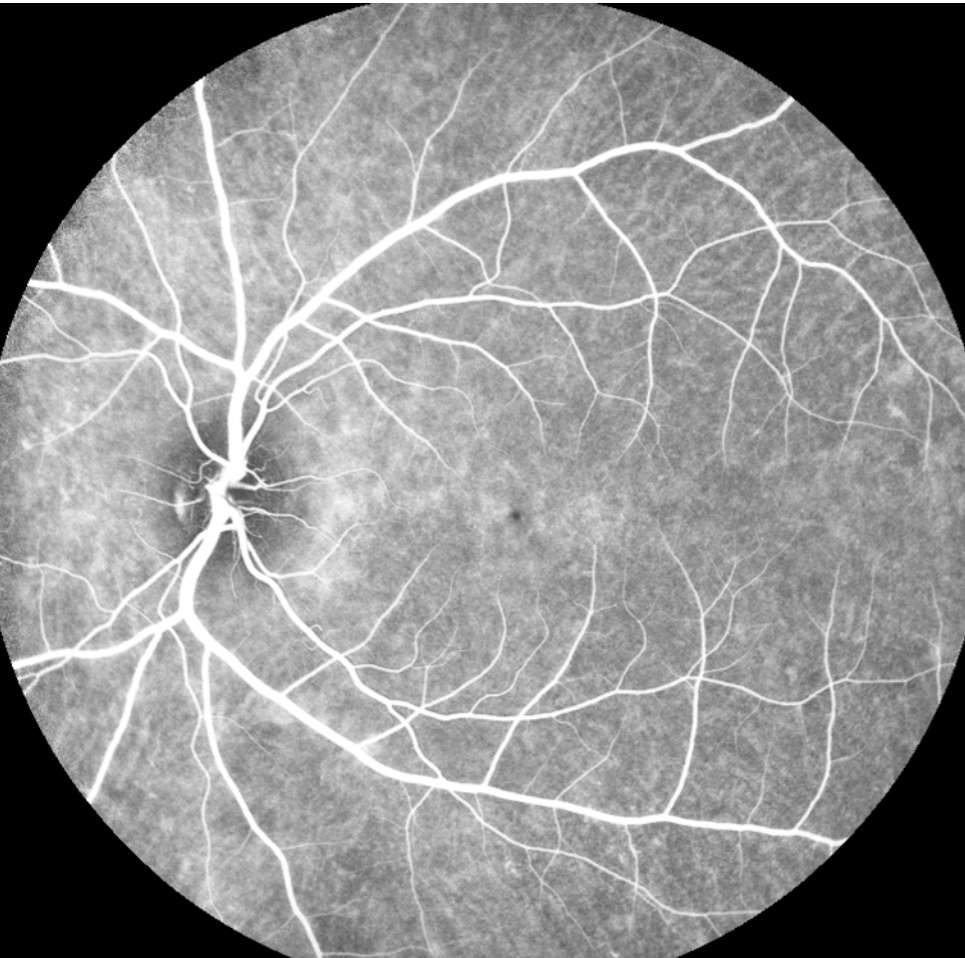
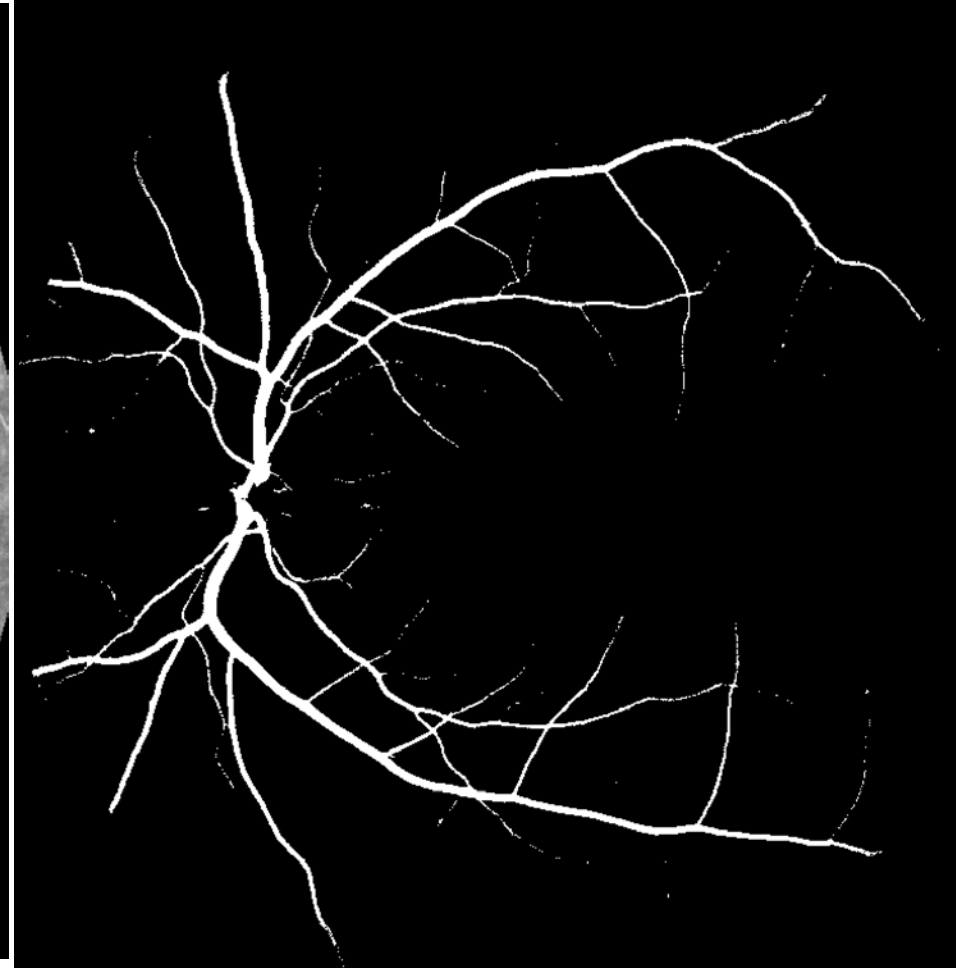


Cyno200188 V1/2minPost

Imaging with 8-bit camera, i.e., the pixel intensity range is 0-255 [AU]



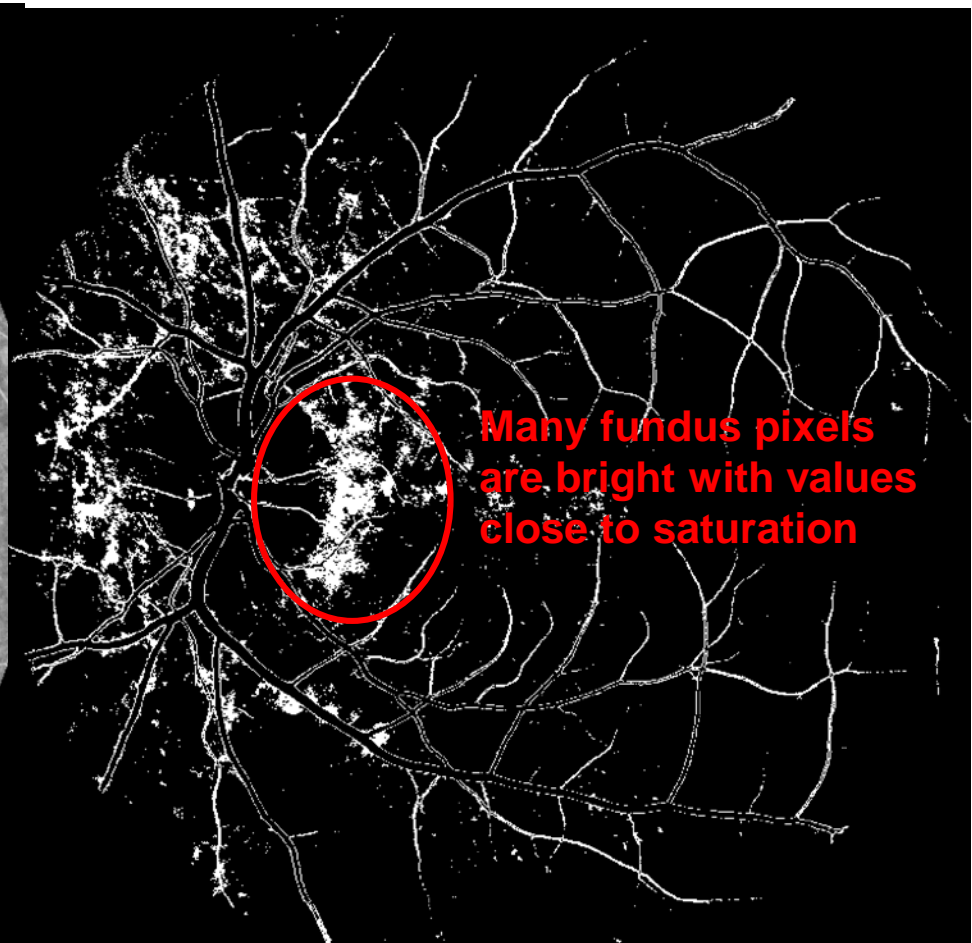
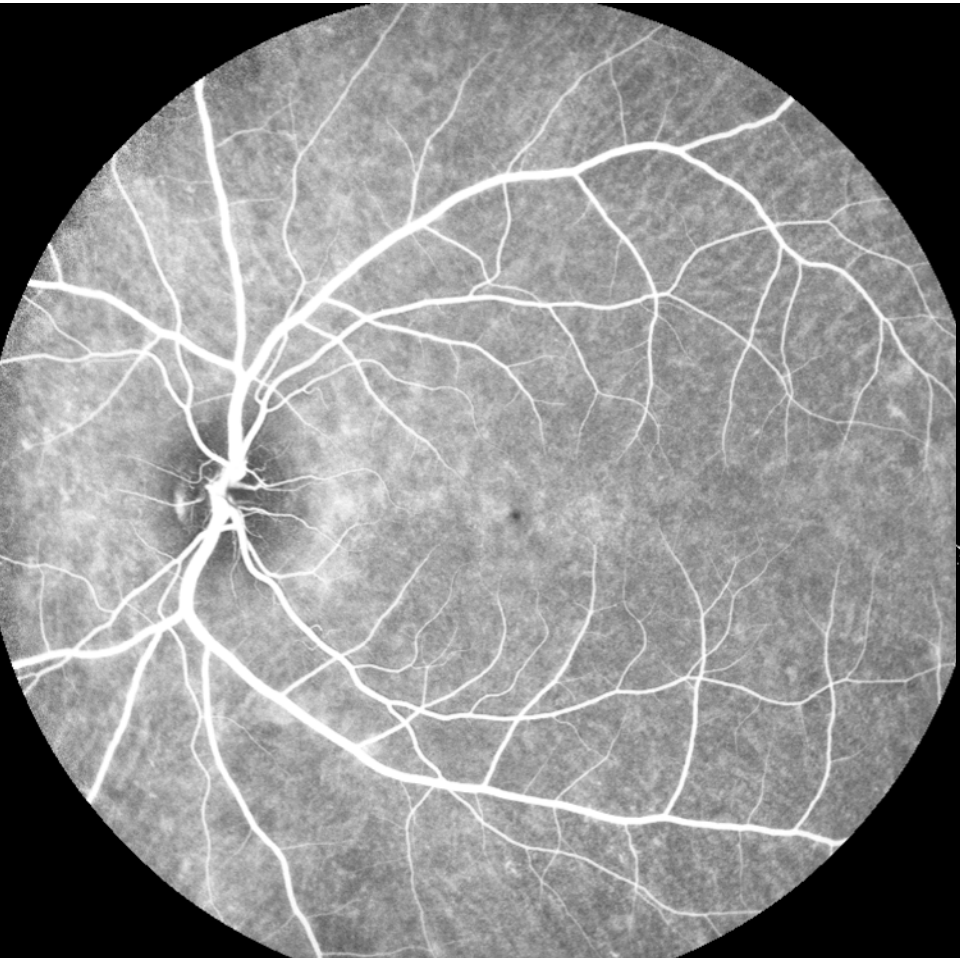
Pixels with intensity above 240 [AU]



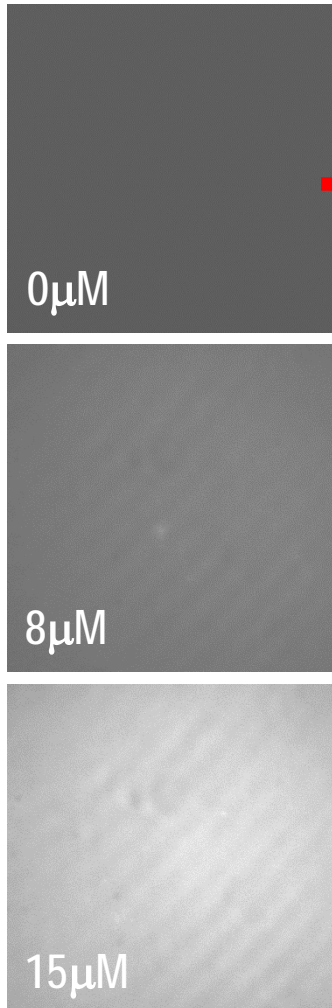
Cyno200188 V1/2minPost

Imaging with 8-bit camera, i.e., the pixel intensity range is 0-255 [AU]

Pixels with intensity in range 200-240 [AU]



Noise model based on a camera calibration



$$\sigma^2 = \sigma_{dark}^2 + \sigma_{shot}^2$$

$$\sigma_{shot} = \gamma \sqrt{I}$$

$$\beta = \gamma^2$$

→ σ_{dark}

$$\sigma_{Model}^2 = \sigma^2 - \sigma_{dark}^2 = \sigma_{shot}^2 = \beta(I - I_0)$$

$$\sigma^2 = \sigma_{dark}^2 + \beta \cdot (I - I_0)$$

