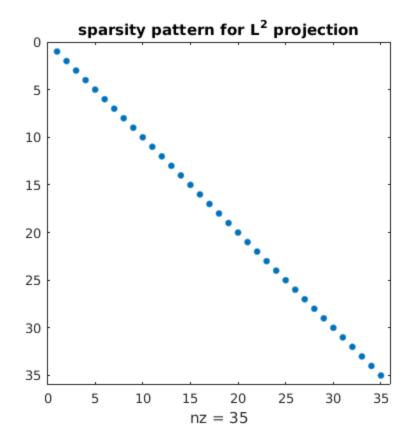
Table of Contents

```
clear all; close all;
%parameters
syms R0;
syms r theta phi x y z;
assumeAlso(0<=phi<=2*pi);
assumeAlso(0<=theta<=2*pi);
assumeAlso(r>0);
assumeAlso(R0>r);
assumeAlso(R0-r>0);
assumeAlso(R0>0);
```

Coordinate transformation

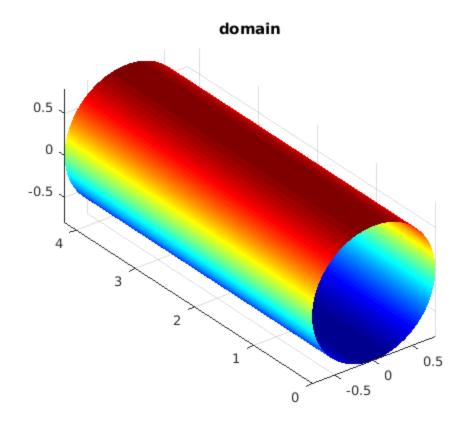
```
The coordinate transformation for a torus T=[(R0+ r.*cos(theta)).*cos(phi) ; ... (R0+
r.*cos(theta)).*sin(phi);... r.*sin(theta)]; The coordinate transformation for a cylinder
T=[r.*cos(theta); ...
    phi;...
   r.*sin(theta)];
% Cartesian coordinates as function Handles
X=matlabFunction( T(1,:), 'Vars',[r,theta,phi,R0]);
Y=matlabFunction( T(2,:), 'Vars', [r,theta,phi,R0]);
Z=matlabFunction( T(3,:),'Vars',[r,theta,phi,R0]);
Jacobi matrix of the transformation
J_T= simplify(jacobian(T', [r theta phi]));
% Inverse of Jacobi matrix
J_T_inv=simplify(inv(J_T),'Steps', 10);
L=-simplify(J_T_inv*J_T_inv'*det(J_T));
% Tnteger modes
syms n m integer;
% Basis function constant in r
psi=symfun(exp(1j*(n*phi+m*theta)),[m,n]);
```

```
% Gradient of basis function
psi grad=gradient(psi,[r theta phi]);
syms m1 n1 m2 n2;
% K=symfun(simplify(psi_grad(m1,n1)'*L*psi_grad(m2,n2)),...
       [m1,n1,m2,n2]);
M=simplify(psi(m1,n1)'*psi(m2,n2)*-det(J_T));
% M=simplify(subs(subs(M,'r',1),'R0',5));
M=symfun(M,[m1,m2,n1,n2]);
num theta=3; num phi=2;
[m,n]=ndgrid( -num_theta:1:num_theta, -num_phi:1:num_phi);
m=reshape(m,numel(m),1);
n=reshape(n,numel(n),1);
nm=[n,m];
MM=sym(zeros((num_theta*2+1)*(num_phi*2+1)));
for idx=1:length(nm)
   for jdx=idx:length(nm)
       MM(idx,jdx)=int(int(...
           M(nm(idx,2),nm(jdx,2),nm(idx,1),nm(jdx,1)),...
           phi,0,2*sym('pi')),theta,0,2*sym('pi'));
   end
end
MM=MM+MM'-diag(diag(MM));
% Plot sparsity pattern
spy(MM);
title('sparsity pattern for L^2 projection');
```



Visualization

Set up grid in theta-phi plane for visulization

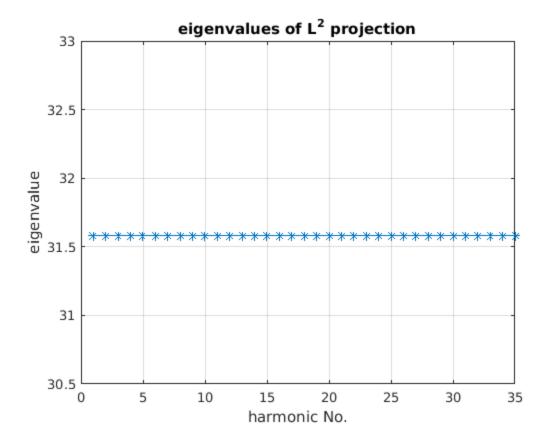


Spectrum of the L2 projection

```
%Get symbolic eigenvectors and eigenvalues
[MM_V,MM_D]=eig(MM);

% Sort eigenvalues, eigenvectors for the given parameters
[D,idx]=sort(double(subs(subs(diag(MM_D),r,minorR),R0,majorR)));
V=MM_V(:,idx);
V=double(subs(subs(V,r,minorR),R0,majorR));

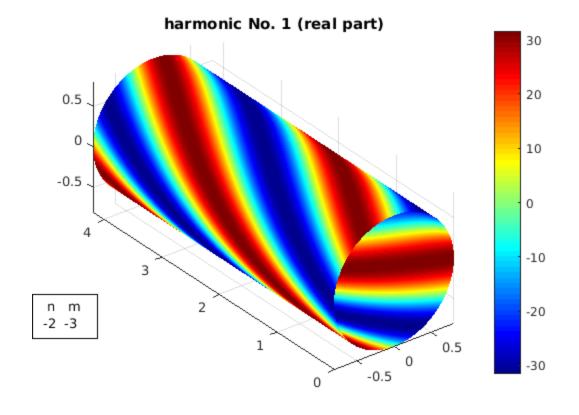
figure;
plot(D,'*-');
xlabel('harmonic No.');
ylabel('eigenvalue');
%axis([1,length(D),-inf,inf]);
title('eigenvalues of L^2 projection'); grid on;
```

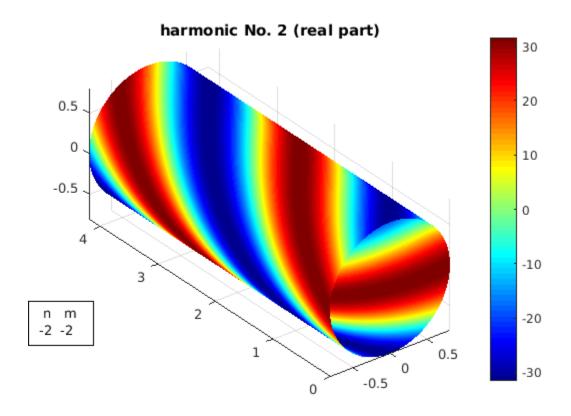


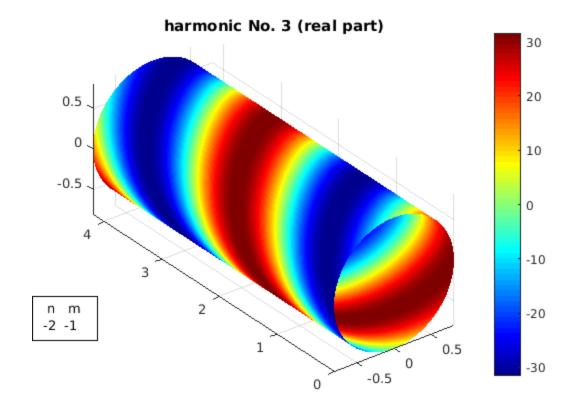
Harmonics of L^2 projection

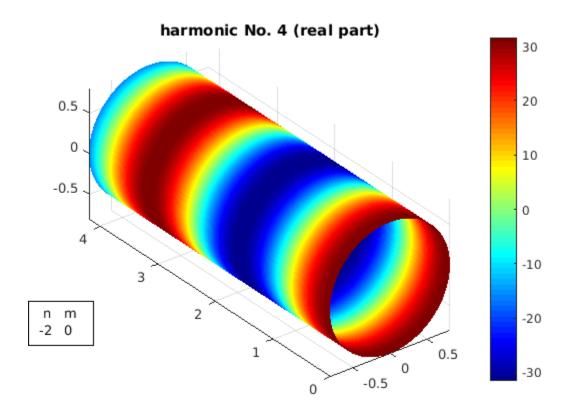
```
figure;
for idx=1:size(V,2)
    figure;
    coeffs=V(:,idx);
    modes=nm(coeffs~=0,:);
    coeffs=coeffs(coeffs~=0);
    fun=0;
    for jdx=1:size(modes,1)
        fun=fun+coeffs(jdx)*exp(1j*...
            (modes(jdx,1)*PHI+(modes(jdx,2)*THETA)));
    end
    surf(XX,YY, ZZ,real(fun)*D(idx));
    axis equal; grid on; colormap jet; shading interp;
    colorbar;
    title(sprintf('harmonic No. %d (real part)', idx));
str=cell(size(modes,1)+1,1);
str{1}=' n
for kdx=1:size(modes,1)
str\{kdx+1\}=sprintf('*3d *3d', modes(kdx,1), modes(kdx,2));
end
```

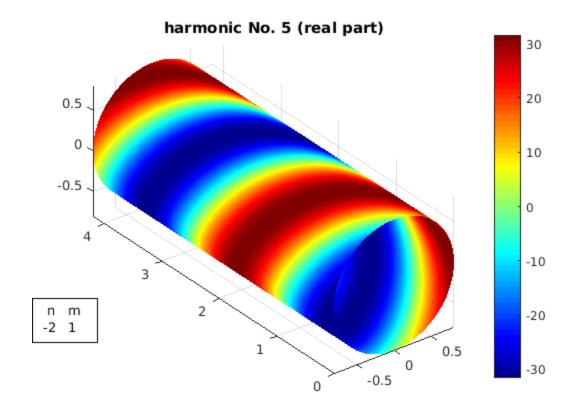
```
dim = [0 0 0.3 0.3];
annotation('textbox',dim,'String',str,'FitBoxToText','on');
end
```

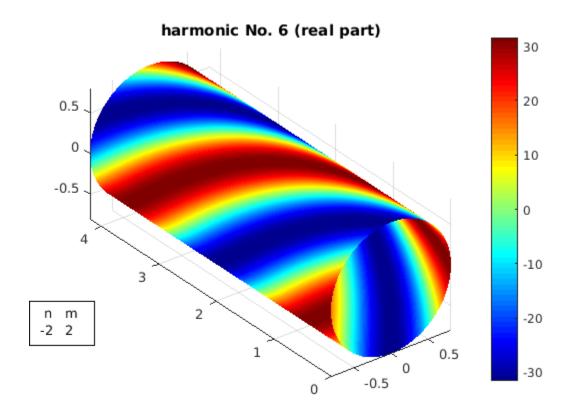


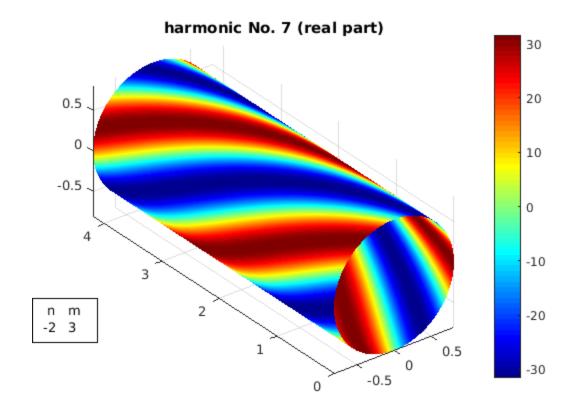


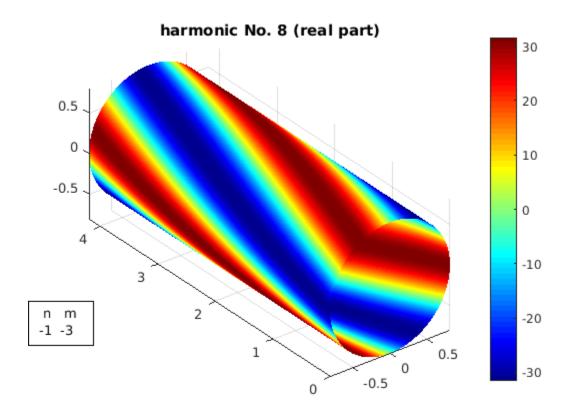


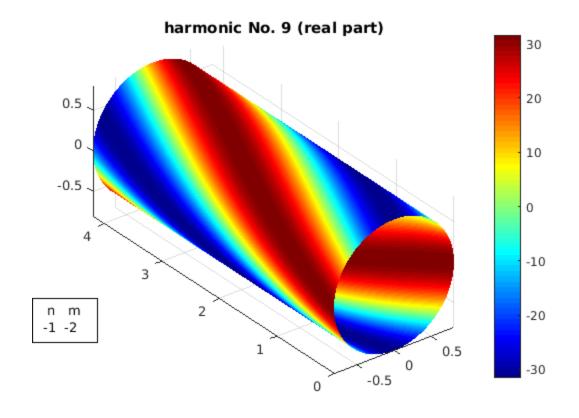


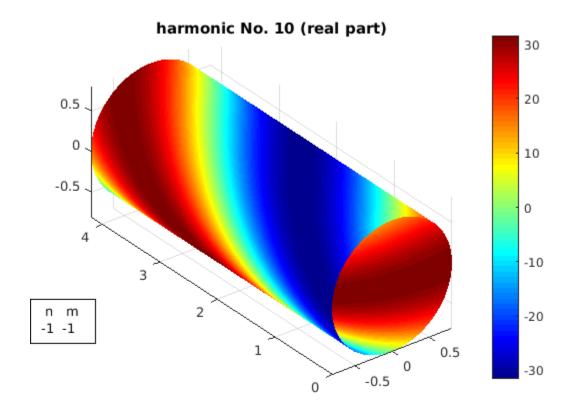


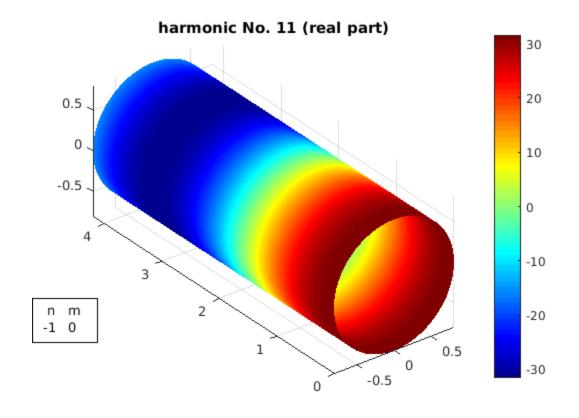


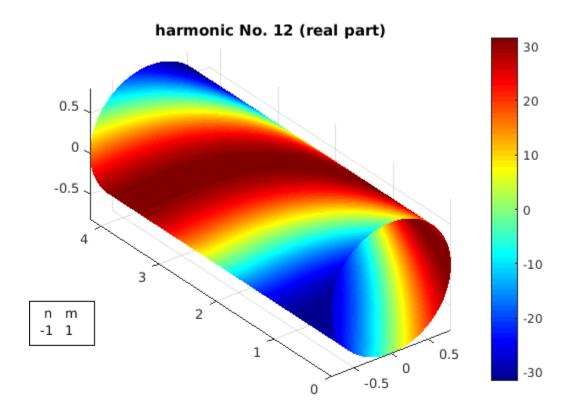


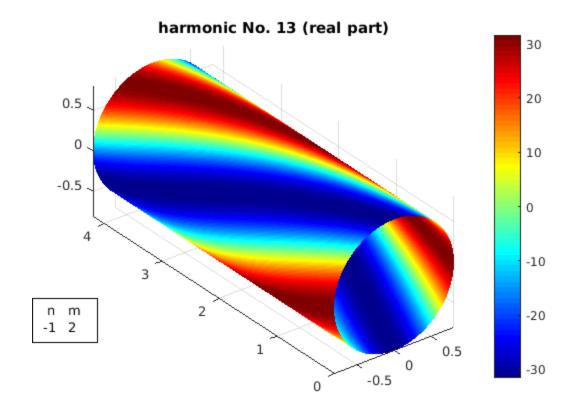


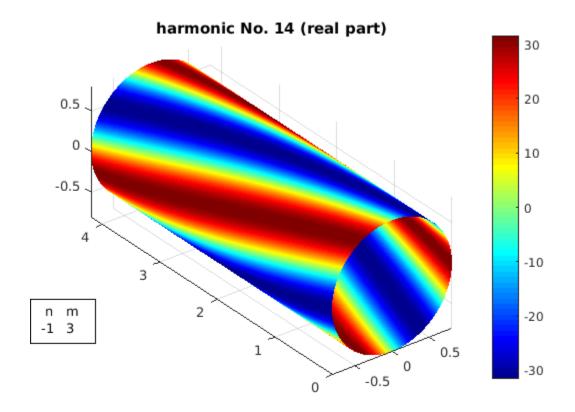


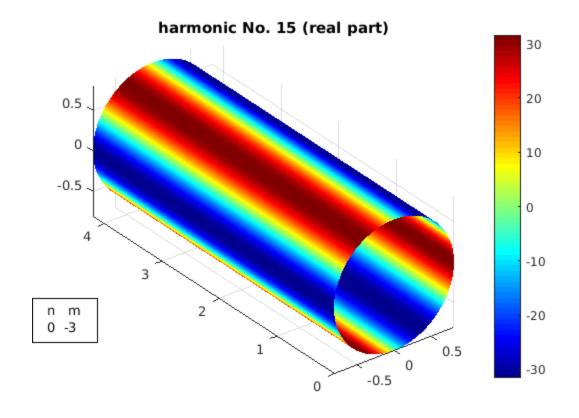


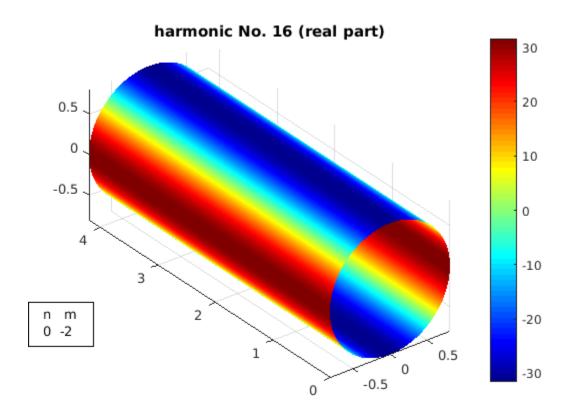


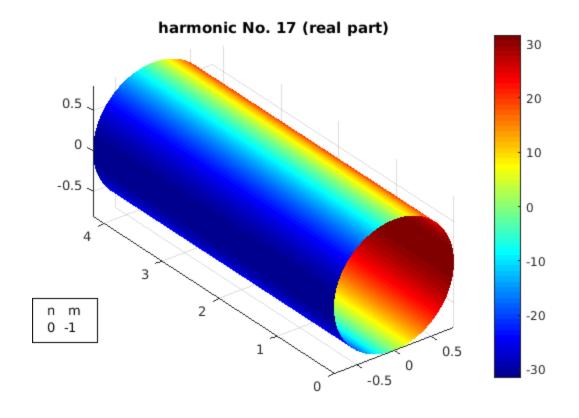


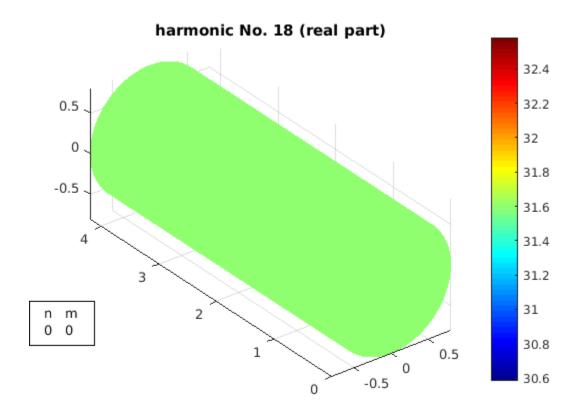


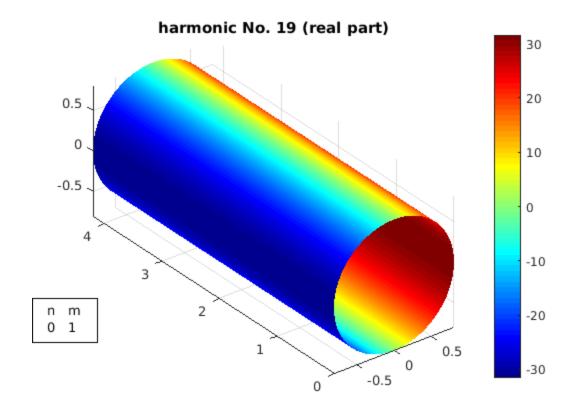


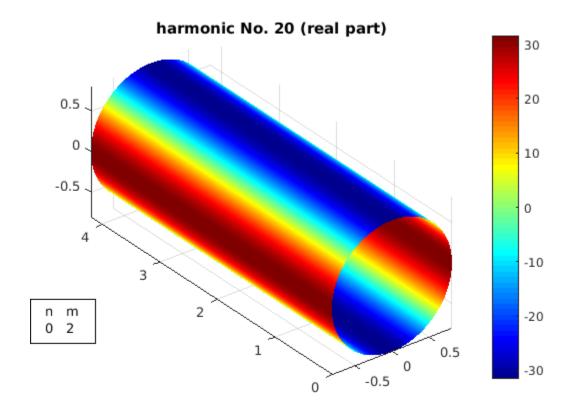


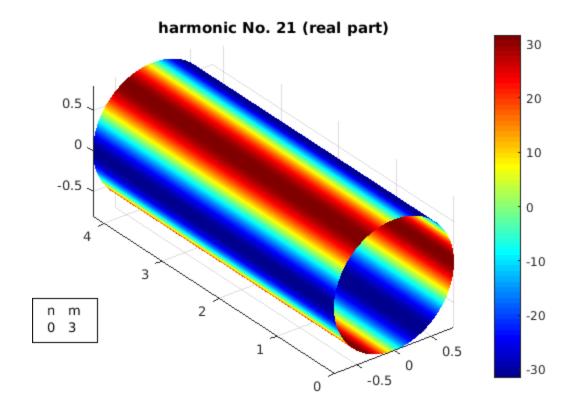


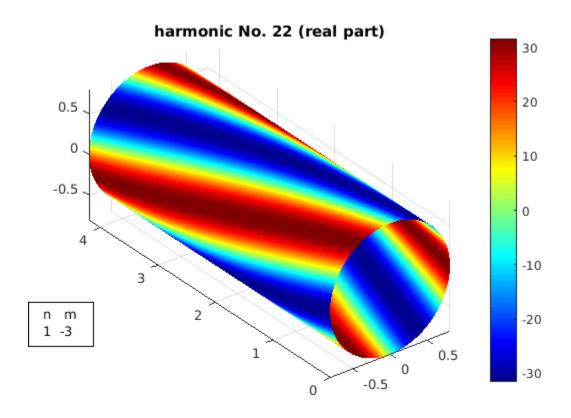


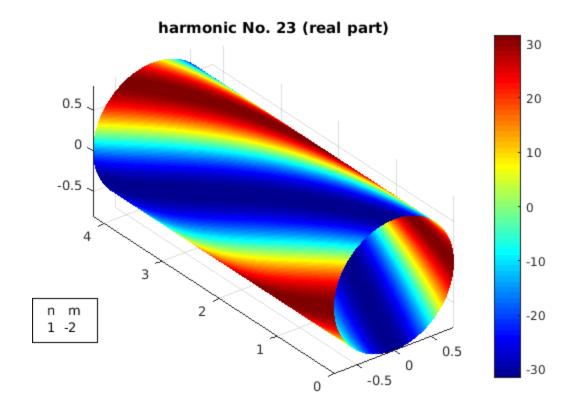


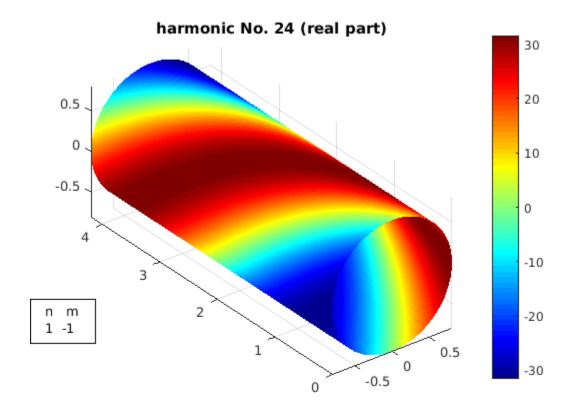


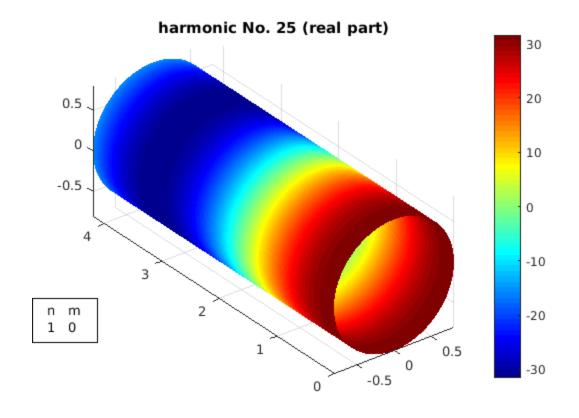


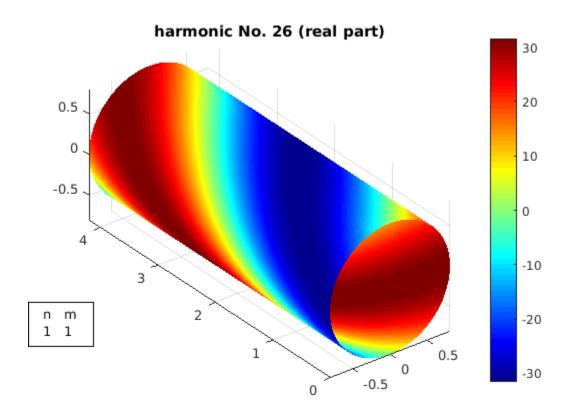


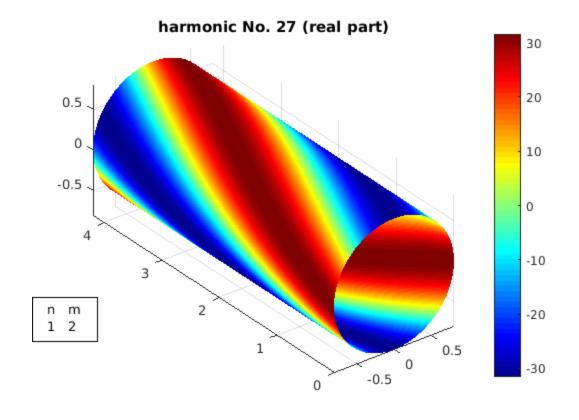


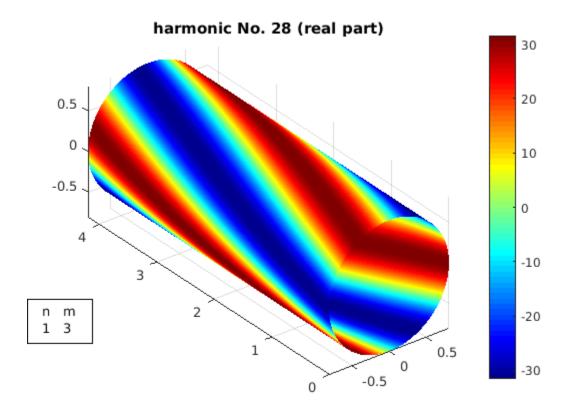


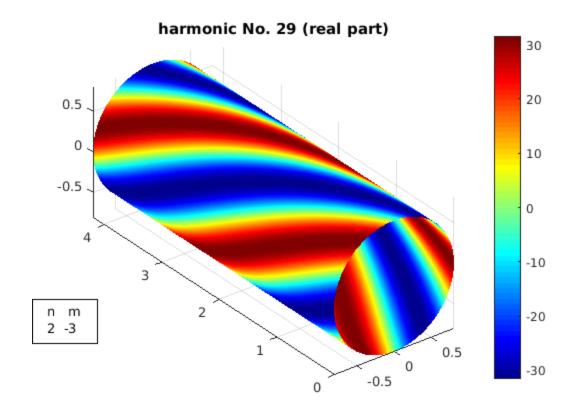


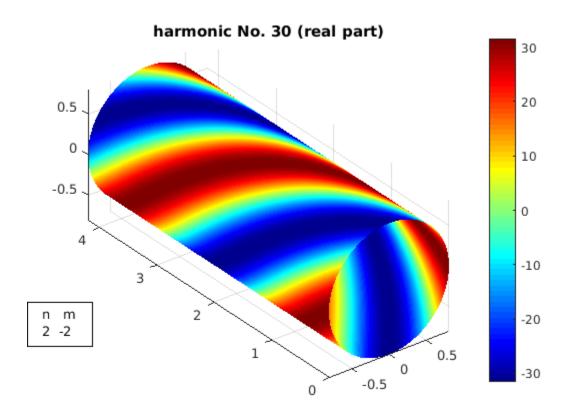


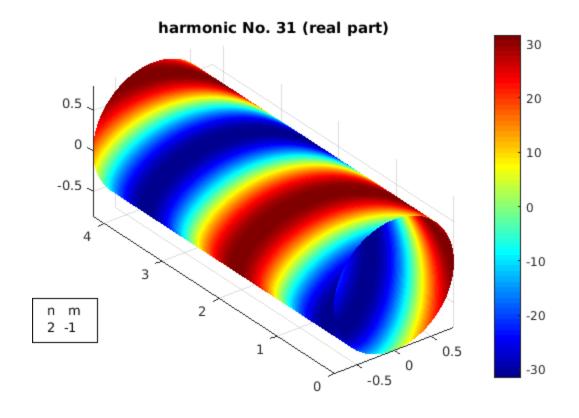


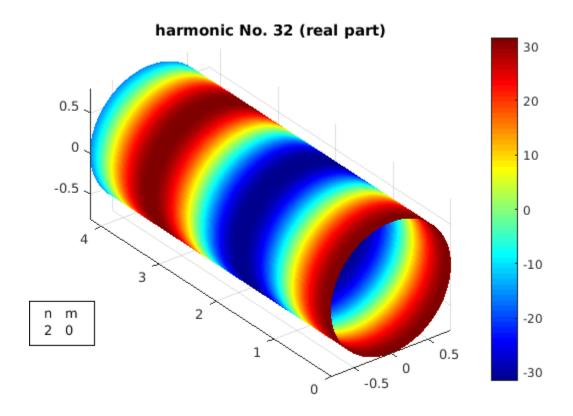


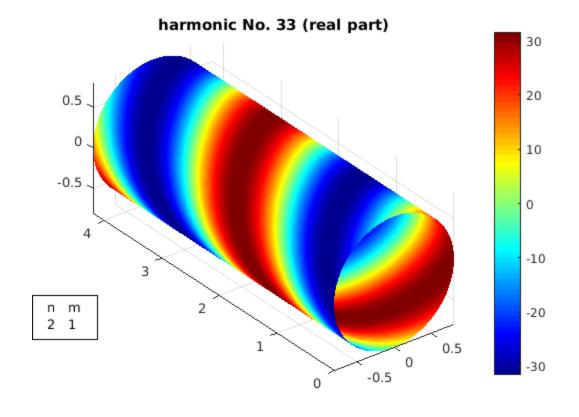


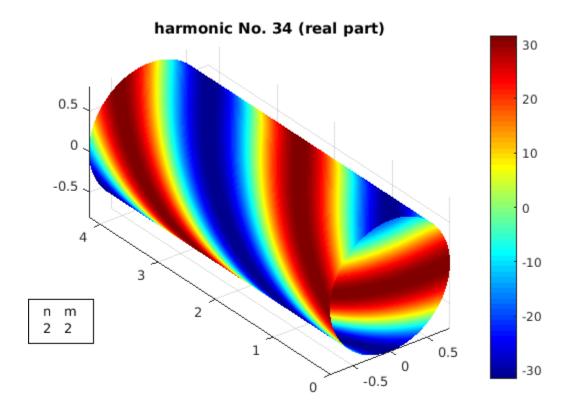


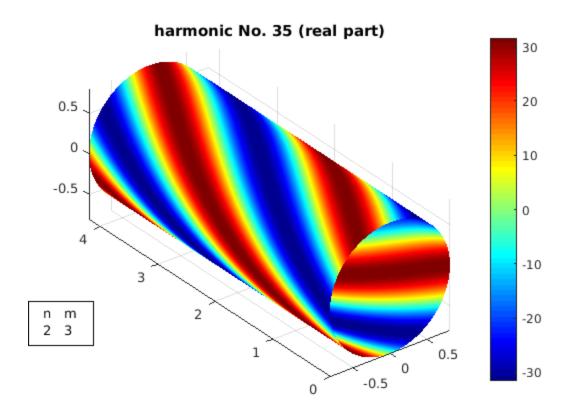












Filtering

The standard approach is to keep just a certain set of Fourier modes this corresponds to ommiting one basis function and its complex conjugate

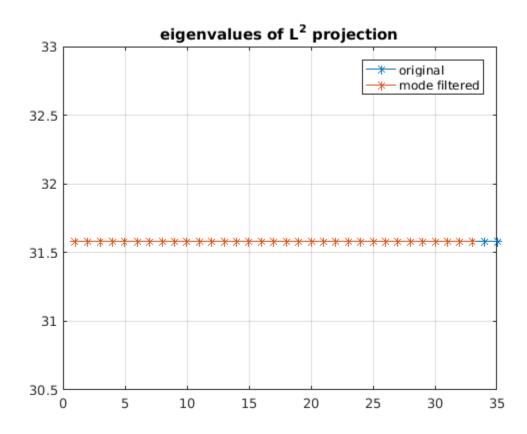
```
filter.nm=[2 3];
% assemble filter matrix
filter.mat=eye(size(MM));
%delete mode ...
idx=find((nm(:,1)==filter.nm(1) & nm(:,2)==filter.nm(2)));
filter.mat(idx,idx)=0;
%and complex conjugate
idx=find((nm(:,1)==-filter.nm(1) & nm(:,2)==-filter.nm(2)));
filter.mat(idx,idx)=0;
%Apply filter
filter.MM=filter.mat'*MM*filter.mat;
%Calculate eigenvalues of filtered matrix
filter.D=eig(double(subs(subs(filter.MM,r,minorR),R0,majorR)));
filter.D(filter.D==0)=[];
% Eigenvalues of original matrix
```

```
d1=eig(double(subs(subs(MM,r,minorR),R0,majorR)));
% Eigen
d2=eig(double(subs(subs(filter.MM,r,minorR),R0,majorR)));
d2(d2==0)=[];
```

Filtering changes global spectrum of operator

Whereas filtering directly the eigenvalues leaves the spectrum untouched and acts only locally. This also works in radial direction

```
figure
plot(D,'*-'); hold on;
plot(filter.D,'*-');
legend('original','mode filtered');
title('eigenvalues of L^2 projection'); grid on;
```



Harmonics of Laplace operator

```
Todo
%
%
%
%
%
%
sort(diag(U))
```

```
응
% Mint=matlabFunction(M,'Vars',[theta,phi,m1,m2,n1,n2]);
% num_theta=5; num_phi=5;
% [m,n]=ndgrid( -num_theta:1:num_theta, -num_phi:1:num_phi);
% m=reshape(m,numel(m),1);
% n=reshape(n,numel(n),1);
% nm=[n,m];
응
% M=zeros((num theta*2+1)*(num phi*2+1));
% for idx=1:length(nm)
     for jdx=idx:length(nm)
응
         M(idx,jdx)=sum(sum(Mint(THETA,PHI,...
응
             nm(idx, 2), nm(jdx, 2), nm(idx, 1), nm(jdx, 1)))...
ွ
             *(2*pi/length(int_grid))^2;
응
     end
% end
% M(abs(M)<1e-13)=0;
% M=M+M'-diag(diag(M));
응
응
% abs(nm) == 0
% size(M)
% rank(M)
્ર
% K=psi_grad(m1,n1)'*L*psi_grad(m2,n2);
% K=subs(subs(K,'r',1),'R0',5);
% K=simplify(K);
용
% disp(K)
응 응
 int(int(psi_grad(m1,n1)'*L*psi_grad(m2,n2),phi,0,2*pi),theta,0,2*pi)
% %K_mn=int(int(K_mn, theta,0,2*pi),phi,0,2*pi);
% Kint=matlabFunction(K,'Vars',[theta,phi,m1,n1,m2,n2]);
Sec.
% real(K)
% integral2(@(x,y)real(Kint(x,y,1,1,3,3)),0,2*pi,0,2*pi)
응
% integral( @(x)exp(1j*(1)*x),0,2*pi)
응
9
응
% K_mn=simplify(int(K, phi,0,2*pi));
% simplify(K_mn)
```

```
% simplify(K_mn(2,2,3,3))
% int(K
응
%
% int(exp(1j*(n1-n2)*theta),0,2*pi)
% K_mn(nm)
% K=zeros(num_phi*num_theta);
%
응
응
% nm=1;
% n=1;
% for idx=1:size(K,1)
% for jdx=idx:size(K,1)
응
% end
%
% end
%
% subs(L)
%
응
%
% %% Flux surface
응
응
%
% r=1;
% R0=4;
% syms R0 r;
% [V,D]=eig([ 2*pi*R0*r, pi*r^2; pi*r^2, 2*pi*R0*r]);
응
%
```

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