

Batch Name : PreCAT OM22 - Fast Track Batch
Module Name : Data Structures

Q. What is a data structure?

We want to store marks of 100 students

int m1, m2, m3, m4,, m100; //400 bytes

- we want to sort marks of 100 students in a descending order
sorting

int marks[100]; //400 bytes

we want to store info of 100 students:

rollno: int
name: char []
marks: float

struct employee emp[100];

- to learn data structure is not to learn any programming language, it is nothing but to learn **algorithms**.

Q. What is a Program?

- a program is a finite set of instructions written in any programming language given to the machine to do specific task.

Q. What is an algorithm?

- an algorithm is a finite set of instructions written in human understandable language like english, if followed, accomplishes given task.

- A Program is an implementation of an Algorithm

- An Algorithm is like a blueprint of a Program.

Algorithm ==> User / Pseudocode ==> Programmer

Program ==> Machine

Q. What is a Pseudocode?

- an algorithm is a finite set of instructions written in human understandable language like english with some **programming constraints**, if followed, accomplishes given task, such algo is also called as pseudocode.

- pseudocode is a special form of an algo

traversal on an array/to scan array ==> to visit each array element sequentially from first element max till last element.

Algorithm : to do sum of array elements:

step-1: initially take sum as 0.

step-2: start traversal of an array and add each array element into the sum sequentially.

Step-3: return final sum

Pseudocode/Special form of an algo: ==> Programmer User

Algorithm ArraySum(A, n)//A is an array having size n

```
{  
    sum = 0;  
    for( index = 1 ; index <= n ; index++ ){  
        sum += A[ index ];  
    }  
  
    return sum;  
}
```

Program: ==> Machine

```
int array_sum( int arr[ ], int size ){  
    int sum = 0;  
    for( int index = 0 ; index < size ; index++ ){  
        sum += arr[ index ];  
    }  
  
    return sum;  
}
```

- An algorithm is a solution of a given problem

- algorithm = solution

- Problem: can we have multiple solutions for single problem

Pune ==> Mumbai

multiple paths exists between Pune & Mumbai

efficient/optimized path ==>

distance in km

cost required for

medium

traffic conditions

- **One problem may have multiple solutions**

Searching: to search given key element into a collection/list of elements

1. linear search
2. binary search

Sorting: to arrange data elements in a collection/list of elements either in an ascending order (or in a descending order).

1. bubble sort
 2. selection sort
 3. insertion sort
 4. merge sort
 5. quick sort
 6. heap sort
 7. radix sort
 8. shell sort
- etc....

- When we have multiple solutions/algo's for a single problem, we need to select an efficient solution/algo out of them, and to decide efficiency of an algo's we need to do their analysis.

- **analysis of an algo** is a work of calculating how much **time** i.e. computer time and **space** i.e. computer memory it needs to run to completion.

- there are two measures of analysis of an algo:

1. **time complexity** of an algo is the amount of time i.e. computer time it needs to run to completion.

2. **space complexity** of an algo is the amount of space i.e. computer memory it needs to run to completion.

Linear Search:

Best case : occurs if key is found at first position in only 1 comparison: $O(1)$

for size of an array = 10 \Rightarrow no. of comparisons = 1

for size of an array = 20 \Rightarrow no. of comparisons = 1

for size of an array = 30 \Rightarrow no. of comparisons = 1

.

.

for size of an array = 50 \Rightarrow no. of comparisons = 1

for size of an array = 100 \Rightarrow no. of comparisons = 1

for size of an array = $n \Rightarrow$ no. of comparisons = 1

Worst case : occurs if either key is found at last position or key is not found $O(n)$.

for size of an array = 10 \Rightarrow no. of comparisons = 10

for size of an array = 20 \Rightarrow no. of comparisons = 20

for size of an array = 30 \Rightarrow no. of comparisons = 30

.

.

for size of an array = 50 \Rightarrow no. of comparisons = 50

for size of an array = 100 \Rightarrow no. of comparisons = 100

for size of an array = $n \Rightarrow$ no. of comparisons = n

best case: if an algo takes min amount of time to run to completion

worst case: if an algo takes max amount of time to run to completion

average case: if an algo takes neither min nor max amount of time to run to completion

for size of an array = 10 \Rightarrow 20 bytes/40 bytes \Rightarrow 10 units

for size of an array = 20 \Rightarrow 40 bytes/80 bytes \Rightarrow 20 units

for size of an array = $n \Rightarrow$ n units

Space Complexity = $O(n)$.

+ Rule: if running time of an algo is having any additive/subtractive/multiplicative/divisive constant then it can be neglected.

e.g.

$O(n + 3) \Rightarrow O(n)$

$O(n - 4) \Rightarrow O(n)$

$O(n / 3) \Rightarrow O(n)$

$O(2 * n) \Rightarrow O(n)$

+ Binary Search:

by means of calculating mid pos big size array gets divided logically into two subarrays: left subarray & right subarray

for left subarray \Rightarrow value of left remains same, right = mid-1

for right subarray \Rightarrow value of right remains same, left = mid+1

if size of an array = 1000

iteration-1: [0 1 2 3 1000] \Rightarrow mid \rightarrow 1 comparison \Rightarrow 500
[0.. 499] 500 [501 1000]

iteration-2: [501 1000] \Rightarrow mid = 750 \Rightarrow 1 comparison \Rightarrow 250
[501..... 749] 750 [751 1000]

iteration-3: [501 750] 1 comparins \Rightarrow 125

after iteration-1: no. of cmp = 1, $n/2$ $\Rightarrow T(n/2^1) + 1$

after iteration-2: no. of cmp = 2, $n/4$ $\Rightarrow T(n/2^2) + 2$

after iteration-3: no. of cmp = 3, $n/8$ $\Rightarrow T(n/2^3) + 3$

.

.

let us assume k no. of iterations takes

after iteration-k: no. of cmp = k, $n/2^k$ $\Rightarrow T(n/2^k) + K$

DS DAY-02:

Rule: if running time of an algo is having a polynomial, then in its time complexity only leading gets considered.

e.g.

$$O(n^3 + n + 5) \Rightarrow O(n^3)$$

Sorting Algorithm:

1. Selection Sort

total no. of comparisons = $(n-1) + (n-2) + (n-3) + \dots$

$$\text{total no. of comparisons} = n(n-1) / 2$$

$$\Rightarrow (n^2 - n) / 2$$

$$\Rightarrow O((n^2 - n) / 2)$$

$$\Rightarrow O(n^2 - n)$$

$$\Rightarrow O(n^2)$$

iteration-1 \Rightarrow 10 20 30 40 50 60 \Rightarrow no. of comparisons = 5

iteration-2 \Rightarrow 10 20 30 40 50 60 \Rightarrow no. of comparisons = 4

.

.

n-1 no. of iterations takes place

Best Case:

iteration-1:

10 20 30 40 50 60

10 20 30 40 50 60

10 20 30 40 50 60

10 20 30 40 50 60

10 20 30 40 50 60

if there is no need of swapping for any pair \Rightarrow if all pairs are in order \Rightarrow array is already sorted \Rightarrow no need to goto next iteration

in best only 1 iteration is required, and

total no. of comparisons = $n-1$

$$T(n) = O(n-1)$$

$$T(n) = O(n)$$

$$\text{Time Complexity} = \Omega(n)$$

- time complexities in an ascending order:
 $O(1) < O(\log n) < O(n) < O(n \log n) < O(n^2)$

3. Insertion Sort:

```
for( i = 1 ; i < SIZE ; i++ ){  
    key = arr[ i ];  
    j = i-1;  
  
    //if pos is valid && key < arr[ j ]  
    while( j >= 0 && key < arr[ j ] ){  
        arr[ j+1] = arr[ j ]; //shift ele towards its right by 1  
        j--; //goto prev element  
    }  
  
    //insert key at its appropriate position  
    arr[ j+1 ] = key;  
}
```

total no. of iterations = $n-1$
in every iteration max n no. of comparisons takes place
= $n(n-1)/2$

=> $O(n^2)$

iteration-1:

10 20 30 40 50

=> 10 20 30 40 50 => no. of comparisons = 1

iteration-2:

=> 10 20 30 40 50

=> 10 20 30 40 50 => no. of comparisons = 1

iteration-3:

=> 10 20 30 40 50

=> 10 20 30 40 50 => no. of comparisons = 1

Best Case: if array is already sorted, then in every iteration only 1 comparison takes place, and insertion sort algo takes max $(n-1)$ no. of iterations to sort all array ele's

total no. of comparisons = $1 * (n-1) = (n-1)$

$T(n) = O(n-1) \Rightarrow O(n) \Rightarrow \Omega(n)$.

Rule: if any algo follows **divide-and-conquer** approach, we get time complexity of that algo in terms of log.

DS DAY-03:

+ Quick Sort

Worst Case occurs in a quick sort if either array ele's are already sorted or are exists in exactly in a reverse order.

iteration-1: 10 20 30 40 50 60
[LP] 10 [20 30 40 50 60]

iteration-2: [20 30 40 50 60]
[LP] 20 [30 40 50 60]

iteration-3: [30 40 50 60]
[LP] 30 [40 50 60]

int arr[1000];
900 ele's are there
if we want to insert/add an element into an array at 100th location

Q. Why Linked List? to overcome limitations of an array

Linked List must has following 2 features:

1. linked must be dynamic - no. of elements that we can add into it should not be fixed
2. addition & deletion operations should gets performed on linked list efficiently i.e. in $O(1)$ time.

Q. What is a Linked List?

- Linked list is a **basic/linear data structure**, which is a **collection/list of logically related similar type of elements** in which,
- an addr of first element in a list always gets stored into a pointer variable referred as **head**, and each element contains actual data and an addr of (link of) its next element (as well as an addr/link of its previous element).
- in a linked list data structure an element is also called as a **node**.

- there basic 2 types of linked list:

1. **singly linked list:** it is a type of linked list in which each node contains an addr of its next node only.

(no. of links in each node = 1)

- there are 2 types of singly linked list:

1. singly linear linked list

2. singly circular linked list

2. **doubly linked list:** it is a type of linked list in which each node contains an addr of its next node as well as an addr of its prev node.

(no. of links in each node = 2)

- there are 2 types of doubly linked list:

1. doubly linear linked list

2. doubly circular linked list

- there are total 4 types of linked list:

1. singly linear linked list

2. singly circular linked list

3. doubly linear linked list

4. doubly circular linked list

1. singly linear linked list:

if (head == NULL) ==> list is empty

if (head != NULL) ==> list is not empty

each node has 2 part

1. data

2. pointer (next)

to store an addr of int var ==> int *

to store an addr of char var ==> char *

to store an addr of float var ==> float *

to store an addr of struct student var ==> struct student *

struct node

```
{
    int data;//4 bytes
    struct node *next;//self referential pointer -> 4 bytes (32-bit compiler)
};
```

sizeof(struct node): 8 bytes (32-bit compiler)

- we can perform 2 basic operations on a linked list data structure

1. **addition:** to add/insert a node into the linked list
2. **deletion:** to delete/remove node from the linked list

1. **addition:** to add/insert a node into the linked list

- we can add node into the linked list by 3 ways:

- i. **add node into the linked list at last position**
- ii. **add node into the linked list at first position**
- iii. **add node into the linked list at any specific position (in between)**

2. **deletion:** to delete/remove node from the linked list

- we can delete node from the linked list by 3 ways:

- i. **delete node from the linked list at first position**
- ii. **delete node from the linked list at last position**
- iii. **delete node from the linked list at any specific position**

to traverse linked list: to visit each node in the linked list sequentially from first node till max last node.

- we can always start traversal from first node, as we get addr of first node from head.

i. **add node into the linked list at last position (slll):**

- we can add as many as we want no. of nodes into the slll - dynamic in $O(n)$ time:

best case : $\Omega(1)$ - if list is empty

worst case: $O(n)$ - if list is not empty we need to traverse the list till last node

average case: $\theta(n)$

- rule: in a linked list always creates new links (links associated newly created node) first and then only break old links.

ii. **add node into the linked list at first position (slll):**

- we can add as many as we want no. of nodes into the slll (dynamic) in $O(1)$ time:

best case : $\Omega(1)$

worst case: $O(1)$

average case: $\theta(1)$

SunBeam