

# Generic pattern unification

## A categorical approach

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# A quick introduction to unification

$$\underbrace{t} \stackrel{?}{=} \underbrace{u}$$

terms with metavariables  $M, N, \dots$

**Unifier** = metavariable substitution  $\sigma$  s.t.

$$t[\sigma] = u[\sigma]$$

**Most general unifier** = unifier  $\sigma$  that uniquely factors any other

$$\forall \delta, \quad t[\delta] = u[\delta] \quad \Leftrightarrow \quad \exists! \delta'. \quad \delta = \delta' \circ \sigma$$

**Goal of unification** = find the most general unifier

# Where is unification used?

## First-order unification

No metavariable argument

### Examples

- Logic programming (Prolog)
- ML type inference systems

$$(M \rightarrow N) \stackrel{?}{=} (\mathbb{N} \rightarrow M)$$

## Second-order unification

$M(\dots)$

### Examples

- $\lambda$ -Prolog
- Type theory, proof assistants

$$(\forall x.M(x, u)) \stackrel{?}{=} t$$

Undecidable

# Pattern unification [Miller '91]

A **decidable** fragment of second-order unification.

**Pattern restriction:**

$$M(\underbrace{x_1, \dots, x_n}_{\text{distinct variables}})$$

$\exists$  unification algorithm [Miller '91]

- fails if no unifier
- returns the most general unifier
- linear complexity [Qian '96]

# This work

## A **generic** algorithm for pattern unification

- Parameterised by a *signature*
- Categorical semantics

## Examples

- *binding signatures*
- Linear syntax (e.g., quantum  $\lambda$ -calculus)
- Intrinsic system F

See our preprint.

# Related work: algebraic accounts of unification

## First-order unification

- Lattice theory [Plotkin '70]
- Category theory
  - [Rydeheard-Burstall '88]
  - [Goguen '89]

## Pattern unification

- Category theory
  - [Vezzosi-Abel '14]  
normalised  $\lambda$ -terms
  - [This work](#)

# Outline

- 1 Pattern unification for pure  $\lambda$ -calculus
  - Syntax
  - Unification algorithm
- 2 Generalisation to binding signatures
- 3 Categorical generalisation
  - A case study: syntax of pure  $\lambda$ -calculus
  - Generic pattern unification
- 4 Example: System F

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# Syntax (De Bruijn levels)

Metavariable context  $(M_1 : m_1, \dots)$

$$\underbrace{\Gamma}_{\text{Variable context}} ; \underbrace{n}_{\text{Variable context}} \vdash t$$

$$\frac{1 \leq i \leq n}{\Gamma ; n \vdash v_i} \text{VAR}$$

$$\frac{\Gamma ; n \vdash t \quad \Gamma ; n \vdash u}{\Gamma ; n \vdash t u} \text{APP}$$

$$\frac{\Gamma ; n + 1 \vdash t}{\Gamma ; n \vdash \lambda t} \text{ABS}$$

$$\frac{(M : m) \in \Gamma \quad 1 \leq i_1, \dots, i_m \leq n \quad i_1, \dots, i_m \text{ distinct}}{\Gamma ; n \vdash M(v_{i_1}, \dots, v_{i_m})} \text{FLEX}$$

No  $\beta/\eta$ -equation.

# Metavariable substitution

**Substitution  $\sigma$  from  $\overbrace{(M_1 : m_1, \dots, M_p : m_p)}^\Gamma$  to  $\Delta$ :**

$$(\sigma_1, \dots, \sigma_p) \quad \text{s.t.} \quad \Delta; m_i \vdash \sigma_i$$

## Notation

$$M_i(v_1, \dots, v_{m_i}) \mapsto \sigma_i$$

## Term substitution

$$\Gamma; n \vdash t \quad \mapsto \quad \Delta; n \vdash t[\sigma]$$

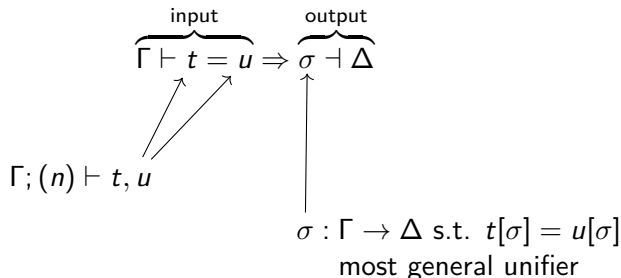
Base case:

$$M_i(x_1, \dots, x_{m_i}) \mapsto \sigma_i[v_j \mapsto x_j]$$

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# Unification algorithm



# Examples

$$\Gamma, M : 2 \vdash M(x, y) = x \Rightarrow (M(v_1, v_2) \mapsto v_1) \dashv \Gamma$$

$$\Gamma, M : 2 \vdash M(x, y) = y \Rightarrow (M(v_1, v_2) \mapsto v_2) \dashv \Gamma$$

# Impossible cases

$$\Gamma \vdash \lambda t = u_1 u_2 \Rightarrow ! \vdash \perp$$

formal "error" context

formal "error" substitution

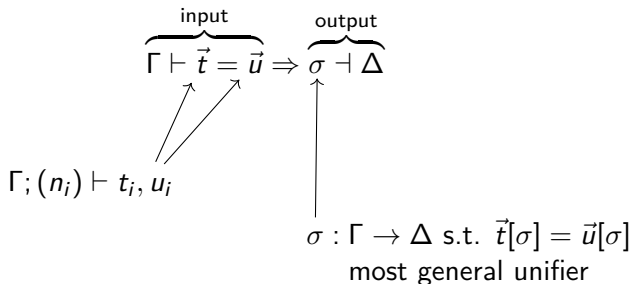
# Congruence

$$\frac{\Gamma \vdash t = u \Rightarrow \sigma \vdash \Delta}{\Gamma \vdash \lambda t = \lambda u \Rightarrow \sigma \vdash \Delta}$$

$$\frac{\Gamma \vdash "t_1, t_2 = u_1, u_2" \Rightarrow \sigma \vdash \Delta}{\Gamma \vdash t_1 \ t_2 = u_1 \ u_2 \Rightarrow \sigma \vdash \Delta}$$



# Unifying lists of terms



# Sequential unification

$$\frac{\Gamma \vdash t_1 = u_1 \Rightarrow \sigma_1 \dashv \Delta_1 \quad \Delta_1 \vdash \vec{t}_2[\sigma_1] = \vec{u}_2[\sigma_1] \Rightarrow \sigma_2 \dashv \Delta_2}{\Gamma \vdash t_1, \vec{t}_2 = u_1, \vec{u}_2 \Rightarrow \sigma_1[\sigma_2] \dashv \Delta_2} \text{U-SPLIT}$$

# Unifying a metavariable $M(\vec{x}) \stackrel{?}{=} \dots$

Three cases

- 1  $M(\vec{x}) \stackrel{?}{=} M(\vec{y})$
- 2  $M(\vec{x}) \stackrel{?}{=} \dots M(\vec{y}) \dots$
- 3  $M(\vec{x}) \stackrel{?}{=} u$  and  $M \notin u$  (non-cyclic)

# Unifying a metavariable with itself

$$M(x_1, \dots, x_m) \stackrel{?}{=} M(y_1, \dots, y_m)$$

Most general unifier

$\vec{p}$  = vector of common positions:  $(x_{p_1}, \dots, x_{p_n}) = (y_{p_1}, \dots, y_{p_n})$

$$\sigma : M(v_1, \dots, v_m) \mapsto N(v_{p_1}, \dots, v_{p_n})$$

Examples

$$\begin{array}{c} \vec{p} = (2) \\ \overbrace{M(x, y) = M(z, y)} \Rightarrow M(v_1, v_2) \mapsto N(v_2) \\ \overbrace{M(x, y) = M(z, x)} \Rightarrow M(v_1, v_2) \mapsto N \\ \vec{p} = () \end{array}$$

# Deep cyclic case

$$M(\vec{x}) \stackrel{?}{=} \dots M(\vec{y}) \dots$$

No unifier

$$\underbrace{M(\vec{x})} = \underbrace{\dots M(\vec{y}) \dots} \Rightarrow ! \vdash \perp$$

sizes cannot match after substitution

# Non-cyclic case

$$M(\vec{x}) \stackrel{?}{=} u \text{ (} M \notin u \text{)} \quad (1)$$

Most general unifier

(1) as the definition of  $M$ :

$$\sigma : M(v_1, \dots, v_m) \mapsto u[x_i \mapsto v_i]$$

Side condition

$$fv(u) \subset \vec{x}$$

$M(x) \stackrel{?}{=} y$  has no unifier ( $x \neq y$ )

# Pruning

What about  $M(x) \stackrel{?}{=} \underbrace{N(x, y)}_u$ ?

Most general unifier

$$N(v_1, v_2) \mapsto M(v_1)$$

- Side-condition  $fv(u) \subset \vec{x}$  is too pessimistic.
- Can be enforced by restricting metavariable arities in  $u$ .

$$N(x, y) \xrightarrow{\text{pruning}} N'(x)$$

# Non-cyclic phase

$$\Gamma \vdash u :> M(\vec{x}) \Rightarrow w; \sigma \vdash \Delta$$

$\Gamma; (n) \vdash u$        $M \notin \Gamma$        $n \vdash \vec{x}$

$\sigma : \Gamma \rightarrow \Delta$   
 pruning substitution

## Formal meaning

$$(\sigma, M(v_1, \dots, v_m) \mapsto w) = \text{most general unifier for } M(\vec{x}) \stackrel{?}{=} u$$



# Pruning a variable

$$\frac{y \notin \vec{x}}{\Gamma \vdash y :> M(\vec{x}) \Rightarrow !; ! \dashv \perp} \text{VAR-FAIL}$$

$$\overline{\Gamma \vdash x_n :> M(\vec{x}) \Rightarrow v_n; id_{\Gamma} \dashv \Gamma}$$

# Pruning a metavariable

$$M(\vec{x}) \stackrel{?}{=} N(\vec{y}) \quad (M \neq N)$$

## Most general unifier

$\vec{l}, \vec{r}$  = vectors of common value positions:

$$(x_{l_1}, \dots, x_{l_p}) = (y_{r_1}, \dots, y_{r_p})$$

Then,

$$M(v_1, \dots, v_m) \mapsto P(v_{l_1}, \dots, v_{l_p})$$

$$N(v_1, \dots, v_n) \mapsto P(v_{r_1}, \dots, v_{r_p})$$

## Examples

Intuition?

$$M(x, y) = N(z, x) \Rightarrow M(v_1, v_2) \mapsto P(v_1)$$

$$N(v_1, v_2) \mapsto P(v_2)$$

$$M(x, y) = N(z) \Rightarrow M(v_1, v_2) \mapsto P, N(v_1) \mapsto P$$

# Pruning operations

**Divide & Conquer:** a fresh metavariable for each argument.

$$\frac{\Gamma \vdash t :> M'(\vec{x}, \overbrace{v_{n+1}}^{\text{bound variable}}) \Rightarrow w; \sigma \vdash \Delta}{\Gamma \vdash \lambda t :> M(\vec{x}) \Rightarrow \lambda w; \sigma \vdash \Delta} \quad M = \lambda M'$$

$$\frac{\text{"}\Gamma \vdash t, u :> M_1(\vec{x}), M_2(\vec{x}) \Rightarrow w_1, w_2; \sigma \vdash \Delta\text{"}}{\Gamma \vdash t \ u :> M(\vec{x}) \Rightarrow w_1 \ w_2; \sigma \vdash \Delta} \quad M = M_1 \ M_2$$

# Non-cyclic unification of multi-terms

$$\Gamma \vdash u_1, \dots, u_n :> M_1(\vec{x}_1), \dots, M_n(\vec{x}_n) \Rightarrow w_1, \dots, w_n; \sigma \vdash \Delta$$

$\Gamma; (n_i) \vdash u_i$ 
 $(M_i : m_i) \notin \Gamma$ 
 $\Delta; m_i \vdash w_i$ 
 $\sigma : \Gamma \rightarrow \Delta$

## Formal meaning

$(\sigma, M_i(v_1, \dots, v_{m_i}) \mapsto w_i) = \text{most general unifier for}$

$$M_1(\vec{x}_1), \dots, M_n(\vec{x}_n) \stackrel{?}{=} u_1, \dots, u_n$$

# Sequential non-cyclic unification

$$\frac{\Gamma \vdash t_1 :> M_1(\vec{x}) \Rightarrow u_1; \sigma_1 \dashv \Delta_1 \quad \Delta_1 \vdash \vec{t}_2[\sigma_1] :> \vec{M}_2 \Rightarrow \vec{u}_2; \sigma_2 \dashv \Delta_2}{\Gamma \vdash t_1, \vec{t}_2 :> M_1(\vec{x}), \vec{M}_2 \Rightarrow u_1[\sigma_2], \vec{u}_2; \sigma_1[\sigma_2] \dashv \Delta_2}$$

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# Parameterisation by a *signature*

## Binding signature for pure $\lambda$ -calculus

$app : (0, 0)$        $abs : (1)$

number of bound variables in the argument

# Example: $M(\vec{x}) \stackrel{?}{=} o(\vec{t})$ , non-cyclic

$$o : (\alpha_1, \dots, \alpha_p)$$

$$\frac{\Gamma \vdash \vec{t} :> M_1(\vec{x}, \overbrace{v_{n+1}, \dots, v_{n+1+\alpha_1}}^{\text{bound variables}}), \dots, M_p(\dots) \Rightarrow \vec{u}; \sigma \vdash \Delta}{\Gamma \vdash o(\vec{t}) :> M(\vec{x}) \Rightarrow o(\vec{u}); \sigma \vdash \Delta}$$



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# Pure $\lambda$ -calculus as a functor

category of finite cardinals and injections between them



Pure  $\lambda$ -calculus as a functor  $\Lambda : \mathbb{F}_m \rightarrow \mathbf{Set}$

$$\Lambda_n = \{t \mid \cdot; n \vdash t\}$$

injective renaming

$$M(\vec{x})[\sigma] = \sigma_M \overbrace{[v_i \mapsto x_i]}$$

# Pure $\lambda$ -calculus as a fixpoint

$$\Lambda_n \cong \underbrace{\{1, \dots, n\}}_{\text{variables}} + \underbrace{\Lambda_n \times \Lambda_n}_{\text{application}} + \underbrace{\Lambda_{n+1}}_{\text{abstraction}}$$

In fact,

$$\Lambda = \mu X. F(X)$$



**Initial algebra** of the endofunctor  $F$  on  $[\mathbb{F}_m, \text{Set}]$

$$F(X)_n = \{0, \dots, n-1\} + X_n \times X_n + X_{n+1}$$

# Pure $\lambda$ -calculus extended with a metavariable $M : m$

$$\Lambda_n^{M:m} = \{t \mid M : m; n \vdash t\}$$

As an initial algebra:

$$\Lambda^{M:m} = \mu X. \underbrace{(F(X))}_{\text{operations / variables}} + \underbrace{\text{metavariables}}_{arg^M}$$

$$= \underbrace{T}_{\text{free monad generated by } F}(arg^M)$$

Pure  $\lambda$ -calculus extended with a metavariable  $M : m$ 

$$\mathit{arg}^M : \mathbb{F}_m \rightarrow \mathbf{Set}$$

$$\begin{aligned} \mathit{arg}^M_n &= \{M\text{-arguments in the variable context } \mathbf{n}\} \\ &= \{\text{choice of } m \text{ distinct variables in the context } \mathbf{n}\} \\ &= \mathbf{Inj}(m, n) \\ &= \mathbf{hom}_{\mathbb{F}_m}(m, n) = ym_n \end{aligned}$$

$$\Lambda^{M:m} = T(ym)$$

# Pure $\lambda$ -calculus with metavariables

Given a metavariable context  $\Gamma$ , define

$$\underline{\Gamma} := \coprod_{(M:m) \in \Gamma} ym$$

$$T(\underline{\Gamma})_n = \{t \mid \Gamma; n \vdash t\}$$

# Unification as a Kleisli coequaliser

## Claims<sup>1</sup>:

- $\text{hom}(yn, T\underline{\Gamma}) = \text{set of terms in context } \Gamma; n.$
- $\text{hom}(\underline{\Gamma}, T\underline{\Delta}) = \text{set of metavariable substitutions } \Gamma \rightarrow \Delta.$
- Most general unifier of  $t, u$ : coequaliser of  $yn \xRightarrow[t]{u} T\underline{\Gamma}$   
in  $\text{Th}^{op}(F) \subset \text{Kl}(T).$

Objects:  $\underline{\Gamma}, \underline{\Delta}, \dots$

"Lawvere theory"

<sup>1</sup>well-known in the first-order case.



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# Signature

- 1  $\mathcal{A}$  small category of contexts (e.g.,  $\mathbb{F}_m, 1$ )

**Intuition:** objects = metavariable arities,  
morphisms = metavariable arguments.

- All morphisms in  $\mathcal{A}$  are monic (pattern restriction).
- $\mathcal{A}$  has equalisers and pullbacks ( $M(\vec{x}) \stackrel{?}{=} N(\vec{y})$ ).

- 2  $F$  endofunctor on  $[\mathcal{A}, \text{Set}]$  of the shape

$$F(X)_a = \coprod_{o \in O_a} X_{L_{o,1}} \times \cdots \times X_{L_{o,n_o}}$$

such that  $F$  restricts to an endofunctor on functors preserving finite connected limits.

# Typing rules

## Notation

$$\underbrace{\Gamma; b \vdash u}_{M_1 : a_1, \dots, M_n : a_n} \quad \text{means} \quad u \in T(\underbrace{\Gamma}_{ya_1 + \dots + ya_n})_b$$

$$F(X)_a = \coprod_{o \in O_a} X_{L_{o,1}} \times \dots \times X_{L_{o,n_o}}$$

$$\frac{\Gamma; L_{o,i} \vdash t_i}{\Gamma; a \vdash o(\vec{t})} \text{RIGID} \qquad \frac{x \in \text{hom}_{\mathcal{A}}(a, b)}{\Gamma, M : a \quad ; \quad b \vdash M(x)} \text{FLEX}$$

No equation.

# Semantics of unification

**Claim:** Given a signature  $(\mathcal{A}, F)$ , a coequaliser diagram in  $\text{Th}^{op}(F)$  has a colimit as soon as there exists a cocone (i.e., a ‘unifier’).

**Proof:** By describing a unification algorithm.

End of this section: soundness proofs for 3 rules.

# Interpreting the unification statements

## Notations

$$\Gamma \vdash t = u \Rightarrow \sigma \dashv \Delta \Leftrightarrow \cdot \begin{array}{c} \xrightarrow{t} \\ \xrightarrow{u} \end{array} \Gamma - \frac{\sigma}{\cdot} \gg \Delta \quad \text{coequaliser}$$

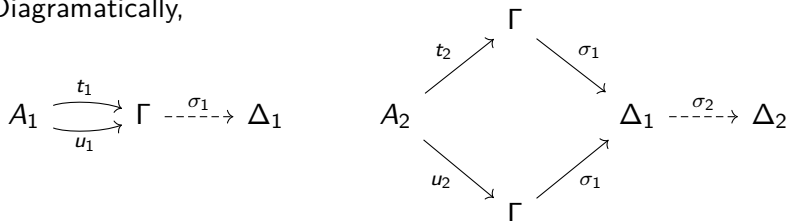
$$\Gamma \vdash t :> f \Rightarrow v; \sigma \dashv \Delta \Leftrightarrow \begin{array}{ccc} \cdot & \xrightarrow{f} & \cdot \\ t \downarrow & & \downarrow v \\ \Gamma - \frac{\sigma}{\cdot} & \gg & \Delta \end{array} \quad \text{pushout}$$

mostly used in  $\text{Th}^{op}(F)_{\perp} = \text{Th}^{op}(F) + \text{a free terminal object } \perp$ .

# Soundness of U-SPLIT [Rydeheard-Burstall '88]

$$\frac{\Gamma \vdash t_1 = u_1 \Rightarrow \sigma_1 \dashv \Delta_1 \quad \Delta_1 \vdash t_2[\sigma_1] = u_2[\sigma_1] \Rightarrow \sigma_2 \dashv \Delta_2}{\Gamma \vdash t_1, t_2 = u_1, u_2 \Rightarrow \sigma_1[\sigma_2] \dashv \Delta_2} \text{U-SPLIT}$$

Diagrammatically,



$$A_1 + A_2 \xRightarrow[u_1, u_2]{t_1, t_2} \Gamma \xRightarrow{\sigma_2 \circ \sigma_1} \Delta_2$$

# Soundness of U-FLEXFLEX

$$\frac{b \vdash x =_{\mathcal{A}^{op}} y \Rightarrow z \vdash c}{M : b \vdash M(x) = M(y) \Rightarrow M \mapsto M'(z) \vdash M' : c} \text{U-FLEXFLEX}$$

Diagrammatically,

$$\frac{a \xRightarrow[x]{y} b - \frac{z}{\phantom{z}} \succ c \quad \text{in } \mathcal{A}^{op}}{\mathcal{L}a \xRightarrow[\mathcal{L}y]{\mathcal{L}x} \mathcal{L}b - \frac{\mathcal{L}z}{\phantom{\mathcal{L}z}} \succ \mathcal{L}c \quad \text{in } \text{Th}^{op}(F)}$$

where

$$a \xrightarrow{x} b \quad \xrightarrow{\mathcal{L} : \mathcal{A}^{op} \rightarrow \text{Th}^{op}(F)} \quad ya \xrightarrow{"M(x)"} T(\underline{M : b})$$

# Soundness of U-NoCYCLE

$$\frac{u|_{\Gamma} = \underline{u'} \quad \Gamma \vdash u' :> M(x) \Rightarrow v; \sigma \vdash \Delta}{\Gamma, M : b \vdash M(x) = u \Rightarrow \sigma, M \mapsto v \vdash \Delta} \text{U-NoCYCLE}$$

Diagrammatically,

$$\begin{array}{ccc} ya & \xrightarrow{"M(x)"} & yb \\ u' \downarrow & & \downarrow v \\ \Gamma - \frac{}{\sigma} & \gg & \Delta \end{array} \quad \text{pushout}$$

$$\begin{array}{ccccc} & & yb & & \\ & \nearrow^{"}M(x)"} & & \searrow_{in_2} & \\ ya & & & & \Gamma + yb \frac{[v, \sigma]}{-} \gg \Delta \\ & \searrow_{u'} & & \nearrow_{in_1} & \\ & & \Gamma & & \end{array} \quad \text{coequaliser}$$



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# Types

## Notation

$n \vdash \tau$  type    $\Leftrightarrow$    the type  $\tau$  is wellformed in context  $n$

$$\frac{1 \leq i \leq n}{n \vdash \eta_i \text{ type}} \text{TYPE-VAR} \qquad \frac{n + 1 \vdash \tau \text{ type}}{n \vdash \forall \tau \text{ type}} \text{FORALL}$$

$$\frac{n \vdash \tau_1, \tau_2 \text{ type}}{n \vdash \tau_1 \rightarrow \tau_2 \text{ type}} \text{ARROW}$$

# Metavariable arities

## Metavariable application

$$M(\overbrace{\alpha_1, \dots, \alpha_p}^{\text{type variables}} \mid \overbrace{x_1, \dots, x_q}^{\text{"ground" variables}})$$

$$M : (p \mid \overbrace{\tau_1, \dots, \tau_q}^{p \vdash \tau_i \text{ type}} \vdash \tau_f)$$

input argument types

number of type variable arguments

output type

# Signature

- Objects of  $\mathcal{A}$  = metavariables arities

$$n|\vec{\tau} \vdash \sigma_f$$

- Endofunctor  $F$  on  $[\mathcal{A}, \text{Set}]$  s.t.

$$\mu F(n|\vec{\tau} \vdash \sigma_f) = \{t \text{ s.t. } n|\vec{\tau} \vdash t : \sigma_f\}$$

# The endofunctor for System $F$

Typing rule	$F(X)_n   \vec{\tau} \vdash \sigma_f = \coprod \dots$
$\frac{\tau_i = \sigma_f}{n   \vec{\tau} \vdash v_i : \sigma_f} \text{VAR}$	$ \vec{\tau} _{\sigma_f}$
$\frac{n   \vec{\tau}, \sigma_1 \vdash t : \sigma_2}{n   \vec{\tau} \vdash \lambda t : \sigma_1 \rightarrow \sigma_2} \text{ABS}$	$\coprod_{\sigma_1, \sigma_2 \text{ s.t. } \sigma_f = (\sigma_1 \rightarrow \sigma_2)} X_{n   \vec{\tau}, \sigma_1 \vdash \sigma_2}$
$\frac{n   \vec{\tau} \vdash t : \sigma \rightarrow \sigma_f \quad n   \vec{\tau} \vdash u : \sigma_f}{n   \vec{\tau} \vdash t u : \sigma_f} \text{APP}$	$\coprod_{\sigma} X_{n   \vec{\tau} \vdash \sigma \rightarrow \sigma_f} \times X_{n   \vec{\tau} \vdash \sigma}$
$\frac{n + 1   \vec{\tau} \vdash t : \sigma}{n   \vec{\tau} \vdash \Lambda t : \forall \sigma} \text{T-ABS}$	$\coprod_{\sigma \text{ s.t. } \sigma_f = \forall \sigma} X_{n+1   \vec{\tau} \vdash \sigma}$
$\frac{n   \vec{\tau} \vdash t : \forall \sigma_1}{n   \vec{\tau} \vdash t \cdot \sigma_2 : \sigma_1[\sigma_2]} \text{T-APP}$	$\coprod_{\sigma_1, \sigma_2 \text{ s.t. } \sigma_f = \sigma_1[\sigma_2]} X_{n   \vec{\tau} \vdash \forall \sigma_1}$

# Unification in system F: an example

$$M(\vec{\alpha}|\vec{x}) \stackrel{?}{=} M(\vec{\beta}|\vec{y})$$

Most general unifier

$$M(\eta_1, \dots, \eta_p | v_1, \dots, v_m) \mapsto N(\vec{\gamma} | \vec{z})$$

where  $\vec{\gamma}$  and  $\vec{z}$  are vectors of common positions

$$\alpha_{\vec{\gamma}} = \beta_{\vec{\gamma}}$$

$$x_{\vec{z}} = y_{\vec{z}}$$

# Summary of the generic unification algorithm

$$\overline{\Gamma \vdash () = () \Rightarrow id_{\Gamma} \dashv \Gamma} \quad \overline{\perp \vdash \vec{t} = \vec{u} \Rightarrow ! \dashv \perp}$$

$$\frac{\Gamma \vdash t_1 = u_1 \Rightarrow \sigma_1 \dashv \Delta_1 \quad \Delta_1 \vdash \vec{t}_2[\sigma_1] = \vec{u}_2[\sigma_1] \Rightarrow \sigma_2 \dashv \Delta_2}{\Gamma \vdash t_1, \vec{t}_2 = u_1, \vec{u}_2 \Rightarrow \sigma_1[\sigma_2] \dashv \Delta_2} \text{U-SPLIT}$$

$$\frac{\Gamma \vdash \vec{t} = \vec{u} \Rightarrow \sigma \dashv \Delta}{\Gamma \vdash o(\vec{t}) = o(\vec{u}) \Rightarrow \sigma \dashv \Delta} \text{U-RIGRIG} \quad \frac{o \neq o'}{\Gamma \vdash o(\vec{t}) = o'(\vec{u}) \Rightarrow ! \dashv \perp}$$

$$\frac{u|_{\Gamma} = u' \quad \Gamma \vdash u' :> M(x) \Rightarrow v; \sigma \dashv \Delta}{\Gamma, M : b \vdash M(x) = u \Rightarrow \sigma, M \mapsto v \dashv \Delta} \text{U-NOCYCLE} + \text{sym}$$

$$\frac{b \vdash x =_{\mathcal{A}^{op}} y \Rightarrow z \dashv c}{\Gamma, M : b \vdash M(x) = M(y) \Rightarrow M \mapsto M'(z) \dashv \Gamma, M' : c} \text{U-FLEXFLEX}$$

$$\frac{u = o(\vec{t}) \quad u|_{\Gamma} \neq \dots}{\Gamma, M : b \vdash M(x) = u \Rightarrow ! \dashv \perp} \text{U-CYCLIC} + \text{sym}$$

# Non cyclic phase

$$\overline{\Gamma \vdash () :> () \Rightarrow (); id_{\Gamma} \dashv \Gamma} \quad \overline{\perp \vdash \vec{t} :> \vec{f} \Rightarrow !; ! \dashv \perp}$$

$$\frac{\Gamma \vdash t_1 :> M_1(\vec{x}) \Rightarrow u_1; \sigma_1 \dashv \Delta_1 \quad \Delta_1 \vdash \vec{t}_2[\sigma_1] :> \vec{M}_2 \Rightarrow \vec{u}_2; \sigma_2 \dashv \Delta_2}{\Gamma \vdash t_1, \vec{t}_2 :> M_1(\vec{x}), \vec{M}_2 \Rightarrow u_1[\sigma_2], \vec{u}_2; \sigma_1[\sigma_2] \dashv \Delta_2}$$

$$\frac{c \vdash_{\mathcal{A}^{op}} y :> x \Rightarrow l; r \dashv d}{\Gamma, M : c \vdash M(y) :> N(x) \Rightarrow M'(l); M \mapsto M'(r) \dashv \Gamma, M' : d} \text{P-FLEX}$$

$$\frac{\Gamma \vdash \vec{t} :> \mathcal{L}^+ x^o \Rightarrow \vec{u}; \sigma \dashv \Delta \quad o = x \cdot o'}{\Gamma \vdash o(\vec{t}) :> N(x) \Rightarrow o'(\vec{u}); \sigma \dashv \Delta}$$

$$\frac{o \neq x \cdot \dots}{\Gamma \vdash o(\vec{t}) :> N(x) \Rightarrow !; ! \dashv \perp}$$



# Pruning $o(\vec{t})$ : variable case

$o$  is a variable  $\Rightarrow \vec{t} = ()$ .

$$\begin{array}{c}
 \frac{\Gamma \vdash \overbrace{\vec{t}}^{()} :> \dots \quad \overbrace{o = x_{o'}}^{o = \vec{x} \cdot o'}}{\Gamma \vdash o(\vec{t}) :> N(\vec{x}) \Rightarrow o'(\vec{u}); \sigma \vdash \Delta} \Leftrightarrow \frac{o = x_i}{\Gamma \vdash o :> N(\vec{x}) \Rightarrow i; id_{\Gamma} \vdash \Gamma} \\
 \\
 \frac{o \neq x \cdot \dots}{\Gamma \vdash o(\vec{t}) :> N(x) \Rightarrow !; ! \vdash \perp} \Leftrightarrow \frac{o \notin \vec{x}}{\Gamma \vdash o :> N(\vec{x}) \Rightarrow !; ! \vdash \perp}
 \end{array}$$

# Pruning $o(\vec{t})$ : operation case

Assume  $o : (\alpha_1, \dots, \alpha_p)$

$$\frac{\Gamma \vdash \vec{t} :> \overbrace{\mathcal{L}^+ x^o}^{M_1(\vec{x}, n, \dots, n+\alpha_1-1), \dots, M_p(\dots)} \Rightarrow \vec{u}; \sigma \vdash \Delta \quad \overbrace{o = o'}^{o = x \cdot o'}}{\Gamma \vdash o(\vec{t}) :> N(x) \Rightarrow o'(\vec{u}); \sigma \vdash \Delta}$$

$$\frac{o \neq x \cdot \dots}{\Gamma \vdash o(\vec{t}) :> N(x) \Rightarrow !; ! \vdash \perp} \quad \text{never applies}$$

# Typing rule for metavariables

## Typing judgement

$$\underbrace{\Gamma}_{\text{Metavariable context}} ; \underbrace{n}_{\text{Type variable context}} \mid \underbrace{t_1, \dots, t_m \vdash u : t_f}_{\substack{\text{Types of variables} \\ n \vdash t_i \text{ type}}}$$

## Typing metavariables

$$\frac{0 < \overbrace{\alpha_1, \dots, \alpha_p}^{\text{distinct}} \leq n \quad 0 < \overbrace{x_1, \dots, x_q}^{\text{distinct}} \leq m \quad \tau_i[\vec{\alpha}] = t_{x_i}}{\Gamma, M : (p \mid \tau_1, \dots, \tau_q \vdash \tau_f) ; n \mid t_1, \dots, t_m \vdash M(\underbrace{\vec{\alpha}}_{\text{type variables}} \mid \vec{x}) : \tau_f[\vec{\alpha}]}$$

# Future directions

- Implementation
  - logic programming
  - verified in Coq/Agda  
(needs rephrasing using structural recursion)
- Unification modulo reduction
- Efficient pattern unification [Qian '96]
- Anti-unification