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OS Aggignment # 01

Q1- Direct memory access is used for high speed I/O devices in order to avoid increasing the CPU's execution Load.

a) How does the CPU interface with the device to cooxdinate the transfer?

The CPU sets up the DMA by giving the device's its address, the memory location and the amount of data to transfer. After that the DMA controller tolker over, reducing the need for the CPU to stay involved in transfer process.

- b) How does the CPU know when the memory operations are complete?
 Once the date transfer is clone, the DMA controller sends a right (interrupt) to the CPU to let it know it can continue processing.
- c) The CPU is allowed to execute other programs while the DMA controller if transferring data. Does this process interfere with the execution of the used program of so describe what forms of interference are coused.

Although DMA does not interfere! be minor delays if both the CPU and DMA try to access memory at the same time. However there delays are typically minimal.

2 - Describe the differences between symmetric and osymmetric multiprocessing. What are the advantages and distadvantages of multiproceepox pyetems?

Symmetric Multiprocessing:

An symmetric multiprocessing, all processors share the same memory and work equally on tasks, leading to better work load distribution.

Asymmetric Multiprocerings

An asymmetric multiprocessing some marn - processor controls the system, while the others handle specific tagks. This get up is simpler to design but does not use resources efficiently.

Advantages: Increased performance, reliability, and fout tolerance. They can handle more tasks simultaneously and are more robust.

They can be complen and costly, and Disadvantages: resource conflicts or synchroni-contion resource between processors may orise.

What is the puspose of interrupts? What are the differences between a trap and an interrupt? can traps be generated intentionally by a user program? If for for what purpose? Purpose of Intersupte: Interrupts are signal, sent to the courtelling it to paule its current teak to deal with an IIO call. This enable veod-fine responses to enternal events. Differences by trap and Interrupts A trap is a software-generated interrupt, typically triggered by errors or system calls, whereast interrupt art hardware based. Intentional toupies Yes user programs can deliberately trigger toaps, often to request services from the operating system through system calls, allowing controlled communication with Os. 4. Rank the following storage experient from slowest to fastest. a Hard digk drives 1) Registers c) Optical Disk d) Main memosy e) Non volocitle memory fl Magnetic tapes 9) cache. Magnetic Tapel, Optical Disks, Hard Disk Oriver. Non volatile memory, Main Memory, Cache

5. Differentiate between multiprogramming systems and multiproceeding systems.

They allow multiple programs to reside in memory at the same time, enabling better cov utilization. The cou switches between programs to maximize usage, although only one process runs at a time.

Multiprocelling Systems:

This involves multiple CPUs working simultaneogly to enewte different parallelis processes concurrently. At provides porallegion and increases processing power.

6. Give two reasons why caches are useful. What problems do they solve? What problems do they cause? It a cache can be made as longe as the device for which it is cachines, why not make it that longe and eliminate the device?

Reasons why they are useful:

· Caches provide factor access to frequently used data compared to main memory.

They reduce average time to access memory, improving overall system performance.

They solve the problems of the speed disposity between the cpu and main memory.

Problems they create:

Caches introduce complexity in maintaining data consistency in multiprocessor systems. Why not make caches thuge?

Making caches our huge of storage devices would be entremply enpensive and still wouldn't be as fast our smaller squicker caches. Large caches also consume more power and are less efficient.

- 7. Distinguish between the client-gerver and peer to peer models of distributed systems.
 - An client server models, clients request services from a control ferver. At offers centralized control and better security management. Whereas in peer to peer models all nodes in the system, act as both clients and servers, sharing resources equally. This mode! Provides better scalability and redundancy but it is harder to secure.
- 8. What is the purpose of system calls, and how do system calls relate to the concept of dual mode operation?

System calls provide a way for user programs to enteract with OS. This allows controlled access to horselwave resorters.

Dual mode protects the system by separating user-mode from kornel-mode. It prevents user programs from directly accessing critical resources.