



as in the	
7 Paris 0	Technology used for this project:
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	To this project Al plays an able in
teletine	encipling advanced functions in
	trioct Do
i e	Dobject Detection and Recognition
1	@ Goosping and Manipulation
	3 collision Avoidance
5 2-45	@ Learning from Demonstration
30/31	and it was total powers the special has a so to the second
(6)	szu estraral enti, nothant la aprèc bhound
	Computer vision
	Computer vision parys on vitor role in a
	project involving abbotic com for raepecited task. It thables the robotic com to perceive
	and understand the envisonment accognize
	Object and make informed decision
	Object and make priorition
<u>(</u>	AI Comera:
	HI comerce is used for this following feature:
	OREsolution: - The comesa should have a resolution
	Suitable for the teisk requirement
	A DIV SHOWS IN ASSESSMENT PROPERTY OF THE STATE OF THE ST
	Pframe rate: A higher frame rate allows the
	Comera to capture fast-Moving object
	2014 100 C 00 (5)
9 15 19	3 field of view: - The camera field of view
	should cover entire workspace of the arbotic com
A STATE OF THE STA	
	@Low light Performance
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