How to Run the Kinect Speech Recognition Demo

- 1. Download and install Kinect SDK 1.8 as described in the next section.
- 2. Open scene 'KinectSpeechRecognition', located in Assets/SpeechRecognitionDemo-folder.
- 3. Run the scene.
- 4. Say clearly one of the listed commands in order to control the avatar by voice commands. Repeat this step as many times as you wish.
- 5. Find the grammar file 'SpeechGrammar.grxml', located in the root folder of the project, modify the commands or add more voice commands. Then re-run the scene to test the updates.

Installation of Kinect Sensor with MS SDK 1.8

- 1. Download the Kinect SDK 1.8 or Kinect Windows Runtime 1.8. Here is the download page: http://www.microsoft.com/en-us/download/details.aspx?id=40278
- 2. Run the installer. The installation of Kinect SDK/Runtime is simple and straightforward.
- 3. Connect the Kinect sensor. The needed device drivers will be installed automatically.

How to Reuse the Kinect Speech Recognition in Your Own Unity Project

- 1. Copy folder 'KinectScripts' from Assets-folder of the example to the Assets-folder of your project. This folder contains the two needed scripts SpeechManager and SpeechWrapper.
- 2. Copy folder 'Resources' from Assets-folder of the example to the Assets-folder of your project. This folder contains the native libraries and grammar file, needed by the Unity-project.
- 3. Add 'SpeechManager'-script to the MainCamera. If you use multiple cameras, create an empty GameObject and add the script to it.
- 4. Set the 'Grammar File Name'-parameter of 'SpeechManager'-component of the MainCamera.
- 5. Use the public functions of 'SpeechManager'-script in your scripts. As an example, see the FixedUpdate()-function of 'BotControlScript' a component of the Robot-object.
- 6. Modify the voice commands in the grammar file 'SpeechGrammar.grxml.txt' located in Assets/Resources-folder, as to your needs.
- 7. Delete the 'SpeechGrammar.grxml' grammar-file, located in the root-folder of your Unity project and then re-run the scene.

Support and Feedback

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