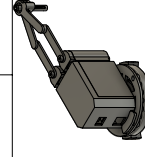
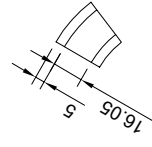
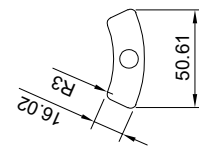
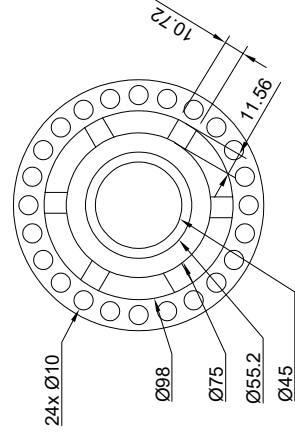
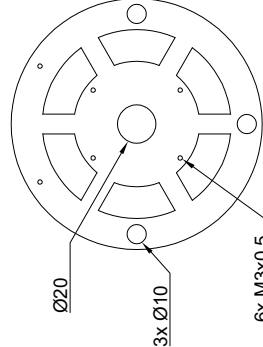
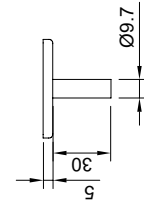
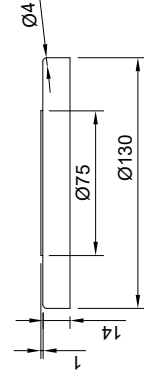
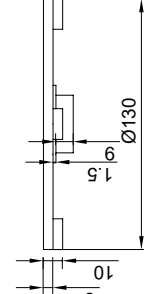
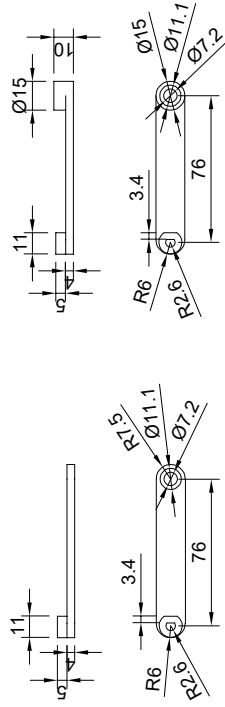
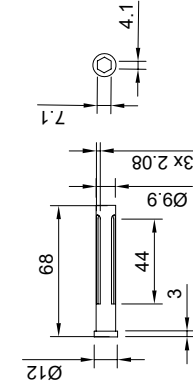
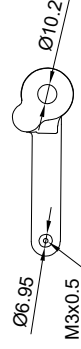
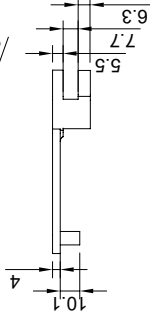
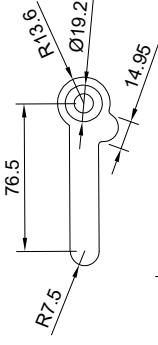
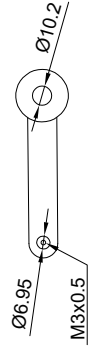
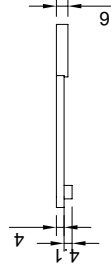
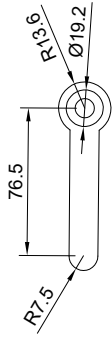
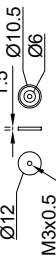


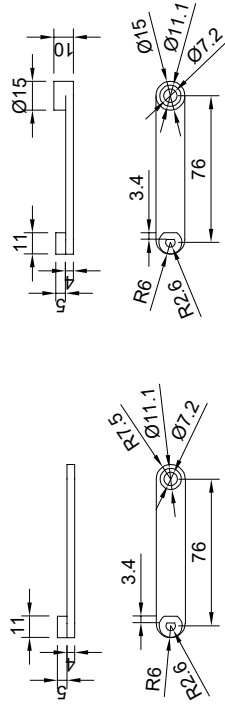
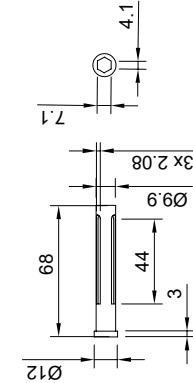
Arm L2R



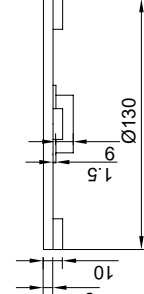
2x Cap for passive joints

**Pen Holder**

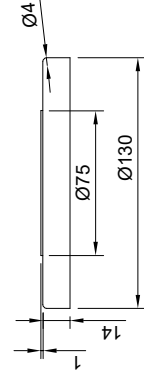
Arm L1L



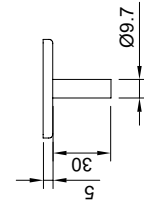
Base - Top Disk



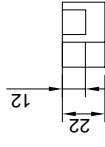
Base - Bottom Disk



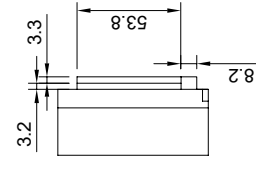
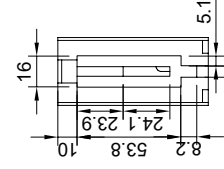
Base - Lock



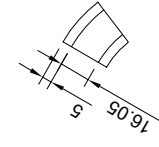
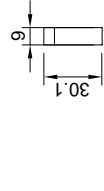
4x Legs




2x Motor casings



2x Motor Caps



Dept.	Technical reference	Created by ANA-MARIA CHIRIAC	Approved by						
		Document type Final Design Drawings	Document status Drawings 1:2 unless stated						
		Title MEDICAL APPLIED ROBOTICS MR10060	DWG No. Group Project final product						
	1:7		<table><tr><td>Rev.</td><td>Date of issue</td><td>Sheet</td></tr><tr><td></td><td>05/01/2016</td><td>1/1</td></tr></table>	Rev.	Date of issue	Sheet		05/01/2016	1/1
Rev.	Date of issue	Sheet							
	05/01/2016	1/1							