



# ENGINEERING MECHANICS

| COURSE CONTENT                          | CODE | SYLLABUS  |
|---|------|---|
| BASICS OF MECHANICS<br>AND FORCE SYSTEM | 1    | 1.1 Significance and relevance of Mechanics<br>1.1.1 Applied mechanics<br>1.1.2 Statics<br>1.1.3 Dynamics<br>1.2 Definitions of Space, time, mass, particle, flexible body and rigid body<br>1.3 Scalar and vector quantity ,Units of measurement (SI units)<br>1.3.1 Fundamental units<br>1.3.2 Derived units<br>1.4 Force<br>1.4.1 Unit<br>1.4.2 Representation as a vector and by Bow's notation<br>1.4.3 Characteristics and effects of a force .<br>1.5 Law of parallelogram |
| EQUILIBRIUM                             | 2    | 2.1 Equilibrium and Equilibrant<br>2.1.1 Free body and Free body diagram<br>2.2 Lami's Theorem – statement and explanation<br>2.2.1 Application for various engineering problems<br>2.3 Types of beam<br>2.4 Types of supports (simple, hinged, roller and fixed)<br>2.5 Types of loads acting on beam (vertical and inclined point load, uniformly distributed load, couple)   |



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| FRICITION                      | 3    | <ul style="list-style-type: none"><li>3.1 Friction and its relevance in engineering<ul style="list-style-type: none"><li>3.1.1 Types and laws of friction</li><li>3.1.2 Limiting equilibrium</li><li>3.1.3 Limiting friction</li><li>3.1.4 Co-efficient of friction</li><li>3.1.5 Angle of friction (only theory)</li><li>3.1.6 Angle of repose (only theory)</li><li>3.1.7 Relation between co-efficient of friction and angle of friction</li></ul></li><li>3.2 Equilibrium of bodies on level surface subjected to<ul style="list-style-type: none"><li>3.2.1 Force parallel to plane</li><li>3.2.2 Force inclined to plane</li></ul></li></ul> |
| CENTROID AND CENTRE OF GRAVITY | 4    | <ul style="list-style-type: none"><li>4.1 Center of gravity of : Square , Rectangle, Triangle, Circle, Semi-circle and Quarter circle(No derivation)</li><li>4.2 Centroid of composite figures composed of not more than three geometrical figures</li><li>4.3 Centre of Gravity of Cube,Cuboid,Cone,Cylinder,Sphere and hemisphere (No derivation)</li></ul>  |
| SIMPLE LIFTING MACHINE         | 5    | <ul style="list-style-type: none"><li>5.1 Simple lifting machine<ul style="list-style-type: none"><li>5.1.1 Related terms: load, effort, mechanical advantage</li><li>5.1.2 Applications and advantages.</li><li>5.1.3 Velocity ratio</li><li>5.1.4 Efficiency of machines</li></ul></li><li>5.2 Law of machine</li><li>5.3 Ideal machine<ul style="list-style-type: none"><li>5.3.1 Friction in machine</li><li>5.3.2 Maximum Mechanical advantage and efficiency</li></ul></li></ul>   |