



Alex Boggess

Mechanical Engineering

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Worcester, MA

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To obtain a full-time position as a mechanical design engineer

EDUCATION

Mechanical Engineering

Worcester Polytechnic Institute (3.36 GPA)

08/2016 – Present

Concentration in Mechanical Design and Minor in Robotics Engineering

Courses

- Design of Machine Elements
- Kinematics of Mechanisms
- Analysis of Mechatronic Systems
- Advanced CAD (Creo)

WORK EXPERIENCE

Advanced CAD (Creo) Peer Learning Assistant

Worcester Polytechnic Institute

01/2020 – Present

Worcester, MA

Achievements/Tasks

- Supervised advanced CAD lab periods and assisted students to complete assignments in Creo

Mechanical Engineering Intern

David Clark Company Incorporated

05/2019 – 08/2019

Worcester, MA

Manufacturer for headset communication systems for high-noise environments

Achievements/Tasks

- Designed parts that assisted floor workers during the manufacturing process including alignment tools and pneumatic actuated assembly station
- Developed testing stations for speakers and circuit boards for Quality Assurance
- Helped with design problems during new product development

ORGANIZATIONS

Society of Manufacturing Engineering
(04/2017 – Present)

General Body Member

SKILLS

Solidworks (CSWA)

Creo

MatLab

MathCAD

ESPRIT

Microsoft Suite

LabVIEW

PERSONAL PROJECTS

Self-Driving 3D Printed RC Car (08/2019 – Present)

- Collaborating in a team to design a modular 3D printed RC Car with front and rear suspension, and differential
- Utilizing MatLab to calculate forces on steering linkage and suspension
- Working with second team to implement self-driving capabilities using an Arduino and Raspberry Pi

Laser Etch-a-sketch (08/2019 – 10/2019)

- Designed a laser Etch-a-sketch using high speed servos as galvanometers
- Users control the XY coordinates of the laser point with two potentiometers to draw, similar to an Etch-a-sketch

Stirling Engine (01/2019 – 03/2019)

- Utilized computer-aided manufacturing to develop a stirling engine using ESPRIT software and HAAS Mini Mills

Permaculture Design Plan (08/2018 – 12/2018)

- Collaborated in a group to research, develop, and propose a sustainable agriculture plan for a non-profit organization
- Organized weekly meetings with organization stakeholders to ensure stakeholder's expectations were met or exceeded
- Conducted interviews with local farmers and agriculture experts to further understand regional farming techniques

Autonomous Mobile Robot with Environmental Awareness (10/2017 – 12/2017)

- Collaborated in a team to construct an autonomous mobile robot capable of discovering and extinguishing a flame
- Led the mechanical design of a unique two-axis gimbal system that manipulates a fan to extinguish a flame

Autonomous Mobile Robot for Payload Manipulation and Delivery (08/2017 – 10/2017)

- Worked on a team of three to construct an autonomous robot capable of transferring a rod to an empty storage container
- Analytically determined linkage forces and optimal power transmission using free-body diagrams and PTC MathCAD

CERTIFICATES

Certified Solidworks Associate