

On the sink side of a PPIB connection, for a (local) peripheral to be able to receive this event, the corresponding PPIB channel is configured as a producer, publishing to the same DPPI channel as the (local) peripheral subscribes to, using the `PPIB.PUBLISH_RECEIVE[n]` register, with `n` the PPIB channel number.

In a PPI system, several peripherals can publish to the same DPPI channel on the source side of a PPIB connection. Similarly, several peripherals can subscribe to the same DPPI channel on the sink side of a PPIB connection. This allows multiple connection options between peripherals in different PPI systems, same as DPPI allows in a local PPI system: one-to-one, one-to-many, many-to-one and many-to-many. However, when multiple peripherals can publish to the same DPPI channel on the source side of a PPIB connection, there is a risk of overflow. See [Handshake and overflow](#) on page 118.

### 6.3.2 Handshake and overflow

The two PPIB instances in a PPIB connection need a handshake to transfer a peripheral event.

This is handled by a Handshake module in the PPIB. If a handshake fails because an earlier event has not been processed completely, the new event won't be sent. Instead, bit `i` in `OVERFLOW.SEND` register on the source side will be set, with `i` the corresponding PPIB channel number.

### 6.3.3 Connection examples

This section contains examples on how to connect two PPI systems using PPIB.

The following example shows how to create a PPIB connection between the `TIMER10` compare event in the `RADIO PD` and the `SAADC` start task in `PERI PD`. `PPIB11` in `RADIO PD` is hardwired to `PPIB21` in `PERI PD`, which allows the PPI systems in the two separate power domains to connect. DPPI channel 0 is used by both power domains. Note that it is only necessary to use the same DPPI channel within the power domain; different DPPI channels can be used across power domains. An example of this is given further down in this section.

```
// RADIO PD
NRF_TIMER10->PUBLISH_COMPARE[0] = (0<<TIMER_PUBLISH_COMPARE_CHIDX_Pos) |
TIMER_PUBLISH_COMPARE_EN_Msk;
NRF_PPIB11->SUBSCRIBE_SEND[0] = (0<<PPIB_SUBSCRIBE_SEND_CHIDX_Pos) |
PPIB_SUBSCRIBE_SEND_EN_Msk;
NRF_DPPIC10->CHENSET = DPPIC_CHENSET_CH0_Msk;

// PERI PD
NRF_SAADC->SUBSCRIBE_START = (0<<SAADC_SUBSCRIBE_START_CHIDX_Pos) |
SAADC_SUBSCRIBE_START_EN_Msk;
NRF_PPIB21->PUBLISH_RECEIVE[0] = (0<<PPIB_PUBLISH_RECEIVE_CHIDX_Pos) |
PPIB_PUBLISH_RECEIVE_EN_Msk;
NRF_DPPIC20->CHENSET = DPPIC_CHENSET_CH0_Msk;
```

The following example shows how to create a PPIB connection between the `TIMER10` compare event in the `RADIO PD` and the `COMP` start task in `LP PD`. The two PPI systems must be connected through PPIB instances `PPIB21` and `PPIB22` in `PERI PD`. These PPIB instances are not connected to any peripheral, only to the PPIB instances in `RADIO` and `LP` power domains. `PERI PD` acts as a central system that connects the two systems by means of local PPIB and DPPIC instances. This allows scaling to larger PPI systems, since multiple PPI systems can be interconnected through a central PPI system. DPPI channel 0 is used for internal `RADIO PD` connections, channel 1 is used by `LP PD`, and channel 5 is used by `PERI PD`. It is