

APL 105      Lecture 7

$$\left. \begin{aligned} \epsilon_x &= \frac{1}{E} (\sigma_x - \nu \sigma_y - \nu \sigma_z) \\ \epsilon_y &= \frac{1}{E} (\sigma_y - \nu \sigma_x - \nu \sigma_z) \\ \epsilon_z &= \frac{1}{E} (\sigma_z - \nu \sigma_x - \nu \sigma_y) \end{aligned} \right\} \text{ due to axial load}$$
$$\tau_{xy} = \frac{\tau_{xy}}{G}, \quad \tau_{yz} = \frac{\tau_{yz}}{G}, \quad \tau_{zx} = \frac{\tau_{zx}}{G}$$

$$G = \frac{E}{2(1+\nu)}$$

Thermal strain (

$$\epsilon_x^t = \epsilon_y^t = \epsilon_z^t = \alpha (T - T_0) \quad \begin{array}{l} \text{if no strain at } T_0 \\ \text{and setup is} \\ \text{subject to temperature } T. \end{array}$$

Equilibrium equations for an isotropic solid

and homogeneous

Eqlm eqns.  $\nabla \cdot T_{ij} + g_i = 0$   $g_i =$  body force per unit mass

$$\left. \begin{aligned} \frac{\partial \sigma_x}{\partial x} + \frac{\partial T_{xy}}{\partial y} + \frac{\partial T_{xz}}{\partial z} + g_x &= 0 \\ \frac{\partial T_{xy}}{\partial x} + \frac{\partial \sigma_y}{\partial y} + \frac{\partial T_{yz}}{\partial z} + g_y &= 0 \\ \frac{\partial T_{xz}}{\partial x} + \frac{\partial T_{yz}}{\partial y} + \frac{\partial \sigma_z}{\partial z} + g_z &= 0 \end{aligned} \right\} 3 \text{ eqns.}$$

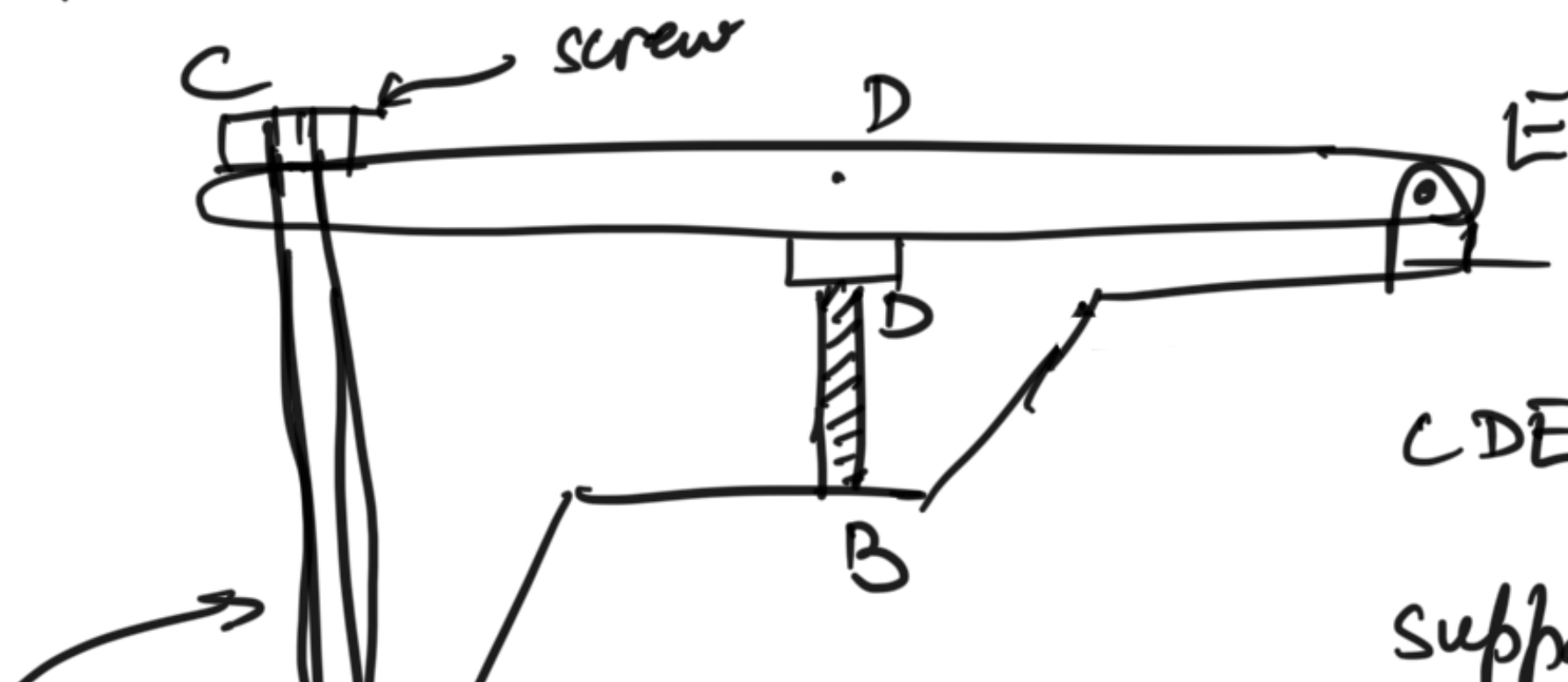
Let  $u, v, w$  be displacement in  $x, y, z$  directions

$$\left. \begin{aligned} \epsilon_x &= \frac{\partial u}{\partial x}, \quad \epsilon_y = \frac{\partial v}{\partial y}, \quad \epsilon_z = \frac{\partial w}{\partial z} \\ \gamma_{xy} &= \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y}, \quad \gamma_{yz} = \frac{\partial w}{\partial y} + \frac{\partial v}{\partial z} \\ \gamma_{xz} &= \frac{\partial u}{\partial z} + \frac{\partial w}{\partial x} \end{aligned} \right\} 6 \text{ eqns.}$$

$$\begin{aligned}
 \epsilon_x &= \frac{1}{E} [\sigma_x - \nu(\sigma_y + \sigma_z)] + \alpha(T - T_0) \\
 \epsilon_y &= \frac{1}{E} [\sigma_y - \nu(\sigma_x + \sigma_z)] + \alpha(T - T_0) \\
 \epsilon_z &= \frac{1}{E} [\sigma_z - \nu(\sigma_x + \sigma_y)] + \alpha(T - T_0) \\
 \tau_{xy} &= \frac{T_{xy}}{G}, \quad \tau_{yz} = \frac{T_{yz}}{G}, \quad \tau_{xz} = \frac{T_{xz}}{G}
 \end{aligned}
 \quad \left. \begin{array}{l} \\ \\ \\ \end{array} \right\} \begin{array}{l} \\ \\ 6 \\ \text{eqns.} \end{array}$$

Elastic Limit

### Sample Problem 2.4



CDE is a rigid bar  
supported to a pin at E



Bolt

rests on a 30 mm dia.  
brass cylinder BD

AC steel

$$E = 200 \text{ GPa}$$

$$\alpha = 11.7 \times 10^{-6} / ^\circ\text{C}$$

BD (brass)

$$E = 115 \text{ GPa}$$

$$\alpha = 20.9 \times 10^{-6} / ^\circ\text{C}$$

22 mm dia. steel bolt

AC which passes through ~~rod~~

a hole in the bar and  
is snugly fit when

$$\text{temp.} = 20^\circ\text{C}$$

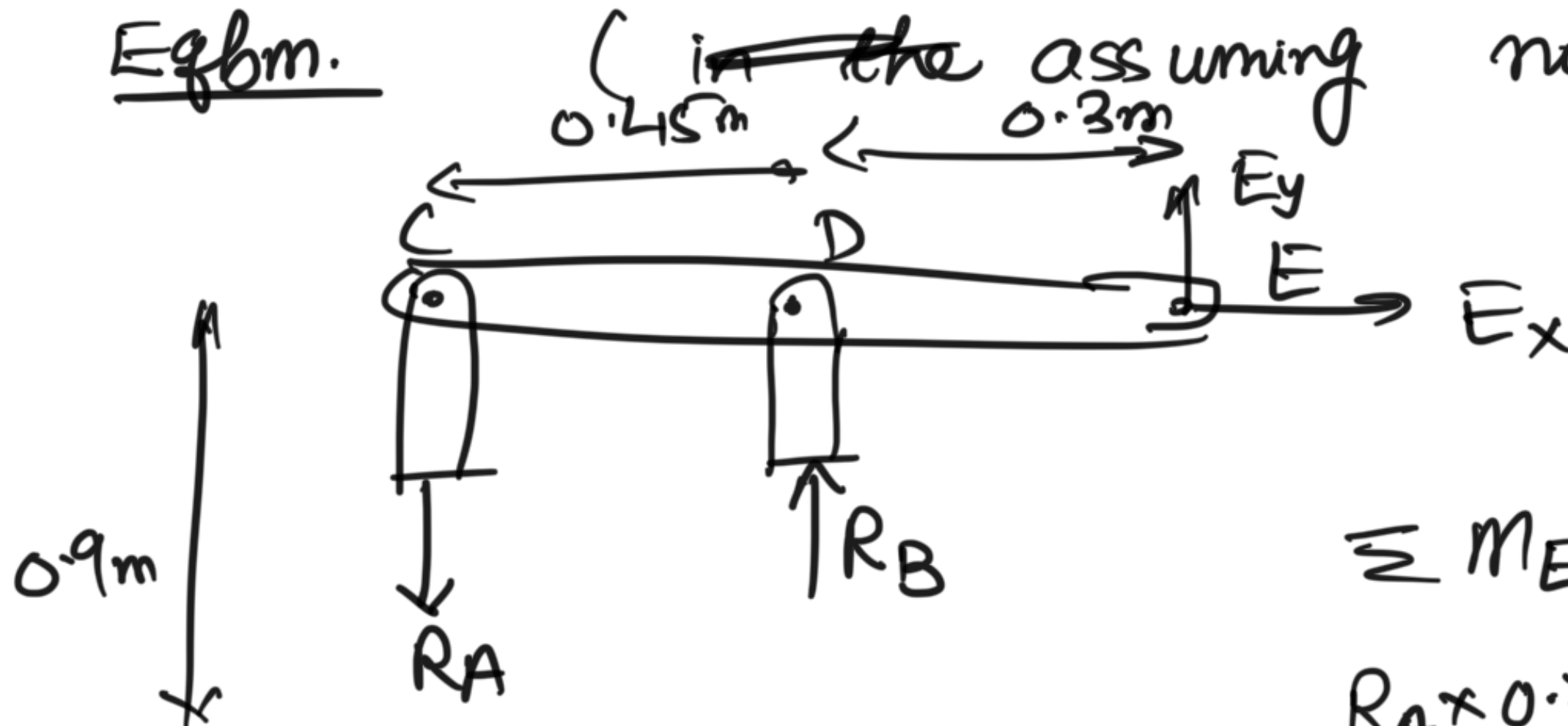
while steel rod is

Brass cylinder heated to  $50^\circ\text{C}$   
kept at  $20^\circ\text{C}$ .

Eqbm.

(~~in the~~ assuming no strains)

$$L_{BD} = 0.3 \text{ m}$$



$$\sum M_E = 0$$

$$R_A \times 0.75 = R_B (0.3)$$

$$R_A = 0.4 R_B$$

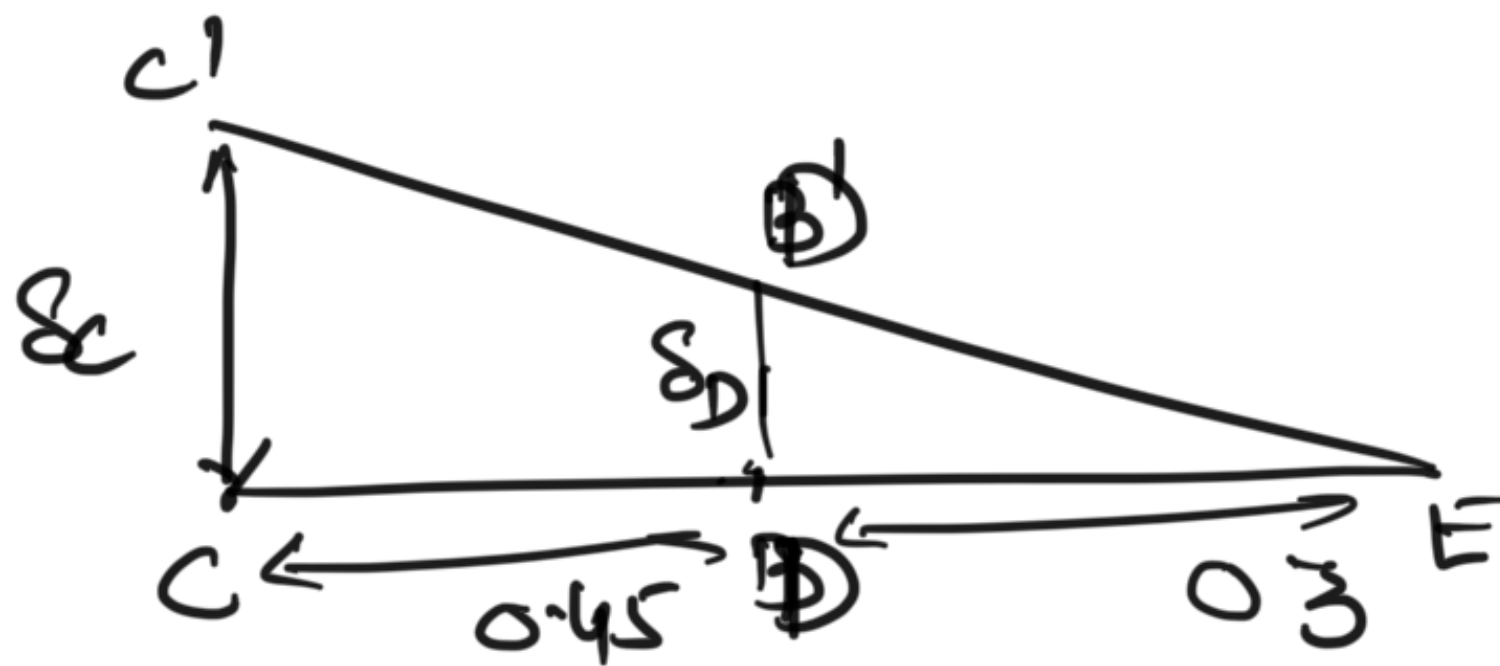
Remove  $R_B$  (redundant)

find  $\delta_{BD}$

$\delta_T$  in rod BD

Let  $R_B$  cause a deflection  $\delta_1$

$$\begin{aligned} \delta_T &= L(\Delta T) \alpha = 0.3(30^\circ\text{C})(20.9 \times 10^{-6}/^\circ\text{C}) \\ &= 188.1 \times 10^{-6} \text{ mm} \end{aligned}$$



$$\frac{\delta_D}{0.75} = \frac{0.3}{0.75} \Rightarrow \delta_D = 0.4 \delta_C$$

$\delta_C$

$$\delta_C = \frac{R_A L}{A_s E_s} = \frac{R_A (0.9)}{\frac{\pi}{4} (0.022)^2 \times (200 \times 10^9)} = 11.84 \times 10^{-9} R_A \uparrow$$

$$\delta_D = 0.4 \delta_C = 4.74 \times 10^{-9} R_A \uparrow$$

$$\delta_{B/D} = \frac{R_B L}{A_B E_B} = \frac{R_B (0.3)}{\frac{\pi}{4} (0.03)^2 \times (105 \times 10^9)} = 4.04 \times 10^{-9} R_B \uparrow$$

$$\begin{aligned} \delta_1 (\text{net compression at B}) &= \delta_D + \delta_{B/D} \\ &= 4.74 \times 10^{-9} R_A + 4.04 \times 10^{-9} R_B \\ &= 5.94 \times 10^{-9} R_B \uparrow \end{aligned}$$

$$\delta_T = \delta_1 \implies R_B \text{ can be found}$$