How Robust are Thresholds for Community Detection?

Alex Wein (MIT)

Joint with Ankur Moitra (MIT) and Will Perry (MIT)

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And if they don't agree, which one is correct?

Model for community detection in graphs

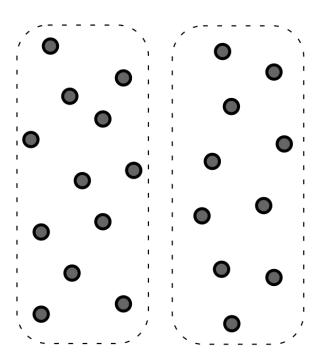
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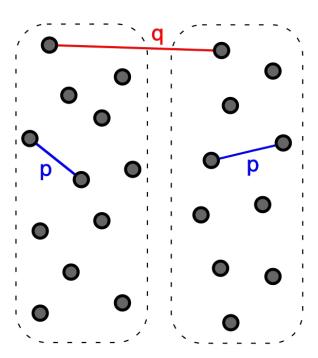
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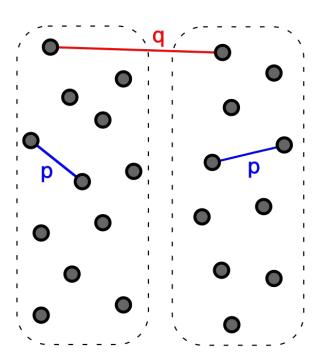
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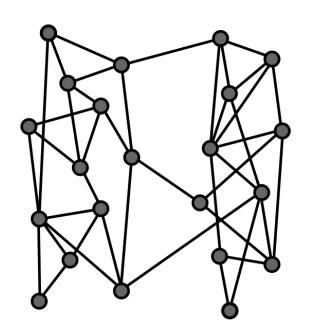


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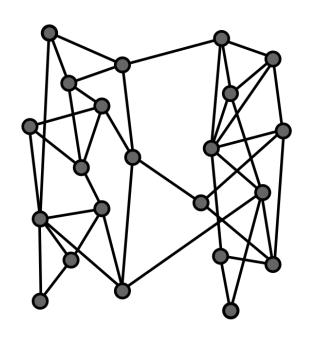


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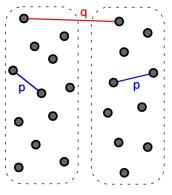
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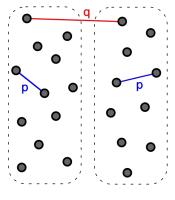
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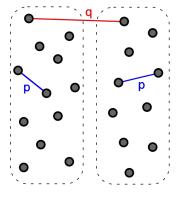
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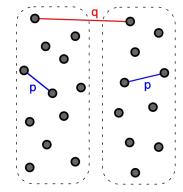
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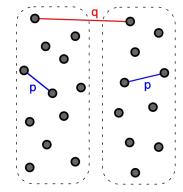
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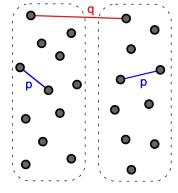


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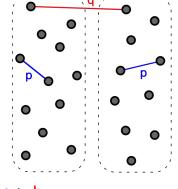
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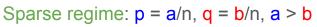


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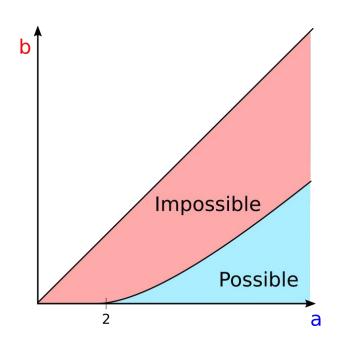
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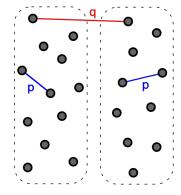
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Answer: We will give evidence that SDPs cannot reach the threshold! — but only because they are actually solving a harder problem.

Semirandom Models

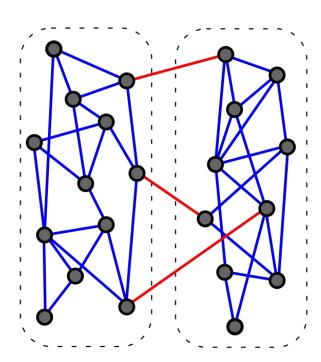
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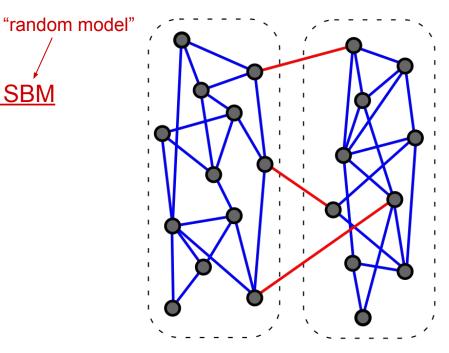
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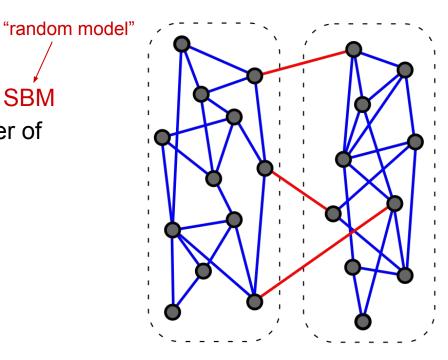
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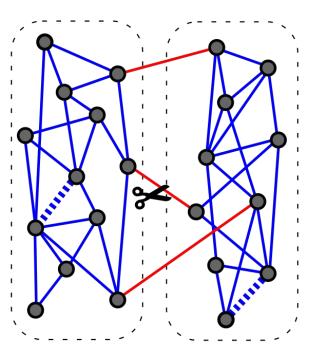
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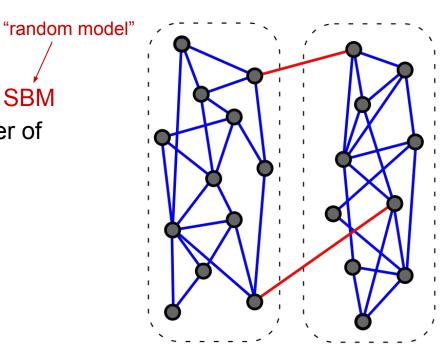
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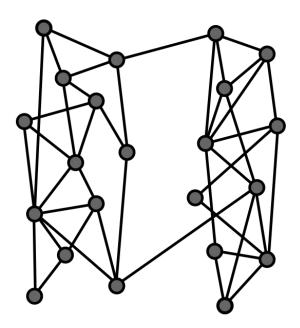
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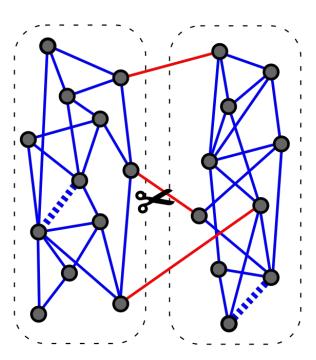
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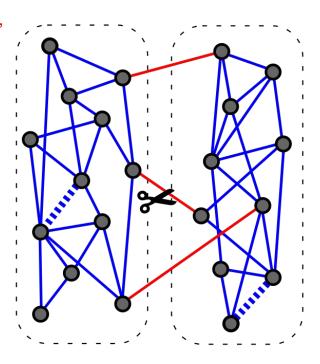
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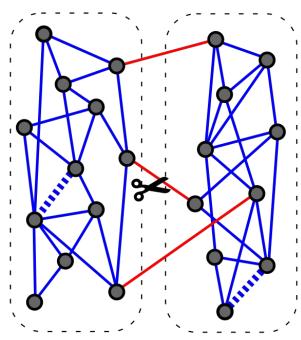
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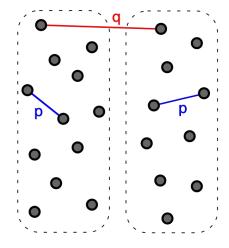
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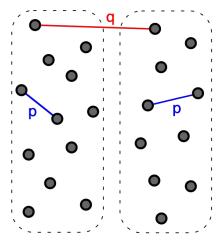


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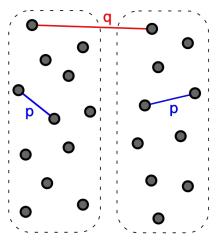
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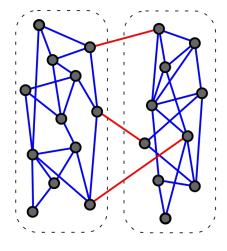


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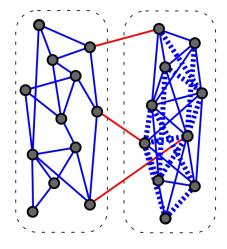
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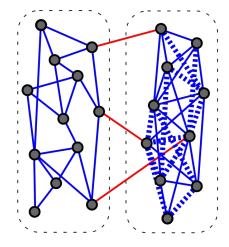
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The vast majority of algorithms fail against the semirandom model!



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- Open: Can [Montanari–Sen '15] analysis be made robust?

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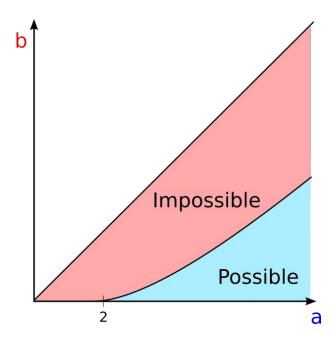
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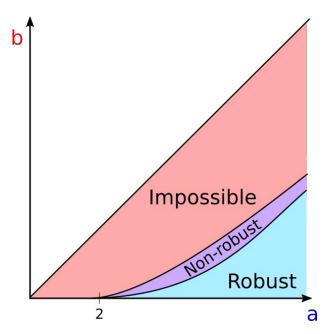
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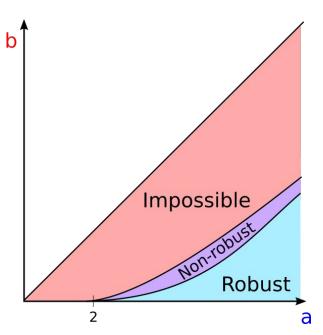
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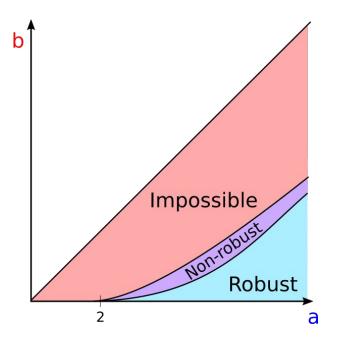


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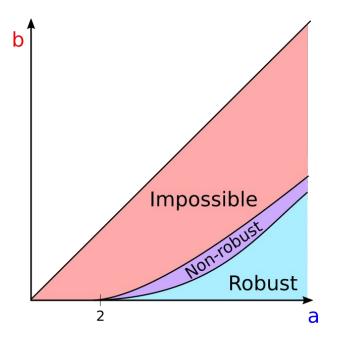


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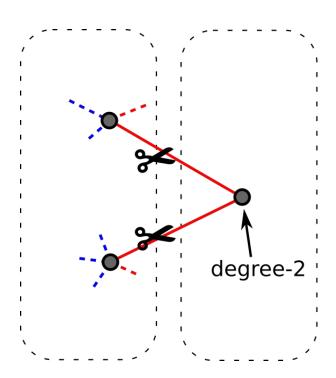
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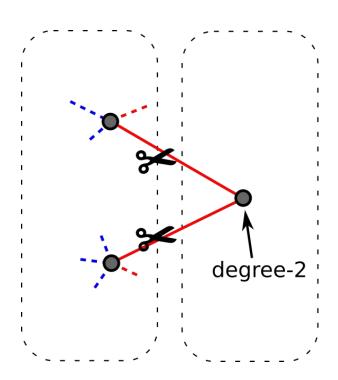
Additional evidence: statistical physics predicts (non-rigorous) that SDP misses the threshold [JMR'15]

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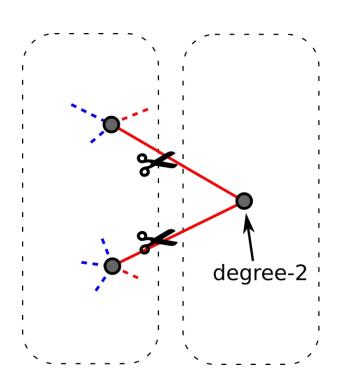
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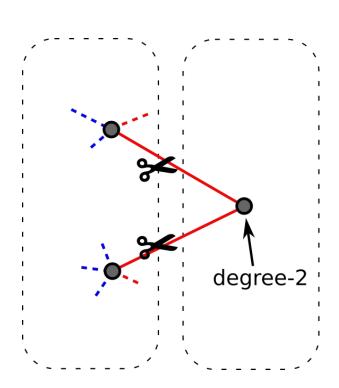


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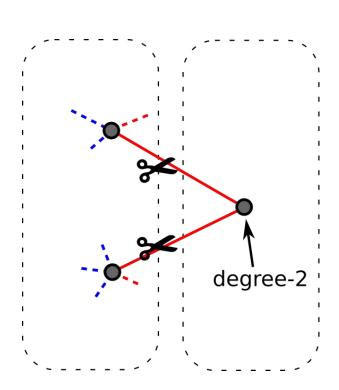
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Interpretation: algorithms reaching the threshold (e.g. linearized belief propagation) rely on the distribution of these structures in the noise



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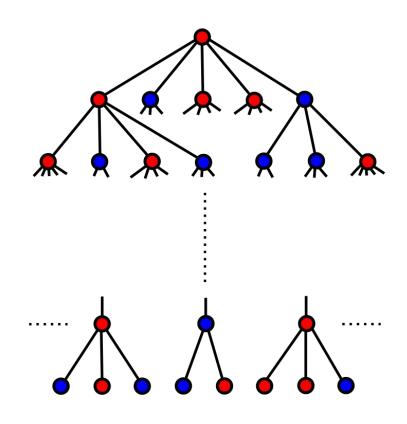
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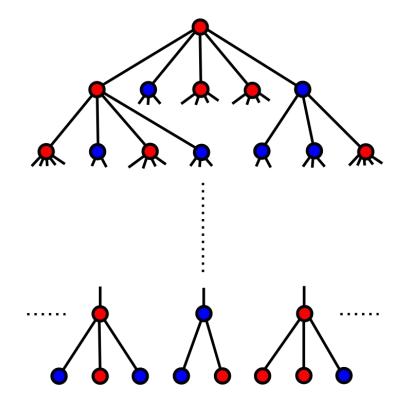
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Use connection to broadcast tree model



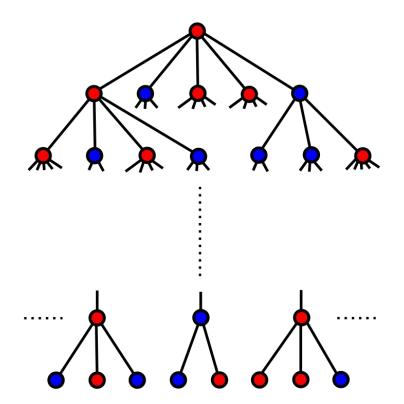
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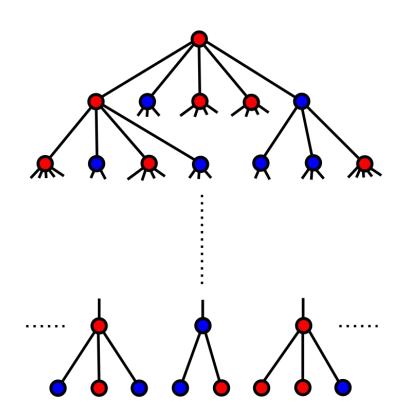


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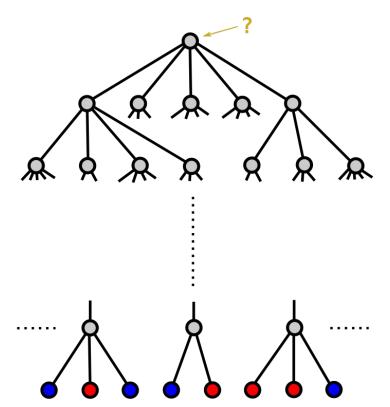
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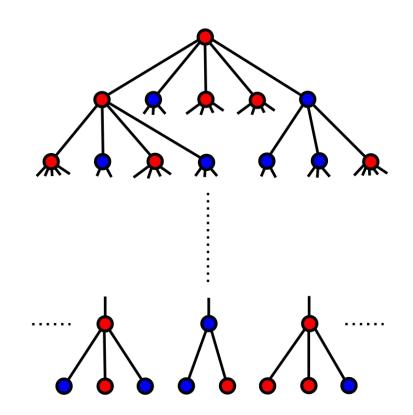
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Answer: when $(a - b)^2 > 2(a + b)$ Look familiar? [Kesten-Stigum '66, Evans-Kenyon-Peres-Schulman '00]



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Thanks! Questions?