

B42 Protocol Specification

v1.1 2020-11-11

B42 is a generic low level protocol for byte based communication channels (such as serial). Its main purpose is easy transmission of small command packets between hosts (computers) and microcontroller boards.

B42 supports up to 3 data bytes (up to 18 bits payload) along with the (mandatory) command byte. The command byte contains 4 bits command code and 2 bits for the number of following data bytes.

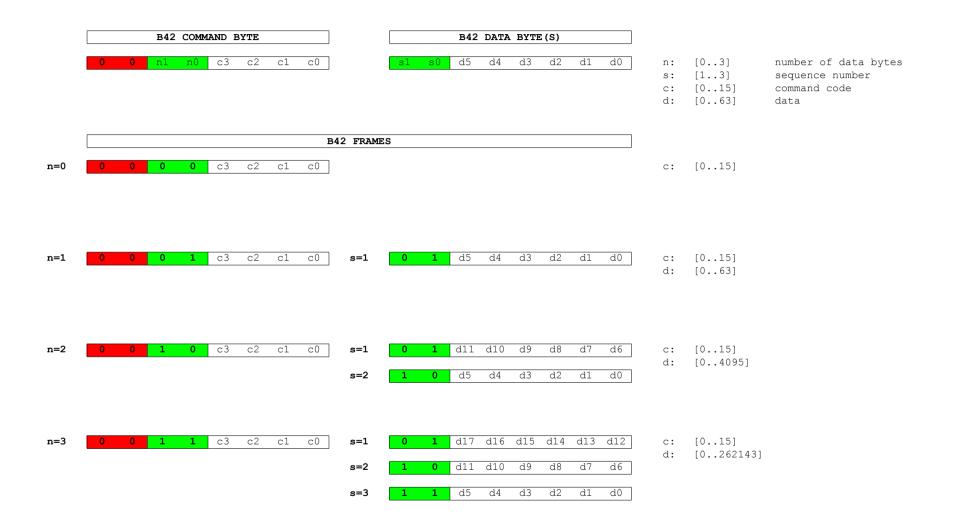
Framing and basic error detection is accomplished by a 2 bit sequence number for every transmitted byte. Zero bytes (0x00) are considered protocol errors. Invalid and incomplete frames are ignored. Each valid command byte starts a new frame.

The higher level application protocols define their custom command codes and data bits on top of B42. Command code zero (0x0) is reserved and should not be used by application protocols.

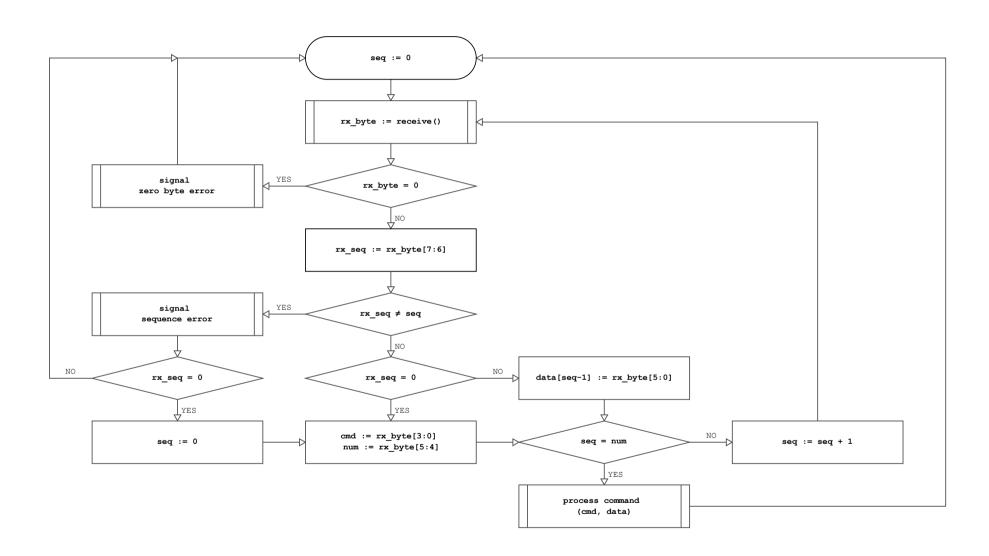
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Bytes and Frames



```
Start:
                                               /* expected sequence number (0: command byte) */
         sea := 0
         num := 0
                                               /* expected number of data bytes */
         cmd := 0
                                               /* command code */
                                               /* command data */
         data := [0, 0, 0]
Loop:
         rx byte := receive byte()
         /* check for invalid zero byte */
         if rx byte = 0:
              signal_zero_byte_error()
              goto Start
                                               /* ignore byte / current frame */
         /* check for invalid byte sequence */
         rx seq := rx byte[7:6]
         if rx seq != seq:
              signal sequence error()
              if rx seq = 0:
                   goto Command
                                               /* command byte -> start of a new frame */
                                               /* ignore byte / current frame */
              goto Start
         /* process received byte */
         if seq = 0:
              goto Command
                                               /* command byte -> start of a new frame */
         data[seq - 1] := rx byte[5:0]
                                               /* data byte -> store data bits */
         if seq = num:
              process command(cmd, data)
                                               /* frame complete */
              goto Start
         seq := seq + 1
                                               /* expect next data byte */
         goto Loop
Command:
         cmd := rx byte[3:0]
         num := rx byte[5:4]
         if num = 0:
              process command(cmd)
                                               /* frame complete (no data bytes) */
              goto Start
                                               /* expect first data byte */
         seq := 1
         goto Loop
```



Implementations

The following reference/example implementations are available:

Board side	b42lib	B42 handler firmware library for Arduino/PlatformIO. https://github.com/amdx/b42lib
Host side	pyb42	B42 and convenience handlers library for Python3. https://github.com/amdx/pyb42

Change log

VERSION/DATE	AUTHOR	CHANGES
1.0 2015-02-02	Thomas Schott, Archimedes Exhibitions GmbH	Initial version.
1.1 2020-11-11	Thomas Schott, Archimedes Exhibitions GmbH	Add purpose note on Front page. Add sequence number reset to Receiver flowchart. Add Implementations page. Add Change log page.