

OctetsFrame_Typedef

- + direction_motor
- + left_wheel_motor
- + right_wheel_motor
- + left_wheel_motor_distance
- + right_wheel_motor_distance
- + front_left_ultrasonic
- + front_right_ultrasonic
- + front_center_ultrasonic
- + rear_left_ultrasonic
- + rear_right_ultrasonic
- + rear_center_ultrasonic
- + battery
- + ack_byte