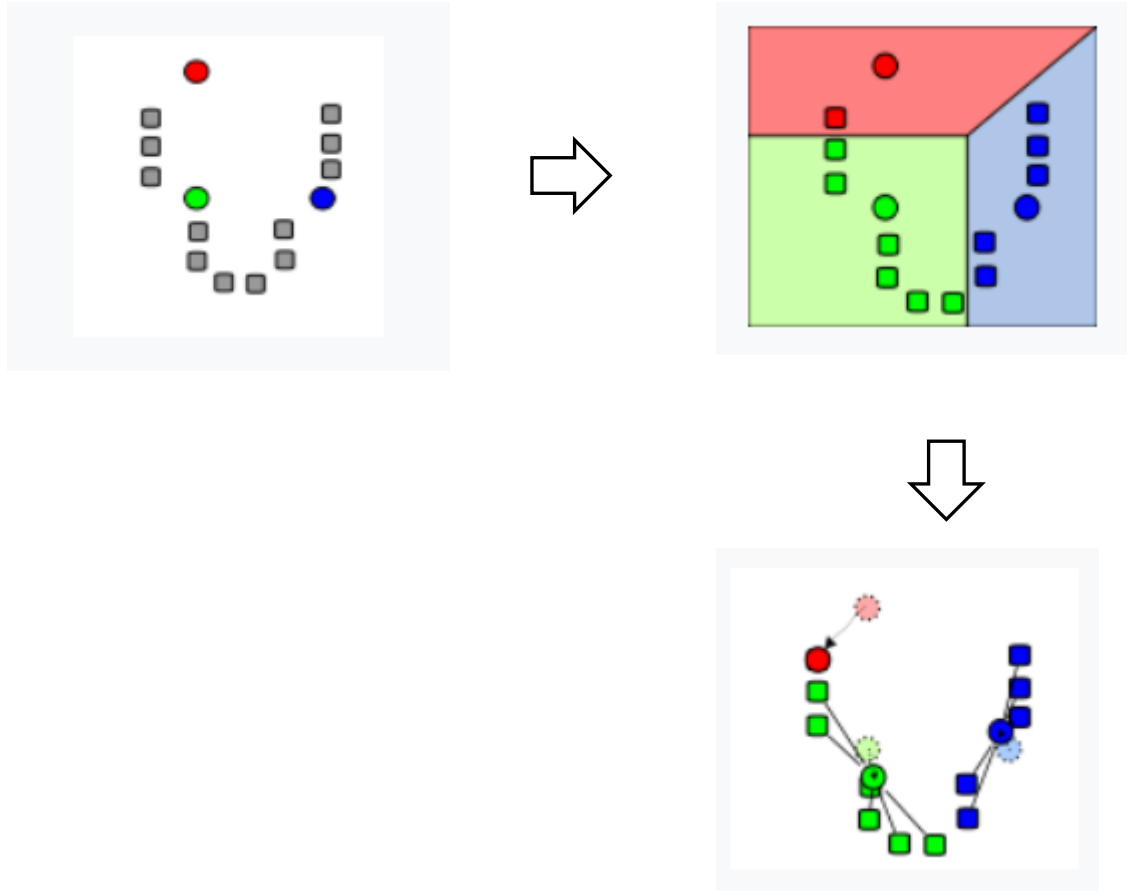
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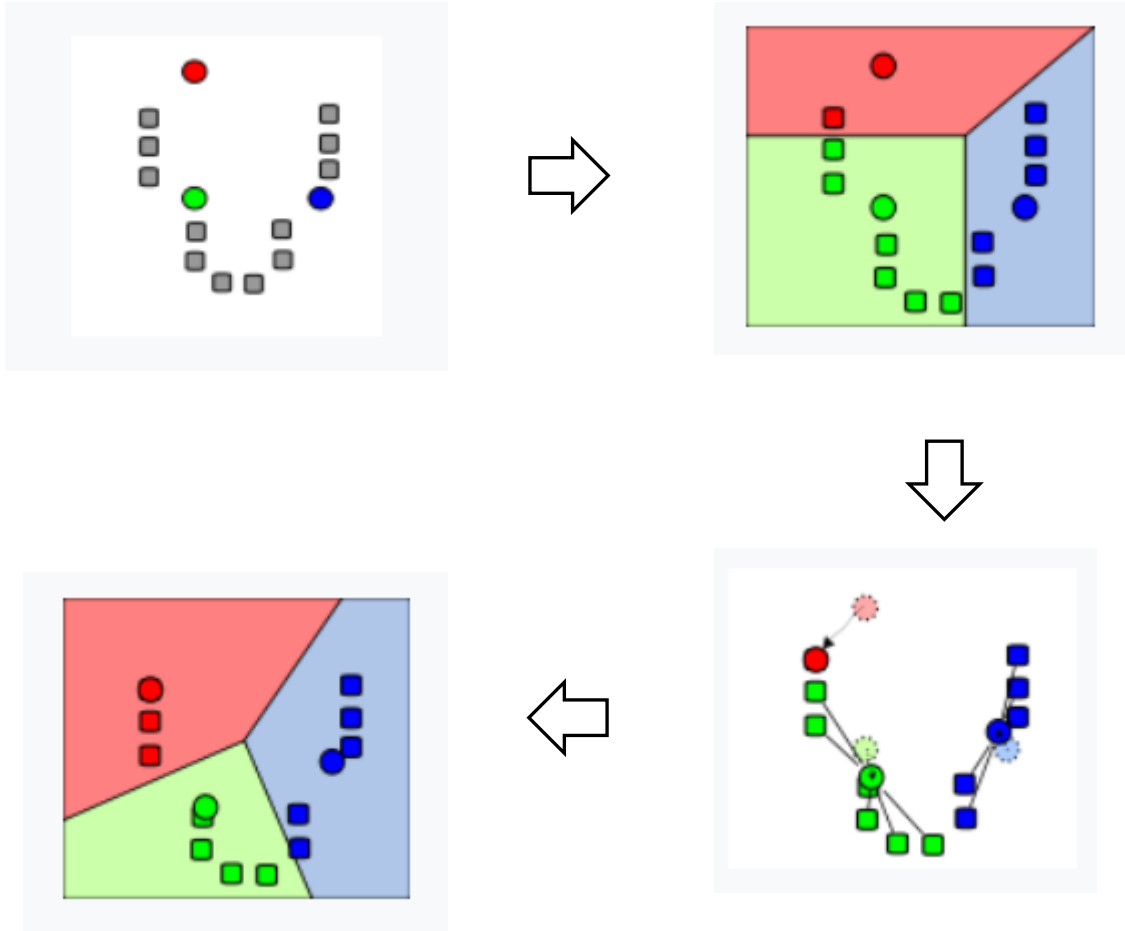
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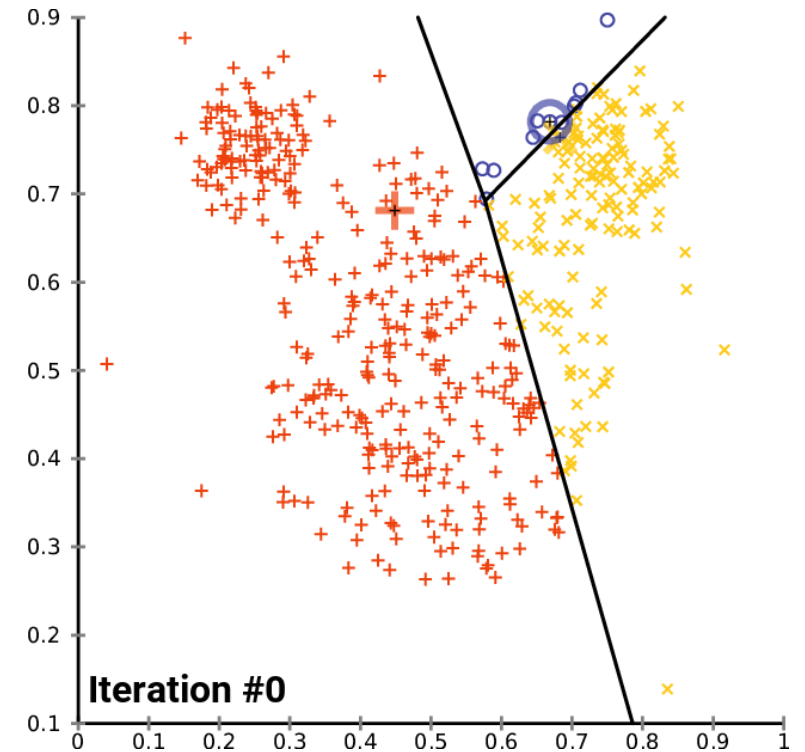
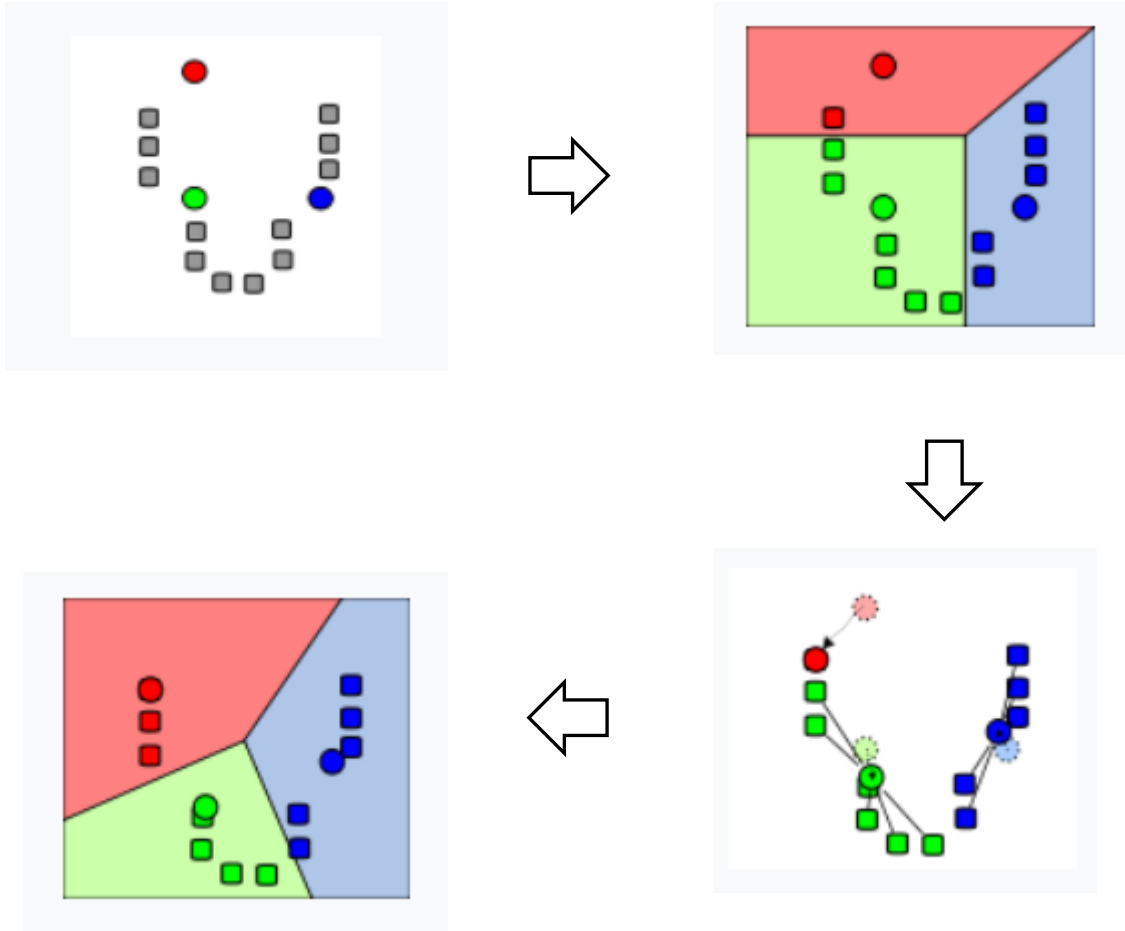
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K-Means

■ Properties

- guaranteed to converge in a finite iterations
 - at each iteration the error reduces
- running time
 - data assignment to the closest cluster: $O(kN)$
 - update the means : $O(N)$
 - Total complexity : $O(kNT)$
- global minima?

K-Means

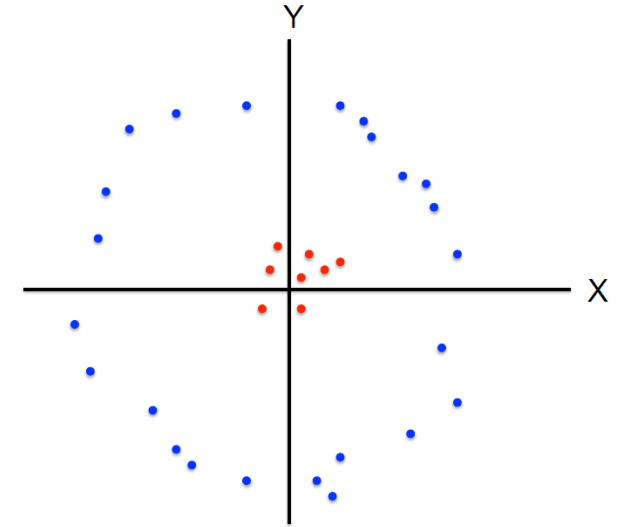
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K-Means

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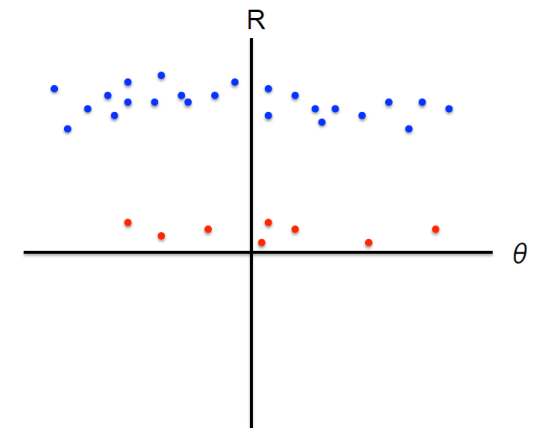
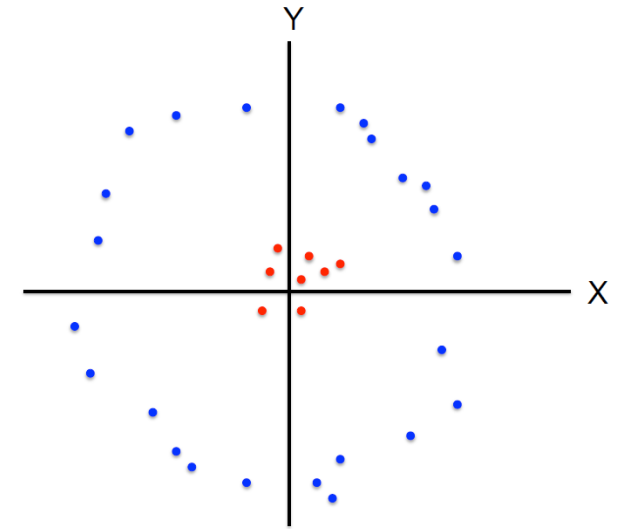
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K-Means

- Convergence

$$\min_{z^{(1)}, \dots, z^{(k)}} \min_{C_1, \dots, C_k} \sum_{j=1}^k \sum_{i \in C_j} \|x^{(i)} - z^{(j)}\|^2$$

K-Means

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- assignment: optimize C with fixed z

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K-Means

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- update: fix C , optimize for z

$$J(z) = \min_{z^{(1)}, \dots, z^{(k)}} \sum_{j=1}^k \sum_{i \in C_j} \|x^{(i)} - z^{(j)}\|^2$$

$$z^{(j)} = \frac{1}{|C_j|} \sum_{i \in C_j} x^{(i)}$$

$$\frac{\delta J(z)}{\delta z^{(j)}} \rightarrow 0$$

K-Means

input



$K = 2$



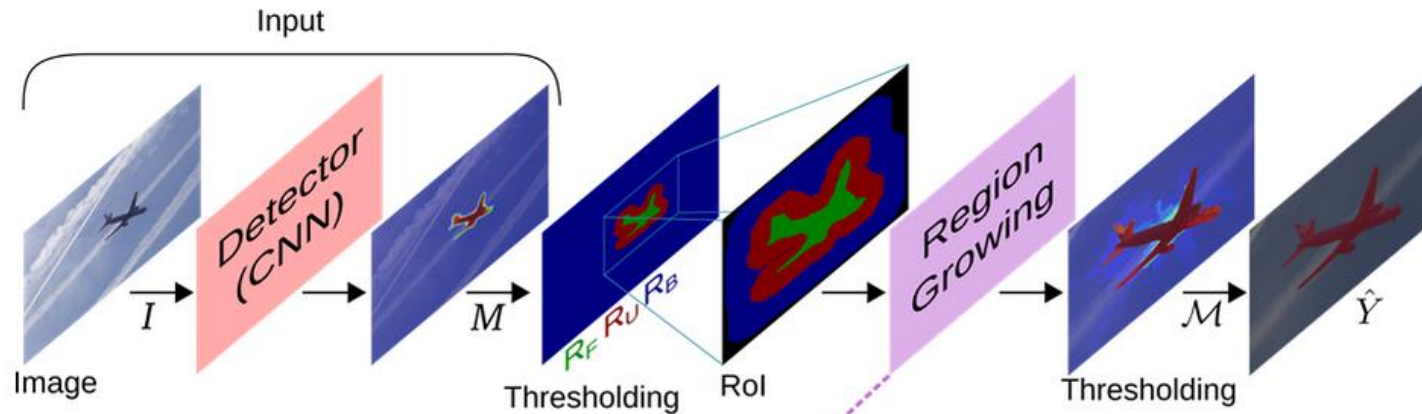
$K = 3$



$K = 10$



Region growing in feature space



$$R_F = \{p_j | M(p_j) > \tau_F\},$$

$$R_U = \{p_j | \tau_B < M(p_j) < \tau_F\},$$

$$R_B = \{p_j | M(p_j) < \tau_B\},$$

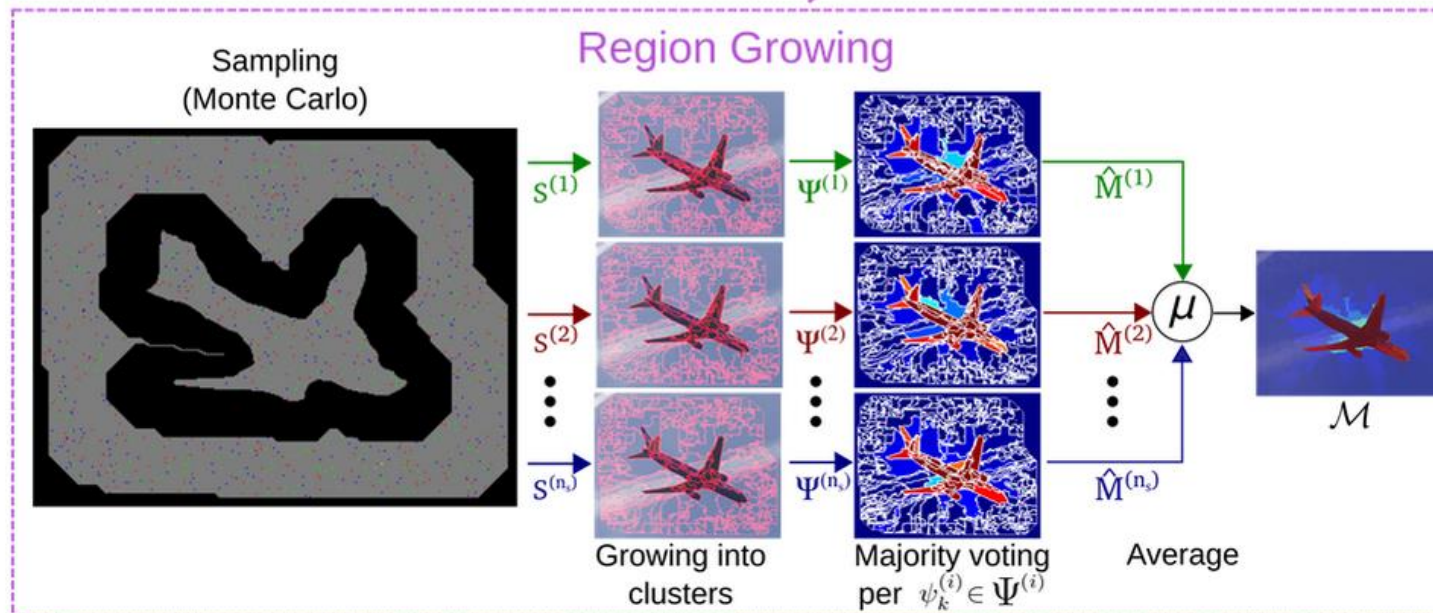
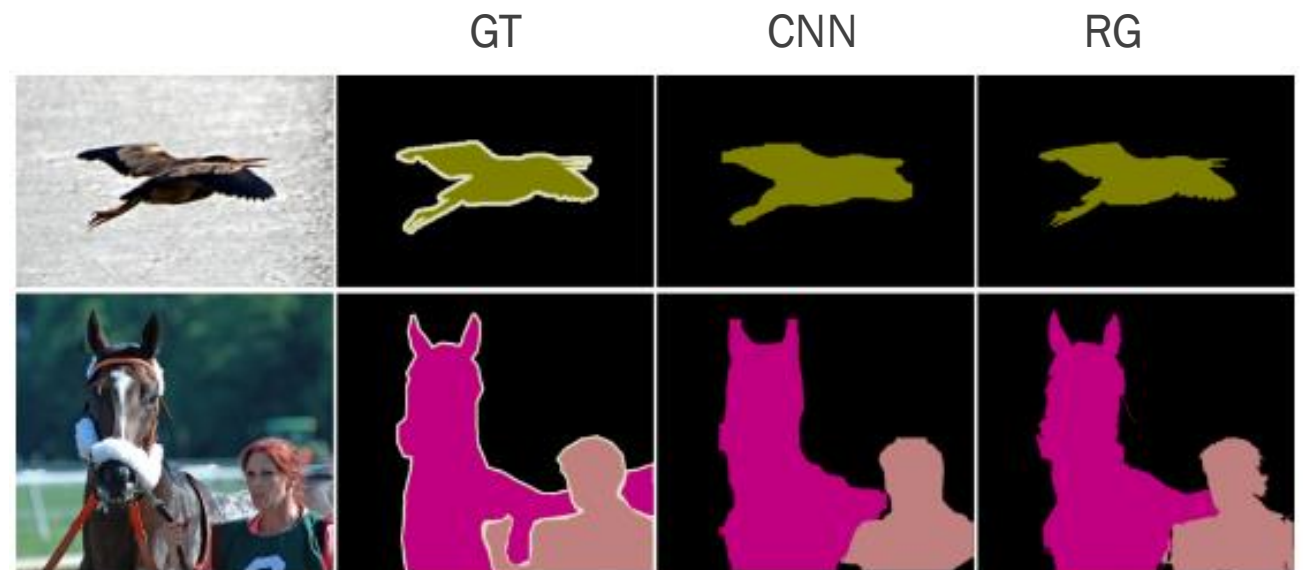


Image credit: PA Dias

Conclusion

- Regions
- Clustering



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- Regions
- Clustering

- Region growing
- Region splitting & merging
- Clustering
 - K-means clustering

