CodeBook Vijay Kumar Amadapudi 11/11/2019

Data source

The data is obtained from the following project:

 $\label{lem:http://archive.ics.uci.edu/ml/datasets/Human+Activity+Recognition+Using+Smartphones and the initial data set in downloaded from the following url:$

https://d396 qusza 40 orc. cloud front.net/get data %2 Fproject files %2 FUCI %20 HAR %20 Dataset.zip

Variables

We extract from initial data only the measurements on the mean and standard deviation. We obtain the following list for our variables:

listvariables

- [[1]] [1] "tBodyAcc-mean-X"
- [[2]] [1] "tBodyAcc-mean-Y"
- [[3]] [1] "tBodyAcc-mean-Z"
- [[4]] [1] "tBodyAcc-std-X"
- [[5]] [1] "tBodyAcc-std-Y"
- [[6]] [1] "tBodyAcc-std-Z"
- [[7]] [1] "tGravityAcc-mean-X"
- [[8]] [1] "tGravityAcc-mean-Y"
- [[9]] [1] "tGravityAcc-mean-Z"
- [[10]] [1] "tGravityAcc-std-X"
- [[11]] [1] "tGravityAcc-std-Y"
- [[12]] [1] "tGravityAcc-std-Z"
- [[13]] [1] "tBodyAccJerk-mean-X"
- [[14]] [1] "tBodyAccJerk-mean-Y"
- $[[15]]\ [1]$ "tBodyAccJerk-mean-Z"
- [[16]] [1] "tBodyAccJerk-std-X"
- [[17]] [1] "tBodyAccJerk-std-Y"
- [[18]] [1] "tBodyAccJerk-std-Z"
- [[19]] [1] "tBodyGyro-mean-X"
- [[20]] [1] "tBodyGyro-mean-Y"
- [[21]] [1] "tBodyGyro-mean-Z"

- [[22]] [1] "tBodyGyro-std-X"
- [[23]] [1] "tBodyGyro-std-Y"
- [[24]] [1] "tBodyGyro-std-Z"
- [[25]] [1] "tBodyGyroJerk-mean-X"
- [[26]] [1] "tBodyGyroJerk-mean-Y"
- [[27]] [1] "tBodyGyroJerk-mean-Z"
- [[28]] [1] "tBodyGyroJerk-std-X"
- [[29]] [1] "tBodyGyroJerk-std-Y"
- [[30]] [1] "tBodyGyroJerk-std-Z"
- [[31]] [1] "tBodyAccMag-mean"
- [[32]] [1] "tBodyAccMag-std"
- [[33]] [1] "tGravityAccMag-mean"
- [[34]] [1] "tGravityAccMag-std"
- $[[35]]\ [1]$ "tBodyAccJerkMag-mean"
- [[36]] [1] "tBodyAccJerkMag-std"
- [[37]] [1] "tBodyGyroMag-mean"
- [[38]] [1] "tBodyGyroMag-std"
- [[39]] [1] "tBodyGyroJerkMag-mean"
- [[40]] [1] "tBodyGyroJerkMag-std"
- $[[41]]\ [1]$ "fBodyAcc-mean-X"
- [[42]] [1] "fBodyAcc-mean-Y"
- [[43]] [1] "fBodyAcc-mean-Z"
- [[44]] [1] "fBodyAcc-std-X"
- [[45]] [1] "fBodyAcc-std-Y"
- [[46]] [1] "fBodyAcc-std-Z"
- [[47]] [1] "fBodyAcc-meanFreq-X"
- [[48]] [1] "fBodyAcc-meanFreq-Y"
- [[49]] [1] "fBodyAcc-meanFreq-Z"
- [[50]] [1] "fBodyAccJerk-mean-X"
- [[51]] [1] "fBodyAccJerk-mean-Y"
- [[52]] [1] "fBodyAccJerk-mean-Z"
- [[53]] [1] "fBodyAccJerk-std-X"
- [[54]] [1] "fBodyAccJerk-std-Y"
- [[55]] [1] "fBodyAccJerk-std-Z"
- [[56]] [1] "fBodyAccJerk-meanFreq-X"
- [[57]] [1] "fBodyAccJerk-meanFreq-Y"

- [[58]] [1] "fBodyAccJerk-meanFreq-Z"
- [[59]] [1] "fBodyGyro-mean-X"
- [[60]] [1] "fBodyGyro-mean-Y"
- [[61]] [1] "fBodyGyro-mean-Z"
- [[62]] [1] "fBodyGyro-std-X"
- [[63]] [1] "fBodyGyro-std-Y"
- [[64]] [1] "fBodyGyro-std-Z"
- [[65]] [1] "fBodyGyro-meanFreq-X"
- [[66]] [1] "fBodyGyro-meanFreq-Y"
- [[67]] [1] "fBodyGyro-meanFreq-Z"
- [[68]] [1] "fBodyAccMag-mean"
- [[69]] [1] "fBodyAccMag-std"
- [[70]] [1] "fBodyAccMag-meanFreq"
- [[71]] [1] "fBodyBodyAccJerkMag-mean"
- [[72]] [1] "fBodyBodyAccJerkMag-std"
- [[73]] [1] "fBodyBodyAccJerkMag-meanFreq"
- [[74]] [1] "fBodyBodyGyroMag-mean"
- [[75]] [1] "fBodyBodyGyroMag-std"
- [[76]] [1] "fBodyBodyGyroMag-meanFreq"
- [[77]] [1] "fBodyBodyGyroJerkMag-mean"
- [[78]] [1] "fBodyBodyGyroJerkMag-std"
- [[79]] [1] "fBodyBodyGyroJerkMag-meanFreq"
- [[80]] [1] "activity"

Features

The original feature file describes well enough the variable since their names has only been slightly changed (removing "()" for "mean()" and "std()"). However, there is now a category variable called "activity" at the end of the table.

Concerning the other variables, let us quote the original feature file:

The features selected for this database come from the accelerometer and gyroscope 3-axial raw signals tAcc-XYZ and tGyro-XYZ. These time domain signals (prefix 't' to denote time) were captured at a constant rate of 50 Hz. Then they were filtered using a median filter and a 3rd order low pass Butterworth filter with a corner frequency of 20 Hz to remove noise. Similarly, the acceleration signal was then separated into body and gravity acceleration signals (tBodyAcc-XYZ and tGravityAcc-XYZ) using another low pass Butterworth filter with a corner frequency of 0.3 Hz.

Subsequently, the body linear acceleration and angular velocity were derived in time to obtain Jerk signals (tBodyAccJerk-XYZ and tBodyGyroJerk-XYZ). Also the magnitude of these three-dimensional signals were calculated using the Euclidean norm (tBodyAccMag, tGravityAccMag, tBodyAccJerkMag, tBodyGyroMag, tBodyGyroJerkMag).

Finally a Fast Fourier Transform (FFT) was applied to some of these signals producing fBodyAccJYZ, fBodyAccJerk-XYZ, fBodyGyro-XYZ, fBodyAccJerkMag, fBodyGyroMag, fBodyGyroJerk-Mag. (Note the 'f' to indicate frequency domain signals).

These signals were used to estimate variables of the feature vector for each pattern:

'-XYZ' is used to denote 3-axial signals in the X, Y and Z directions.