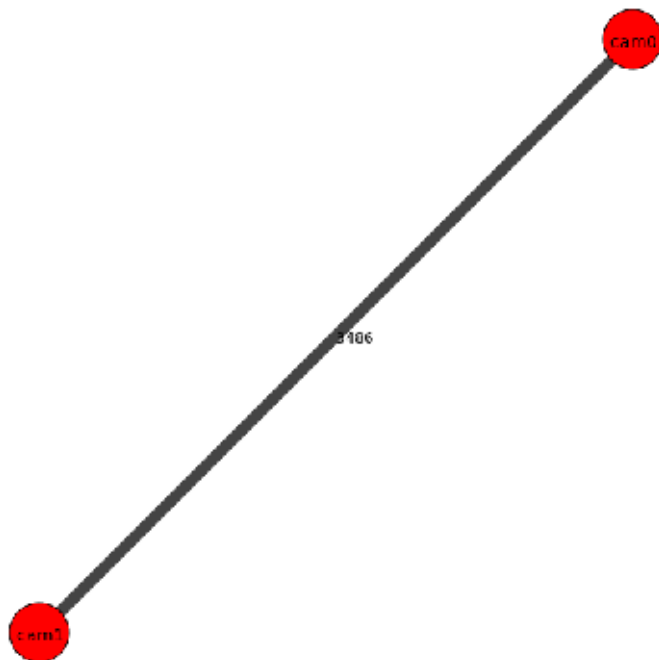
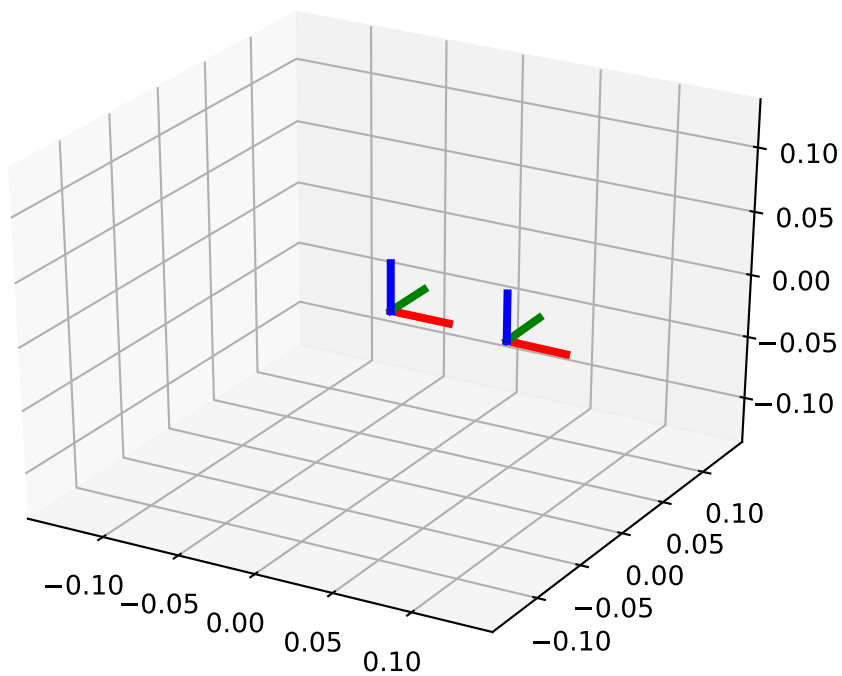


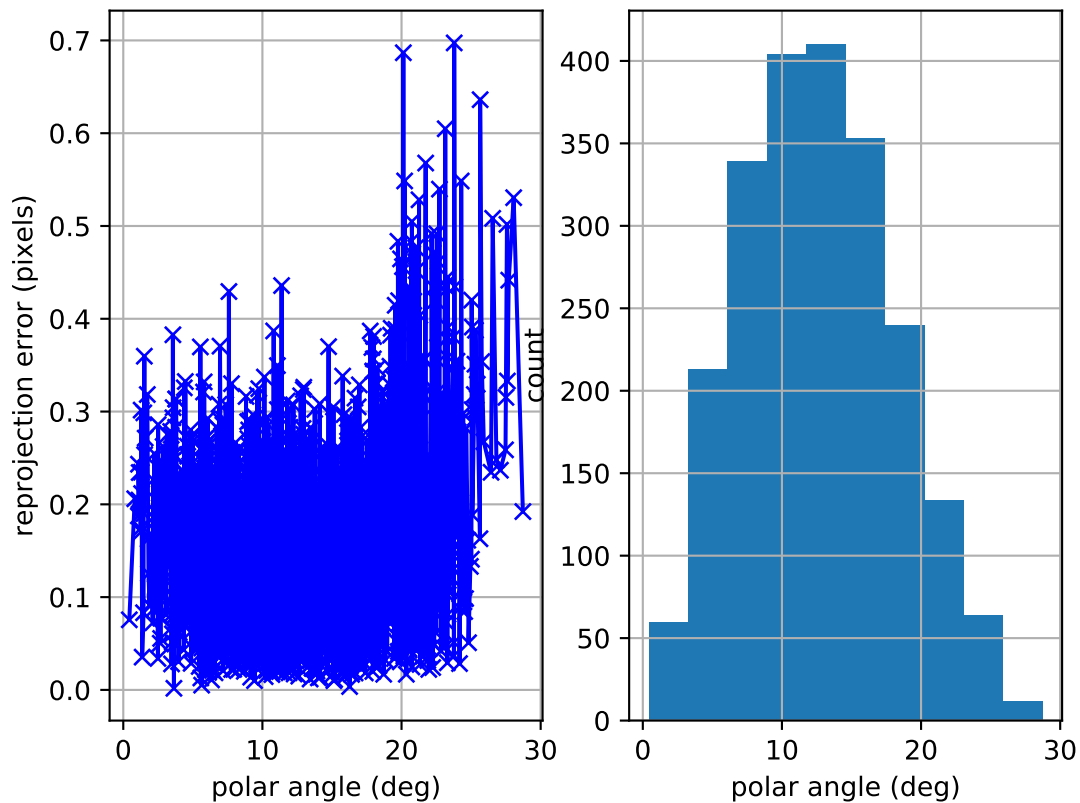
Inter-camera observations graph (edge weight=#mutual obs.)



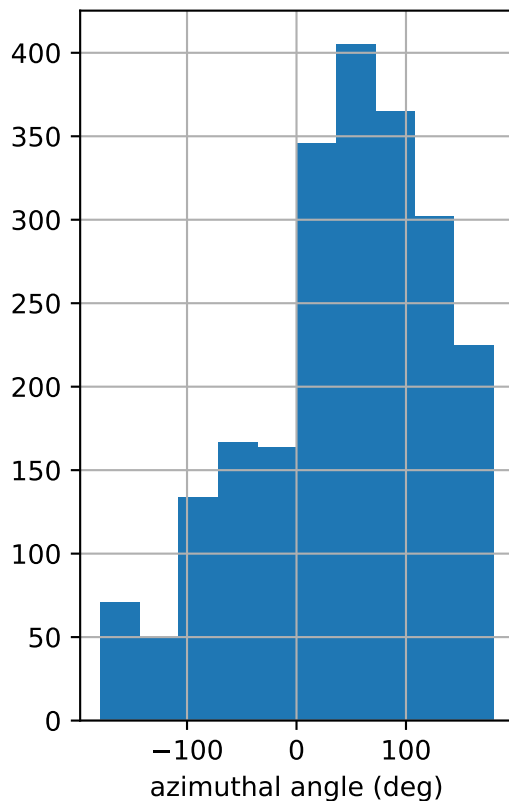
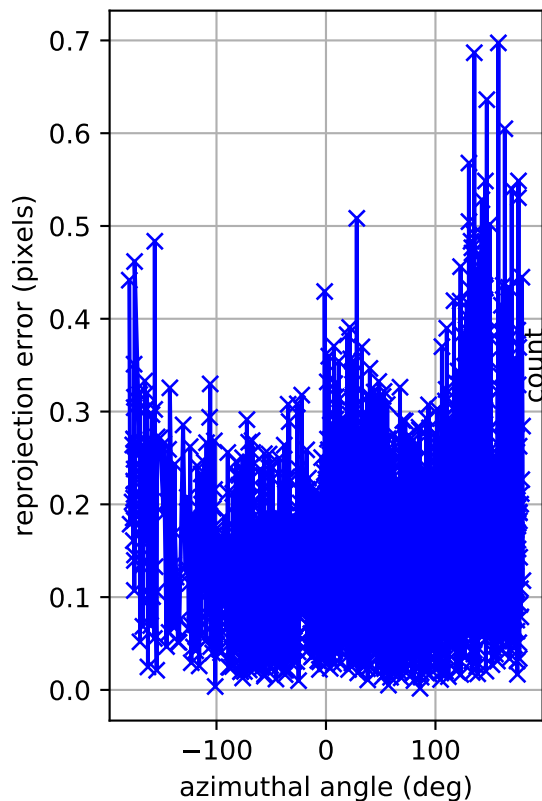
camera system



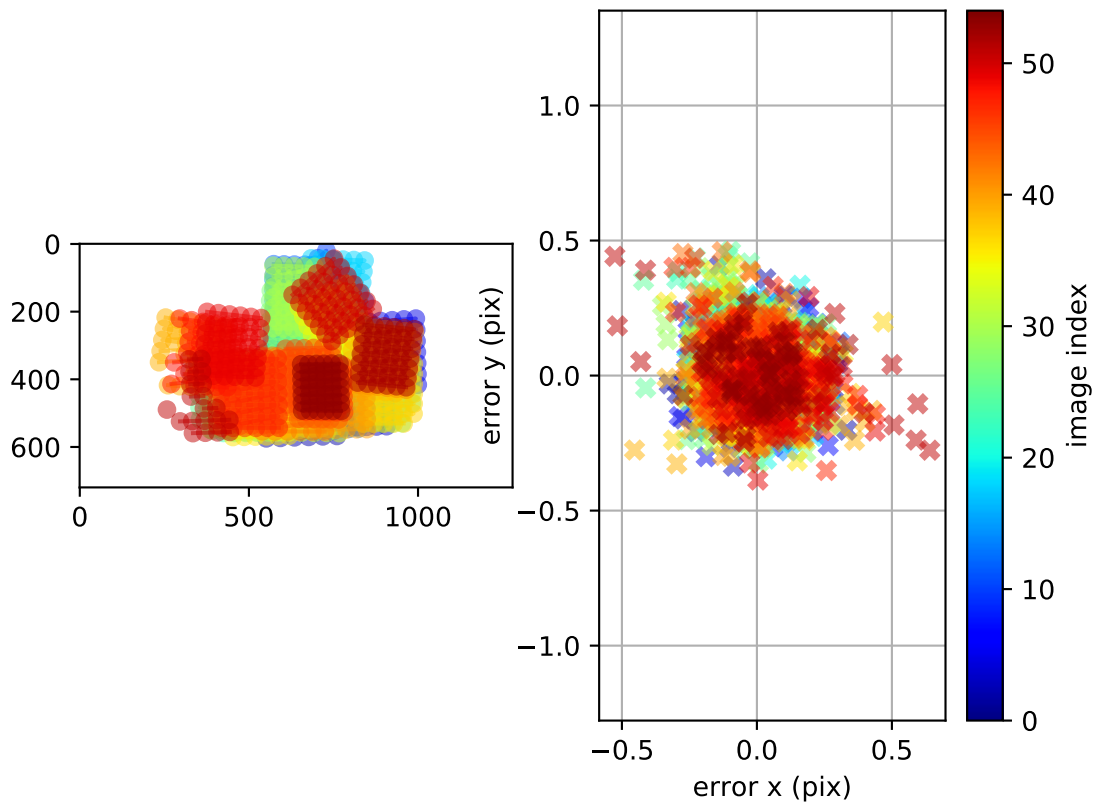
cam0: polar error



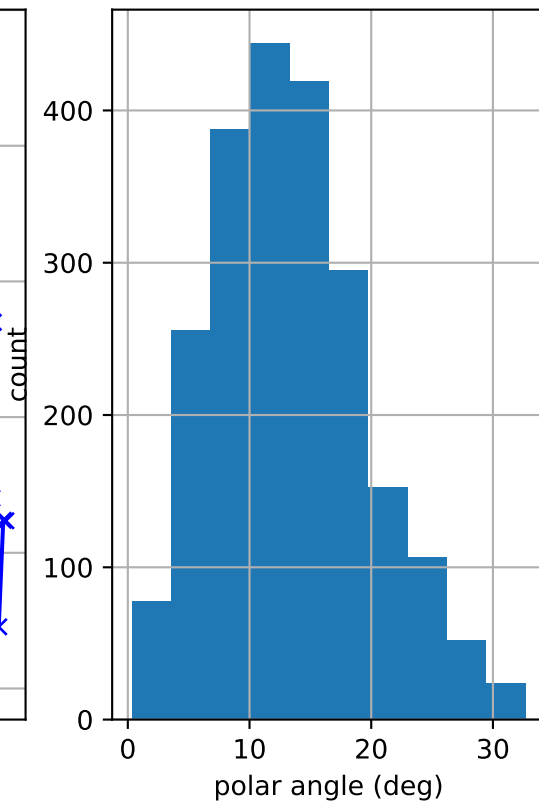
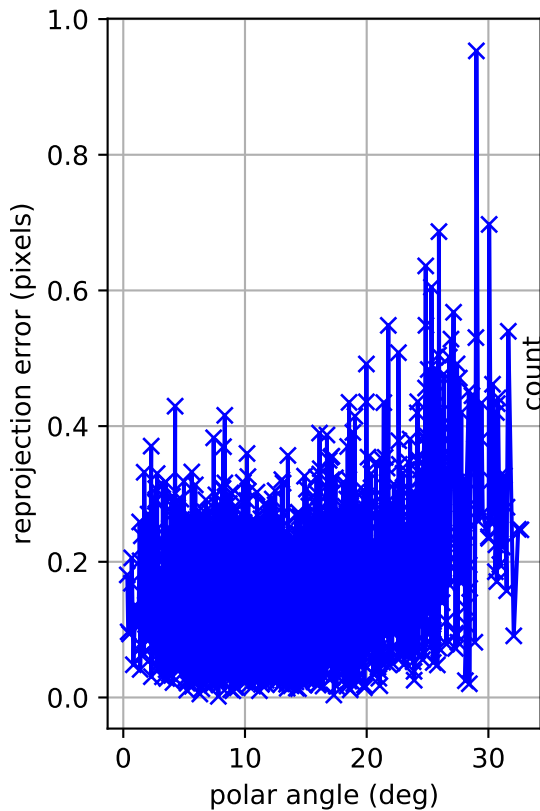
cam0: azimuthal error



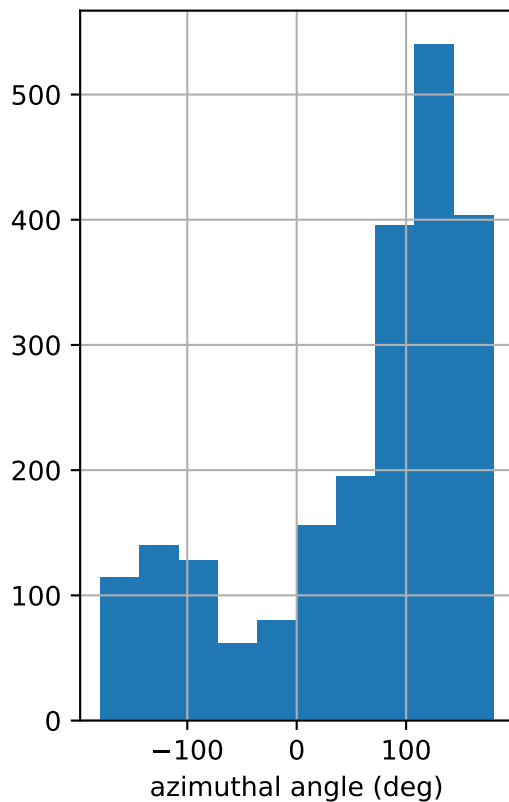
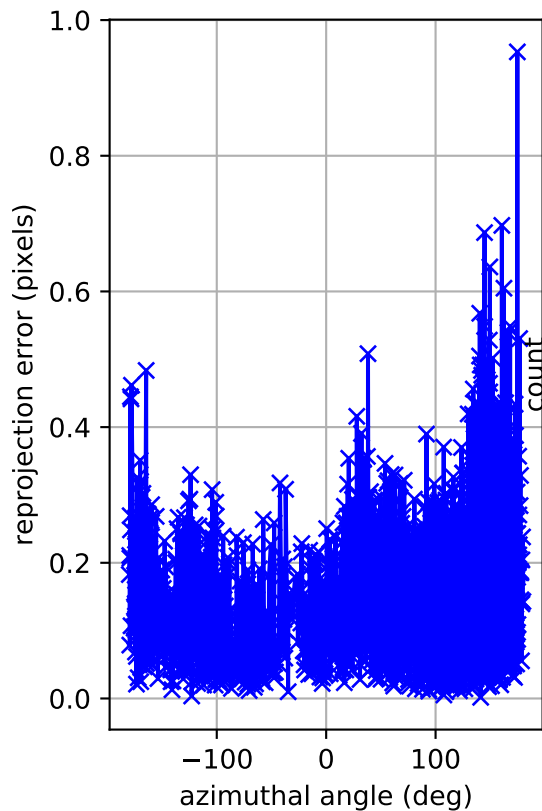
cam0: reprojection errors



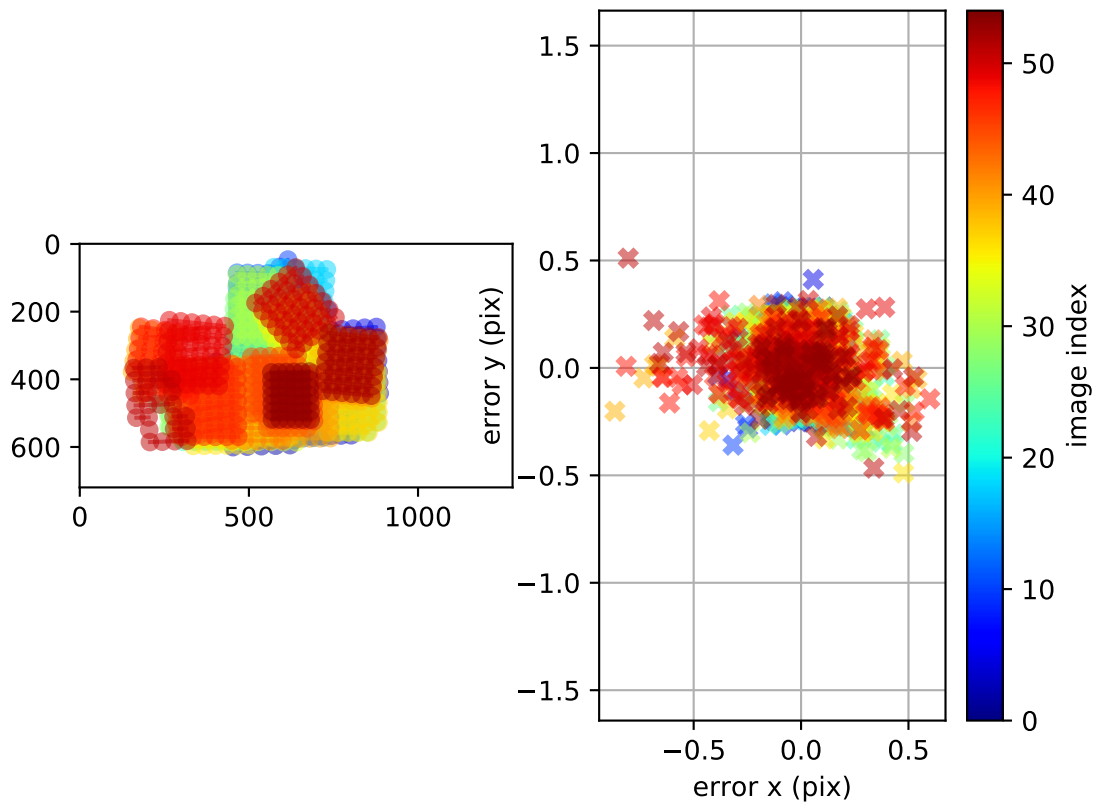
cam1: polar error



cam1: azimuthal error



cam1: reprojection errors





# Location of removed outlier corners

