

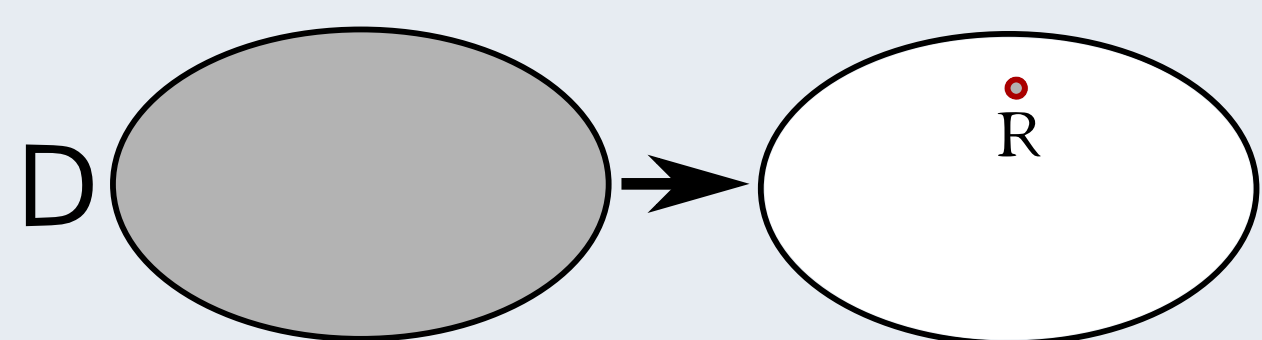
Local-Access Generators

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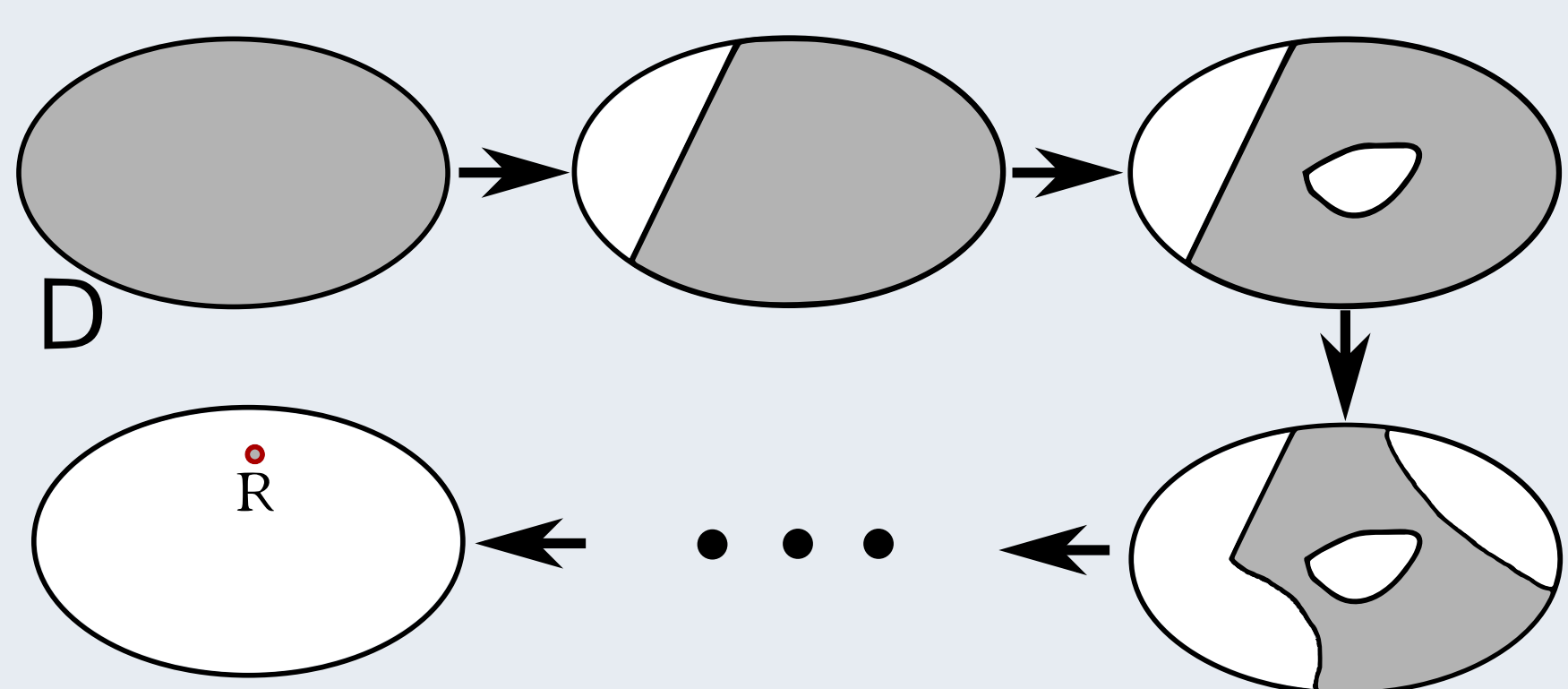
Partial Sampling from a Distribution

Full Sampling $R \sim D$ in $\mathcal{O}(T)$ time



N steps of *Partial Sampling*

Each partial step should take $\tilde{\mathcal{O}}(T/N)$ time.



Problem Statement

A local-access generator of a random object $R \sim D$, provides indirect access to R' with a *query oracle* s.t.

- All query responses are **consistent** with each other
- The **distribution** of R' is ϵ -close to D in L_1 distance

Trivial Example - Sampling $G(n, p)$

Model: Undirected graph on N vertices (numbered $\langle 1, 2, 3, \dots, N \rangle$), where each edge exists with prob. p .

Query Model: Given vertices u, v , is $(u, v) \in E$?

- Just a collection of $\frac{n(n-1)}{2}$ Bernoulli RVs with bias p .

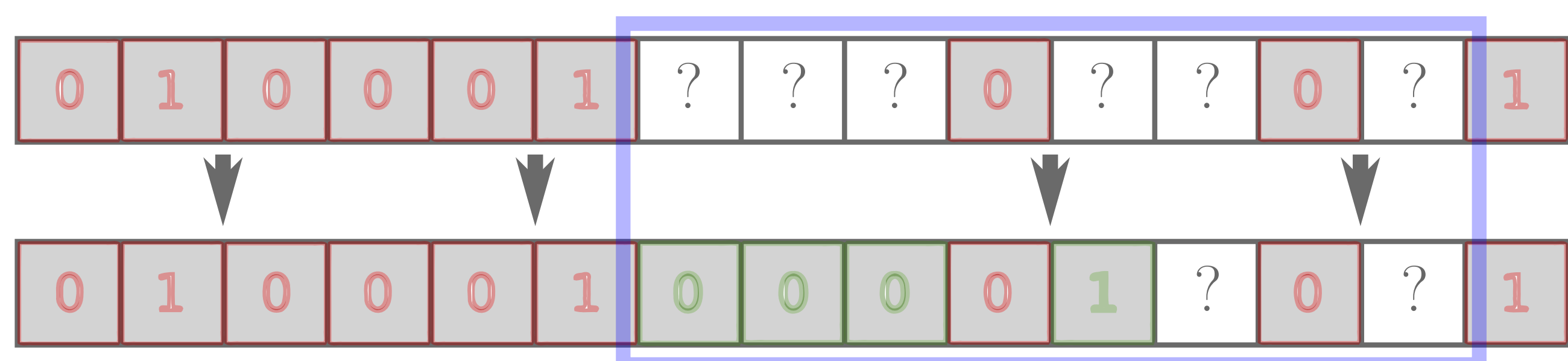
Find Next-Neighbor (*skip-sampling*)

Adjacency List query: Return neighbors of v in order.

$$\mathbb{P}[k \text{ non-neighbors before next-neighbor}] = p(1-p)^k$$

- Can sample from this distribution in $\tilde{\mathcal{O}}(1)$ time [cite].
- Avoid sampling each 0 separately.

Issue: Adjacency matrix is symmetric. So, each zero must also appear in the corresponding column of v .



If the sampled neighbor is a 0, discard and resample.

Cannot afford too many re-samplings.

Bucketing Approach & *Random-Neighbor* Queries

- Divide each row of the adjacency matrix into contiguous buckets
- Expected number of neighbors in a bucket is $\Theta(\log n)$
- Each vertex v is associated with buckets $\langle B_1^v, B_2^v, B_3^v, \dots \rangle$
- An **unfilled** bucket may contain some indirectly exposed neighbors
- A **filled** bucket will contain every possible sampled neighbor

Filling the i^{th} bucket B_i^v of vertex v

- Use skip-sampling to produce a **potential** *next-neighbor* u of v in B_i^v
- Check if (u, v) was set to 0, by looking at bucket \mathcal{B} of u containing v
- If so, re-sample. Otherwise, mark u as a neighbor of v , and update \mathcal{B}
- W.h.p, only $\mathcal{O}(\log^2 n)$ **potential** neighbors are generated in B_i^v

Random-Neighbor(v)

- Choose a random bucket \mathcal{B} of v . If the \mathcal{B} is **unfilled**, fill it.
- If k neighbors found in \mathcal{B} , start over (reject) with probability $1 - k/M$.
- If accepted, return a uniformly random neighbor found in \mathcal{B} .

For $M = \mathcal{O}(\log^2 N)$, the max number of neighbors in any bucket is $< M$. So, the number of rejection sampling rounds is $\mathcal{O}(\log^2 N)$ in expectation.

Stochastic Block Model

- Each vertex is assigned to some community $C_i \subseteq V$ for $i \in [r]$
- Communities $\{C_i\}_{i \in [r]}$ partition V : if $u \in C_i, v \in C_j$, then $\mathbb{P}_{(u,v) \in E} = p_{ij}$

Given sizes of each community C_i and a range of length ℓ

- Count number of occurrences of each community in any contiguous range
- Sample from *Multivariate Hypergeometric Distribution*

$$\Pr[\mathbf{S}_\ell^C = \langle s_1, \dots, s_r \rangle] = \frac{\binom{C_1}{s_1} \cdot \binom{C_2}{s_2} \dots \binom{C_r}{s_r}}{\binom{B}{\ell}} \quad \text{where } \ell = \sum_{i=1}^r s_i \text{ and } B = \sum_{i=1}^r C_i$$

Multivariate Hypergeometric Distribution

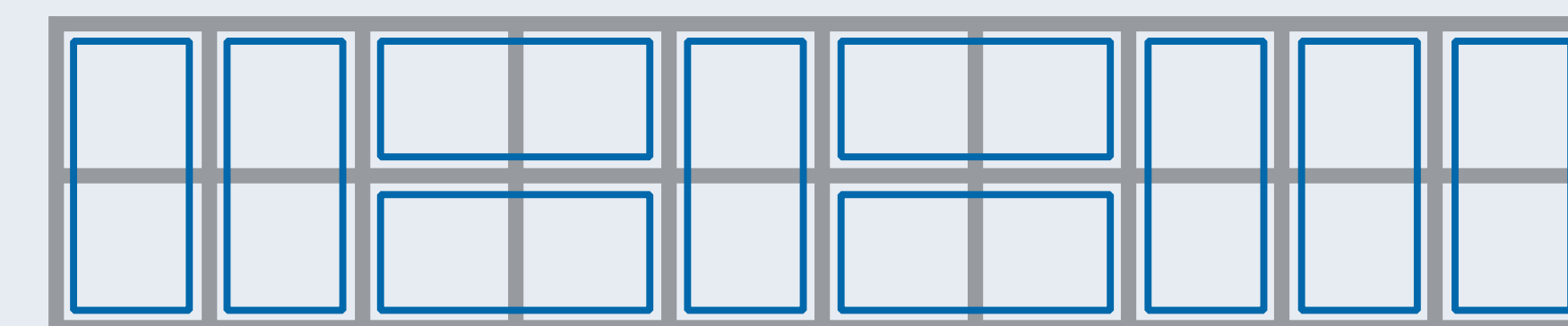
[cite] solves the special case of $r = 2$ and $B = 2\ell$.

- **Extending to $B \neq 2\ell$:** Divide ℓ into $\mathcal{O}(\log n)$ dyadic segments.
- **Extending to $r > 2$:** Make a tree with r leaves (one for each C_i). Every branch down the tree is equivalent to a $r = 2$ splitting.

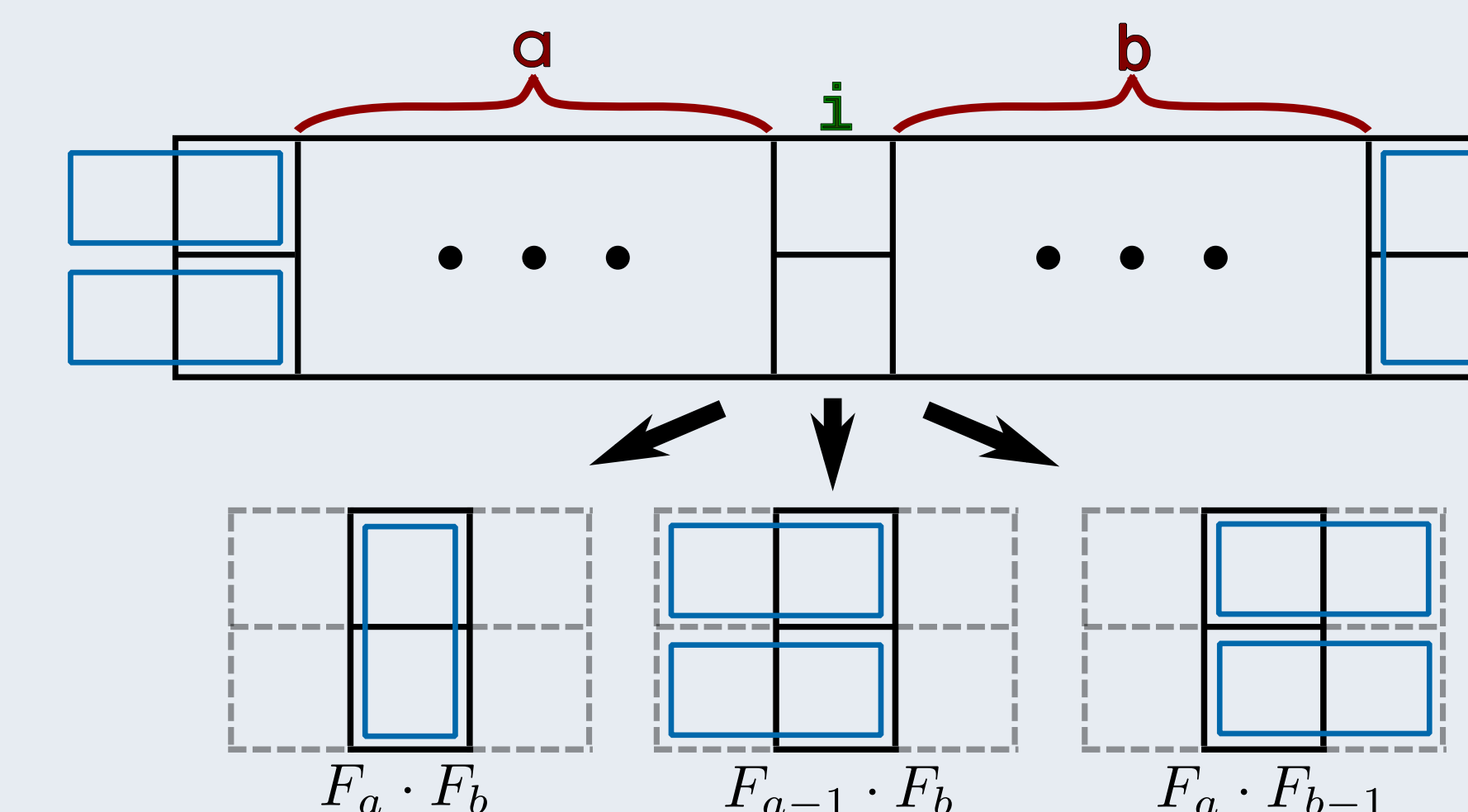
Work in Progress

Domino Tiling

A $2 \times n$ grid tiled with dominoes: F_n tilings possible.



Query: Domino at position i : *vertical* OR *horizontal*?



Sufficient to approximate F_c/F_{c-1} : Use ϕ if $c = \Omega(\log(n))$

Open: (Dimer model) $k \times n$ grid for $k = \Omega(1)$.

Dimer Model: Domino Tiling

Glossary

Some Necessary and Useful Vocabulary