

Homework 1

PHY 250, Winter 2024

Due: 02-04-2024

Assignment

The goal of this assignment is to solidify the concepts we have discussed over the last few weeks by writing a *three vector* class. Specifically, inside of your namespace in your MyClass.hpp file create a new class called `vec3` with the following properties,

- 1 Three floats called x, y, and z.
- 2 A default constructor that initializes all three values to 0.0.
- 3 An explicit constructor that takes three floats and sets x, y, and z appropriately.
- 4 A destructor. Because we are not doing any dynamic memory allocation, it is not strictly necessary to write a destructor; however, we will include one for good practices. It will just be,
`<your namespace>::vec3::~~vec3(){}`

Discussion

To make our lives easier we will begin by overloading the `[]` operator. For our `vecN` class we had a `float*` so it made sense to use

```
1 float& PHY::vecN::operator[] (const int index){  
2     return m_vals[index];  
3 }
```

This will be slightly different for our `vec3` class. Because the only variables that our `vec3` class has are `float` x, y, z; they will be stored continuously in memory.

The `[]` operator works in the following way. Let's say we make an array of five floats,

```
1 float arr[5];
```

What we are doing is asking for a block of memory that can hold 5 floats. We may reserved the following block,

0xfe0	0xfe4	0xfe8	0xfec	0xff0
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We treat `arr` as an array but really it is just a `float*` that points to `0fe0`. When we use the `[]` operator with a variable say

```
1 float x = arr[2];
```

What we are saying is,

- 1 go to address `arr` points to, `0xfe0`.
- 2 move forward in memory two blocks, `0xfe8`
- 3 give me the float at, dereference, this block of memory, `*(0xfe8)`

The following statements are equivalent

```
1 float x = arr[2];  
2 float x = *(arr + 2);
```

The point to all of this was to try and explain why we can do the following for our `vec3` class.

To overload the `[]` operator in our `vec3` class use the following code in your `.cpp` file,

```
1 float& vec3::operator[](const int index){  
2     return (&x)[index];  
3 }
```

You will also need to include the appropriate definition in your `.hpp` file

Assignment cont.

Your `vec3` class should also have the following member functions and operators.

- 4 Overload the `[]` operator to return a `float&`.
- 5 Overload the `+`, `-`, `*`, `/` operators to perform element wise addition, subtraction, multiplication, and division. They should take a const `vec3&` as an argument and return a `vec3`.
- 6 Overload the `+=`, `-=` operators to perform element wise `+=`, `-=`. They should take a const `vec3&` as an argument and return a `vec3&`.
- 7 Overload the `*=`, `/=` operators to scale all elements. They should take a const `float` as an argument and return a `vec3&`.
- 8 Overload the `==` to perform element wise comparison. It should take a const `vec3&` as an argument and return a `bool`.
- 9 Write a member function that computes the length of your `vec3`, l2 norm. It should return a `float`.
- 10 Write a member function that normalizes your `vec3`. It should return a `vec3&`.

We can also overload operators out side of the class, this is useful for operations where the order is ambiguous, e.g.

$$a * x == x * a$$

Outside of the scope of your `vec3` class, but still inside your namespace, include the following lines in your `.hpp` file.

```
1 class vec3{
2     ...
3 };
4
5 vec3 operator*(const float scale, const vec3& other);
6 vec3 operator*(const vec3& other, const float scale);
```

Then in your `.cpp` file, replacing `PHY` with your namespace

```

1 PHY::vec3 PHY::operator*(const float scale, const vec3& other){
2     PHY::vec3 ret(other);
3     ret *= scale;
4     return ret;
5 }
6 PHY::vec3 PHY::operator*(const vec3& other, const float scale){
7     PHY::vec3 ret(other);
8     ret *= scale;
9     return ret;
10 }

```

A nonmember function or operator refers to a function that acts on a class but is defined outside of class scope, for us still inside namespace.

- 11 Write a nonmember function that computes the dot product of two `vec3`.
- 12 Write a nonmember function that computes the cross product of two `vec3`.
- 13 Write a nonmember function that computes the distance, l_2 , between two `vec3`.
- 14 Overload the `/` operator for a `vec3`, just like the example but division.
- 15 Overload the `>=`, `<=` operators to element wise compare a `vec3` with a `float`.

Lastly, write a new class called `vec4`. It will contain four `floats` `x`, `y`, `z`, `w`; it should have

1. A default constructor that initializes all four values to 0.0.
2. An explicit constructor that takes four floats and sets `x`, `y`, `z`, and `w` appropriately.
3. A destructor. Again just `PHY::vec4::~~vec4(){}`

We will now go back to our old friend the `=` operator. Because we are not dynamically allocating any memory, there is no fear of a memory leak so you do not need to worry about safety.

- 16 For your `vec4`, inside the class scope, overload the `=` operator. It should take a const `vec3&` as an argument and return a `vec4&`.

GLHF