

# Lecture 23: Contextual Decision Processes with Low Bellman Rank are PAC-Learnable

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## 1 Contextual Decision Processes

This lecture was given by Nan Jiang and he discussed about his recent paper [JKA<sup>+</sup>16].

Let context space  $\mathcal{X}$ , action space  $\mathcal{A}$ , horizon  $H$

In each episode,

$$\left\{ \begin{array}{l} x_1 \in \mathcal{X} \text{ is drawn, play } a_1 \in \mathcal{A} \\ r_1, x_2 \text{ are drawn, play } a_2 \\ \vdots \\ r_{H-1}, x_H \text{ are drawn, play } a_H \\ r_H \text{ is drawn. End} \end{array} \right.$$

Policy  $\pi : \mathcal{X} \rightarrow \mathcal{A}$ .

Value  $V^\pi = \mathbb{E} \left[ \sum_{h=1}^H r_h | a_{1:H} \sim \pi \right]$

## 2 Value-based RL with function approximation

Given  $\mathcal{F} \subseteq (\mathcal{X} \times \mathcal{A} \rightarrow [0, 1])$  assume  $|\mathcal{F}| = N < \infty$

We want to identify  $f \in \mathcal{F}$  such that

- $V^{\pi_f}$  is high, where  $\pi_f : x \mapsto \operatorname{argmax}_{a \in \mathcal{A}} f(x, a)$
- $f$  obeys a set of Bellman equation (or “ $f$  is valid” for short):  $\mathcal{E}(f, \pi_{f'}, h) = 0, \forall f' \in \mathcal{F}, h \in [H]$

where Bellman Error is

$$\mathcal{E}(f, \pi, h) := \mathbb{E} [f(x_h, a_h) - r_h - f(x_{h+1}, a_{h+1}) | a_{1:h-1} \sim \pi, a_{h:h+1} \sim \pi_f]$$

Formally, we aim to achieve value  $V_{\mathcal{F}}^* = \sup_{f \in \mathcal{F}: f \text{ is valid}} V^{\pi_f}$

## 3 Bellman rank

Define the Bellman error matrix for each level  $h$  as an  $N \times N$  matrix, with the  $(f', f)$ -th entry being  $\mathcal{E}(f, \pi_{f'}, h)$ . Informally, Bellman rank  $M$  is the maximal rank of such matrices over all  $h$ , and is naturally small for a number of RL settings.

PAC-learning goal: identify  $f \in \mathcal{F}$  such that  $V^{\pi_f} \geq V_{\mathcal{F}}^* - \epsilon$  with probability at least  $1 - \delta$ , using only  $\text{poly}(M, |\mathcal{A}|, H, \log(N/\delta), 1/\epsilon)$  episodes of data.

## 4 Algorithm: OLIVE

Here is a simplified version of the algorithm OLIVE. This will be discussed in next lecture.

1. Let  $V_f = \mathbb{E}[\max_{a \in \mathcal{A}} f(x, a)]$
2. Let  $\mathcal{F}_0 = \mathcal{F}$
3. For every epoch  $t=1,2,\dots$
4. Pick  $f_t = \operatorname{argmax}_{f \in \mathcal{F}_{t-1}} V_f$  and  $\pi_t = \pi_{f_t}$ .
5. If  $\sum_{h=1}^H \mathcal{E}(f_t, \pi_t, h) \leq \varepsilon$   
    Terminate and return  $\pi_t$   
    End if
6. Pick  $h_t \in [1, \dots, H]$  such that  $\mathcal{E}(f_t, \pi_t, h_t) \geq \frac{\varepsilon}{H}$
7. Collect data  $\{(x_1^{(i)}, a_1^{(i)}, r_1^{(i)}, \dots, x_{h_t}^{(i)}, a_{h_t}^{(i)}, r_{h_t}^{(i)}, x_{h_t+1}^{(i)})\}_{i=1}^n$
8.  $\forall f \in \mathcal{F}_{t-1}$ , let  $\hat{\mathcal{E}}(f, \pi_t, h_t) = \frac{1}{n} \sum_{i=1}^n \frac{I(a_{h_t}^{(i)} = \pi_f(x_{h_t}^{(i)}))}{1/|\mathcal{A}|} \left( f(x_{h_t}^{(i)}, a_{h_t}^{(i)}) - r_{h_t}^{(i)} - f(x_{h_t+1}^{(i)}, \pi_f(x_{h_t+1}^{(i)})) \right)$
9. Let  $\mathcal{F}_t := \{f \in \mathcal{F}_{t-1} : |\hat{\mathcal{E}}(f, \pi_t, h_t)| \leq \phi\}$
10. End for

## References

- [JKA<sup>+</sup>16] Nan Jiang, Akshay Krishnamurthy, Alekh Agarwal, John Langford, and Robert E Schapire. Contextual decision processes with low bellman rank are PAC-learnable. *arXiv preprint arXiv:1610.09512*, 2016.