

Weakest Preconditions (continue)

1. Let $flip \equiv \text{if } T \rightarrow x := 0 \square T \rightarrow x := 1 \text{ fi}$, $head \equiv x = 0$, and $tail \equiv x = 1$.
 - a. What is $M(flip, \emptyset)$?
 $M(flip, \emptyset) = \{\{head\}, \{tail\}\}.$
 - b. What is $wp(flip, head \vee tail)$?
 For any state σ (let's assume that x is not defined in σ to simplify the notation), we have $M(flip, \sigma) = \{\{\sigma \cup head\}, \{\sigma \cup tail\}\}$, and it satisfies $head \vee tail$, thus $wp(flip, head \vee tail) \Leftrightarrow T$.
 - c. What is $wp(flip, head)$? And what is $wp(flip, tail)$?
 For any state σ , we have $M(flip, \sigma) = \{\{\sigma \cup head\}, \{\sigma \cup tail\}\}$, it doesn't satisfy $head$ and it doesn't satisfy $tail$; thus $wp(flip, head) \Leftrightarrow wp(flip, tail) \Leftrightarrow F$.

Calculate wlp for Loop-Free Programs

- We start with the calculations of wlp in loop-free programs because: 1) if a program is loop-free (also error-free), then $wlp \Leftrightarrow wp$ 2) if a program can create runtime errors, then we can add "error-avoiding information" to convert wlp to wp . 3) We will handle wlp for loops in the future.
- The following algorithm takes S and q and calculates a predicate for $wlp(S, q)$. Since this calculation procedure is "robotic" or syntactical, so we use \equiv instead of $=$ or \Leftrightarrow here.
 - $wlp(\text{skip}, q) \equiv q$.
 - $wlp(v := e, Q(v)) \equiv Q(e)$, where Q is a predicate function.
 - We have learned this backward assignment rule, and in general this operation that takes us from $Q(v)$ to $Q(e)$ is called **syntactic substitution**; we will study this carefully in the future.
 - $wlp(S_1; S_2, q) \equiv wlp(S_1, wlp(S_2, q))$.
 - $wlp(\text{if } B \text{ then } S_1 \text{ else } S_2 \text{ fi}, q) \equiv (B \rightarrow wlp(S_1, q)) \wedge (\neg B \rightarrow wlp(S_2, q))$.
 - $wlp(\text{if } B_1 \rightarrow S_1 \square B_2 \rightarrow S_2 \text{ fi}, q) \equiv (B_1 \rightarrow wlp(S_1, q)) \wedge (B_2 \rightarrow wlp(S_2, q))$.
- 2. Calculate the following weakest liberal preconditions.
 - a. $wlp(x := x + 1, x \geq 0) \equiv (x + 1 \geq 0) \Leftrightarrow x \geq -1$
 - b. $wlp(y := y + x; x := x + 1, x \geq 0) \equiv wlp(y := y + x, x + 1 \geq 0) \equiv x + 1 \geq 0$
 - c. $wlp(y := y + x; x := x + 1, x \geq y) \equiv wlp(y := y + x, x + 1 \geq y) \equiv x + 1 \geq y + x \Leftrightarrow y \leq 1$
 - d. $wlp(x := x + 1; y := y + x, x \geq y) \equiv wlp(x := x + 1, x \geq y + x) \equiv x + 1 \geq y + x + 1 \Leftrightarrow y \leq 0$
 - e. $wlp(\text{if } y \geq 0 \text{ then } x := y \text{ fi}, x \geq 0) \equiv wlp(\text{if } y \geq 0 \text{ then } x := y \text{ else skip fi}, x \geq 0)$
 $\equiv (y \geq 0 \rightarrow y \geq 0) \wedge (y < 0 \rightarrow x \geq 0)$
 $\Leftrightarrow T \wedge (y < 0 \rightarrow x \geq 0)$
 $\Leftrightarrow y < 0 \rightarrow x \geq 0$
 $\Leftrightarrow y \geq 0 \vee x \geq 0$

$$\begin{aligned} \text{f. } wlp(\text{if } y \geq 0 \rightarrow x := y \square x < 0 \rightarrow x := y + 1 \text{ fi}, x \geq 0) &\equiv (y \geq 0 \rightarrow y \geq 0) \wedge (x < 0 \rightarrow y + 1 \geq 0) \\ &\Leftrightarrow x < 0 \rightarrow y \geq -1 \Leftrightarrow x \geq 0 \vee y \geq -1 \end{aligned}$$

Avoid Runtime Error in Expressions

- Runtime errors can appear while evaluating expressions. To avoid such errors while calculating $\sigma(e)$, we define **domain predicate** $D(e)$ such that $\sigma \models D(e)$ implies $\sigma(e) \neq \perp_e$.
 - For example, to avoid runtime error, we can define $D(b[b[k]]) \equiv 0 \leq k < \text{size}(b) \wedge 0 \leq b[k] < \text{size}(b)$.
 - Here is another example, we can define $D(x/y + u/v) \equiv y \neq 0 \wedge v \neq 0$.
- Let us define $D(e)$ using the following algorithm.
 - If e contains no operations that can fail, then $D(e) \equiv T$
 - $D(b[e]) \equiv D(e) \wedge 0 \leq e < \text{size}(b)$.
 - $D(e_1/e_2) \equiv D(e_1 \% e_2) \equiv D(e_1) \wedge D(e_2) \wedge e_2 \neq 0$.
 - $D(\text{sqrt}(e)) \equiv D(e) \wedge e \geq 0$.
 - $D(\text{op } e) \equiv D(e)$.
 - $D(e_1 \text{ op } e_2) \equiv D(e_1) \wedge D(e_2)$ for op other than $/$ and $\%$.
 - $D(f(e_1, e_2, \dots)) \equiv D(e_1) \wedge D(e_2) \wedge \dots$ for $f()$ other than $\text{sqrt}()$.
 - $D(\text{if } B \text{ then } e_1 \text{ else } e_2 \text{ fi}) \equiv D(B) \wedge (B \rightarrow D(e_1)) \wedge (\neg B \rightarrow D(e_2))$.

3. Calculate domain predicate $D(e)$ for the following expressions.

- $$\begin{aligned} D(b[b[k]]) &\equiv D(b[k]) \wedge 0 \leq b[k] < \text{size}(b) \\ &\equiv D(k) \wedge 0 \leq k < \text{size}(b) \wedge 0 \leq b[k] < \text{size}(b) \\ &\equiv T \wedge 0 \leq k < \text{size}(b) \wedge 0 \leq b[k] < \text{size}(b) \\ &\Leftrightarrow 0 \leq k < \text{size}(b) \wedge 0 \leq b[k] < \text{size}(b) \end{aligned}$$
- Let $B \equiv 0 \leq k < \text{size}(b)$.

$$\begin{aligned} D(\text{if } B \text{ then } b[k] \text{ else } -1 \text{ fi}) &\equiv D(B) \wedge (B \rightarrow D(b[k])) \wedge (\neg B \rightarrow D(-1)) \\ &\Leftrightarrow T \wedge (B \rightarrow D(b[k])) \wedge (\neg B \rightarrow T) \\ &\Leftrightarrow B \rightarrow D(b[k]) \\ &\equiv 0 \leq k < \text{size}(b) \rightarrow 0 \leq k < \text{size}(b) \\ &\Leftrightarrow T \end{aligned}$$

Avoid Runtime Error in Statements

- To avoid runtime errors in the execution of S , we can define domain predicate $D(S)$ that gives a sufficient condition that avoids runtime errors. We will discuss how to avoid divergence in the future.
- Let us define $D(S)$ using the following algorithm.
 - $D(\text{skip}) \equiv T$
 - $D(v := e) \equiv D(e)$
 - $D(b[e_1] := e_2) \equiv D(b[e_1]) \wedge D(e_2)$
 - $D(S_1; S_2) \equiv D(S_1) \wedge wp(S_1, D(S_2))$
 - $D(S_1)$ guarantees the execution of S_1 is error-free, $D(S_2)$ guarantees the execution of S_2 is error-free.
 - $wp(S_1, D(S_2))$ guarantees that S_2 is executed in an acceptable state.
 - $D(\text{if } B \text{ then } S_1 \text{ else } S_2 \text{ fi}) \equiv D(B) \wedge (B \rightarrow D(S_1)) \wedge (\neg B \rightarrow D(S_2))$.
 - $D(\text{if } B_1 \rightarrow S_1 \square B_2 \rightarrow S_2 \text{ fi}) \equiv D(B_1 \vee B_2) \wedge (B_1 \rightarrow D(S_1)) \wedge (B_2 \rightarrow D(S_2))$.

- $D(\text{while } B \text{ do } S_1 \text{ od}) \equiv D(B) \wedge (B \rightarrow D(S_1)).$
- $D(\text{do } B_1 \rightarrow S_1 \square B_2 \rightarrow S_2 \text{ od}) \equiv D(B_1 \vee B_2) \wedge (B_1 \rightarrow D(S_1)) \wedge (B_2 \rightarrow D(S_2)).$

Calculate wp for Loop-Free Programs

- $wp(S, q) \equiv D(S) \wedge wlp(S, q) \wedge D(wlp(S, q))$
4. Calculate $w_1 \Leftrightarrow wp(x := b[k], \text{sqrt}(x) \geq 1).$
- $D(x := b[k]) \equiv 0 \leq k < \text{size}(b)$
 - $wlp(x := b[k], \text{sqrt}(x) \geq 1) \equiv \text{sqrt}(b[k]) \geq 1$
 - $D(wlp(x := b[k], \text{sqrt}(x) \geq 1)) \equiv D(\text{sqrt}(b[k]) \geq 1) \equiv b[k] \geq 0 \wedge 0 \leq k < \text{size}(b)$
 - $w_1 \equiv 0 \leq k < \text{size}(b) \wedge \text{sqrt}(b[k]) \geq 1 \wedge b[k] \geq 0 \wedge 0 \leq k < \text{size}(b)$
 $\Leftrightarrow \text{sqrt}(b[k]) \geq 1 \wedge b[k] \geq 0 \wedge 0 \leq k < \text{size}(b)$
 $\Leftrightarrow b[k] \geq 1 \wedge 0 \leq k < \text{size}(b)$
5. Calculate $w_0 \Leftrightarrow wp(x := y; z := v/x, z > x + 2).$
- Let $w \equiv wlp(x := y; z := v/x, z > x + 2).$
Then $w \equiv wlp(x := y, v/x > x + 2) \equiv v/y > y + 2.$
 - $D(w) \equiv D(v/y > y + 2) \equiv y \neq 0$
 - $D(x := y; z := v/x) \equiv D(x := y) \wedge wp(x := y, D(z := v/x))$
 $\equiv T \wedge wp(x := y, x \neq 0)$
 $\equiv T \wedge D(x := y) \wedge wlp(x := y, x \neq 0) \wedge D(wlp(x := y, x \neq 0))$
 $\equiv T \wedge T \wedge y \neq 0 \wedge D(y \neq 0) \Leftrightarrow y \neq 0$
 - $w_0 \Leftrightarrow y \neq 0 \wedge v/y > y + 2$