# Cedille2: A proof theoretic redesign of the Calculus of Dependent Lambda Eliminations

by

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- Some wise dude

#### ACKNOWLEDGMENTS

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# PREFACE

# INTRODUCTION TO TYPE THEORY

# THEORY DESCRIPTION AND BASIC METATHEORY

hi

 $\begin{aligned} \operatorname{dom}_{\Pi}(\omega,K) &= \star & \operatorname{codom}_{\Pi}(\omega) &= \star \\ \operatorname{dom}_{\Pi}(\tau,K) &= K & \operatorname{codom}_{\Pi}(\tau) &= \square \\ \operatorname{dom}_{\Pi}(0,K) &= K & \operatorname{codom}_{\Pi}(0) &= \star \end{aligned}$ 

Figure 2.1: Domain and codomains for function types. The variable K is either  $\star$  or  $\square$ .

$$|x| = x \qquad |f \bullet_{\tau} a| = |f| \bullet_{\tau} |a|$$

$$|\star| = \star \qquad |[s, t, T]| = |t|$$

$$|\Box| = \Box \qquad |t.1| = |t|$$

$$|\lambda_{0} x : A \cdot t| = |t| \qquad |t.2| = |t|$$

$$|\lambda_{\omega} x : A \cdot t| = \lambda_{\omega} x \cdot |t| \qquad |x =_{A} y| = |x| =_{|A|} |y|$$

$$|\lambda_{\tau} x : A \cdot t| = \lambda_{\tau} x : |A| \cdot |t| \qquad |\operatorname{refl}(t)| = \lambda_{\omega} x \cdot x$$

$$|(x : A) \to_{m} B| = (x : |A|) \to_{m} |B| \qquad |J(A, P, x, y, r, w)| = |r| |w|$$

$$|(x : A) \cap B| = (x : |A|) \cap |B| \qquad |\vartheta(e)| = |e|$$

$$|f \bullet_{0} a| = |f| \bullet_{\omega} |a| \qquad |\vartheta(e)| = |e|$$

$$|f \bullet_{0} a| = |f| \bullet_{\omega} |a| \qquad |\varphi(a, b, e)| = |a|$$

Figure 2.2: Erasure of syntax, for type-like and kind-like syntax erasure is homomorphic, for term-like syntax erasure reduces to the untyped lambda calculus.

$$(\lambda_m x : t_1. t_2) \bullet_m t_3 \leadsto_{\beta} [x := t_3] t_2$$

$$[t_1, t_2, t_3].1 \leadsto_{\beta} t_1$$

$$[t_1, t_2, t_3].2 \leadsto_{\beta} t_2$$

$$J(t_1, t_2, t_3, t_4, \operatorname{refl}(t_5), t_6) \leadsto_{\beta} t_6 \bullet_0 t_5$$

$$\vartheta(\operatorname{refl}(t.1)) \leadsto_{\beta} \operatorname{refl}(t)$$

$$\varphi(t_1, t_2, t_3).1 \leadsto_{\beta} t_1$$

Figure 2.3: Reduction rules for arbitrary syntax.

$$\frac{\vdash \Gamma}{\Gamma \vdash \star \rhd \Box} \mathsf{AXIOM} \qquad \qquad \frac{\vdash \Gamma \quad (x : A) \in \Gamma}{\Gamma \vdash x \rhd A} \mathsf{VAR}$$
 
$$\frac{\Gamma \vdash A \rhd \mathsf{dom}_{\Pi}(m, K) \qquad \Gamma, x : A \vdash B \rhd \mathsf{codom}_{\Pi}(m)}{\Gamma \vdash (x : A) \to_{m} B \rhd \mathsf{codom}_{\Pi}(m)} \mathsf{PI}$$
 
$$\frac{\Gamma \vdash A \rhd \mathsf{dom}_{\Pi}(m, K) \qquad \Gamma, x : A \vdash t \rhd B \qquad x \notin \mathsf{FV}(|t|) \text{ if } m = 0}{\Gamma \vdash \lambda_{m} \, x : A . \, t : (x : A) \to_{m} B} \mathsf{LAM}$$
 
$$\frac{\Gamma \vdash f \rhd (x : A) \to_{m} B \qquad \Gamma \vdash a \lhd A}{\Gamma \vdash f \multimap_{m} a \rhd [x := a]B} \mathsf{APP}$$

Figure 2.4: Inference rules for function types, including erased functions. The variable K is either  $\star$  or  $\square$ .

$$\frac{\Gamma \vdash A \bowtie \star \qquad \Gamma, x : A \vdash B \bowtie \star}{\Gamma \vdash (x : A) \cap B \bowtie \star} \operatorname{Int} \qquad \frac{\Gamma \vdash T \bowtie (x : A) \rightarrow_{\tau} B \qquad \Gamma \vdash t \lhd A}{\Gamma \vdash s \lhd [x := t]B \qquad t \equiv s} \operatorname{PAIR}$$

$$\frac{\Gamma \vdash t \bowtie (x : A) \cap B}{\Gamma \vdash t . 1 \bowtie A} \operatorname{FST} \qquad \qquad \frac{\Gamma \vdash t \bowtie (x : A) \cap B}{\Gamma \vdash t . 2 \bowtie [x := t.1]B} \operatorname{SND}$$

Figure 2.5: Inference rules for intersection types.

$$\frac{\Gamma \vdash A \bowtie \star}{\Gamma \vdash a \lhd A} \frac{\Gamma \vdash b \lhd A}{\Gamma \vdash b \lhd A} \operatorname{EQ} \frac{\Gamma \vdash t \rhd A}{\Gamma \vdash \operatorname{refl}(t) \rhd t =_A t} \operatorname{Refl}$$

$$\frac{\Gamma \vdash A \bowtie \star}{\Gamma \vdash a =_A b \rhd \star} \Gamma \vdash P \lhd (x \ y : A) \to_{\tau} (e : x =_A y) \to_{\tau} \star \qquad \Gamma \vdash x \lhd A}{\Gamma \vdash y \lhd A} \frac{\Gamma \vdash r \lhd x =_A y}{\Gamma \vdash w \lhd (a : A) \to_0 P \bullet_{\tau} a \bullet_{\tau} a \bullet_{\tau} \operatorname{refl}(a)} \operatorname{J}$$

$$\frac{\Gamma \vdash a \bowtie (x : A) \cap B}{\Gamma \vdash b \lhd (x : A) \cap B} \frac{\Gamma \vdash b \lhd (x : A) \cap B}{\Gamma \vdash b \lhd (x : A) \cap B} \frac{T \equiv A}{\Gamma \vdash v \lhd (a : A) \to_{\omega} (x : A) \cap B} \operatorname{PRM}$$

$$\frac{\Gamma \vdash a \bowtie A}{\Gamma \vdash e \lhd (a : A) \to_{\omega} (x : A) \cap B} \frac{\Gamma \vdash b \lhd (x : A) \cap B}{\Gamma \vdash v \lhd (a : A) \to_{\omega} (x : A) \cap B} \operatorname{PRM}$$

$$\frac{\Gamma \vdash a \lhd A}{\Gamma \vdash e \lhd (a : A) \to_{\omega} (x : A) \cap B} \operatorname{CAST}$$

$$\frac{\Gamma \vdash a \lhd A}{\Gamma \vdash v \lhd (a : A) \to_{\omega} (x : A) \cap B} \operatorname{CBool} := (X : \star) \to_0 (x : X) \to_{\omega} (y : X) \to_{\omega} X$$

$$\operatorname{ctt} := \lambda_0 X : \star \lambda_\omega x : X . \lambda_\omega y : X . x$$

$$\operatorname{cff} := \lambda_0 X : \star \lambda_\omega x : X . \lambda_\omega y : X . y \qquad \Gamma \vdash e \lhd \operatorname{ctt} =_{\operatorname{cBool}} \operatorname{cff} \\ \Gamma \vdash \delta(e) \rhd (X : \star) \to_0 X$$

Figure 2.6: Inference rules for equality types.

$$\frac{\Gamma \vdash t \rhd A \qquad A \leadsto_{\beta}^{*} B}{\Gamma \vdash t \rhd B} \text{HDINF} \qquad \frac{\Gamma \vdash t \rhd A \qquad \Gamma \vdash B \rhd K \qquad A \equiv B}{\Gamma \vdash t \vartriangleleft B} \text{CHK}$$

$$\frac{-\text{CTXEM}}{\vdash \Gamma, x : A} \qquad \frac{x \notin \text{FV}(\Gamma) \qquad \vdash \Gamma \qquad \Gamma \vdash A \rhd K}{\vdash \Gamma, x : A} \text{CTXAPP}$$

Figure 2.7: Weak-head reduction inference rule, checking rule, and context well-formedness rules.

# PROOF NORMALIZATION AND RELATIONSHIP TO SYSTEM $\mathbf{F}^\omega$

# CONSISTENCY AND RELATIONSHIP TO CDLE

#### **OBJECT NORMALIZATION**

A  $\varphi_i$ -proof is a proof that allows i nested  $\varphi$  syntactic constructs. For example, a  $\varphi_0$ -proof allows no  $\varphi$  subterms, a  $\varphi_1$ -proof allows  $\varphi$  subterms but no nested  $\varphi$  subterms, and a  $\varphi_2$ -proof allows  $\varphi_1$  subterms. Defined inductively, a  $\varphi_0$ proof is a proof with no  $\varphi$  syntactic constructs and a  $\varphi_{i+1}$ -proof is a proof with  $\varphi_i$ -proof subterms.

For any  $\varphi_i$ -proof p there is a strictification s(p) that is a  $\varphi_0$ -proof in Figure 5.1.

**Lemma 1** (Strictification Preserves Inference). Given  $\Gamma \vdash t \triangleright A$  then  $\Gamma \vdash$ s(t) > A

Proof. By induction on the typing rule, the 
$$\varphi$$
 rule is the only one of interest: 
$$\Gamma \vdash f \Vdash (a:A) \to_{\omega} (x:A) \cap B$$
 Case: 
$$\frac{\Gamma \vdash a \lhd A}{\Gamma \vdash a \lhd A} \quad \Gamma \vdash e \lhd (a:A) \to_{\omega} a =_A (f \bullet_{\omega} a).1 \qquad \text{FV}(|e|) = \varnothing}{\Gamma \vdash \varphi(a,f,e) \rhd (x:A) \cap B}$$
 CAST

Need to show that  $\Gamma \vdash s(\varphi(a, f, e)) \rhd (x : A) \cap B$  which reduces to:  $\Gamma \vdash s(f) \bullet_{\omega} s(a) \rhd (x : A) \cap B$ . By the IH we know that s(f) infers the same function type, and that s(a) infers the same argument type, therefore the application rule concludes the proof.

**Lemma 2** (Strict Proofs are Normalizing). Given  $\Gamma \vdash t \rhd A$  then s(t) is strongly normalizing

*Proof.* Direct consequence of strong normalization of proofs 

$$s(x) = x \qquad s([s,t,T]) = [s(s),s(t),s(T)]$$

$$s(\star) = \star \qquad s(t.1) = s(t).1$$

$$s(\Box) = \Box \qquad s(t.2) = s(t).2$$

$$s(\lambda_m x : A. t) = \lambda_m x : s(A). s(t) \qquad s(x =_A y) = s(x) =_{s(A)} s(y)$$

$$s((x : A) \rightarrow_m B) = (x : s(A)) \rightarrow_m s(B) \qquad s(\text{refl}(t)) = \text{refl}(s(t))$$

$$s((x : A) \cap B) = (x : s(A)) \cap s(B) \qquad s(\vartheta(e)) = \vartheta(s(e))$$

$$s(f \bullet_m a) = s(f) \bullet_m s(a) \qquad s(\delta(e)) = \delta(s(e))$$

$$s(J(A, P, x, y, r, w)) = J(s(A), s(P), s(x), s(y), s(r), s(w))$$

$$s(\varphi(a, f, e)) = s(f) \bullet_\omega s(a)$$

Figure 5.1: Strictification of a proof.

**Lemma 3** (Strict Objects are Normalizing). Given  $\Gamma \vdash t \rhd A$  then |s(t)| is strongly normalizing

#### *Proof.* Proof Idea:

Proof reduction tracks object reduction in the absence of  $\varphi$  constructs. Thus, the normalization of a proof provides an upper-bound on the number of reductions an object can take to reach a normal form.

A proof,  $\Gamma \vdash t_1 \rhd A$ , is contextually equivalent to another proof,  $\Gamma \vdash t_2 \rhd A$ , if there is no context with hole of type A whose object reduction diverges for  $t_1$  but not  $t_2$ . In other words, if a context can be constructed that distinguishes the terms based on their object reduction.

**Lemma 4.** A  $\varphi_1$ -proof, p, is contextually equivalent to its strictification, s(p)

*Proof.* Proof by induction on the typing rule for p, focus on the application rule:

Case: 
$$\frac{\Gamma \vdash f \bowtie (x:A) \to_m B \qquad \Gamma \vdash \stackrel{\mathcal{D}_2}{a \triangleleft A}}{\Gamma \vdash f \bullet_m a \bowtie [x:=a]B} \text{App}$$

In particular, we care about when  $f = \varphi(v, b, e).2$  and  $m = \omega$ . Note that the first projection has a proof-reduction that yields a which makes it unproblematic.

We know that s(v) = v because f is a  $\varphi_1$ -proof. Let  $v_n$  be the normal form of v and note that  $|v_n|$  is also normal. Likewise, we have  $e_n$  and  $|e_n|$  normal.

Suppose there is a context  $C[\cdot]$  where |p| diverges but |s(p)| normalizes. (Note that the opposite assumption is impossible). If  $|v_n|$  is a variable, then reduction in |p| is blocked (contradiction). Otherwise  $|v_n| = \lambda x. x \ t_1 \cdots t_n$  where  $t_i$  are normal.

Now it must be the case that  $|e \bullet_{\omega} v| = |e_n| \bullet_{\omega} |v_n|$  is normalizing. Thus, we have a refl proof that  $v_n = (f \bullet_{\omega} v_n).1$ . (Note, this proof must be refl because  $\mathrm{FV}(|e|) = \varnothing$ ). But, this implies convertibility, thus  $|v_n| =_{\beta} |f| \bullet_{\omega} |v_n|$ , but this must mean more concretely that  $|f| \bullet_{\omega} |v_n| \leadsto_{\beta} |v_n|$ . Yet  $|f| \bullet_{\omega} |v_n| \bullet_{\omega} a$  is strongly normalizing because it is s(p). Therefore, p in this case is strongly normalizing which refutes the assumption yielding a contradiction.

**Lemma 5.** If  $t_1$  is strongly normalizing and contextually equivalent to  $t_2$  then  $t_2$  is strongly normalizing

*Proof.* Immediate by the definition of contextual equivalence.  $\Box$ 

**Theorem 1.** A  $\varphi_i$ -proof p is strongly normalizing for all i

*Proof.* By induction on i.

Case: i = 0

Immediate because s(p) = p and strict proofs are strongly normalizing.

Inductive Case:

Suppose that  $\varphi_i$ -proof is strongly normalizing. Goal: show that  $\varphi_{i+1}$ -proof is strongly normalizing.

# CEDILLE2: SYSTEM IMPLEMENTATION

# CEDILLE2: INTERNALLY DERIVABLE CONCEPTS

# CONCLUSION AND FUTURE WORK

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