- In a reduction, a local copy of each list (target) variable is made and initialised for each thread
- Updates occur on the local copy
- Local copies are reduced to a single value and combined with the original global value
- The same effect as a reduction can be achieved using other directives eg. #pragma omp critical (see next)
- However, reduction is more scalable

#### Threads and OpenMP

- Other ways of controlling thread access are using:
  - Barriers force each thread to wait until all of the threads have finished executing

```
#pragma omp barrier
```

- Mutual exclusion - define a block of the code that only one thread at a time can execute (sort of defeats the point of adding the parallelism...)

```
#pragma omp critical or
#pragma omp atomic (for memory updates only)
```

- We can also use #pragma omp critical to stop false sharing
- All of the above can be used to prevent race conditions

```
#pragma omp parallel
{
    int id=omp_get_thread_num();
    A[id] = big_calc1(id);
#pragma omp barrier

B[id] = big_calc2(id, A);
}
```

```
float res;
#pragma omp parallel
{    float B;    int i, id, nthrds;
    id = omp_get_thread_num();
    nthrds = omp_get_num_threads();
    for(i=id;i<niters;i+=nthrds){
        B = big_job(i);
#pragma omp critical
        res += consume (B);
    }
}</pre>
```

- Barriers are *implicit* at the end of work sharing constructs such as #pragma omp for, and at the end of parallel regions
- To get rid of this implicit barrier, we add nowait, eg.

```
#pragma omp parallel shared (A, B, C) private(id)
{
    id=omp_get_thread_num();
    A[id] = big_calc1(id);
    #pragma omp barrier

#pragma omp for
    for(i=0;i<N;i++){C[i]=big_calc3(i,A);}

#pragma omp for nowait
    for(i=0;i<N;i++){ B[i]=big_calc2(C, i); }
    A[id] = big_calc4(id);

}

implicit barrier at the end
    of a parallel region

no implicit barrier
due to nowait
```

- Variables within a worksharing construct (eg. #pragma omp for)
   are private by default
- This can be achieved explicitly using eg. #pragma omp for private(x), where x are the variables inside the construct this creates a new local (uninitialised) copy of x for each thread
- Outside working constructs, variables are shared
- Default attributes can be overridden using default (private | shared | none)
- We can also use:
  - firstprivate initialises from shared variable
  - lastprivate passes last value out to shared variable

#### Threads and OpenMP

Consider this example of PRIVATE and FIRSTPRIVATE

```
variables: A = 1,B = 1, C = 1
#pragma omp parallel private(B) firstprivate(C)
```

- Are A,B,C local to each thread or shared inside the parallel region?
- What are their initial values inside and values after the parallel region?

#### Inside this parallel region ...

- "A" is shared by all threads; equals 1
- "B" and "C" are local to each thread.
  - B's initial value is undefined
  - C's initial value equals 1

#### Following the parallel region ...

- B and C revert to their original values of 1
- A is either 1 or the value it was set to inside the parallel region

- Other useful features of OpenMP that we will not cover in detail include
  - #pragma omp master denotes a structured block that is only executed by the master thread
  - #pragma omp single only executed by one thread (not necessarily the master thread)
  - #pragma omp sections gives a different structured block
    to each thread
  - Simple and nested locks these produce a memory fence, flushing all thread visible variables

# **Parallelism**Threads and OpenMP

Cheat Sheet

#### Directives:

```
#pragma omp parallel
#pragma omp parallel for (or parallel do for FORTRAN)
#pragma omp parallel for collapse(number of loops)
#pragma omp parallel for reduction (operation:variable name)
#pragma omp parallel shared(A,B,C) private(x)
#pragma omp sections
#pragma omp nowait
```

#### To avoid if possible (but sometimes necessary):

```
#pragma omp barrier
#pragma omp critical
#pragma omp atomic
#pragma omp master
#pragma omp single
```

#### Runtime Library functions:

```
omp_get_num_threads()
omp_get_thread_num()
omp_set_num_threads()
omp_get_max_threads()
omp_num_procs()
```

# Parallelism Threads and OpenMP

- In summary:
  - OpenMP can be a relatively simple way to parallelise your program (see last slide), but...
  - THINK before you implement
  - Race conditions and global/private variables can create strange bugs that can be difficult to find
  - False sharing can degrade your performance if not mitigated against

```
#include <omp.h>
     static long num steps = 100000;
                                               double step;
                                                     For good OpenMP
                                                     implementations,
     void main ()
                                                     reduction is more
              int i; double x, pi, sum = 0.0;
                                                     scalable than critical.
              step = 1.0/(double) num steps;
     #pragma omp parallel for private(x) reduction(+:sum)
              for (i=0;i < num steps; i++){
                     x = (i+0.5)*step;
i private by
                     sum = sum + 4.0/(1.0+x*x);
default
                                                Note: we created a
              pi = step * sum;
                                                parallel program without
                                                changing any executable
                                                code and by adding 2
                                                simple lines of text!
```

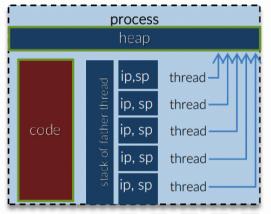
- Some useful resources:
  - ARCHER2 Youtube courses (<a href="https://www.archer2.ac.uk/training/courses/200514-mpi/">https://www.archer2.ac.uk/training/courses/200514-mpi/</a>)
  - James' git repository MPI in Python (<a href="https://github.com/JamesFergusson/Research-Computing/blob/master/">https://github.com/JamesFergusson/Research-Computing/blob/master/</a>
     14 Parallelisation.ipynb
  - https://mpitutorial.com/tutorials/ (some examples from here)
  - Several other online lecture courses

#### Message Passing Interface (MPI)

 If we want to parallelise our code over multiple cores without shared memory, we need to use MPI - recall:



A unique process that spawns a number of threads. There is a unique memory space that is accessible by all the threads

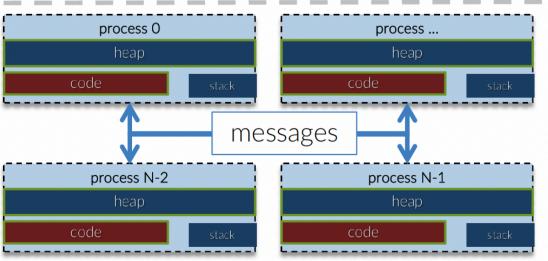


# Distributed-Memory (e.g. MPI)

N processes are created, each with its own copy of the code and its own memory space.

A process *can not* access the memory space of another process.

The processes communicate through *messages*.



## Message Passing Interface (MPI)

- This means that once we have split up the problem, we need to explicitly communicate between cores
- This is done using the routines:

```
MPI_Init initialise MPI
MPI_Comm_size get number of processes
MPI_Comm_rank get the process ID (rank)
MPI_Send send data from core
MPI_Recv receive data to core
MPI_Finalize close MPI
```

This is almost all you need to know to use MPI

## Message Passing Interface (MPI)

Example: Compile and run mpi.cpp

- Compile with mpicc mpi.cpp -o whatever name
  - mpicc is a wrapper around a certain compiler(s)
  - You can see what commands are run using mpicc -show (for me, it uses gcc)
- To run, use the command mpirun -np 4 ./whatever\_name
  - The flag -np sets the number of *processes*
  - You must ensure that the number of ranks does not exceed the number of available cores
  - If you do assign more ranks than cores, the program will probably run, but the performance will be poor

- MPI\_Init initialises execution environment, takes command line arguments (always keep these arguments)
- MPI\_COMM\_WORLD is defined by mpi.h and designates processes in the MPI job
- Each statement executes independently in each process
- As with OpenMP, there is no defined output order
- Note we have also included the library <mpi.h> and installed mpich (see Dockerfile)

- The previous example performed the same command for each rank
   usually, we want to split a given problem between several cores
- We therefore require the processes running on different cores to communicate using:
  - MPI\_Send(void\* data, int count, MPI\_Datatype data\_type, int destination, int tag, MPI\_Comm communicator)
  - MPI\_Recv(void\* data, int count, MPI\_Datatype data\_type, int source, int tag, MPI\_Comm communicator, MPI Status\* status)
- Although this looks like a lot to remember, most MPI calls use the same syntax (see example)

#### Message Passing Interface (MPI)

- The MPI data types are mostly just the normal data types you use in the language you are coding, with MPI in front
  - Eg. MPI\_INT, MPI\_FLOAT
- We can even choose which ranks will send/receive certain chunks of work

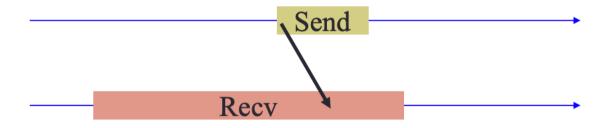
Example 1: Compile and run mpi send recv.cpp

 Change the code so that process 0 sends a message to all other processes (not just 1)

Example 2: Compile and run mpi\_ping\_pong.cpp

#### Message Passing Interface (MPI)

• In the ping pong example, we notice that some signals are `received' before they are sent - how is this possible?

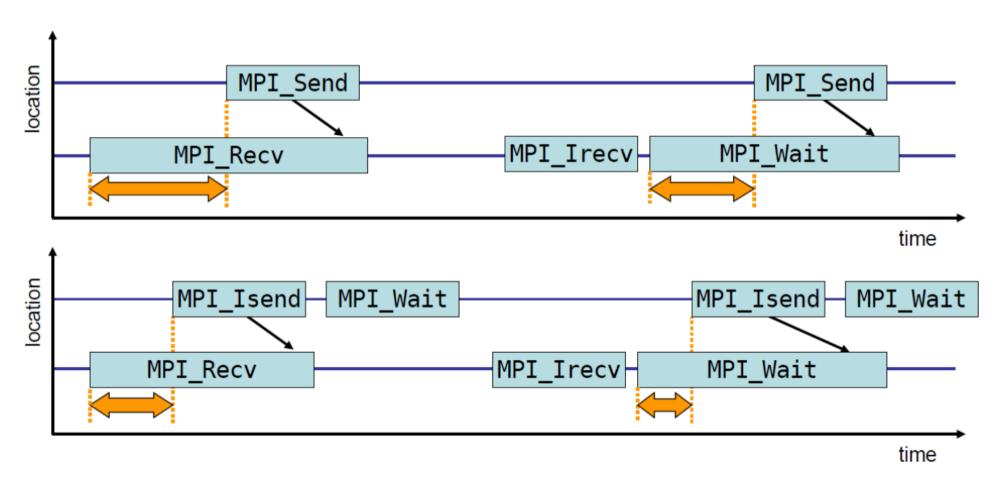


- If the (blocking) receive is posted before its matching send, the receiving task must wait until the data is sent
  - We will come onto blocking...

- With MPI\_Send and MPI\_Recv, the instruction is complete when it is safe to change/access the data we sent/received
- We can choose either to
  - Start a communication and wait for it to complete blocking
  - Start a communication and return control to the main problem nonblocking
    - This requires us to check for completion before we can change/ access the data we sent/received
- MPI\_Send and MPI\_Recv are both blocking operations
- These can be unsafe and lead to deadlocks if the message passing cannot be completed
  - Eg. MPI Send is called before MPI Recv for a previous exchange

- Non-blocking allows separation between the initiation of a communication and the completion
- This can be more efficient but the programmer must also make sure to check for completion
- For these, we instead use MPI\_Isend and MPI\_Irecv
  - MPI\_Isend(void\* data, int count, MPI\_Datatype data\_type, int destination, int tag, MPI\_Comm communicator, MPI Request \*req)
  - MPI\_Irecv(void\* data, int count, MPI\_Datatype data\_type, int source, int tag, MPI\_Comm communicator, MPI\_Status\* status, MPI\_Request \*req)
- The I stands for `immediate'

## Message Passing Interface (MPI)



http://www.morrisriedel.de/wp-content/uploads/2019/10/High-Performance-Computing-Lecture-5-1-Understanding-MPI-Communicators-and-Data-Structures.pdf

#### Message Passing Interface (MPI)

• If using MPI Isend and MPI Irecv, we can use

```
MPI_Wait(MPI_Request *req, MPI_Status *status)
```

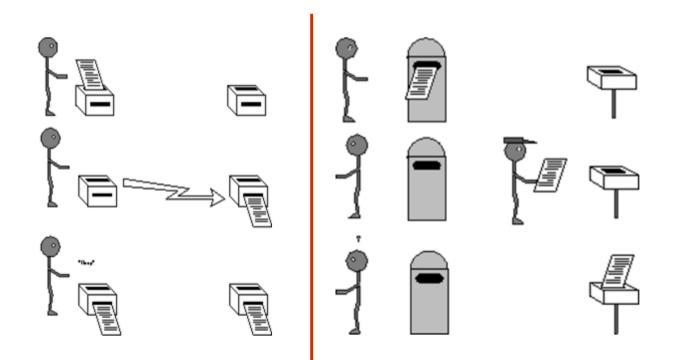
to wait until the communication pointed to by req is complete

We can also use

```
MPI_Test(MPI_Request *req, int *flag, MPI_Status
*status)
```

to test whether the message has been completed

- MPI\_Isend and MPI\_Irecv can use either:
  - Synchronous communication the sender blocks further operations until an acknowledgement or response is received
  - Asynchronous communication the sender continues execution without waiting for an acknowledgement



- Some other options are:
  - MPI\_Bsend (buffer send) always completes, irrespective of receiver
  - MPI\_Ssend (synchronous send) only completes when the receive has completed, guarantees the buffer passed can be safely reused
  - MPI\_Rsend (ready send) always completes, irrespective of whether the receive has completed
- For comparison, standard send and receives
- All of the above can be used as blocking or non-blocking