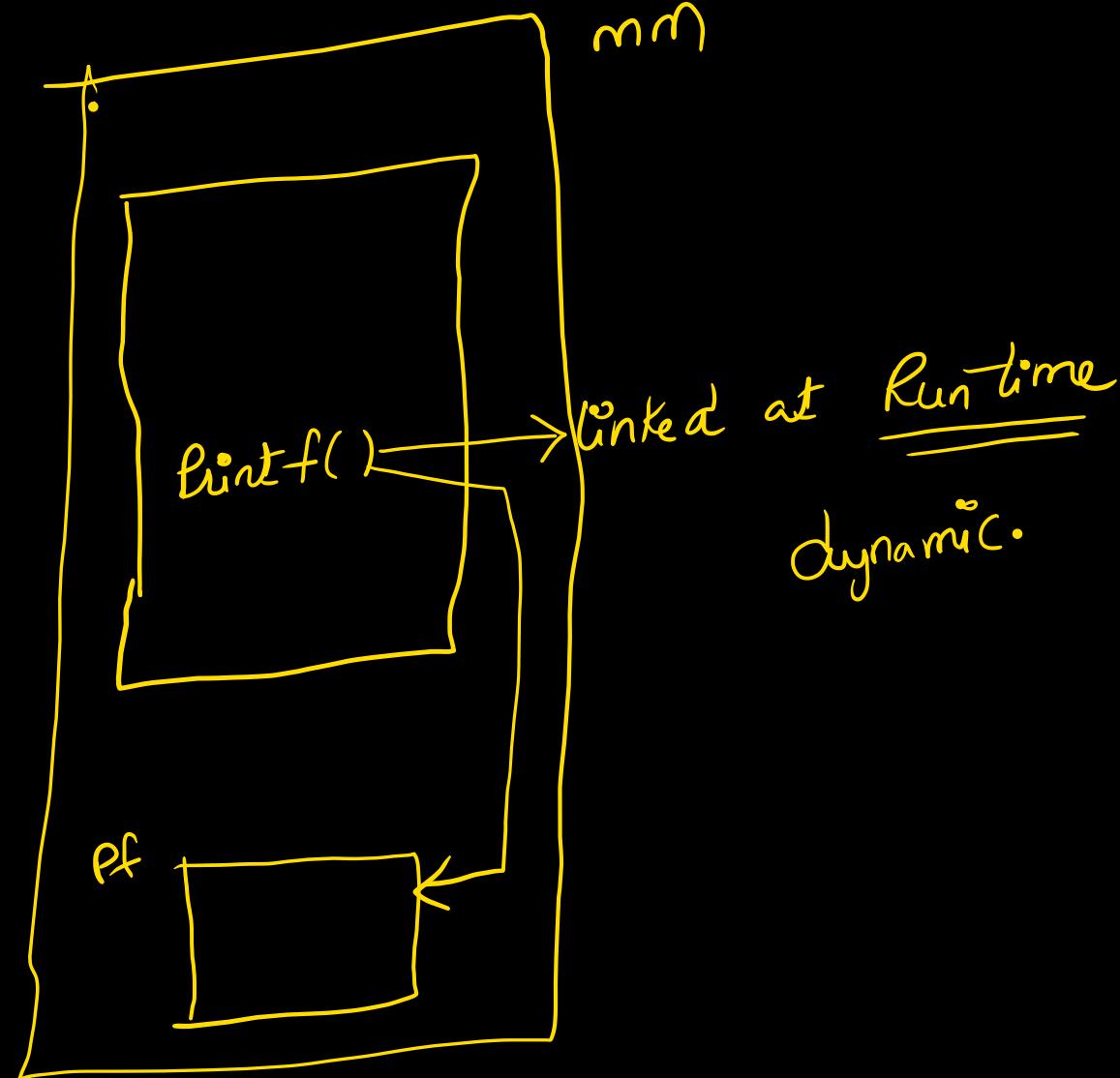
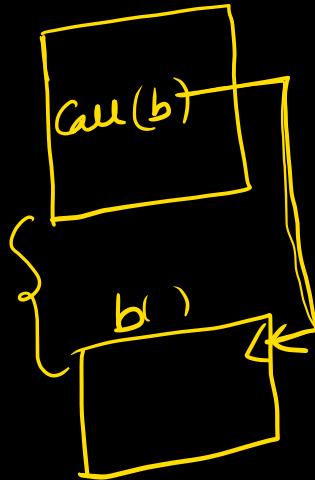
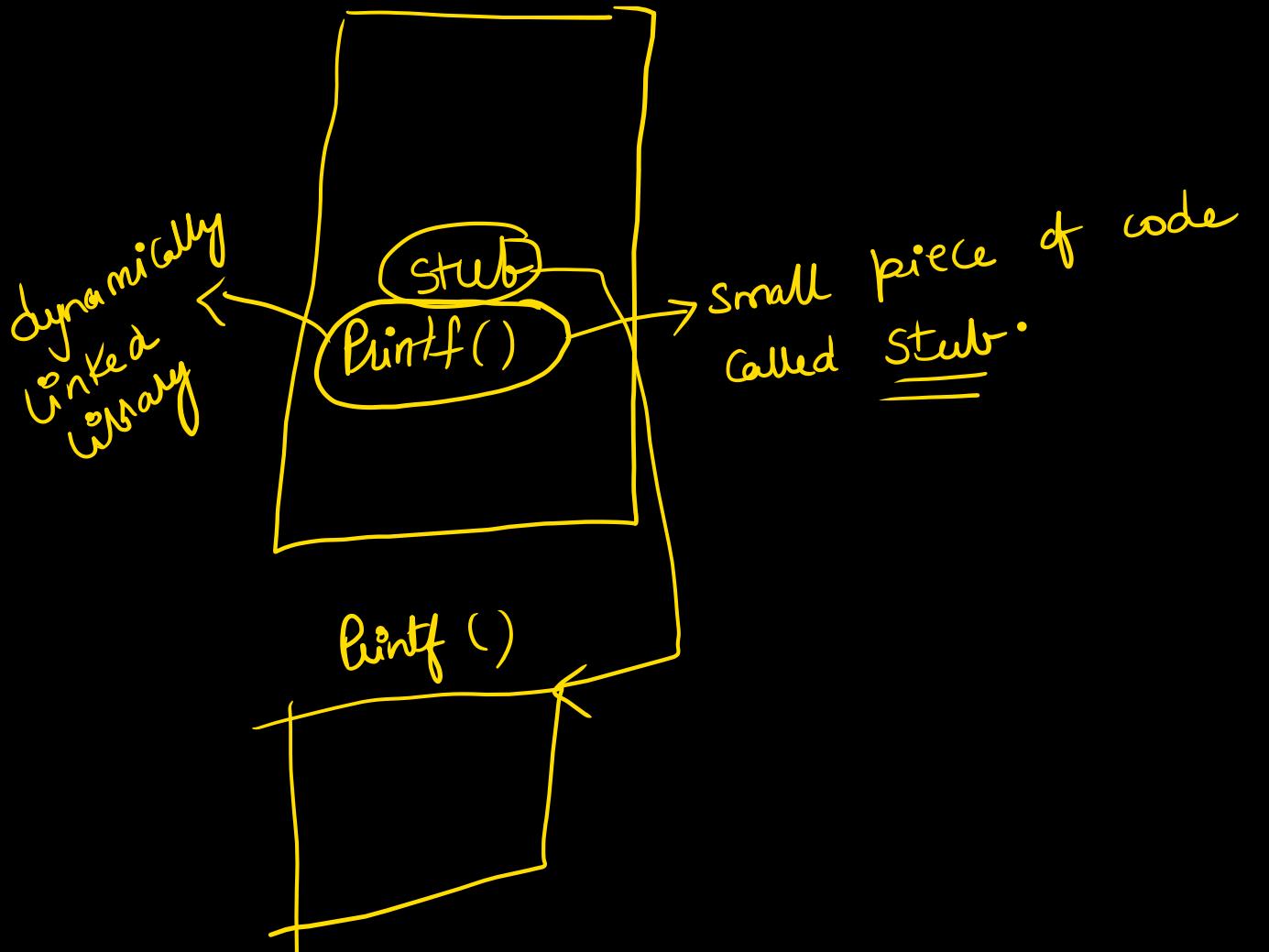


Linking :

Static

dynamic





memory management:

1) Fixed partitioning with equal sized partitions ^{main memory}

$$P_1 \rightarrow 1 \text{ MB}$$

Rule: only 1 process/partition.

$$(P_S > 4 \text{ MB}) \times$$

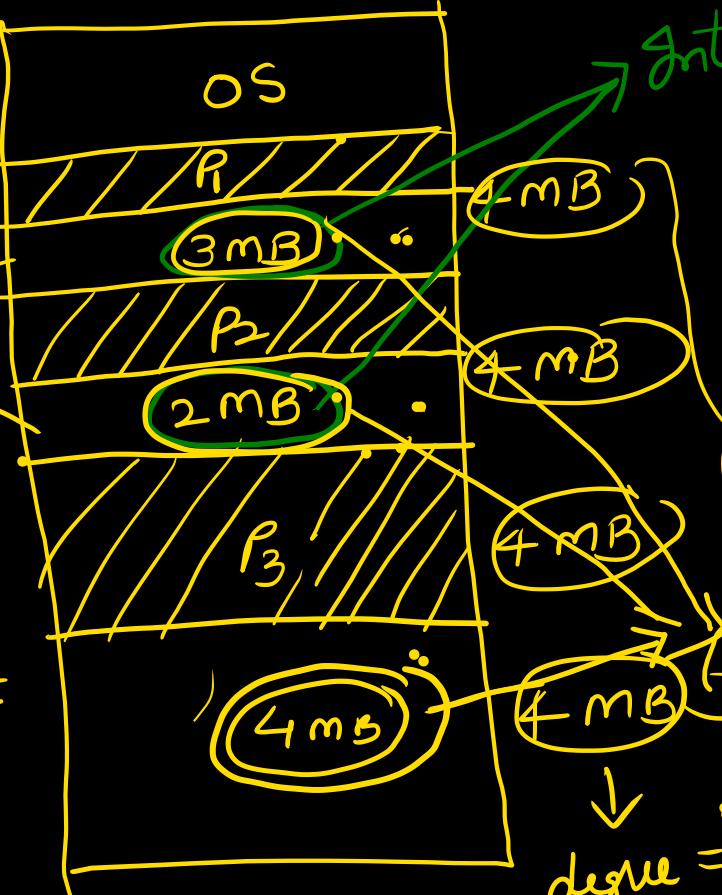
$$P_2 \rightarrow 2 \text{ MB}$$

$$P_3 \rightarrow 4 \text{ MB}$$

$$P_4 \rightarrow 9 \text{ MB} \rightarrow X$$

$4 + 3 + 2 \rightarrow$ available but
process has to be contiguous.

Cannot be given to any process.



internal fragmentation.

equal partitions

external fragmentation
degree = "4"

Disadv:

- Process size is limited
 - Internal fragmentation
 - External fragmentation
 - Degree of multiprogramming is fixed
- ↓
- no of processes that can
be present in 'mm'

→ Fixed partitioning with unequal sized partitions:

$P_1 \rightarrow 0.5 \text{ MB}$

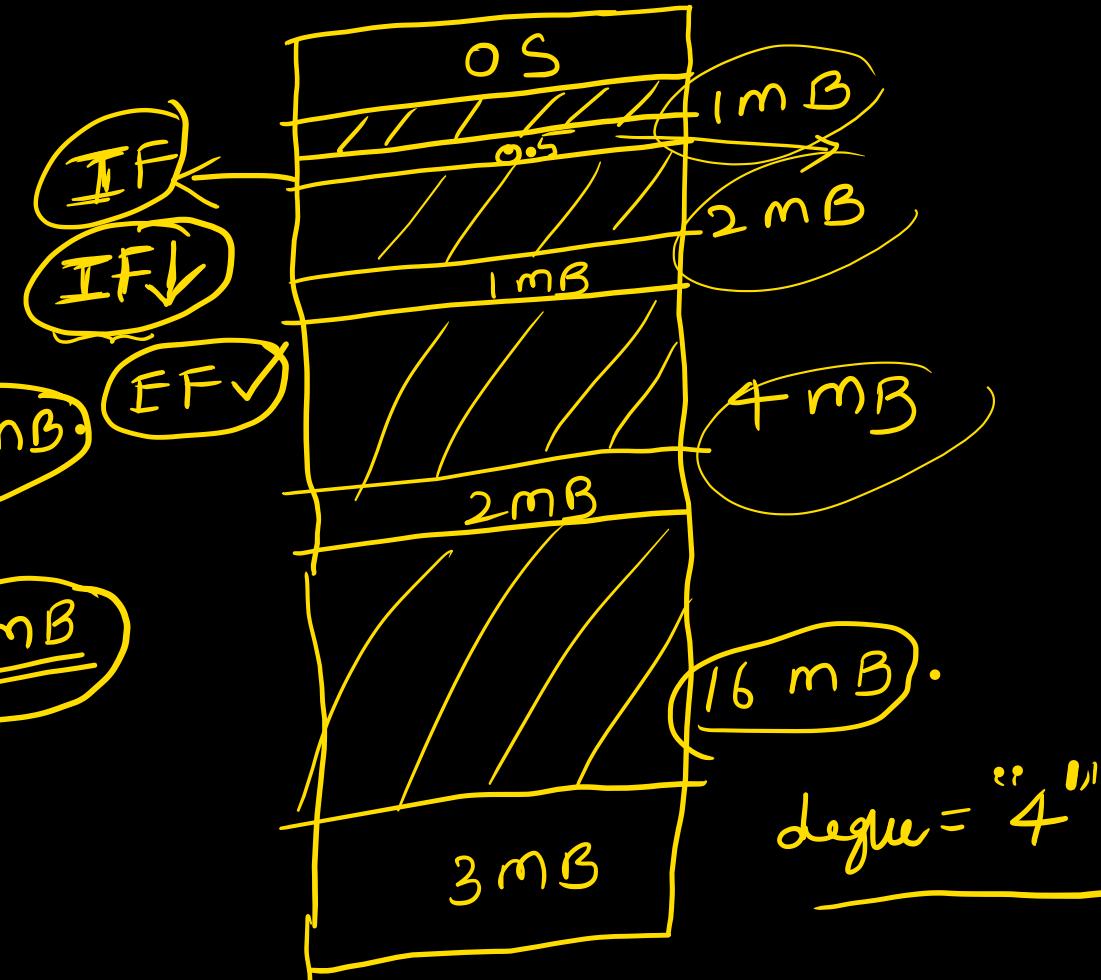
$\checkmark P_{10} \rightarrow 6 \text{ MB}$

Disadv: (i) Size of OS is limited

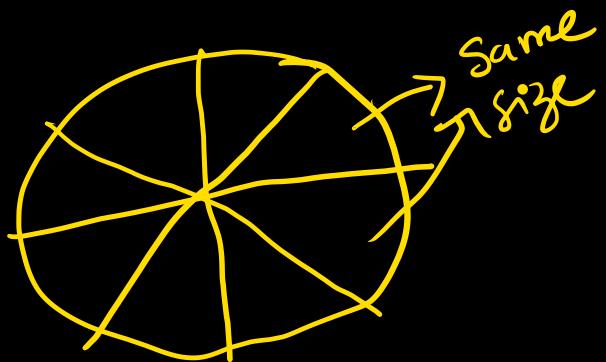
(ii) IF↓

(iii) EF✓

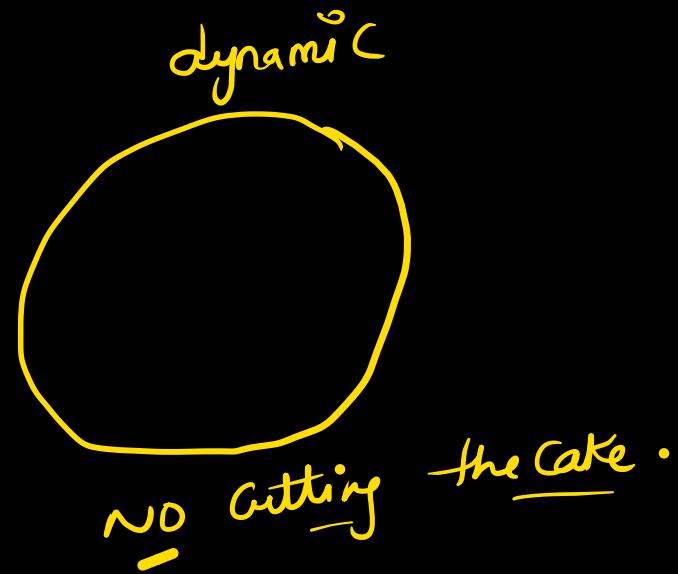
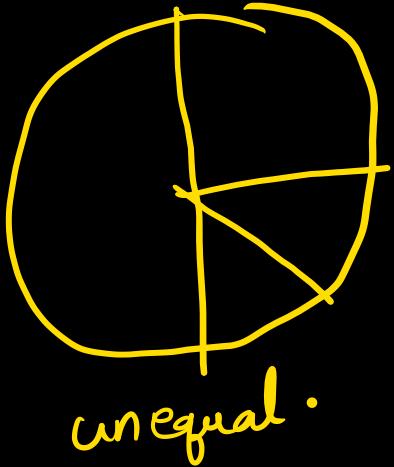
(iv) degree of MP → fixed



Dynamic partitioning:



Equal



$P_1 \rightarrow 4 \text{ mB}$

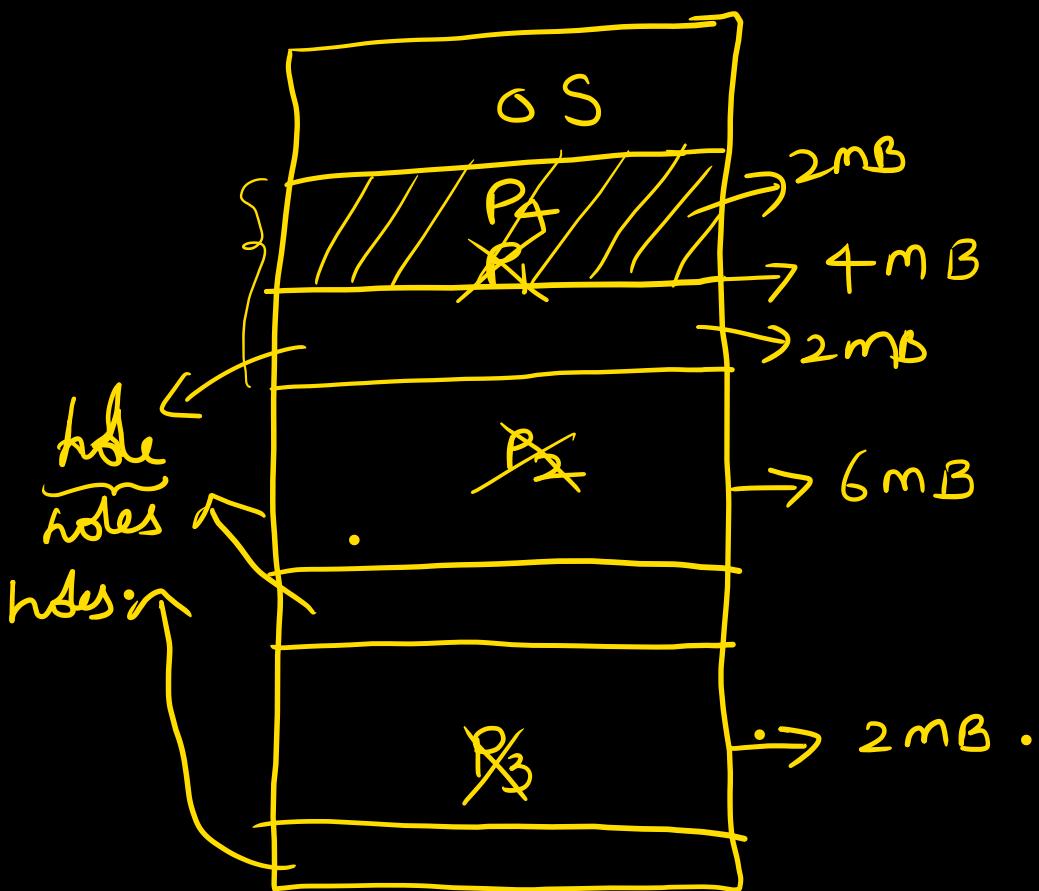
$P_2 \rightarrow 6 \text{ mB}$

$P_3 \rightarrow 2 \text{ mB}$

$P_4 \rightarrow 2 \text{ mB}$

NO IF X

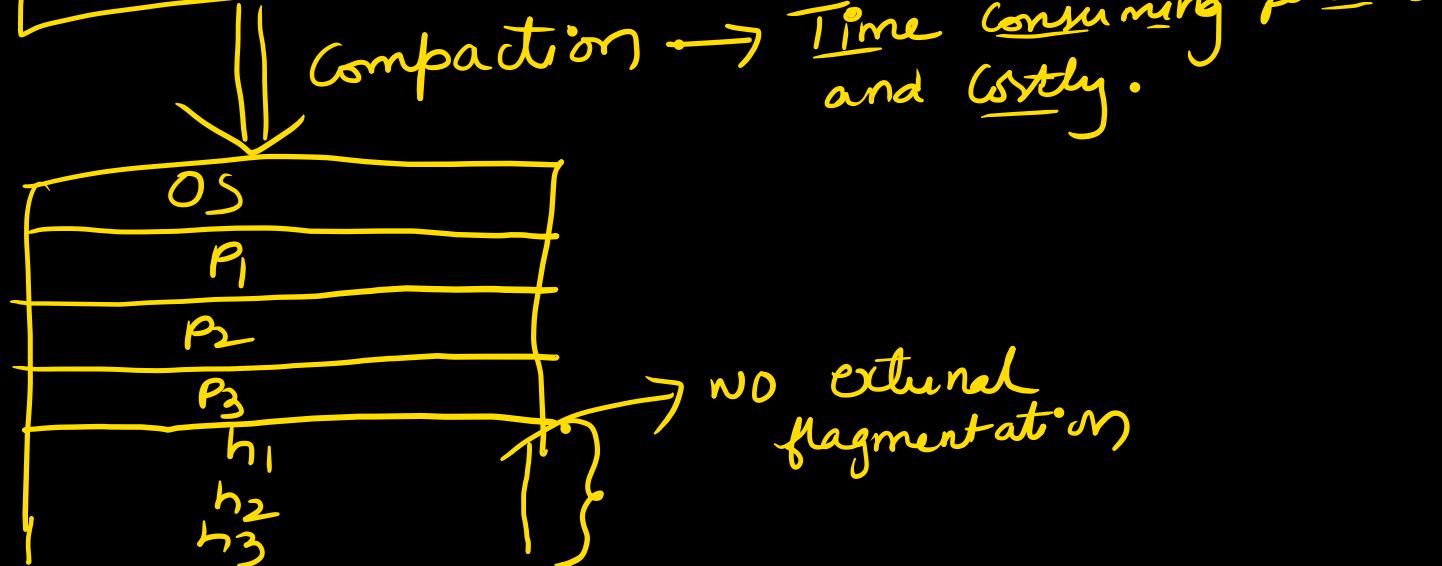
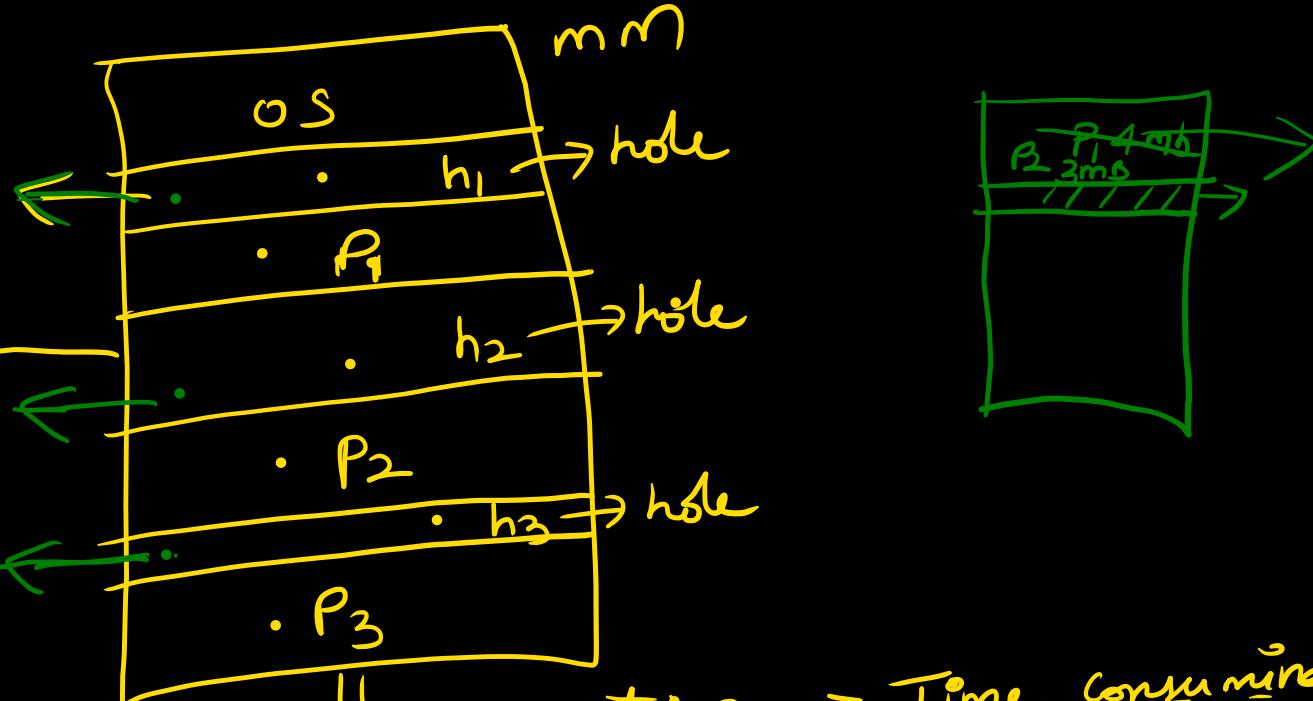
External Fragmentation
 \rightarrow because of holes.



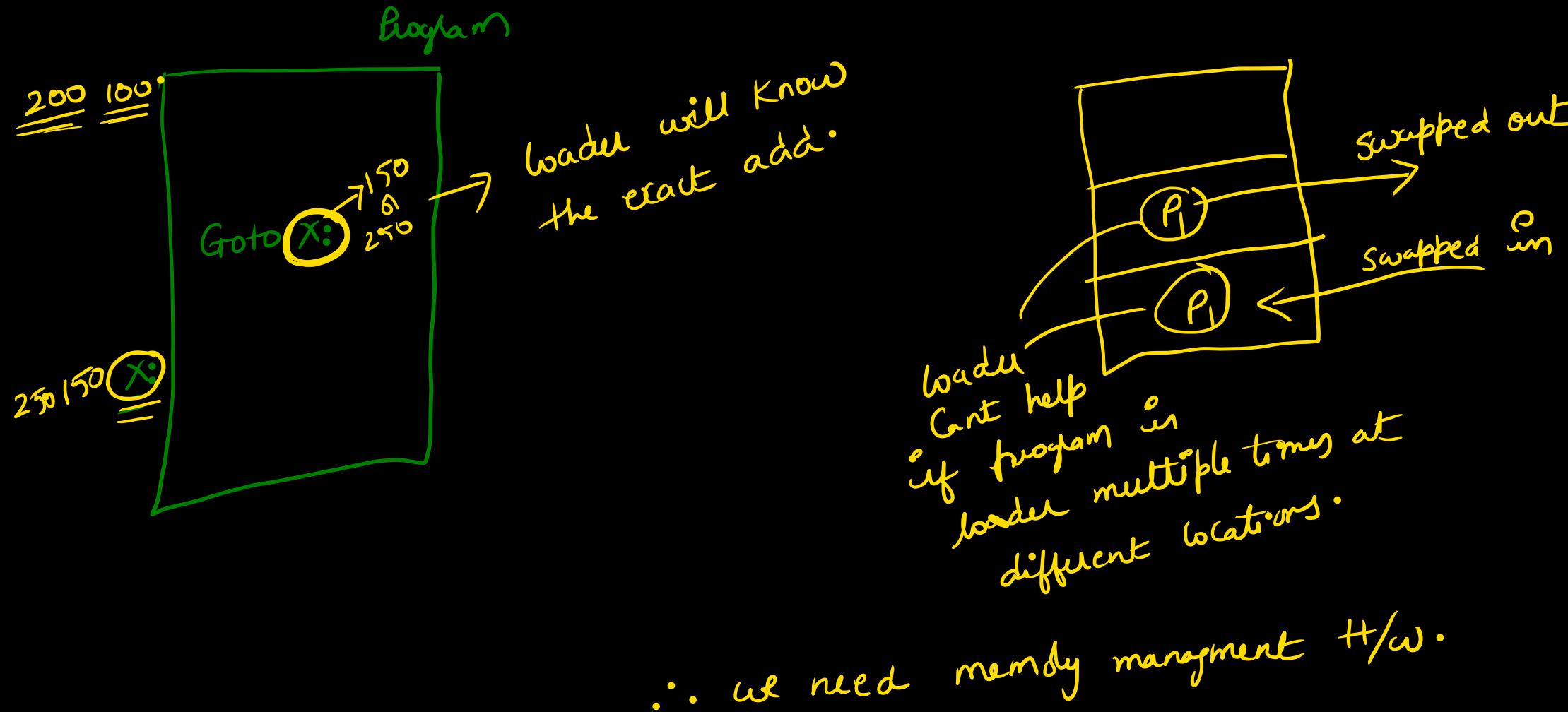
Paging

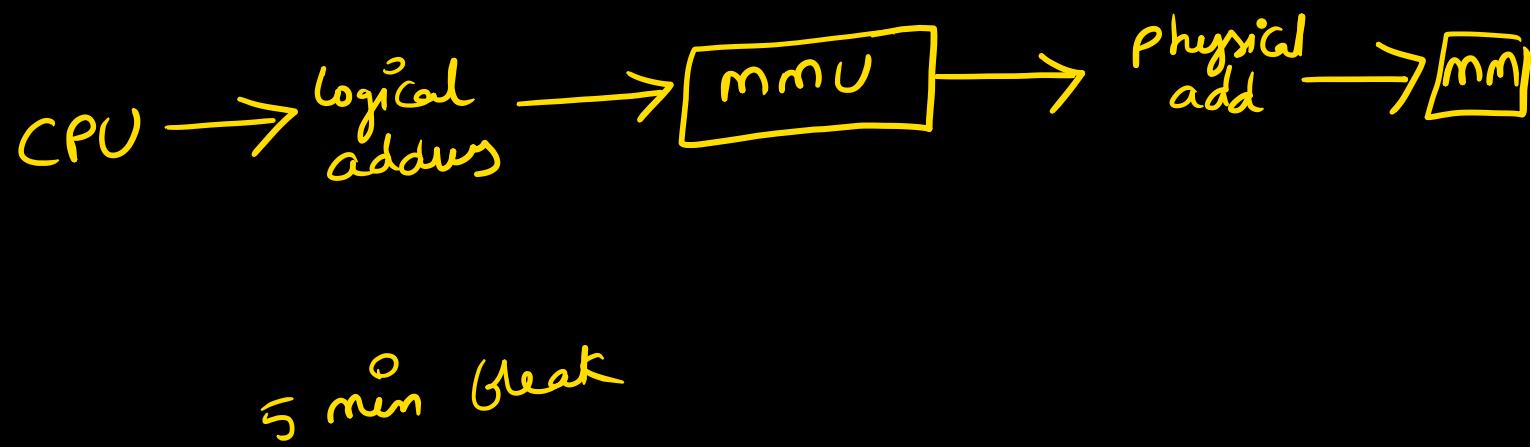
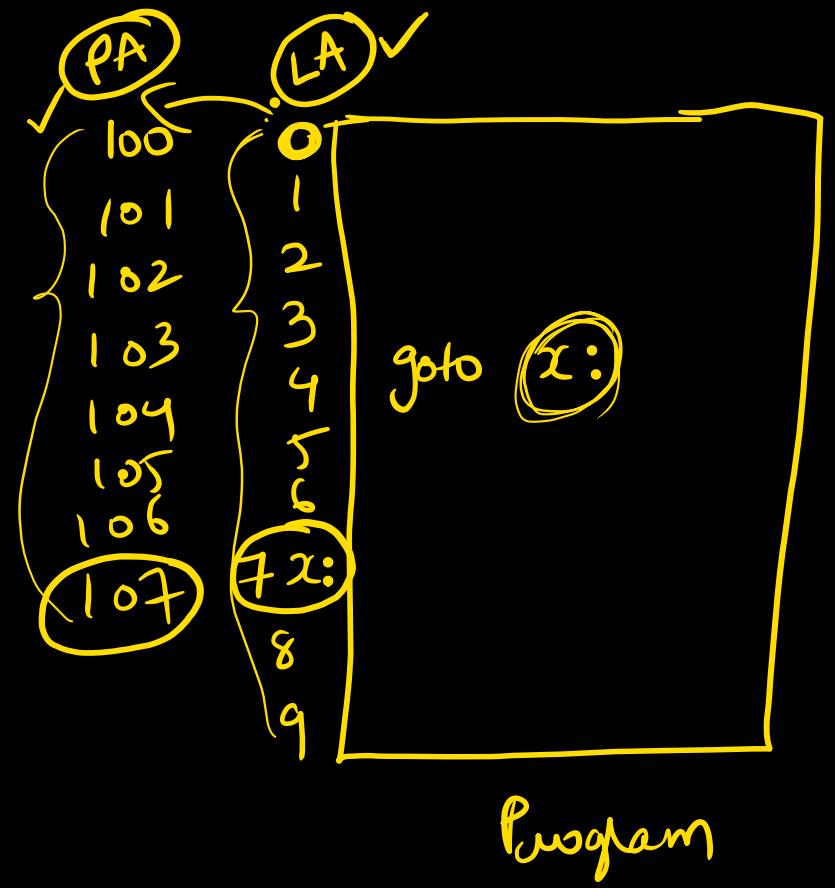
Processes can be non contiguous.

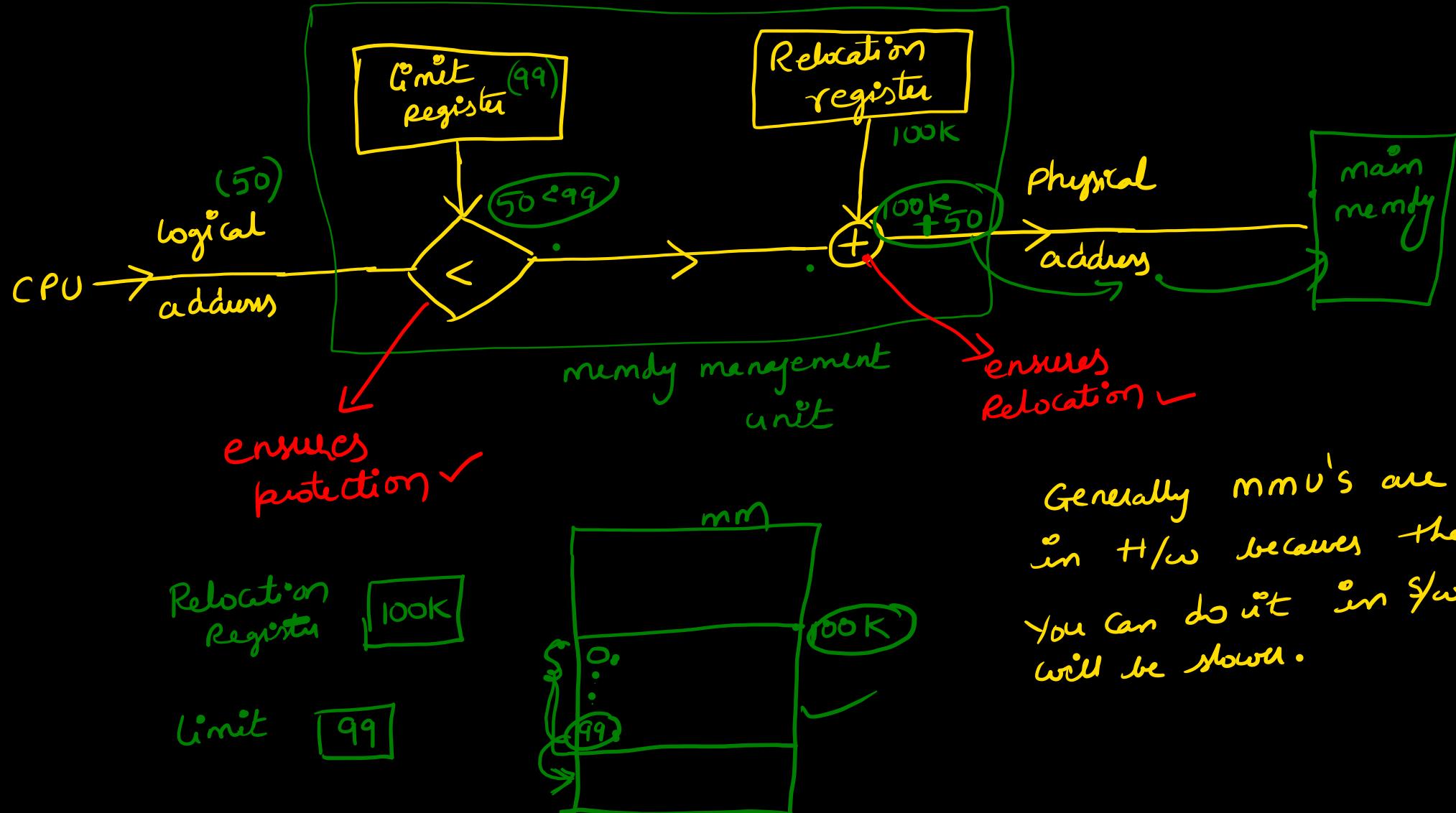
Segmentation



Time consuming process
and costly.







Generally MMU's are implemented in H/W because they are faster.
 You can do it in S/W also but it will be slower.

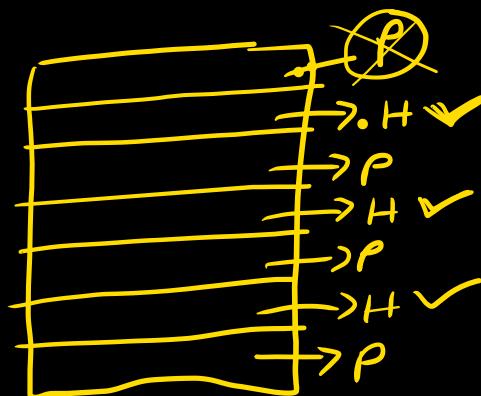
advantage of Dynamic partitioning:

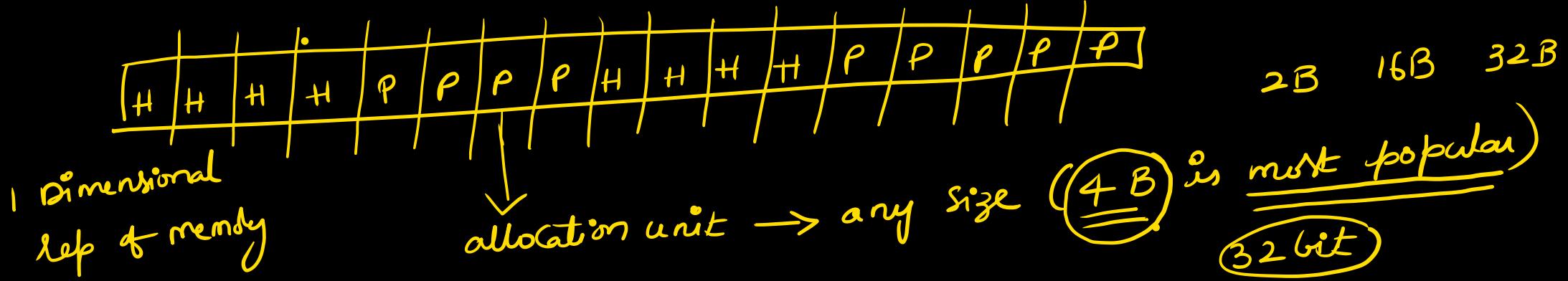
- (i) Degree of MP is dynamic (not fixed)
- (ii) NO limitation on size of process
- (iii) NO internal fragmentation

Disadvantage:

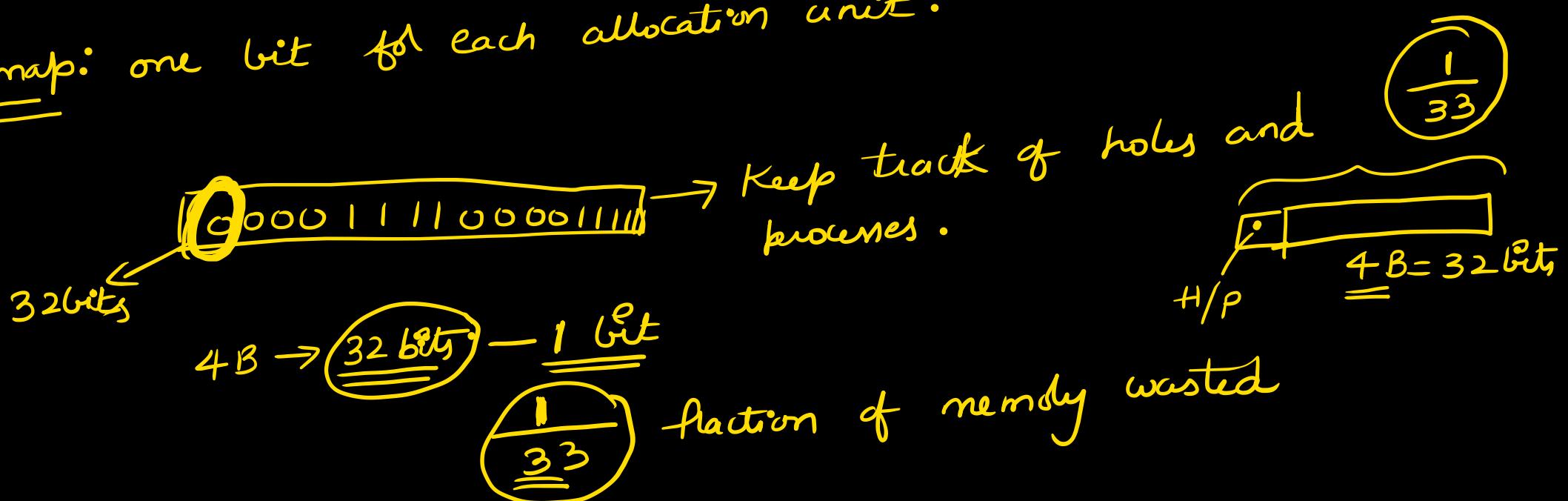
→ allocation and deallocation of memory is complex because of holes.

→ external fragmentation.

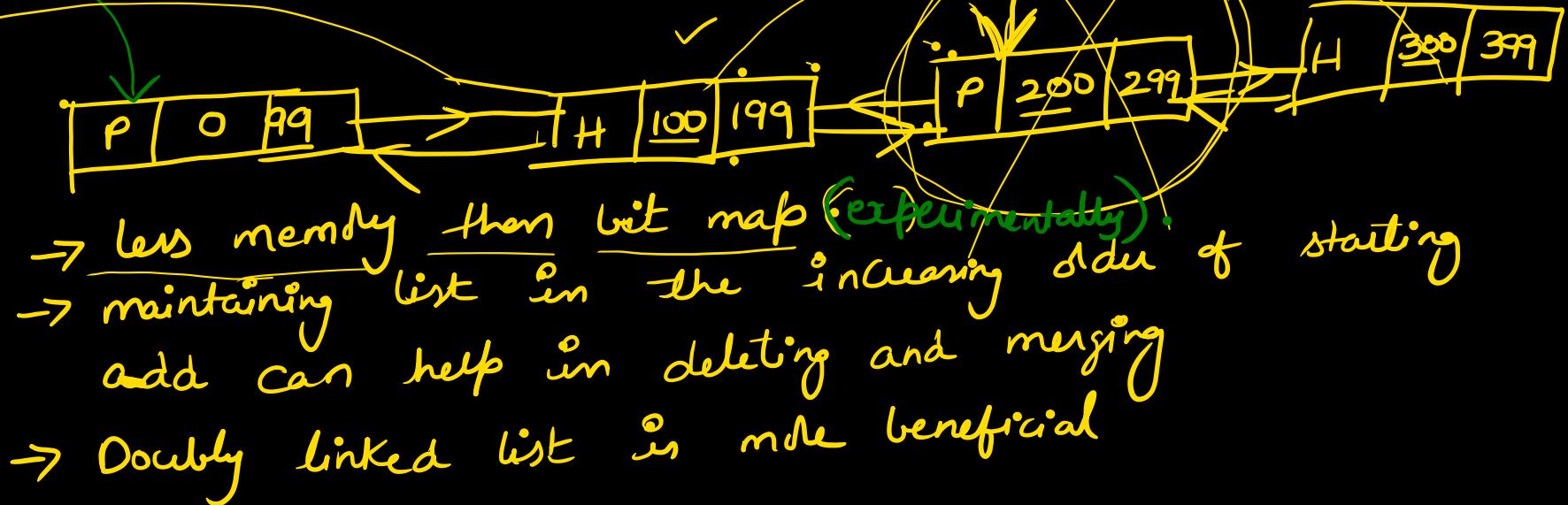
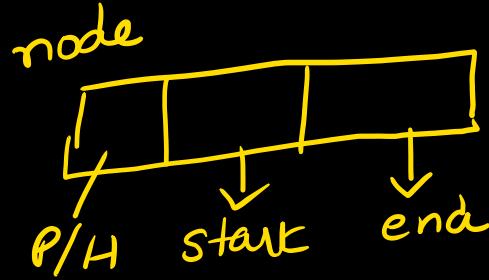
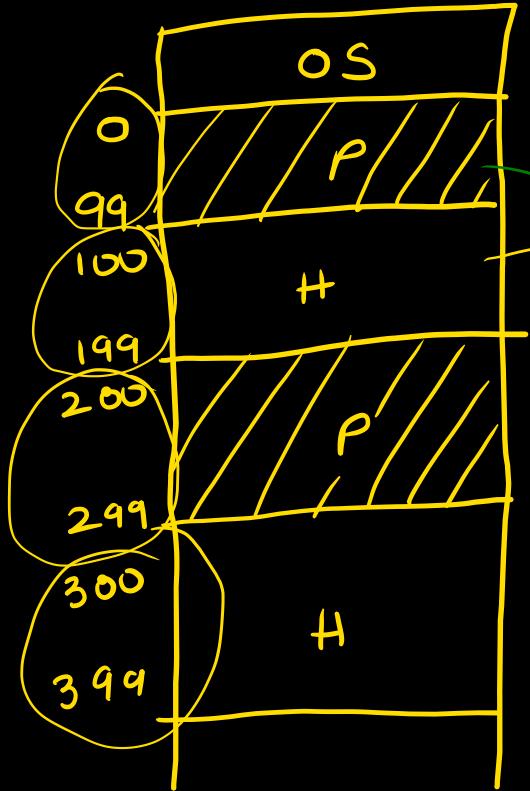


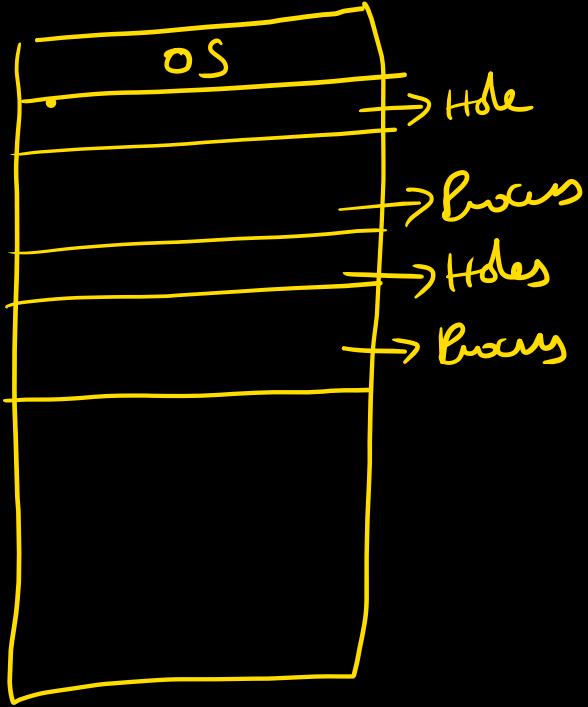


Bit map: one bit for each allocation unit.



Linked list representation:

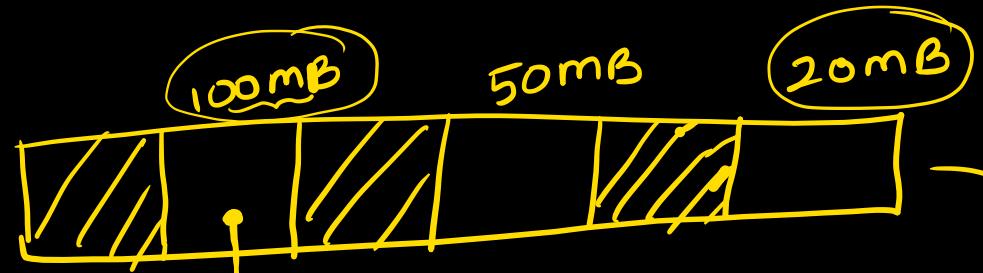




$P_1 \rightarrow 4 \text{ MB}$ → which ~~at~~ hole will be allotted.

- (i) First fit
- (ii) Next fit
- (iii) Best fit
- (iv) Worst fit
- (v) Quick fit

First fit



linked list rep.



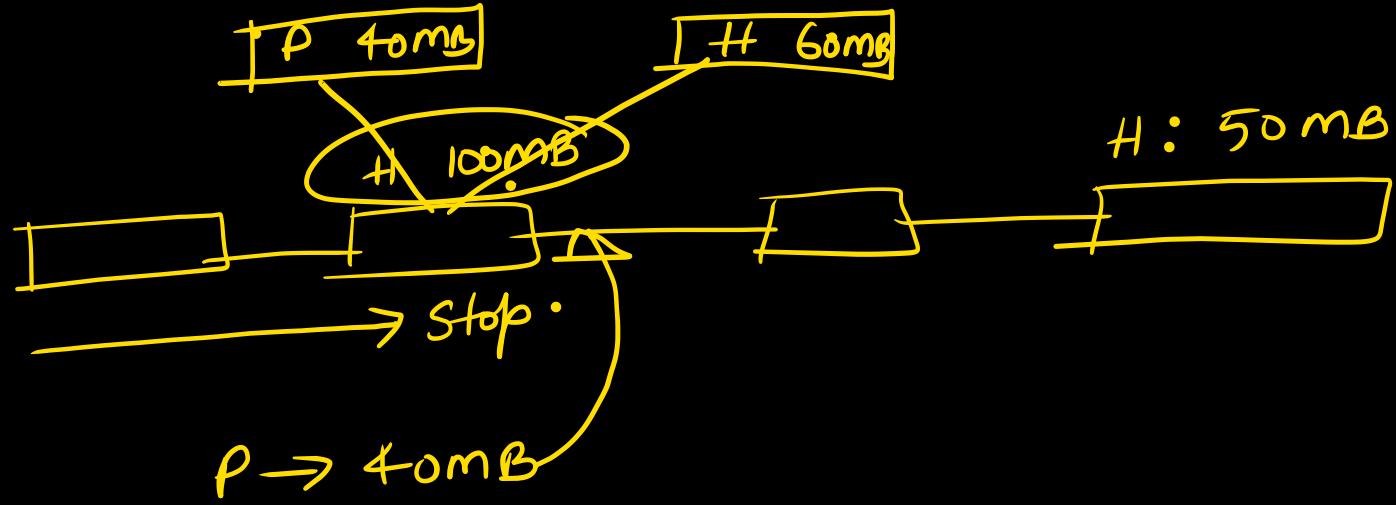
traverse \rightarrow I have large enough to hold the process.

simple to implement.

c programming (malloc) uses first fit.

First fit is the best algo.

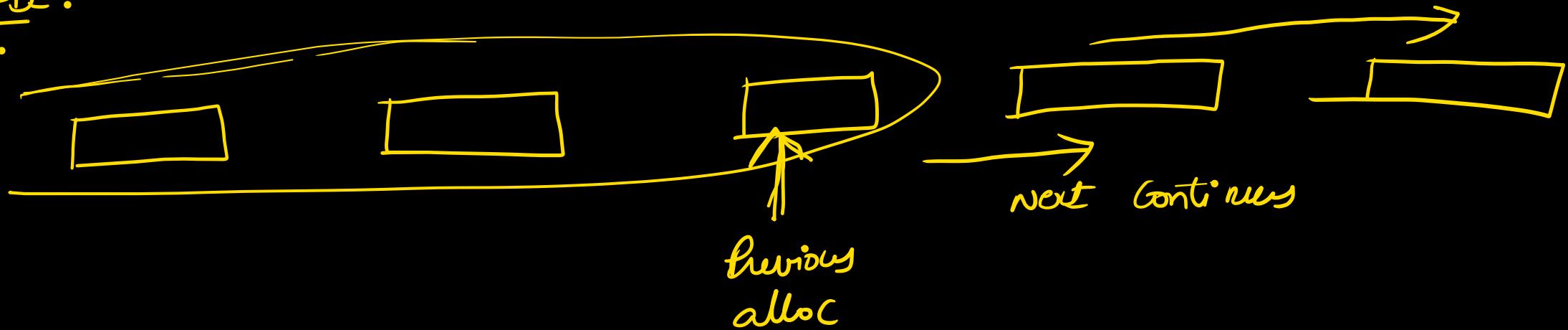
First fit:



First is the best

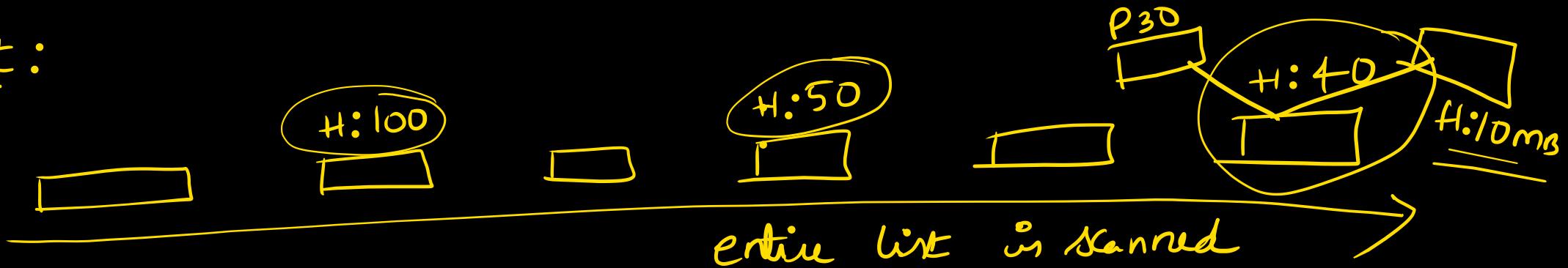
next fit:

-
-



First fit is best

Best Fit:



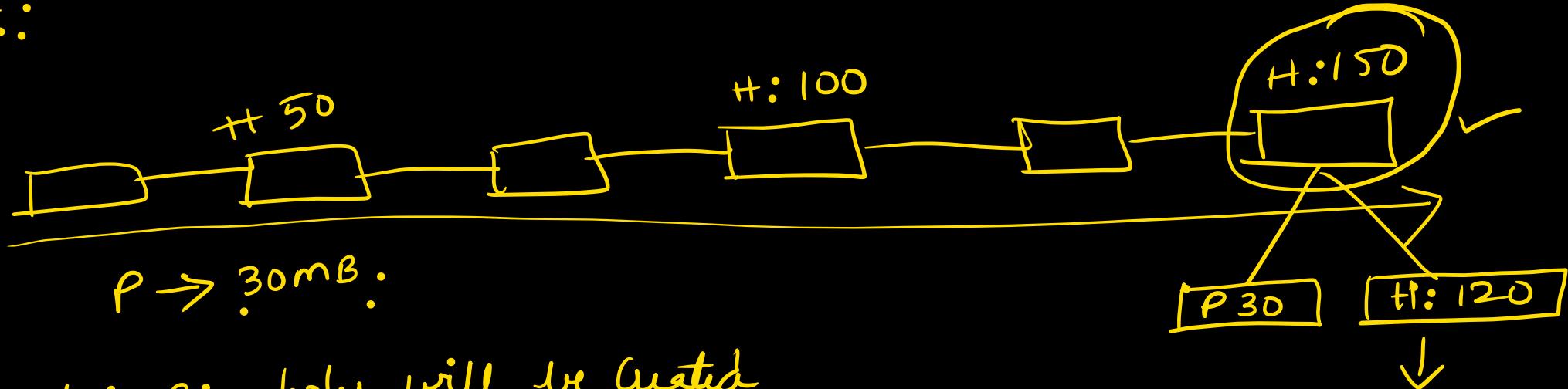
disadv:

$P \rightarrow 30mB$

- 1) This is time consuming.
- 2) very small holes will be created which will be useless.

First is best one.

worst Fit:

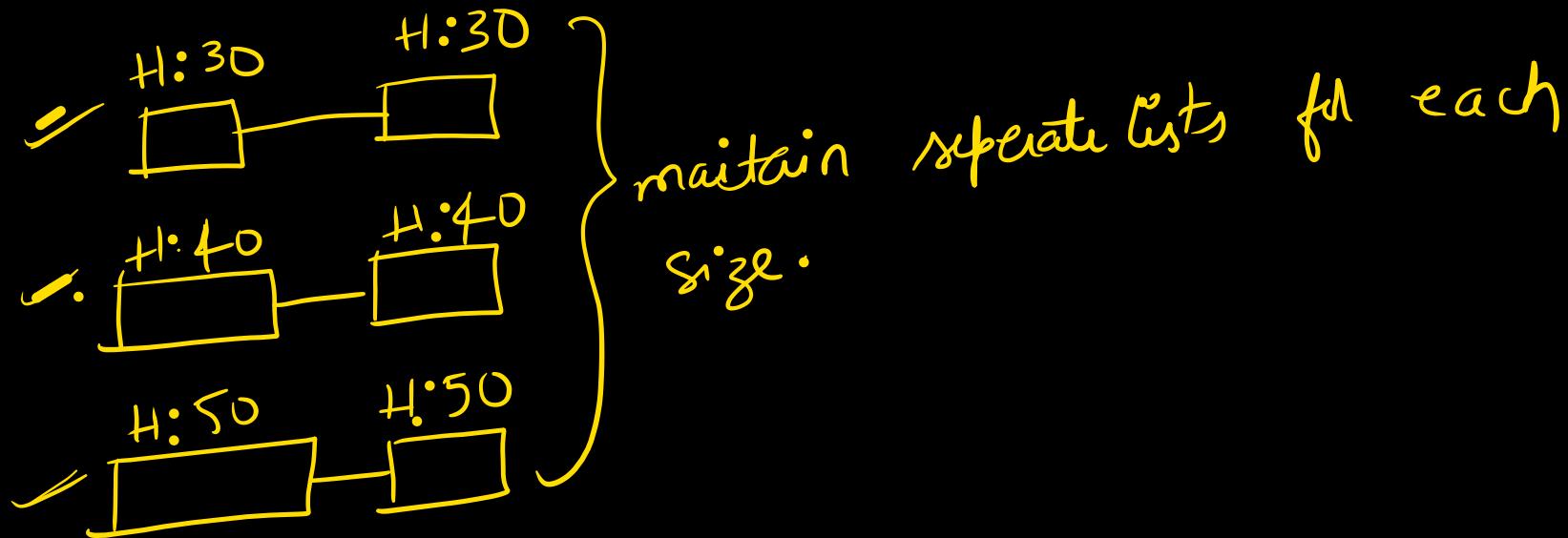


adv: Big holes will be created

dis: entire scan is required.

First fit is best.

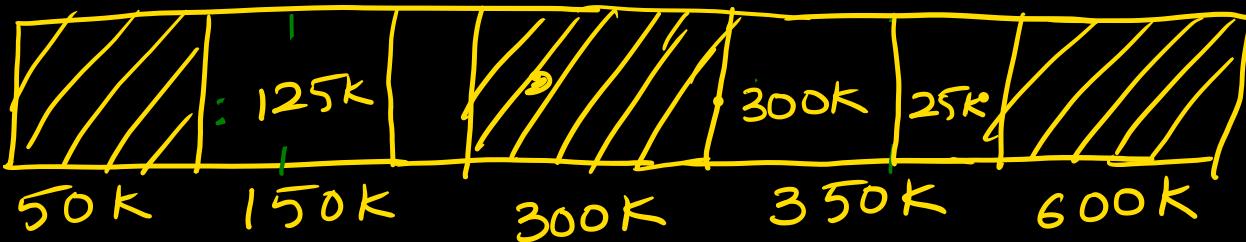
Quick Fit:



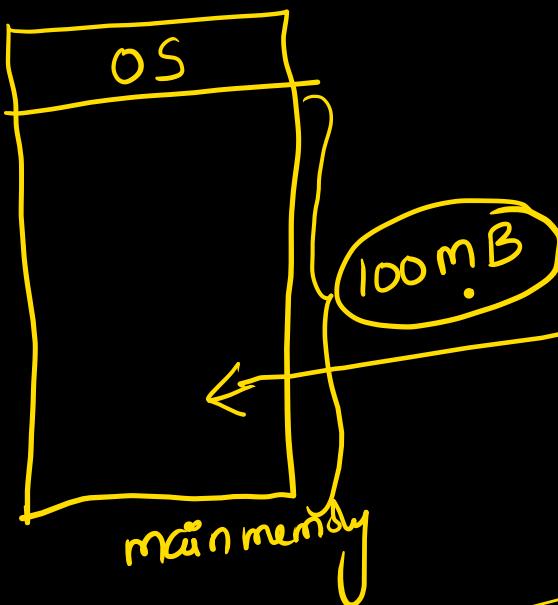
Did Dis: maintenance .

not used .

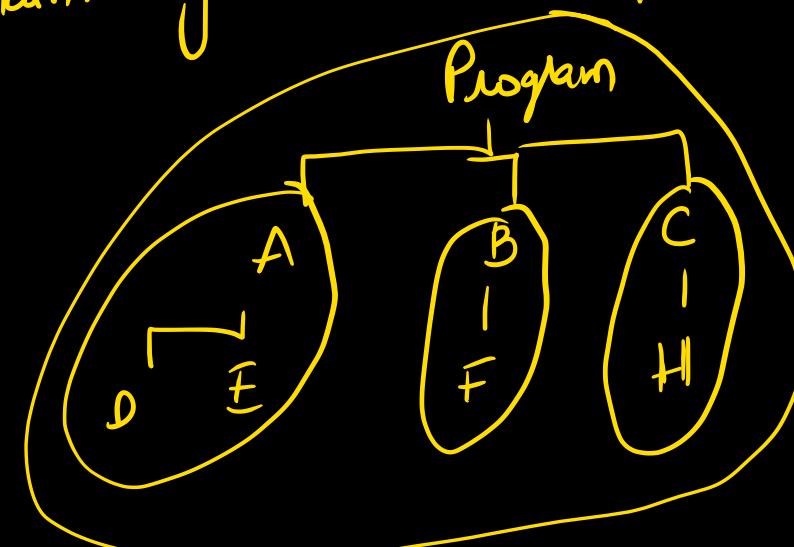
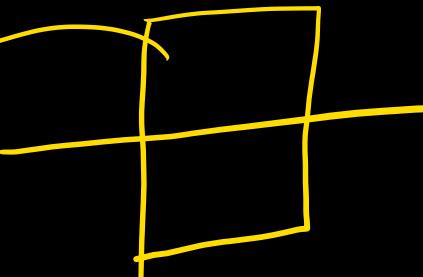
Gate 16) Process requests 300K, 25K, 125K, 50K ✓.



- a) Either FF & BF
 FF BF
- b) FF but not BF
- c) BF but not FF
 300K, 50K, 125K, 25K ✓
- d) None.



$PS > 100 \text{ MB}$ X

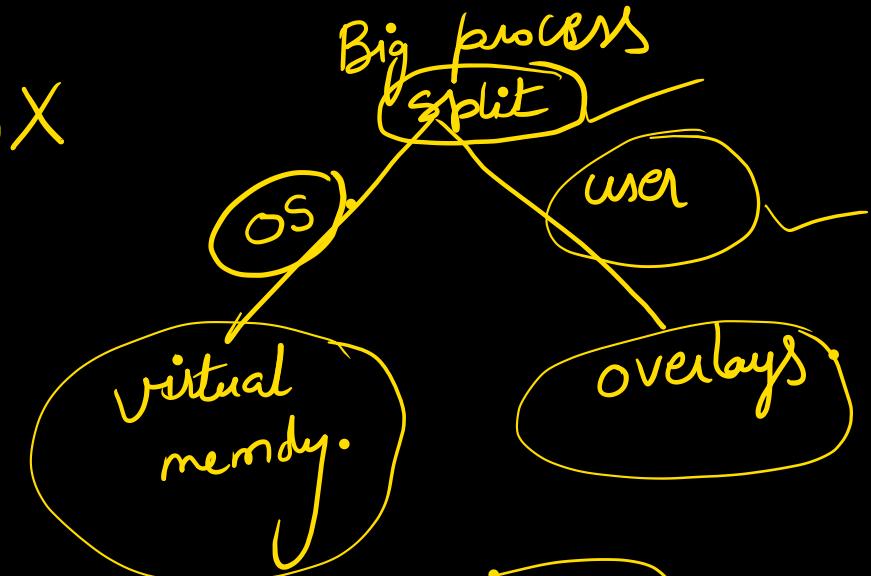


$(A + D + E) + \text{Overlay direct}$

$(B + F) . + " "$

$(C + H) + "$

A series of three curved brackets containing text, representing memory addresses or pointers. The first bracket contains "(A + D + E) + Overlay direct". The second bracket contains "(B + F) . + " ". The third bracket contains "(C + H) + " ".



Consider a 2 pass assembler

Pass 1: 70 KB ✓

Pass 2: 80 KB ✓

symbol table: 30 KB ✓

Common Routine: 20 KB ✓

Total memory: 200 KB

But at anytime only one pass will be in use and both passes
always need ST and CR. If overlay drive is 10 KB, then what is the
minimum partition size required?

$$\text{Pass 1 requirement} = \overbrace{70 + 30 + 20} + 10 = 130 \text{ KB} \quad \checkmark$$

$$\text{Pass 2 req} = 80 + \overbrace{30 + 20} + 10 = 140 \text{ KB} \quad \checkmark$$

$$140 \text{ KB} \quad \checkmark$$

