



Data driven inference of model discrepancies in Zika virus dynamics

Michel Tosin

michel.tosin@uerj.br

Americo Cunha Jr

americo@ime.uerj.br

Flávio Coelho

fccoelho@fgv.br

NUMERICO – Nucleus of Modeling and Experimentation with Computers

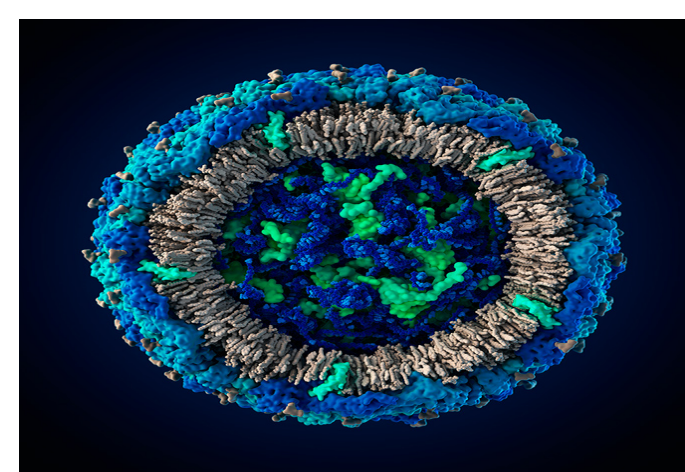


Introduction

- Zika virus: global widespread and connection with **congenital diseases**
- 2016: Zika becomes a **public health emergency of international concern**
- Main vector: *Aedes* mosquitoes
- A **validated model** can reveal new characteristics of the disease
- Prediction results** are affected by model errors and lack of data
- Relations of **model parameters** are also of interest



Aedes aegypti



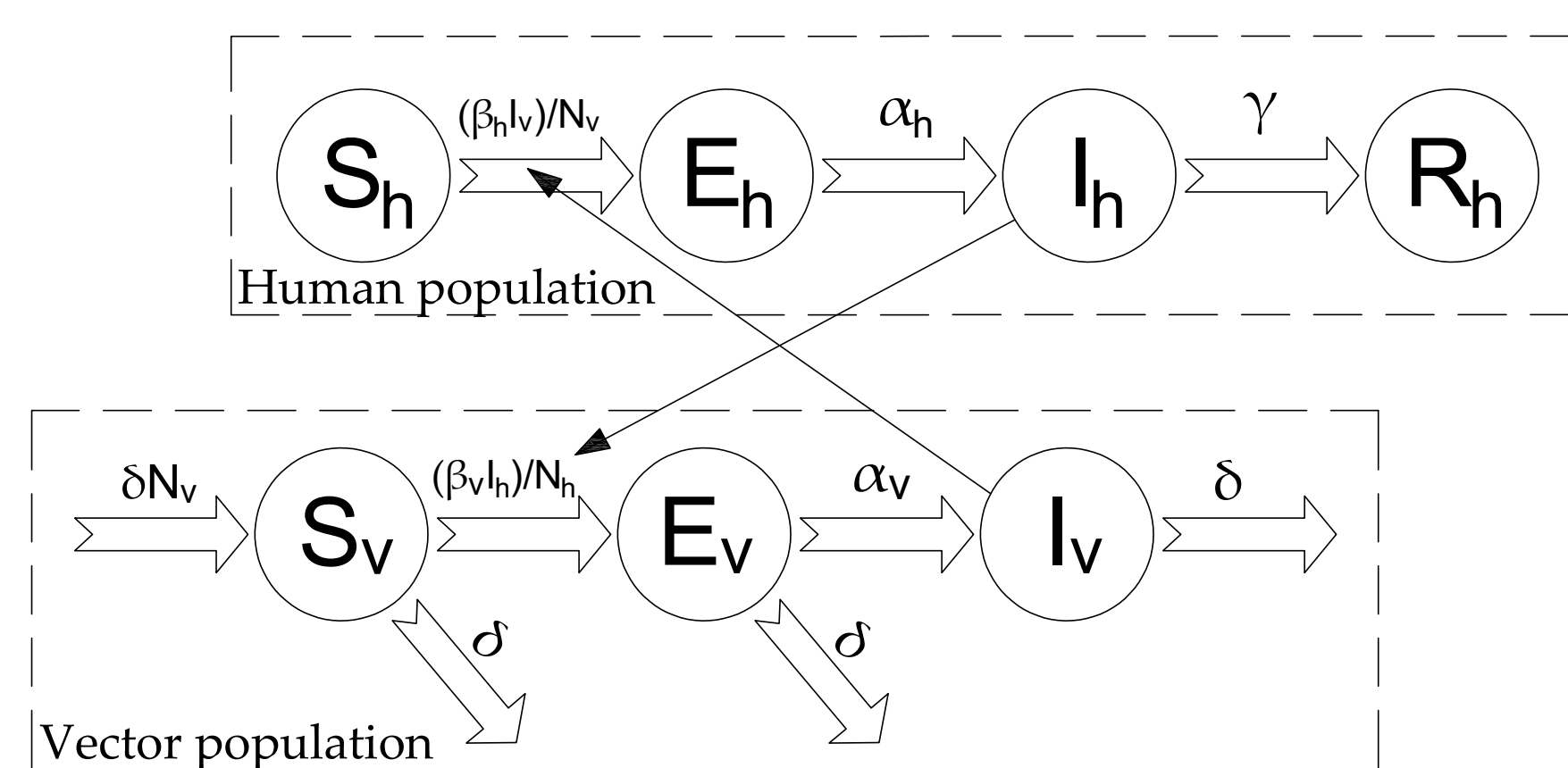
Zika virus

Objectives

- Perform sensitivity analysis to compare the **parameters' global effect** for a set of hierarchical models
- Improve a calibration result using a bigger data set obtained from a **hierarchical superior model**
- Develop a statistical framework using **Bayesian Inference** and **Polynomial Chaos Expansion** to quantify epidemic model discrepancies

Computational Model

SEIR-SEI Compartmental Model

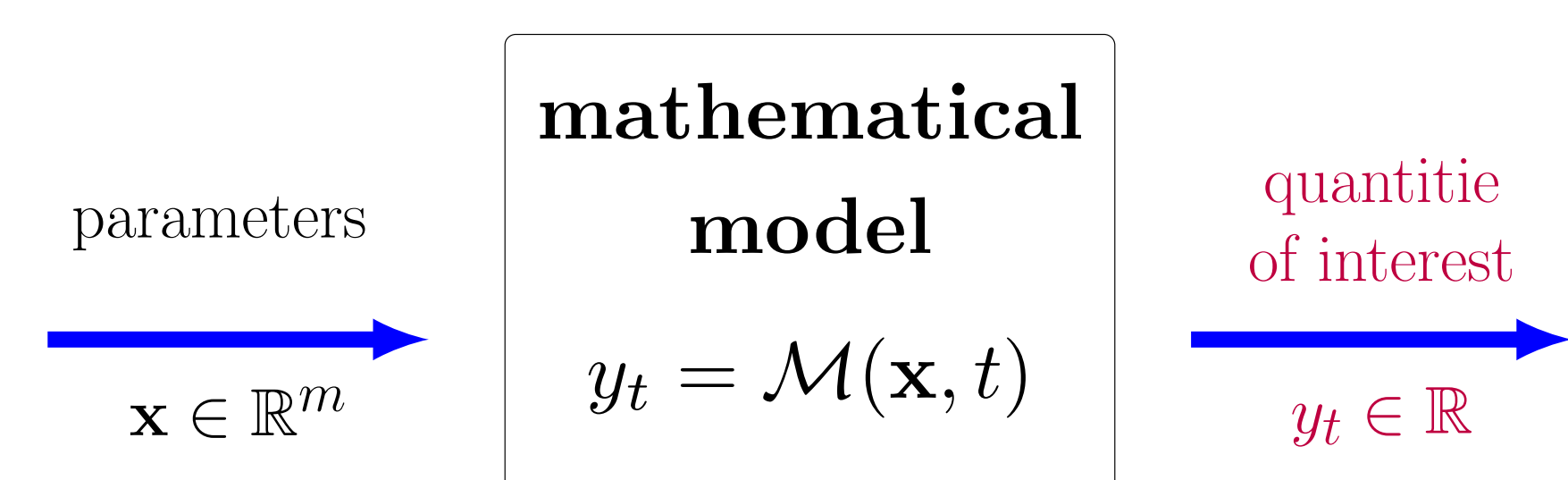


Dynamical System

$$\begin{aligned} \frac{dS_h}{dt} &= -\beta_h S_h \frac{I_v}{N_v}, & \frac{dS_v}{dt} &= \delta N_v - \beta_v S_v \frac{I_h}{N_h} - \delta S_v, \\ \frac{dE_h}{dt} &= \beta_h S_h \frac{I_v}{N_v} - \alpha_h E_h, & \frac{dE_v}{dt} &= \beta_v S_v \frac{I_h}{N_h} - (\alpha_v + \delta) E_v, \\ \frac{dI_h}{dt} &= \alpha_h E_h - \gamma I_h, & \frac{dI_v}{dt} &= \alpha_v E_v - \delta I_v, \\ \frac{dR_h}{dt} &= \gamma I_h, & \frac{dC}{dt} &= \alpha_h E_h. \end{aligned}$$

+ Initial Conditions

Quantities of Interest (QoI)



- Cumulative cases of infectious:** $C(t) = \int_{\tau=0}^t \alpha_h E_h(\tau) d\tau$
- New cases per week:** $N_w = C_w - C_{w-1}$, $w = 1 \dots 52$, $N_1 = C_1$

Sensitivity Analysis

The Hoeffding-Sobol' decomposition for n iid inputs $X_i \sim \mathcal{U}(0, 1)$ gives

$$Y_t = \mathcal{M}_0 + \sum_{1 \leq i \leq n} \mathcal{M}_i(X_i) + \sum_{1 \leq i < j \leq n} \mathcal{M}_{ij}(X_i, X_j) + \dots + \mathcal{M}_{1\dots n}(X_1 \dots X_n),$$

$$\mathcal{M}_0 = \mathbb{E}[Y_t], \quad \mathcal{M}_i(X_i) = \mathbb{E}[Y_t | X_i] - \mathcal{M}_0, \quad \mathcal{M}_{ij}(X_i, X_j) = \mathbb{E}[Y_t | X_i, X_j] - \mathcal{M}_0 - \mathcal{M}_i - \mathcal{M}_j.$$

Sobol' Indices: interaction effect of inputs in u

$$S_u = \text{Var} [\mathcal{M}_u(X_u)] / \text{Var} [\mathcal{M}(X)]$$

Metamodelling: Polynomial Chaos

The **Polynomial Chaos Expansion** of model $Y = \mathcal{M}(X)$, for a multivariate orthonormal polynomial family Φ_α with coefficients y_α ,

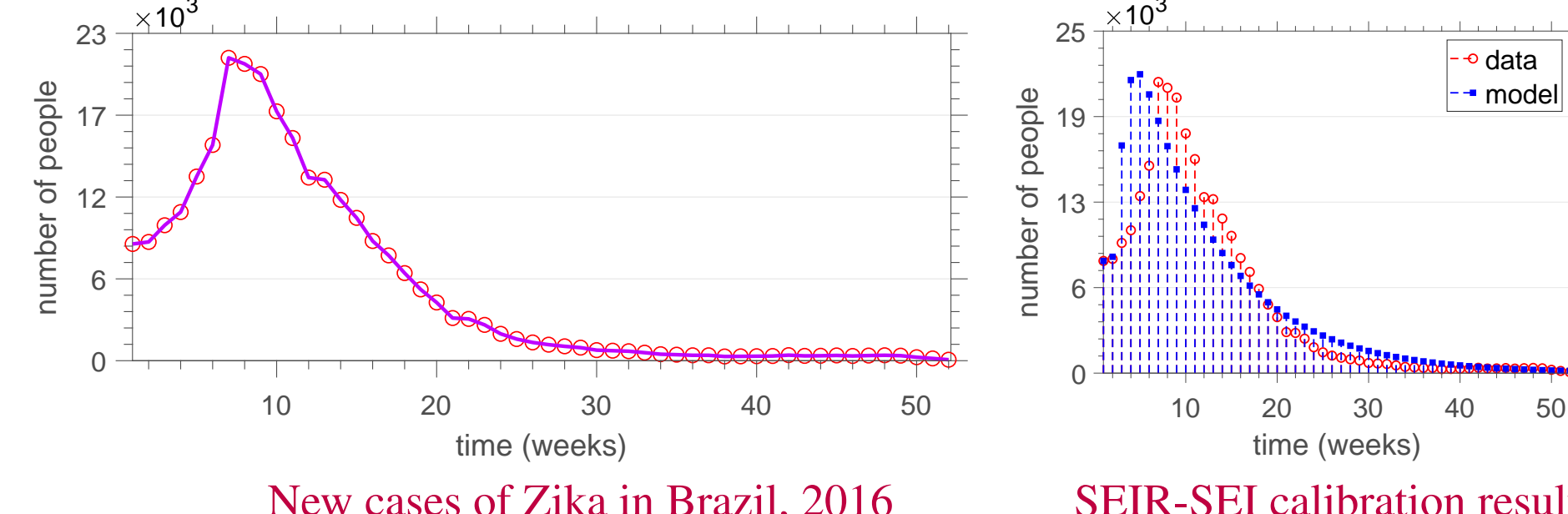
$$Y_t = \sum_{\alpha \in \mathbb{N}^k} y_\alpha(t) \Phi_\alpha(X),$$

enables **analytic** computation of **Sobol Indices**:

$$S_u = \sum_{\alpha \in \mathcal{A}_u} y_\alpha^2 / \sum_{\alpha \in \mathcal{A} \setminus \emptyset} y_\alpha^2, \quad \mathcal{A}_u = \{\alpha \in \mathcal{A} : i \in u \iff \alpha_i \neq 0\}$$

Hierarchical Calibration

⇒ **Real data set**: 52 values of New Cases of infectious humans for Zika by epidemiological week of 2016 from Brazil's Health Organizations



⇒ **New data set**: 358 values of Cumulative Cases from SEIR-SEI model

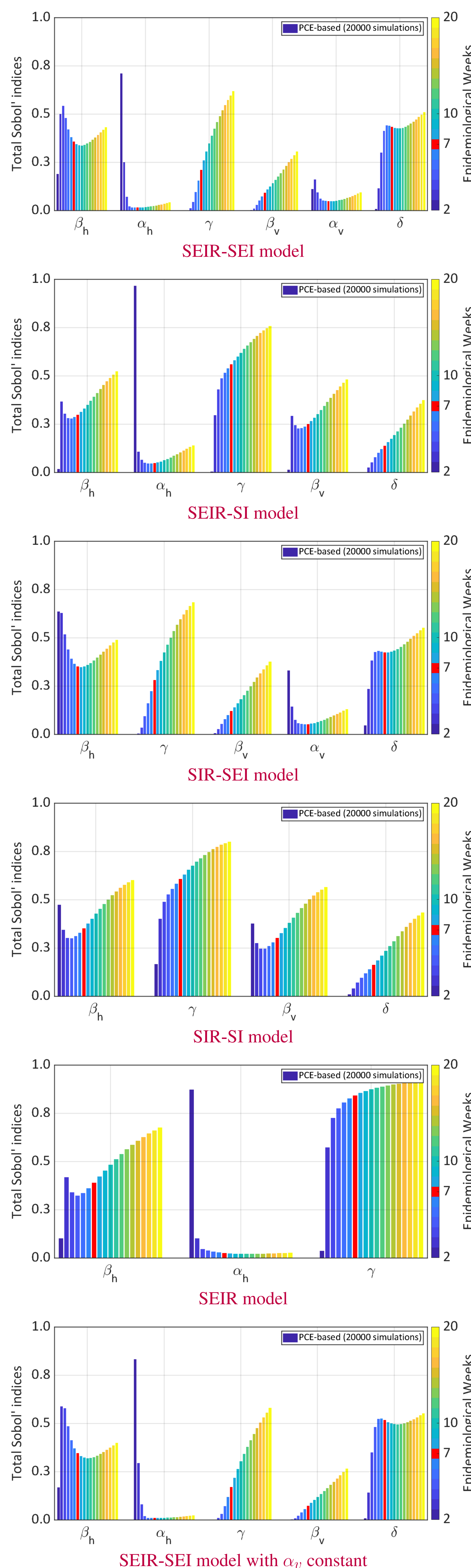
Use bigger data set from a calibrated model to improve the calibration results for other models and test some hypotheses of modeling

Models of Interest

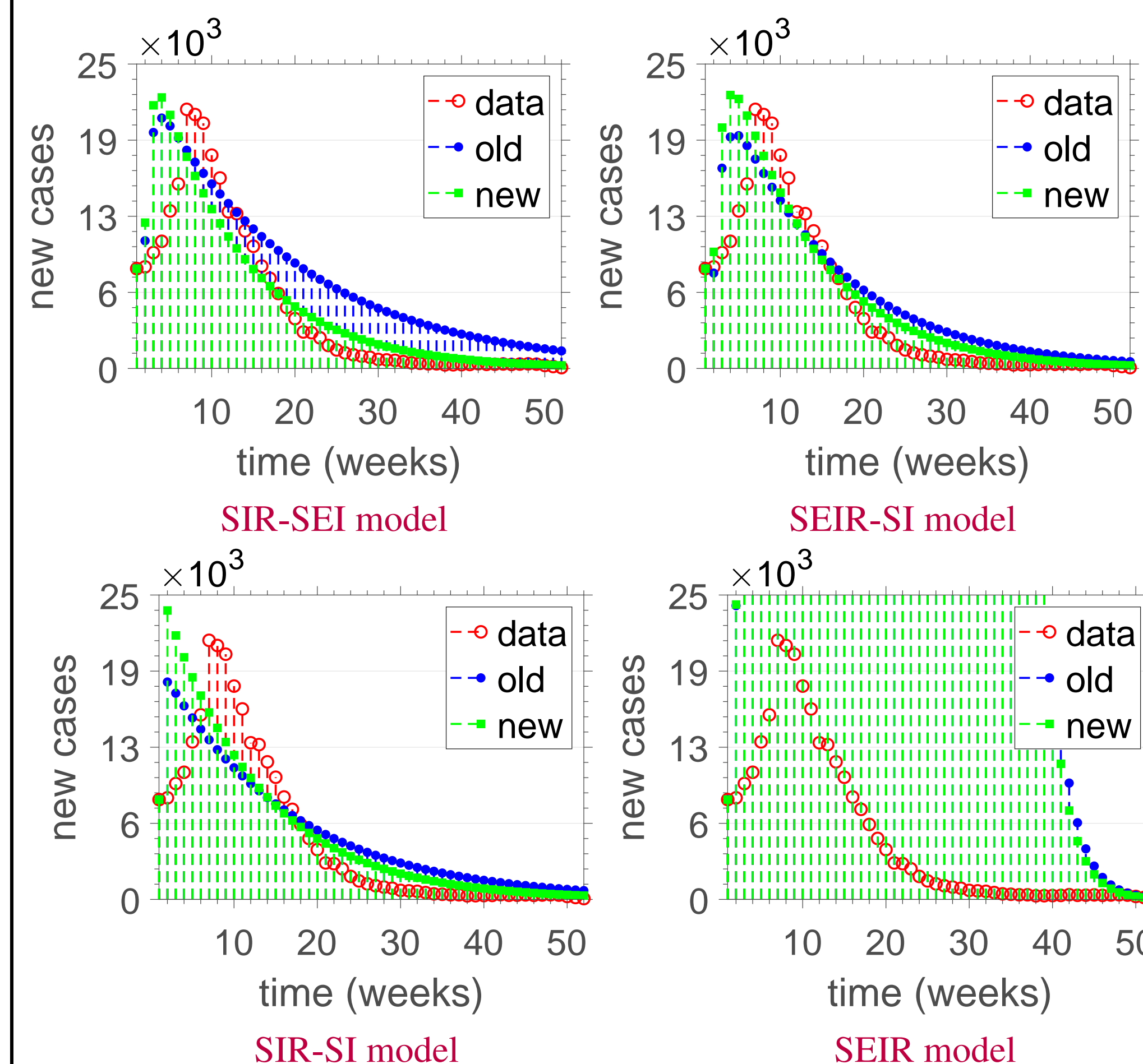
- SIR-SEI model
- SEIR-SEI model
- SIR-SI model
- SEIR model

Results

Sobol' Indices



Calibration Results



Statistical Inference (ongoing research)

Discrepancy Calculation

Suppose a data set $\mathcal{D} = (t_1, y_1^{dat}), (t_2, y_2^{dat}), \dots, (t_{N_d}, y_{N_d}^{dat})$ of measures of the y_t . The i -th observation is given by

$$y_{i, reality}^{dat} = \underbrace{\mathcal{M}(\mathbf{x}, t_i)}_{\text{model}} + \underbrace{\varepsilon_i}_{\text{error}}.$$

Sargsyan, Najm and Ghanem's [4] novel approach to deal with the model discrepancies is to adopt a metamodel structure which lumps the error into the parameters

$$Y^{dat} \approx \mathcal{M}(\mathbf{X}_\epsilon, t), \quad \mathbf{X}_\epsilon = \sum_{\alpha \in \mathcal{I}} \mathbf{X}_\alpha(t) \Psi_\alpha(\xi),$$

where \mathbf{X}_α coefficients are defined as random to be able to be identified by using Bayesian Inference

Bayesian Inference

- Inference problem become use data information to update the *prior* probability density function(PDF), defined for \mathbf{X}_α . The solution corresponds *posterior* PDF
- From Bayes' rule,

$$\pi(\mathbf{X}_\alpha | \mathcal{D}) = \frac{\pi(\mathcal{D} | \mathbf{X}_\alpha) \pi(\mathbf{X}_\alpha)}{\pi(\mathcal{D})}.$$

→ $\pi(\mathbf{X}_\alpha | \mathcal{D})$: posterior distribution → $\pi(\mathbf{X}_\alpha)$: prior distribution
→ $\pi(\mathcal{D} | \mathbf{X}_\alpha)$: likelihood function → $\pi(\mathcal{D})$: evidence

To define a good point of start, the **Maximum Entropy Principle** is applied to construct the **most informative prior distribution**

Final Remarks

- Comparative results of global Sobol' Indices show how the lack of some parameters can change the sensibility effect of the others
- With a bigger data set, the limitations in the prediction capacity of the hierarchically inferior models become more evident
- A framework for statistical inference exploring Polynomial Chaos to measure the model discrepancies was presented
- In future works, the authors intend explore this new framework to quantify model discrepancy and then improve its predictions

Acknowledgements



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