CSC263H

Data Structures and Analysis

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Winter 2024 - Week 3

ADT: Dictionaries

Dictionary ADT:

- Objects: A collection of key-value pairs (keys are unique).
- · Operations:
 - Search(D,k): return x in D s.t. x.key = k, or NIL if no such x is in D.
 - Insert(D,x): insert x in D; if some y in D has y.key equal to x.key, replace y by x.
 - Delete(D,x): remove x from D.

Note: k is a key, x is a node.

Data Structures for Dictionaries: Lists

Unsorted List:

- Search(D,k):
- Insert(D, x):

Data Structures for Dictionaries: Lists

Sorted List (by keys):

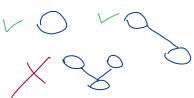
- Search(D,k):
- Delete(D, x):

Data Structures for Dictionaries: Lists

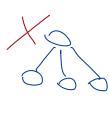
- · Searching the list randomly is slow and sub-optimal.
- Using binary search on a sorted list, we can reduce the run-time of the search to $\mathcal{O}(\log n)$.
- Is there a data structure that stores and organizes keys in a dictionary in such a way?

Binary Search Tree (BST): A binary tree that satisfies the binary search tree property: for every node x, x.key is greater than every key in left sub-tree of x, and x.key is less than every key in right sub-tree of x.

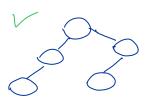
· Each node has at most two children.



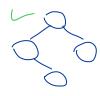




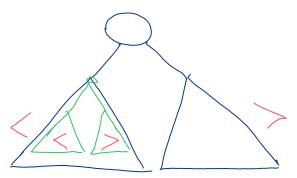
Nodes don't have to be full, unlike binary heaps.



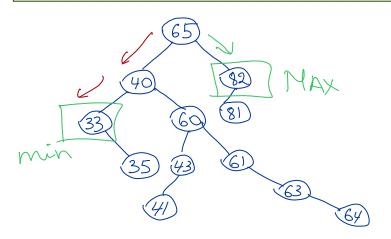




BST property is recursive!



- Minimum value of a BST: left-most node with no left child
- Maximum value of a BST: right-most node with no right child



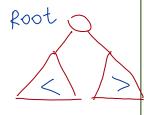
Information at each node x:

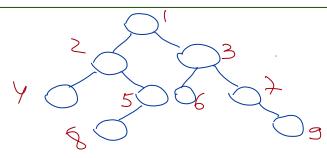
- *x.key*: the key
- x.left: the left child (node)
- *x.right*: the right child (node)
- *x.p*: the parent (node)

Because of BST property, we can say that the keys in a BST are **sorted**.

How to obtain a sorted list from a BST?

- Inorder traversal (Depth First: Left, Root, Right)
- Preorder traversal (Depth First: Root, Left, Right)
- Postorder traversal (Depth First: Left, Right, Root)
- Level-by-level traversal (Breadth-First)





BSTs: Inorder Traversal

InorderTraversal(x):

print all keys in BST rooted at x in ascending order

print all keys in BST rooted at x in ascending order

Inorder Traversal (X. left)

Print (X. key)

Inorder Traversal (X. right)

Worst-case Running Time:



BSTs: Finding Minimum

BSTMin(x): Return the node with the minimum key in the tree rooted at x.

BSTMin(x):

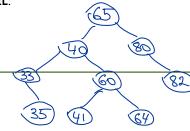
- Start from the x.
- 2. keep going left, until the left child is **NIL**.
- 3. return the final node.

Worst-case Running Time: /



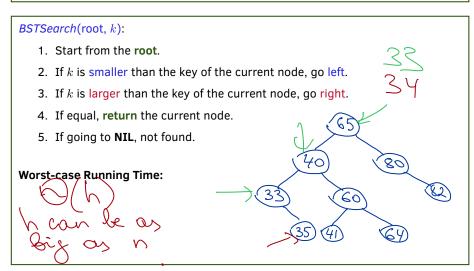


- **while** x.left \neq NIL:
- x = x.left
- return x



BSTs: Search

Search(D,k): return x in D s.t. x.key = k, or NIL if no such x is in D.



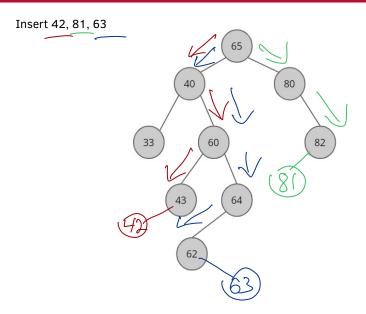
BSTs: Search

Insert(D,x): insert x in D; if some y in D has y.key equal to x.key, replace y by x.

BSTInsert(root, x):

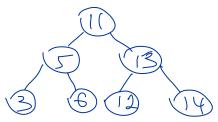
- 1. Start from the root.
- 2. Go down, left and right like what we do in BSTSearch
- 3. When next position is NIL, insert there.
- 4. If find equal key, replace the node.

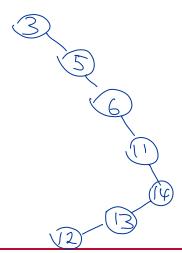




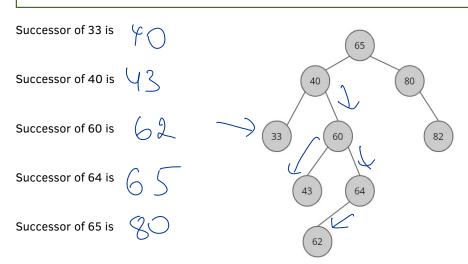
If inserting the same set of data, but in a different sequence, will the shape of the BST be the same?

Insert sequence 1: 11, 5, 13, 12, 6, 3, 14 **Insert sequence 2:** 3, <u>5</u>, 6, 11, 14, 13, 12





Successor(x): Find the node which is the successor of x in the <u>sorted list</u> obtained by <u>inorder traversal</u> (i.e., node with the smallest key larger than x).



Case 1: x has a right child.

• Successor(x) must be the **minimum** in the **right subtree** of x.

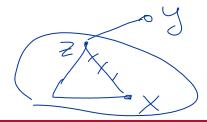
Case 2: x does **not** have a *right* child.

Case 1: *x* has a *right* child.

• Successor(x) must be the **minimum** in the **right subtree** of x.

Case 2: x does **not** have a *right* child.

- x is the maximum in some subtree A (because x has no right child).
- Maximum of a subtree is the last node visited in the subtree in an inorder traversal. So, the successor y of x is visited right after finishing A.
- Right after finishing visiting a left subtree, its parent is visited.
 So A must be the left subtree of y.



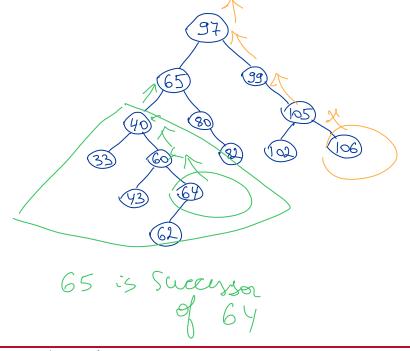
Case 1: x has a *right* child.

• Successor(x) must be the **minimum** in the **right subtree** of x.

Case 2: x does not have a right child.

- x is the maximum in some subtree A (because x has no right child).
- So, the successor \boldsymbol{y} of \boldsymbol{x} is visited right after finishing \boldsymbol{A} in inorder traversal.
- So A must be the left subtree of y.
- Go up to x.p.
- If x is a right child of x.p, keep going up.
- If x is a left child of x.p, stop, x.p is the guy!

Then X is already Nox so it dos not



```
Successor(x):
       if x.right \neq NIL:
          return BSTMinimum(x.right)
       y = x.p
       while y \neq \text{NIL} and x == y.right:
                                               \#x is right child
          x = y
                      #keep going up
          y = y.p
       return y
```

 $h \in O(n)$

Worst case running time:

Bst Nivimum - takes O(h) or Care 1: cox 2: Going from a leaf at height he to zoot. Also O(n)

BSTs: Delete

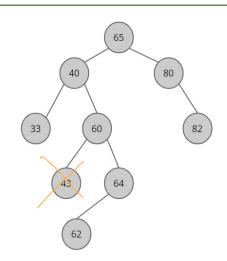
Delete(D,x): remove x from D.

Case 1: x has no child.

· Just delete it

Case 2: x has one child.

Case 3: x has two children.



BSTs: Delete

Delete(D,x): remove x from D.

Case 1: x has no child.

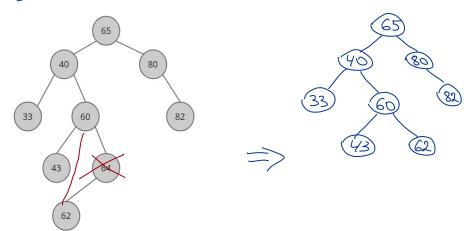
Just delete it

Case 2: x has one child.

- Delete x;
- **Promote** x's only child to x's spot, together with the child's subtree.

Case 3: x has two children.

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BSTs: Delete

```
BSTTransplant(root, x, y): \\ \# \ promote \ y \ to \ x's \ position \\ 1 \qquad \textbf{if} \ x.p == \ NIL: \\ \# \ if \ x \ is \ the \ root \\ 2 \qquad root = y \qquad \# \ y \ replaces \ x \ as \ root \\ 3 \qquad \textbf{else if} \ x == x.p.left: \\ \# \ if \ x \ is \ its \ parent's \ left \ child \\ 4 \qquad x.p.left = y \qquad \# \ make \ y \ the \ new \ left \ child \ of \ the \ parent \\ 5 \qquad \textbf{else:} \qquad \# \ if \ x \ is \ its \ parent's \ right \ child \\ 6 \qquad x.p.right = y \qquad \# \ make \ y \ the \ new \ right \ child \ of \ the \ parent \\ 7 \qquad \textbf{if} \ y \neq \ NIL: \\ 8 \qquad y.p = x.p \qquad \# \ update \ the \ parent \ of \ y
```

BSTs: Delete

Delete(D,x): remove x from D.

Case 1: x has no child.

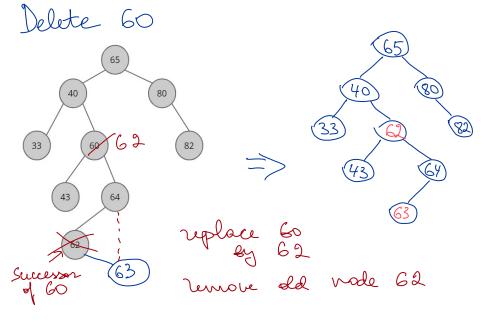
· Just delete it

Case 2: x has one child.

- Delete x:
- **Promote** x's only child to x's spot, together with the child's subtree.

Case 3: x has two children.

- Delete x:
- Replace x by its successor y;
- Remove y from its original position;
 - y must be the minimum of right subtree of x.
 So y has at most one child.



Side Note: Thinking Process

I can see that it works, pretty clever! But HOW ON EARTH can I come up with this kind of clever algorithms!

Thinking Process:

- Understand the BST property (the invariant).
- predict the final shape of the tree.
- · see how to get there.

BSTs: Delete



Running Time Analysis of BST Operations

Worst-case Running Time:

• BSTSearch: \bigcirc \bigcirc

• BSTInsert:

• BSTDelete:

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A BST is **NOT** necessarily complete (unlike binary heap).

After Lecture

- Review BSTs in the Course Notes (first part of Chapter 3) and CLRS (CLRS Chapter 12.3).
- · Relevant exercises in the Course Notes and CLRS.
- Complete implementation of BSTExtractMin and BSTExtractMax.