### CS 295A/395D: Artificial Intelligence

#### **Elementary Game Theory**

Prof. Emma Tosch

30 March 2022



#### Agenda

Review decision theory

Elementary game theory

- Optimum vs. optimal solutions
- Strategies
- Vocabulary

#### Logistics

- BB theory assignment out today
- Exam through game theory
  - Temporal reasoning pushed to next unit
  - Exam next Friday (April 8)
- Next unit: temporal reasoning and program synthesis
  - Removed machine learning

## **Decision node** Chance node **Reward node**

Note: "decision tree" also refers to a classification algorithm in machine learning and is completely different from the type of decision tree we will talk about here.

## Recap: Decision Theory

We can express taking actions in a world with uncertainty via decision trees

Decisions trees are temporally-ordered nodes where each level corresponds to alternating:

- Decision nodes state of the system; outgoing edges represent different actions
- Chance nodes probability distributions over outcomes; outgoing edges represent reachable states with some probability
- Reward nodes utility obtained from following the path

# **Decision node Chance node Reward node**

## Recap: Maximize expected utility

$$EU[a \mid e_1, e_2, \dots] = \sum_{s'} P(S_{t+1} = s' \mid a, e_1, e_2, \dots) U(s')$$

Best action is the action a that maximizes  $EU[\ a \mid e_1, e_2, ...\ ]$ 

Sum of the utility of actions taken.

Note: "decision tree" also refers to a classification algorithm in machine learning and is completely different from the type of decision tree we will talk about here.

# **Decision node** Chance node **Reward node**

Note: "decision tree" also refers to a classification algorithm in machine learning and is completely different from the type of decision tree we will talk about here.

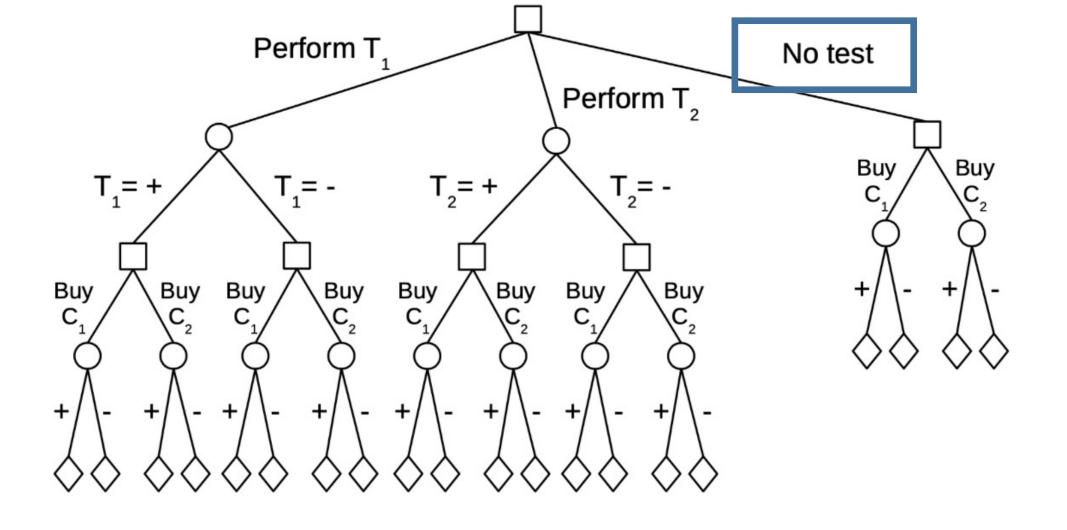
### Recap: Comparing actions

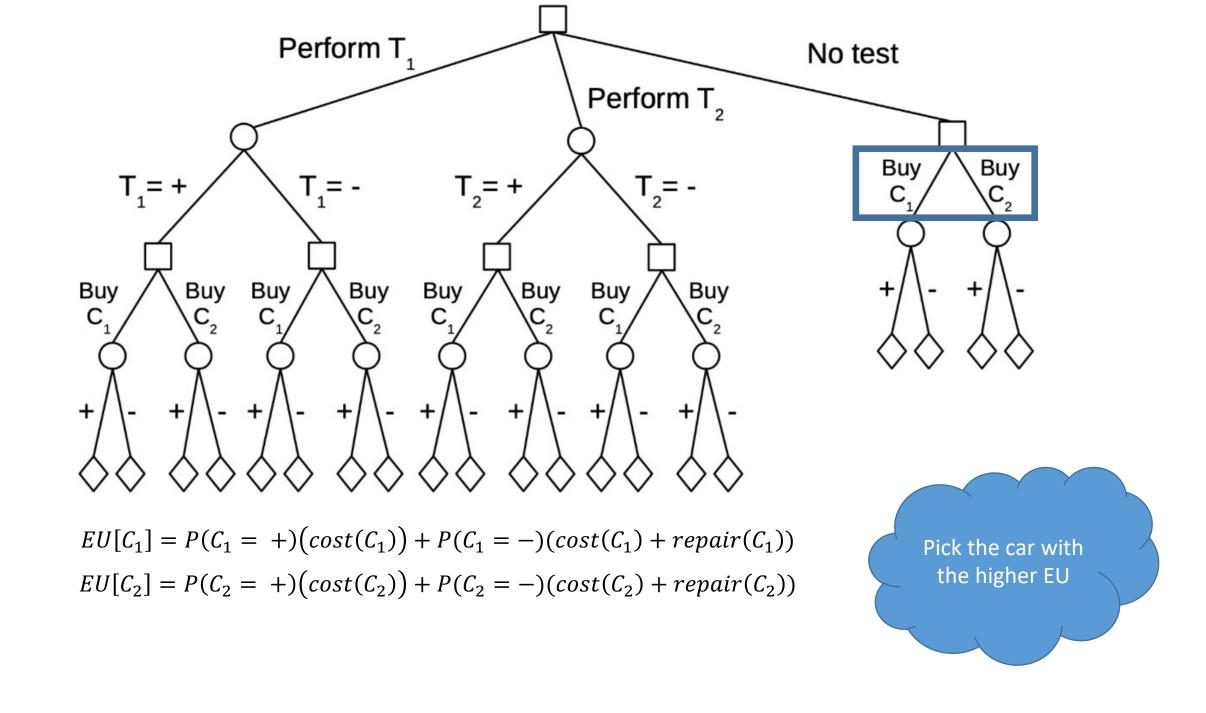
$$EU[\ a \mid e_1, e_2, \dots\ ] = \sum_{s'} P(\ S_{t+1} = s' \mid a, e_1, e_2, \dots) \ U(s')$$

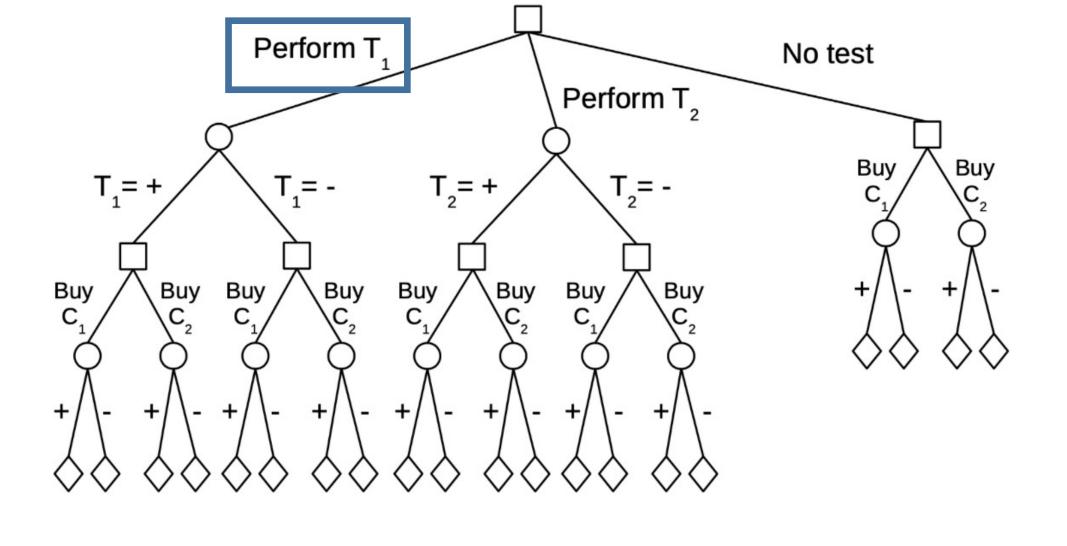
Probability mass function – over all sources of uncertainty associated with this action.

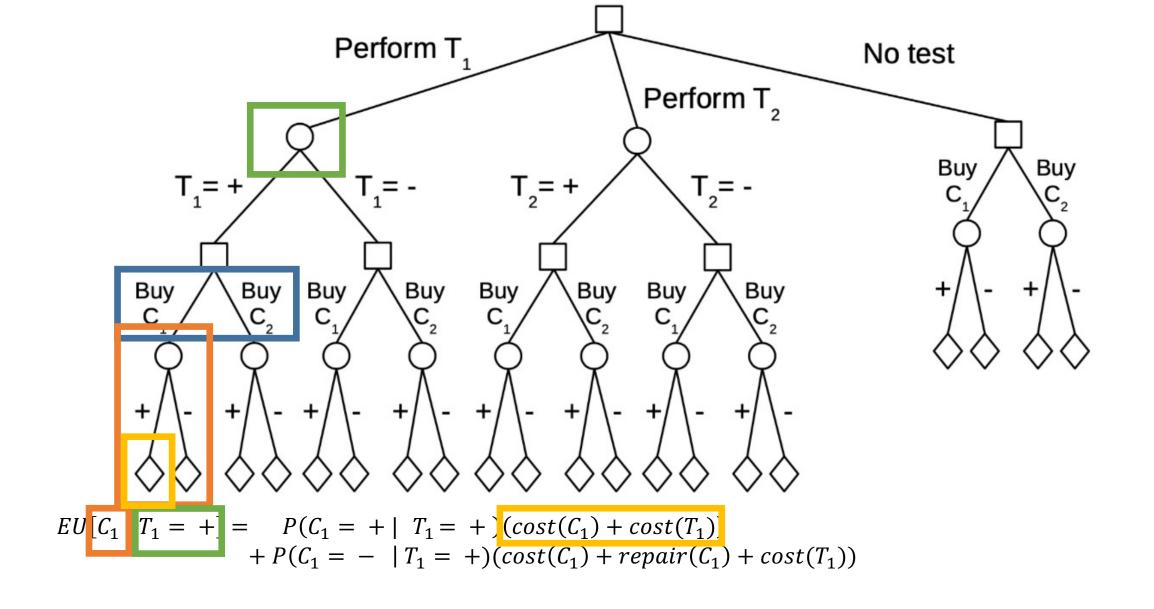
#### Utility function

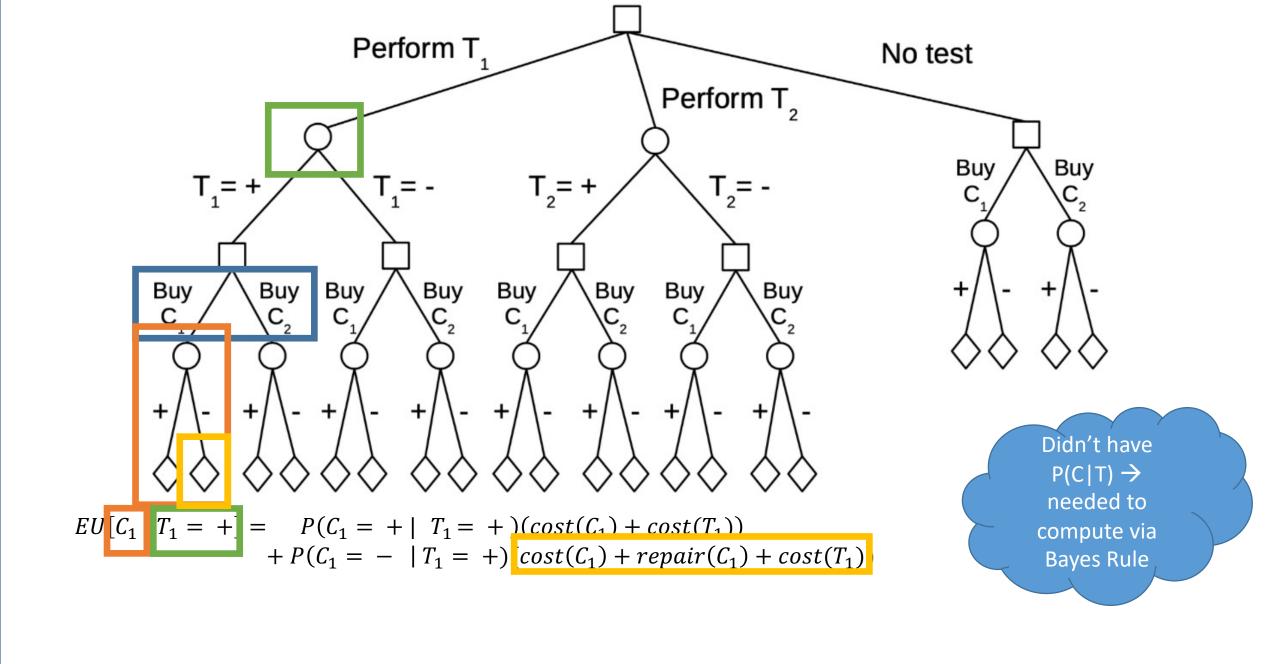
- Basic actions: reward
- Actions with subsequent actions with uncertain outcomes: EU of those actions

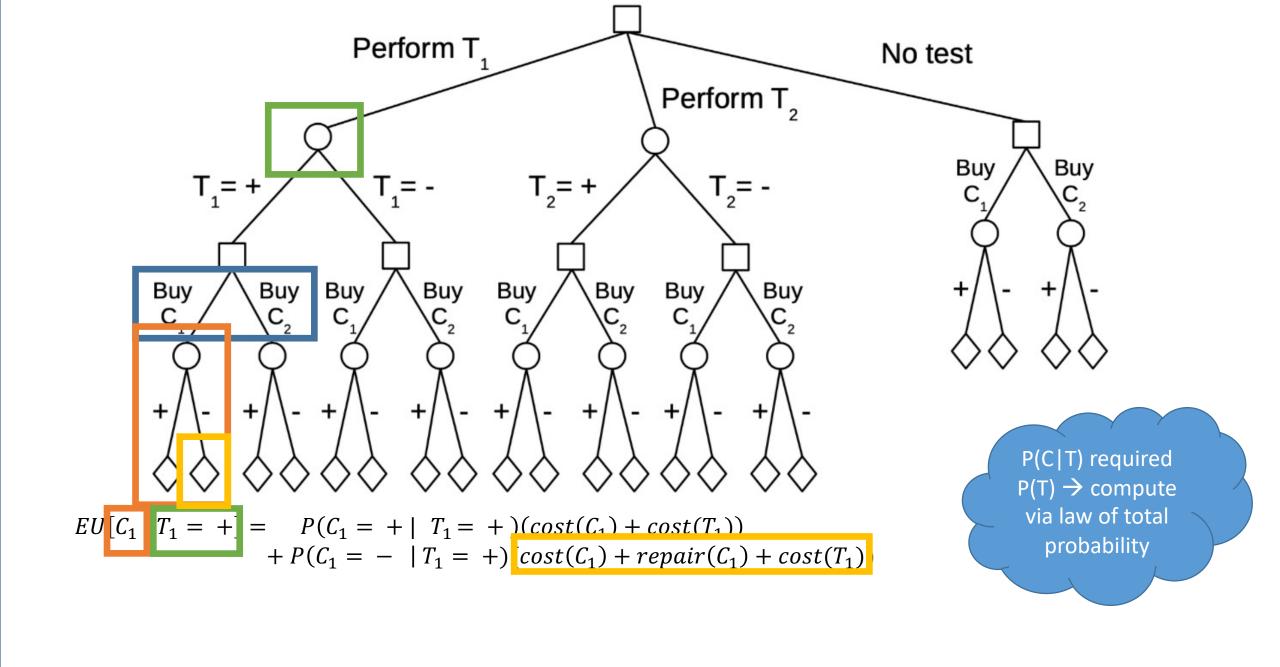


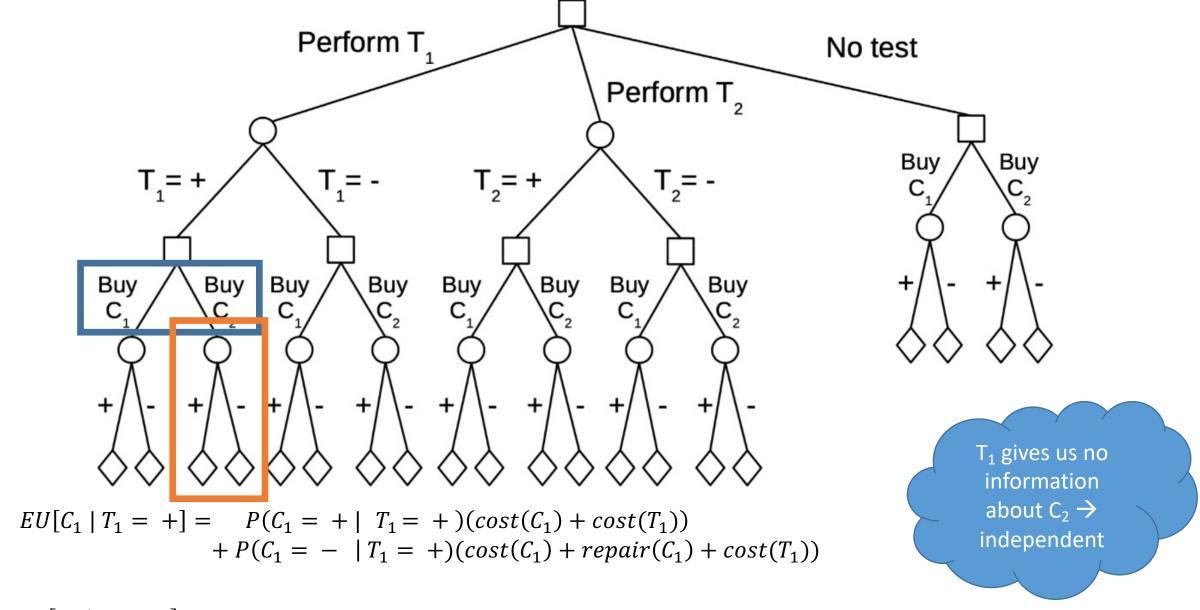




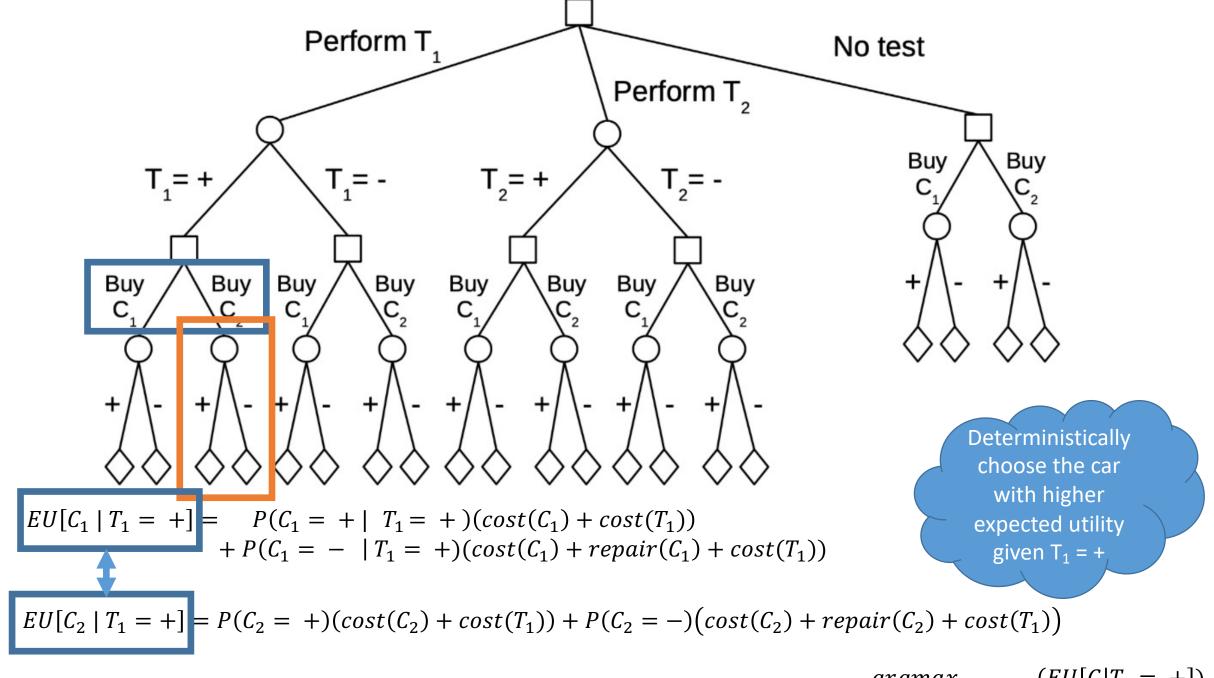




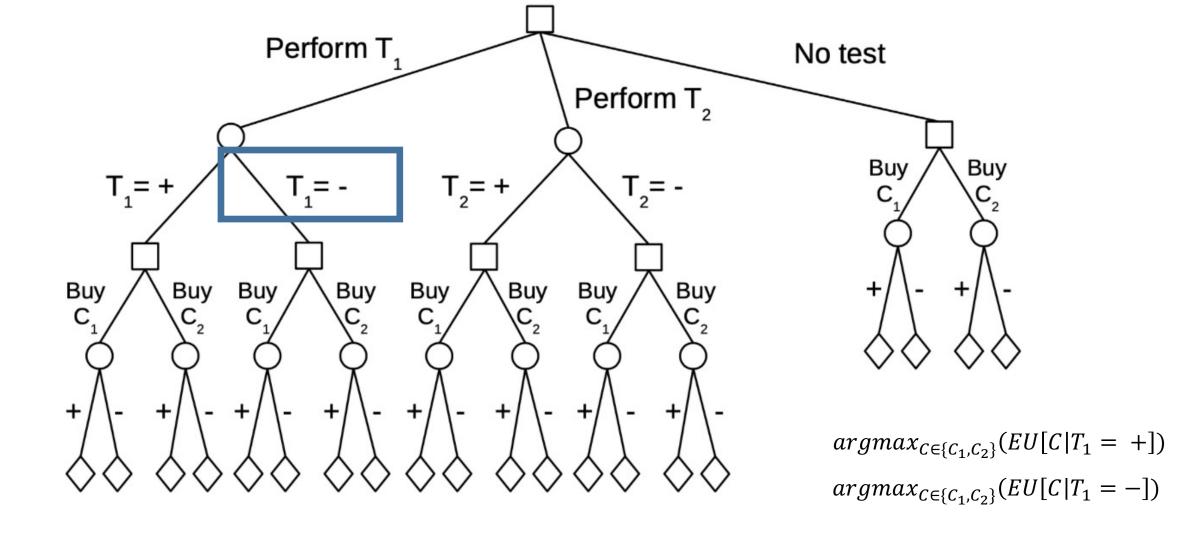


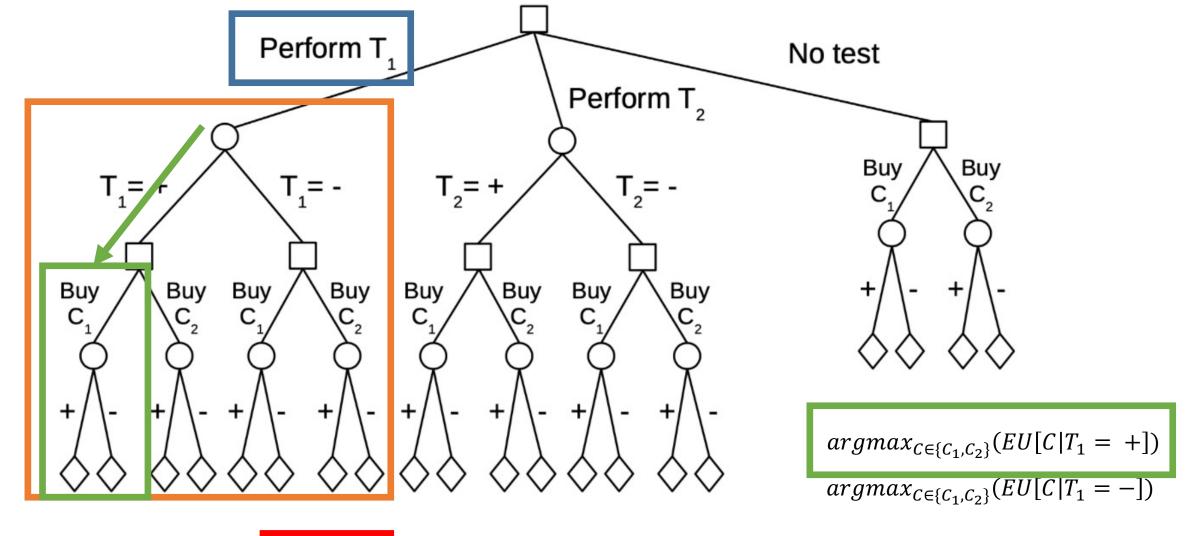


 $EU[C_2 \mid T_1 = +]$ 



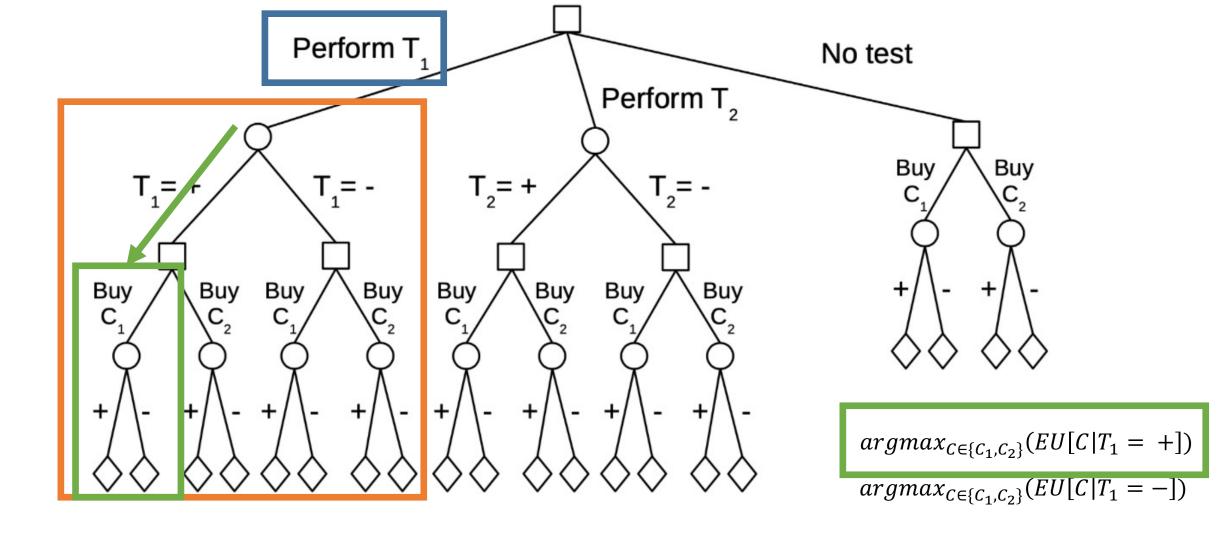
 $argmax_{C \in \{C_1, C_2\}}(EU[C|T_1 = +])$ 





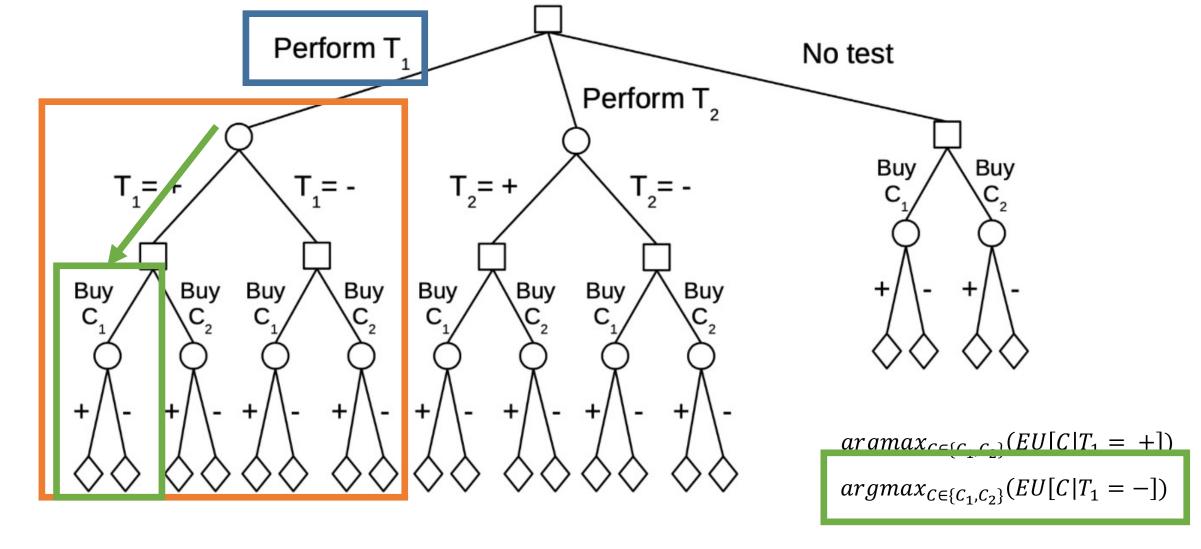
$$EU[T_1] = P(T_1 = +)U(T_1 = +) + P(T_1 = -)U(T_1 = -)$$

If we deterministically choose  $C_1$  when  $T_1 = +, ...$ 



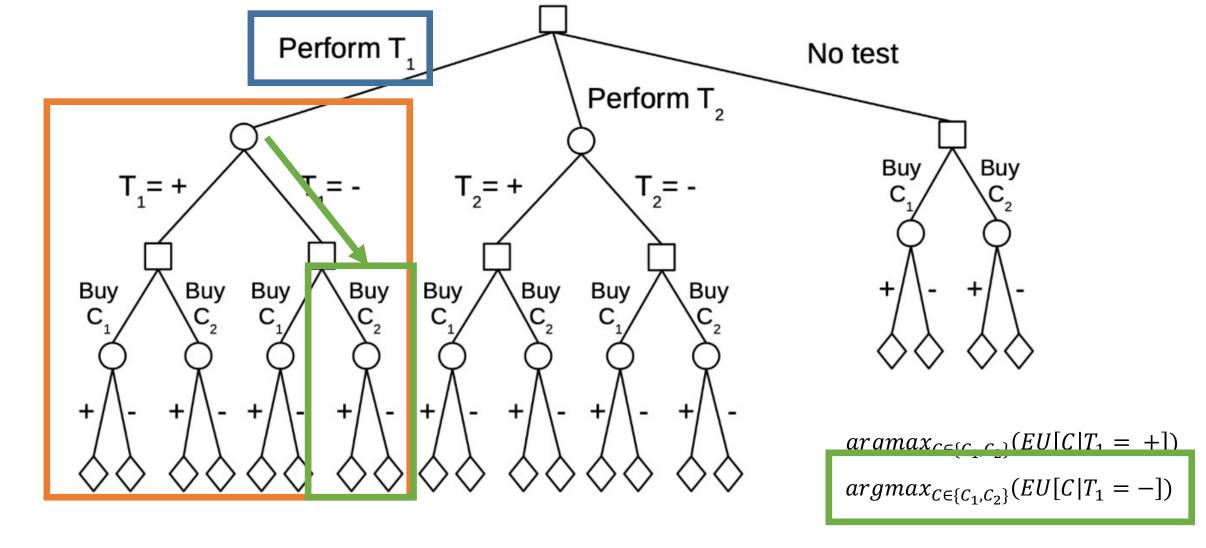
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If we deterministically choose  $C_1$  when  $T_1 = +, ...$ 



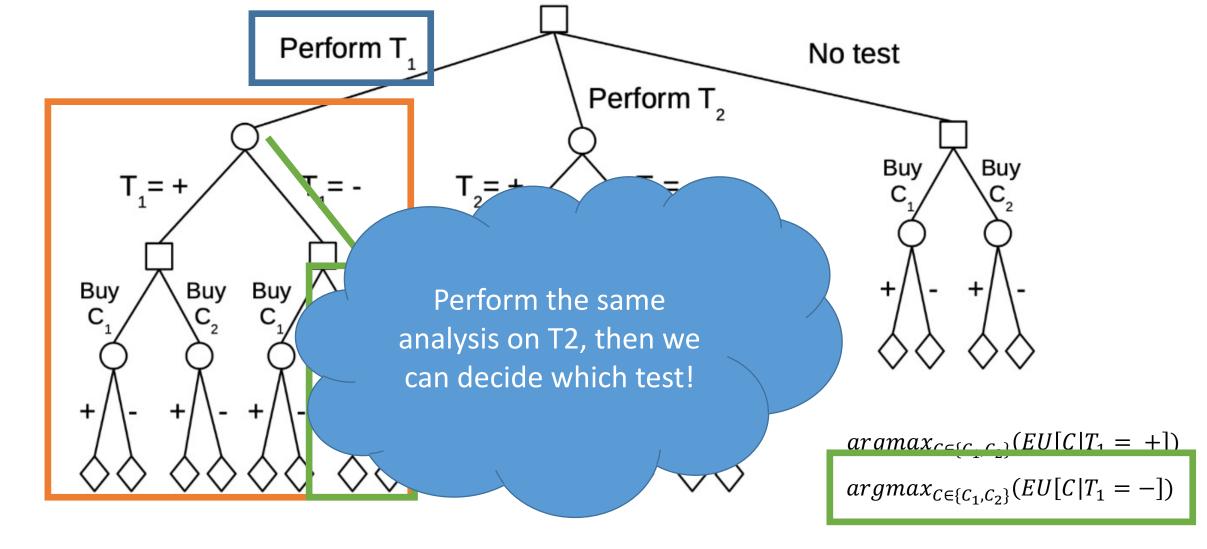
$$EU[T_1] = P(T_1 = +)EU(C_1|T_1 = +) + P(T_1 = -)U(T_1 = -)$$

If we deterministically choose  $C_2$  when  $T_1 = -$ , ...



$$EU[T_1] = P(T_1 = +)EU(C_1|T_1 = +) + P(T_1 = -)U(T_1 = -)$$

If we deterministically choose  $C_2$  when  $T_1 = -$ , ...



$$EU[T_1] = P(T_1 = +)EU(C_1|T_1 = +) + P(T_1 = -)EU(C_2|T_1 = -)$$

If we deterministically choose  $C_2$  when  $T_1 = -$ , ...

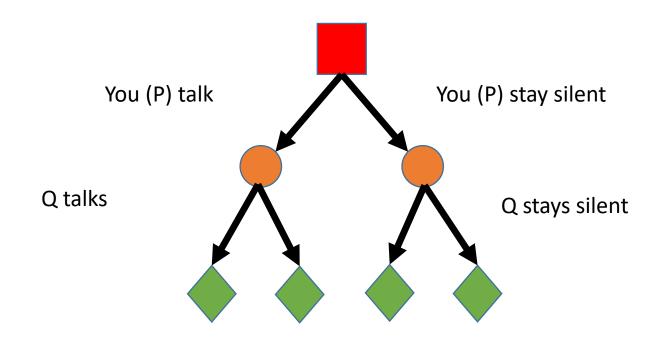
### When uncertainty comes from another agent's actions

Car example: taking an action in one branch closes off possibilities in another

- Randomness comes from
  - Epistemic uncertainty about effects of past actions (e.g., accuracy of test results)
  - Epistemic uncertainty about future state (e.g., quality of car)

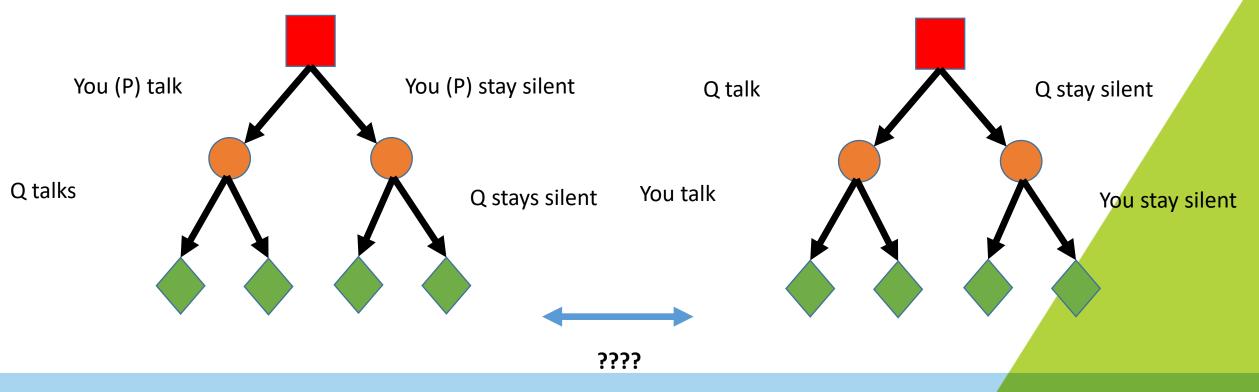
Consider the case when randomness comes from another agent's actions...

You (agent P) and an accomplice (agent Q) have been arrested for a crime...



But Q also knows all this and must make the same choices...

You (agent P) and an accomplice (agent Q) have been arrested for a crime...



**Both parties know this** 

P and Q have been arrested for a crime and separated for in the choice of whether or not to confess and each action is as:

You don't know how your accomplice will act. What do you do?

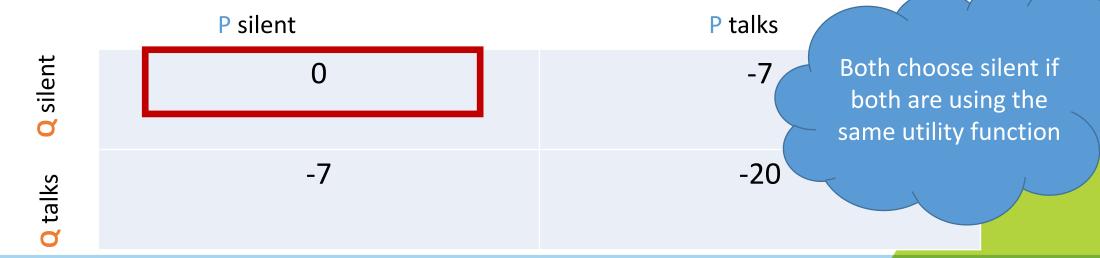
Utility function: Collective cost?

	P silent	P talks
<b>Q</b> silent	(O, O)	(-2, -5)
Q talks	(-5, - <del>2</del> )	(-10, -10)

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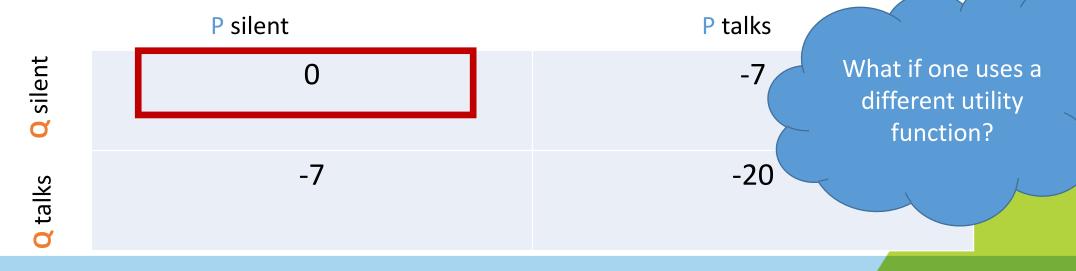
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**Utility function: Individual Cost?** 

D + - II - -

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<b>Q</b> silent	(O, O)	(-2, -5)
talks	(-5, - <mark>2</mark> )	(-10, -10)

P silent

-5

You and an accomplice have been arrested for a crime and interrogation. You have the choice of whether or not to confe associated with a cost. You don't know how your accomplice will

P talks
-2
-10

Utility function:

Individual cost?

**Both parties know this matrix** 

qos

silent

**Q** talks

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talks
-5
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Utility function:

Individual cost?

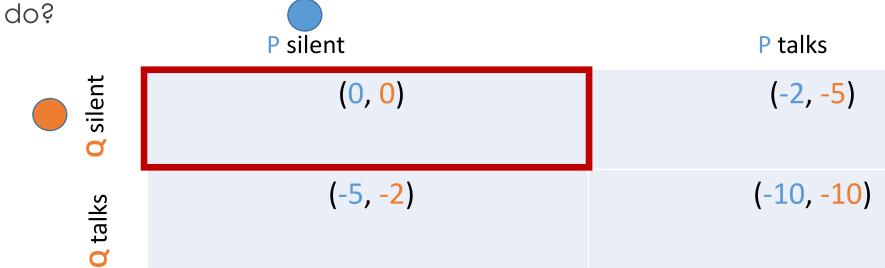


**Both parties know this matrix** 

qos

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Utility function: Individual Cost?



You and an accomplice have been arrested for a crime and interrogation. You have the choice of whether or not to confe associated with a cost. You don't know how your accomplice will

Local reasoning, rather than global

P silent

O talks O silent

(-5, -2)

Weak case



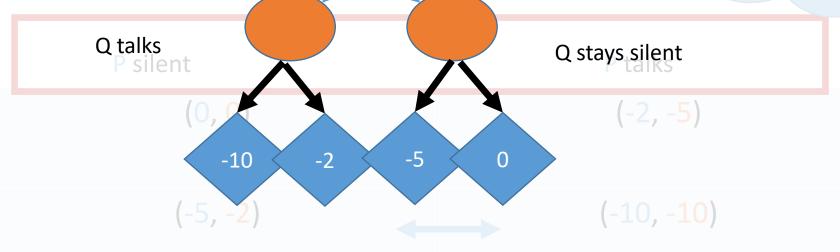
Decision/action

You and an accomplice have been all for a crime and interrogation. You have you (P) taskice er or you (P) stay silent

Local reasoning, rather than globa

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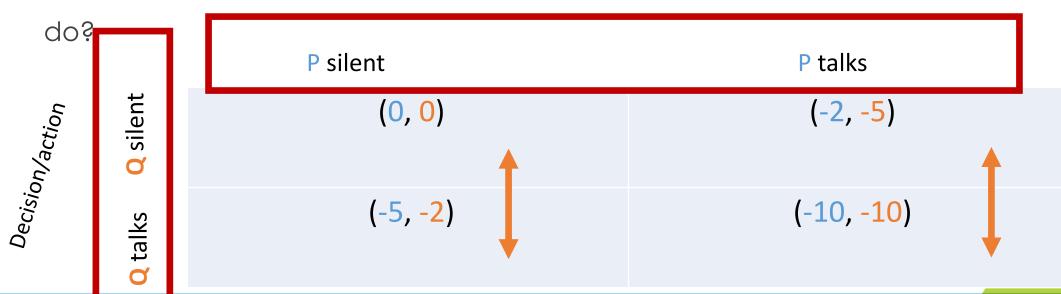
Weak case



Decision/action

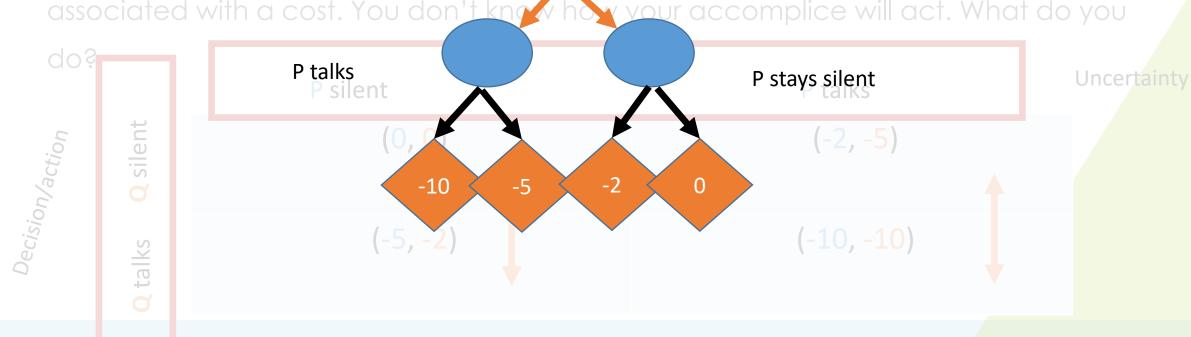
Weak case

You and an accomplice have been arrested for a crime and separated for interrogation. You have the choice of whether or not to confess and each action is associated with a cost. You don't know how your accomplice will act. What do you

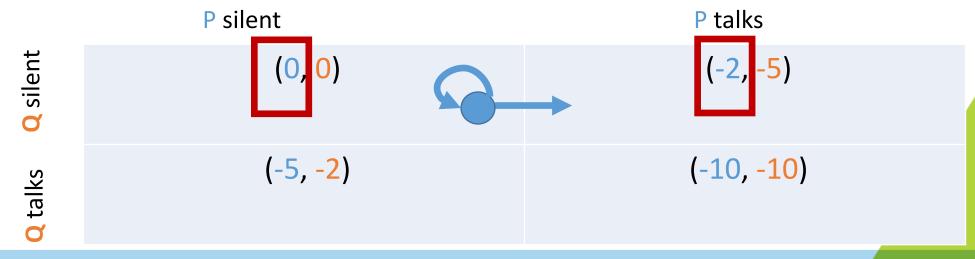


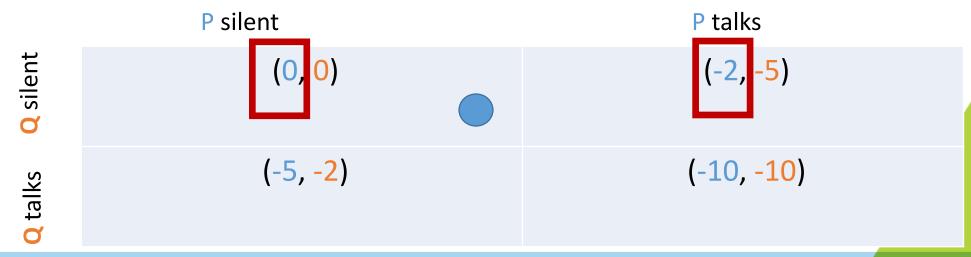
Uncertainty

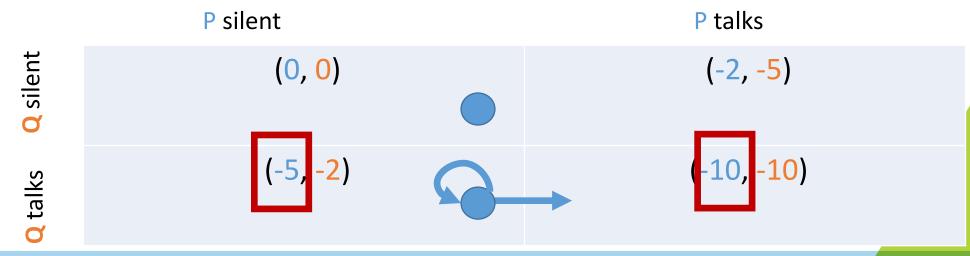
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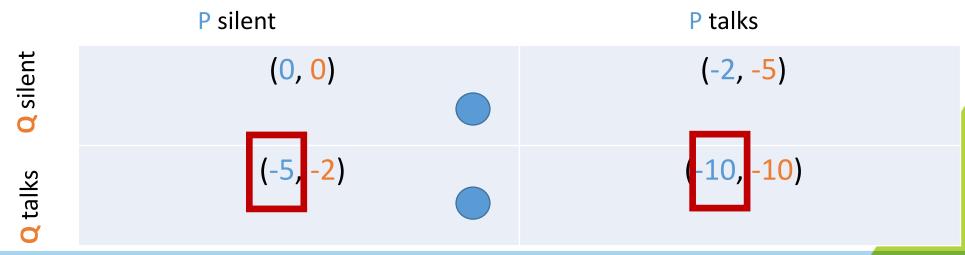


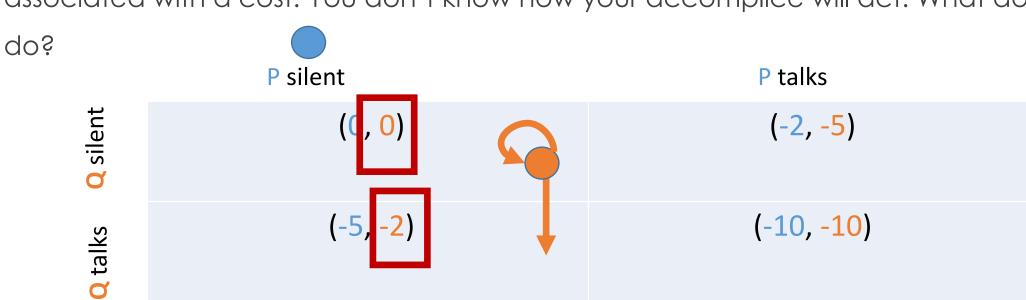
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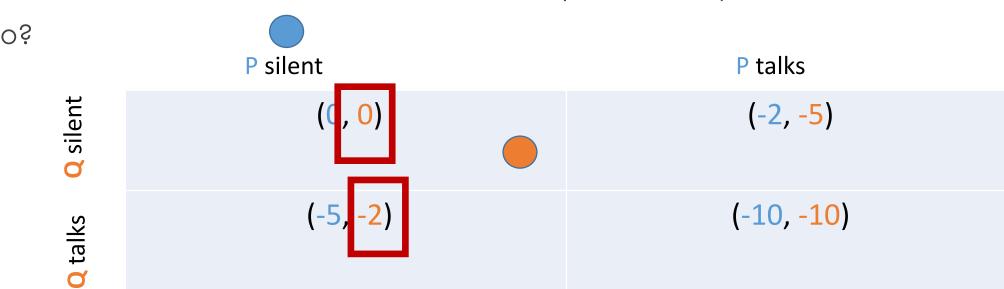


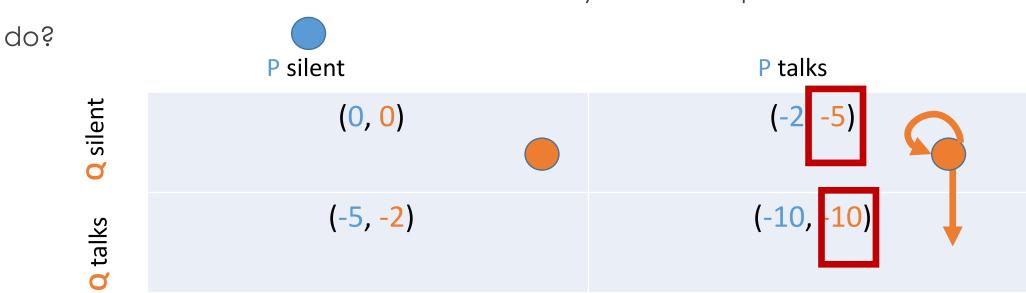


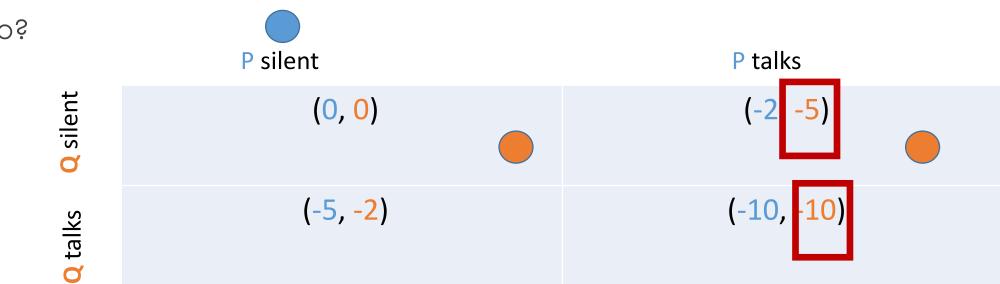


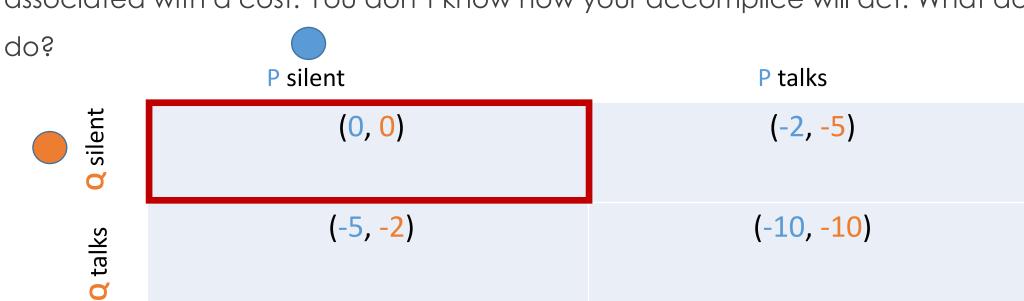












You and an accomplice have been arrested for a crime and se interrogation. You have the choice of whether or not to confess associated with a cost. You don't know how your accomplice will a do?

Consider a different payoff matrix

	P silent	P talks
<b>Q</b> silent	(-2, - <mark>2</mark> )	(0, -15)
Q talks	(-15, <mark>0</mark> )	(-10, -10)

Still globally optimal for collective utility?



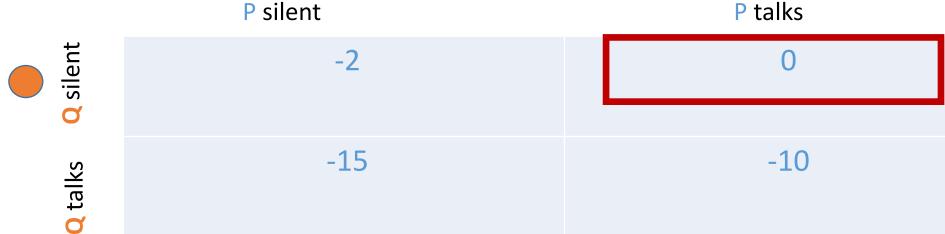
You and an accomplice have been arrested for a crime and so interrogation. You have the choice of whether or not to confess associated with a cost. You don't know how your accomplice will a

individual utility...
will a

Assume Q uses

collective utility,

but P uses



Still globally optimal for individual utility for P?

qos

You and an accomplice have been arrested for a crime and se decides to mimic? interrogation. You have the choice of whether or not to confess associated with a cost. You don't know how your accomplice will act. What you

What if Q knows P's

utility function and

P silent
P talks

-2
-15
-10

Still globally optimal for individual utility?

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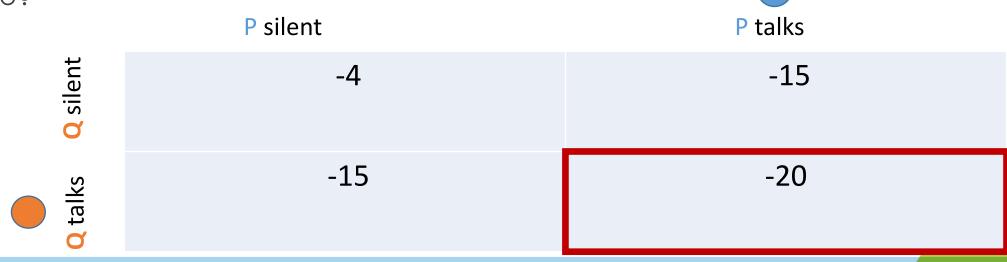
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Still globally optimal for individual utility?

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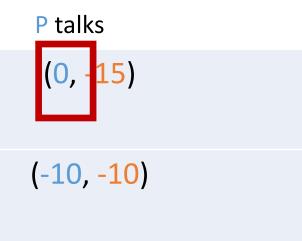


P silent

(-15, 0)

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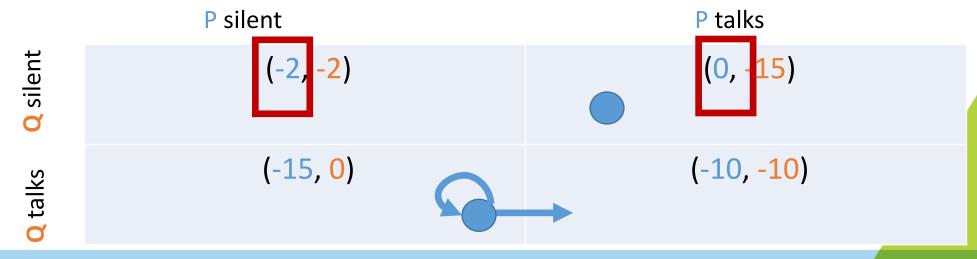
Local reasoning, rather than global

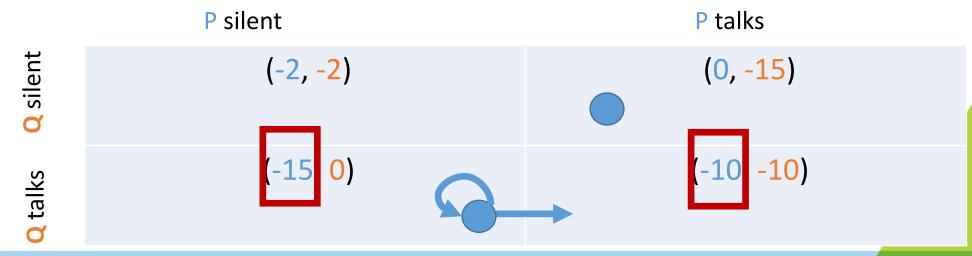


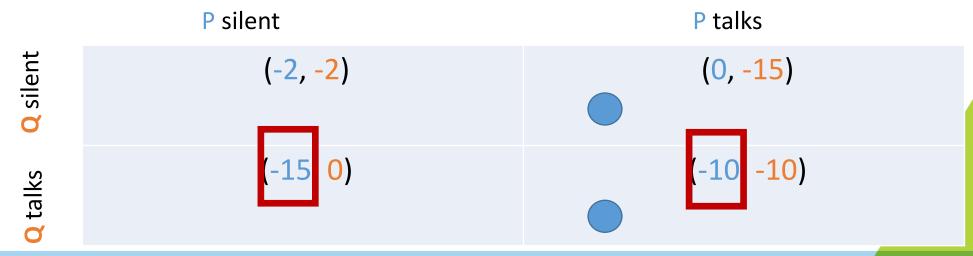
**Incentivize talking** 

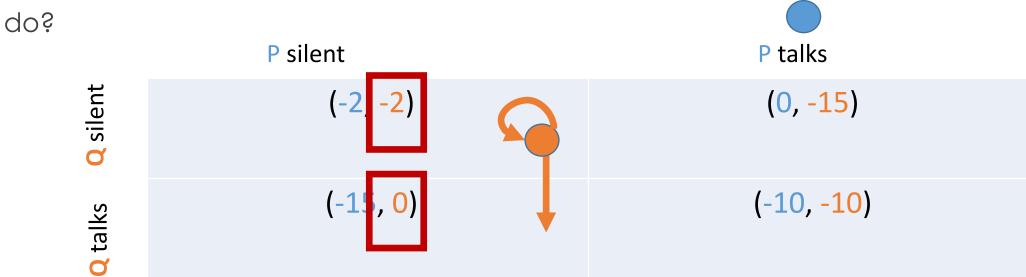
2 silent

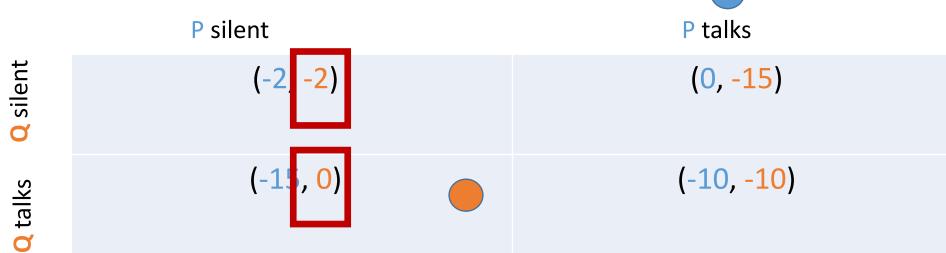
**Q** talks

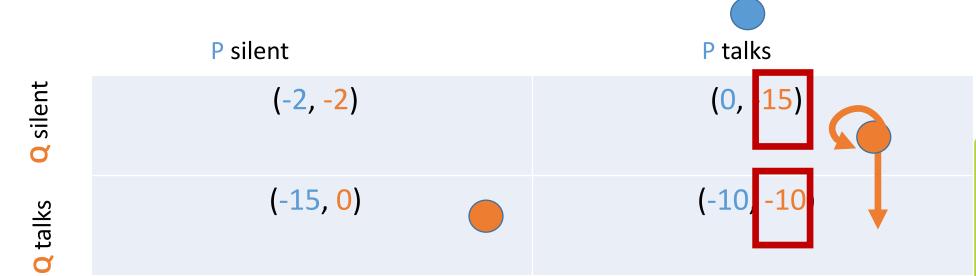


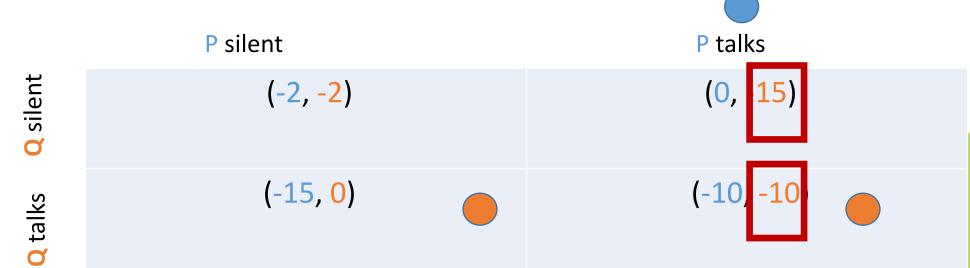


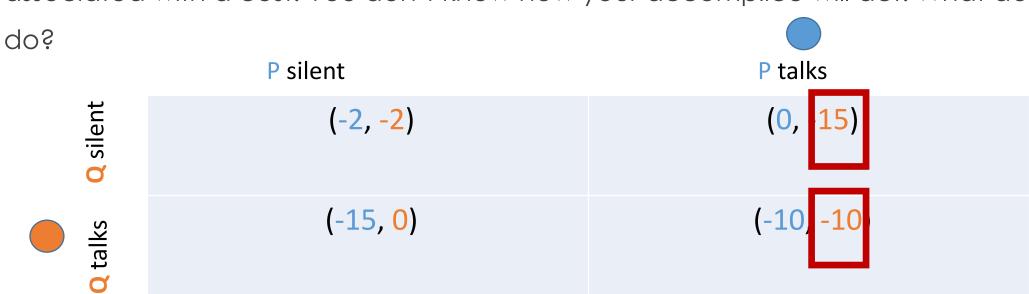


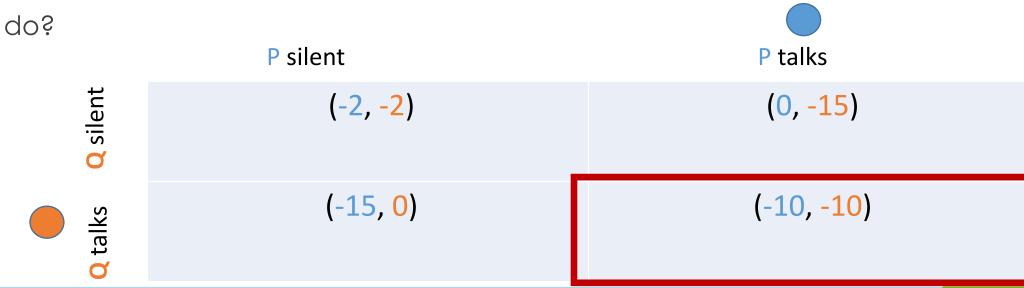






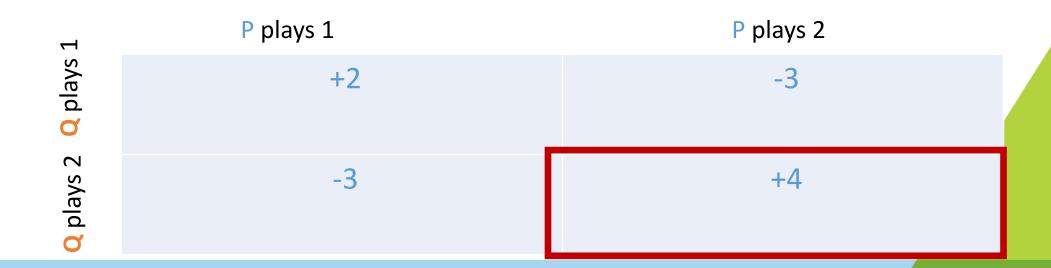


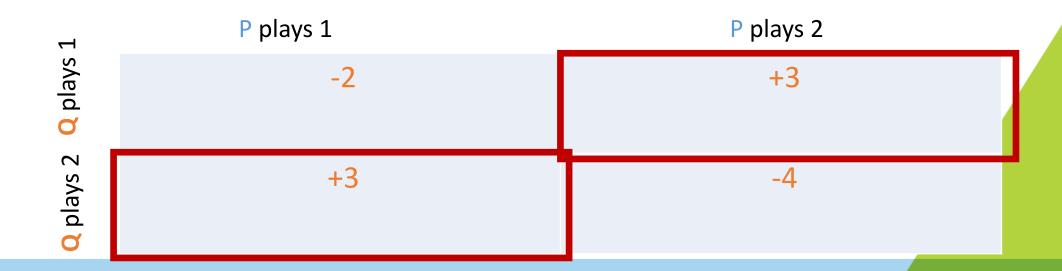




$\leftarrow$	P plays 1	P plays 2
Q plays 1	(+2, - <mark>2</mark> )	(-3, +3)
Q plays 2	(-3, +3)	(+4, -4)

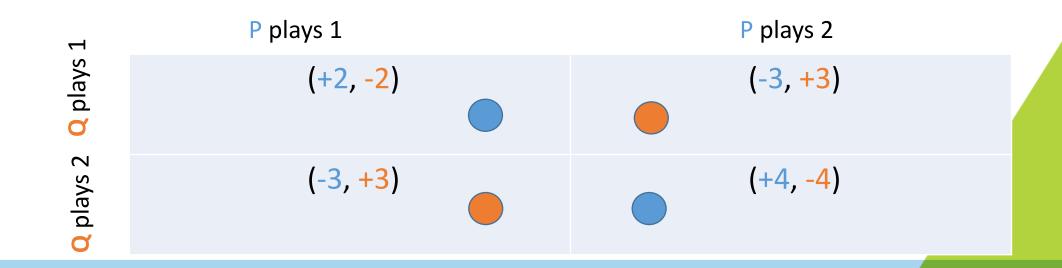
$\leftarrow$	P plays 1	P plays 2
Q plays	0	0
Q plays 2	0	0



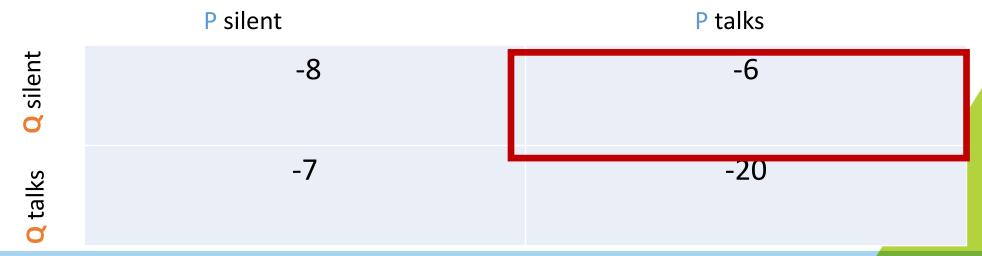


Choose between 1 and 2 fingers. P wins if sum is even. Q wins if pays the winner.

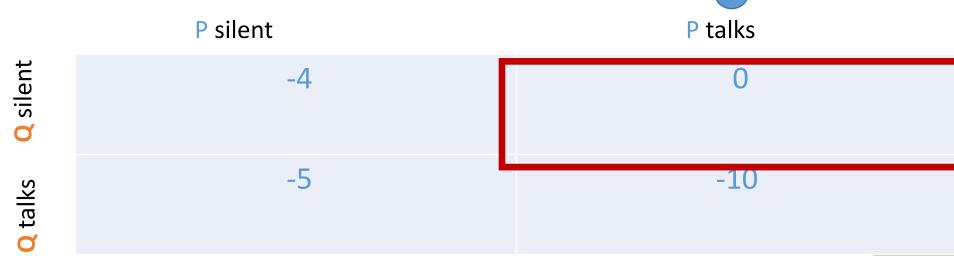
Choose probabilistically



	P silent	P talks
<b>Q</b> silent	(-4, -4)	(0, -6)
Q talks	(-5, -2)	(-10, -10)



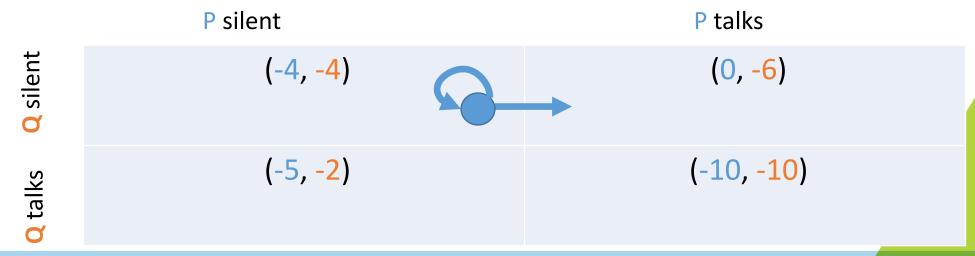
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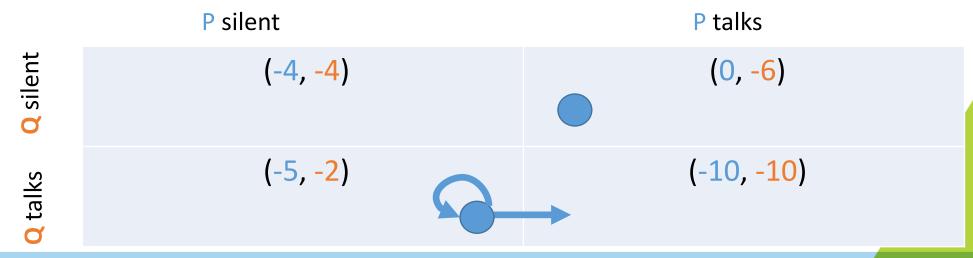


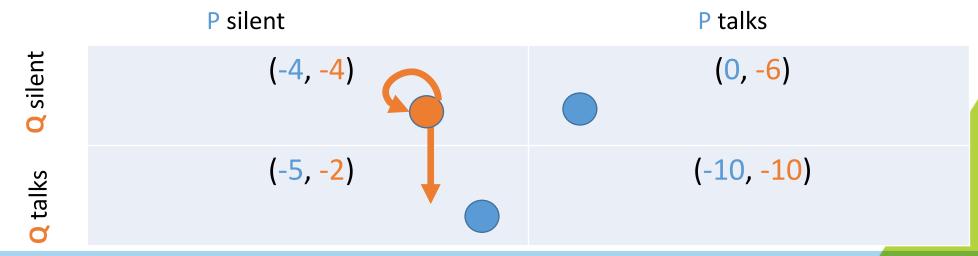
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associated	WIIII a Cosi. 100 doli i kilow 110 W	your accomplied will act. What ao y
qoś		
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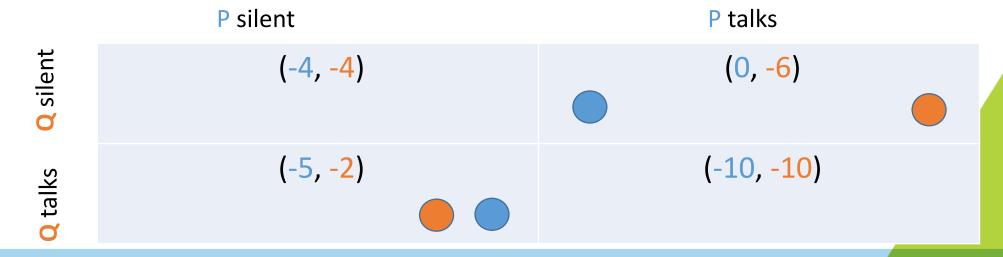




You and an accomplice have been arrested for a crime and se interrogation. You have the choice of whether or not to confess associated with a cost. You don't know how your accomplice will a do?

Suppose we model Q's choice probabilistically...

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# **Vocabulary & Concepts**

- Always assume local decision making (all players maximizing individual utility)
- Zero sum every entry in global collective payoff is 0
- Pure strategy always pick the same action no matter what
- Mixed strategy pick an action probabilistically
- Dominant strategy one action is strictly better no matter what the other plays does