

# Exploring the nonlinear dynamics of a bistable energy harvester

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**NUMERICO** – Nucleus of Modeling and Experimentation with Computers

<http://numerico.ime.uerj.br>

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João Peterson (UERJ)

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Armação dos Búzios - RJ, Brazil



# Outline

1 Introduction

2 Nonlinear Dynamics

3 Stochastic Dynamics

4 Final Remarks



## Section 1

### Introduction



April 4,  
2005



March 13,  
2013



L. Gammaitoni, Fundamentals on energy, NiPS Summer School 2018, University of Perugia.







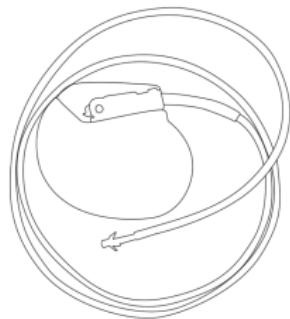
Wikimedia Commons, "File:St Jude Medical pacemaker in hand.jpg — Wikimedia Commons, the free media repository", 2014.

What's common in both cases?



What's common in both cases?

Electronic devices demanding energy!

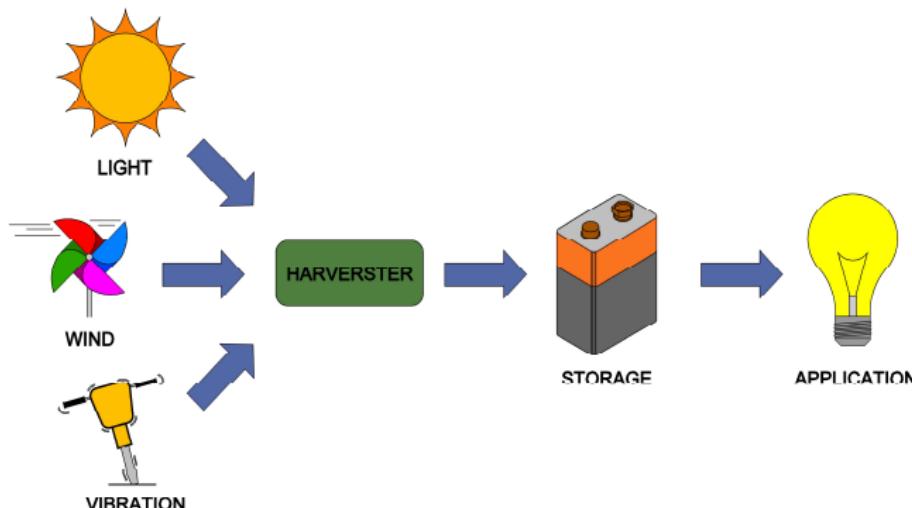


A word cloud centered around the theme of energy harvesting and smart design. The words are arranged in a cluster, with larger words representing more prominent concepts. The words include: sensor, monitoring, smart, challenge, design, powered, harvested, eh, battery, harvesting, energy, node, holistic, harvester, power, rectenna, vibration, optimisation, wireless, bistable, and vibration.

\*Picture obtained from Google Images.

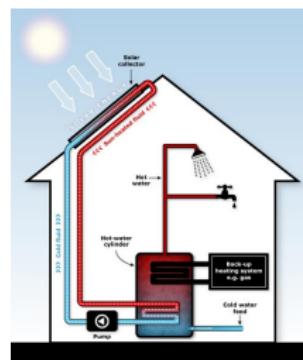
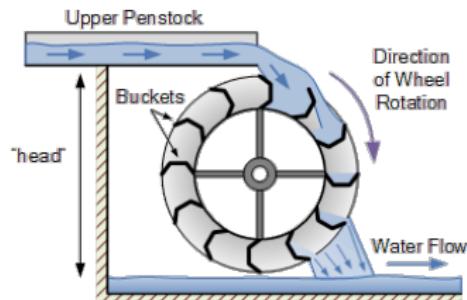


# Energy Harvesting concept



- Capture wasted energy from external sources
- Store this wasted energy for future use
- Use the stored energy to supply other devices

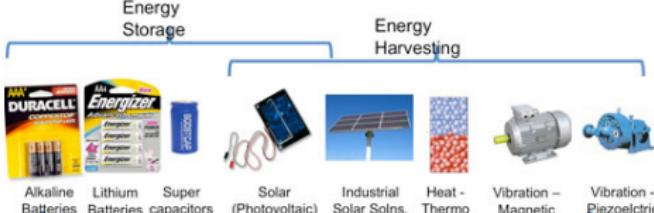
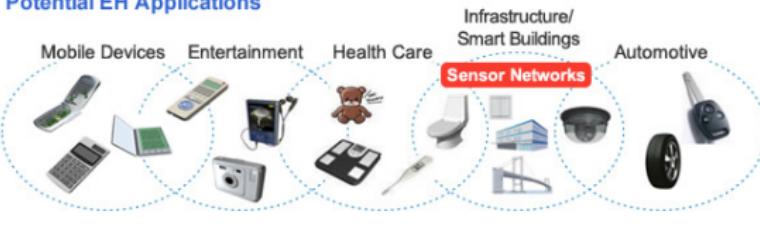
# Classical technologies in Energy Harvesting



\*Pictures obtained from Google Images, several sources. If you are the owner of any one of these images, consider its use a compliment.

# Emergent technologies in Energy Harvesting

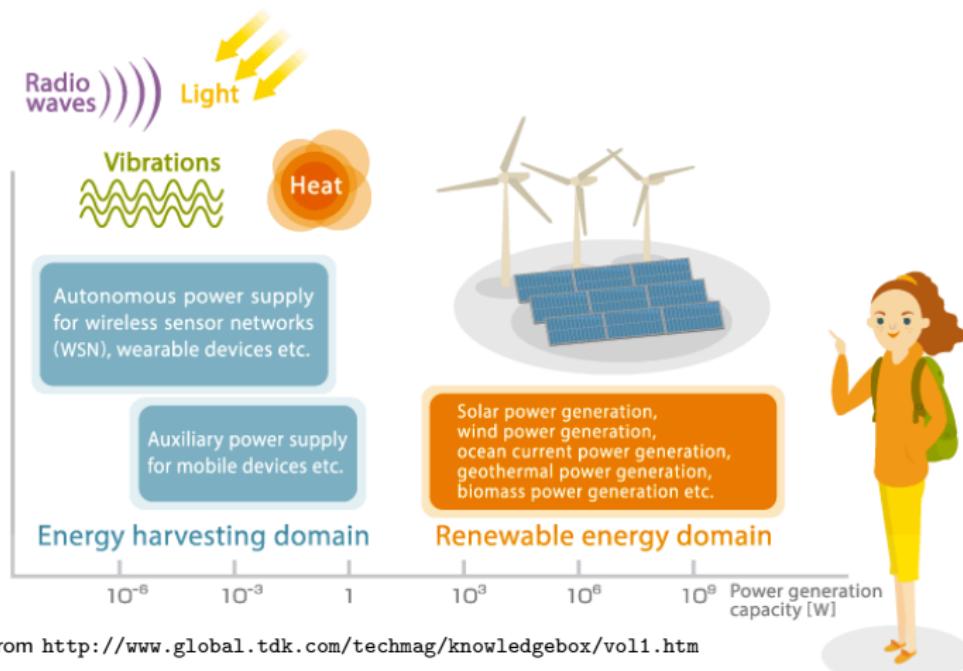
## Potential EH Applications



\*Pictures obtained from Google Images, several sources. If you are the owner of any one of these images, consider its use a compliment.

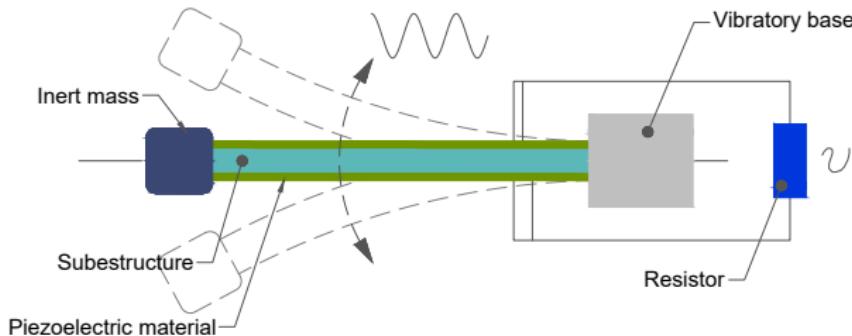
# Energy scale for modern Energy Harvesting technologies

- Power generation capacity and main applications of energy harvesting



# Vibration based Energy Harvesting

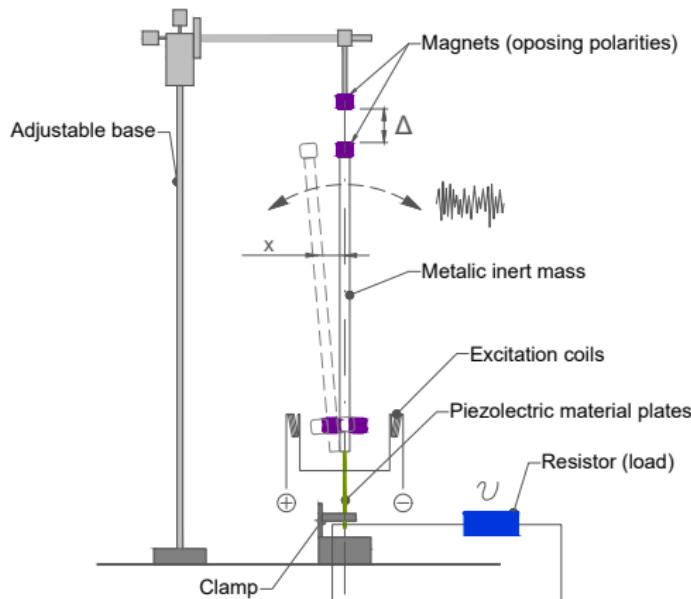
## Monostable system driven by regular signal



S. Roundy, P. K. Wright and J. Rabaey, A study of low level vibrations as a power source for wireless sensor nodes. **Computer Communications**, 26: 1131-1144, 2003.

# Vibration based Energy Harvesting

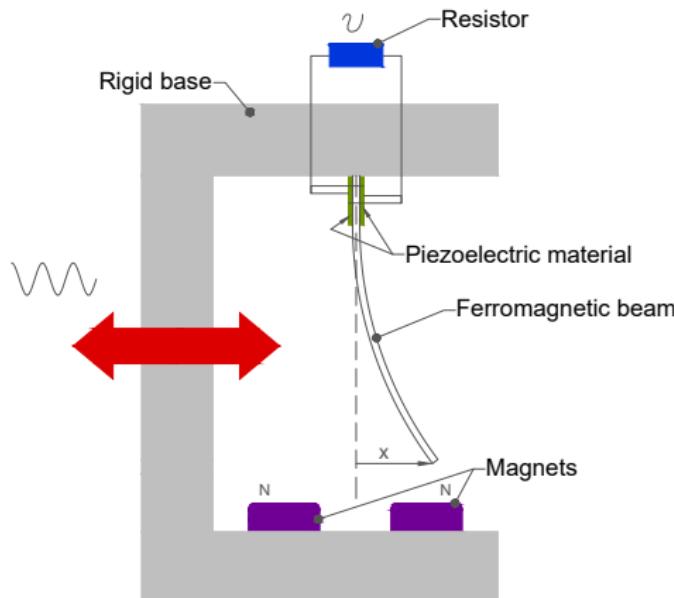
## Bistable system driven by a noisy signal



F. Cottone, H. Vocca and L. Gammaitoni, Nonlinear energy harvesting. *Physical Review Letters*, 102: 080601, 2009.

# Vibration based Energy Harvesting

## Bistable system driven by regular signal



A. Erturk, J. Hoffmann and D. J. Inman, *A piezomagnetoelastic structure for broadband vibration energy harvesting*. *Applied Physics Letters*, 94: 254102, 2009.

# Research objectives

This research has several objectives:

- Investigate in detail the underlying nonlinear dynamics
  - Time series
  - Poincaré sections
  - Bifurcation diagrams
  - Basis of attractions
  - Test 0-1 for chaos
- Model the underlying uncertainties and study their influence
  - System parameters variability
  - Noise in system excitation
- Propose strategies to enhance the recovered energy
  - Nonlinear optimization
  - Control of chaos

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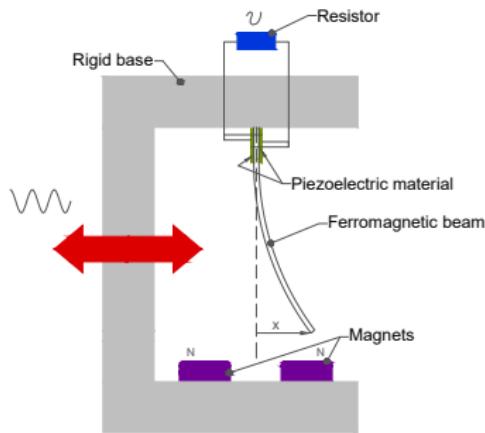


## Section 2

Nonlinear Dynamics



# Bistable harvester driven by regular signal



$$\ddot{x} + 2\xi\dot{x} - \frac{1}{2}x(1-x^2) - \chi v = f \cos \Omega t$$

$$\dot{v} + \lambda v + \kappa \dot{x} = 0$$

$$x(0) = x_0, \dot{x}(0) = \dot{x}_0, v(0) = v_0$$

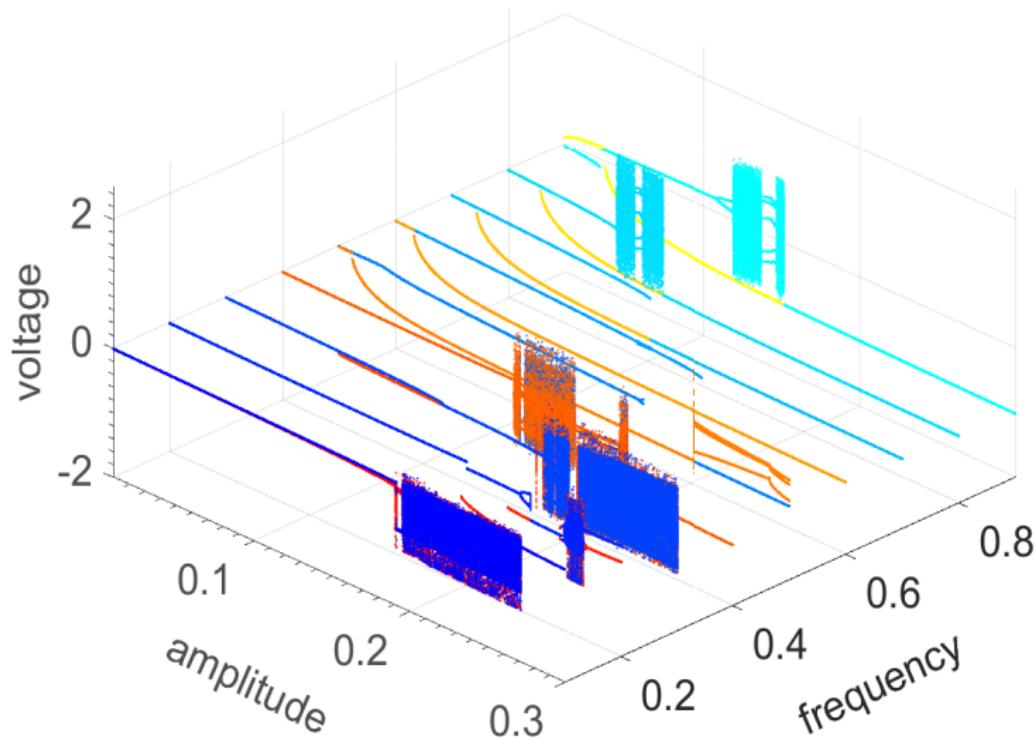


A. Erturk, J. Hoffmann and D. J. Inman, *A piezomagnetoelastic structure for broadband vibration energy harvesting*. **Applied Physics Letters**, 94: 254102, 2009.

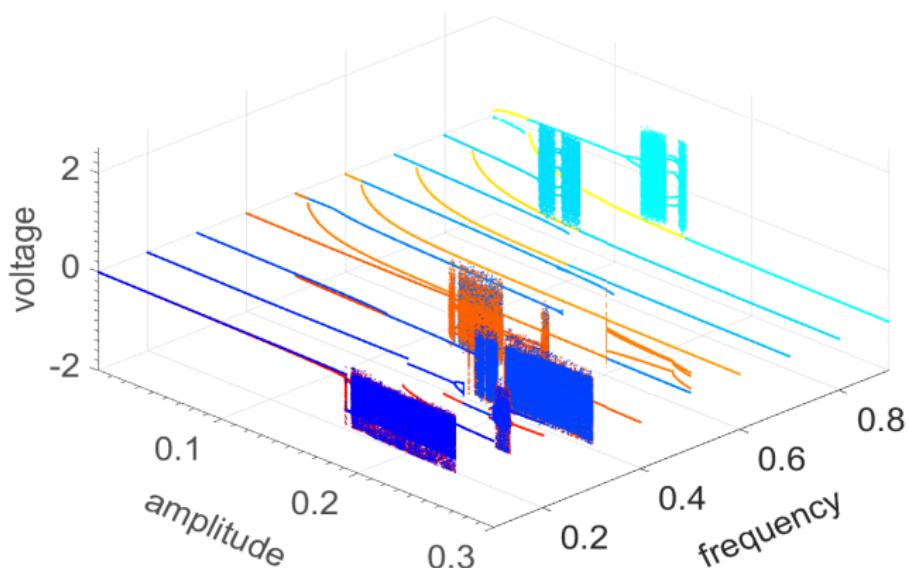
# Nonlinear dynamics animation



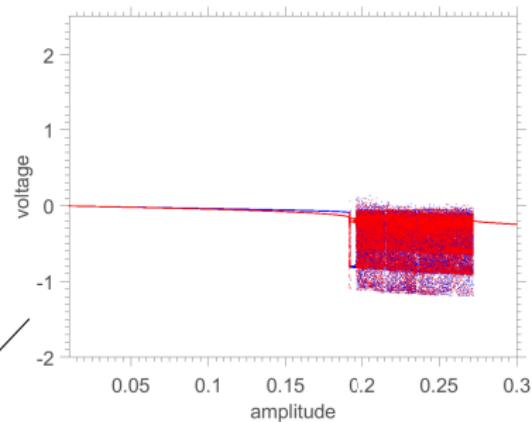
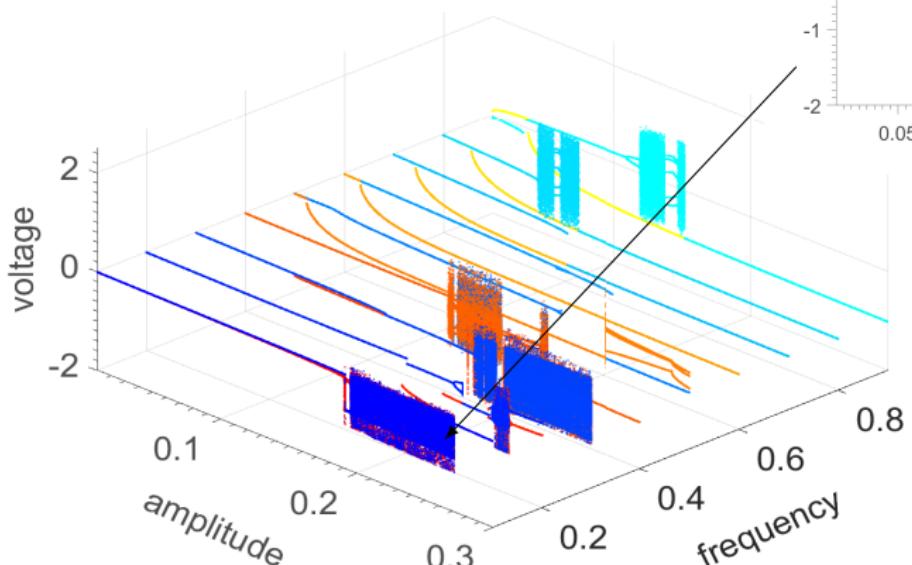
# Global overview of force amplitude effect



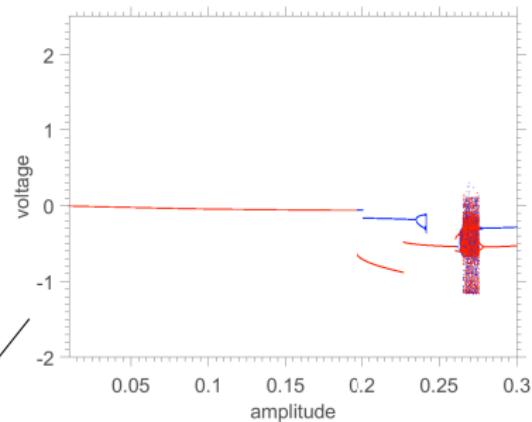
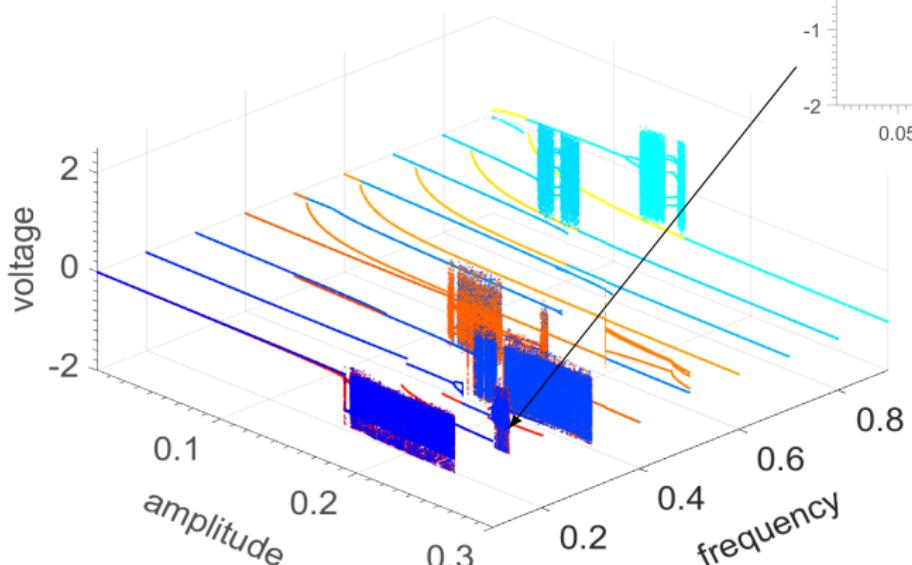
# Bifurcation diagrams: voltage vs amplitude



# Bifurcation diagrams: voltage vs amplitude

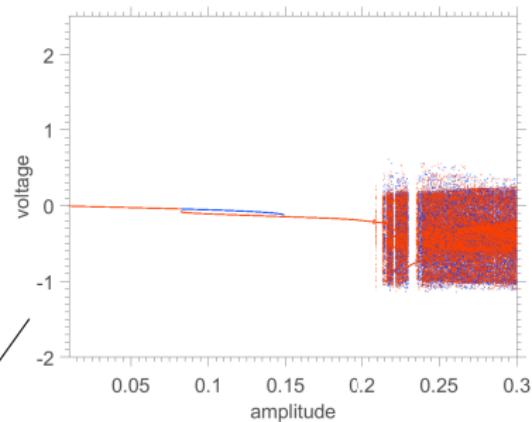
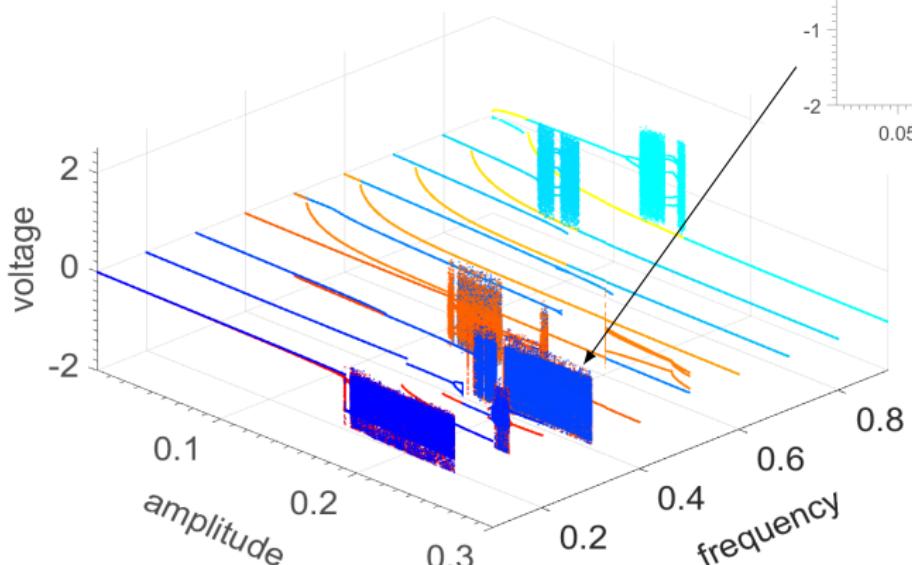


# Bifurcation diagrams: voltage vs amplitude



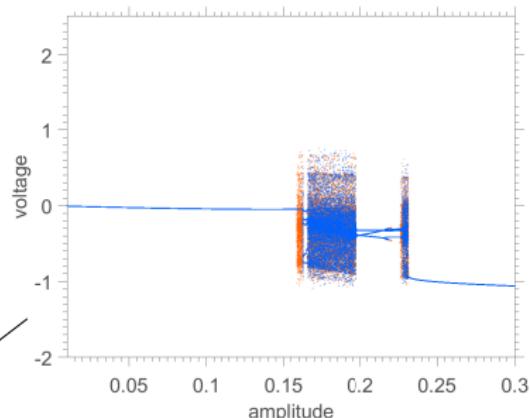
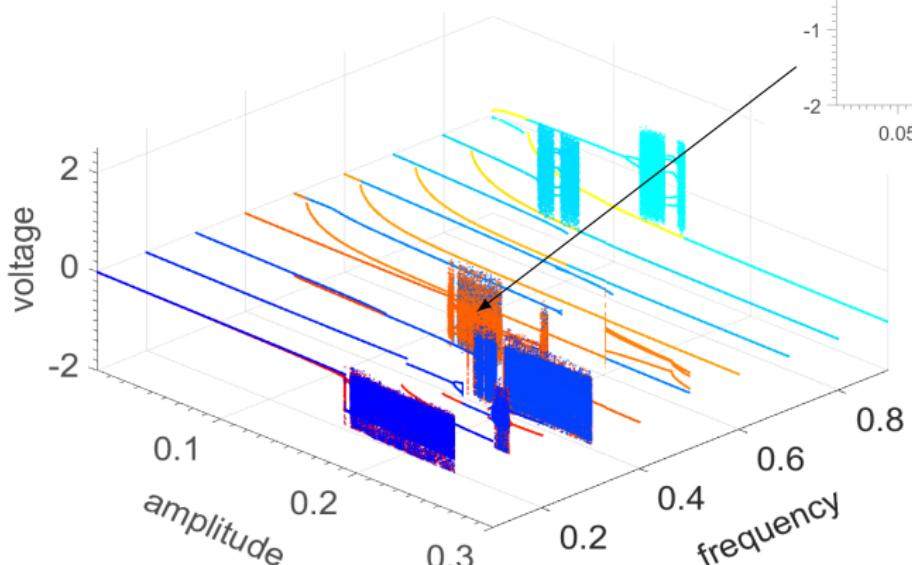
$$\Omega = 0.2$$

# Bifurcation diagrams: voltage vs amplitude



$$\Omega = 0.3$$

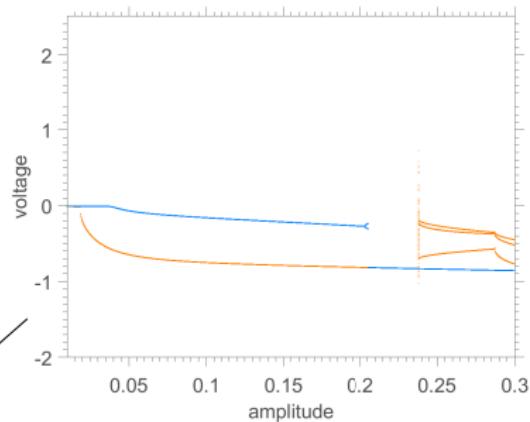
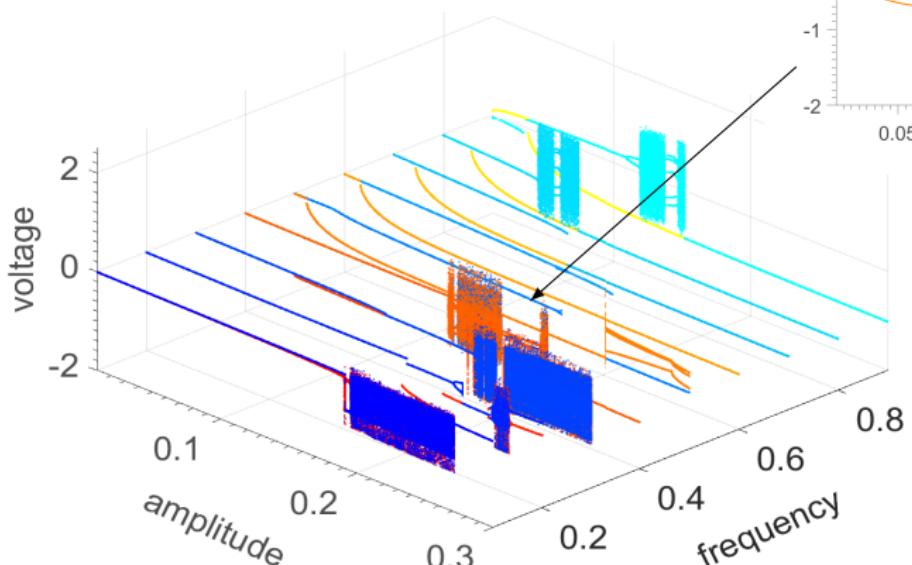
# Bifurcation diagrams: voltage vs amplitude



$$\Omega = 0.4$$



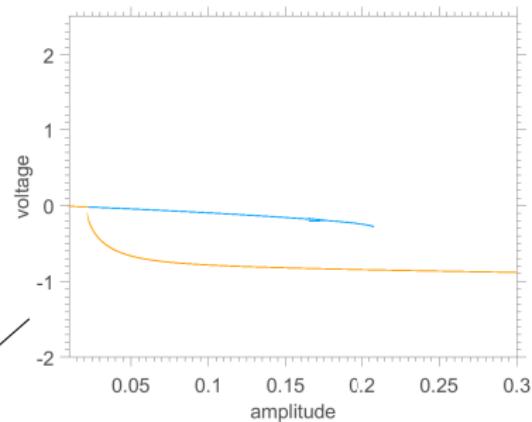
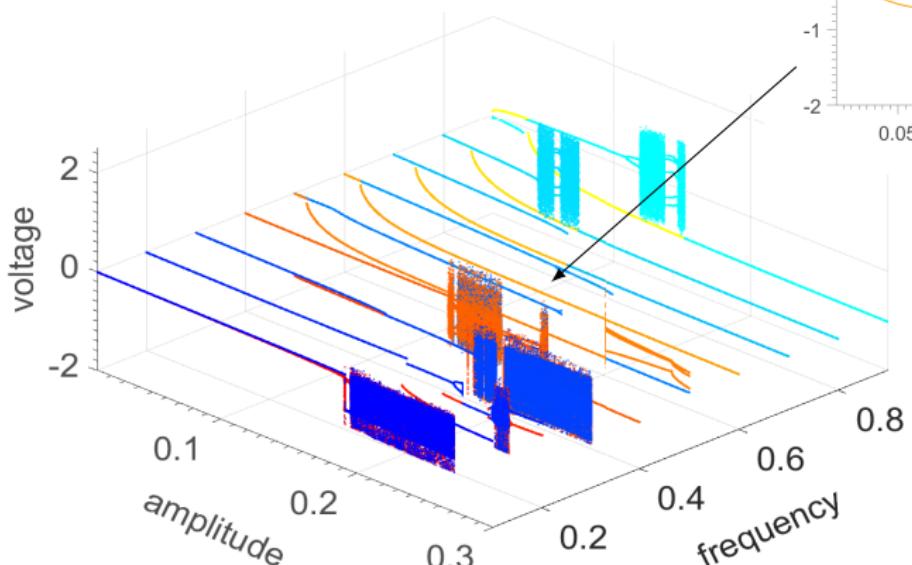
# Bifurcation diagrams: voltage vs amplitude



$$\Omega = 0.5$$

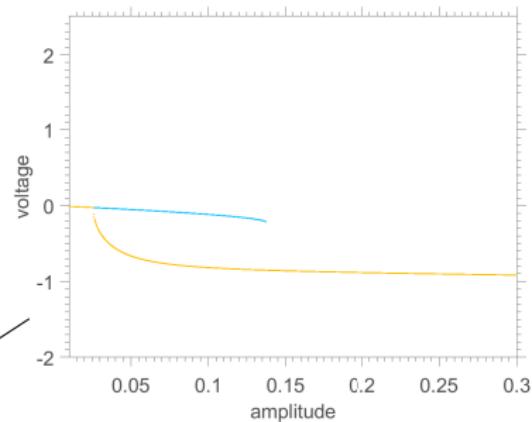
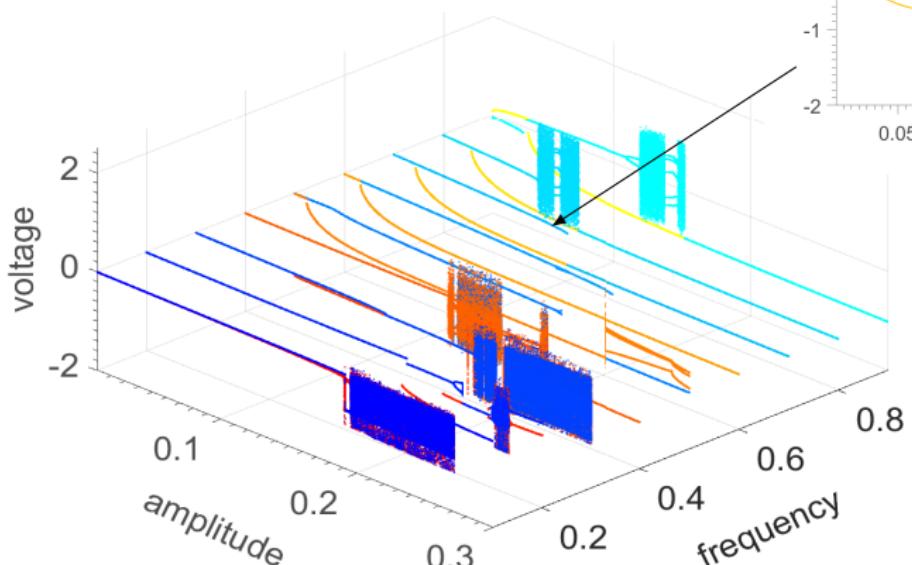


# Bifurcation diagrams: voltage vs amplitude



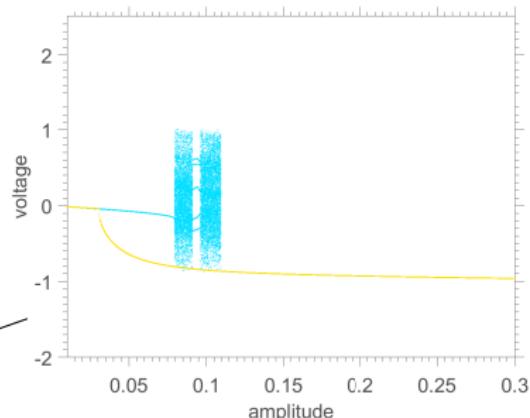
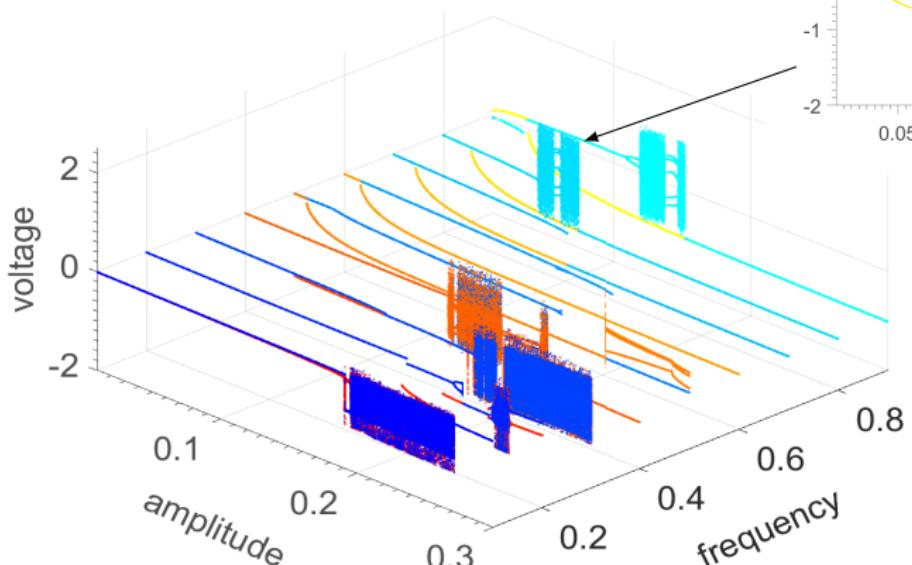
$$\Omega = 0.6$$

# Bifurcation diagrams: voltage vs amplitude

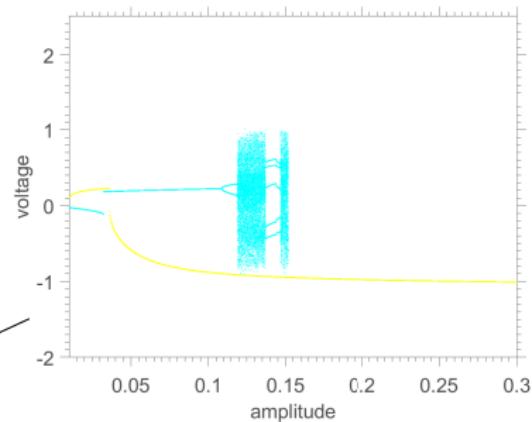
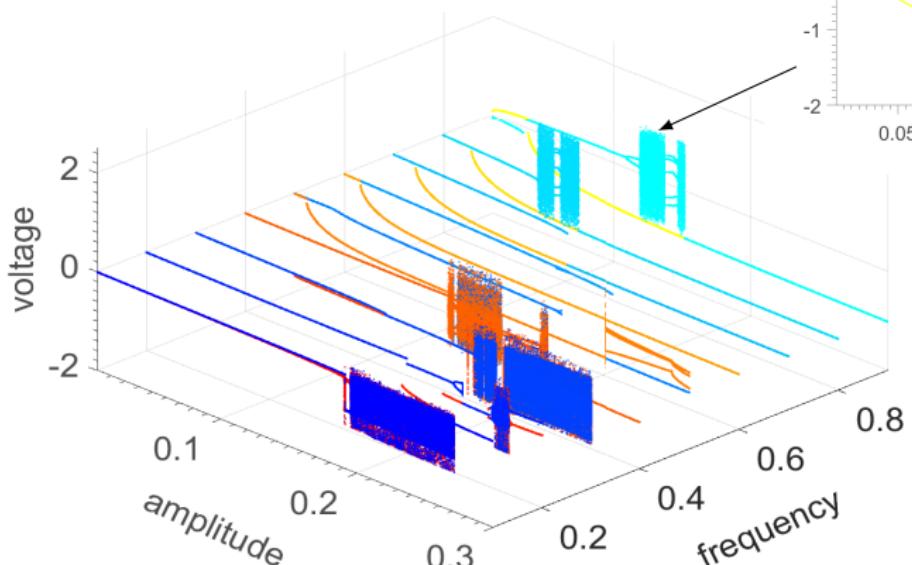


$$\Omega = 0.7$$

# Bifurcation diagrams: voltage vs amplitude



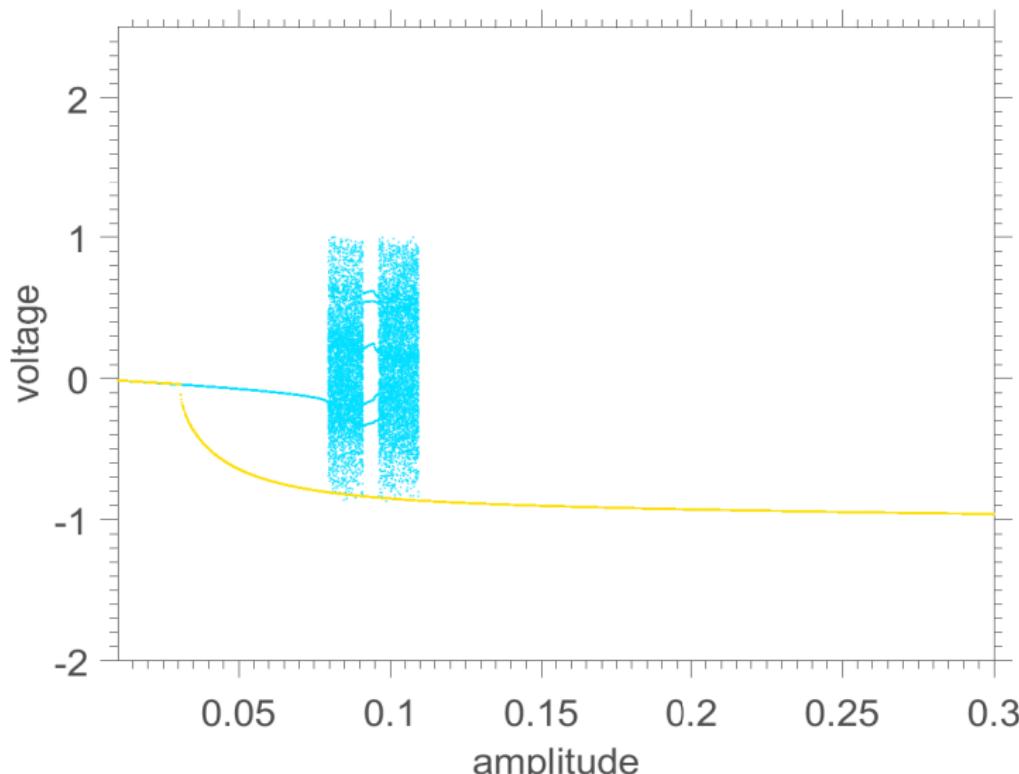
# Bifurcation diagrams: voltage vs amplitude



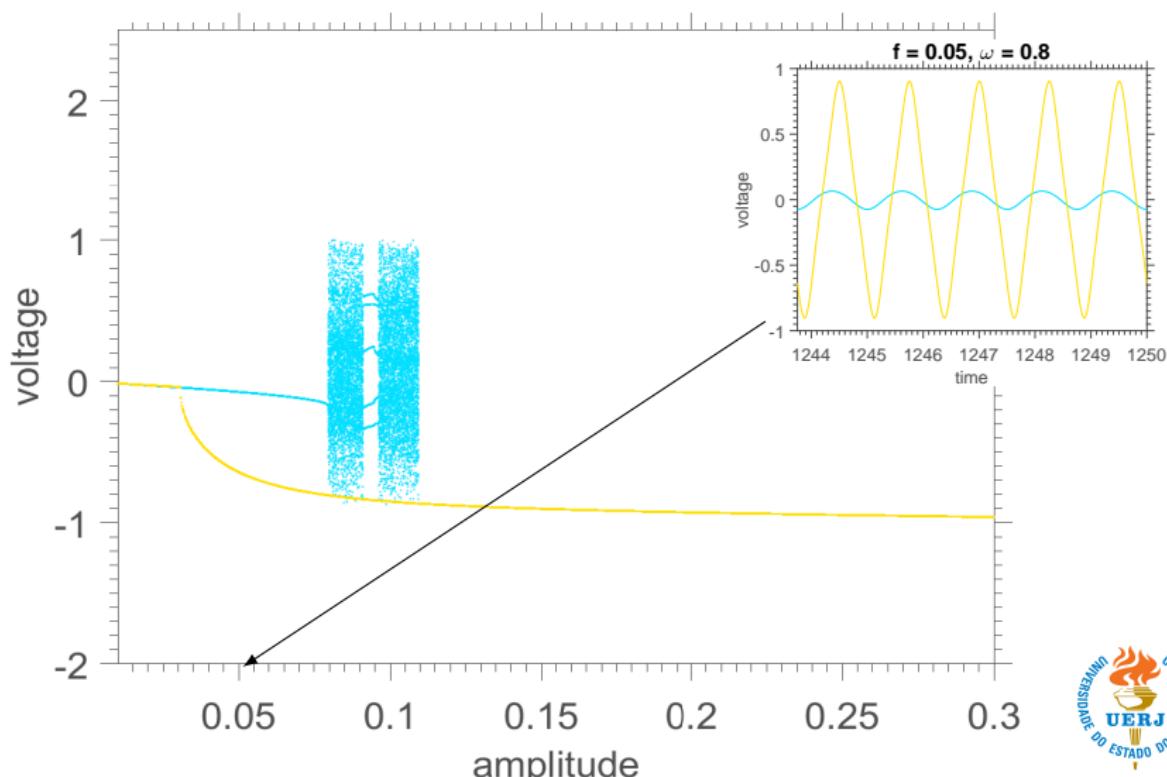
$$\Omega = 0.9$$



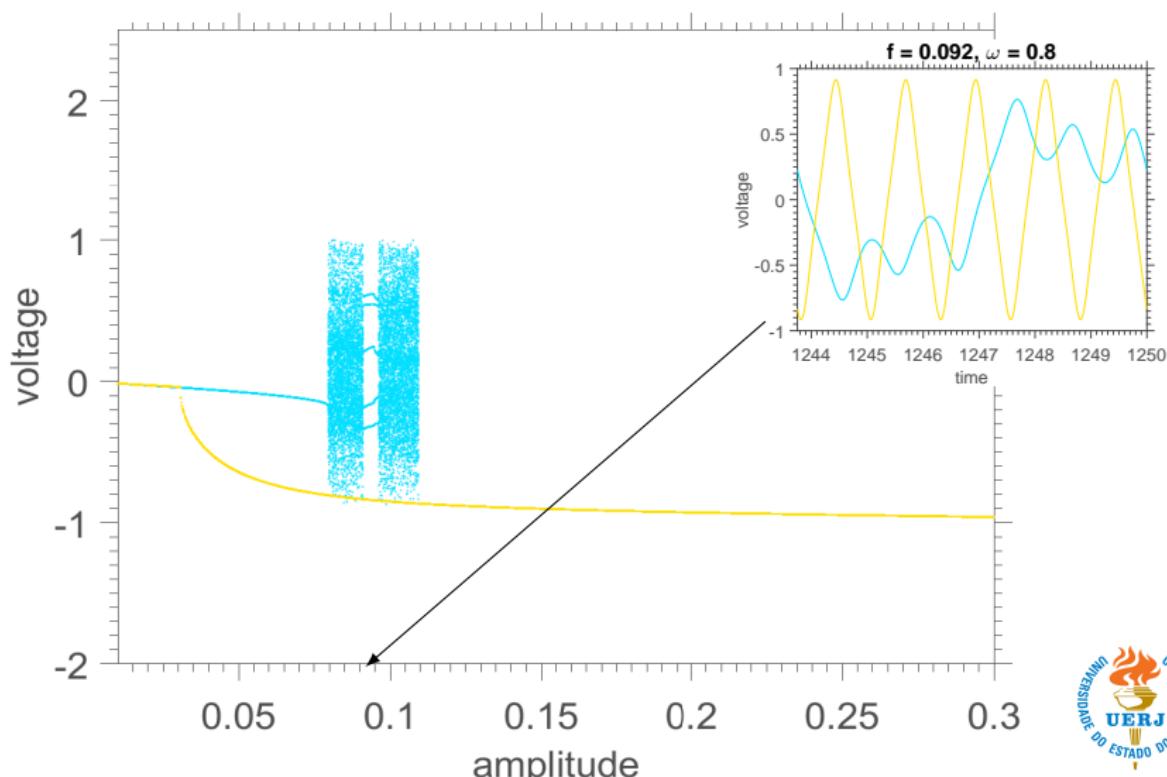
# Forward and backward bifurcation diagrams ( $\Omega = 0.8$ )



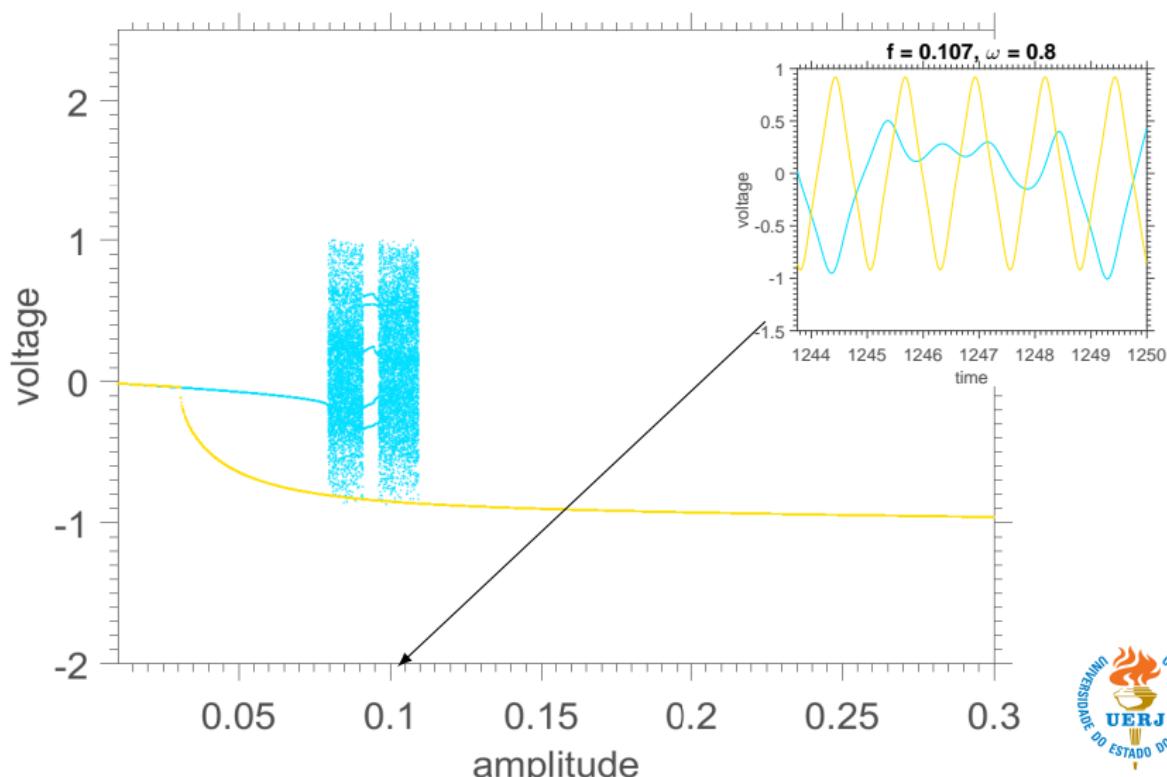
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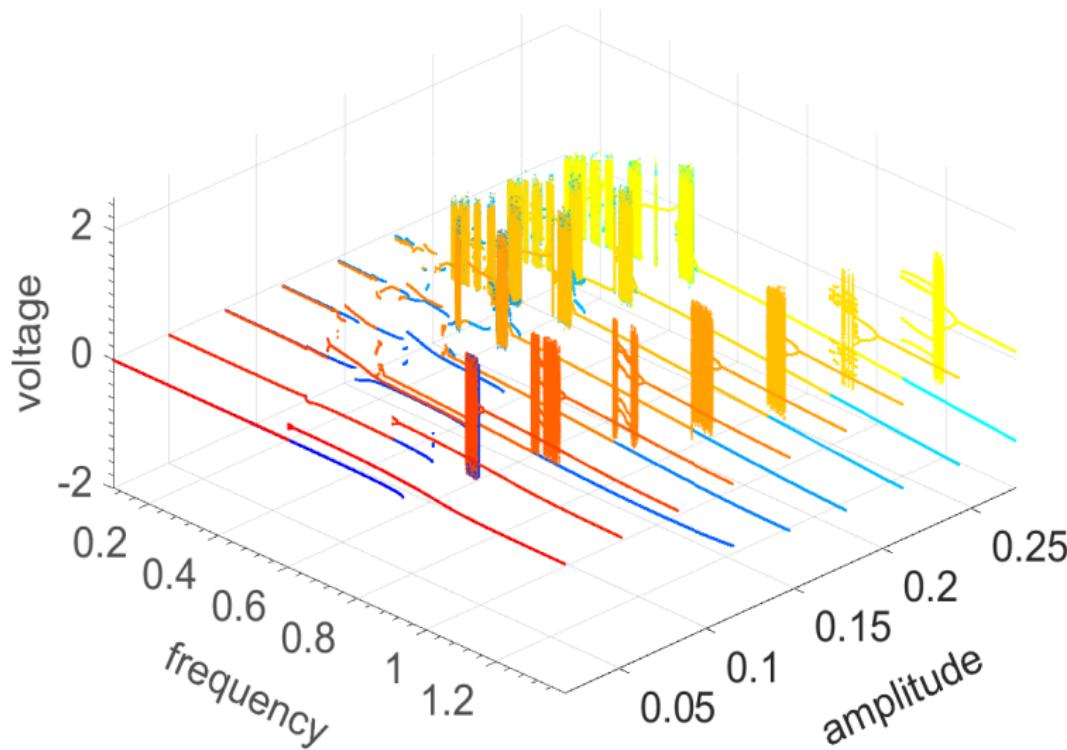
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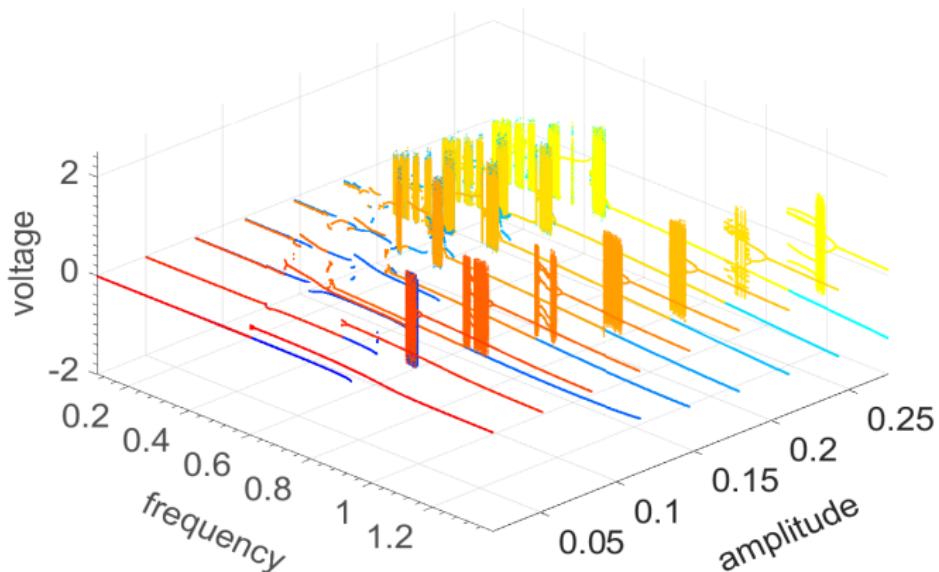
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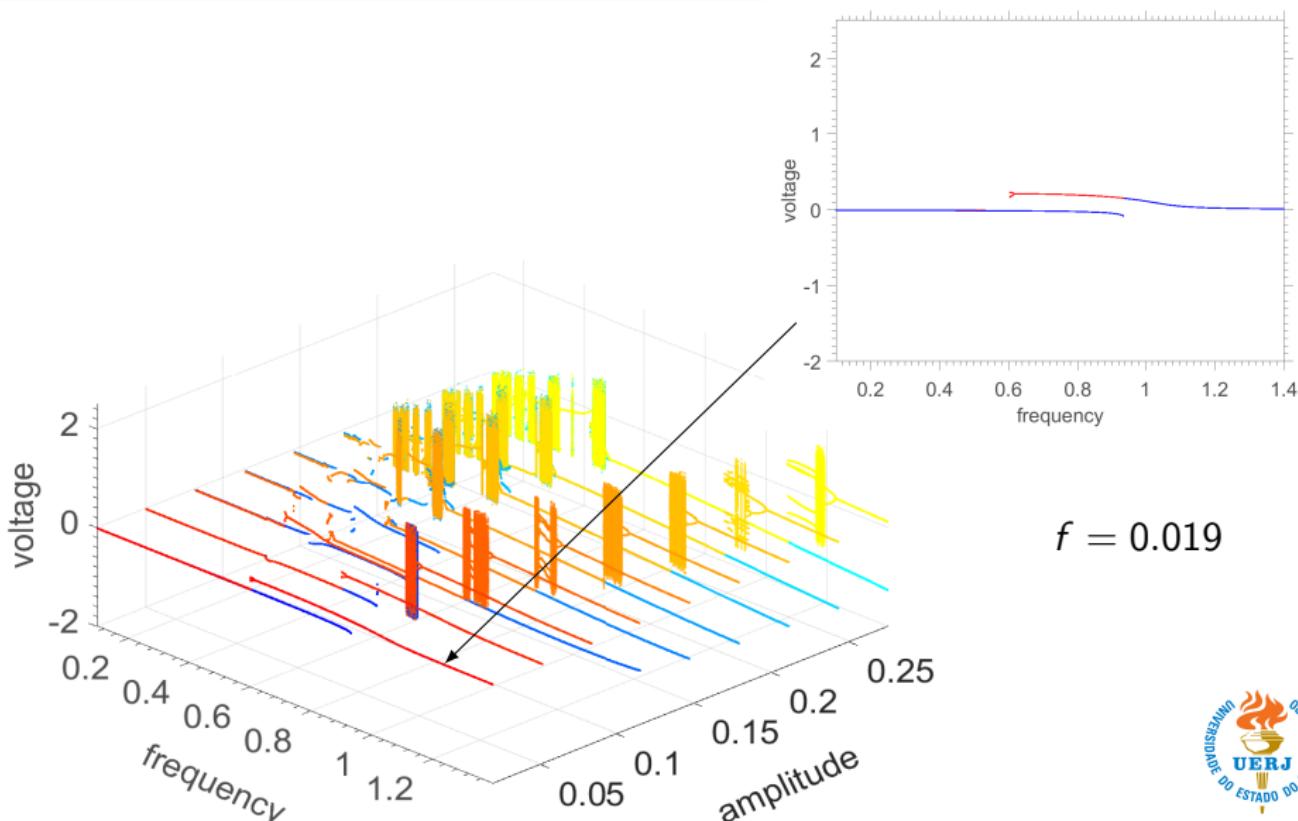
# Global overview of force frequency effect



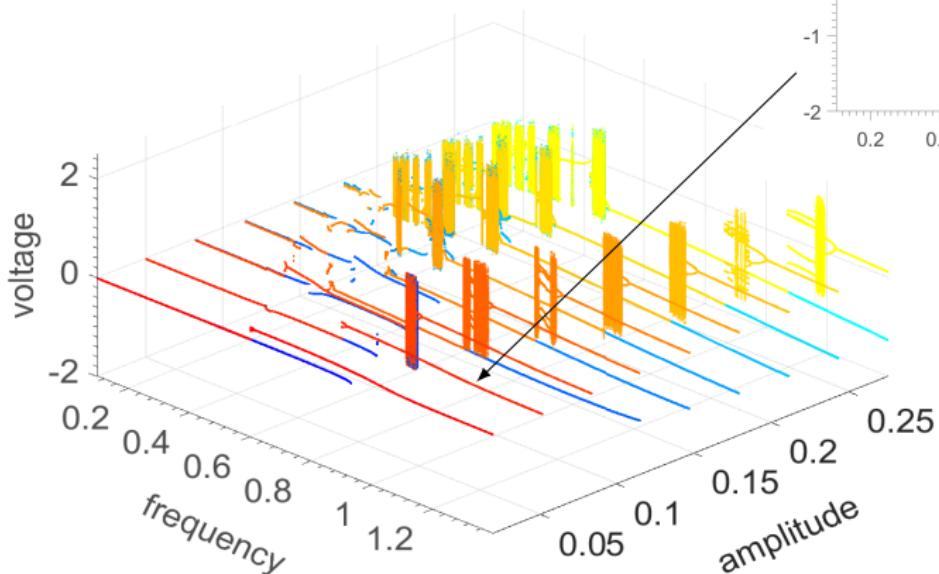
# Bifurcation diagrams: voltage vs frequency



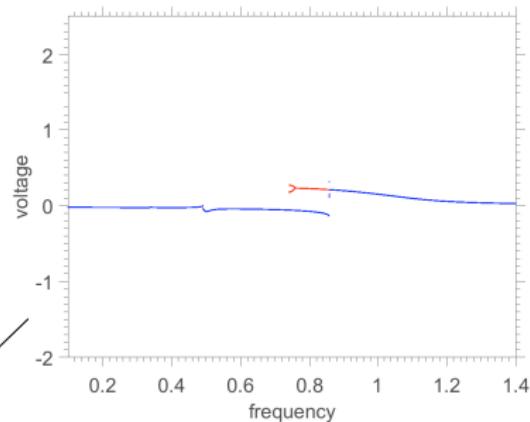
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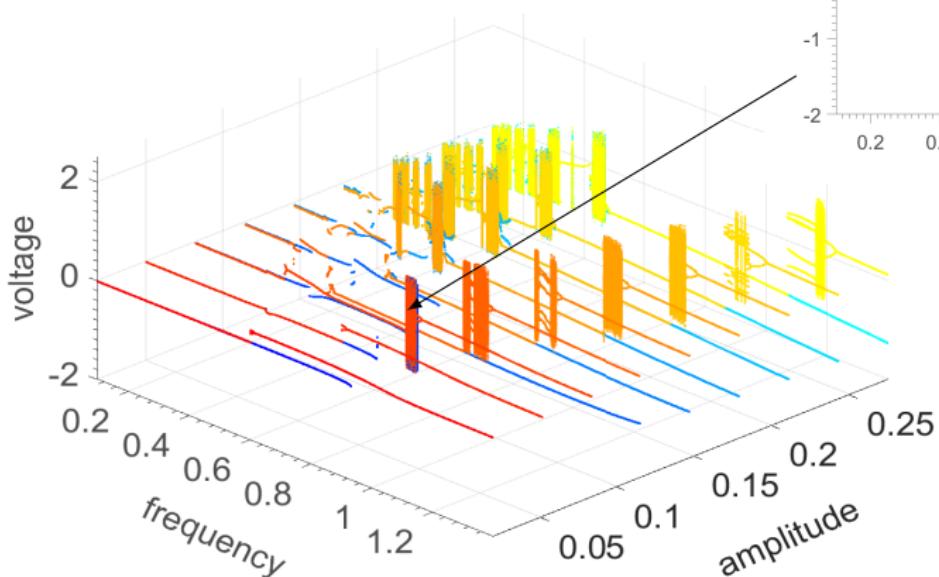
# Bifurcation diagrams: voltage vs frequency



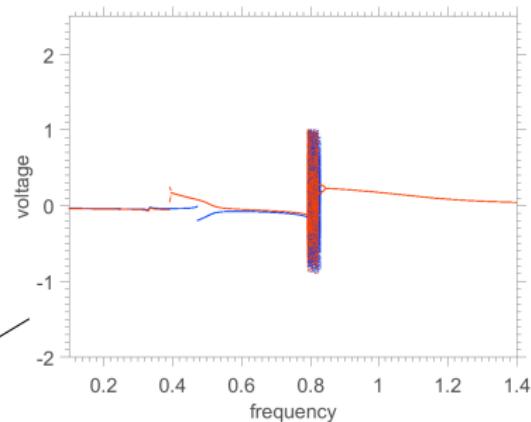
$$f = 0.051$$



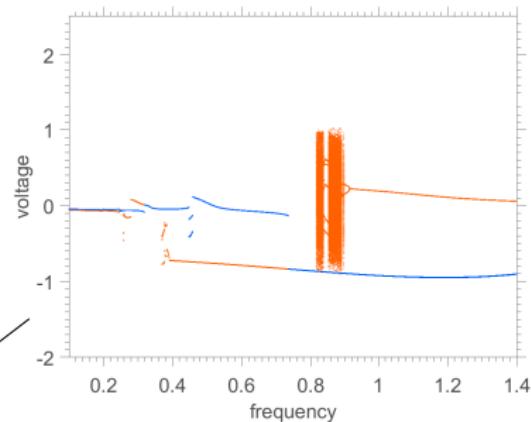
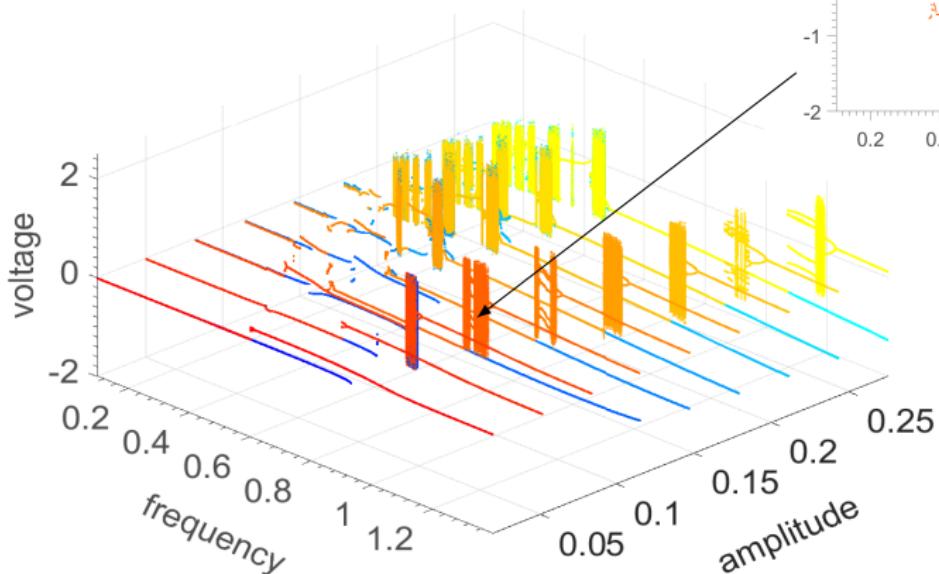
# Bifurcation diagrams: voltage vs frequency



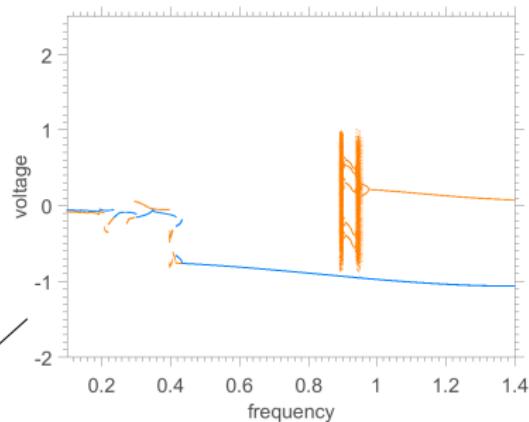
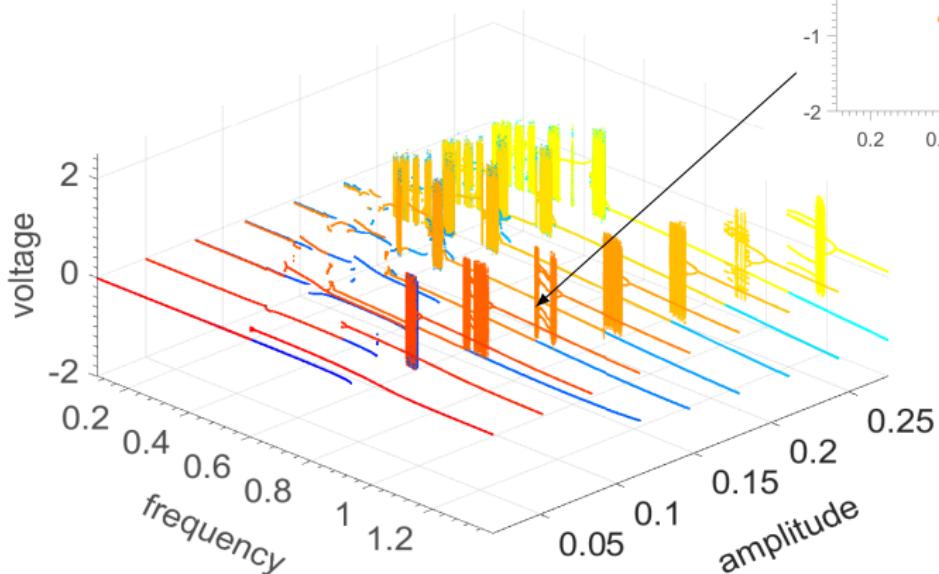
$$f = 0.083$$



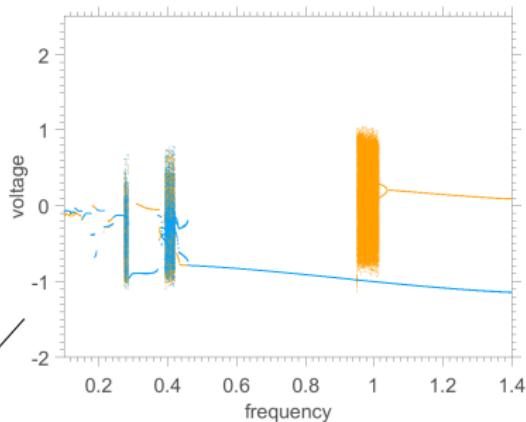
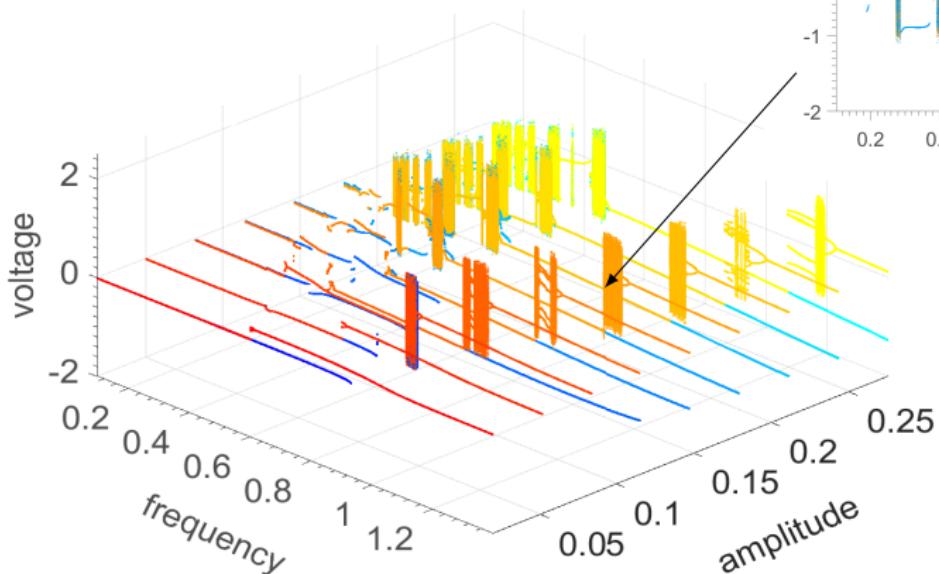
# Bifurcation diagrams: voltage vs frequency



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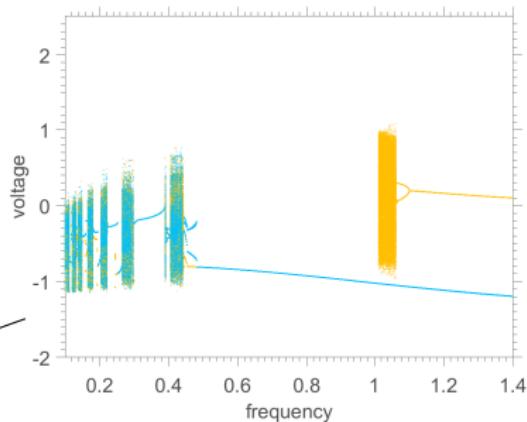
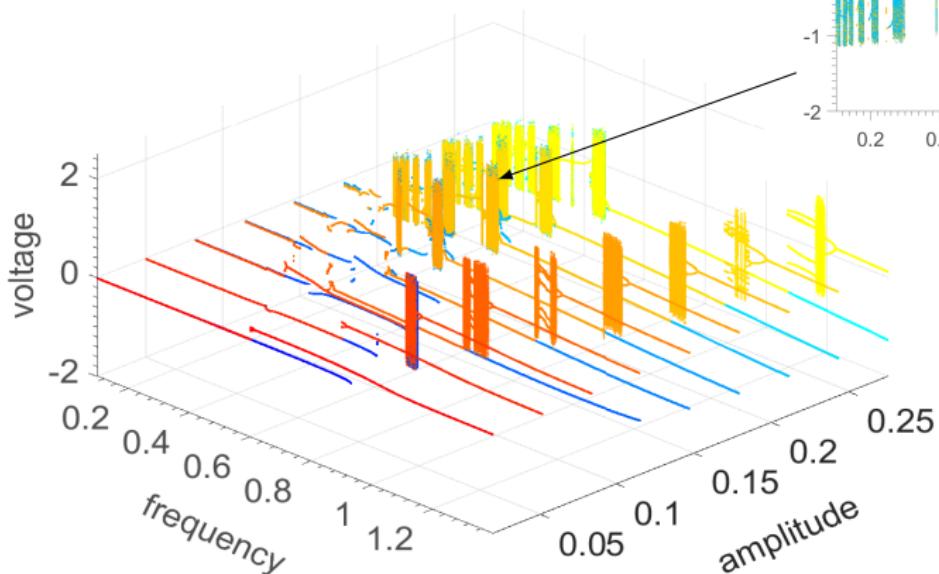
# Bifurcation diagrams: voltage vs frequency



$$f = 0.179$$

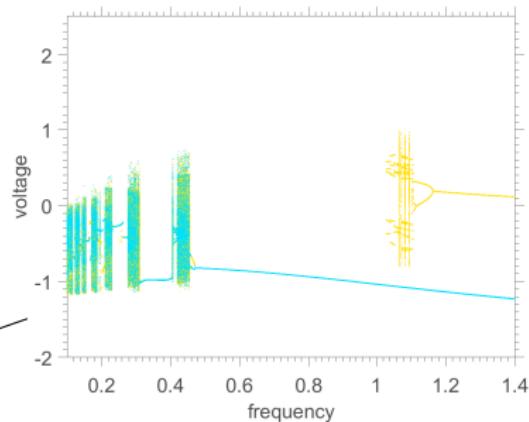
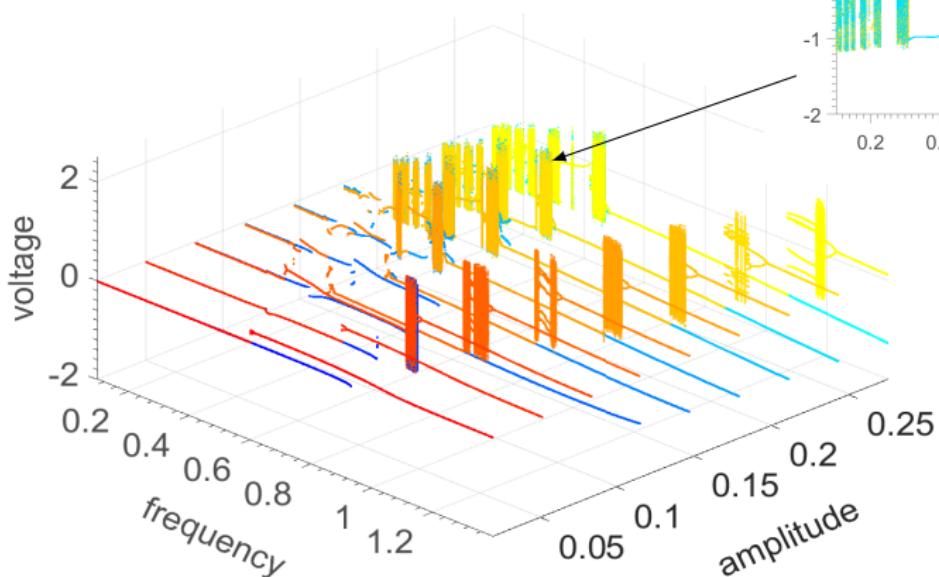


# Bifurcation diagrams: voltage vs frequency



$$f = 0.211$$

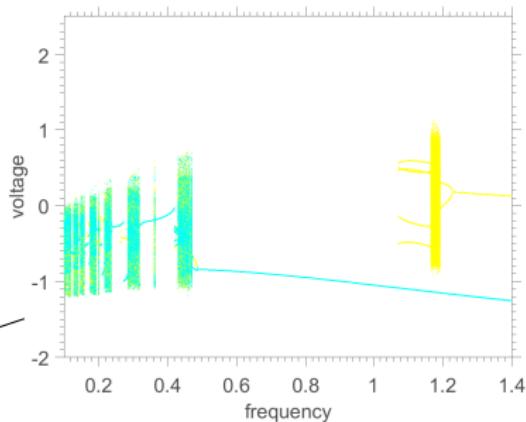
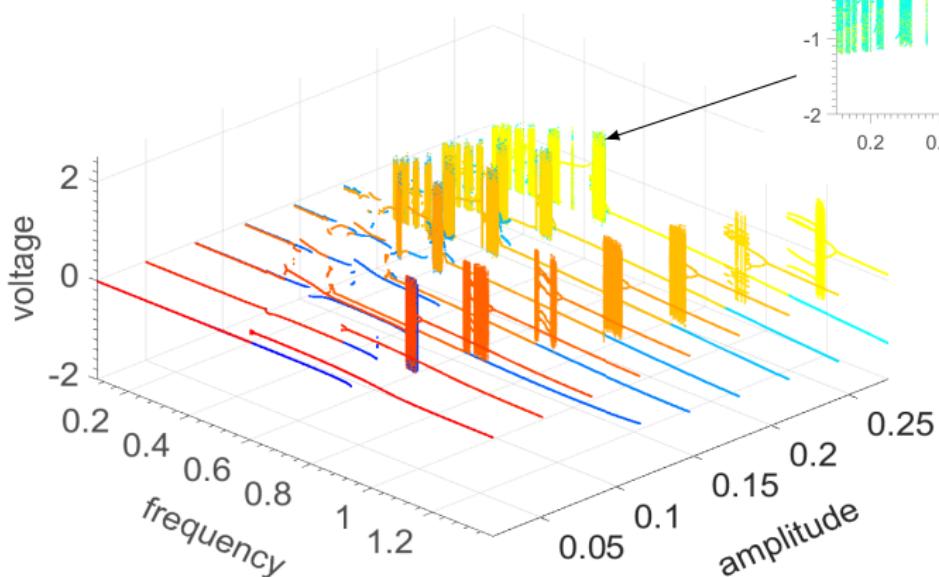
# Bifurcation diagrams: voltage vs frequency



$$f = 0.243$$



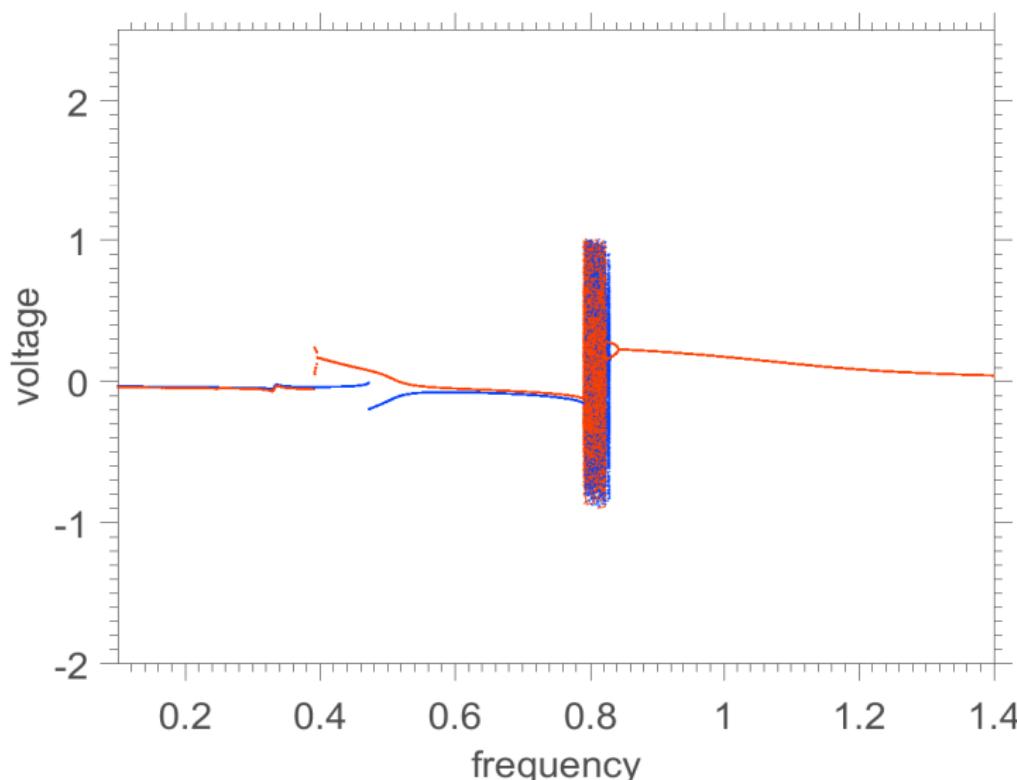
# Bifurcation diagrams: voltage vs frequency



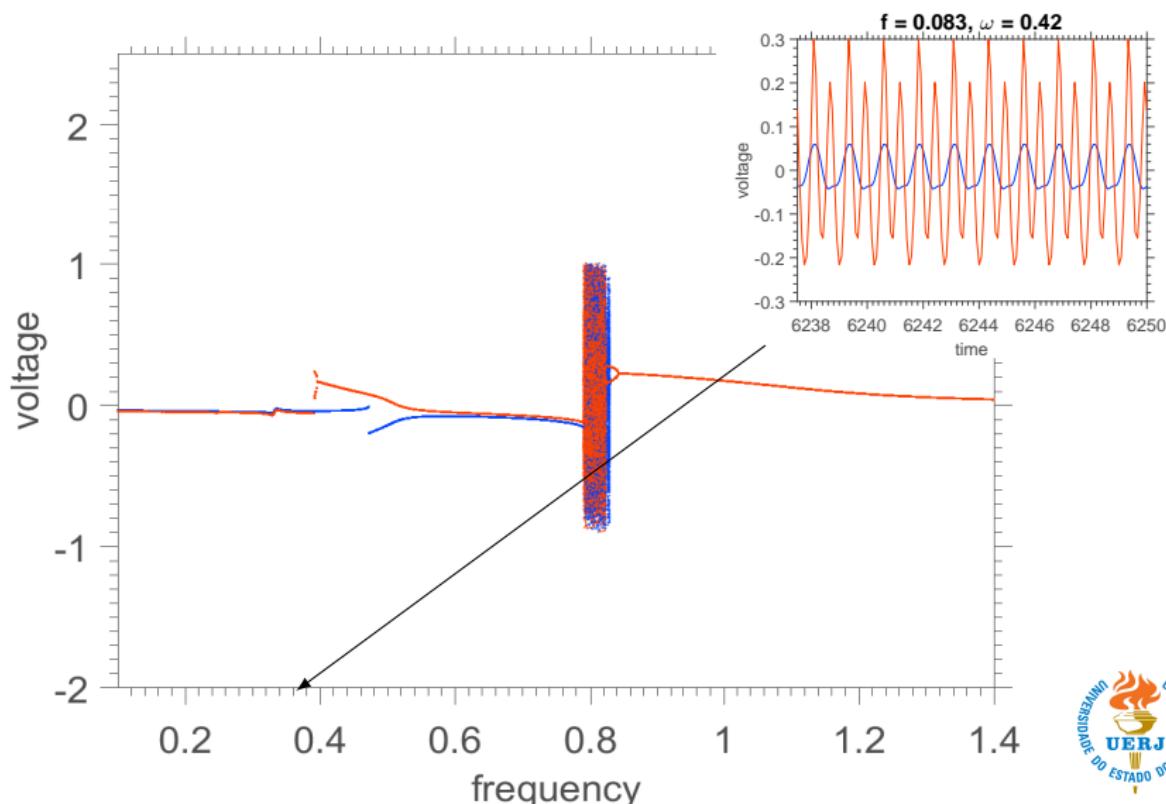
$$f = 0.275$$



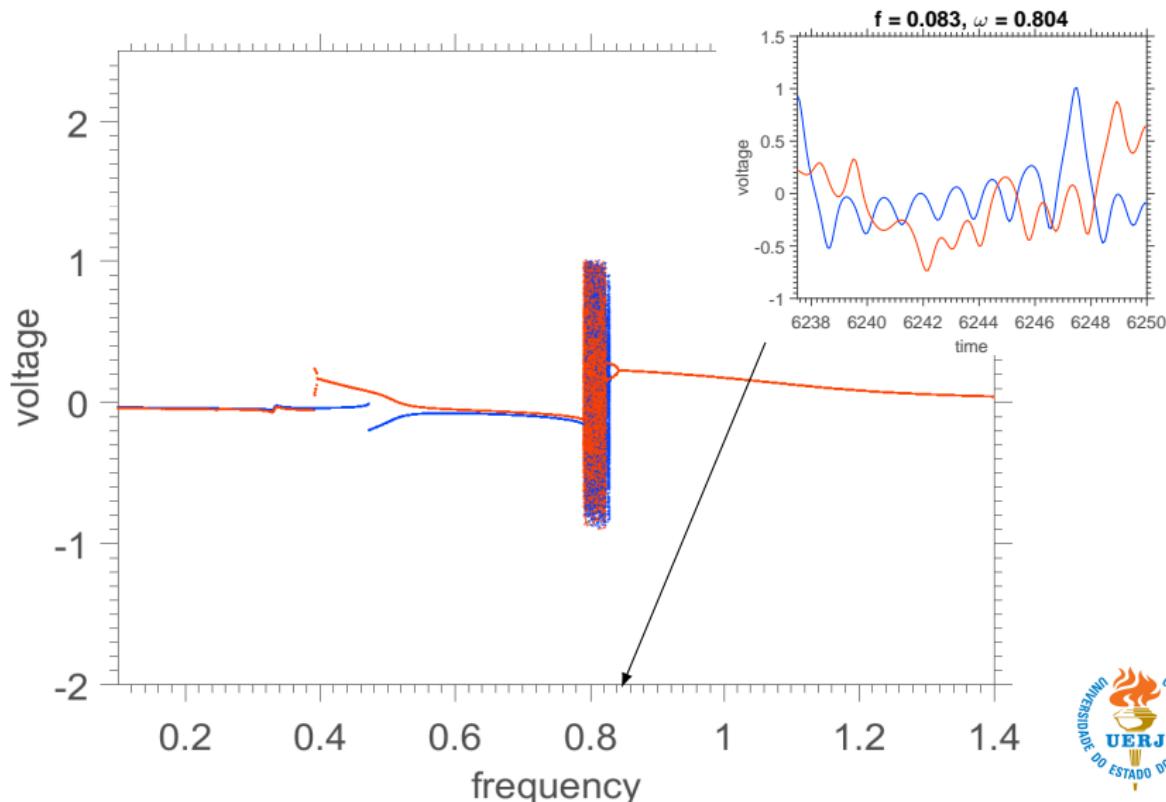
# Forward and backward diagrams ( $f = 0.083$ )



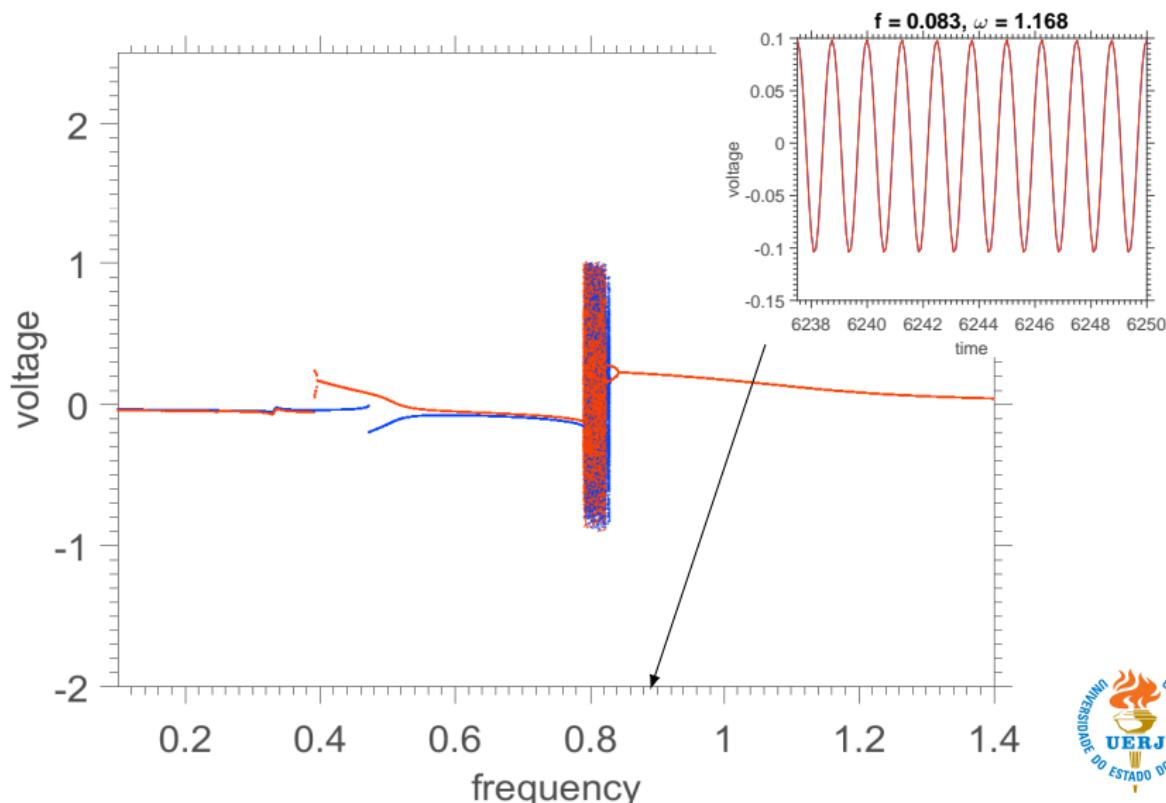
# Forward and backward diagrams ( $f = 0.083$ )



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# Basins of attraction

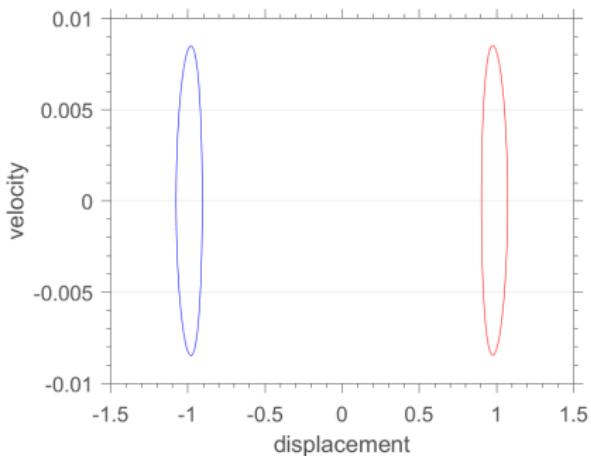
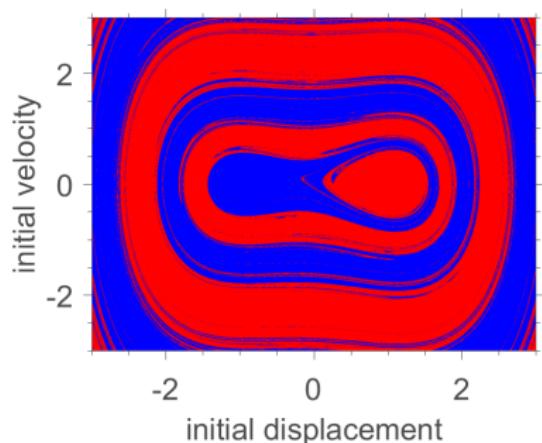


Figure:  $f = 0.083$  and  $\Omega = 0.1$

# Basins of attraction

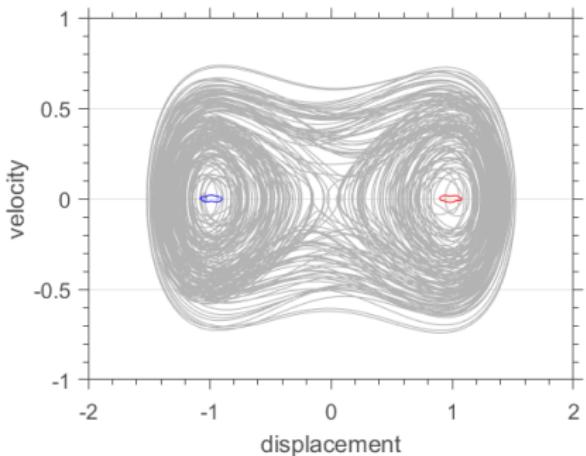
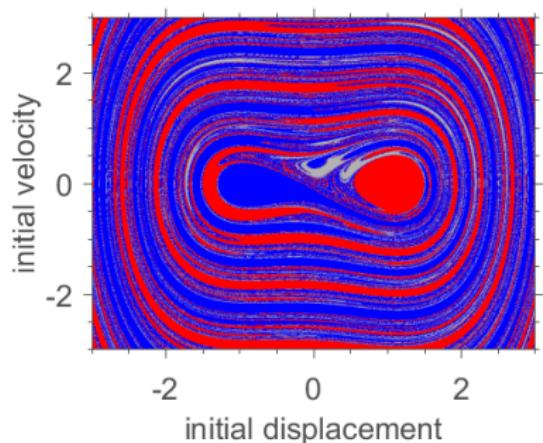


Figure:  $f = 0.083$  and  $\Omega = 0.2$

# Basins of attraction

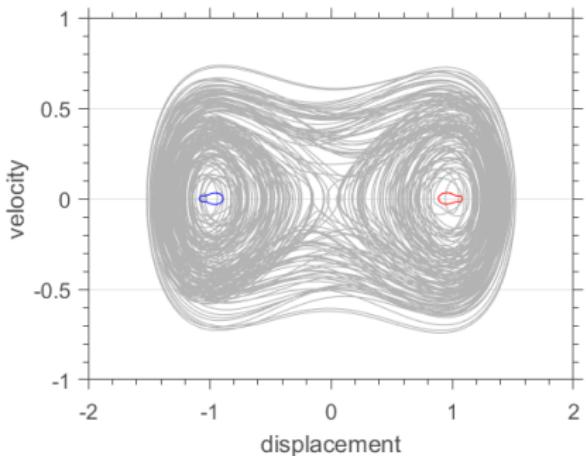
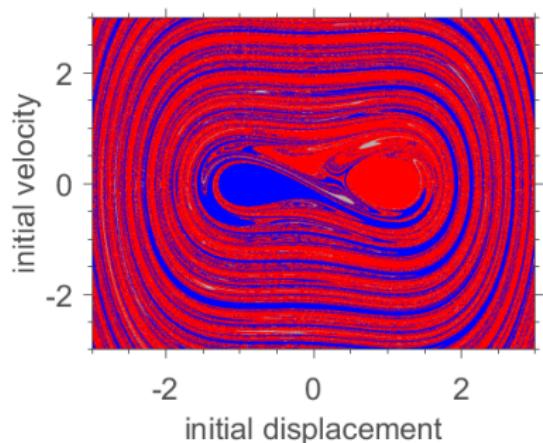


Figure:  $f = 0.083$  and  $\Omega = 0.3$

# Basins of attraction

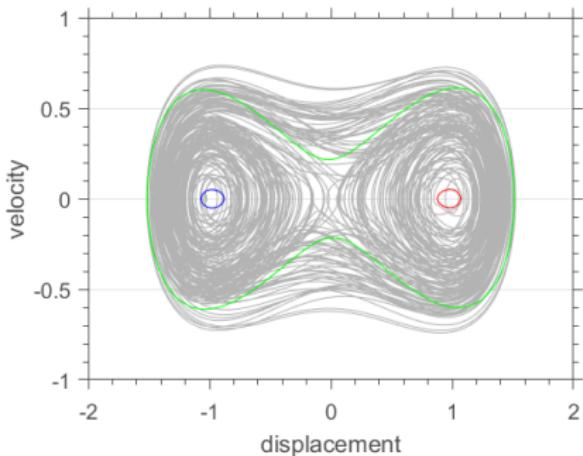
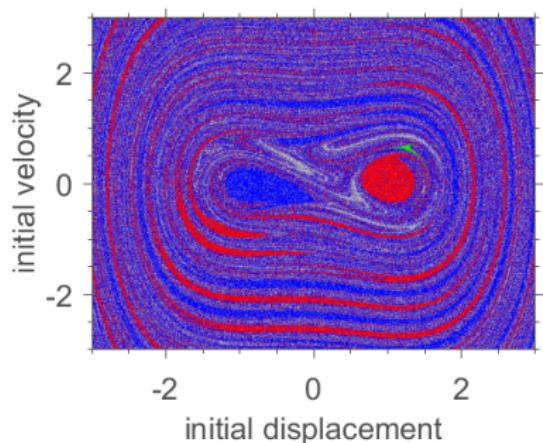


Figure:  $f = 0.083$  and  $\Omega = 0.4$

# Basins of attraction

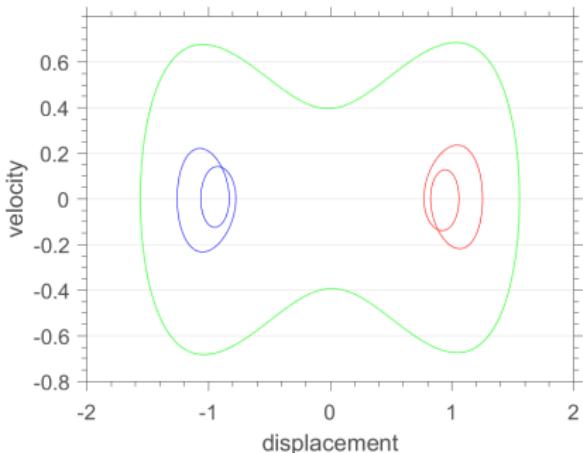
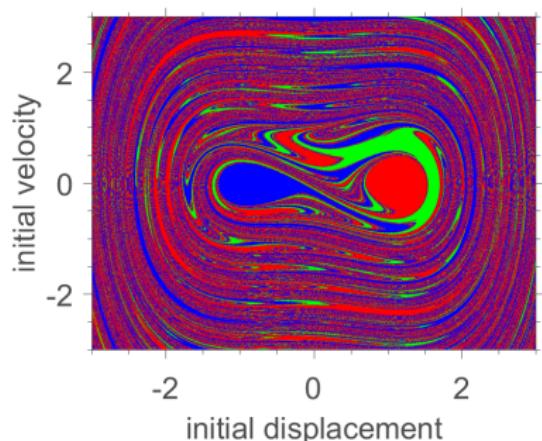


Figure:  $f = 0.083$  and  $\Omega = 0.5$

# Basins of attraction

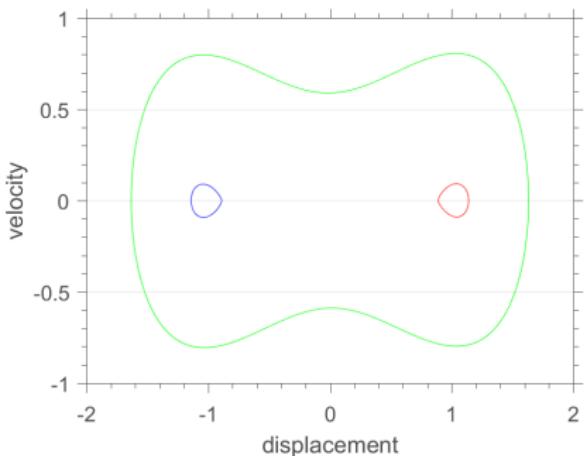
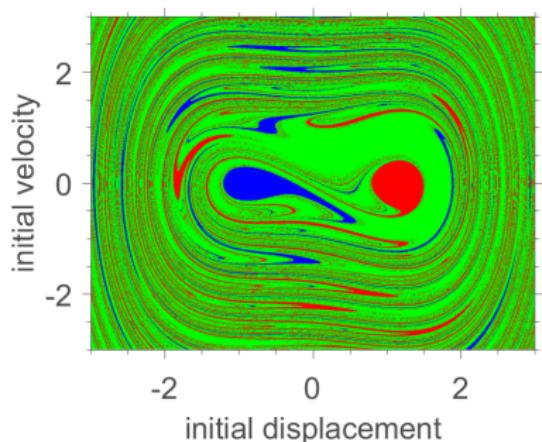


Figure:  $f = 0.083$  and  $\Omega = 0.6$

# Basins of attraction

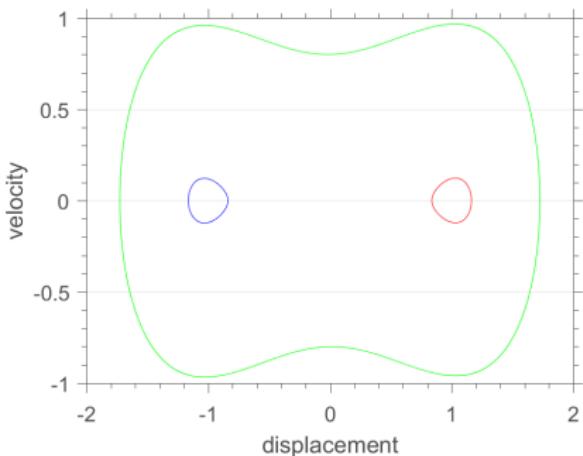
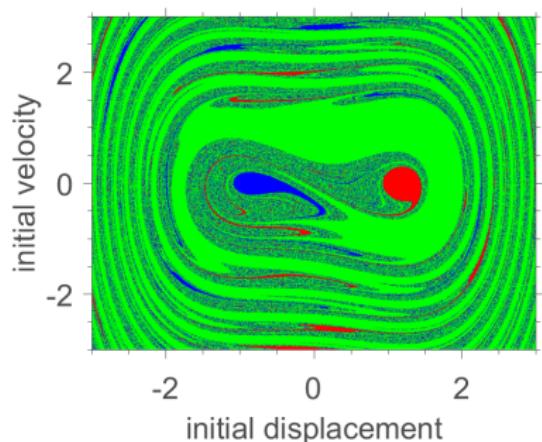


Figure:  $f = 0.083$  and  $\Omega = 0.7$

# Basins of attraction

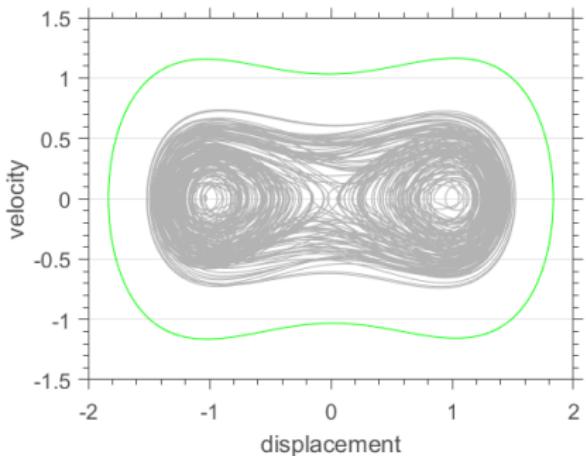
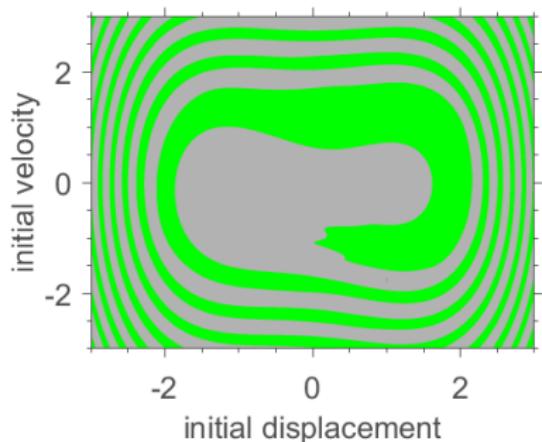


Figure:  $f = 0.083$  and  $\Omega = 0.8$

# Basins of attraction

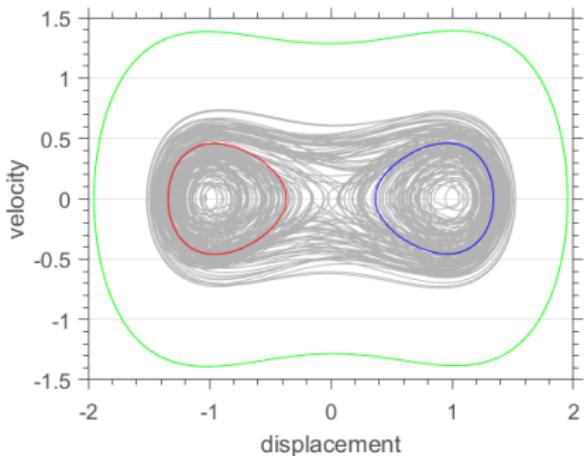
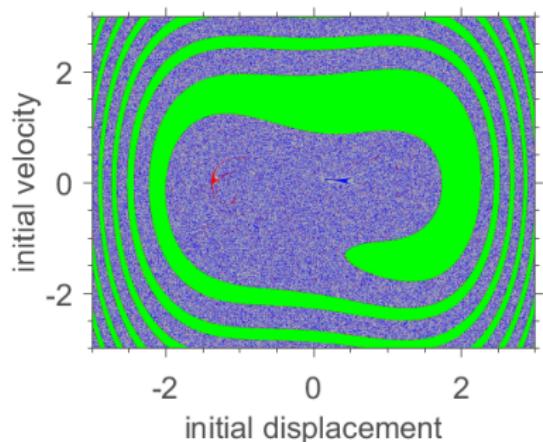


Figure:  $f = 0.083$  and  $\Omega = 0.9$

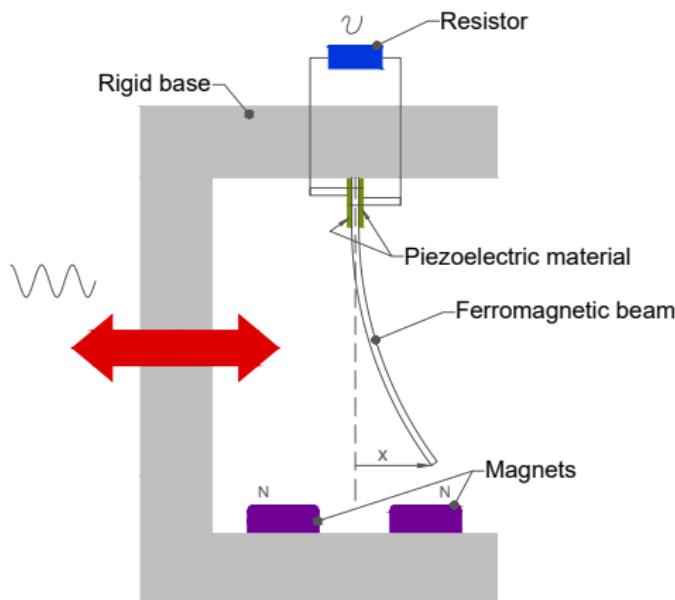
## Section 3

### Stochastic Dynamics



# Vibration based Energy Harvesting

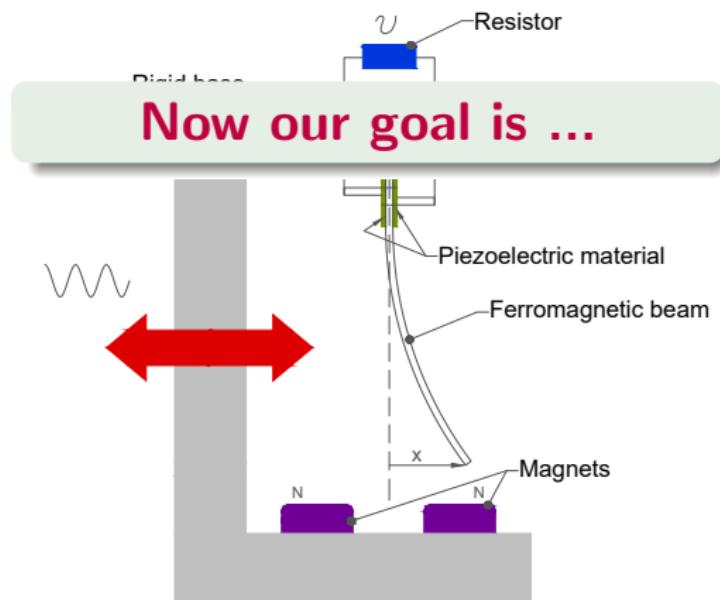
## Bistable system driven by regular signal



A. Erturk, J. Hoffmann and D. J. Inman, *A piezomagnetoelastic structure for broadband vibration energy harvesting*. *Applied Physics Letters*, 94: 254102, 2009.

# Vibration based Energy Harvesting

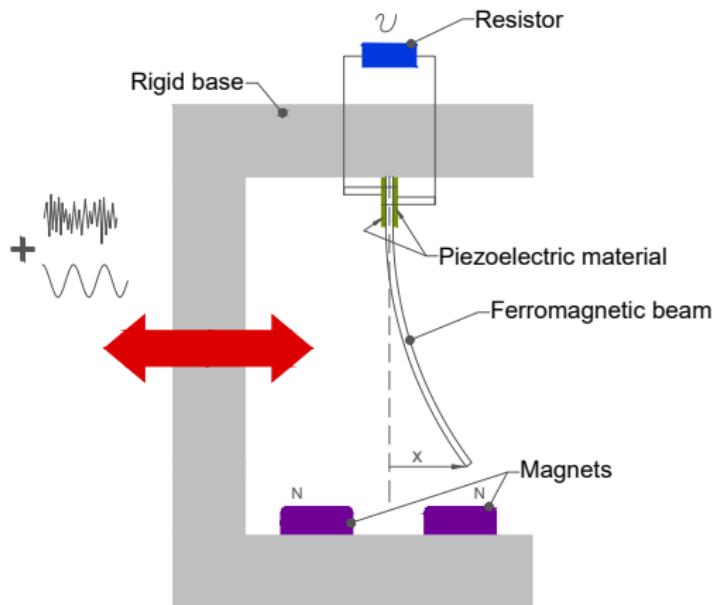
**Bistable system driven by regular signal**



A. Erturk, J. Hoffmann and D. J. Inman, *A piezomagnetoelastic structure for broadband vibration energy harvesting*. *Applied Physics Letters*, 94: 254102, 2009.

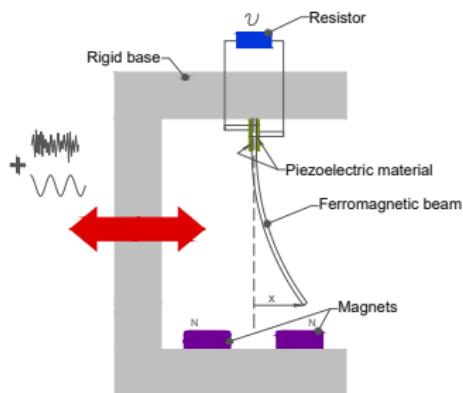
# Vibration based Energy Harvesting

**Bistable system driven by regular and noisy signals**



V. G. Lopes, J. V. L. L. Peterson, and A. Cunha Jr, **On the nonlinear stochastic dynamics of piezo-magneto-elastic energy harvester driven by colored noise**, (in preparation) 2019.

# Bistable harvester driven by regular and noisy signals



$$\ddot{x} + 2\xi\dot{x} - \frac{1}{2}x(1-x^2) - \chi v = f \cos \Omega t + \text{"noise"}$$

$$\dot{v} + \lambda v + \kappa \dot{x} = 0$$

$$x(0) = x_0, \quad \dot{x}(0) = \dot{x}_0, \quad v(0) = v_0$$



A. Erturk, J. Hoffmann and D. J. Inman, *A piezomagnetoelastic structure for broadband vibration energy harvesting*. **Applied Physics Letters**, 94: 254102, 2009.

# Nonlinear stochastic dynamical system

- external excitation  $N_t$ :

- zero-mean stationary Gaussian process
- covariance function:

$$\text{cov}_{N_t}(t_1, t_2) = \sigma \exp\left(-\frac{|t_2 - t_1|}{\tau_{\text{corr}}}\right), \quad \frac{\sigma^2}{\tau_{\text{corr}}} = \text{constant}$$

- stochastic evolution law:

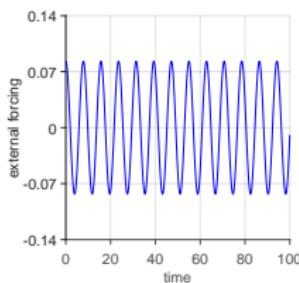
$$\ddot{X} + 2\xi \dot{X} - \frac{1}{2}x(1 - X^2) - \chi V = f \cos \Omega t + N_t$$

$$\dot{V} + \lambda V + \kappa \dot{X} = 0$$

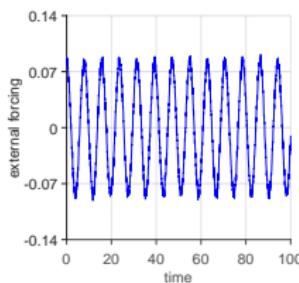
$$X(0) = x_0, \quad \dot{X}(0) = \dot{x}_0, \quad V(0) = v_0$$



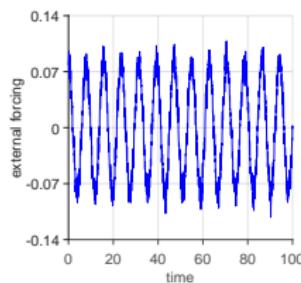
# Realizations of random external force



(a) 1% of noise



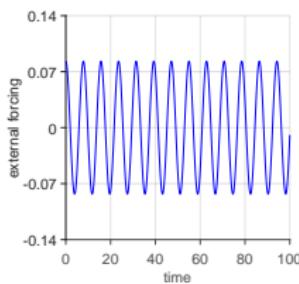
(b) 25% of noise



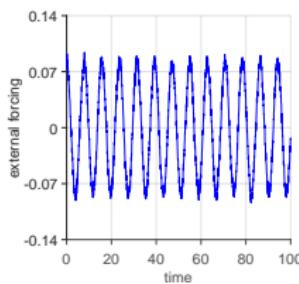
(c) 50% of noise

$$\sigma^2 / \tau_{cor} = 1$$

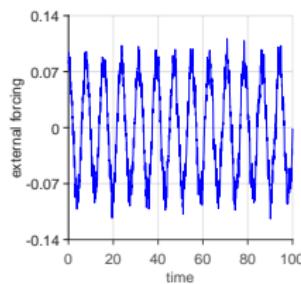
# Realizations of random external force



(a) 1% of noise



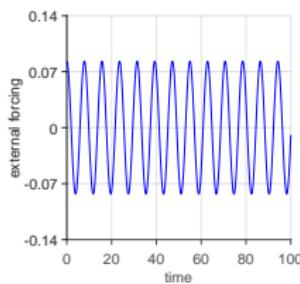
(b) 25% of noise



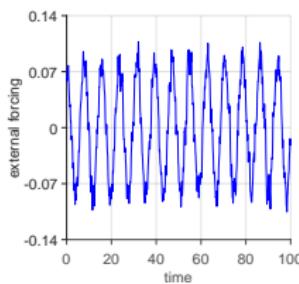
(c) 50% of noise

$$\sigma^2 / \tau_{cor} = 0.5$$

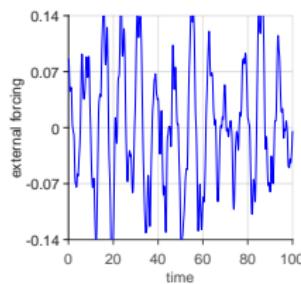
# Realizations of random external force



(a) 1% of noise



(b) 25% of noise



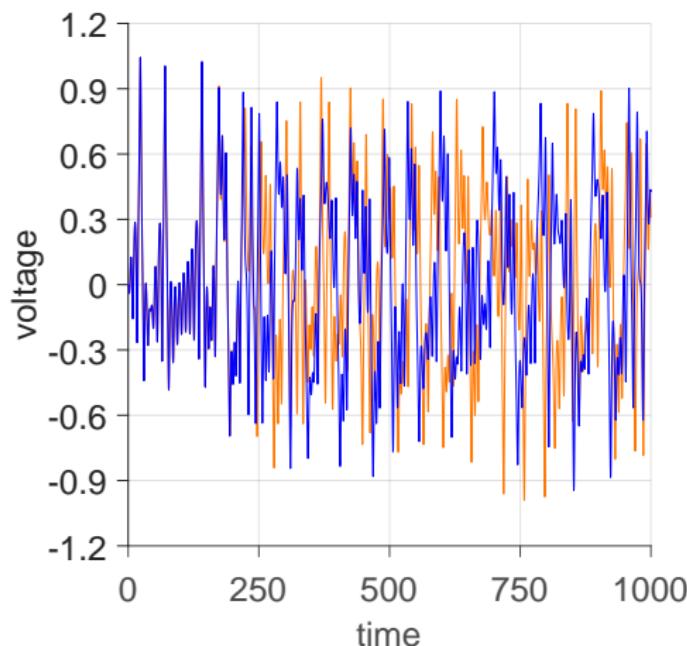
(c) 50% of noise

$$\sigma^2/\tau_{cor} = 0.1$$

# Nonlinear stochastic dynamics animation



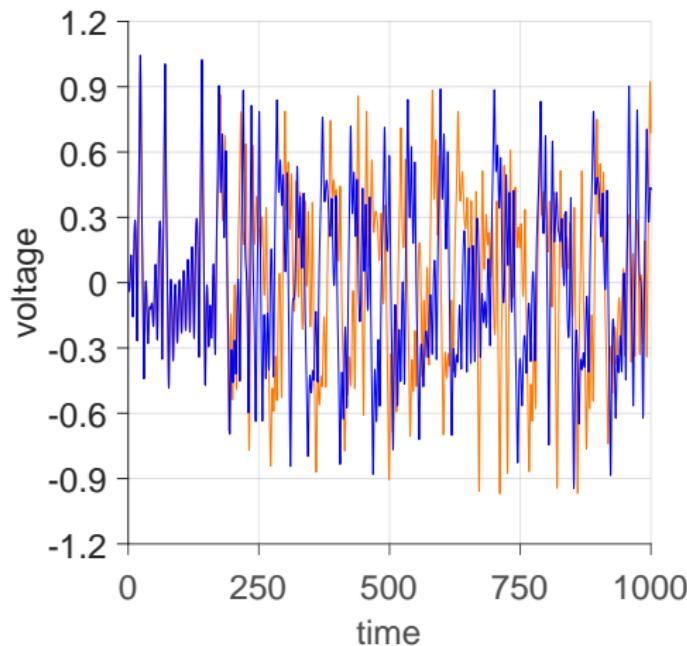
# Typical voltage time series (1% of noise)



$$(a) \sigma^2/\tau_{cor} = 1$$

$$f = 0.115, \Omega = 0.8$$

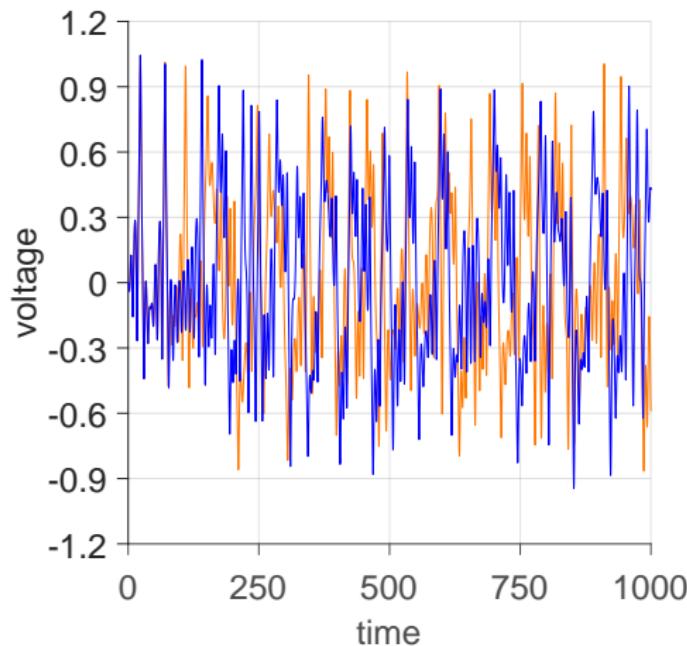
# Typical voltage time series (1% of noise)



$$(b) \sigma^2 / \tau_{cor} = 0.5$$

$$f = 0.115, \Omega = 0.8$$

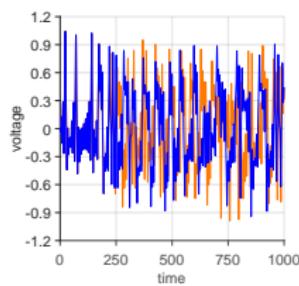
# Typical voltage time series (1% of noise)



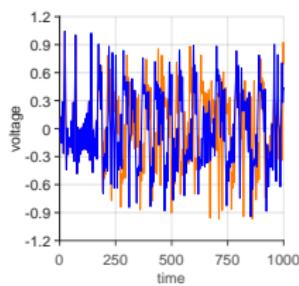
$$(c) \sigma^2 / \tau_{cor} = 0.1$$

$$f = 0.115, \Omega = 0.8$$

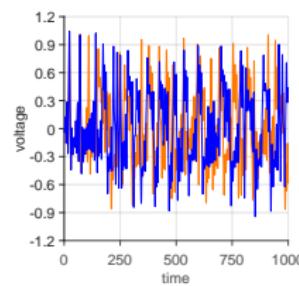
# Typical voltage time series (1% of noise)



(a)  $\sigma^2/\tau_{cor} = 1$



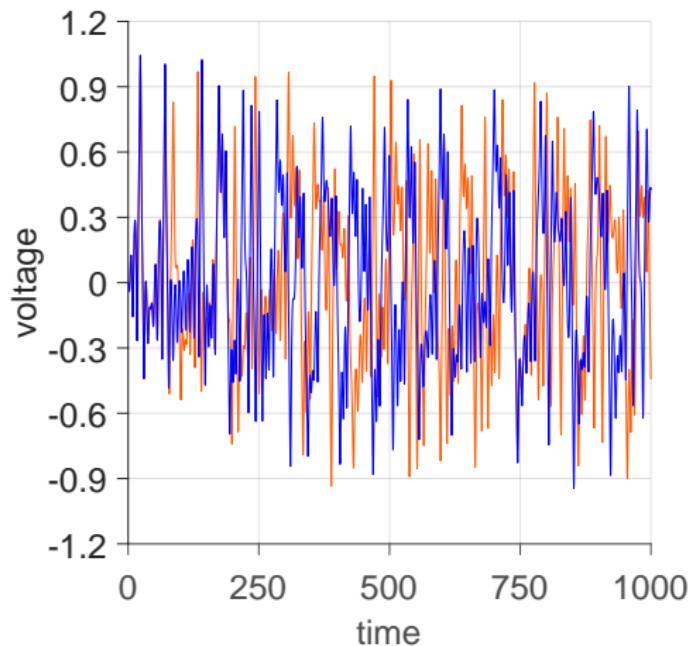
(b)  $\sigma^2/\tau_{cor} = 0.5$



(c)  $\sigma^2/\tau_{cor} = 0.1$

$$f = 0.115, \Omega = 0.8$$

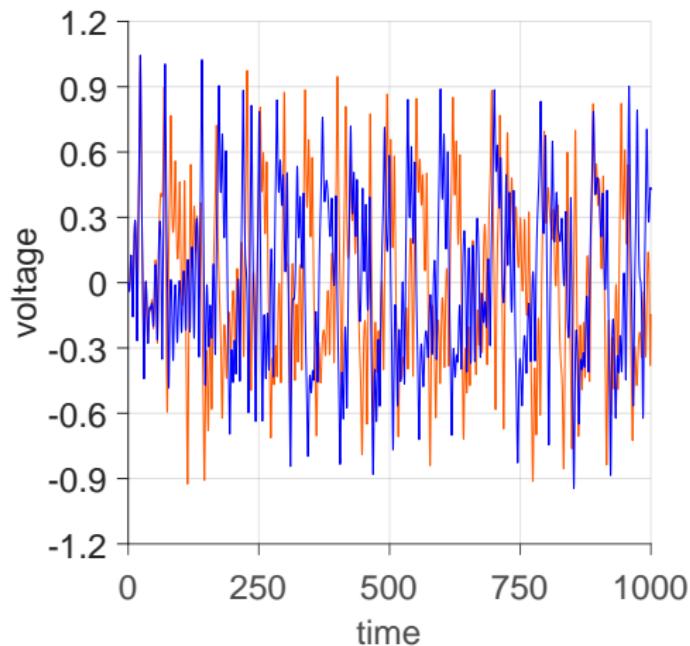
# Typical voltage time series (25% of noise)



$$(a) \sigma^2/\tau_{cor} = 1$$

$$f = 0.115, \Omega = 0.8$$

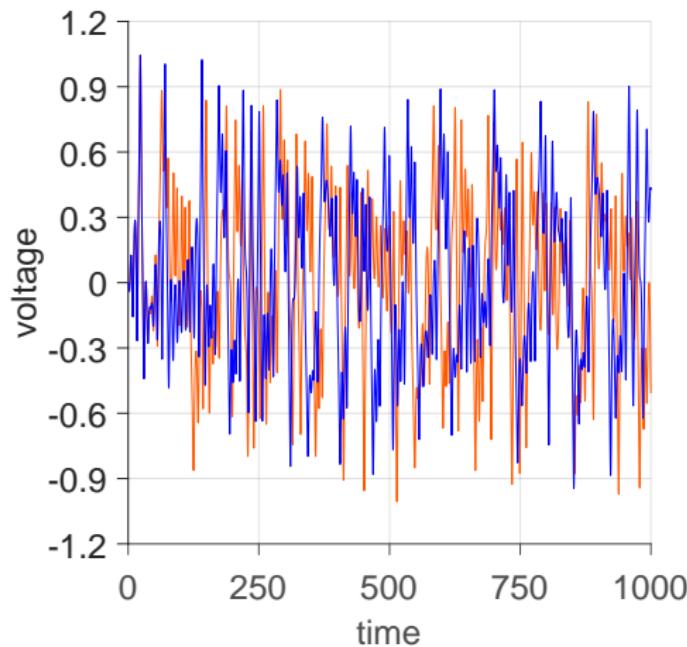
# Typical voltage time series (25% of noise)



$$(b) \sigma^2 / \tau_{cor} = 0.5$$

$$f = 0.115, \Omega = 0.8$$

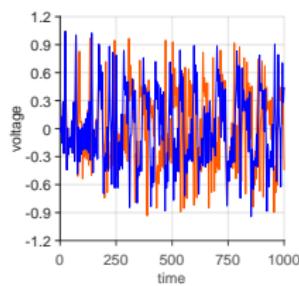
# Typical voltage time series (25% of noise)



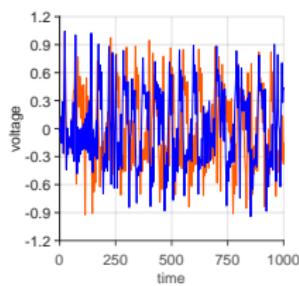
$$(c) \sigma^2 / \tau_{cor} = 0.1$$

$$f = 0.115, \Omega = 0.8$$

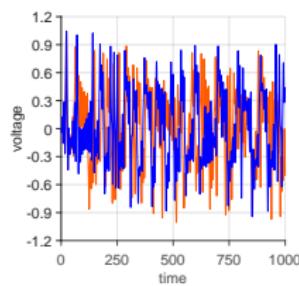
# Typical voltage time series (25% of noise)



(a)  $\sigma^2 / \tau_{cor} = 1$



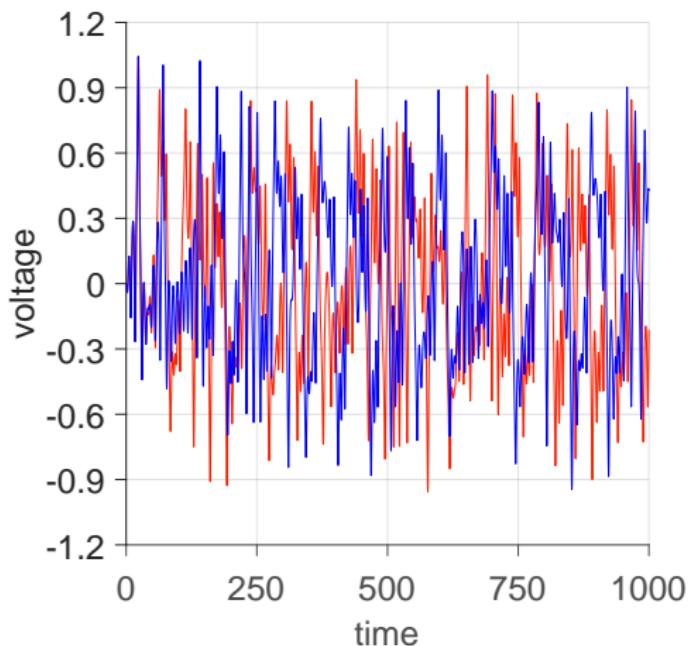
(b)  $\sigma^2 / \tau_{cor} = 0.5$



(c)  $\sigma^2 / \tau_{cor} = 0.1$

$$f = 0.115, \Omega = 0.8$$

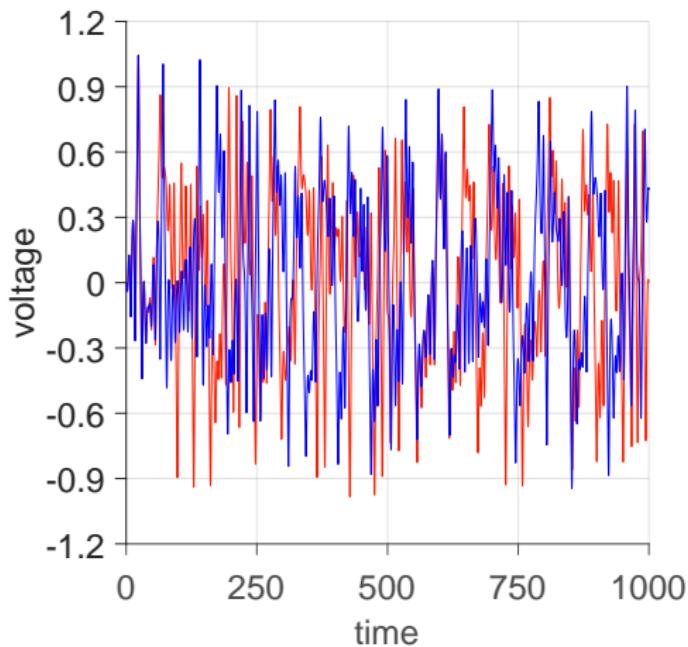
# Typical voltage time series (50% of noise)



$$(a) \sigma^2/\tau_{cor} = 1$$

$$f = 0.115, \Omega = 0.8$$

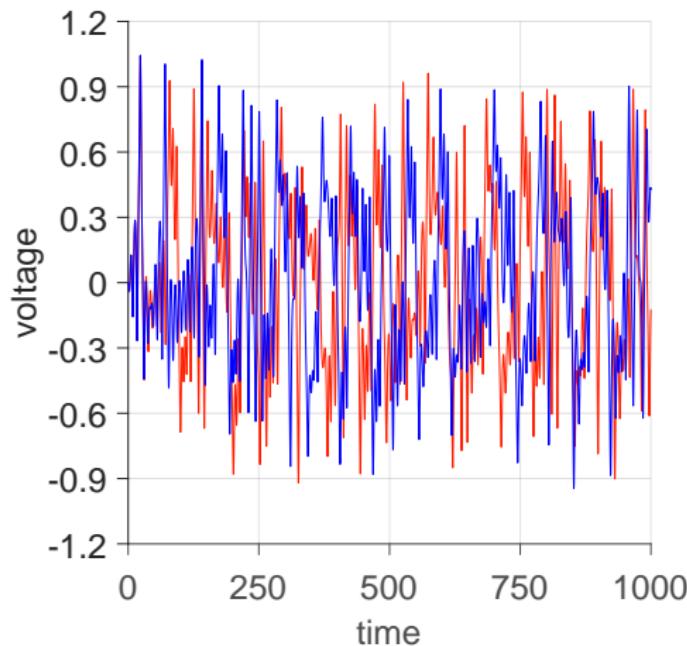
# Typical voltage time series (50% of noise)



$$(b) \sigma^2 / \tau_{cor} = 0.5$$

$$f = 0.115, \Omega = 0.8$$

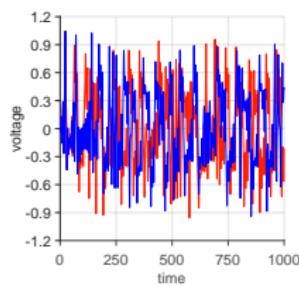
# Typical voltage time series (50% of noise)



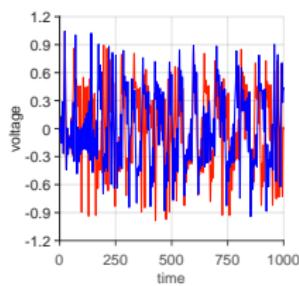
$$(c) \sigma^2/\tau_{cor} = 0.1$$

$$f = 0.115, \Omega = 0.8$$

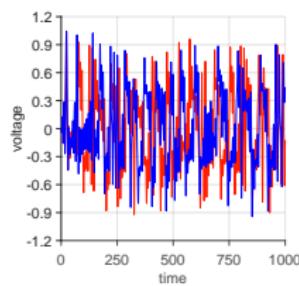
# Typical voltage time series (50% of noise)



(a)  $\sigma^2/\tau_{cor} = 1$



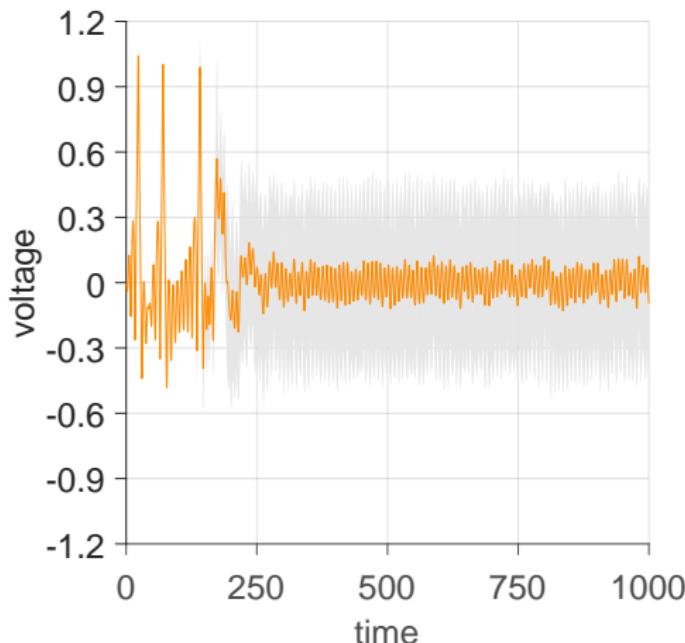
(b)  $\sigma^2/\tau_{cor} = 0.5$



(c)  $\sigma^2/\tau_{cor} = 0.1$

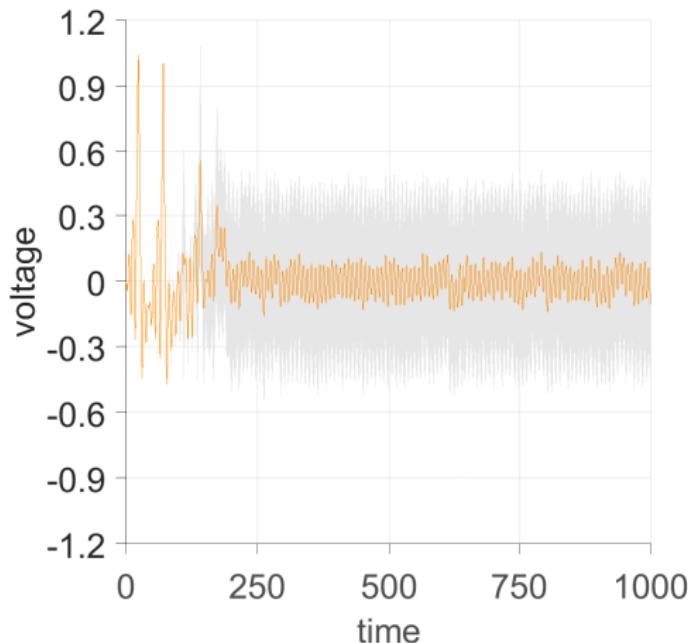
$$f = 0.115, \Omega = 0.8$$

# Low-order statistics (1% of noise)



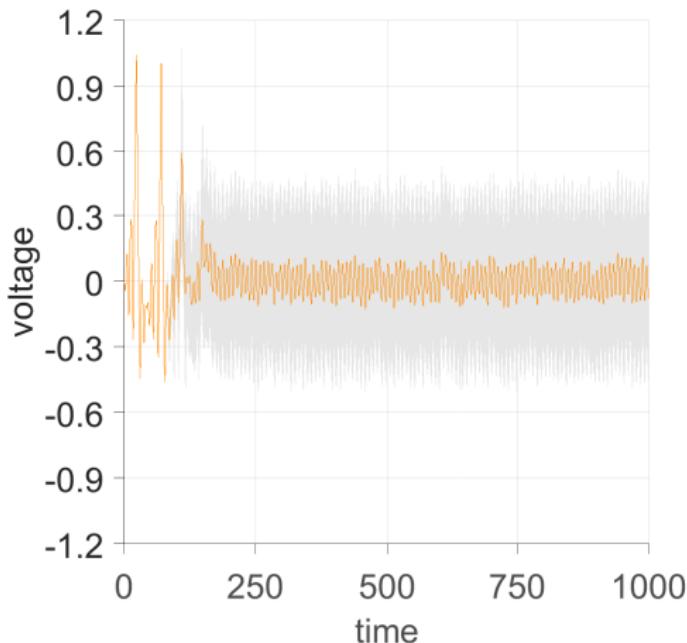
$$(a) \sigma^2 / \tau_{cor} = 1$$

# Low-order statistics (1% of noise)



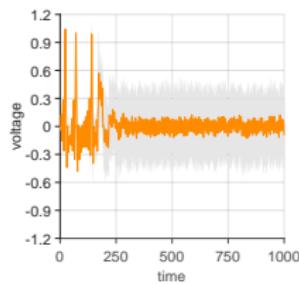
$$(b) \sigma^2 / \tau_{cor} = 0.5$$

# Low-order statistics (1% of noise)

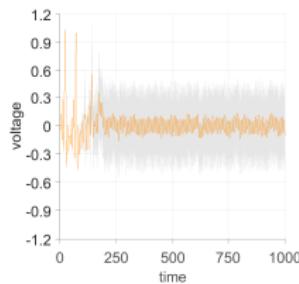


$$(c) \sigma^2 / \tau_{cor} = 0.1$$

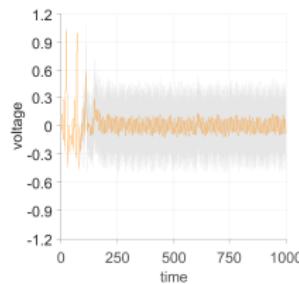
# Low-order statistics (1% of noise)



(a)  $\sigma^2/\tau_{cor} = 1$

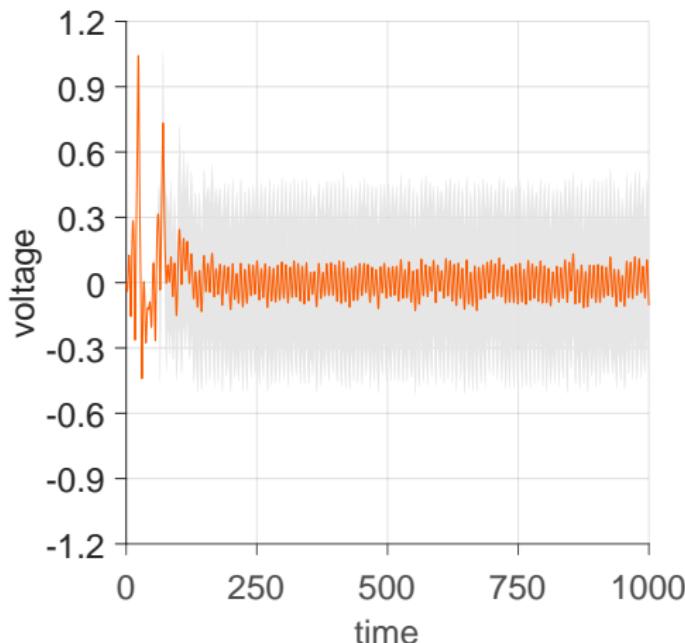


(b)  $\sigma^2/\tau_{cor} = 0.5$



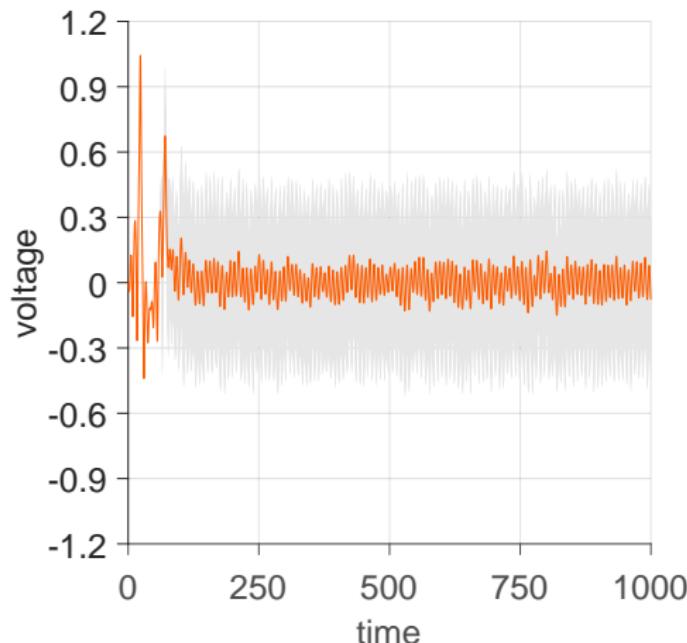
(c)  $\sigma^2/\tau_{cor} = 0.1$

# Low-order statistics (25% of noise)



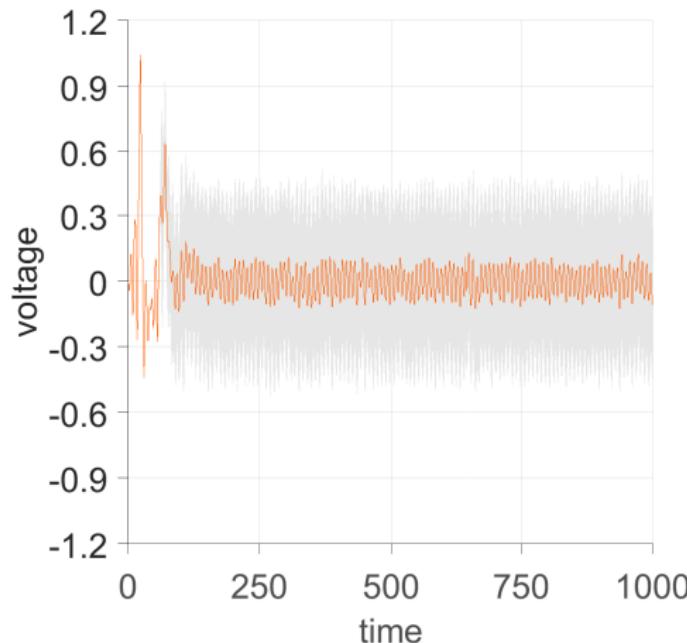
$$(a) \sigma^2 / \tau_{cor} = 1$$

# Low-order statistics (25% of noise)



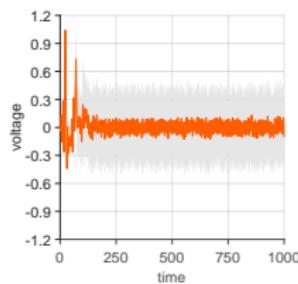
$$(b) \sigma^2 / \tau_{cor} = 0.5$$

# Low-order statistics (25% of noise)

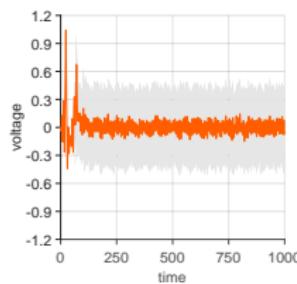


$$(c) \sigma^2 / \tau_{cor} = 0.1$$

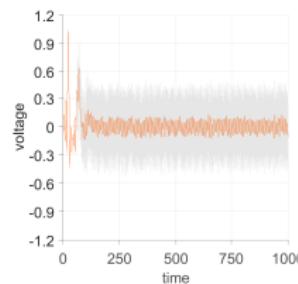
# Low-order statistics (25% of noise)



(a)  $\sigma^2/\tau_{cor} = 1$

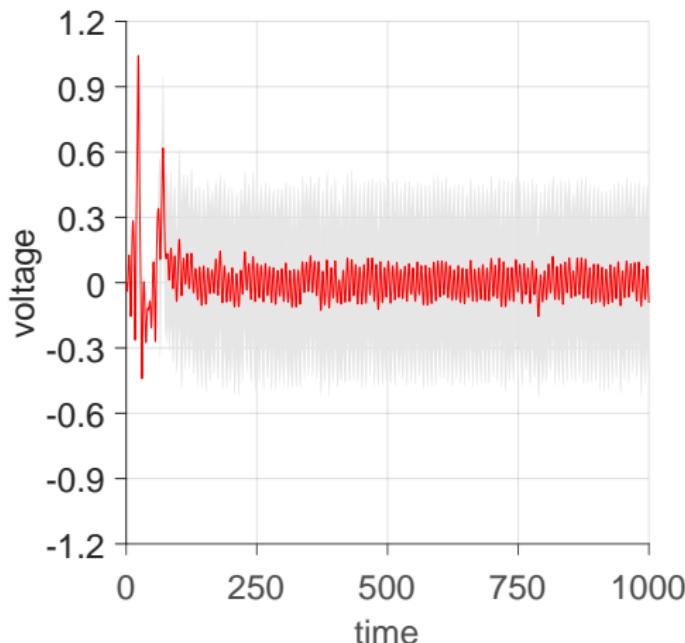


(b)  $\sigma^2/\tau_{cor} = 0.5$



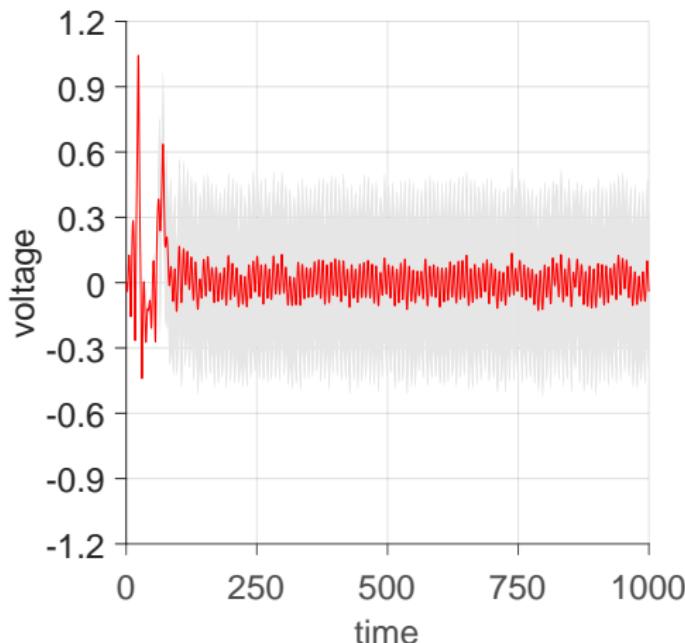
(c)  $\sigma^2/\tau_{cor} = 0.1$

# Low-order statistics (50% of noise)



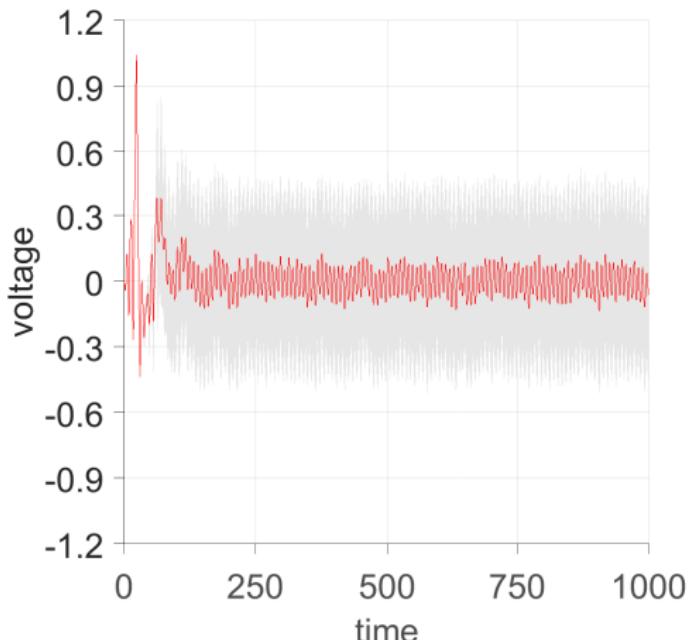
(a)  $\sigma^2/\tau_{cor} = 1$

# Low-order statistics (50% of noise)



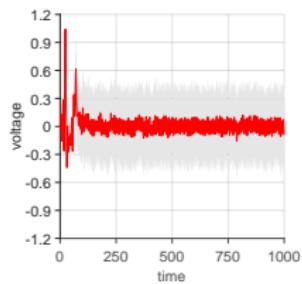
$$(b) \sigma^2 / \tau_{cor} = 0.5$$

# Low-order statistics (50% of noise)

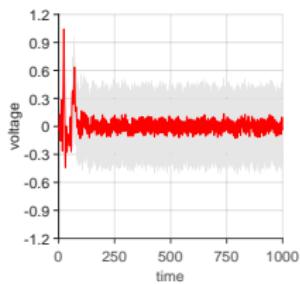


$$(c) \sigma^2 / \tau_{cor} = 0.1$$

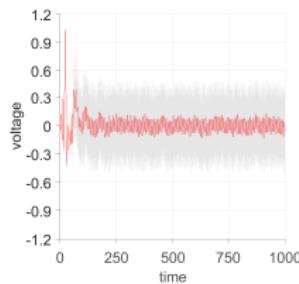
# Low-order statistics (50% of noise)



(a)  $\sigma^2/\tau_{cor} = 1$

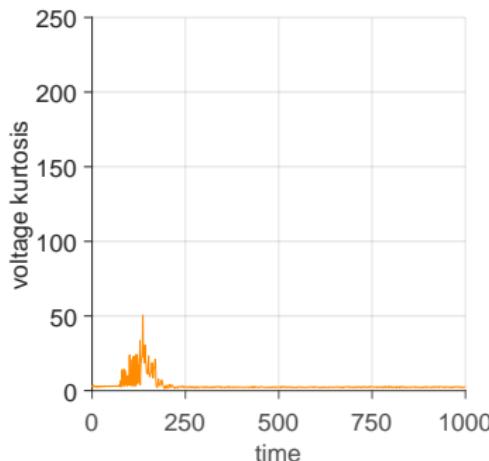
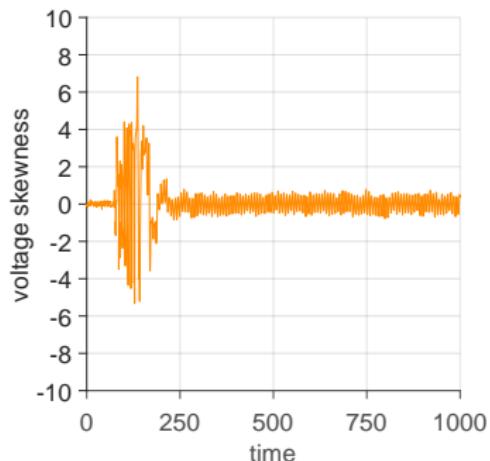


(b)  $\sigma^2/\tau_{cor} = 0.5$



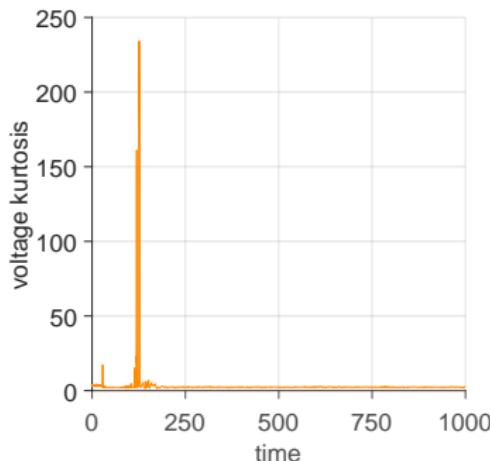
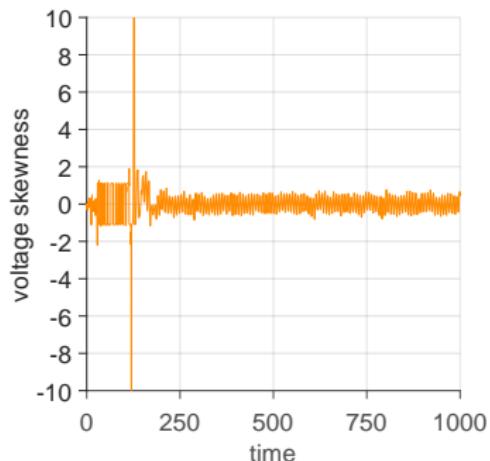
(c)  $\sigma^2/\tau_{cor} = 0.1$

# High-order statistics (1% of noise)



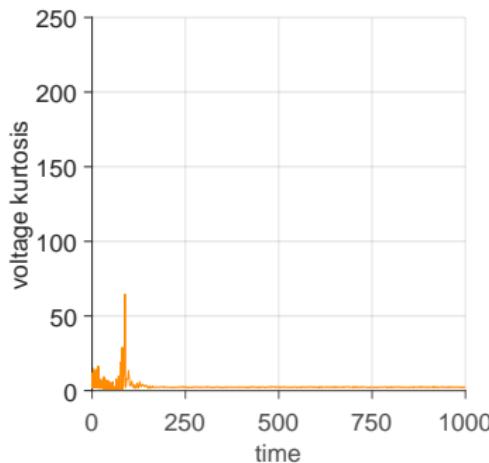
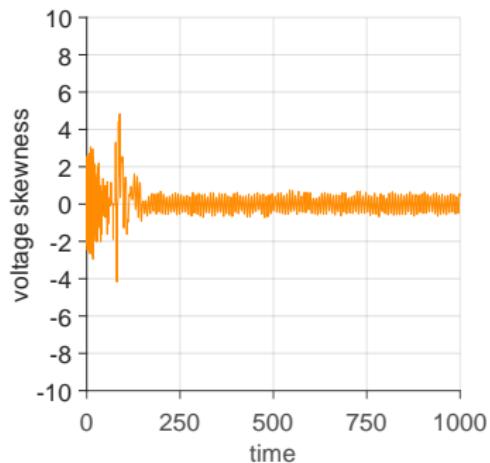
$$(a) \sigma^2/\tau_{cor} = 1$$

# High-order statistics (1% of noise)



$$(b) \sigma^2 / \tau_{cor} = 0.5$$

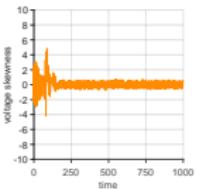
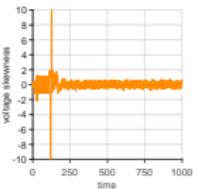
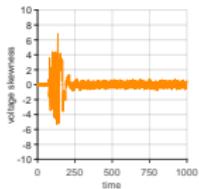
# High-order statistics (1% of noise)



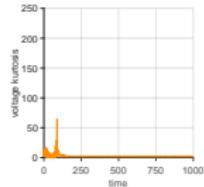
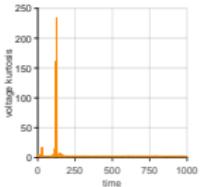
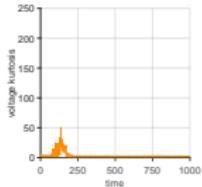
$$(c) \sigma^2 / \tau_{cor} = 0.1$$

# High-order statistics (1% of noise)

$$\sigma^2/\tau_{cor} \in \{1, 0.5, 0.1\}$$

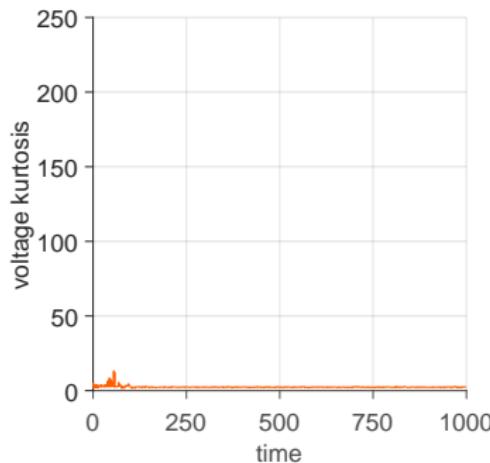
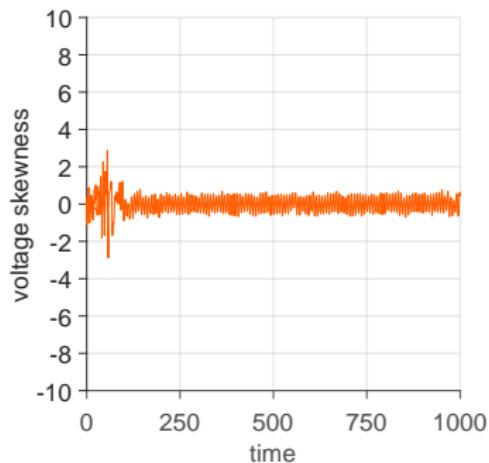


sknewness



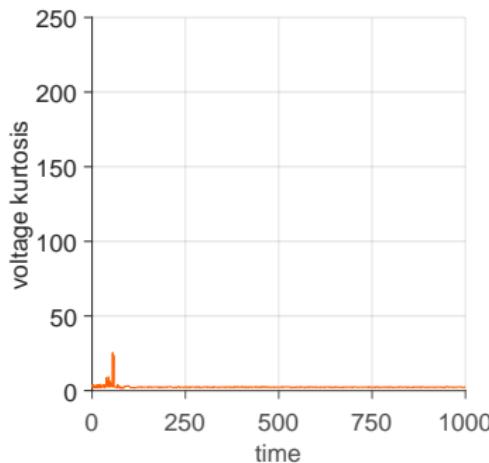
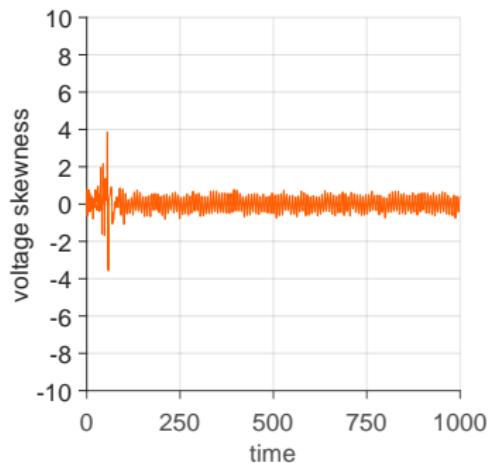
kurtosis

# High-order statistics (25% of noise)



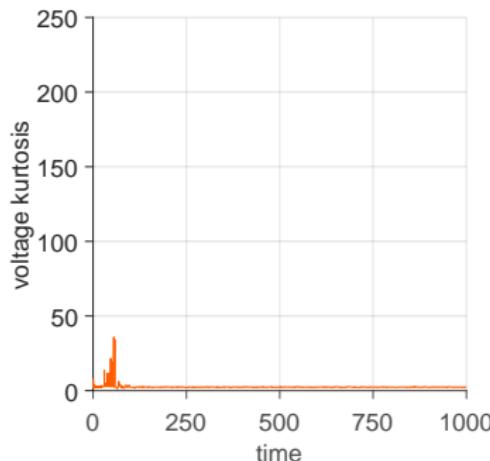
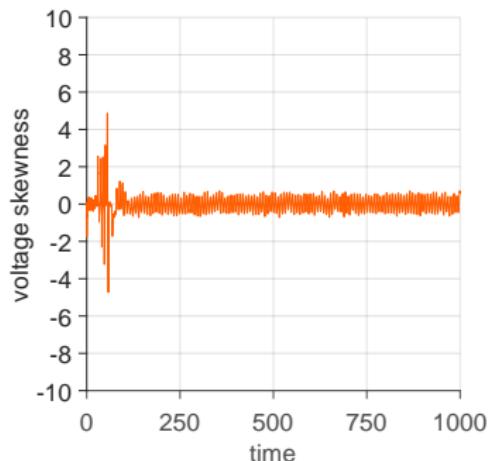
$$(a) \sigma^2/\tau_{cor} = 1$$

# High-order statistics (25% of noise)



$$(b) \sigma^2 / \tau_{cor} = 0.5$$

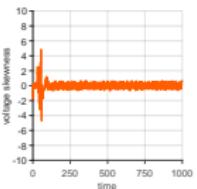
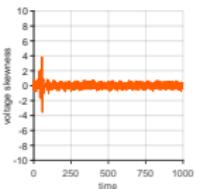
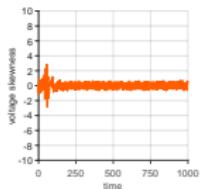
# High-order statistics (25% of noise)



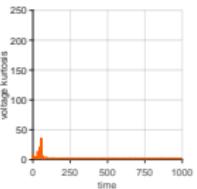
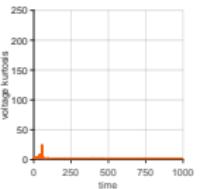
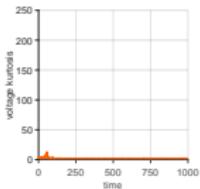
$$(c) \sigma^2/\tau_{cor} = 0.1$$

# High-order statistics (25% of noise)

$$\sigma^2/\tau_{cor} \in \{1, 0.5, 0.1\}$$

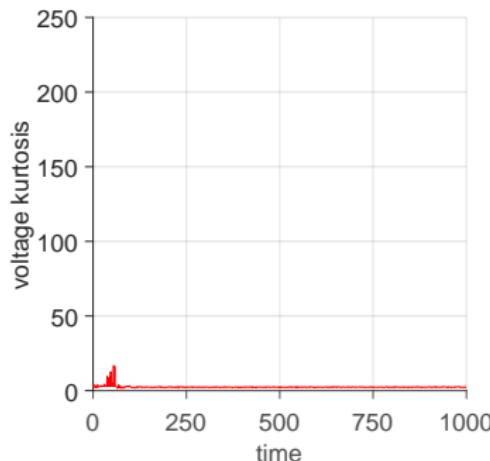
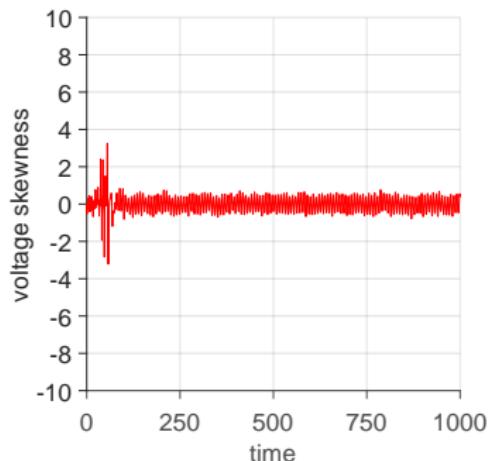


sknewness



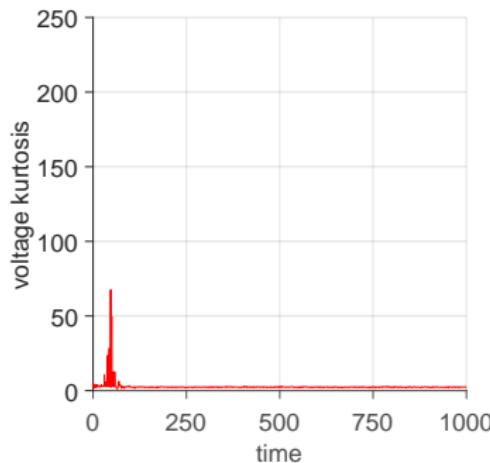
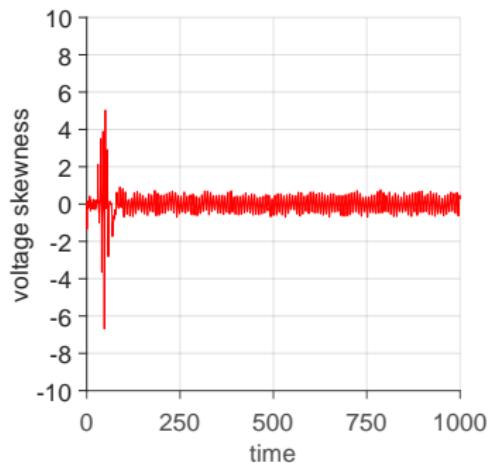
kurtosis

# High-order statistics (50% of noise)



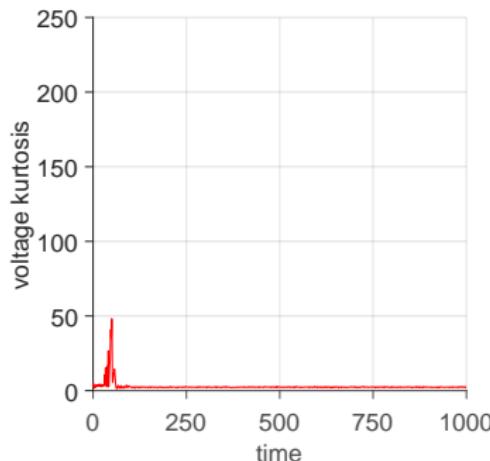
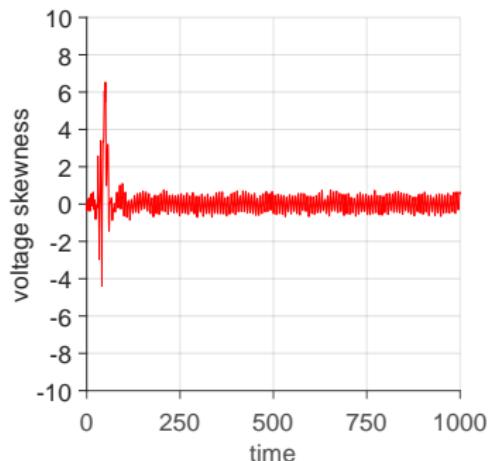
$$(a) \sigma^2/\tau_{cor} = 1$$

# High-order statistics (50% of noise)



$$(b) \sigma^2 / \tau_{cor} = 0.5$$

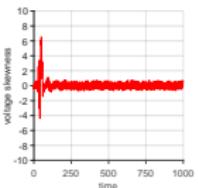
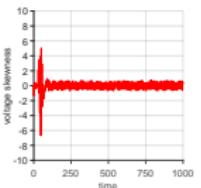
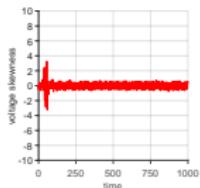
# High-order statistics (50% of noise)



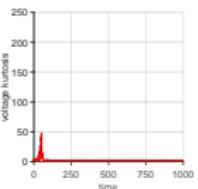
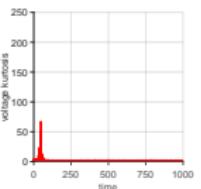
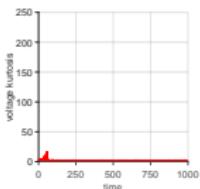
$$(c) \sigma^2 / \tau_{cor} = 0.1$$

# High-order statistics (50% of noise)

$$\sigma^2/\tau_{cor} \in \{1, 0.5, 0.1\}$$



sknewness



kurtosis

## Section 4

### Final Remarks



# Final remarks

## Contributions:

- Investigation of the system deterministic dynamics
  - bifurcation analysis
  - basis of attractions exploration
- Investigation of the system stochastic dynamics
  - colored noise disturbance
  - intensity and correlation time effects

## Ongoing research:

- Improve system efficiency via control of chaos
- Construction of an experimental apparatus



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Científico e Tecnológico



C A P E S



# Thank you for your attention!

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V. G. Lopes, J. V. L. L. Peterson, and A. Cunha Jr,

**Nonlinear characterization of a bistable energy harvester dynamical system**, 2019.  
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(under review) <https://hal.archives-ouvertes.fr/hal-01531845>



# Physical system parameters

parameter	value
$\xi$	0.01
$\chi$	0.05
$f$	0.083
$\Omega$	0.8
$\lambda$	0.05
$\kappa$	0.5

# Computational representation of the noise

Karhunen-Loève decomposition:

$$N_t = \mathbb{E} \{ N_t \} + \sum_{n=1}^{\infty} \sigma_n \sqrt{\lambda_n} \varphi_n(t) Y_n$$

$$\int_{\mathbb{R}} \text{cov}_N(t_1, t_2) \varphi_n(t_2) dt_1 = \lambda_n \varphi_n(t_1), \quad t_1 \in \mathbb{R}$$

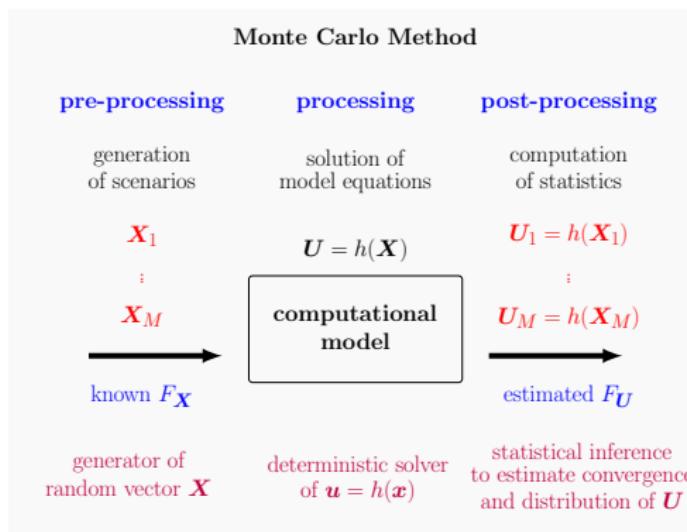
$$\mathbb{E} \{ Y_n \} = 0 \quad \text{and} \quad \mathbb{E} \{ Y_n Y_m \} = \delta_{mn}$$



D. Xiu, **Numerical Methods for Stochastic Computations: A Spectral Method Approach**, Princeton University Press, 2010.



# Propagation of uncertainties: Monte Carlo method



A. Cunha Jr, R. Nasser, R. Sampaio, H. Lopes, and K. Breitman, *Uncertainty quantification through Monte Carlo method in a cloud computing setting*. *Computer Physics Communications*, 185: 1355–1363, 2014.