

Lecture 6: Proof of The Upper Bound for Thompson Sampling with Beta Priors and Bernoulli Rewards

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1 Thompson Sampling with Beta Priors and Bernoulli Rewards

1.1 Algorithm Description And Theorem Statement

Recall from last lecture:

Algorithm 1 Thompson Sampling for Bernoulli Bandits

- 1: Using beta distribution as prior.
 - 2: For each arm $a \in \mathcal{A}$, $S_a = F_a = 0$.
 - 3: **for** $t=1, 2, \dots$, **do**
 - 4: For each $a \in \mathcal{A}$, sample $\theta_{a,t} \sim \text{Beta}(S_a + 1, F_a + 1)$.
 - 5: Play arm $A_t = \arg\max_{a \in \mathcal{A}} \theta_{a,t}$ and collect reward R_t .
 - 6: If $R_t = 1$, $S_{A_t} = S_{A_t} + 1$. Else if $R_t = 0$, $F_{A_t} = F_{A_t} + 1$.
 - 7: **end for**
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This algorithm dates back to 1933 [Tho33], but the first finite time regret analysis appeared only in 2012 [AG12]. Our presentation of TS and its proof will follow a later paper [AG13].

Theorem 1. Assume Bernoulli reward distributions for the K arms with means μ_0, \dots, μ_{K-1} , where $\mu_0 > \max_{a \geq 1} \mu_a$. Then for any ε ,

$$R_T(\text{TS with Beta}, (\mathcal{D}_a)_{a \in \mathcal{A}}) \leq (1 + \varepsilon) \sum_{a=1}^{K-1} \frac{\log T}{d(\mu_a, \mu_0)} \Delta_a + O\left(\frac{K}{\varepsilon^2}\right)$$

where $d(\mu_a, \mu_0) := \mu_a \log \frac{\mu_a}{\mu_0} + (1 - \mu_a) \log \frac{1 - \mu_a}{1 - \mu_0}$.

Note: By Pinsker's inequality, $d(\mu_a, \mu_0) \geq 2(\mu_a - \mu_0)^2 = 2\Delta_a^2$. The upper bound for UCB is worse than that of TS due to this inequality.

1.2 Notation and comments

- $\theta_{a,t}$: draw from arm a 's posterior at time t .
- $S_{a,t}$: the number of successes (i.e., ones) of arm a up to and including time t .
- $F_{a,t}$: the number of failures (i.e., zeroes) of arm a up to and including time t .
- Note that $S_{a,t} + F_{a,t} = N_t(a)$, which is the number of times that arm a is selected up to and including time t .
- $\hat{\mu}_{a,t-1} = \frac{\sum_{i=1, A_i=a}^{t-1} R_i}{N_{t-1}(a)+1} = \frac{S_{a,t-1}}{N_{t-1}(a)+1}$

- Note that 1 is added to the denominator on purpose to prevent division by zero.
- For each a and any $\varepsilon > 0$, we will introduce thresholds x_a, y_a satisfying following conditions.
 - $\mu_a < x_a < y_a < \mu_0$
 - $d(x_a, \mu_0) = \frac{d(\mu_a, \mu_0)}{1+\varepsilon}$
 - $d(x_a, y_a) = \frac{d(x_a, \mu_0)}{1+\varepsilon} = \frac{d(\mu_a, \mu_0)}{(1+\varepsilon)^2}$
 - Note that we can always choose such thresholds due to the continuity of KL-divergence.
- $\mathcal{H}_t = \{A_1, R_1, \dots, A_{t-1}, R_{t-1}\}$ history of actions and rewards *before* time t .
 - For consistency, we use t for the subscript instead of $t-1$.
- We introduce two events.
 - $E_{a,t}^\mu = \{\hat{\mu}_{a,t-1} \leq x_a\}$
 - $E_{a,t}^\theta = \{\theta_{a,t} \leq y_a\}$
 - The idea is that these two events are more likely to happen as time progresses.
 - Note that given \mathcal{H}_t , $E_{a,t}^\mu$ is determined to be either true or false and $E_{a,t}^\theta$ is still random, but the probability that it happens can be exactly calculated.
- $p_{a,t} := \mathbb{P}(\theta_{0,t} > y_a | \mathcal{H}_t)$

1.3 Key Lemma

Lemma 2. For all t and $a \neq 0$,

$$\mathbb{P}(A_t = a, E_{a,t}^\mu, E_{a,t}^\theta | \mathcal{H}_t) \leq \frac{1-p_{a,t}}{p_{a,t}} \mathbb{P}(A_t = 0, E_{a,t}^\mu, E_{a,t}^\theta | \mathcal{H}_t)$$

Note: We expect $\frac{1-p_{a,t}}{p_{a,t}}$ to be very small.

Proof. Note that $E_{a,t}^\mu$ is fixed given \mathcal{H}_t and there is nothing to prove when it does not happen. From now on, we will assume this event happened. Using Bayes rule, we get:

$$\begin{aligned} \text{LHS} &= \mathbb{P}(A_t = a, E_{a,t}^\theta | \mathcal{H}_t) \\ &= \mathbb{P}(A_t = a | E_{a,t}^\theta, \mathcal{H}_t) \mathbb{P}(E_{a,t}^\theta | \mathcal{H}_t) \\ \text{RHS} &= \frac{1-p_{a,t}}{p_{a,t}} \mathbb{P}(A_t = 0 | E_{a,t}^\theta, \mathcal{H}_t) \mathbb{P}(E_{a,t}^\theta | \mathcal{H}_t). \end{aligned}$$

Thus it suffices to prove that $\mathbb{P}(A_t = a | E_{a,t}^\theta, \mathcal{H}_t) \leq \frac{1-p_{a,t}}{p_{a,t}} \mathbb{P}(A_t = 0 | E_{a,t}^\theta, \mathcal{H}_t)$. Given $E_{a,t}^\theta$, $\{A_t = a\}$ implies that $\theta_{\tilde{a},t} \leq y_a$ for any $\tilde{a} \in \mathcal{A}$. Therefore,

$$\begin{aligned} \text{LHS} &\leq \mathbb{P}(\forall \tilde{a} \in \mathcal{A}, \theta_{\tilde{a},t} \leq y_a | E_{a,t}^\theta, \mathcal{H}_t) \\ &= \mathbb{P}(\theta_{0,t} \leq y_a | E_{a,t}^\theta, \mathcal{H}_t) \mathbb{P}(\forall \tilde{a} \neq 0, \theta_{\tilde{a},t} \leq y_a | E_{a,t}^\theta, \mathcal{H}_t) \\ &= (1-p_{a,t}) \mathbb{P}(\forall \tilde{a} \neq 0, \theta_{\tilde{a},t} \leq y_a | E_{a,t}^\theta, \mathcal{H}_t) \end{aligned}$$

The last equality holds because the event $\{\theta_{a,t} \leq y_a\}$ is independent of $E_{a,t}^\theta$. Similarly, given $E_{a,t}^\theta$, $\{A_t = 0\}$ happens whenever $\theta_{0,t} > y_a$ and $\theta_{\tilde{a},t} \leq y_a$ for any $\tilde{a} \neq 0$. This gives us

$$\begin{aligned} \text{RHS} &\geq \frac{1 - p_{a,t}}{p_{a,t}} \mathbb{P}(\theta_{0,t} > y_a, \theta_{\tilde{a},t} \leq y_a \forall \tilde{a} \neq 0 | E_{a,t}^\theta, \mathcal{H}_t) \\ &= (1 - p_{a,t}) \mathbb{P}(\forall \tilde{a} \neq 0, \theta_{\tilde{a},t} \leq y_a | E_{a,t}^\theta, \mathcal{H}_t) \end{aligned}$$

The above two inequalities complete the proof of the key lemma. \square

1.4 (Incomplete) Proof of Theorem

We will start by rewriting $N_T(a)$ as the sum of indicator variables and taking expectation.

$$\begin{aligned} \mathbb{E}N_T(a) &= \sum_{t=1}^T \mathbb{P}(A_t = a) \\ &= \sum_{t=1}^T [\mathbb{P}(A_t = a, E_{a,t}^\mu, E_{a,t}^\theta) + \mathbb{P}(A_t = a, E_{a,t}^\mu, \overline{E_{a,t}^\theta}) + \mathbb{P}(A_t = a, \overline{E_{a,t}^\mu})] \\ &= S_1 + S_2 + S_3 \end{aligned}$$

In this (incomplete) proof, we will focus on S_1 only. We will control S_2 and S_3 in the next lecture. To impose an upper bound, we will use the tower property of expectation several times.

$$\begin{aligned} \mathbb{P}(A_t = a, E_{a,t}^\mu, E_{a,t}^\theta) &= \mathbb{E}[\mathbb{P}(A_t = a, E_{a,t}^\mu, E_{a,t}^\theta | \mathcal{H}_t)] (\because \text{tower property}) \\ &\leq \mathbb{E}\left[\frac{1 - p_{a,t}}{p_{a,t}} \mathbb{P}(A_t = 0, E_{a,t}^\mu, E_{a,t}^\theta | \mathcal{H}_t)\right] (\because \text{key lemma}) \\ &= \mathbb{E}\left[\mathbb{E}\left[\frac{1 - p_{a,t}}{p_{a,t}} \mathbb{I}(A_t = 0, E_{a,t}^\mu, E_{a,t}^\theta | \mathcal{H}_t)\right]\right] (\because p_{a,t} \text{ is a function of } \mathcal{H}_t) \\ &= \mathbb{E}\left[\frac{1 - p_{a,t}}{p_{a,t}} \mathbb{I}(A_t = 0, E_{a,t}^\mu, E_{a,t}^\theta)\right] (\because \text{tower property}) \\ &\leq \mathbb{E}\left[\frac{1 - p_{a,t}}{p_{a,t}} \mathbb{I}(A_t = 0)\right] \end{aligned}$$

Let τ_k be the time at which action 0 is taken for the k^{th} time with $\tau_0 := 0$. The key idea is that $p_{a,t}$ is updated only when $\{A_t = 0\}$ happens.

$$\begin{aligned} S_1 &\leq \sum_{t=1}^T \mathbb{E}\left[\frac{1 - p_{a,t}}{p_{a,t}} \mathbb{I}(A_t = 0)\right] \\ &\leq \mathbb{E}\left[\sum_{k=0}^{T-1} \frac{1 - p_{a,\tau_k+1}}{p_{a,\tau_k+1}} \sum_{t=\tau_k+1}^{\tau_{k+1}} \mathbb{I}(A_t = 0)\right] \\ &= \mathbb{E}\left[\sum_{k=0}^{T-1} \frac{1 - p_{a,\tau_k+1}}{p_{a,\tau_k+1}}\right] \end{aligned}$$

The second inequality might not be equality because k can be strictly less than $T - 1$. The last equality holds because the second summation from the second line is exactly 1 by definition of τ_k .

The lecture ended by stating the following lemma without proof. The proof requires extensive calculations involving Beta and Binomial distributions. See the appendix of [AG13] for details.

Lemma 3.

$$\mathbb{E}\left[\frac{1 - p_{a, \tau_k+1}}{p_{a, \tau_k+1}}\right] \leq \begin{cases} \frac{3}{\Delta'_a} & \text{if } k < \frac{8}{\Delta'_a} \\ \Theta(e^{-k\Delta'^2_a/2} + \frac{1}{(k+1)\Delta'^2_a}e^{-kD_a} + \frac{1}{e^{k\Delta'^2_a/4}-1}) & \text{otherwise} \end{cases}$$

where $\Delta'_a = \mu_0 - y_a$ and $D_a = d(y_a, \mu_0)$.

References

- [AG12] Shipra Agrawal and Navin Goyal. Analysis of Thompson sampling for the multi-armed bandit problem. In *COLT*, pages 39–1, 2012.
- [AG13] Shipra Agrawal and Navin Goyal. Further optimal regret bounds for Thompson sampling. In *AISTATS*, pages 99–107, 2013.
- [Tho33] William R Thompson. On the likelihood that one unknown probability exceeds another in view of the evidence of two samples. *Biometrika*, 25(3/4):285–294, 1933.