Machine Learning Assignment 1

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INTRODUCTION

Supervised machine Learning generally boils down to approximating a continuous function. One method of doing so is by making use of Linear Regression. In any method whatsoever, there always remains a set of hyperparameters which need to be tuned intuitively. In this assignment, we experiment with various values of such hyperparameters and try to draw a conclusion out of them.

EXPERIMENTATION

Part 1

A synthetic dataset is generated and is divided into train and test in a 4:1 ratio randomly. This is done by permuting the data in a random fashion and choosing the first 80% of the dataset to be the training set and the rest to be the test set. This part is kept as a separate function to make sure new data is generated only when required, and not all the time before training. The data is saved in the present working directory.

The dataset is then trained using Linear regression. The weights are initialised to random values between zero and one. At the end of each iteration, the loss up to that iteration is sent to STDOUT. Gradient descent is performed as per the following rule:

$$\theta_j := \theta_j - \alpha \frac{1}{m} \sum_{i=1}^m (h_\theta(x^{(i)}) - y^{(i)}) x_j^{(i)}$$

Here θ is the weight vector, with θ_j marking each element of the vector. α is the learning rate, m is the number of training examples and h_{θ} is the hypothesis function.

The training function returns the training error, testing error and the RMSE error. For the error, we use squared loss, i.e.:

$$J(\theta) = \frac{1}{2m} \sum_{i=1}^{m} \left(W^{T} \Phi_{n}(x) - y \right)^{2}$$

The training takes place separately for degrees 1 to 9. The degrees denote the polynomial degree of the function we are trying to approximate. Since bias is also introduced, there are a total of degree + 1 parameters to be tuned while training. At the end of a certain number of iterations, these values are saved in the local directory.

The parameter values learned have been provided in Table 1. The first row denotes the degree.

1	2	3	4	5	6	7	8	9
0.797531 9619	0.823028 0506	0.818393 5063	1.166862 8	1.442892 006	1.594227 469			1.056935 601
-1.441639 135	-1.628034 357	-1.265472 884	-1.637685 999	-1.876832 283	-2.252152 497		-1.278813 704	-0.940861 88
	0.197333 2989	-1.059530 691	-1.869621 587	-2.140028 412	-1.565307 6			-1.410866 293
		0.969801 3993		-0.177134 7154		-1.541795 004		-0.929530 0843
			1.535320 926	0.413476 0332			-0.428483 5354	-0.410347 7217
				2.233017 764	1.128940 674	0.862934 4587	0.357140 9422	-0.016717 29166
					1.847131 128	0.816115 8519	-	0.103302 1222
						1.831891 609	0.845241 2498	0.523226 7054
							1.552610 11	0.886524 7169
								1.451567 311

Table 1: Weights for 10 datapoints

Part 2

Part 2 takes up the job of looking into how good the training went about using visual plots. First, it asks the user if there is a desire to generate a new dataset, or if at all the training needs to be performed again. After such confirmations, it proceeds to plot the data. First, it reads the saved data and weights after which it recomputes the test and train errors. This is done as the test and train errors, though computed, were not saved in Part 1. For plotting the approximated function using the given weights, the output of the function is obtained for inputs between 0 and 1, separated by 0.01. Thus, when a line plot is drawn on this, it gives the illusion of a curve.

Fig 1: Curve fitting against 10 datapoints

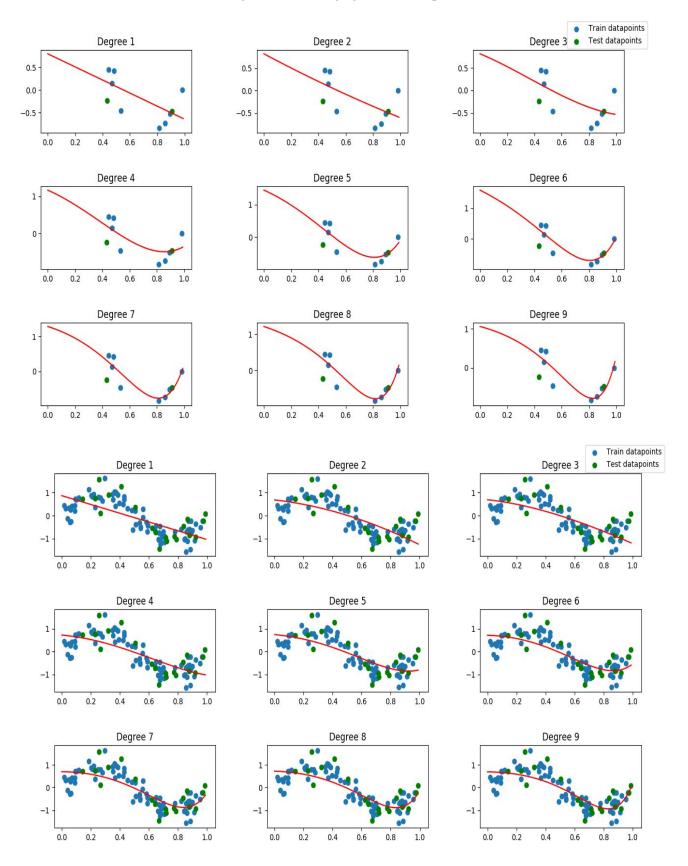


Fig 2: Curve fitting against 100 datapoints

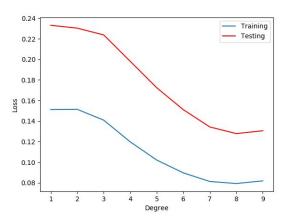


Fig 3: Loss v/s degree for 100 datapoints

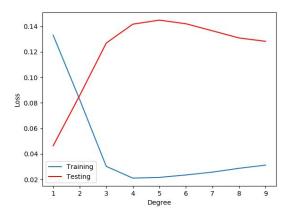


Fig 4: Loss v/s degree for 10 datapoints

Next, the error values obtained in the previous part is plotted against the degree of the polynomial function which is being approximated. Lastly, the degree for which the minimum value of test error was obtained, is returned.

In the experiment, it was found that if the number of datapoints is restricted to 10, the plots obtained were a bit arbitrary. When increased to 100, they looked like they had been anticipated.

Part 3

Part 3 makes a call to Part 2 to obtain the best value of n. Accordingly, it then instructs Part 1 to generate data with various sizes, namely 10, 100, 1,000, and 10,000. The weights obtained have been presented in Table 2, 3 and 4. Upon testing a number of times, the value of the best n is found according to the following distribution (Table 5). The plot against no of datapoints is given in Fig 5.

Table 5: Distribution of degrees

Degree	7	8	9
%	6.67	13.33	80.00

Table 2: Weights for 100 datapoints

1	2	3	4	5	6	7	8	9
0.871026 2544			0.908950 669				0.821845 2823	
-1.894498 614	-1.656683 609	-1.625247 068					-0.529345 3787	
	-0.226027 0969		-1.916144 381				-1.938706 417	
		1.160183 327	-0.460245 4562				-1.206534 577	
			2.240392 562				-0.917430 5237	
				1.875091 938	0.908160 266	0.605138 7781	0.439045 7082	0.381673 158
					2.073271 886		1.074630 988	
						1.563315 841	1.146619 257	0.708973 1967
							1.346124 277	1.513295 952
								1.273084 84

Table 3: Weights for 1000 datapoints

1	2	3	4	5	6	7	8	9
0.795294	0.795661	0.671008	0.674772	0.676215	0.741085	0.680414	0.797758	0.701040
9234	4451	6979	2721	1944	8763	0972	8119	2116
-1.606634	-1.160043	-0.635297	-0.771208	-0.597161	-1.063300	-0.659153	-1.048135	-0.675897
293	219	9473	8956	0846	577	834	427	5782
	-0.643251	-0.593078	-0.377599	-1.008405	-0.543273	-1.003218	-0.616417	-0.770524
	0116	5415	4579	992	5428	382	6367	1842
		-0.603542	-0.709381	-0.529990	-0.156100	-0.325332	-1.015222	-0.702825
		5272	2278	1328	4362	3324	288	1569
			0.082220	0.234952	-0.111481	-0.363662	-0.038812	-0.778274
			34768	8062	7494	6983	81459	6306
				0.267195	-0.173285	0.475429	0.417499	0.278040
				1549	7535	1399	5428	7732
					0.421244	0.043486	0.413433	0.087793
					2658	57395	1526	55429
						0.387009	-0.177975	0.338968
						0428	0626	5656

			0.767720 4145	0.901786 2445
				0.197253 533

Table 4: Weights for 10,000 datapoints

1	2	3	4	5	6	7	8	9
0.781714				0.682811				
3592	3363	0663	5004	1931	908	685	9958	7123
	-0.728133							
909	1692	4095	3226	8669	8963	6363	4965	198
				-0.319905				
	800	251	8272	1655	144	163	7892	8136
		-0.077089	-0.557043	-0.274101	-0.078618	-0.830478	-0.628142	-0.171826
		84932	3458	1187	73709	5904	2084	8267
			0.292768	-0.307388	-0.296437	0.032630	-0.196983	-0.722522
			2211	3862	6787	71575	0868	0256
				0.135145	0.453599	-0.065458	0.078122	0.038532
				2717	0327	67159	1145	14125
						0.560727		
					3538	4715	8567	6662
						0.817546	0.118368	-0.161832
						4423	9984	919
							0.691812	0.653741
							0453	6599
								0.828182
								0676

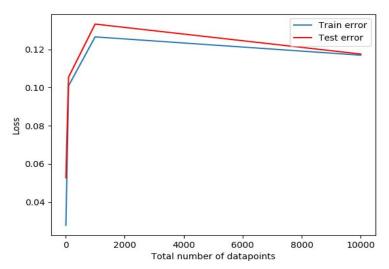


Fig 5: Loss v/s no of datapoints

Part 4

Two other cost functions were experimented with, namely the mean absolute error and the fourth power error. For the mean absolute error, the following formula was used for computing cost

$$J(\theta) = \frac{1}{2m} \sum_{i=1}^{m} \left| W^{T} \Phi_{n}(x) - y \right|$$

and the following for gradient.

$$rac{d ext{MAE}}{dy_{ ext{pred}}} = egin{cases} +1, & y_{ ext{pred}} > y_{ ext{true}} \ -1, & y_{ ext{pred}} < y_{ ext{true}} \end{cases}$$

For the fourth power error, the cost function was

$$\frac{1}{2m} \sum_{i=1}^{m} \left(W^T \Phi_n(x) - y \right)^4$$

Table 6: Weights for Squared error loss

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0.025	0.05	0.1	0.2	0.5				
0.7293215757	0.7465717494	0.9291357642	1.042771469	0.9614016857				
-0.7186918233	-0.8293871128	-0.9888155837	-1.183347055	-0.5719301969				
-0.845257154	-0.9279066871	-1.329807527	-1.330827547	-1.885688898				
-0.8664141269	-0.2307502415	-0.8151101417	-0.9837553255	-1.699878445				
0.07024936875	-0.1309270971	-0.3318826047	-0.6089554393	-0.173358147				
0.1790967975	-0.1041283308	0.246028049	-0.1855961717	-0.2156919053				
-0.1095506467	0.1267188376	0.4721587248	0.9466496538	0.669988285				
0.3165117195	-0.1687833015	0.7737945748	0.4701290394	0.8501394341				
0.2331473181	0.7872001551	0.8259655405	1.190339921	1.096247705				
0.5834135234	0.242288971		0.6975961542	1.155297139				

Accordingly, the gradient comes out to be

$$\frac{2}{m} \sum_{i=1}^{m} (h_{\theta}(x^{(i)}) - y^{(i)})^{3} x_{j}^{(i)}$$

Here, the weights have been initialised randomly between 0 and 0.001 to prevent exploding of values.

The RMSE error is trained and computed for each degree. For each instance of the learning rate (0.025, 0.05, 0.1, 0.2 and 0.5) and for every cost function, the degree having the minimum value of RMSE is chosen and plotted across the learning rate values. The weights have been given in Table 6, 7 and 8. The provided weights are for that degree for which the minimum value of RMSE was obtained. The first row of the table mentions the learning rate.

Table 7: Weights for Mean Absolute Error

0.025	0.05	0.1	0.2	0.5
0.5897437497	0.7458329931	0.990000795	1.225462428	1.269331133
-0.5366108515	-0.7737905044	-1.352076637	-1.661870657	-1.43829365
-0.5703084878	-0.5708972985	-0.8887757569	-1.341224788	-1.558887571
-0.5431326869	-1.033364742	-0.3741909892	-0.4470348273	-1.569393699
-0.3934620506	0.06160323211	-0.5582285952	-0.1297491422	-0.2512687934
0.263836122	0.266539504	0.1825713155	-0.3301895356	0.3245040276
0.2240216534	0.06892601893	0.4764327226	0.2615325467	0.9356641203
0.02726837111	0.2371244755	0.3778189537	0.3538152723	1.070499122
-0.1784790498	0.5112638983	0.3292100977	1.07589597	1.193997085
0.5924522313		0.5246380648	0.9210709979	

Table 8: Weights for Fourth Power Error

0.025	0.05	0.1	0.2	0.5
0.6245150067	0.8007088396	0.9432650773	0.989307045	0.9290307589
-0.670324757	-0.9542326425	-1.168411553	-1.129097379	-0.6344867589
-0.6319956396	-0.883328324	-1.152236085	-1.400483947	-1.812908766
-0.3972964747	-0.5198589783	-0.6711720606	-0.870859511	-1.294542826
-0.1873818257	-0.1955922497	-0.2225846011	-0.3046772061	-0.5224040152
-0.0342709929				
7	0.04018260693	0.1083178591	0.1296636942	0.1047213058
0.0724038637	0.201124684	0.3334643396	0.4263289758	0.5362645949
0.1431212527	0.3063118265	0.4794926944	0.618876233	0.8057831371
0.1888810998	0.3731522693	0.5704175346	0.7354502344	0.9603547974
0.2180880341	0.4133952611	0.6234962827	0.8010226496	1.034530432

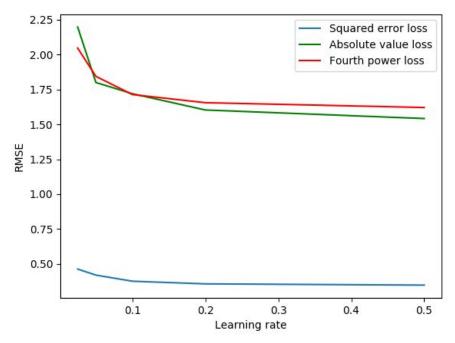


Fig 6: Test RMSE v/s Learning rate

CONCLUSION

We conclude that the best degree for fitting the curve has been 9 (as evident from Table 5), as seen in Part 4. The best cost function is Squared Error Loss (as evident from Fig 6). In reality, higher powers are prone to noises, and since noises were manually added to the synthetic dataset generated, perhaps that's why it did not perform well. The mean absolute error is not differentiable and hence, not used in general. The best learning rate has been experimentally found to be 0.5. Along with that, we can infer that we should have sufficient number of datapoints to draw valid conclusions about our model. For instance, in Part 2, having 10 datapoints gave us a wrong notion about our model (ref to Fig 4), whereas having a 100 datapoints could fit the data better (Fig 2). Having an even higher no of datapoints decreases the loss, as evident in Part 3 (Fig 5).

REFERENCES

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