

MaNo : Exploiting Matrix Norm for Unsupervised Accuracy Estimation

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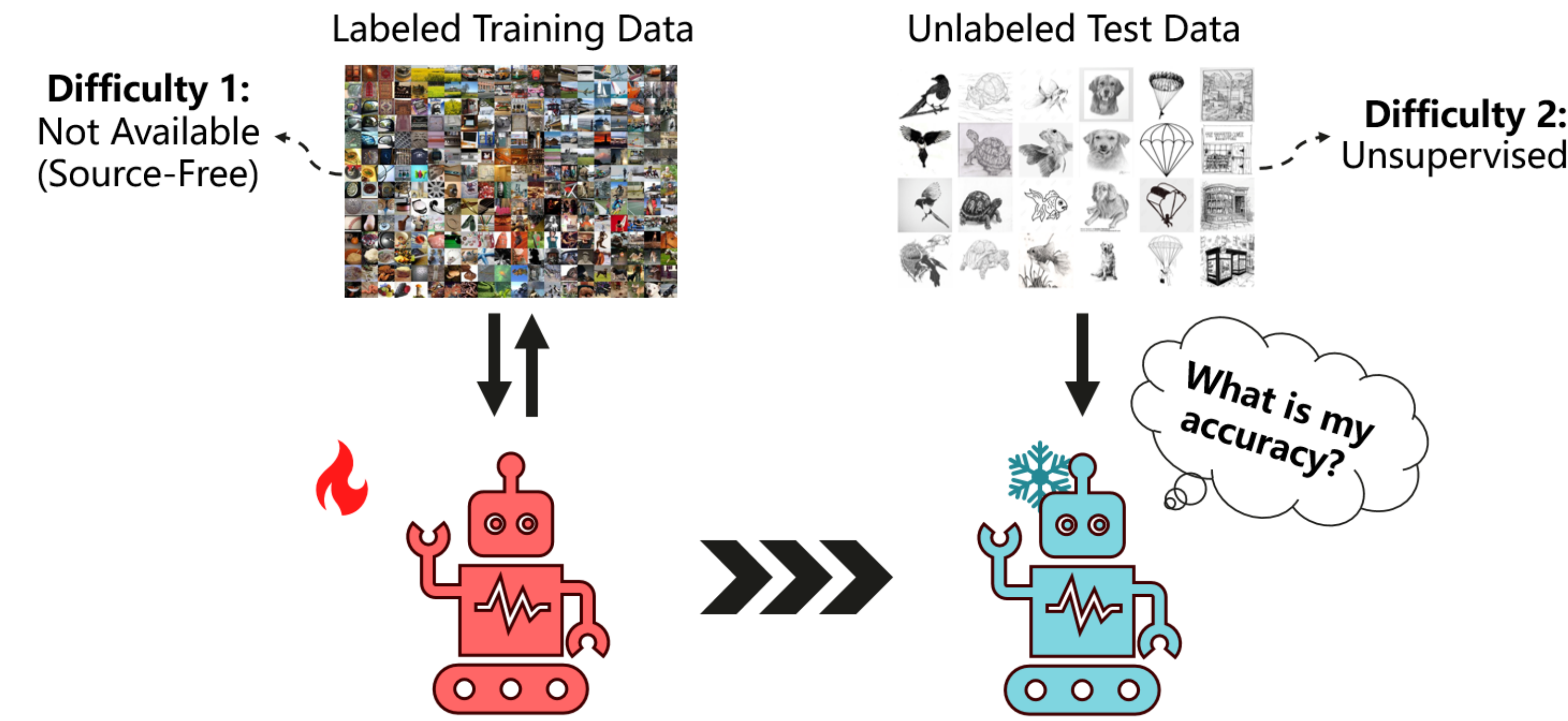
TL;DR

- Predicting generalization performance under distribution shifts is challenging
- Most methods use logits without dealing with miscalibration cases
- We propose **MaNo**, a **theoretically grounded** estimation approach
- It automatically takes into account miscalibration scenarios
- It can be applied to ResNets, ConvNext, and ViT architectures
- Benefits: **SOTA, efficient, architecture agnostic, robust**

Problem Setup

Goal: given a pre-trained model f , predicts its performance on a test set $\mathcal{D}_{\text{test}}$.

- Takes as input a pre-trained model f and test data $\mathcal{D}_{\text{test}}$.
- Distribution shifts, i.e., $p_S \neq p_T$ where training data $\sim p_S$ and test data $\sim p_T$.
- Outputs an estimation score $\mathcal{S}(f, \mathcal{D}_{\text{test}})$ linearly correlated with the true accuracy.

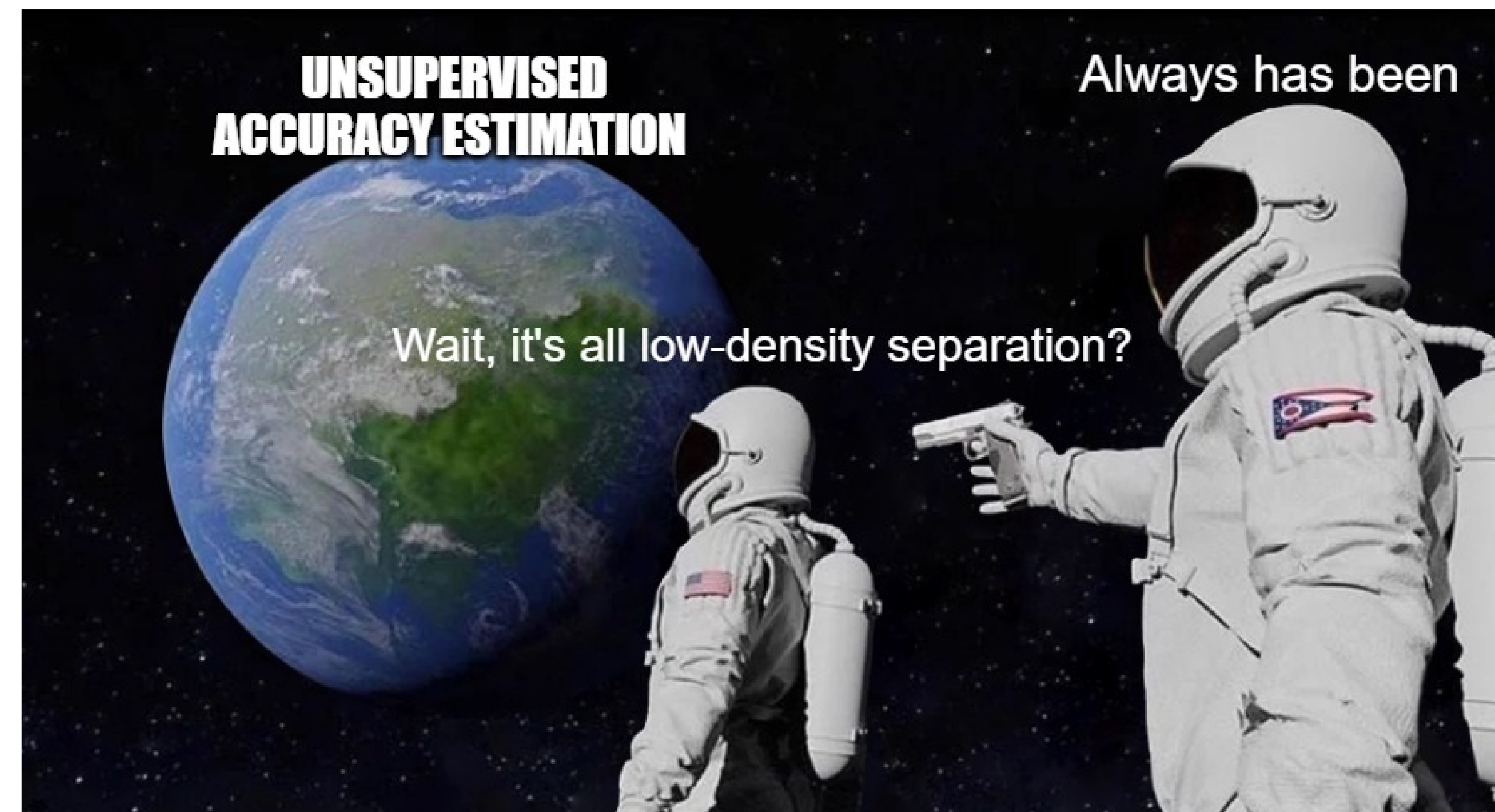


This is a challenging task often occurring in real-world scenarios.

Motivation

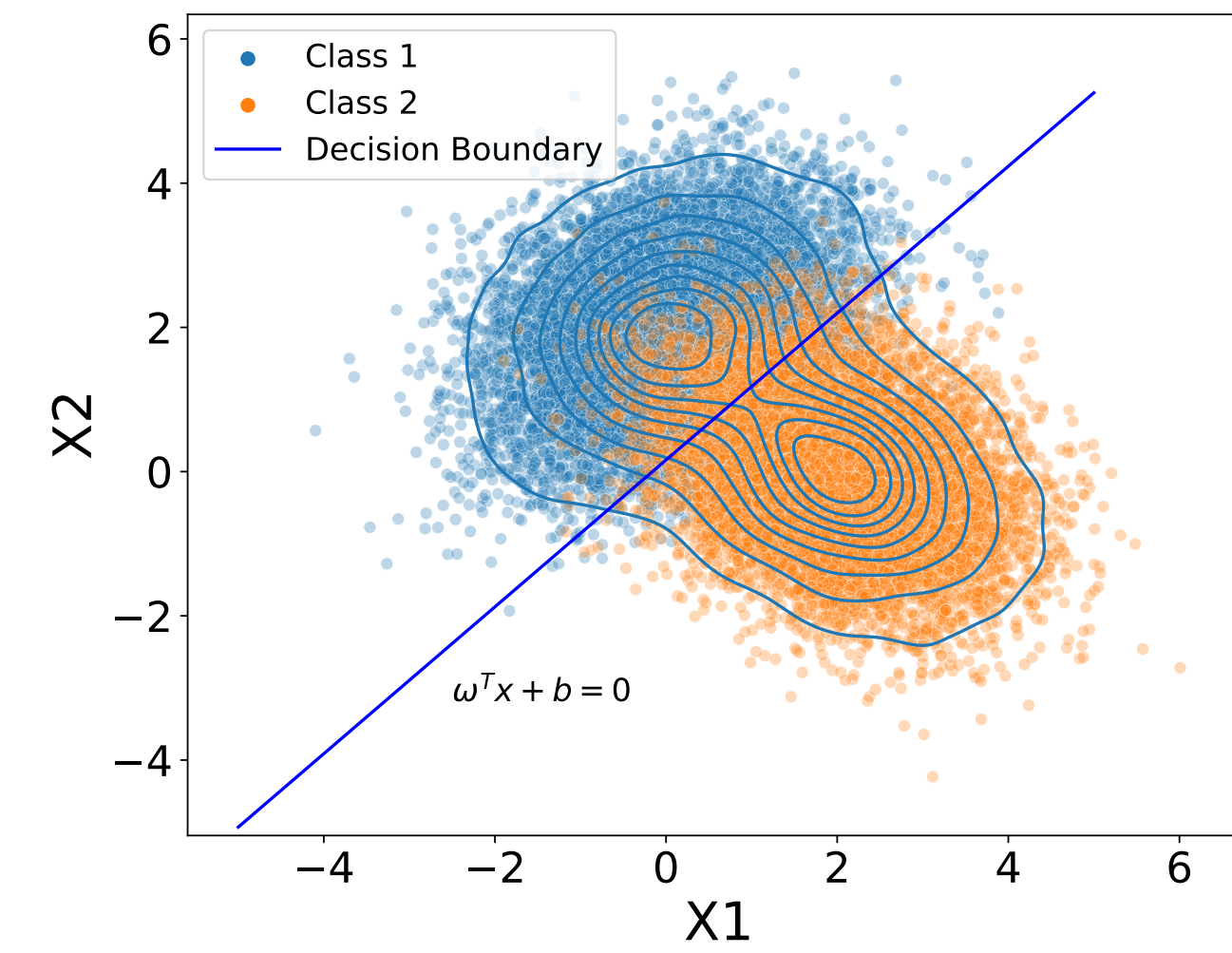
Question 1: Why are logits informative of generalization performance?

Question 2: How to alleviate the overconfidence issues of logits-based methods?

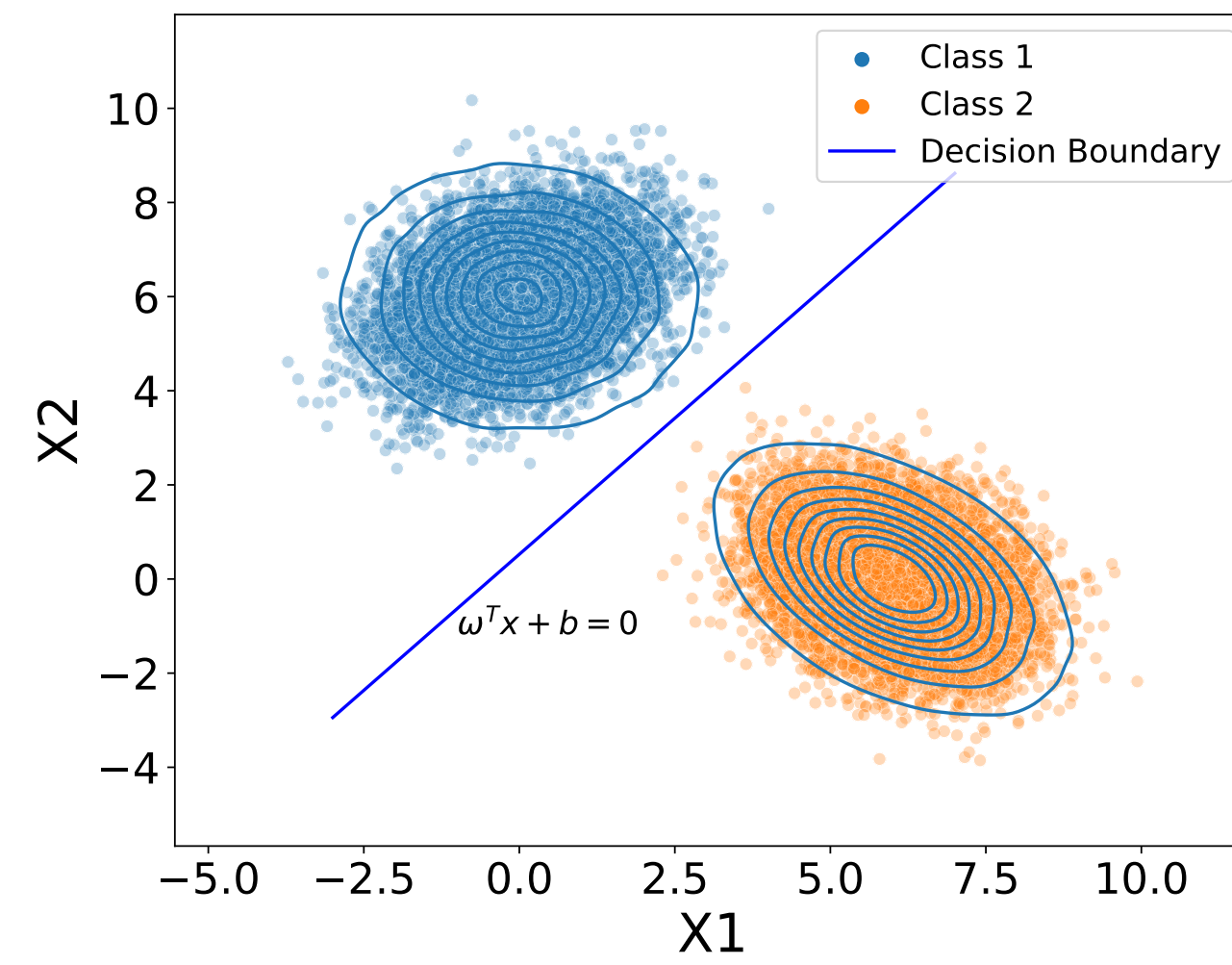


Logits Reflect Distances to Decision Boundaries

- Decision boundary of class k is the hyperplane $\{\mathbf{z}' \in \mathbb{R}^q | \omega_k^\top \mathbf{z}' = 0\}$,
- Distance from a point \mathbf{z} this hyperplane is $d(\omega_k, \mathbf{z}) = |\omega_k^\top \mathbf{z}| / \|\omega_k\|$,
- Logits reflects decision to decision boundary as $|\mathbf{q}_k| = |\omega_k^\top \mathbf{z}| \propto d(\omega_k, \mathbf{z})$,
- Low-density assumption:** misclassified samples are closer to decision boundaries.



High-density region



Low-density region

Logits (in absolute values) positively correlated to generalization performance.

Experimental Results: Better, Faster, Stronger

- Comparison between **MaNo** and its competitors with metrics ρ and R^2 ,
- Comparison across several architectures: ResNets, ConvNext, ViT,
- Extensive evaluation with common benchmarks on various distribution shifts.

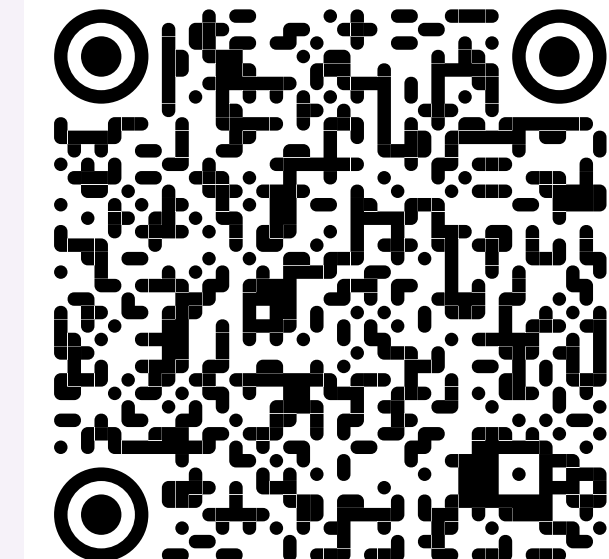
Shift	MaNo	COT	MDE	Nuclear	Dispersion	ProjNorm
	-	2024	2024	2023	2023	2022
Synthetic	0.991	0.988	0.947	0.982	0.960	971
Subpopulation	0.983	0.962	0.920	0.973	0.909	897
Natural	0.905	0.871	0.436	0.455	0.410	382
Overall improvement	2%	25%	6%	26%	28%	

MaNo outperforms all the baselines while being training-free.

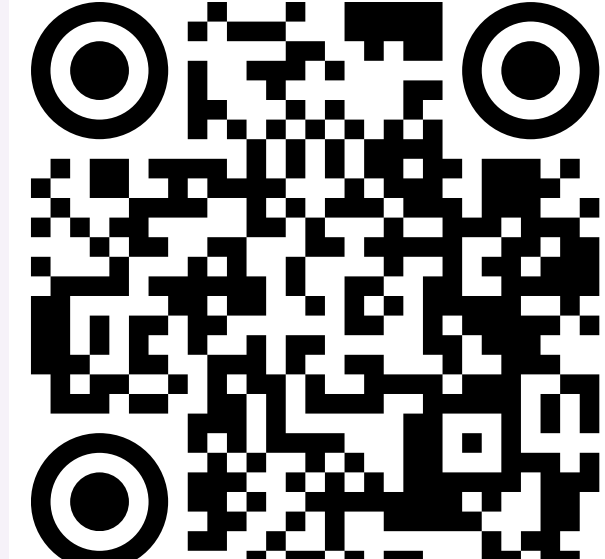
Main References

- Odonnat et al. - AISTATS 2023
T-similarity
- Deng et al. - ICML 2023
Nuclear
- Xie et al. - NeurIPS 2024 (this work)
MaNo

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MANo: A Simple Three-Step Recipe

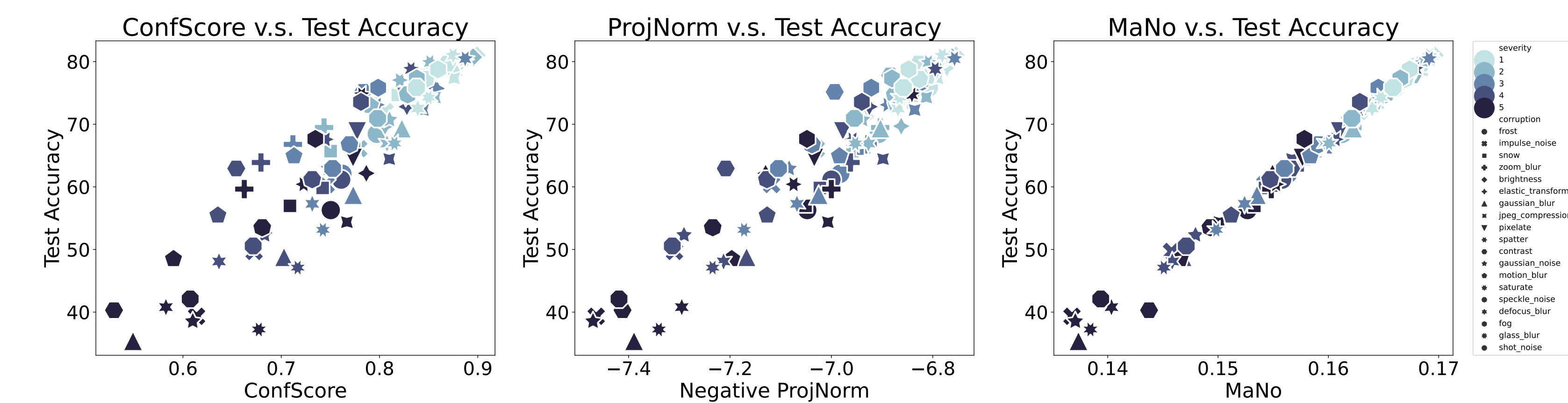
- Input:** Pre-trained model f , test dataset $\mathcal{D}_{\text{test}} = \{\mathbf{x}_i\}_{i=1}^N$.
- Inference:** Recover logits $\mathbf{q}_i = f(\mathbf{x}_i)$.
- Criterion:** $\Phi(\mathcal{D}_{\text{test}}) = \text{KL}(\text{uniform} || \text{softmax proba})$

$$1) \quad v(\mathbf{q}_i) = \begin{cases} 1 + \mathbf{q}_i + \frac{\mathbf{q}_i^2}{2}, & \text{if } \Phi(\mathcal{D}_{\text{test}}) \leq \eta \\ \exp(\mathbf{q}_i), & \text{if } \Phi(\mathcal{D}_{\text{test}}) > \eta \end{cases}$$

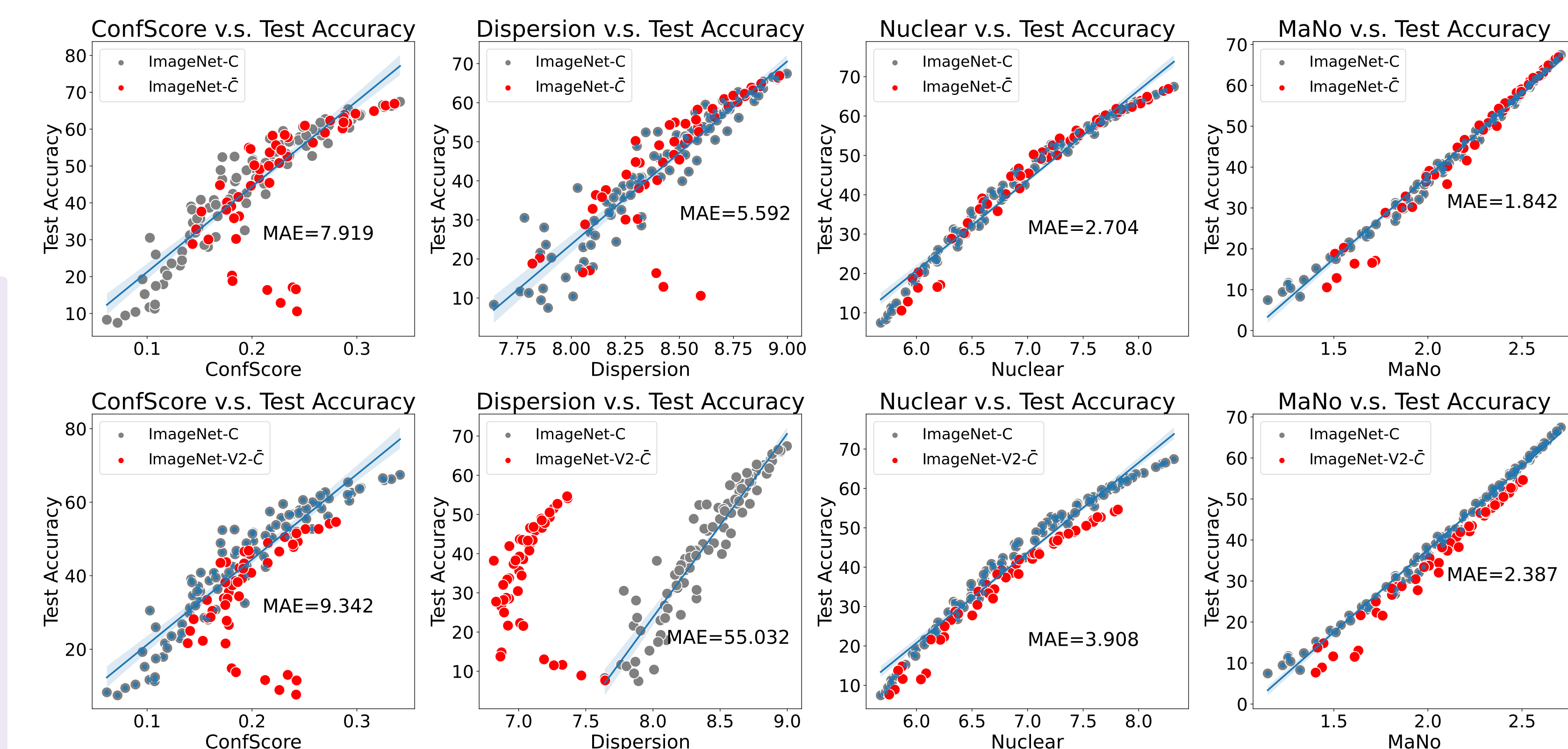
$$2) \quad \sigma(\mathbf{q}_i) = \frac{v(\mathbf{q}_i)}{\sum_{k=1}^K v(\mathbf{q}_i)_k} \in \Delta_K$$

$$3) \quad \mathcal{S}(f, \mathcal{D}_{\text{test}}) = \frac{1}{\sqrt[p]{NKK}} \|\mathbf{Q}\|_p = \left(\frac{1}{NK} \sum_{i=1}^N \sum_{k=1}^K |\sigma(\mathbf{q}_i)_k|^p \right)^{\frac{1}{p}}$$

MaNo is simple yet efficient and theoretically grounded as we prove that it captures the model's uncertainty.



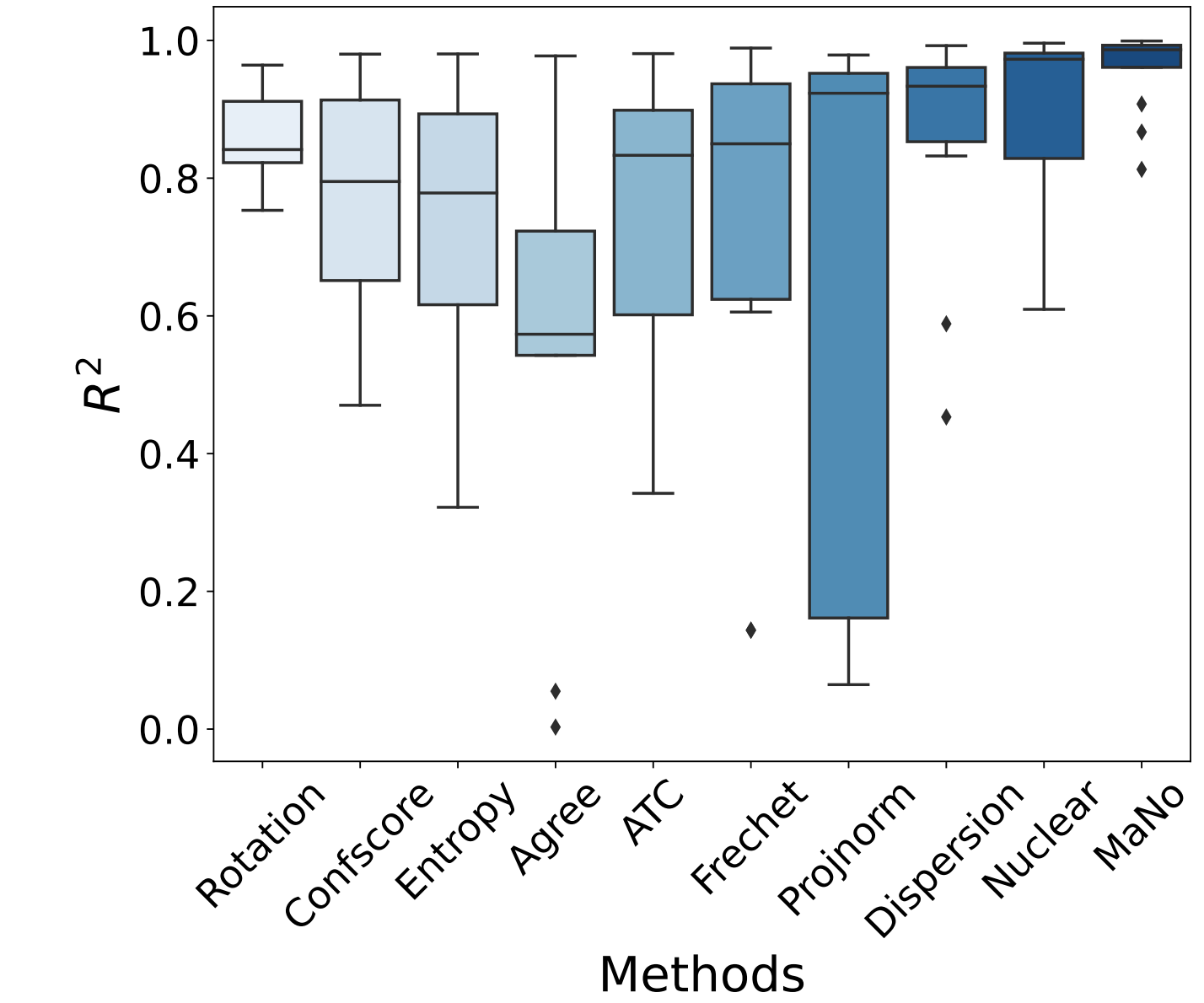
MaNo linearly correlates with ground-truth test accuracy on Entity-18.



MaNo significantly surpasses its competitors on variants of ImageNet.

Robustness Comparison

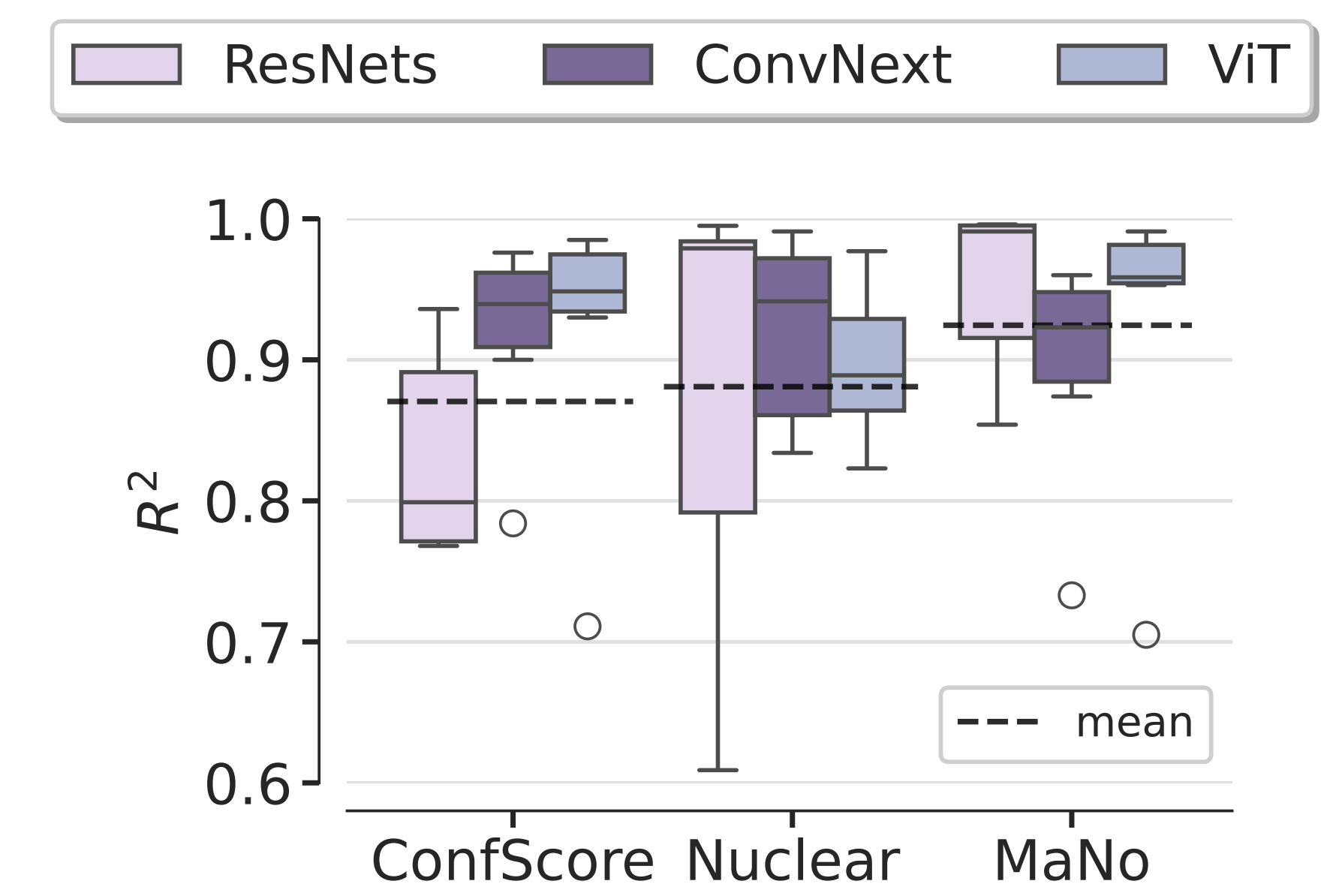
We compare our method with its competitors on all the distribution shifts.



Overall, **MaNo** leads to the best and most robust estimations.!

Beyond ResNets: ConvNext and Vision Transformers

To ensure the efficiency and versatility of **MaNo**, we apply it to 2 other SOTA architectures.



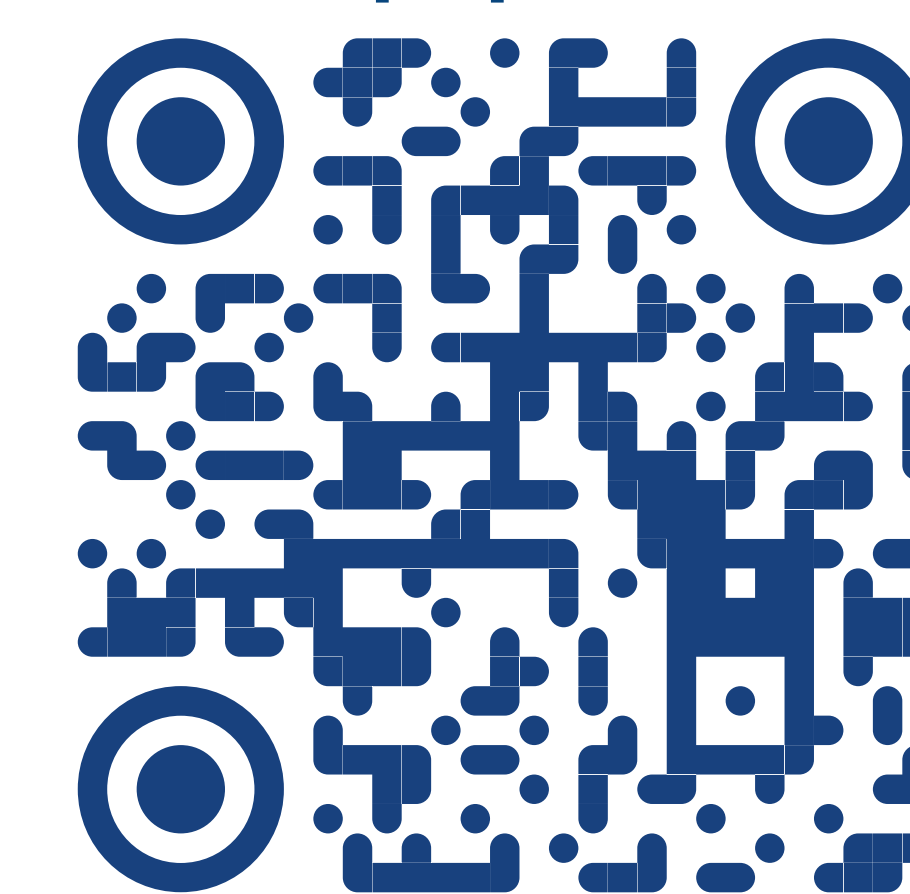
MaNo is the best approach with SOTA architectures!

Take Home Message

Predicting generalization performance under distribution shifts is challenging.
→ Start using **MaNo** for an **efficient** and **accurate** estimation!

Want to Know More?

paper



code

