

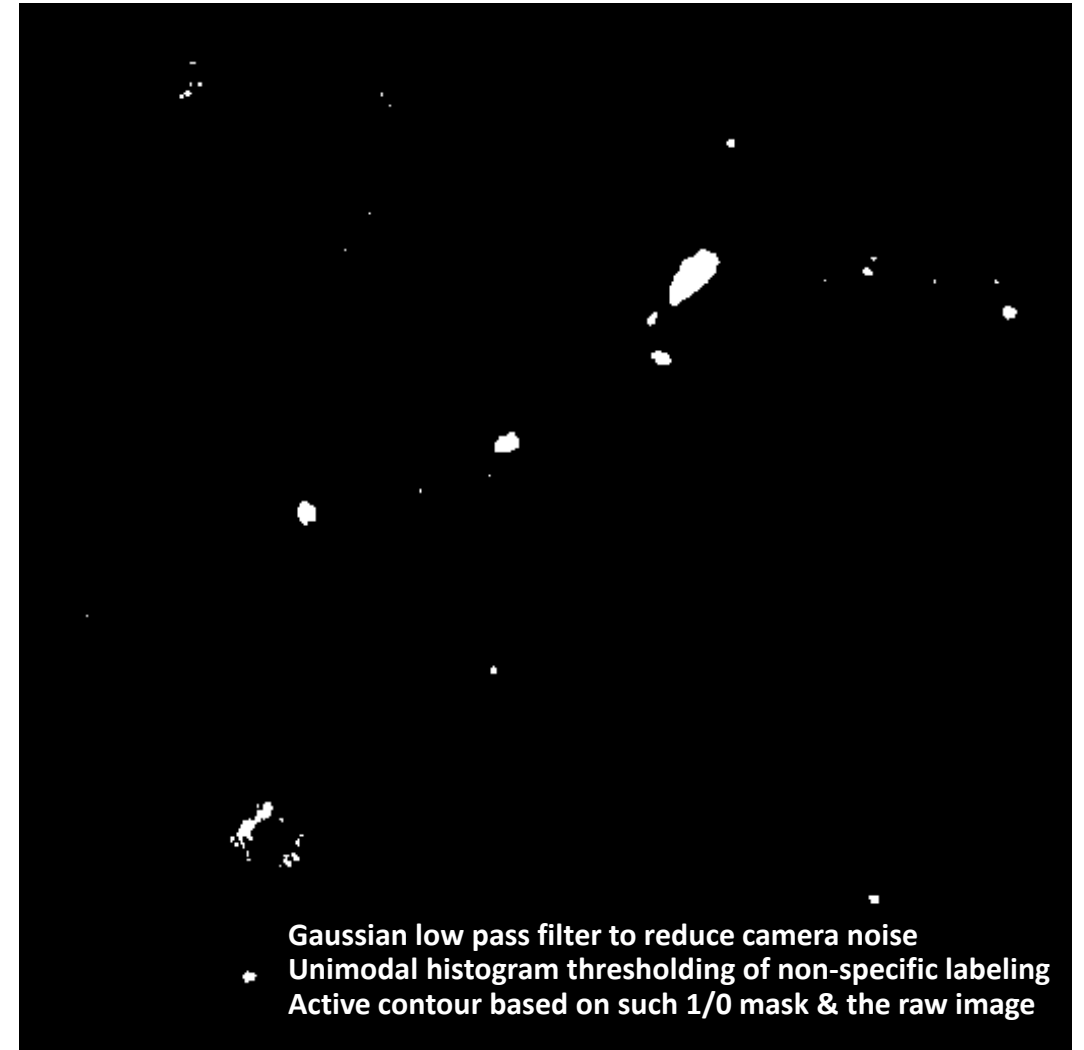
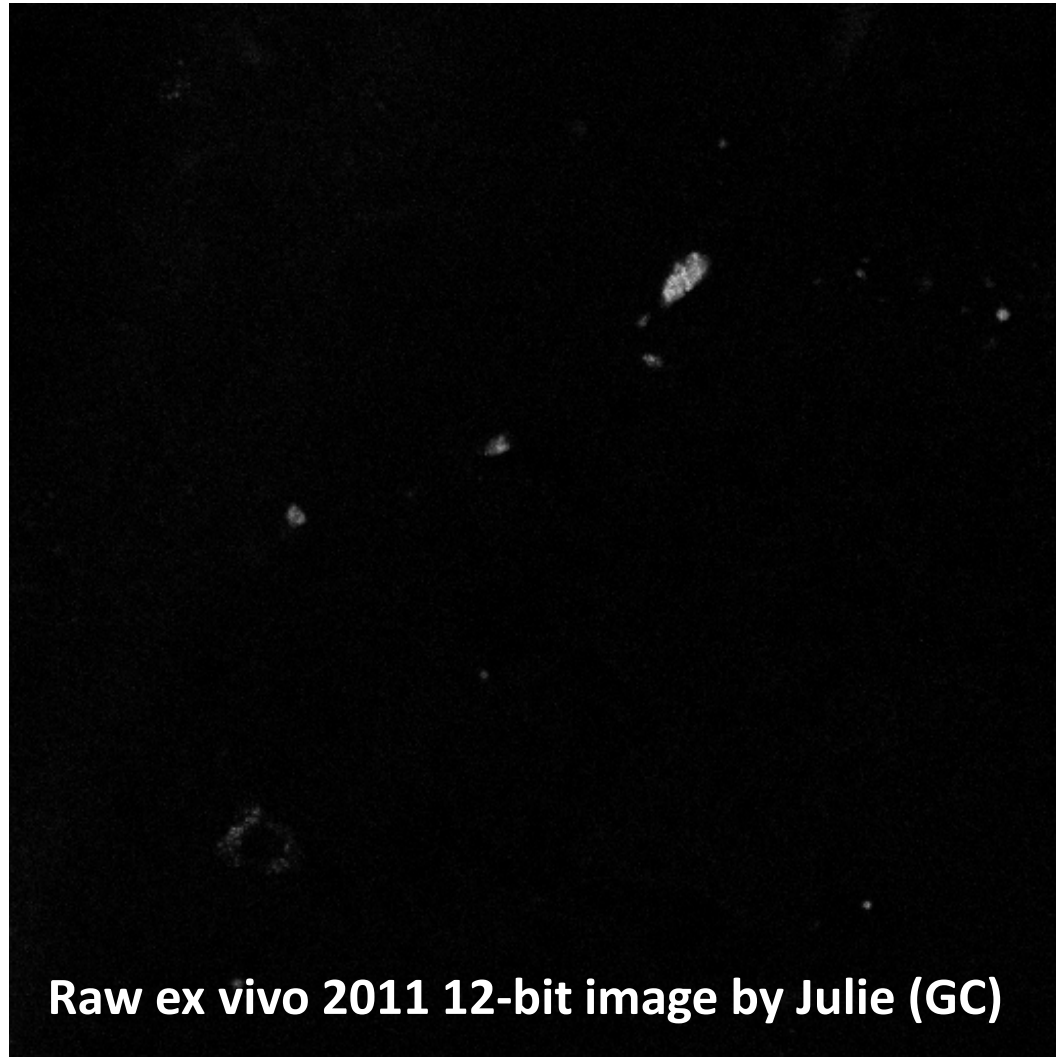
Analysis of AMDX2011 aggregates in retinal images

Alex Matov
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Image classification & disease detection

- Computer vision metrics (brightness, morphology, localization within the retina, etc.)
- Deep learning with neural networks (classification into different disease types/stages)
- Database image storage (rapid delivery of a searchable pool of informative analytics)

Preliminary analysis



Preliminary analysis

45x1 struct array w fields:

Area
Centroid
BoundingBox
SubarrayIdx
MajorAxisLength
MinorAxisLength
Eccentricity
Orientation
ConvexHull
ConvexImage
ConvexArea
Image
FilledImage
FilledArea
EulerNumber
Extrema
EquivDiameter
Solidity
Extent
PixelIdxList
PixelList
Perimeter
PerimeterOld

Raw ex vivo 2011 image by Julie

Area: 7533 (example)

Centroid: [1.4850e+03 601.4648]

BoundingBox: [1.4325e+03 543.5000 112 124]

SubarrayIdx: {[1x124 double] [1x112 double]}

MajorAxisLength: 146.6684

MinorAxisLength: 66.7536

Eccentricity: 0.8904

Orientation: 48.0603

ConvexHull: [49x2 double]

ConvexImage: [124x112 logical]

ConvexArea: 7978

Image: [124x112 logical]

FilledImage: [124x112 logical]

FilledArea: 7533

EulerNumber: 1

Extrema: [8x2 double]

EquivDiameter: 97.9353

Solidity: 0.9442

Extent: 0.5424

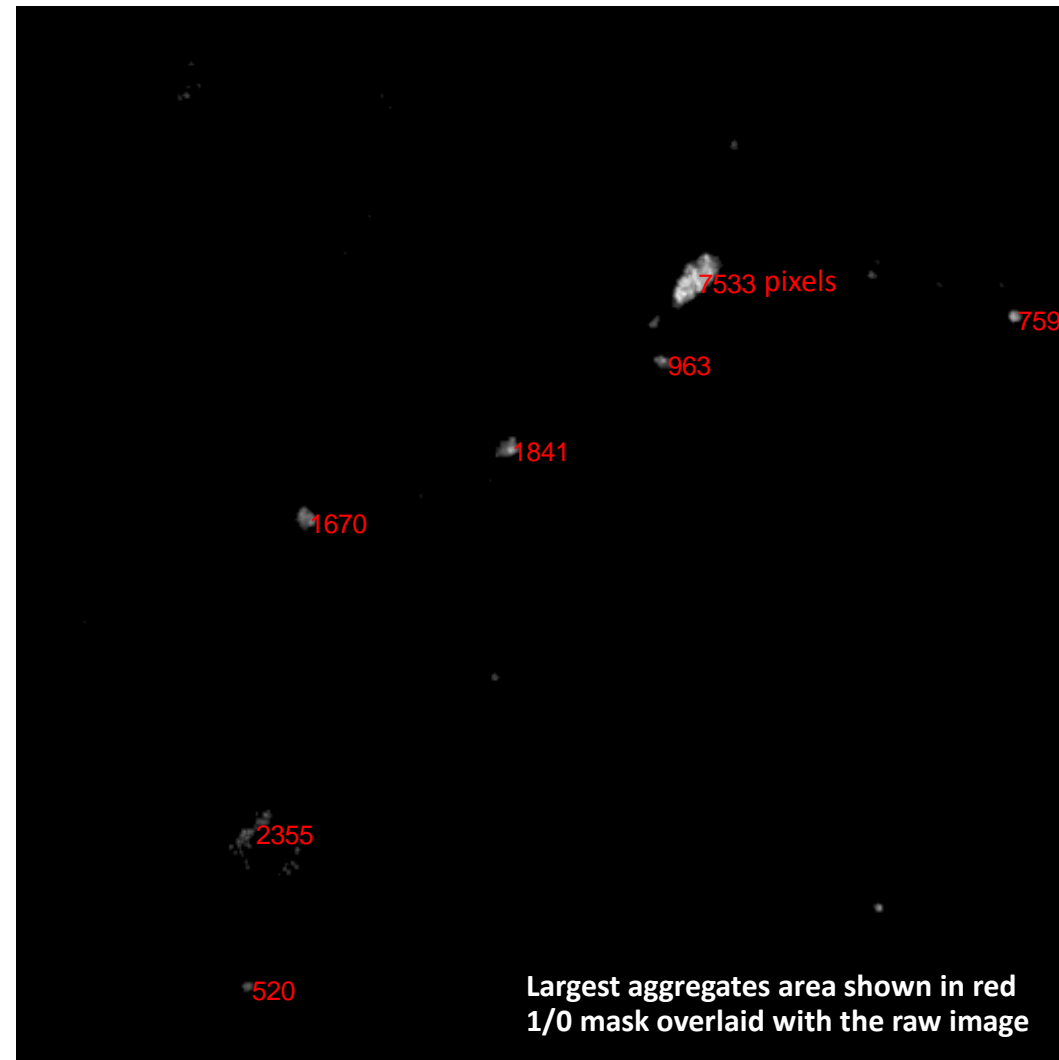
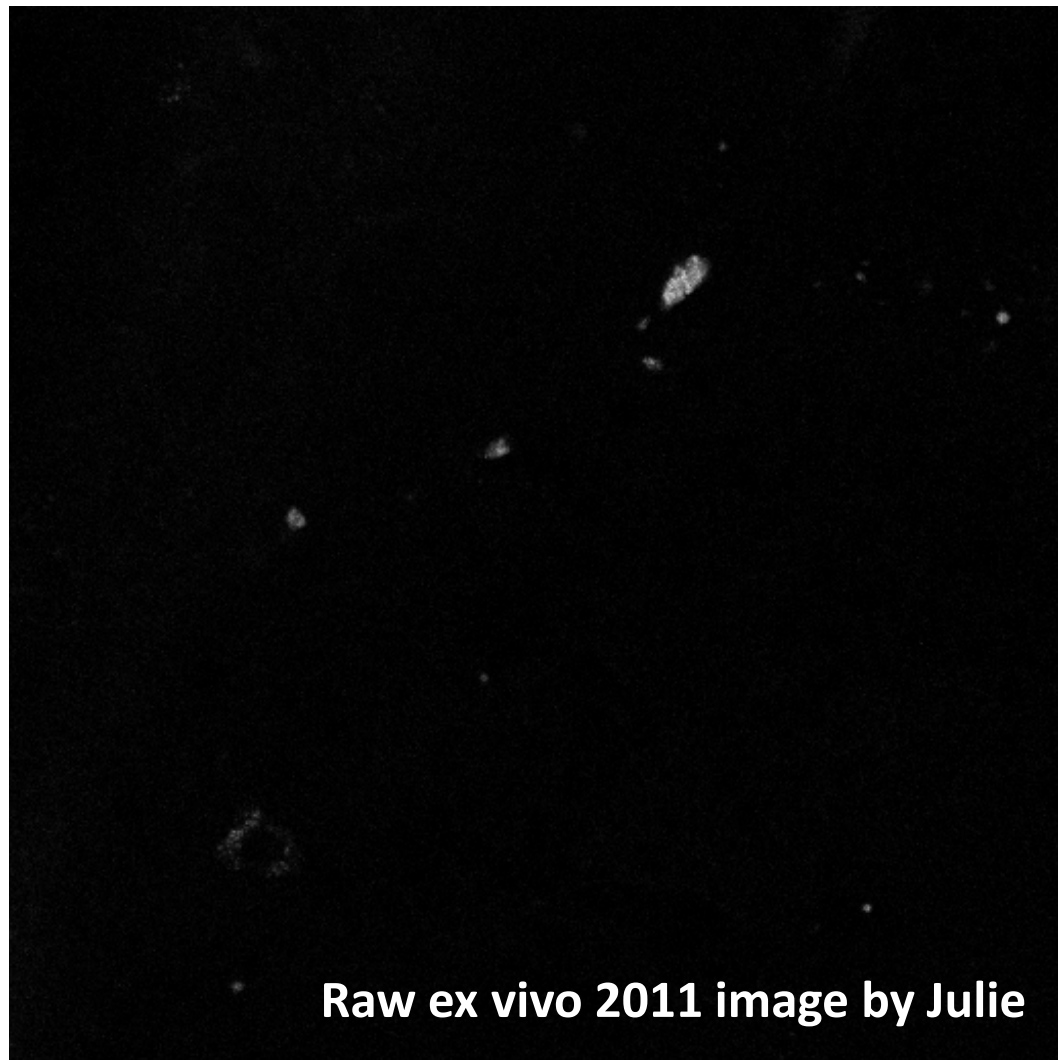
PixelIdxList: [7533x1 double]

PixelList: [7533x2 double]

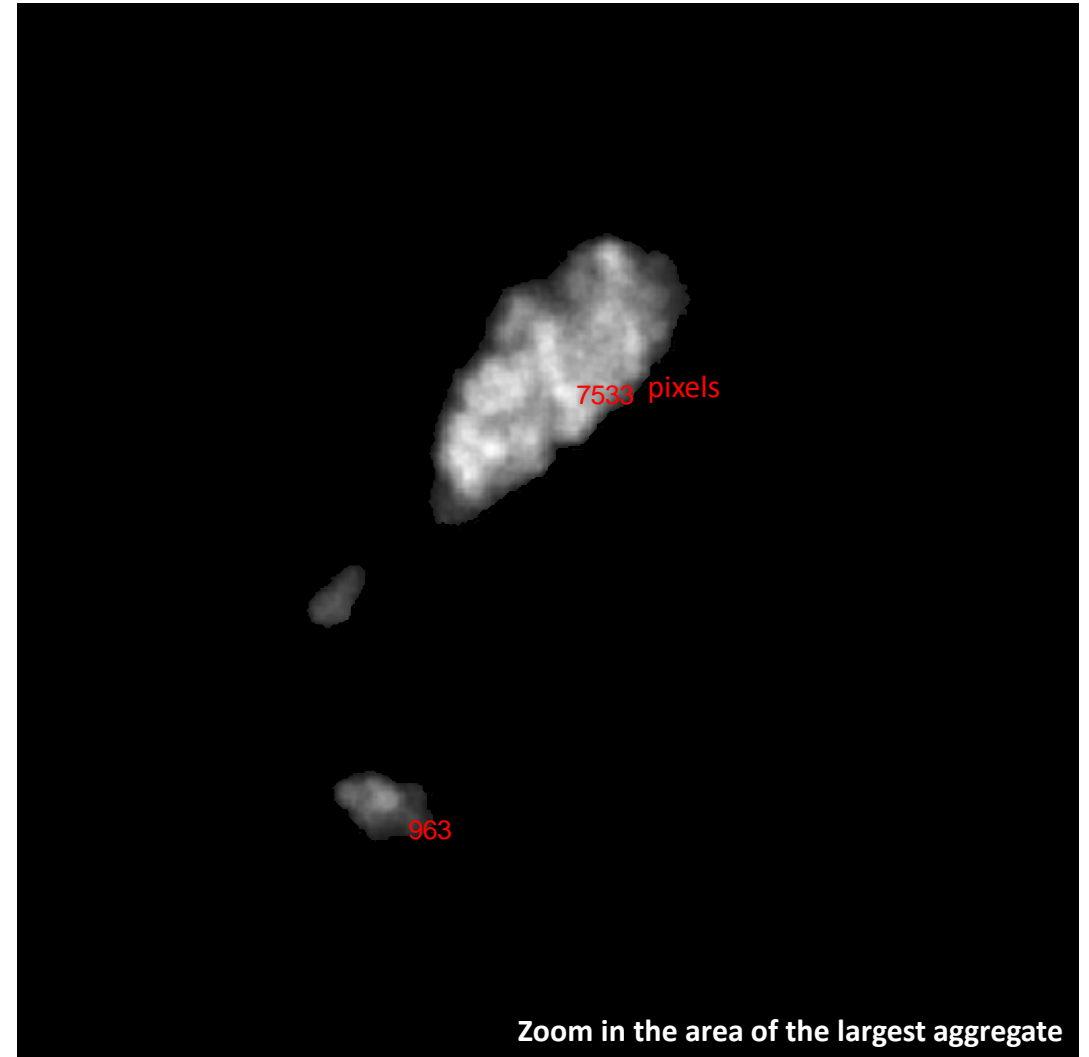
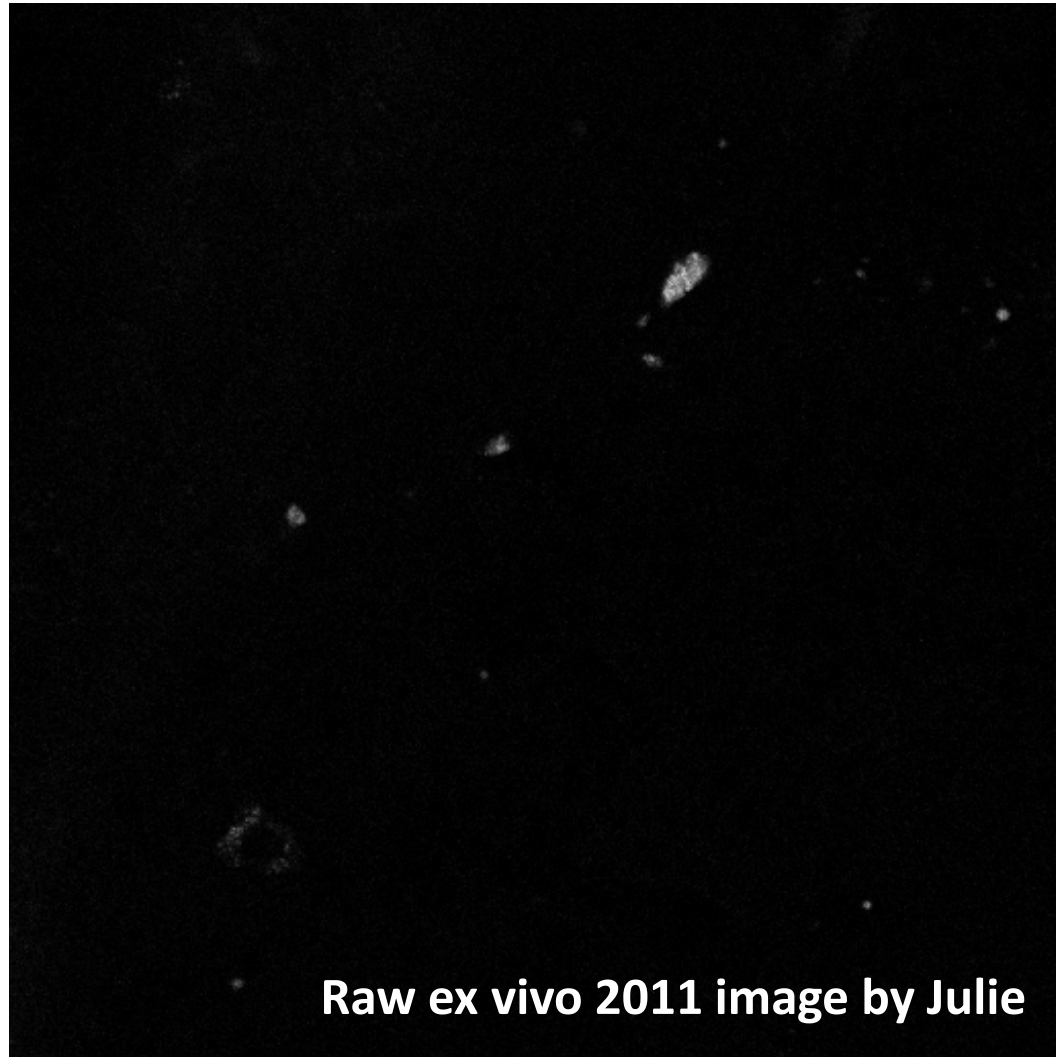
Perimeter: 377.2390

PerimeterOld: 398.8600

Preliminary analysis



Preliminary analysis



Examples of image metrics

SIZE AND DISTRIBUTION OF AGGREGATES

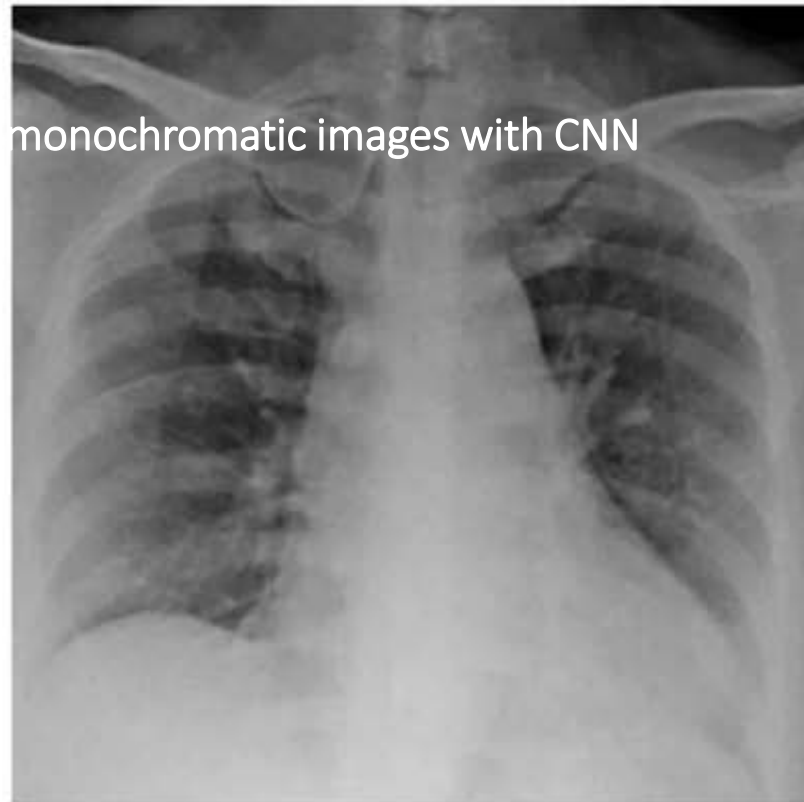
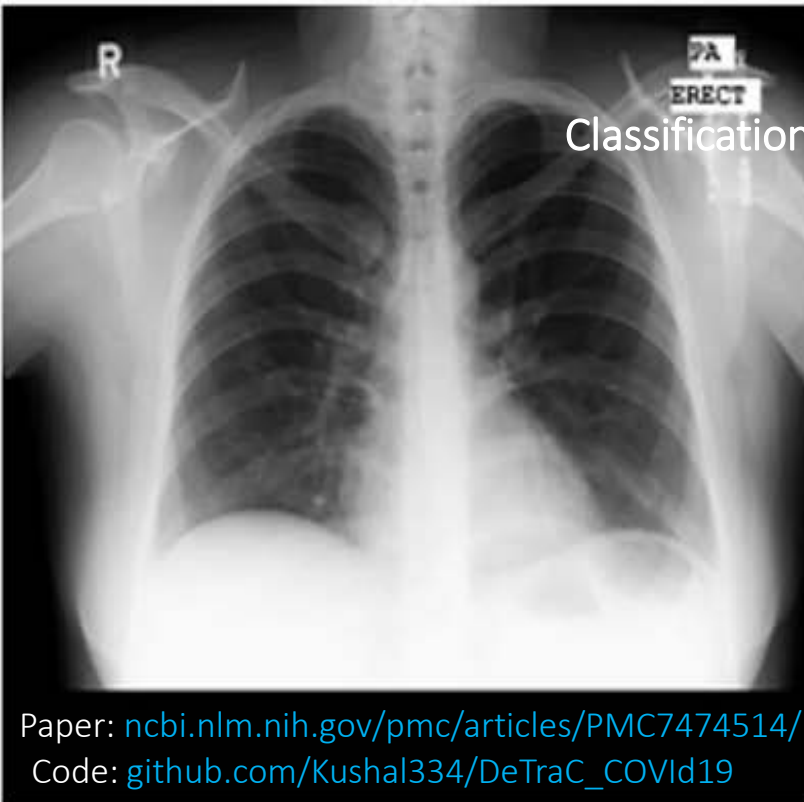
- 1) object: number – number of fluorescent aggregate in image
- 2) object: EulerNumber - number of objects in the image minus the total number of holes in those objects – distinguishes reticular or mesh-like patterns vs more uniformly distributed aggregates
- 3) object_size:average - The average number of above-threshold pixels per object – captures information about the size of the aggregates
- 4) object_size:variance - The variance of the number of above-threshold pixels per object – quantifies the homogeneity of fluorescent objects in cells
- 5) object_size:ratio - The ratio of the size of the largest aggregate to the smallest within the retina – assessing the distribution of fluorescent aggregate sizes
- 6) object_distance: average – average aggregate distance to the optical nerve – provides information about how individual aggregate are distributed throughout the retina
- 7) object_distance: variance – variance of object distance to the optical nerve – captures information about the distribution of objects around a central point
- 8) Object_distance: ratio – ratio of largest to smallest distance to the optical nerve

AGGREGATES EDGE FEATURES

- 9) edges:area_fraction - fraction of the non-zero pixels in an aggregate that are along an edge – distinguishes protein that localizes along the aggregate edges
- 10) edges:homogeneity - Measure of edge intensity homogeneity - captures homogeneity of edge gradients, or ‘are the edges primarily steep or more gradually sloping?’
- 11) edges:direction_maxmin_ratio - Measure of edge direction homogeneity 1 – captures homogeneity of edge direction, or are the edges primarily in one direction or are they more evenly distributed? images with patterns containing edges oriented predominantly along a particular direction result in edge gradient histograms
- 12) edges:direction_maxnextmax_ratio - Measure of edge direction homogeneity 2 – ratio of the largest to the next largest value in the histogram from above feature
- 13) edges:direction_difference - Measure of edge direction difference - this feature distinguish aggregate patterns in which there are parallel edges

SHAPE OF THE AGGREGATES

- 14) obj_skel_len - The average length of the morphological skeleton of the aggregates (or blood vessels in the eye)
- 15) obj_skel_hull_area_ratio - The ratio of aggregate skeleton length to the area of the convex hull of the skeleton, averaged over all aggregates
- 16) obj_skel_branch_per_len - The ratio of the number of branch points in skeleton to length of the vascular skeleton
- 17) convex_hull: fraction of overlap - fraction of convex hull occupied by protein fluorescence (above-threshold pixels)
- 18) convex_hull: shape_factor



Classification of monochromatic images with CNN

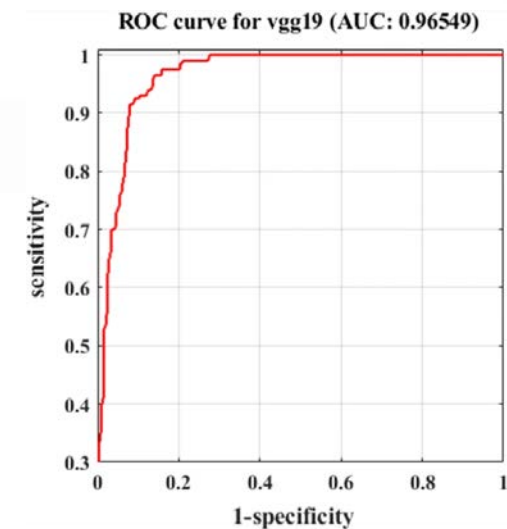
(a)

(b)

Examples of a) normal, b) COVID-19, and c) SARS chest X-ray images

ImageNet (15 million images)
pre-trained CNN networks:

- AlexNet
- VGG19 keras.io/api/applications/vgg/
- ResNet
- GoogleNet
- SqueezeNet



- 80 normal chest images (4,020 × 4,892 pixels)
- 105 COVID-19 images (4,248 × 3,480 pixels) 8-bit depth (max. intensity value 256)
- 11 SARS images (4,248 × 3,480 pixels)

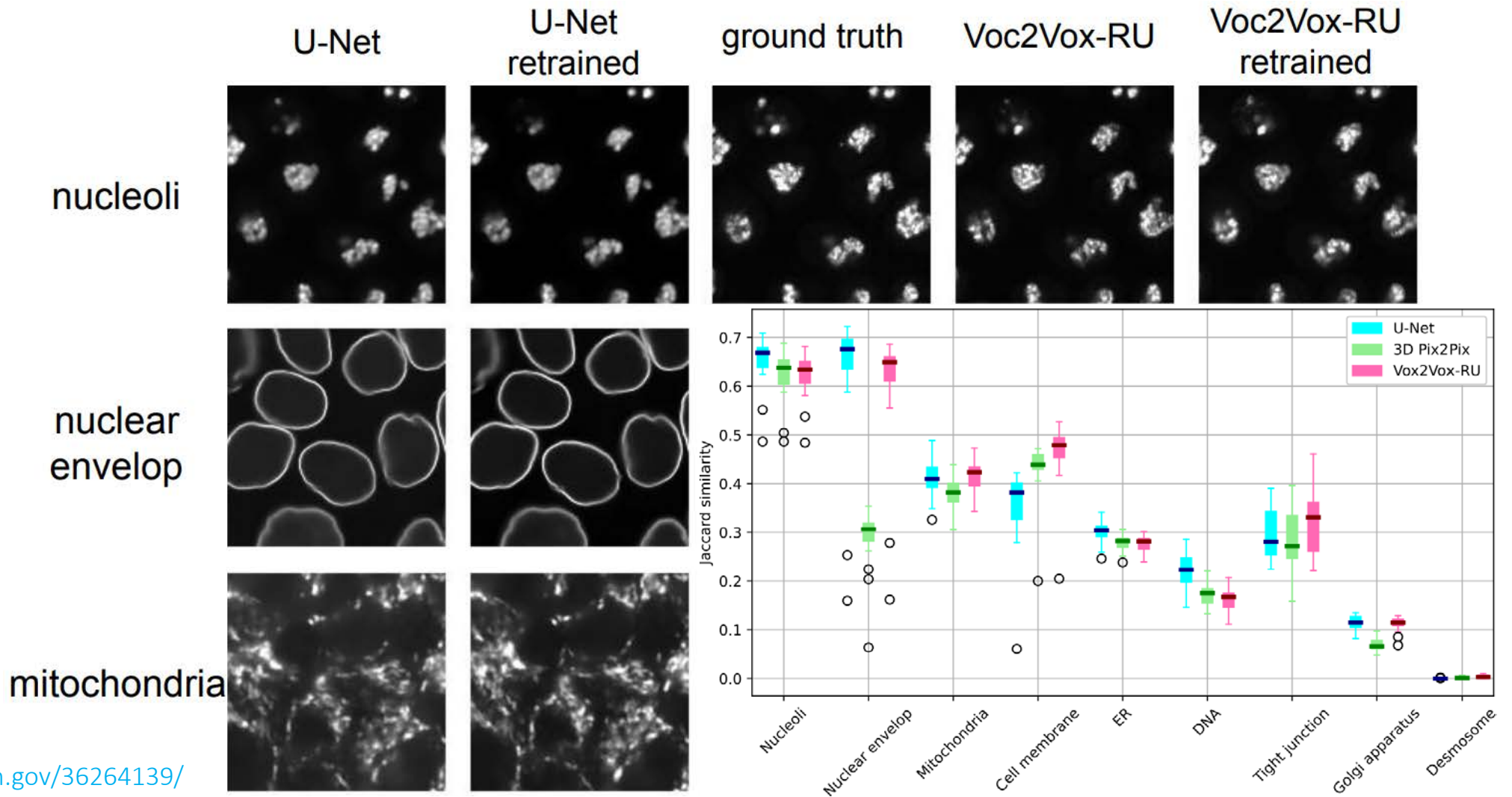
Transfer learning scenarios:

- “shallow tuning” adapts only the last classification layer & freezes the parameters of the remaining layers without training
- “deep tuning” retrain all parameters of the pre-trained network from end-to-end
- “fine-tuning” gradually trains more layers by tuning the learning parameters until a significant performance boost is achieved

Paper: ncbi.nlm.nih.gov/pmc/articles/PMC7474514/
Code: github.com/Kushal334/DeTraC_COVID19

Improving and evaluating deep learning models of cellular organization

similarity with
AMDX-2011P
aggregates



Paper: pubmed.ncbi.nlm.nih.gov/36264139/

Code: murphylab.cbd.cmu.edu/Software/2022_insilico/

Storage of image data & delivery of analytics

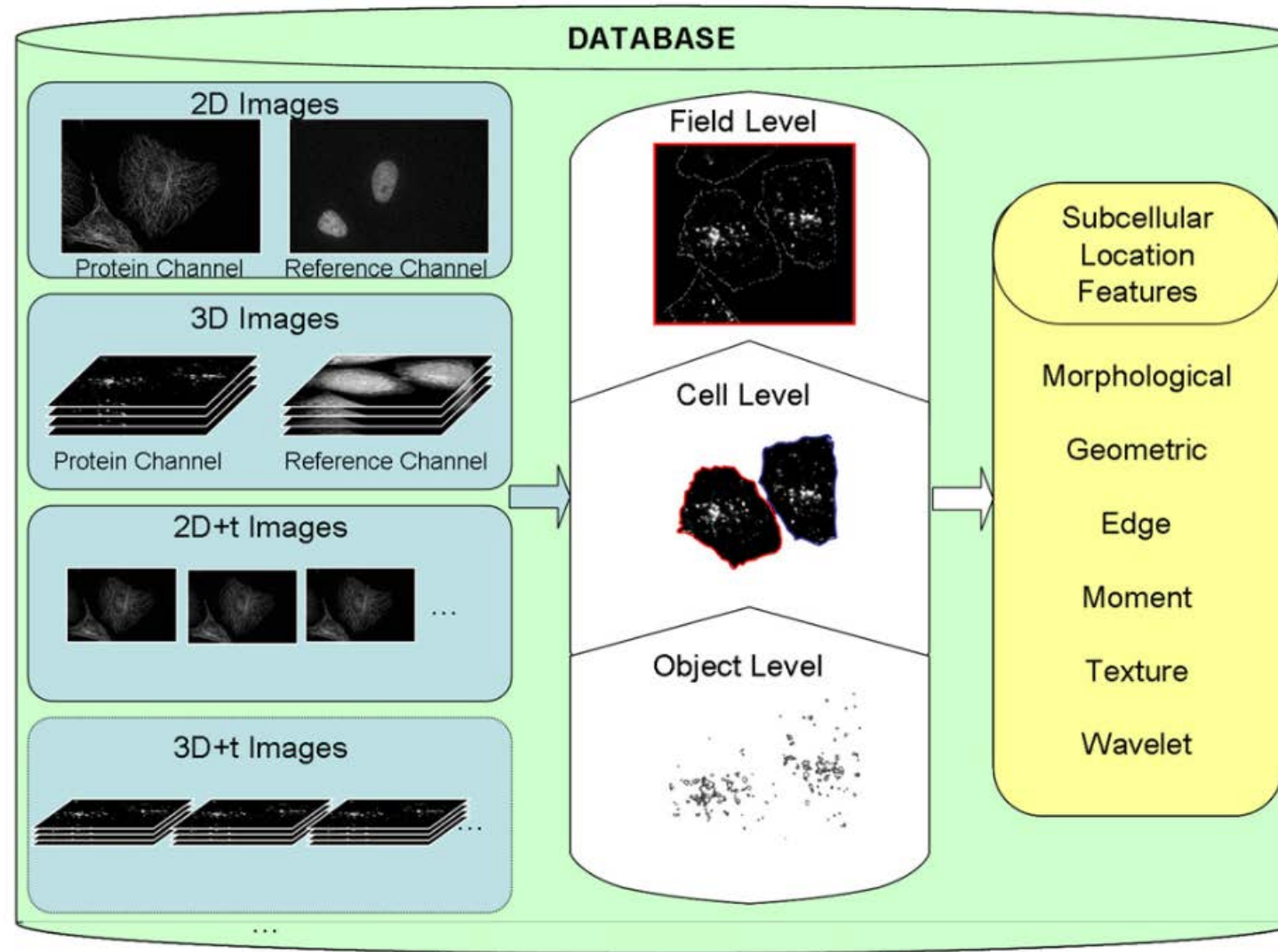


Figure 1. The Image Database Depicted Contains Images with Related Biological Protocol, Acquisition Parameters, and Subcellular Location Features