

Least Squares method

Linear least squares is a method for estimating unknown parameters in a linear regression model, with the goal of minimizing the sum of the squares of the difference between observed responses in the given data set and those predicted by a linear function of a set of explanatory variables.

Let $\{(x_i, y_i)\}_{i=1}^n$ be a set of given data.

For linear least square, $y = a_0 + a_1 x$

We try to find a_0 and a_1 such that the difference between the linear model and the given data is minimum.

The error between the model and the given data is

$$d_i = y_i - (a_0 + a_1 x_i), \quad i = 1, 2, \dots, n.$$

$$\text{Let } D = \sum_{i=1}^n d_i^2 = \sum_{i=1}^n (y_i - a_0 - a_1 x_i)^2$$

To minimize D , from Calculus, we have

$$\frac{\partial D}{\partial a_0} = - \sum_{i=1}^n 2(y_i - a_0 - a_1 x_i) = -2 \sum_{i=1}^n (y_i - a_0 - a_1 x_i)$$

$$\frac{\partial D}{\partial a_1} = -2 \sum_{i=1}^n (y_i - a_0 - a_1 x_i)(x_i) = -2 \left(\sum_{i=1}^n x_i y_i - a_0 \sum_{i=1}^n x_i - a_1 \sum_{i=1}^n x_i^2 \right)$$

Let $\frac{\partial D}{\partial a_0} = 0$, $\frac{\partial D}{\partial a_1} = 0$, we have

$$\begin{cases} \sum_{i=1}^n (a_0 + a_1 x_i - y_i) = 0 \\ \sum_{i=1}^n x_i y_i - a_0 \sum_{i=1}^n x_i - a_1 \sum_{i=1}^n x_i^2 = 0 \end{cases}$$

This implies

$$\begin{cases} na_0 + \left(\sum_{i=1}^n x_i\right)a_1 = \sum_{i=1}^n y_i \\ \left(\sum_{i=1}^n x_i\right)a_0 + \left(\sum_{i=1}^n x_i^2\right)a_1 = \sum_{i=1}^n x_i y_i \end{cases}$$

By Cramer's rule,

$$a_1 = \frac{\begin{vmatrix} n & \sum y_i \\ \sum x_i & \sum x_i y_i \end{vmatrix}}{\begin{vmatrix} n & \sum x_i \\ \sum x_i & \sum x_i^2 \end{vmatrix}} \quad (1)$$

$$= \frac{n \sum x_i y_i - \sum x_i \cdot \sum y_i}{n \sum x_i^2 - \sum x_i \sum x_i}$$

$$a_0 = \frac{\sum y_i}{n} - \frac{a_1 (\sum x_i)}{n} \quad (2)$$

Example 1.

x	-3	-2	1	0	1	2	3
y	0	2	1	-3	-1	-5	-9

For linear least squares, $y = a_0 + a_1 x$,

$$\begin{cases} a_0 + a_1(3) = 0 \\ a_0 + a_1(-2) = 2 \\ a_0 + a_1(1) = 1 \\ a_0 + a_1(0) = -3 \\ a_0 + a_1(1) = -1 \\ a_0 + a_1(2) = -5 \\ a_0 + a_1(3) = -9 \end{cases}$$

Find a_0 and a_1

$$\begin{aligned} 3x + 5y &= 1 \\ 2x + 3y &= 2 \end{aligned}$$

Cramer's rule:

$$x = \frac{\begin{vmatrix} 1 & 5 \\ 2 & 3 \end{vmatrix}}{\begin{vmatrix} 3 & 5 \\ 2 & 3 \end{vmatrix}} = \frac{3 - 10}{9 - 10} = 7$$

$$y = \frac{\begin{vmatrix} 3 & 2 \\ 2 & 1 \end{vmatrix}}{\begin{vmatrix} 3 & 5 \\ 2 & 3 \end{vmatrix}} = \frac{6 - 2}{-1} = -4$$

In matrix form, we have

$$\underbrace{\begin{bmatrix} 1 & -3 \\ 1 & -2 \\ 1 & 1 \\ 1 & 0 \\ 1 & 1 \\ 1 & 2 \\ 1 & 3 \end{bmatrix}}_{A_{7 \times 2}} \underbrace{\begin{bmatrix} a_0 \\ a_1 \end{bmatrix}}_{\hat{x}_{2 \times 1}} = \underbrace{\begin{bmatrix} 0 \\ 2 \\ 1 \\ -3 \\ -1 \\ -5 \\ -9 \end{bmatrix}}_{b_{7 \times 1}}$$

$$A \hat{x} = b$$

$$\underbrace{(A^T A)}_{2 \times 2} \underbrace{\hat{x}}_{2 \times 1} = \underbrace{A^T b}_{2 \times 1}$$

$A^T A = 2 \times 2$ matrix

$$\hat{x} = (A^T A)^{-1} (A^T b)$$

In MATLAB,

$$n = \text{length}(x);$$

$$A = [\text{ones}(n, 1) \quad x];$$

$$b = y;$$

$$A = A' * A;$$

$$B = A' * b;$$

$$C = A \setminus B;$$

$$x_t = -3 : 0.02 : 3$$

$$y_t = C(1) + C(2) * x_t;$$

$$\text{plot}(x, y, 'x', x_t, y_t);$$

$$x = [-3 \ -2 \ -1 \ 0 \ 1 \ 2 \ 3]';$$

$$y = [0 \ 2 \ 1 \ -3 \ -1 \ -5 \ -9]';$$

Alternatively, using (1) and (2), we can also obtain a_0 and a_1 .

$$a_1 = \frac{(n * \text{sum}(X * y) - \text{sum}(X) * \text{sum}(y))}{(n * \text{sum}(X.^2) - (\text{sum}(X))^2)}$$

$$a_0 = \text{sum}(Y)/n - a_1 * \text{sum}(X)/n$$

Example 2

Let $y = a_0 + a_1 x + a_2 x^2$ (quadratic model)

Using the same data $\{(x_i, y_i)\}_{i=1}^n$ shown above,

$n = \text{length}(x);$

$A = [\text{ones}(n, 1) \quad x \quad x.^2];$

$b = y;$

$A = A' * A;$

$B = A' * b;$

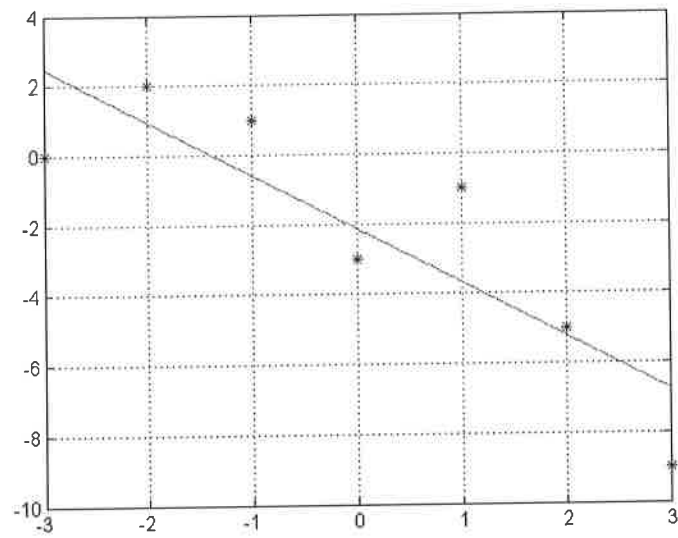
$c = A \setminus B; \quad \% \quad c = [a_0 \quad a_1] \quad \text{or} \quad c(1) = a_0, \quad c(2) = a_1.$

$xt = -3 : 0.2 : 3;$

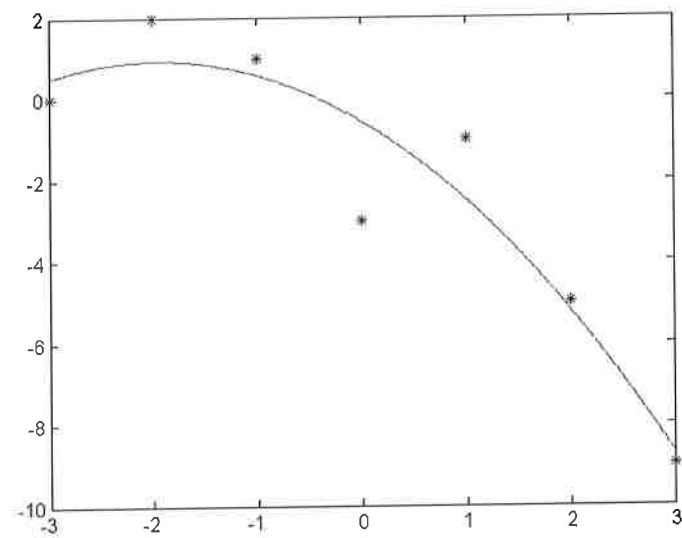
$yt = c(1) + c(2) * xt + c(3) * xt.^2;$

$\text{plot}(x, y, 'x', xt, yt);$

Linear least squares



Quadratic least squares



Example 3

$$y = a_0 + a_1 x + a_2 x^2 + a_3 x^3$$

```
load data1
```

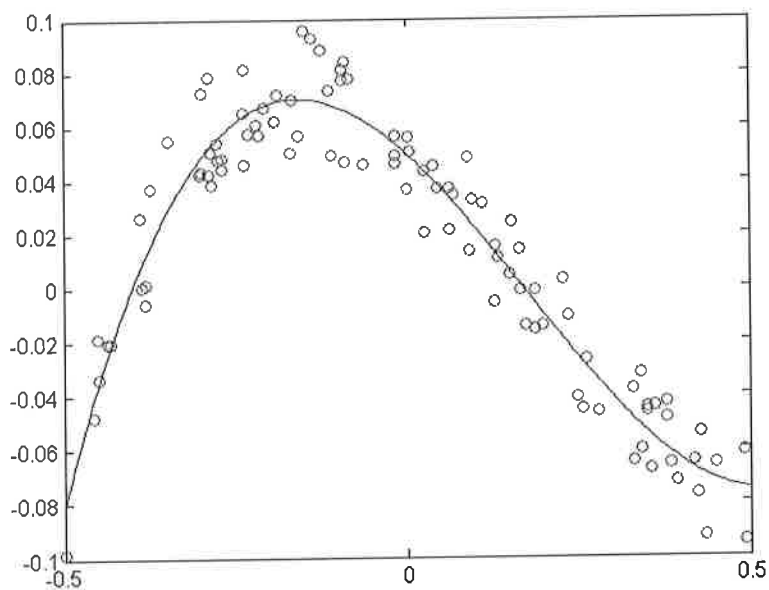
```
A = [t.^3 t.^2 t.^1 t.^0];
```

```
x=A\y; %% is theoretically equivalent to x=(A'*A)\(A'*y)
```

```
xt=linspace(-.5,.5,200);
```

```
yt=x(1)*xt.^3+x(2)*xt.^2+x(3)*xt+x(4);
```

```
plot(t,y,'or',xt,yt,'b');
```



Example 4.

7

```
load Carsmall
```

```
x = Weight ; y = Horsepower ; z = MPG ;
```

```
plot3(x, y, z, 'r.');
```

```
hold on ;
```

```
c = ones(length(x), 1);
```

```
b = regress(z, [x y c]); % linear regression  $z = b(1)*x + b(2)*y + b(3)$ 
```

```
[X, Y] = meshgrid(linspace(1500, 5000, 10), linspace(40, 240, 10))
```

```
C = ones(10);
```

```
mesh(X, Y, b(1)*X + b(2)*Y + b(3)*C);
```

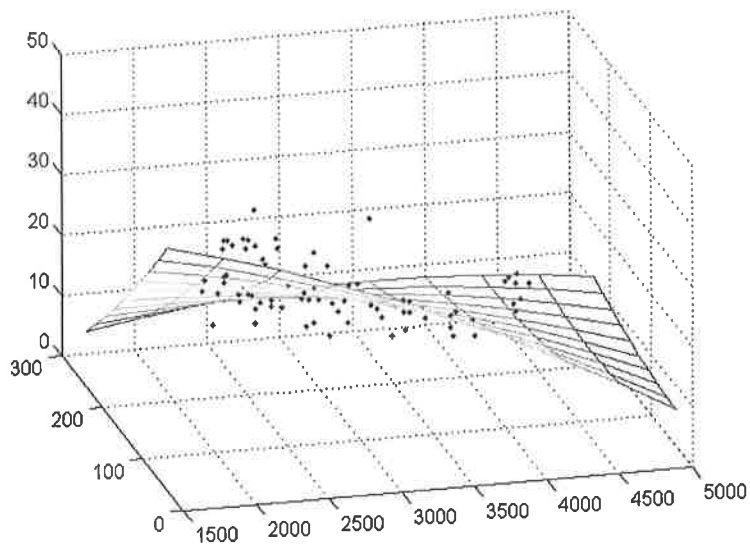
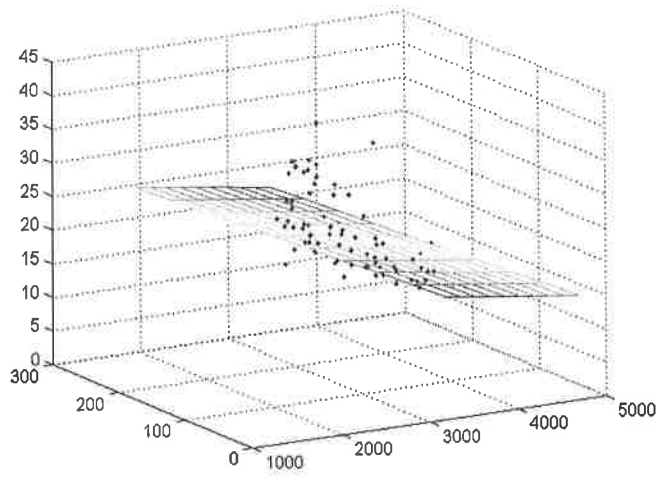
```
b = regress(z, [x.^2, y.^2, x.*y, x, y, c]);
```

figure

```
plot(x, y, z, 'r.');
```

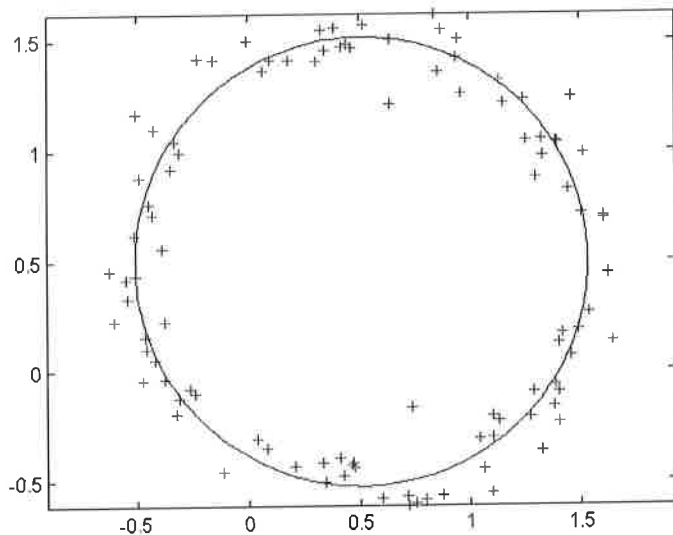
```
hold on
```

```
mesh(X, Y, b(1)*X.^2 + b(2)*Y.^2 + b(3)*X.*Y + b(4)*X +  
b(5)*Y + b(6)*C);
```



Example

```
load data2.mat
n=length(t);
A=[ones(n,1),zeros(n,1),cos(2*pi*t/T);
  zeros(n,1),ones(n,1),sin(2*pi*t/T)];
z=[x;y];
X=A\z;
fprintf('M(t)=%f+%fcos(\theta)\n',X(1),X(3))
fprintf(' %f+%fsin(\theta)\n',X(2),X(3))
theta=linspace(0,2*pi,200);
xt=X(1)+X(3)*cos(theta);
yt=X(2)+X(3)*sin(theta);
plot(x,y,'+r',xt,yt);
axis equal
```



Consider $\{(x_i, y_i)\}_{i=1}^n$

$$x(t) = a + r \cos\left(2\pi \frac{t}{T}\right)$$

$$y(t) = b + r \sin\left(2\pi \frac{t}{T}\right)$$

$t \geq 0$

Minimize the error

$$E(a, b, r) = \sum_{i=1}^n \left\| \begin{pmatrix} x(t) \\ y(t) \end{pmatrix} - \begin{pmatrix} x_i \\ y_i \end{pmatrix} \right\|^2$$

Find a, b, r .