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Extercise 3.3

a.
$$g(\tilde{N}) = \sum_{P=1}^{p} (\tilde{X}_{p}^{T}\tilde{N} - y_{p})^{2}$$

$$= (a-b)^{2} = a^{2} + 2ab + b^{2}$$

$$= \sum_{P=1}^{p} \left[(\tilde{X}_{p}^{T}\tilde{N})^{2} - 2(\tilde{X}_{p}^{T}\tilde{N})(y_{p}) + y_{p}^{2} \right]$$

$$= \sum_{P=1}^{p} \left[(\tilde{X}_{p}^{T}\tilde{N}) \cdot (\tilde{X}_{p}^{T}\tilde{N}) - 2(\tilde{X}_{p}^{T}\tilde{N})(y_{p}) + y_{p}^{2} \right]$$

$$= \sum_{P=1}^{p} \left[(\tilde{X}_{p}^{T}\tilde{N}) \cdot (\tilde{X}_{p}^{T}\tilde{N}) - 2(\tilde{X}_{p}^{T}\tilde{N})(y_{p}) + y_{p}^{2} \right]$$

$$= \sum_{P=1}^{p} \left[(\tilde{X}_{p}^{T}\tilde{N}) \cdot (\tilde{X}_{p}^{T}\tilde{N}) - 2(\tilde{X}_{p}^{T}\tilde{N})(y_{p} + y_{p}^{2}) \right]$$

$$= \sum_{P=1}^{p} \left[(\tilde{X}_{p}^{T}\tilde{N}) \cdot (\tilde{X}_{p}^{T}\tilde{N}) - 2(\tilde{X}_{p}^{T}\tilde{N}) \cdot y_{p} + y_{p}^{2} \right]$$

$$= \sum_{P=1}^{p} \left[(\tilde{X}_{p}^{T}\tilde{N}) \cdot (\tilde{X}_{p}^{T}\tilde{N}) - 2(\tilde{X}_{p}^{T}\tilde{N}) \cdot y_{p} + y_{p}^{2} \right]$$

Comparing above equation with
$$g(\tilde{w}) = 1 \tilde{w}^T Q \tilde{w} + r^T \tilde{w} t$$

$$Q = 1 \sum_{P=1}^{\infty} \chi_P^T \cdot \chi_P^T$$

$$r = -\tilde{\chi}_P^T \cdot \gamma_P$$

$$d = \frac{\gamma_P^2}{\gamma_P^2}$$

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b. if NXN square symmetric matrix Q satisfies

xTQX7,0 for all values of Z then it must have all non negative eigen values

Substitute
$$Q = \sum_{p=1}^{P} \chi_{p}^{T} \cdot \chi_{p}$$
 in eq Q
 $\chi^{T} \left(\sum_{p=1}^{P} \chi_{p}^{T} \cdot \chi_{p}^{T} \right) \cdot \chi > 0$
 $\chi^{T} \left(\sum_{p=1}^{P} \chi_{p}^{T} \cdot \chi_{p}^{T} \right) \cdot \chi_{p} > \chi$

magnitude of x is always positive ie. non negative

(o
$$\nabla^{2}g(\tilde{w}) = Q$$

$$g(\tilde{w}) = \sum_{P=1}^{p} (\tilde{x}_{p}^{T}\tilde{w} - y_{p})^{2}$$

$$\nabla g(\tilde{w}) = \sum_{P=1}^{p} 2 (\tilde{x}_{p}^{T}\tilde{w} - y_{p}) \tilde{x}_{p}$$

$$\nabla^{2}g(\tilde{w}) = 2\sum_{P=1}^{p} (\tilde{x}_{p}^{T}\tilde{w} \cdot x_{p}^{T} - y_{p} \cdot \tilde{x}_{p}) - \nabla^{2}g(\tilde{w}) \geqslant 0$$

$$\nabla^{2}g(\tilde{w}) = 2\sum_{P=1}^{p} (\tilde{x}_{p}^{T}\tilde{w} \cdot x_{p}^{T} - y_{p} \cdot \tilde{x}_{p}) - \nabla^{2}g(\tilde{w}) \geqslant 0$$

$$\nabla^{2}g(\tilde{w}) = 2\sum_{P=1}^{p} (\tilde{x}_{p}^{T}\tilde{w} \cdot x_{p}^{T} - y_{p} \cdot \tilde{x}_{p}^{T}) - \nabla^{2}g(\tilde{w}) \geqslant 0$$

$$\nabla^{2}g(\tilde{w}) = 2\sum_{P=1}^{p} \tilde{x}_{p}^{T} \cdot x_{p}^{T} = Q.$$

do By Newton's method,

$$\nabla^{2}g(N^{k-1})W^{k} = \nabla^{2}g(N^{k+1})W^{k+1} - \nabla g(N^{k+1}) \qquad (6)$$

$$g(\widetilde{N}) = \sum_{P=1}^{2} (\widetilde{\chi}_{P}^{T} \widetilde{N} - y_{P})^{2}$$

$$\nabla g(\widetilde{N}) = 2\sum_{P=1}^{2} (\widetilde{\chi}_{P}^{T} \widetilde{N} - y_{P}) \widetilde{\chi}_{P}^{T}$$

$$\nabla^{2}g(\widetilde{N}) = 2\sum_{P=1}^{2} \widetilde{\chi}_{P}^{T} \widetilde{\chi}_{P}^{T} \qquad (from 3.c.)$$

Substituting in eq () $\nabla^2 g(w^{k-1})w^k = \nabla^2 g(w^{k-1})w^{k+1} - \nabla g(w^{k-1}) \rho$ $\partial Z \tilde{\chi}_p^{\mu} \chi_p^{\tau} \tilde{w} = \partial Z \tilde{\chi}_p^{\mu} \chi_p^{\tau} w - \partial Z \tilde{\chi}_p^{\tau} \chi_p^{\tau} \tilde{w} + \partial Z \tilde{\chi}_p^{\tau} \tilde{\chi}_p^{\tau} \tilde{w} + \partial Z \tilde{\chi}_p^{\tau} \tilde{\chi}_p^{\tau} \tilde{w} = \partial Z \tilde{\chi}_p^{\tau} \tilde{\chi}_p^{\tau} \tilde{w} + \partial Z \tilde{\chi}_p^{\tau} \tilde{\chi}_p^{\tau} \tilde{w} = \partial Z \tilde{\chi}_p^{\tau} \tilde{\chi}_p^{\tau} \tilde{w} + \partial Z \tilde{\chi}_p^{\tau} \tilde{\chi}_p^{\tau} \tilde{w} = \partial Z \tilde{\chi}_p^{\tau} \tilde{\chi}_p^{\tau} \tilde{w} + \partial Z \tilde{\chi}_p^{\tau} \tilde{\chi}_p^{\tau} \tilde{w} = \partial Z \tilde{\chi}_p^{\tau} \tilde{\chi}_p^{\tau} \tilde{w} + \partial Z \tilde{\chi}_p^{\tau} \tilde{\chi}_p^{\tau} \tilde{w} + \partial Z \tilde{\chi}_p^{\tau} \tilde{\chi}_p^{\tau} \tilde{w} = \partial Z \tilde{\chi}_p^{\tau} \tilde{\chi}_p^{\tau} \tilde{w} + \partial Z \tilde{\chi}_p^{\tau} \tilde{\chi}_p^{\tau} \tilde{w} = \partial Z \tilde{\chi}_p^{\tau} \tilde{\chi}_p^{\tau} \tilde{w} + \partial Z \tilde{\chi}_p^{\tau} \tilde{\chi}_p^{\tau} \tilde{\chi}_p^{\tau} \tilde{w} + \partial Z \tilde{\chi}_p^{\tau} \tilde{\chi}_p^{\tau}$

a.
$$\sigma^{-1}(\sigma(t))$$

$$\sigma(t) = \frac{1}{1+e^{-t}}$$

$$= \sigma^{-1}\left(\frac{1}{1+e^{-t}}\right)$$

$$= \log t = \frac{1}{1+e^{-\sigma(t)}}$$

$$f^{-1}(t) = \log t$$

$$f^{-1}(f(t)) = \log t = t$$

$$f^{-1}(f(t)) = \log et = t$$

$$t(1+\sigma e^{-\sigma(t)}) = 1$$

$$t + t \cdot e^{-\sigma(t)} = 1$$

$$dogdt + dog$$

$$e^{-\sigma(t)} = \frac{1-t}{t}$$

$$loge^{-\sigma(t)} = log \frac{1-t}{t}$$

$$-\sigma(t) loge = log \frac{1-t}{t}$$

$$|\sigma(t)| = log + 1$$

$$|\sigma(t)| = \log \frac{t}{1-t}$$

$$\sigma^{-1}\left(\frac{1}{1+e^{-t}}\right)$$

from 3.10. a. 1

$$\sigma^{-1}(\sigma(t)) = t$$

$$\sigma^{-1}(t) = \log \frac{t}{1-t}$$

$$\sigma^{-1}(t) = \log \frac{t}{1-t}$$

$$\begin{aligned}
\sigma(b+x_{p}^{T}w) &\approx y_{p} \\
g(\vec{w}) &= \sum \left(\sigma(b+x_{p}^{T}\vec{w}) - y_{p}\right)^{2} \\
\forall g(\vec{w}) &= \sum_{s=1}^{p} \left(\sigma_{p}(b+x_{p}^{T}\vec{w}) - y_{p}\right) \cdot \nabla \sigma(b+x_{p}^{T}w)\right) \\
\nabla g(\vec{w}) &= \sum_{s=1}^{p} \left(\sigma(b+x_{p}^{T}\vec{w}) - y_{p}\right) \cdot \sigma(b+x_{p}^{T}\vec{w}) \\
&= \left(1 - \sigma(b+x_{p}^{T}\vec{w})\right) \chi_{p} \\
&= \sigma(t) = \sigma(t) \left(1 - \sigma(t)\right) \cdot \sigma(b) = 0.
\end{aligned}$$
Significant

Excercise 3.13 $g(\tilde{w}) = \sum_{p \in I} (\sigma(b + \tilde{x}_{p}^{T}\tilde{w}) - y_{p})^{2} + \lambda ||w||_{2}^{2}$ $\nabla g(\tilde{w}) = \lambda \sum_{p = I} (\sigma(b + \tilde{x}_{p}^{T}\tilde{w} - y_{p})) \nabla \sigma(b + \tilde{x}_{p}^{T}\tilde{w}) - y_{p}) + \nabla \lambda ||w||_{2}^{2}$ $\nabla g(\tilde{w}) = + \nabla \lambda ||w||_{2}^{2}$ $= \lambda \sum_{p = I} (\sigma(\tilde{x}_{p}^{T}\tilde{w}) - y_{p}) \sigma(\tilde{x}_{p}^{T}\tilde{w}) ||I - \sigma(\tilde{x}_{p}^{T}\tilde{w})) \tilde{x}_{p}^{2} + C ||w||_{2}^{2}$ $= \lambda \sum_{p = I} (\sigma(\tilde{x}_{p}^{T}\tilde{w}) - y_{p}) \sigma(\tilde{x}_{p}^{T}\tilde{w}) ||I - \sigma(\tilde{x}_{p}^{T}\tilde{w})) \tilde{x}_{p}^{2} + C ||u||_{2}^{2}$ $= \lambda \sum_{p = I} (\sigma(\tilde{x}_{p}^{T}\tilde{w}) - y_{p}) \sigma(\tilde{x}_{p}^{T}\tilde{w}) ||I - \sigma(\tilde{x}_{p}^{T}\tilde{w})) \tilde{x}_{p}^{2} + C ||u||_{2}^{2}$ $= \lambda \sum_{p = I} (\sigma(\tilde{x}_{p}^{T}\tilde{w}) - y_{p}) \sigma(\tilde{x}_{p}^{T}\tilde{w}) ||I - \sigma(\tilde{x}_{p}^{T}\tilde{w})) \tilde{x}_{p}^{2} + C ||u||_{2}^{2}$ $= \lambda \sum_{p = I} (\sigma(\tilde{x}_{p}^{T}\tilde{w}) - y_{p}) \sigma(\tilde{x}_{p}^{T}\tilde{w}) ||I - \sigma(\tilde{x}_{p}^{T}\tilde{w})) \tilde{x}_{p}^{2} + C ||u||_{2}^{2}$ $= \lambda \sum_{p = I} (\sigma(\tilde{x}_{p}^{T}\tilde{w}) - y_{p}) \sigma(\tilde{x}_{p}^{T}\tilde{w}) ||I - \sigma(\tilde{x}_{p}^{T}\tilde{w})| \tilde{x}_{p}^{2} + C ||u||_{2}^{2}$ $= \lambda \sum_{p = I} (\sigma(\tilde{x}_{p}^{T}\tilde{w}) - y_{p}) \sigma(\tilde{x}_{p}^{T}\tilde{w}) ||I - \sigma(\tilde{x}_{p}^{T}\tilde{w})| \tilde{x}_{p}^{2} + C ||u||_{2}^{2}$ $= \lambda \sum_{p = I} (\sigma(\tilde{x}_{p}^{T}\tilde{w}) - y_{p}^{2}) \sigma(\tilde{x}_{p}^{T}\tilde{w}) ||I - \sigma(\tilde{x}_{p}^{T}\tilde{w})| \tilde{x}_{p}^{2} + C ||u||_{2}^{2}$ $= \lambda \sum_{p = I} (\sigma(\tilde{x}_{p}^{T}\tilde{w}) - y_{p}^{2}) \sigma(\tilde{x}_{p}^{T}\tilde{w}) ||I - \sigma(\tilde{x}_{p}^{T}\tilde{w})| \tilde{x}_{p}^{2} + C ||u||_{2}^{2}$ $= \lambda \sum_{p = I} (\sigma(\tilde{x}_{p}^{T}\tilde{w}) - y_{p}^{2}) \sigma(\tilde{x}_{p}^{T}\tilde{w}) ||u||_{2}^{2}$ $= \lambda \sum_{p = I} (\sigma(\tilde{x}_{p}^{T}\tilde{w}) - y_{p}^{2}) \sigma(\tilde{x}_{p}^{T}\tilde{w}) ||u||_{2}^{2}$ $= \lambda \sum_{p = I} (\sigma(\tilde{x}_{p}^{T}\tilde{w}) - y_{p}^{2}) \sigma(\tilde{x}_{p}^{T}\tilde{w}) ||u||_{2}^{2}$ $= \lambda \sum_{p = I} (\sigma(\tilde{x}_{p}^{T}\tilde{w}) - y_{p}^{2}) \sigma(\tilde{x}_{p}^{T}\tilde{w}) ||u||_{2}^{2}$ $= \lambda \sum_{p = I} (\sigma(\tilde{x}_{p}^{T}\tilde{w}) - y_{p}^{2}) \sigma(\tilde{x}_{p}^{T}\tilde{w}) ||u||_{2}^{2}$ $= \lambda \sum_{p = I} (\sigma(\tilde{x}_{p}^{T}\tilde{w}) - y_{p}^{2}) \sigma(\tilde{x}_{p}^{T}\tilde{w}) ||u||_{2}^{2}$ $= \lambda \sum_{p = I} (\sigma(\tilde{x}_{p}^{T}\tilde{w}) - y_{p}^{2}) \sigma(\tilde{x}_{p}^{T}\tilde{w}) ||u||_{2}^{2}$ $= \lambda \sum_{p = I} (\sigma(\tilde{x}_{p}^{T}\tilde{w}) - y_{p}^{2}) \sigma(\tilde{x}_{p}^{T}\tilde{w}) ||u||_{2}^{2}$ $= \lambda \sum_$