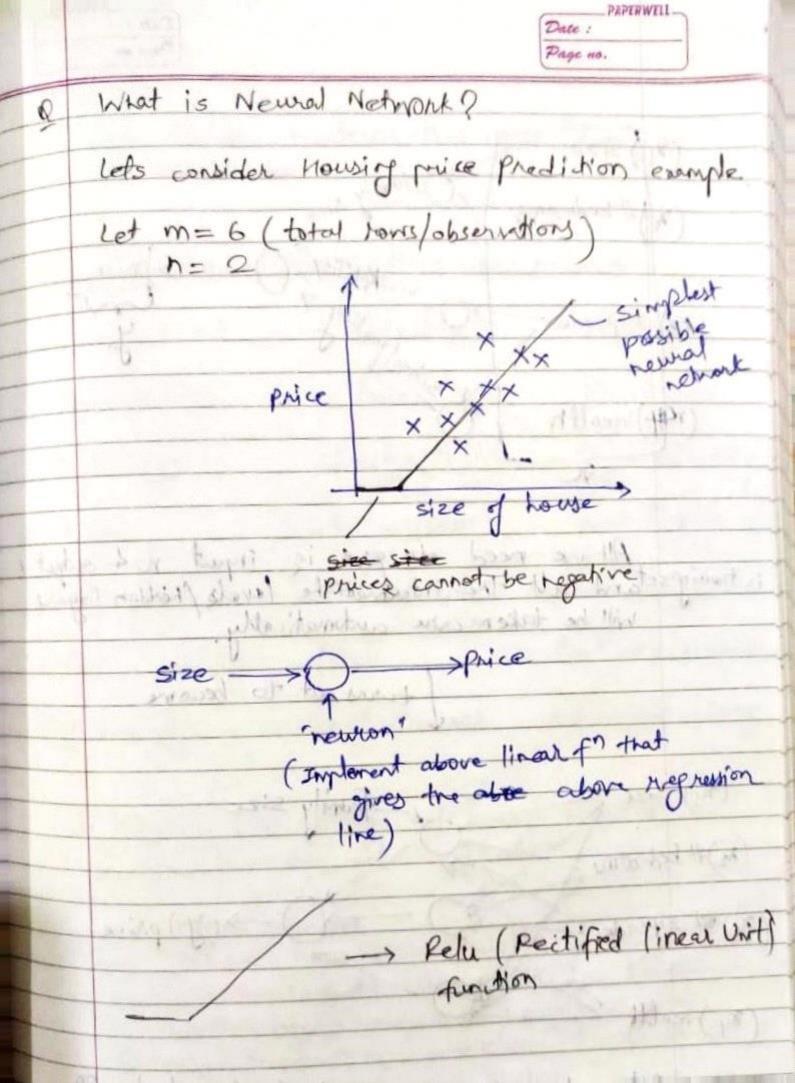
classification : > cat (1) on Not cat (0) ve don Where Jen(x)=64x64x3

ing properties british Was Раде но. $\hat{y} = \sigma(z) = 1$ $1 + e^{-z}$ $1 + e^{-(w^{T}x+b)}$ sigmoid fur hon Another alternative to b vector is) No=1 so that now on e Rh+1 ŷ = o (o'x) will not where $0 = \begin{bmatrix} 0 & -1 & b \\ 0 & -1 & b \\ 0 & 0 & 0 \end{bmatrix}$ use here in the class 154 11/4

set of all training enoughly Dass; XER DOXM on X. stape= (n, m) 7 = [gn, g2) ... ymm] YERIXM " Y.shape = (1 m) (x) = 0 Logistic Regnession? Given nERM, ŷ = P(y=1/n) Parameter o or w = parameter vetor WER" , bER Output $\hat{y} = \omega^T x + b \rightarrow \text{will not mark good}$ $\frac{\partial x}{\partial x} - \omega x \hat{y} \leq \omega$ but we want $\hat{q} \in [0,1]$ So $\hat{y} = \sigma(z) = \sigma(\omega^T r + b) = \frac{1}{1 + e^{-z}}$

(XI) size To family size () # bedrooms price Sochool Profility O (73) zipcode (rat) wealth All we need to give is input n 4 outputy in their restand all the intermediate levels / housen layers will be taken come automatically. I turns out to become - Family size (M) size ; (m) # bed-coms > (y) price (N3) = zipcode (my) realth Although Family size is just dependent on size of house at bediening he will say well manual with



J = 2 L(a", f") W1, W2, N1, X2 ER Lets initialize J=0; dw,=0; dw2=0; db=0; Let total features (M=2) i.e. Mixe 2(i) = w x (i) + 6 ain = 0 (zi) J=J+ - y' log a'i) - (1-y'i) log (1-a'i) dz(i) = a(i) y(i) dw, = dw, + x, dz / for j=1 to k dw. = dw; + x; dz (i) dw2 = dw2 + x2 dz (1) db = db + + dz(i) -> gives a [m) \(\frac{m}{2} \L(\alpha^{(i)}, y^{(i)}) \) J = J/mdul = du/m -> give () = du () y () dw2 = dw2/m" db = db/m

Date ! Page no.

you decide whatever this node "family size" Dupervised learning with newal network: Input (2) Application adjut (y) 1 tome features Peal Estate Price (lick on ad ? (0/1) Online Advertising 1 Ad, User Info Photo-topging Object (1, ... , 1000) 3 Image Tent transcript. Speck Recognition @ Audio Hindi Machine translation 3 English Andromous driving 6 Inge/Radar Joso Position of other cars slightly different types of newal retrodle are used for different applications. For above enamples Standard Neural Network (1) Real state (Home features - price) (2) Online Advarizing (Ad - aick on Not)] - CNN Speech Recognition -> RNN

(5) Machine themphion -> RMN
(6) Tresp Antonomous -> Hybrid NN
driving

Gradient Descent y=00 (wtx+b), 0 (z)=1 J (w,b) = 1 = L(goi) you) $= -\frac{1}{m} \sum_{i=1}^{m} y^{(i)} \log \hat{y}^{(i)} + (i - y^{(i)}) \log (1 - \hat{y}^{(i)})$ Find w.b that minimizes J(w,b) $J(w,b) \rightarrow convex function ())$ [Non-convert:] Lets ignore 6 for now for simplicity John Took mister

y=g(0x) = 0 (16x) ho(n) = g Logistic regression cost function: g = 0 (wTx + 6) where 5 (z)= 1 1+e^z Giran (Guiya), (m) gal). . . (xm) gany fredition for label for ith training example training example

training example

(\$\hat{y} = h_0(n)\$ Loss function fractions (L(\hat{q}, y)) = - ($y | o \hat{y} \hat{y} +$ for single fraing enough.

(1-y) $| o \hat{y} (1-\hat{y}) |$ Cost: function J (w, b) = In E L (g'i) , y'i) for entire $=-\frac{1}{m}\sum_{i=1}^{m}\left[y^{(i)}|g^{(i)}+(1-y^{(i)})|g^{(i)}-\hat{y}^{(i)}\right]$ will try to find who that minimizes cost f" J

Date:
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So in birary classification our god icto learn q classifier that can input an image propresentate prepresented by feature vector X and predict the converponding labely is I am o.

Notation we will use :-

sigle trainging enample: (x,y)

ne Ron.

y e (0,1)

m= total thaining enamples

training set = { (n(1) y(1)) (n(2) y(2)) ... (n(m) (m))}

m = mouin = futal training enamples

mtest = total test exemples

Month we have to come up with a cost function that is applicable to logistic repression of it convex f? cost function for logistic regression: $cost(h_0(n), y) = \begin{cases} -\log(h_0(n)) & \text{if } y=1 \\ -\log(1-h_0(n)) & \text{if } y=0 \end{cases}$ cost (horn, y) refers to the cost/penalty
the leaving also has to pay when it predicts he (n) & actual label is y water total factor of the Call Buttonil

So FINAL vectorized Logistic Regnession Implementation Z = wTX+b (i.e. np.dot(wT, X)+b) $A = \sigma(Z)$ dZ = A-Y $dW = \frac{1}{m} X dZ^T$ db = Inp. sum (dZ) so now Gradient descent code will be w:= w- acdw b : = b - adb iteration of gradient descent without using a single for loop. But to implement multiple iterations of gradient descent we still need a fan' loop even in vectorized implementation, fan the number of Heredians.

bias wit that usually outputs value 1. sometimes when we talk about neural networks Sometimes we will say that this is a newron with a simo sigmoid/ logistic activation function. [B3] usually we call this as parameters but in neural networks literature we refer this as " weights" Layer Layer 2 Layer3 In newal networks The first layer (layer 1) is called input layer The final layer (layer 3) is called output layer because that layer has the neuron that computes outputs the final value computed by the hypothesis.

Newal network: - Much better way to leave compler bypothesis non linear hypothesis ever when your input feature space is by Newton model: Landent acilling & south output inhe (Mo=1) with sigh newcon

Formard Propagation: Vectorized Implementation

$$(x_1/a_1^{(1)})$$

$$(x_2/a_2^{(1)})$$

$$(x_3/a_3^{(1)})$$

$$z_{1}^{(2)} = \theta_{10}^{(1)} \eta_{0} + \theta_{11}^{(1)} \eta_{1} + \theta_{12}^{(1)} \eta_{2} + \theta_{13}^{(1)} \eta_{3}$$

$$Z_{2}^{(2)} = \theta_{20}^{(1)} \eta_{0} + \theta_{21}^{(1)} \eta_{1} + \theta_{22}^{(1)} \chi_{2} + \theta_{23}^{(1)} \chi_{3}$$

$$Z_{3}^{(2)} = \theta_{30}^{(1)} \gamma_{0} + \theta_{31}^{(1)} \gamma_{1} + \theta_{32}^{(1)} \gamma_{2} + \theta_{33}^{(1)} \gamma_{3}$$

$$\Rightarrow \begin{array}{l} a_1 = g(z_1^{(2)}) & \text{so these } z_j^{(i)} \text{ values} \\ a_1 = g(z_1^{(2)}) & \text{are just values} \\ a_2 = g(z_2^{(2)}) & \text{input values} \\ a_2 = g(z_2^{(2)}) & \text{input values} \\ a_3 = g(z_2^{(2)}) & \text{a particular jth} \\ a_4 = g(z_2^{(2)}) & \text{a particular jth} \\ a_4 = g(z_2^{(2)}) & \text{a particular jth} \\ a_5 = g(z_2^{(2)}) & \text{a particular jth} \\ a_6 = g(z_2$$

$$a_3^2 = g(z_3^2)$$
 a particular j'm we newton of ith Level

we have 3 input unity exercises 3 hidden units



layer 2 is called the hidden layer. We can have more than I hidden layers, also. 3) a: - Activation of neuron i in layer j eg. a⁽²⁾ — activation of the first newton/arit Activation => The value that is computed by and that is output by We label these intermediate on hidden layer nodes $q^{(2)}, q^{(2)}, \dots, q^{(2)}$ and calle them "activation units". (b) = mathin of meight controlling function, mapping from layer j to layer $\alpha_{1}^{(2)} = g\left(\theta_{10}^{(1)} n_{0} + \theta_{11}^{(1)} n_{1} + \theta_{12}^{(1)} n_{2} + \theta_{13}^{(1)} n_{3}\right)$ $a_{2}^{(2)} = g \left(\theta_{20}^{(1)} n_{0} + \theta_{21}^{(1)} n_{1} + \theta_{22}^{(1)} n_{2} + \theta_{23}^{(1)} n_{3} \right)$ $Q_3^{(2)} = g \left(\theta_{30}^{(1)} x_0 + \theta_{31}^{(1)} x_1 + \theta_{32}^{(1)} x_2 + \theta_{33}^{(1)} x_3 \right)$ $h_0(x) = a_1^{(3)} = g(\theta_{10}) + \theta_{11}^{(2)} a_1^{(2)} + \theta_{12}^{(2)} a_2^{(2)} + \theta_{11}^{(2)} a_1^{(2)} + \theta_{12}^{(2)} a_2^{(2)} + \theta_{12}^{(2)$ $\theta_{13}^{(2)}$ It up between super loin for sturct o

DELTA PHO

clearly from the curive we can observe that I struce we draw for

 $tost(h_{\theta}(n), y) = -log(h_{\theta}(n))$ for y = 1

so when ho(n)= 1 & y = 1 + cost (ho(n), y) = 0

ho(n) >0 & y=1 = cost (hoch), y) & a

has malignant turnor but it is actually benjan then the leaving algo has to pay soo cost penalty for whom prediction

y=0:-

DENE S cost (ho(n),y)= -log(1-ho(x)) for y=0