lalue_I teration
Declare:
U, U - current utilities for states, in trally &
of - max change of any utility of any state in an iteration
E - max allowable error of utility in any
E - max allowable error of utility in any state. (controls convergence of algorithm)
Regnises MDP with:
Actions as A(s): actions in states
States 5
Rewards (s): Newards in state s
discount /
Transition Model: P(s'/a,s), aka Ta(s,a,s
Loop
U = U'
$S = \emptyset$
for each state in States
U'(s) = R(s) + 1 max & P(s'/a,s) U(s')

 $S = \emptyset$ for each state in States  $V'(s) = R(s) + V \max_{a \in A(s)} \leq P(s'|a,s) U(s')$ if  $abs(U'(s) - U(s)) \geq S$  d = abs(U'(s) - U(s)) $Vntil S \leq (I-V) / V$  Uz(2,3) = R(2,3) + / max [(-1 x1,0 + .72x.1 + .120), (.72x.8 + -1x.1. (0x.8+.1x-1+.1x0), (0x1.+1-x1.+8.x0) V max [-.728, M284, -. 1,0] 10 t. 9244284 = 0+.9x.476 = .4284 M1.4284 -1 (x) Fill in values for all states for U,(s) Ks Util, ties are closen for states closen to the exit. (Kles-Add because fewer steps are reguired. Same as (2,3). It's -72/+1/1 Same # of skps?

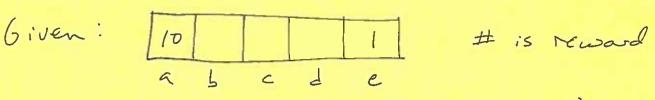
May 4284 -1 2(x) Should n't be there's no firepit danger.

How long does value iteration run?

Unitit

Un





Actions: East, West, and Exit(in States a, e only)

Trans, tions: detoministic

- 1. For 8=1, what is optimal policy? Actin for each state
- 7. For Y= . I, what is optimal policy?
- For what I are E and W equally good when in state d? U(s): P(s) + I man (t, )

1. To e e in T no discounting, go to highest reward from d, 1 ×10 = 10

2. Go west for all and get (from d). Go east from d: \( \text{\cond} \) \( \text{\cond} \) \( \text{\cond} \) \( \text{\cond} \) 8 x 10 = . 1 × 10 = . 01 from c 12/0=.01 x 10=.1

10 = = > 1 ex.t

3. 
$$f_{\times 10} = f_{\cdot 1.0} = f_{\times 10-1}$$

$$Y = \sqrt{\frac{1}{10}}$$

·01 × 10=.1