

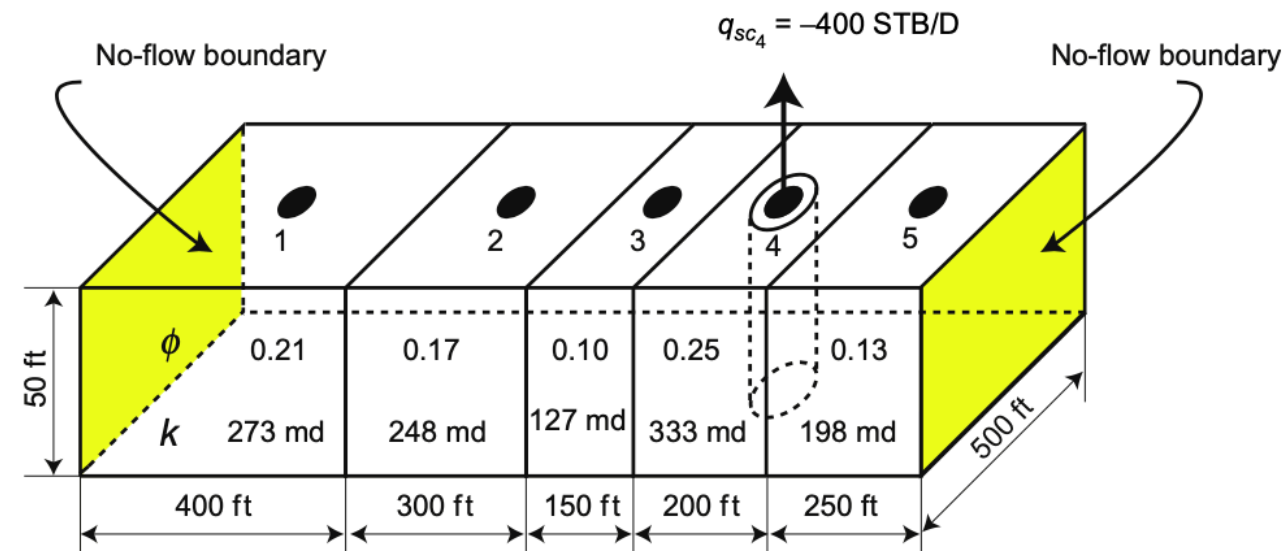
# Petroleum Reservoir Simulation with Python

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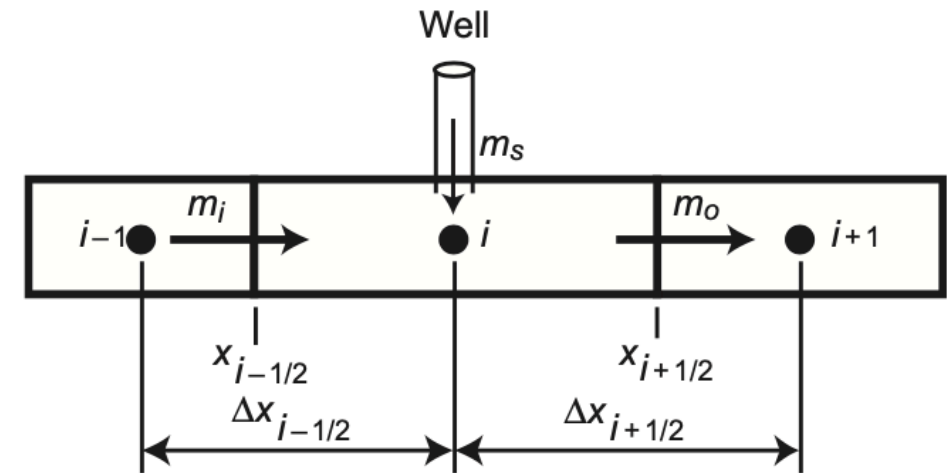


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## Basic principles

- Mass conservation:  
$$m_i - m_o + m_s = m_a$$
- Fluid flow rate (Darcy's law):  
$$u_x = q_x / A_x = -\frac{k_x}{\mu} \frac{\partial p}{\partial x}$$



## Derivation of PDE

- Mass rate,  $w = m/t = \rho u A$
- Density,  $\rho = m/V_p$
- Pore volume,  $V_p = V_b \phi$
- Volumetric rate,  $q = q_s/\rho$

$$\begin{aligned} m_i - m_o + m_s &= m_a \\ w_i \Delta t - w_o \Delta t + q_s \Delta t &= V_b \Delta t (\phi \rho) \\ (\rho u_x A_x)_i \Delta t - (\rho u_x A_x)_o \Delta t + \rho q \Delta t &= V_b \Delta t (\phi \rho) \\ \frac{(\rho u_x A_x)_i - (\rho u_x A_x)_o + \rho q}{V_b} &= \frac{\Delta t (\phi \rho)}{\Delta t} \\ \frac{(\rho u_x)_i - (\rho u_x)_o}{\Delta x} + \frac{\rho q}{V_b} &= \frac{\Delta t (\phi \rho)}{\Delta t} \end{aligned}$$

## Derivation of PDE

$$\begin{aligned} \frac{-[(\rho u_x)_o - (\rho u_x)_i]}{\Delta x} + \frac{\rho q}{V_b} &= \frac{\Delta_t(\phi\rho)}{\Delta t} \\ \lim_{\Delta x \rightarrow 0} \frac{-[(\rho u_x)_o - (\rho u_x)_i]}{\Delta x} + \frac{\rho q}{V_b} &= \lim_{\Delta t \rightarrow 0} \frac{\Delta_t(\phi\rho)}{\Delta t} \\ -\frac{\partial(\rho u_x)}{\partial x} + \frac{\rho q}{V_b} &= \frac{\partial(\phi\rho)}{\partial t} \\ \frac{\partial}{\partial x} \left( \frac{k_x}{\mu} \frac{\partial p}{\partial x} \right) + \frac{\rho q}{V_b} &= \frac{\partial(\phi\rho)}{\partial t} \end{aligned}$$

- Formation volume factor,  $B = \rho_{sc}/\rho$

$$\frac{\partial}{\partial x} \left( \frac{k_x}{\mu B} \frac{\partial p}{\partial x} \right) + \frac{q_{sc}}{V_b} = \frac{\partial}{\partial t} \left( \frac{\phi}{B} \right)$$

# Discretization of PDE in space and time

- Volume,  $V = A\Delta x$
- For gridblock  $i$ ,

$$\begin{aligned}\frac{\partial}{\partial x} \left( \frac{A_x k_x}{\mu B} \frac{\partial p}{\partial x} \right)_i \Delta x_i + q_{sc_i} &= V_{b_i} \frac{\partial}{\partial t} \left( \frac{\phi}{B} \right)_i \\ \frac{\partial}{\partial x} \left( \frac{A_x k_x}{\mu B} \frac{\partial p}{\partial x} \right)_i &\approx \left[ \left( \frac{A_x k_x}{\mu B} \frac{\partial p}{\partial x} \right)_{i+1/2} - \left( \frac{A_x k_x}{\mu B} \frac{\partial p}{\partial x} \right)_{i-1/2} \right] / \Delta x \\ \frac{\partial}{\partial x} \left( \frac{A_x k_x}{\mu B} \frac{\partial p}{\partial x} \right)_i \Delta x_i &\approx \left[ \left( \frac{A_x k_x}{\mu B \Delta x} \right)_{i+1/2} (p_{i+1} - p_i) - \left( \frac{A_x k_x}{\mu B \Delta x} \right)_{i-1/2} (p_i - p_{i-1}) \right] \\ \frac{\partial}{\partial x} \left( \frac{A_x k_x}{\mu B} \frac{\partial p}{\partial x} \right)_i \Delta x_i &\approx T_{i+1/2} (p_{i+1} - p_i) - T_{i-1/2} (p_i - p_{i-1})\end{aligned}$$

## Discretization of PDE in space and time

$$T_{i+1/2}(p_{i+1} - p_i) - T_{i-1/2}(p_i - p_{i-1}) + q_{sc_i} \approx V_{b_i} \frac{\partial}{\partial t} \left( \frac{\phi}{B} \right)_i$$

$$T_{i-1/2}(p_{i-1} - p_i) + T_{i+1/2}(p_{i+1} - p_i) + q_{sc_i} \approx V_{b_i} \frac{\partial}{\partial t} \left( \frac{\phi}{B} \right)_i$$

$$\frac{\partial}{\partial t} \left( \frac{\phi}{B} \right)_i \approx \frac{1}{\Delta t} \left[ \left( \frac{\phi}{B} \right)_i^{n+1} - \left( \frac{\phi}{B} \right)_i^n \right]$$

## Discretization of PDE in space and time

- Forward-difference discretization (Explicit)

$$T_{i-1/2}^n(p_{i-1}^n - p_i^n) + T_{i+1/2}^n(p_{i+1}^n - p_i^n) + q_{sc_i}^n \approx \frac{V_{b_i}}{\Delta t} \left[ \left( \frac{\phi}{B} \right)_i^{n+1} - \left( \frac{\phi}{B} \right)_i^n \right]$$

$$T_{i-1/2}^n(p_{i-1}^n - p_i^n) + T_{i+1/2}^n(p_{i+1}^n - p_i^n) + q_{sc_i}^n \approx \frac{V_{b_i}}{\Delta t} \left( \frac{\phi}{B} \right)_i' [p_i^{n+1} - p_i^n]$$

$$\left( \frac{\phi}{B} \right)_i' = \left[ \left( \frac{\phi}{B} \right)_i^{n+1} - \left( \frac{\phi}{B} \right)_i^n \right] / [p_i^{n+1} - p_i^n]$$



## Discretization of PDE in space and time

- Backward-difference discretization (Implicit)

$$T_{i-1/2}^{n+1}(p_{i-1}^{n+1} - p_i^{n+1}) + T_{i+1/2}^{n+1}(p_{i+1}^{n+1} - p_i^{n+1}) + q_{sc_i}^{n+1} \approx \frac{V_{b_i}}{\Delta t} \left( \frac{\phi}{B} \right)'_i [p_i^{n+1} - p_i^n]$$

## Initial and boundary conditions

- Specified boundary pressure,  $p_b$

$$\left[ \frac{k_x A_x}{\mu B (\Delta x) / 2} \right]_{bB} (p_b - p_i)$$

- Specified boundary pressure-gradient,  $\partial p / \partial x$

$$\mp \left[ \frac{k_x A_x}{\mu B} \right]_{bB} \frac{\partial p}{\partial x}$$

## Well representation

- Specified well pressure gradient,  $\partial p / \partial r$

$$q_{sc_i} = - \frac{2\pi r_w kh}{B\mu} \frac{\partial p}{\partial r}$$

- Specified well FBHP,  $p_{wf}$

$$q_{sc_i} = - \frac{2\pi kh}{B\mu [\log_e(r_{eq}/r_w) + s]} (p_i - p_{wf})$$

$$q_{sc_i} = -G(p_i - p_{wf})$$

$$r_{eq} = 0.14 [(\Delta x)^2 + (\Delta y)^2]^{0.5}$$

## Single phase flow

- Incompressible flow,  $c_\phi = 0$

$$\phi = \phi^* [1 + c_\phi (p - p^*)]$$

$$T_{i-1/2}(p_{i-1} - p_i) + T_{i+1/2}(p_{i+1} - p_i) + q_{sc_i} \approx \frac{V_{b_i}}{\Delta t} \left[ \left( \frac{\phi}{B} \right)_i^{n+1} - \left( \frac{\phi}{B} \right)_i^n \right]$$

$$\frac{V_{b_i}}{\Delta t} \left[ \left( \frac{\phi}{B} \right)_i^{n+1} - \left( \frac{\phi}{B} \right)_i^n \right] = \frac{V_{b_i} \phi_i^* c_\phi}{B \Delta t} [p_i^{n+1} - p_i^n] = 0$$

$$T_{i-1/2}(p_{i-1} - p_i) + T_{i+1/2}(p_{i+1} - p_i) + q_{sc_i} \approx 0$$

## Single phase flow

- Slightly compressible flow,

$$\frac{V_{b_i}}{\Delta t} \left[ \left( \frac{\phi}{B} \right)_i^{n+1} - \left( \frac{\phi}{B} \right)_i^n \right] \approx \frac{V_{b_i} \phi_i (c_\phi + c)}{B \Delta t} [p_i^{n+1} - p_i^n]$$

$$T_{i-1/2}(p_{i-1} - p_i) + T_{i+1/2}(p_{i+1} - p_i) + q_{sc_i} \approx \frac{V_{b_i} \phi_i (c_\phi + c)}{B \Delta t} [p_i^{n+1} - p_i^n]$$

## Transmissibility

$$T_{i,i\pm 1} = T_{i\mp 1/2} = \frac{1}{\mu B} \times \frac{2}{\Delta x_i / (A_{x_i} k_{x_i}) + \Delta x_{i\mp 1} / (A_{x_{i\mp 1}} k_{x_{i\mp 1}})}$$

# Methods of solution of linear equations (Thomas' algorithm)

- Incompressible flow

$$T_{i-1/2}(p_{i-1} - p_i) + T_{i+1/2}(p_{i+1} - p_i) + q_{sc_i} = 0$$

$$T_{i-1/2}p_{i-1} - T_{i-1/2}p_i + T_{i+1/2}p_{i+1} - T_{i+1/2}p_i = -q_{sc_i}$$

$$T_{i-1/2}p_{i-1} - (T_{i-1/2}p_i + T_{i+1/2}p_i) + T_{i+1/2}p_{i+1} = -q_{sc_i}$$

$$T_{i-1/2}p_{i-1} - (T_{i-1/2} + T_{i+1/2})p_i + T_{i+1/2}p_{i+1} = -q_{sc_i}$$

- Slightly compressible flow

$$T_{i-1/2}(p_{i-1}^{n+1} - p_i^{n+1}) + T_{i+1/2}(p_{i+1}^{n+1} - p_i^{n+1}) + q_{sc_i}^{n+1} \approx \frac{V_{b_i}\phi_i(c_\phi + c)}{B\Delta t} [p_i^{n+1} - p_i^n]$$

$$T_{i-1/2}p_{i-1}^{n+1} - \left( T_{i-1/2} + T_{i+1/2} + \frac{V_{b_i}\phi_i(c_\phi + c)}{B\Delta t} \right) p_i^{n+1} + T_{i+1/2}p_{i+1}^{n+1} = -q_{sc_i}^{n+1} - \frac{V_{b_i}\phi_i(c_\phi + c)}{B\Delta t} p_i^n$$

## Methods of solution of linear equations (Thomas' algorithm)

- The equation for block,  $i$

$$w_i x_{i-1} + c_i x_i + e_i x_{i+1} = d_i$$

- For example, for incompressible flow

$$w_i = T_{i-1/2}, c_i = -(T_{i-1/2} + T_{i+1/2}), e_i = T_{i+1/2}, d_i = -q_{sc_i}$$



# Methods of solution of linear equations (Thomas' algorithm)

- Algorithm

- i. Set  $u_1 = e_1/c_1$  and  $g_1 = d_1/c_1$

- ii. For  $i = 2, 3, \dots, N - 1,$

- $u_i = e_i/(c_i - w_i u_{i-1})$  and

- For  $i = 2, 3, \dots, N,$

- $g_i = (d_i - w_i g_{i-1})/(c_i - w_i u_{i-1})$

- iii. Set  $x_N = g_N$

- iv. For  $i = N - 1, N - 2, \dots, 3, 2, 1,$

- $x_i = g_i - u_i x_{i+1}$

## Case study

Reservoir fluid properties are

$B = 1RB/STB$ ,  $\mu = 1.5cp$ , and

$c = 2.5 \times 10^{-5} psi^{-1}$ . Initially,

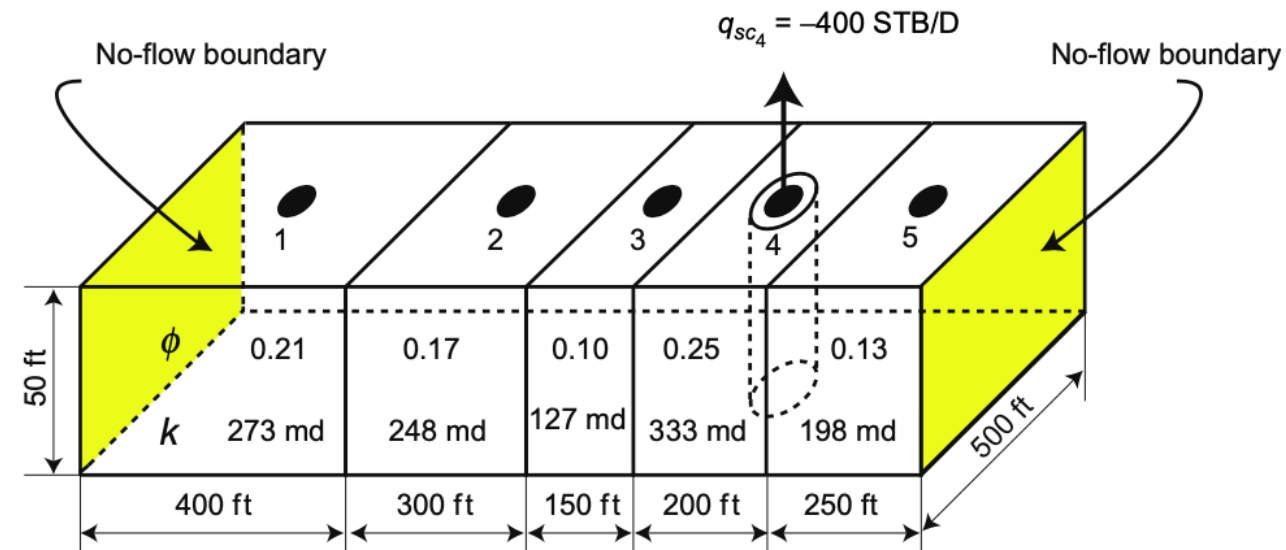
reservoir pressure is  $3000psia$ . A  $6in$  vertical well was drilled at the center of gridblock 4. The well is switched to a

constant FBHP of  $1500psia$  if the reservoir cannot sustain the specified

production rate. Find the pressure

distribution in the reservoir after 10

days using the implicit formulation.



## Case study: Single phase 1D slightly compressible implicit reservoir simulation

$$\begin{aligned} T_{i-1/2}(p_{i-1}^{n+1} - p_i^{n+1}) + T_{i+1/2}(p_{i+1}^{n+1} - p_i^{n+1}) + q_{sc_i}^{n+1} &\approx \frac{V_{b_i}\phi_i(c_\phi + c)}{B\Delta t} [p_i^{n+1} - p_i^n] \\ T_{i-1/2}p_{i-1}^{n+1} - \left( T_{i-1/2} + T_{i+1/2} + \frac{V_{b_i}\phi_i(c_\phi + c)}{B\Delta t} \right) p_i^{n+1} + T_{i+1/2}p_{i+1}^{n+1} &= -q_{sc_i}^{n+1} - \frac{V_{b_i}\phi_i(c_\phi + c)}{B\Delta t} p_i^n \\ T_{i-1/2}p_{i-1}^{n+1} - \left( T_{i-1/2} + T_{i+1/2} + \frac{V_{b_i}\phi_i(c_\phi + c)}{B\Delta t} \right) p_i^{n+1} + T_{i+1/2}p_{i+1}^{n+1} &= G(p_i^{n+1} - p_{wf}) - \frac{V_{b_i}\phi_i(c_\phi + c)}{B\Delta t} p_i^n \\ T_{i-1/2}p_{i-1}^{n+1} - \left( T_{i-1/2} + T_{i+1/2} + \frac{V_{b_i}\phi_i(c_\phi + c)}{B\Delta t} + G \right) p_i^{n+1} + T_{i+1/2}p_{i+1}^{n+1} &= -Gp_{wf} - \frac{V_{b_i}\phi_i(c_\phi + c)}{B\Delta t} p_i^n \\ w_i p_{i-1}^{n+1} + c_i p_i^{n+1} + e_i p_{i+1}^{n+1} &= d_i \end{aligned}$$

# Case study: Single phase 1D slightly compressible implicit reservoir simulation with Python

- Inputs

```
k = np.array([273, 248, 127, 333, 198]) # permeability (mD)
phi = np.array([0.21, 0.17, 0.10, 0.25, 0.13]) # porosity (%)
x = np.array([400, 300, 150, 200, 250]) # length (ft)
n = len(x) # number of blocks
t = 5 # time step (days)
t_end = 135//t # after (135) days
p = np.zeros((t_end, 5)) # pressure (psia)
p[0]= 3000 # initial pressure (psia)
h = 50 # height (ft)
w = 500 # width (ft)
B = 1 # FVF (RB/STB)
mu = 1.5 # viscosity (cp)
cp = 2.5e-5 # compressibility (1/psi)
```

# Case study: Single phase 1D slightly compressible implicit reservoir simulation with Python

- Inputs

```
rw = 6/2 * 0.08333 # interal radius (ft)
re = 0.14 * (x[3]**2 + w**2)**0.5 # external radius (ft)
A = h * w # area (ft2)
Bc = 0.001127 # conversion factor to stb
ac = 5.614583 # rb to stb
t = 5 # time step (days)
qsc = np.zeros(5) # well flow rates (STB/D)
qsc[3] = -400 # well flow rate at block 4 (STB/D)
qw = 0 # west boundary flow rate (STB/D)
qe = 0 # east boundary flow rate (STB/D)
G = ((2*np.pi*Bc*k[3]*h)/(B*mu*np.log(re/rw)))
```

## Case study: Single phase 1D slightly compressible implicit reservoir simulation with Python

- Transmissibility

$$T = (1/(\mu*B)) * (2*Bc) / ((x[:-1]/(A*k[:-1])) + (x[1:]/(A*k[1:])))$$

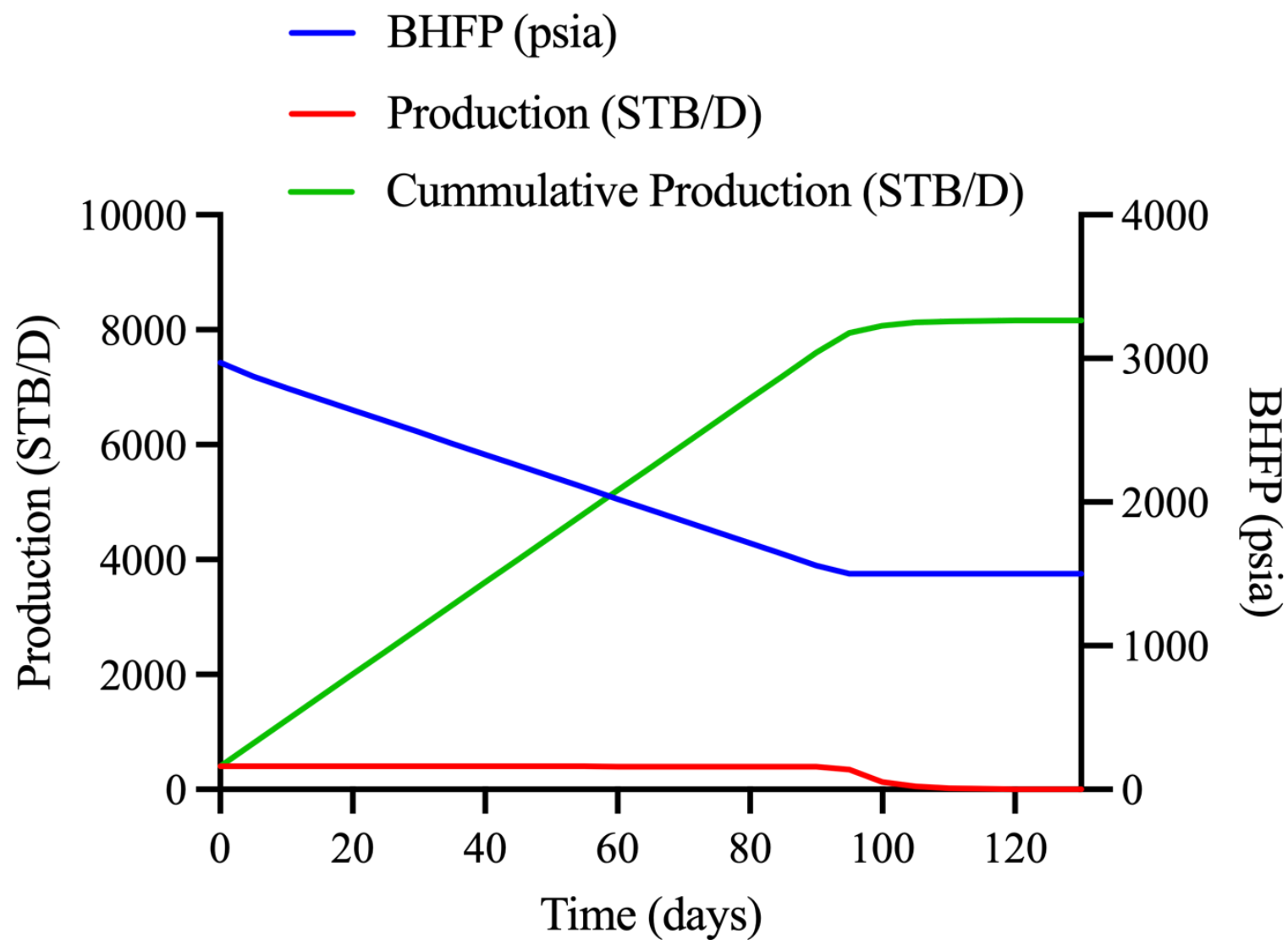
- Accumulation

$$ma = (A * x * \phi_i * c_p) / (ac * B * t)$$

# Case study: Single phase 1D slightly compressible implicit reservoir simulation with Python

- Thomas' algorithm

```
for t_idx in range(1, t_end):
    c = np.zeros((n, 7))
    for i in range(n):
        if i == 0:
            c[i][:4] = [0, -(qw + T[0] + ma[0]), T[0], -qsc[0] - ma[0] * p[t_idx - 1][0]]
            c[i][4:] = [c[i][2] / c[i][1], c[i][3] / c[i][1], 0]
        elif i == n - 1:
            c[i][:4] = [T[-1], -(qe + T[-1] + ma[-1]), 0, -qsc[-1] - ma[-1] * p[t_idx - 1][-1]]
            c[i][4:] = [0, (c[i][3] - (c[i][0] * c[i - 1][5])) / (c[i][1] - (c[i][0] * c[i - 1][4])), 0]
        else:
            c[i][:4] = [T[i - 1], -(T[i - 1] + T[i] + ma[i]), T[i], -qsc[i] - ma[i] * p[t_idx - 1][i]]
            c[i][4:] = [c[i][2] / (c[i][1] - (c[i][0] * c[i - 1][4])),
                        (c[i][3] - (c[i][0] * c[i - 1][5])) / (c[i][1] - (c[i][0] * c[i - 1][4])), 0]
    c[:, -1][-1] = c[:, -2][-1]
    for i in range(0, n - 1)[::-1]:
        c[i, -1] = c[i, -2] - (c[i, -3] * c[i + 1, -1])
    p[t_idx] = c[:, -1]
```





## References

1. Petroleum Reservoir Simulation: The Engineering Approach

<https://www.geokniga.org/bookfiles/geokniga-petroleum-reservoir-simulation.pdf>