

Bifurcation analysis and control of chaos on bistable piezoelectric energy harvesting systems

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1 Introduction

2 Dynamical System

3 Controlling Chaos

4 Final Remarks

Section 1

Introduction



April 4,
2005



March 13,
2013



L. Gamaitoni, Fundamentals on energy, NiPS Summer School 2018, University of Perugia.







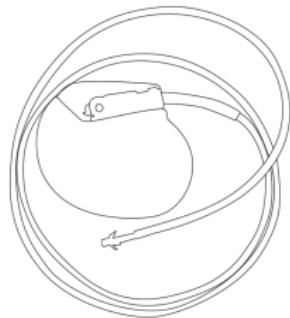
Wikimedia Commons, "File:St Jude Medical pacemaker in hand.jpg — Wikimedia Commons, the free media repository", 2014.

What's common in both cases?



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Electronic devices demanding energy!



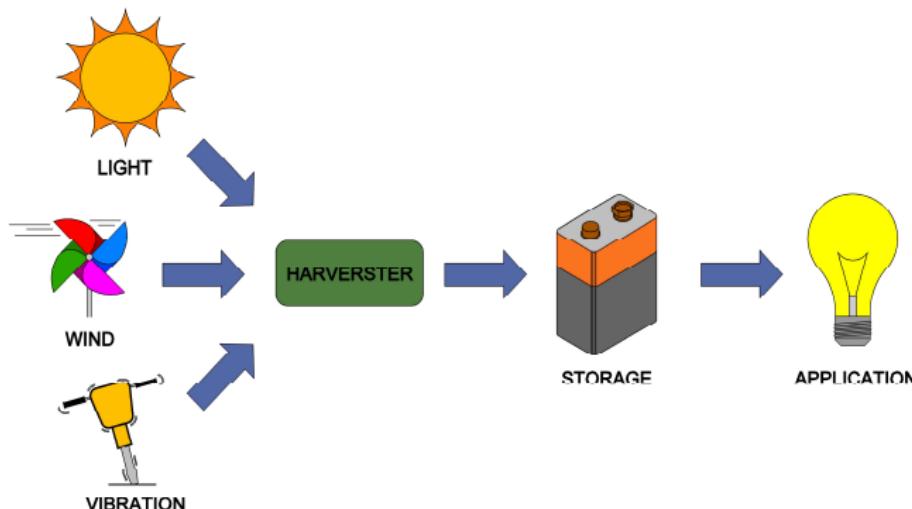
sensor
monitoring
wireless
eh
harvested
bistable
harvester
vibration

smart challenge
design powered
battery
harvesting
energy node
power holistic
rectenna
optimisation

*Picture obtained from Google Images.

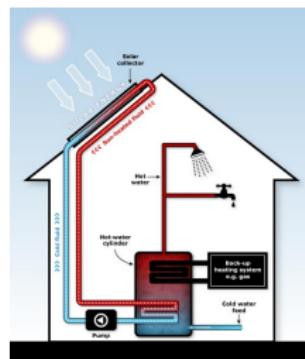
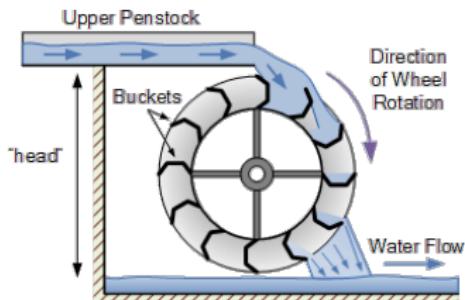


Energy Harvesting concept



- Capture wasted energy from external sources
- Store this wasted energy for future use
- Use the stored energy to supply other devices

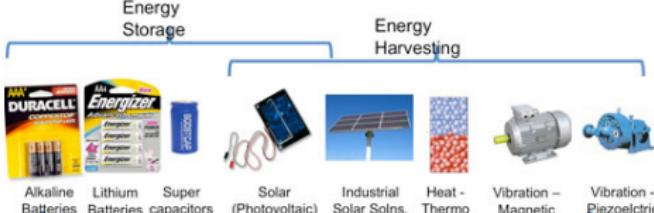
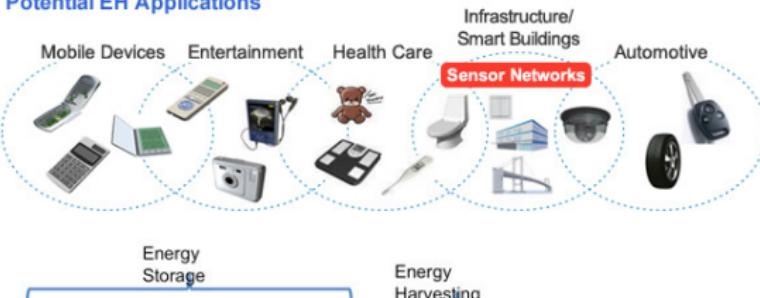
Classical technologies in Energy Harvesting



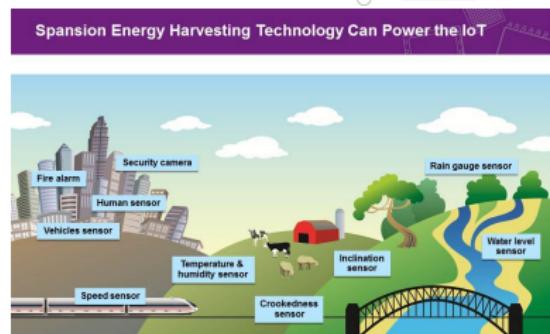
*Pictures obtained from Google Images, several sources. If you are the owner of any one of these images, consider its use a compliment.

Emergent technologies in Energy Harvesting

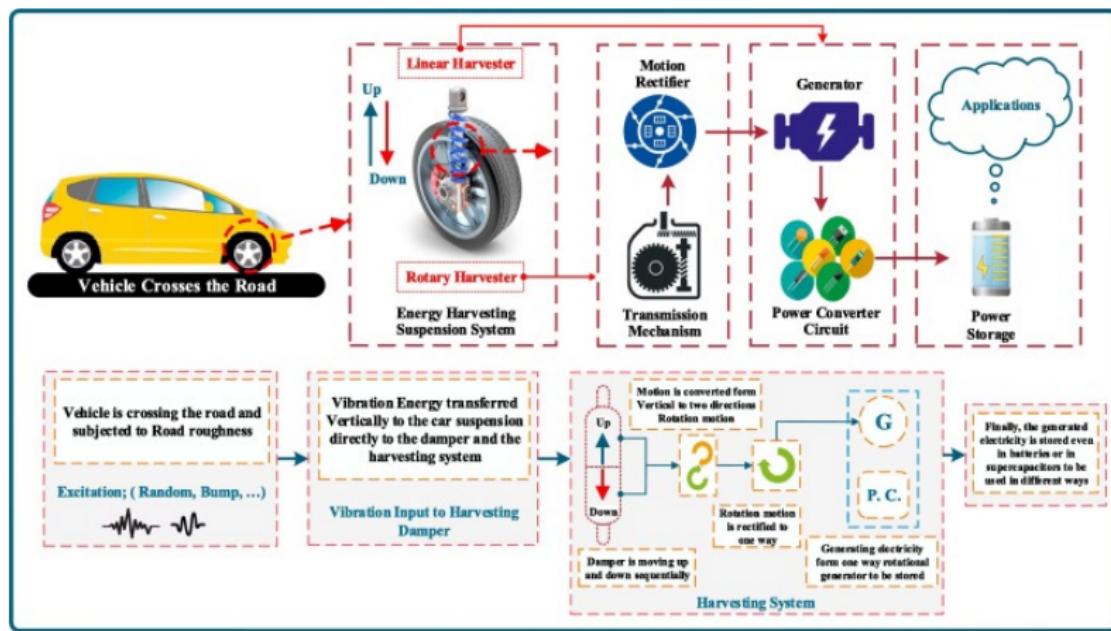
Potential EH Applications



*Pictures obtained from Google Images, several sources. If you are the owner of any one of these images, consider its use a compliment.

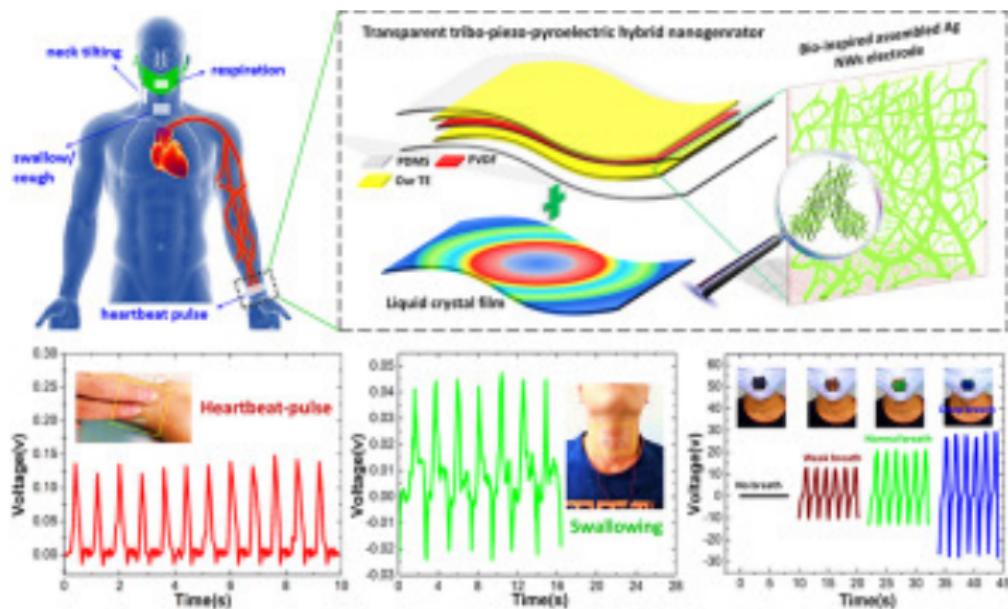


Emergent technologies in Energy Harvesting



*Picture from: Mohamed A.A. Abdelkareem et al, *Vibration energy harvesting in automotive suspension system: A detailed review*, Applied Energy, Volume 229, 2018
<http://www.sciencedirect.com/science/article/pii/S0306261918311851>)

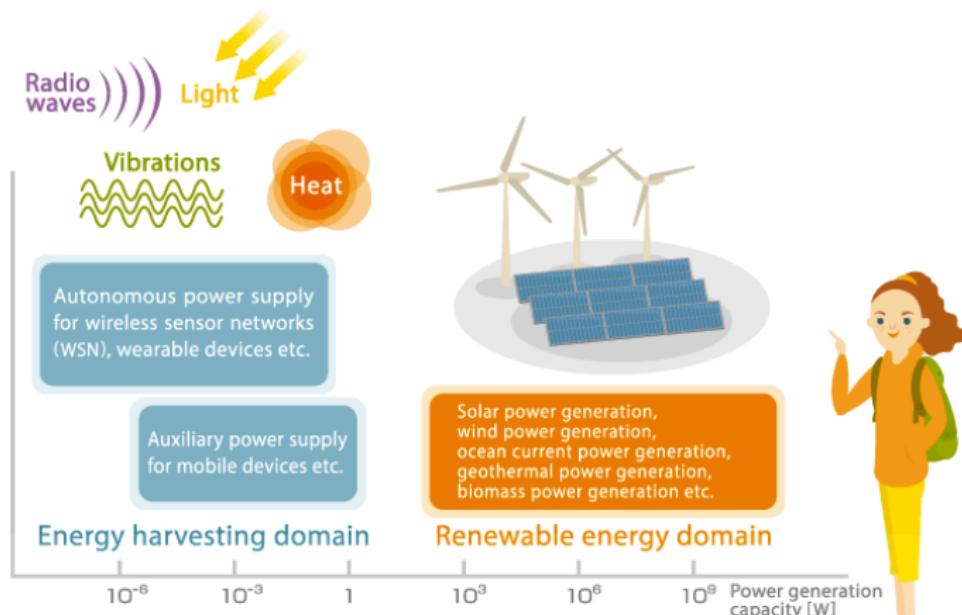
Emergent technologies in Energy Harvesting



*Picture from: Jian-Guo Sun et al, A flexible transparent one-structure tribo-piezo-pyroelectric hybrid energy generator based on bio-inspired silver nanowires network for biomechanical energy harvesting and physiological monitoring, Nano Energy, Volume 48, 2018

Energy scale for modern Energy Harvesting

- Power generation capacity and main applications of energy harvesting



*Picture from <http://www.global.tdk.com/techmag/knowledgebox/vol1.htm>

Energy Harvesting working principles

- Vibration based (piezoelectric effect)
- Contact based (triboelectric effect)
- Temperature based (thermoelectric effect)
- Heat based (pyroelectric effect)
- Light based (photoelectric effect)
- Fluid flow based
- Radio frequency based
- etc



Energy Harvesting working principles

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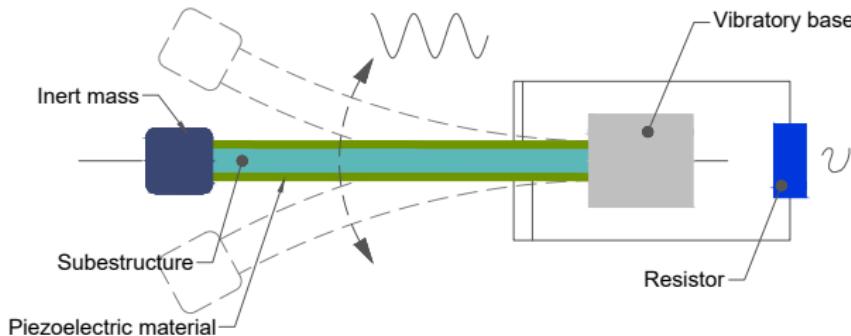
Some characteristics of Vibration Energy Harvesting

- No energy transmission systems required
- No large energy storage devices required
- Wide range of application areas
- Many physical layouts available
- System dynamics high complexity
- Low power recovering
- Recovered power quality depends on excitation
- Suitable for small electronic powering



Linear Vibratory Harvester

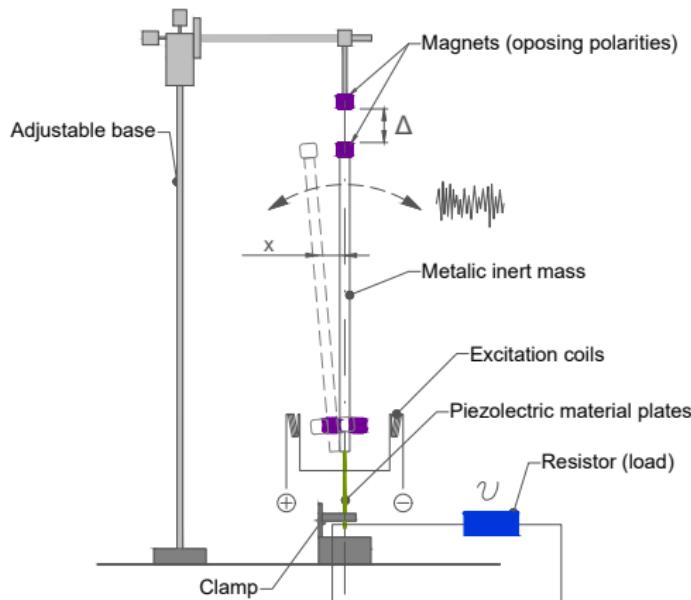
Monostable system driven by regular signal



S. Roundy, P. K. Wright and J. Rabaey, A study of low level vibrations as a power source for wireless sensor nodes. *Computer Communications*, 26: 1131-1144, 2003.

Nonlinear Vibratory Harvester

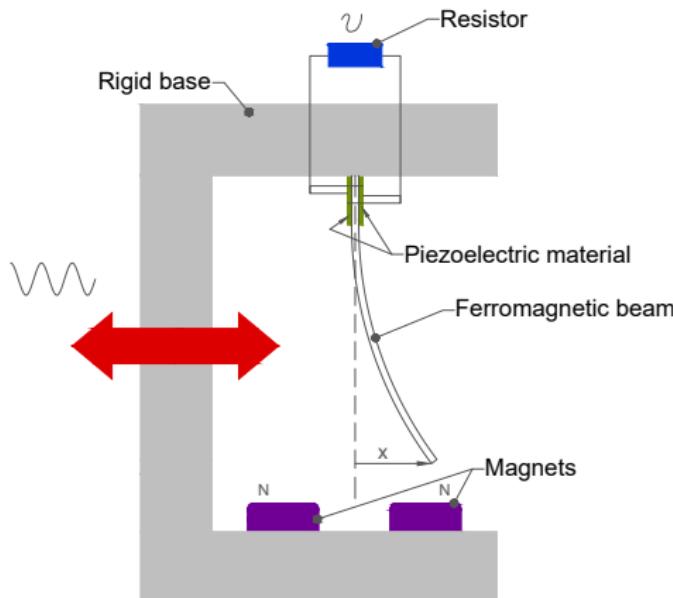
Bistable system driven by a noisy signal



F. Cottone, H. Vocca and L. Gammaitoni, Nonlinear energy harvesting. *Physical Review Letters*, 102: 080601, 2009.

Nonlinear Vibratory Harvester

Bistable system driven by regular signal



A. Erturk, J. Hoffmann and D. J. Inman, *A piezomagnetoelastic structure for broadband vibration energy harvesting*. *Applied Physics Letters*, 94: 254102, 2009.

Research objectives

This research has several objectives:

- Investigate in detail the underlying nonlinear dynamics
 - Time series
 - Poincaré sections
 - Bifurcation diagrams
 - Basis of attractions
 - Test 0-1 for chaos
- Model the underlying uncertainties and study their influence
 - System parameters variability
 - Noise in system excitation
- Propose strategies to enhance the recovered energy
 - Nonlinear optimization
 - Control of chaos

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Section 2

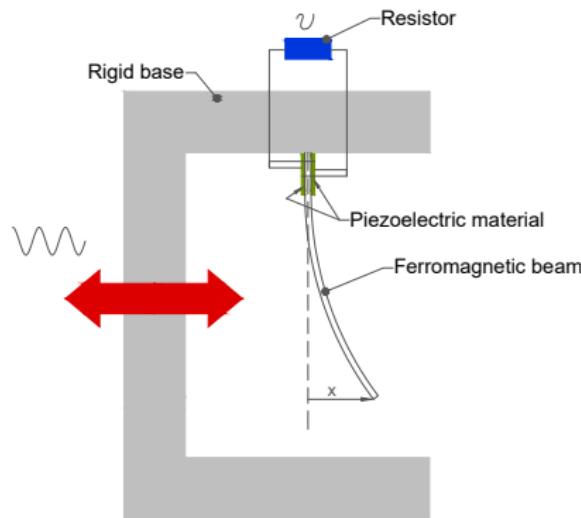
Dynamical System



Linear Dynamics



Linear harvester driven by regular signal



$$\ddot{x} + 2\xi\dot{x} + x + \chi v = f \cos \Omega t$$

$$\dot{v} + \lambda v + \kappa \dot{x} = 0$$

$$x(0) = x_0, \dot{x}(0) = \dot{x}_0, v(0) = v_0$$

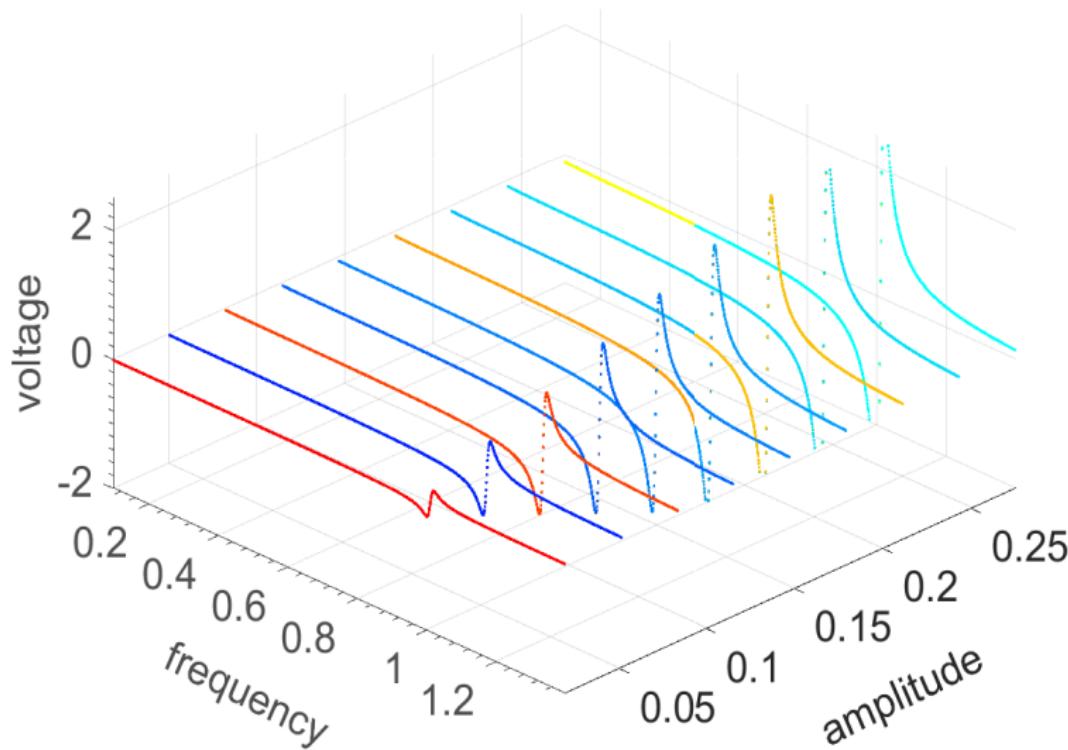


A. Erturk, J. Hoffmann and D. J. Inman, *A piezomagnetoelastic structure for broadband vibration energy harvesting*. **Applied Physics Letters**, 94: 254102, 2009.

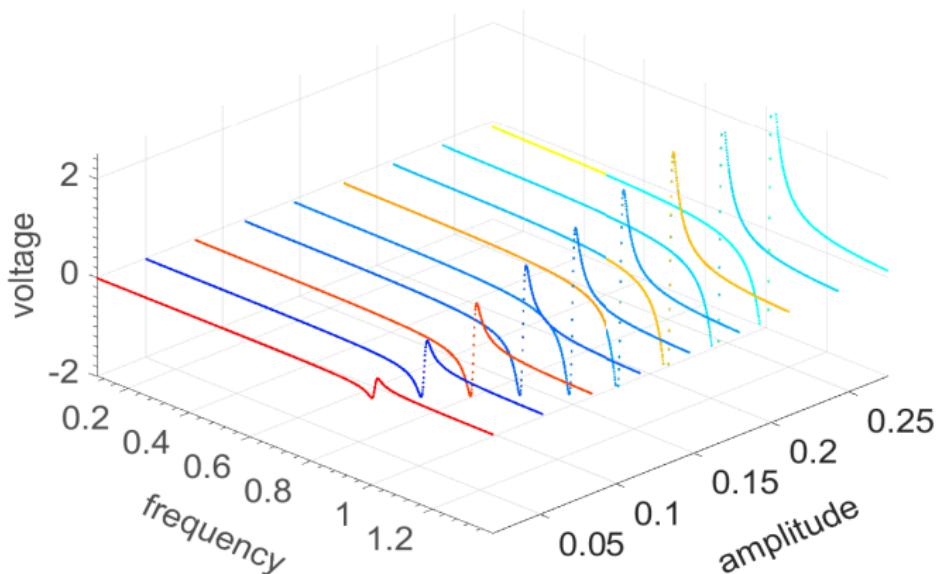
Linear dynamics animation



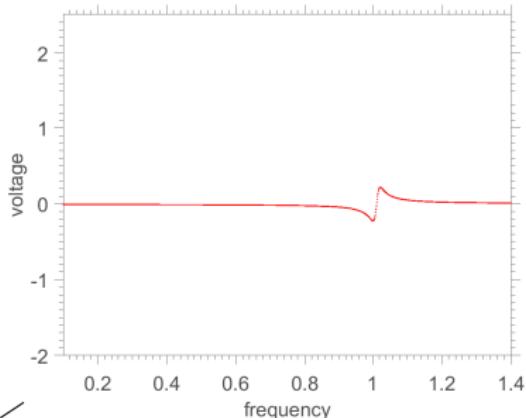
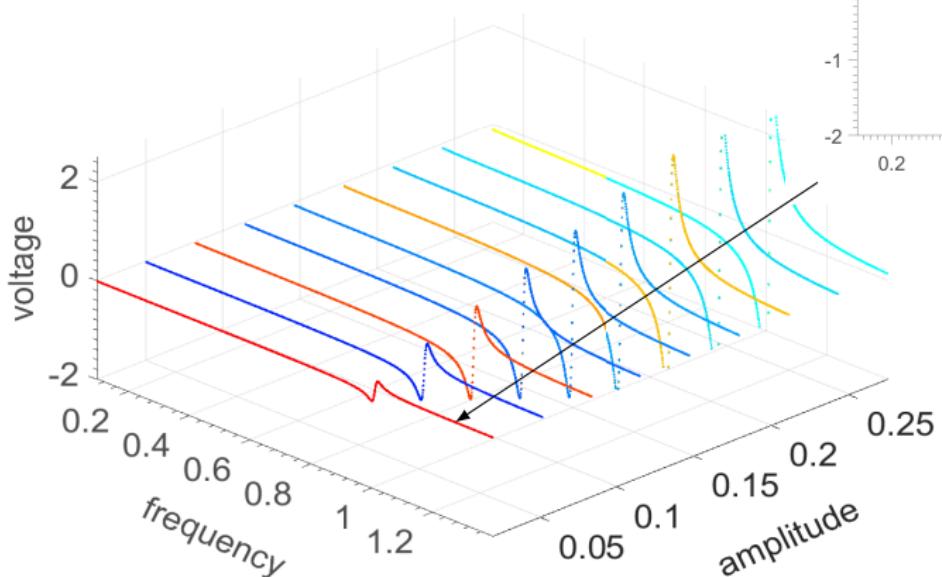
Global overview of excitation frequency effect



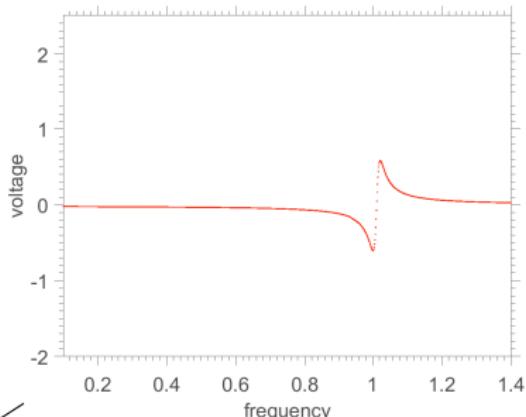
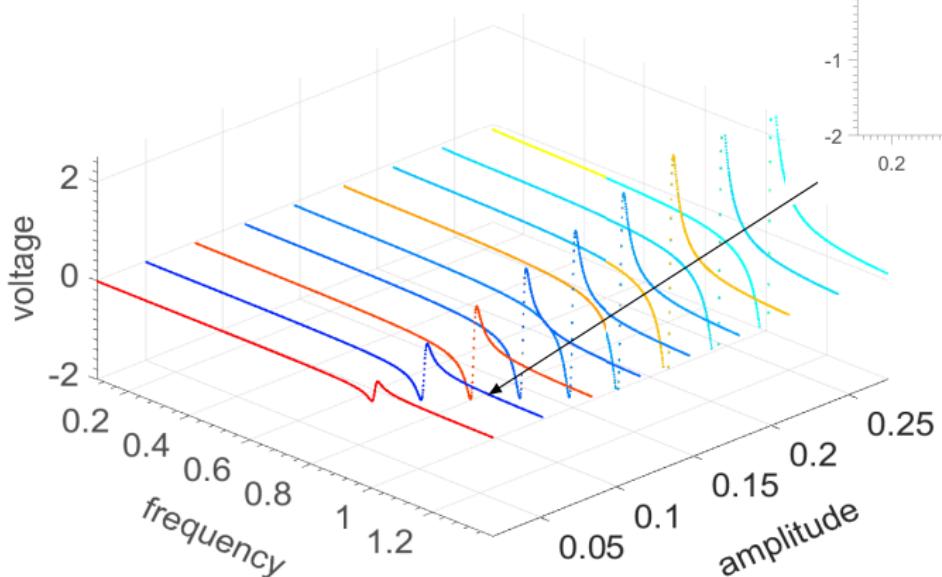
Bifurcation diagrams: voltage × frequency



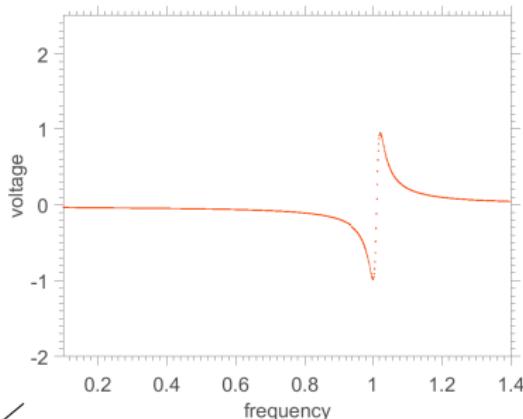
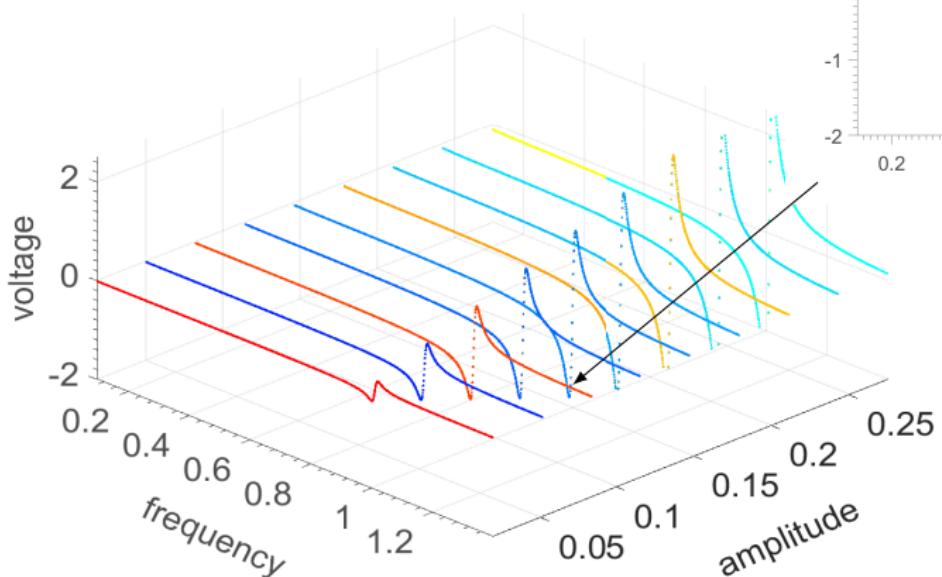
Bifurcation diagrams: voltage × frequency



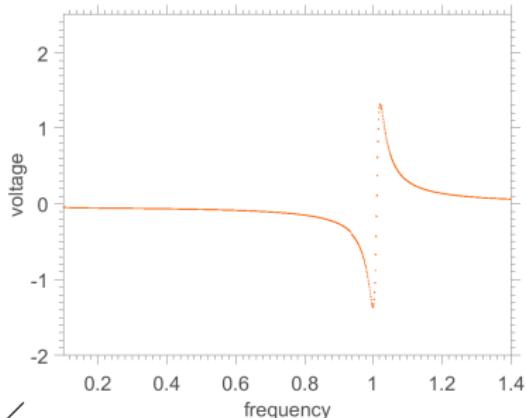
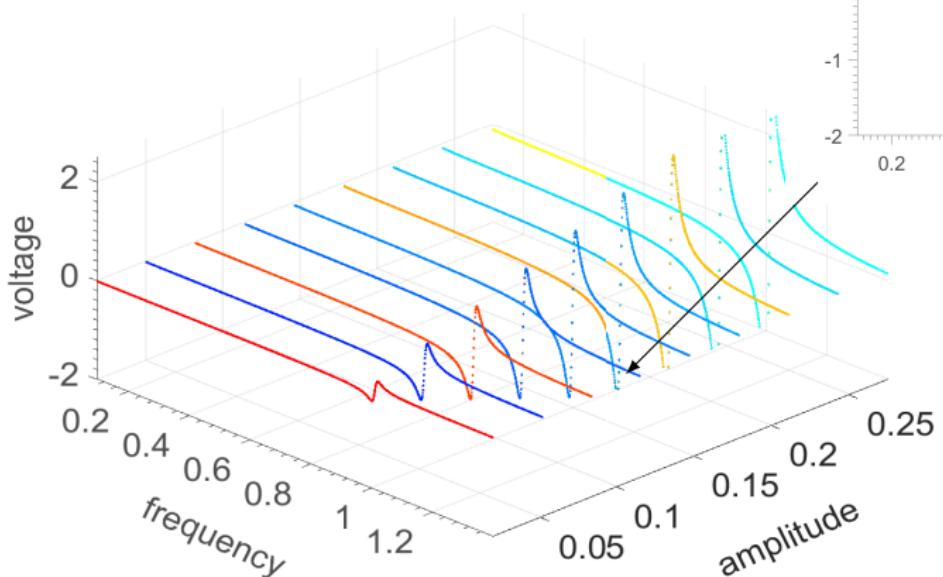
Bifurcation diagrams: voltage \times frequency



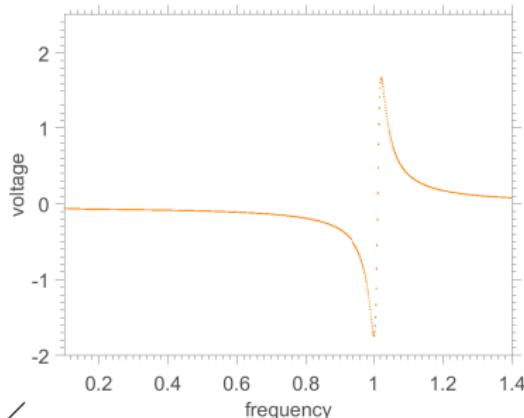
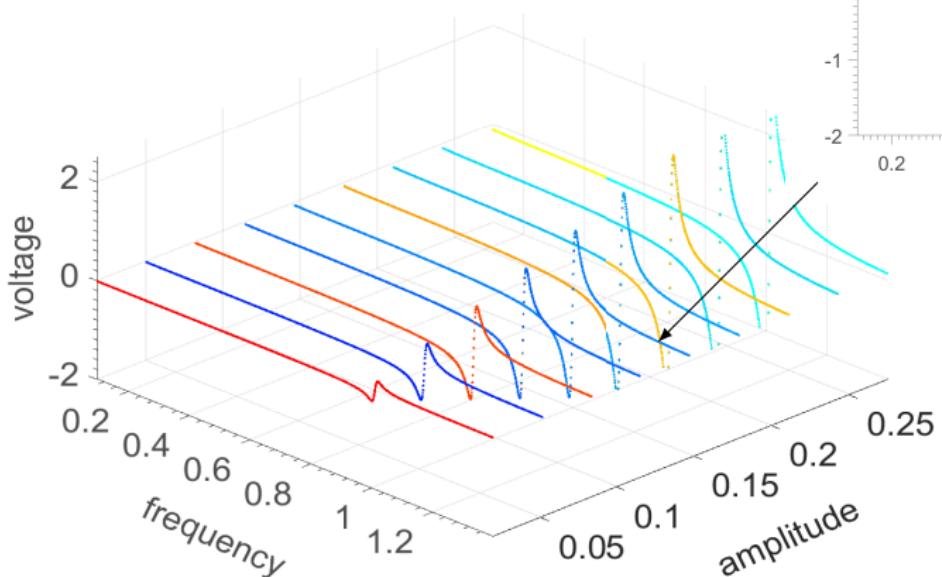
Bifurcation diagrams: voltage \times frequency



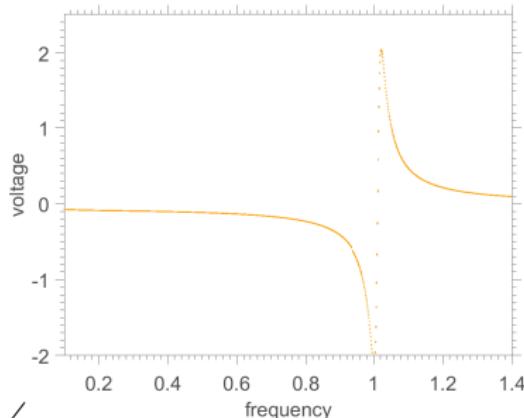
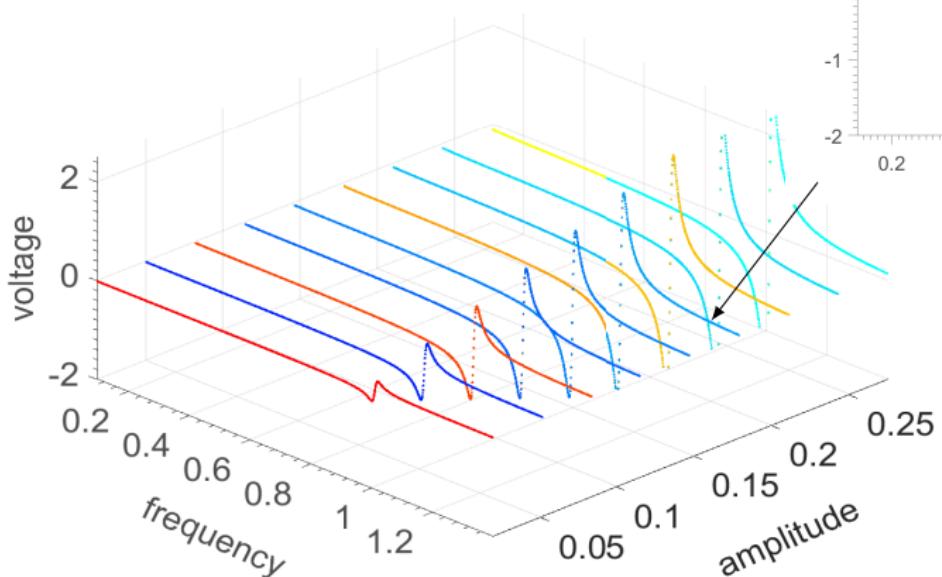
Bifurcation diagrams: voltage × frequency



Bifurcation diagrams: voltage × frequency

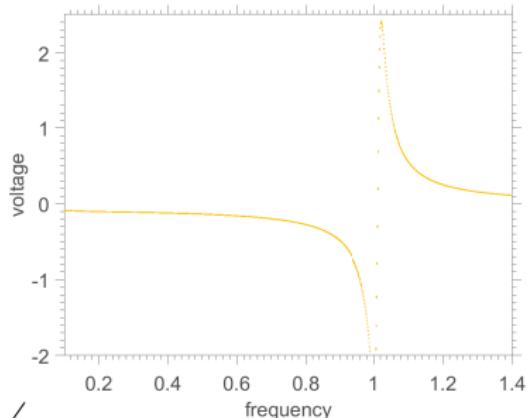
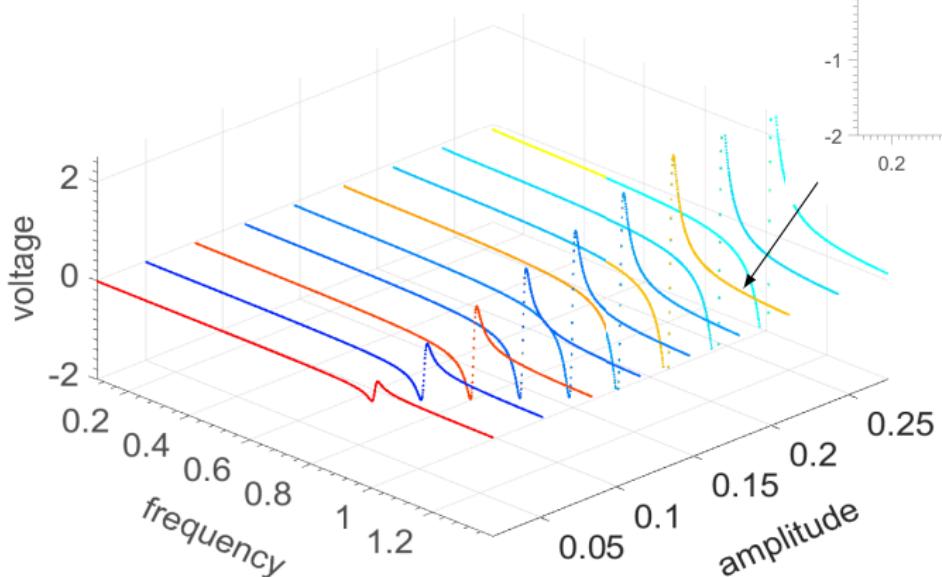


Bifurcation diagrams: voltage × frequency



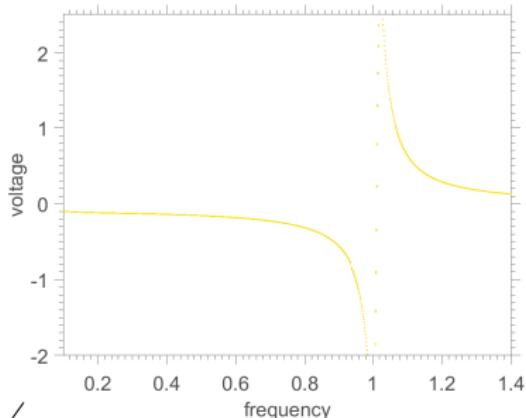
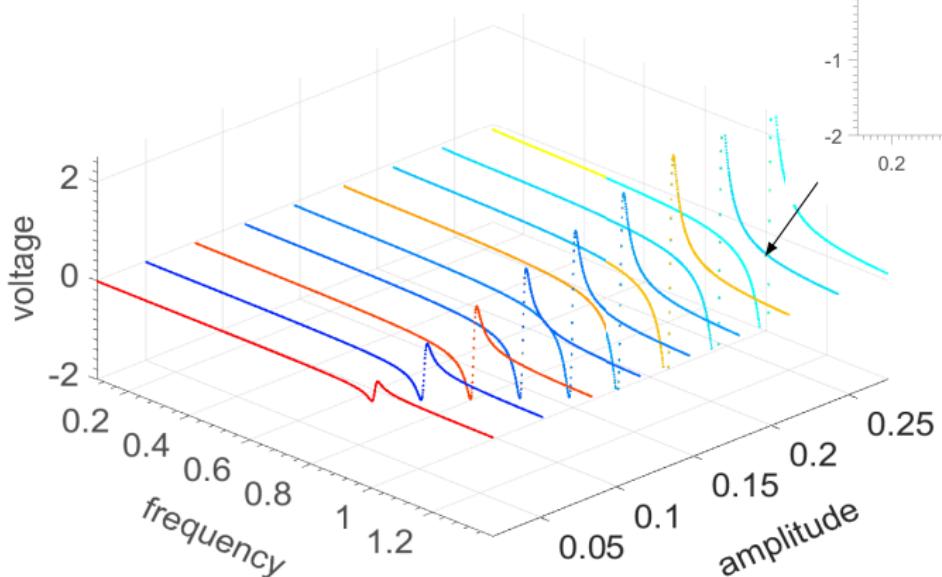
$$f = 0.179$$

Bifurcation diagrams: voltage × frequency

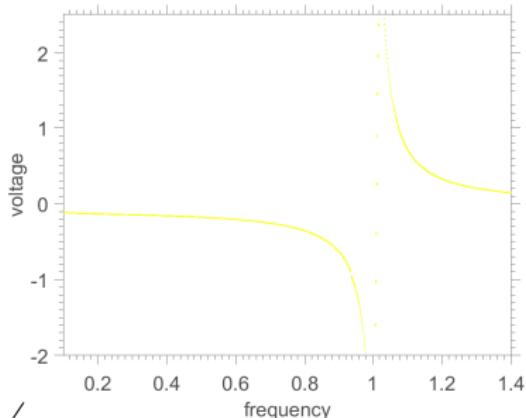
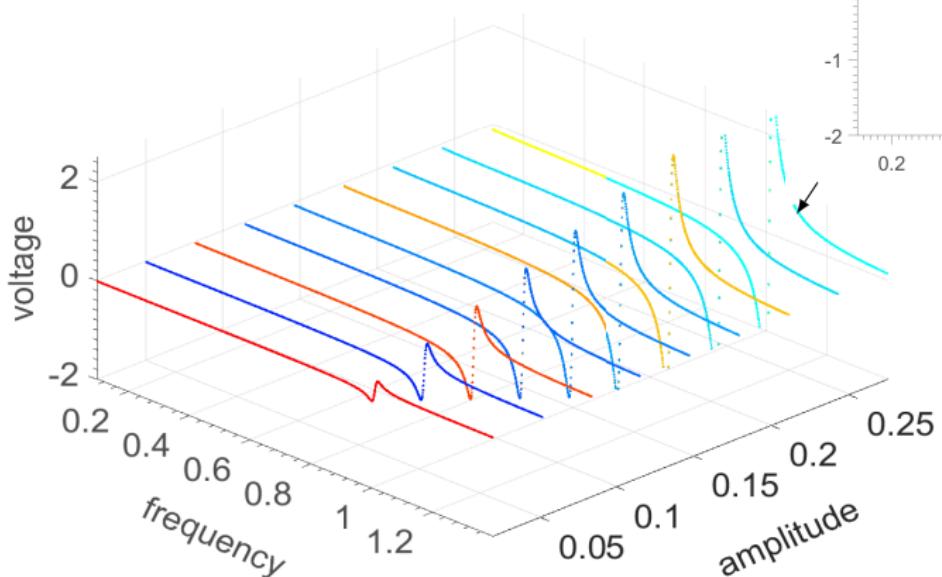


$$f = 0.211$$

Bifurcation diagrams: voltage \times frequency

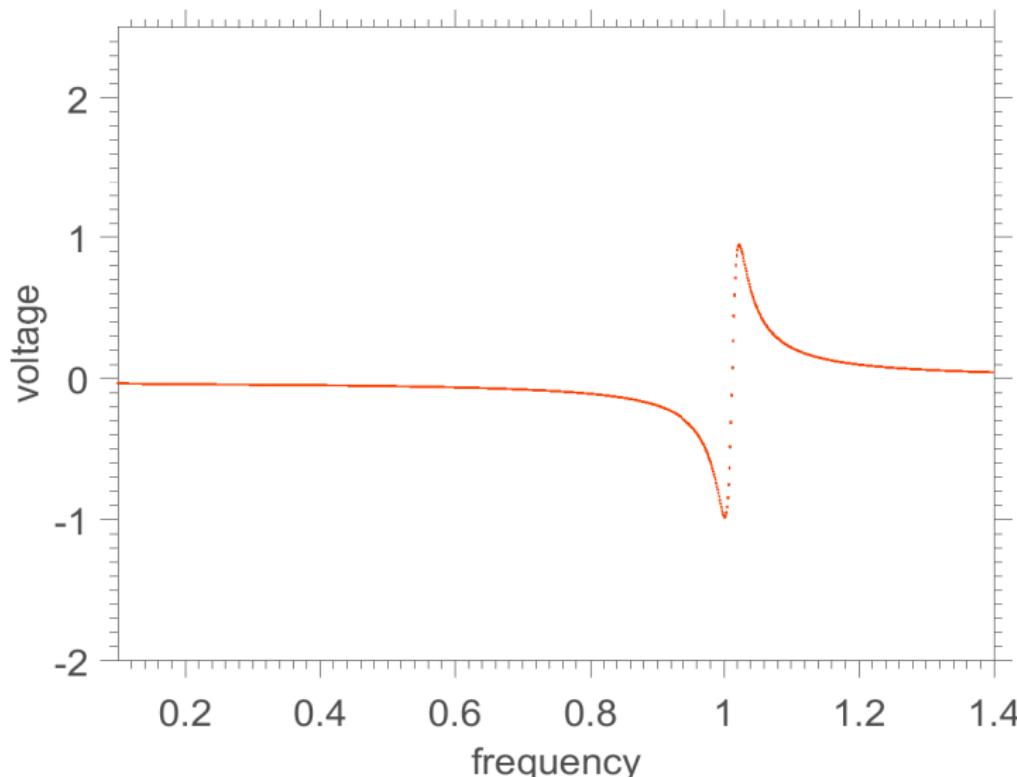


Bifurcation diagrams: voltage \times frequency

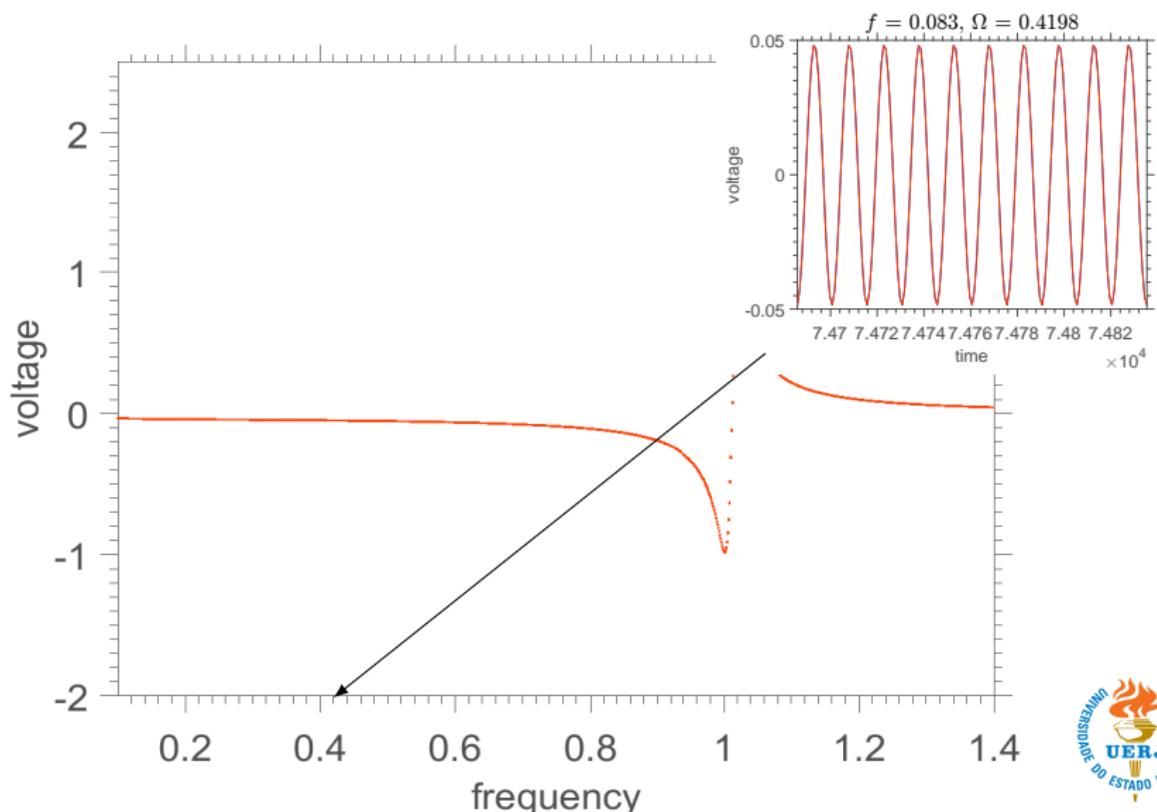


$$f = 0.275$$

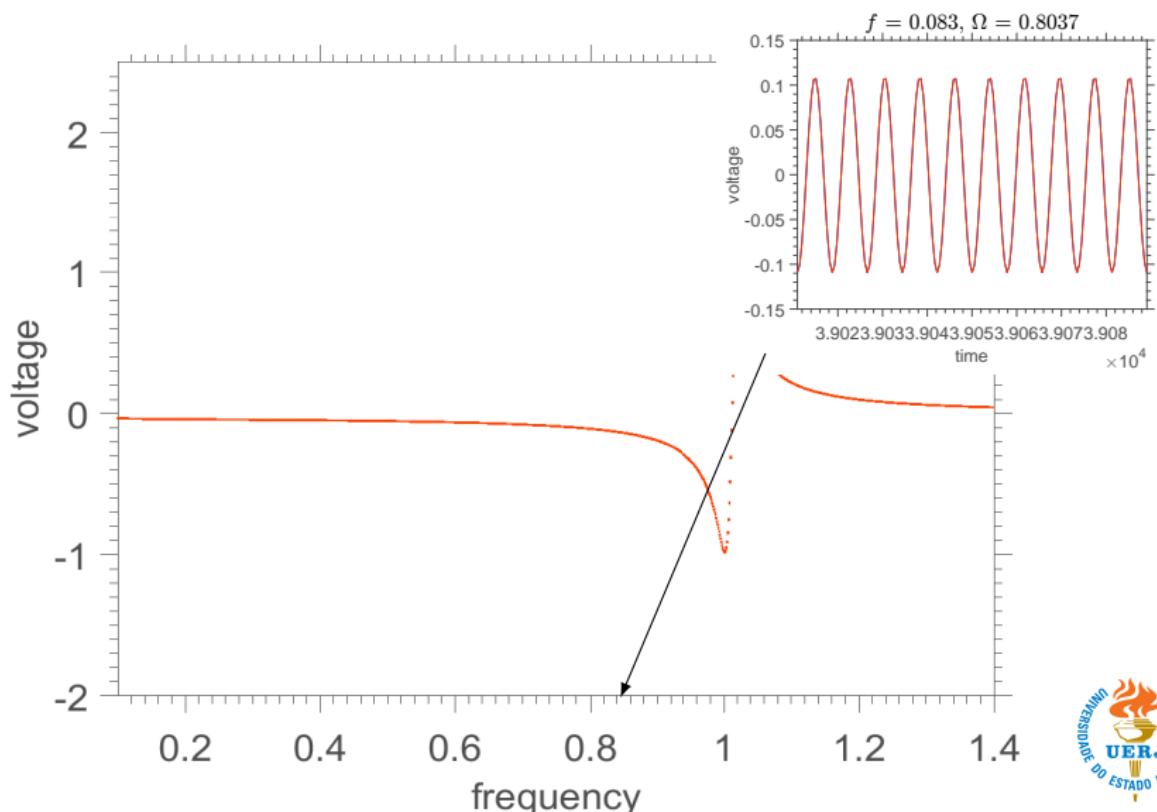
Forward and backward diagrams ($f = 0.083$)



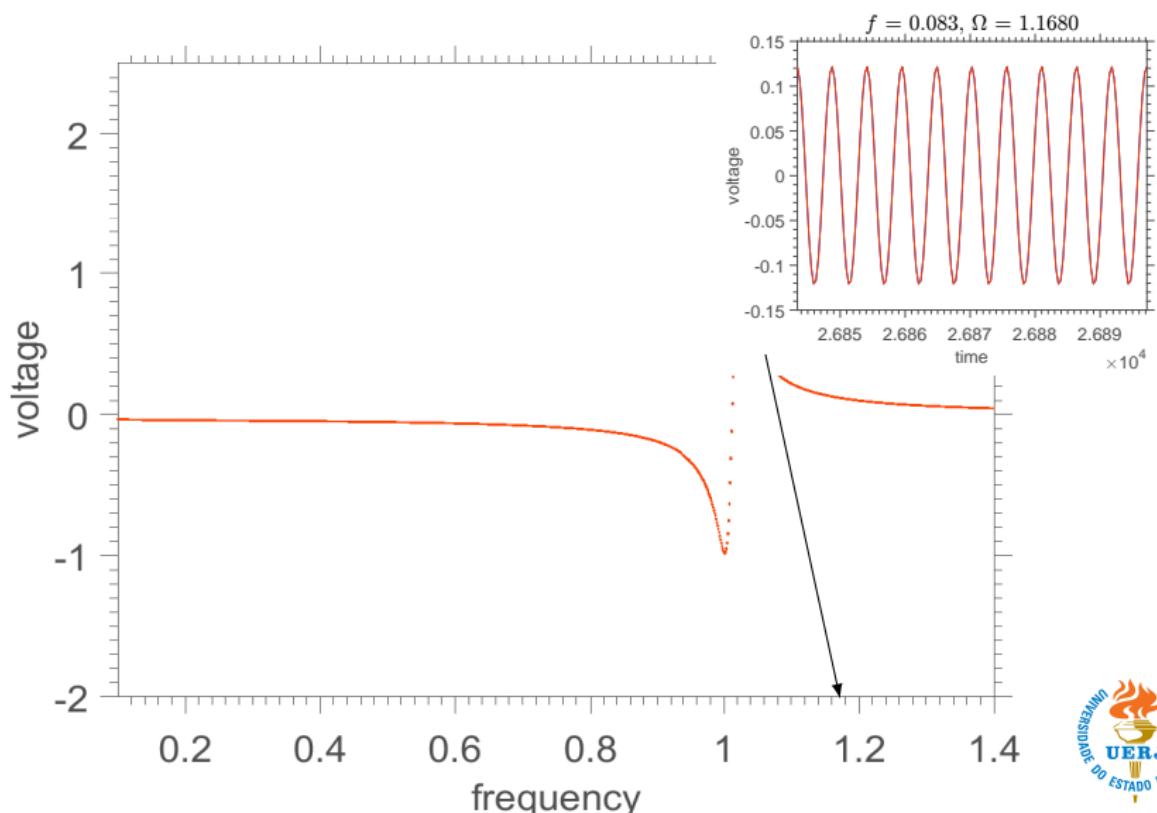
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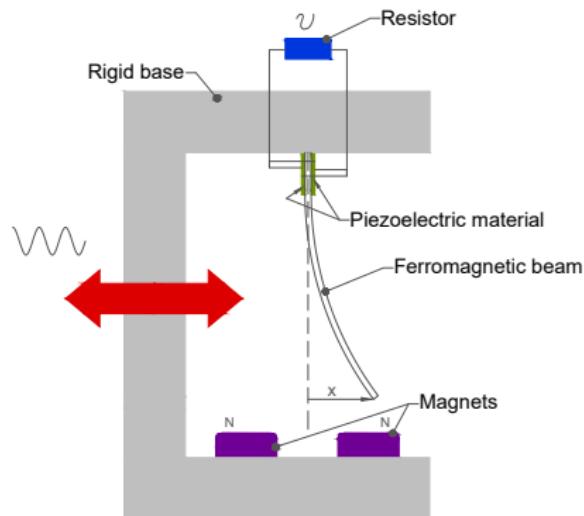
Forward and backward diagrams ($f = 0.083$)



Nonlinear Dynamics



Bistable harvester driven by regular signal



$$\ddot{x} + 2\xi\dot{x} - \frac{1}{2}x(1-x^2) - \chi v = f \cos \Omega t$$

$$\dot{v} + \lambda v + \kappa \dot{x} = 0$$

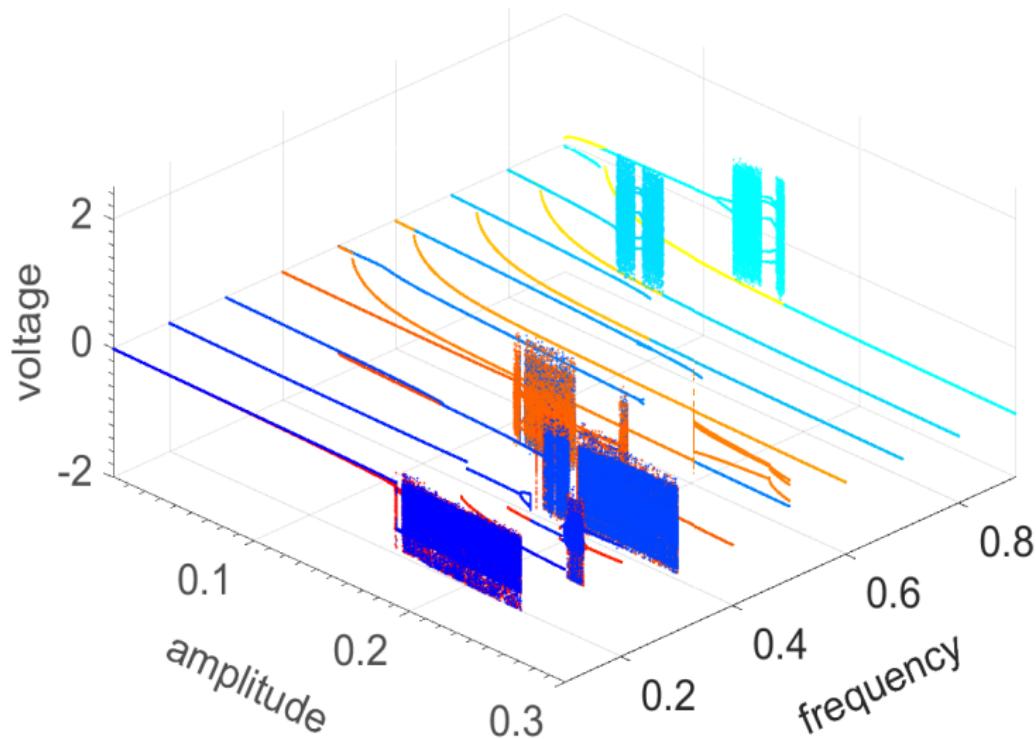
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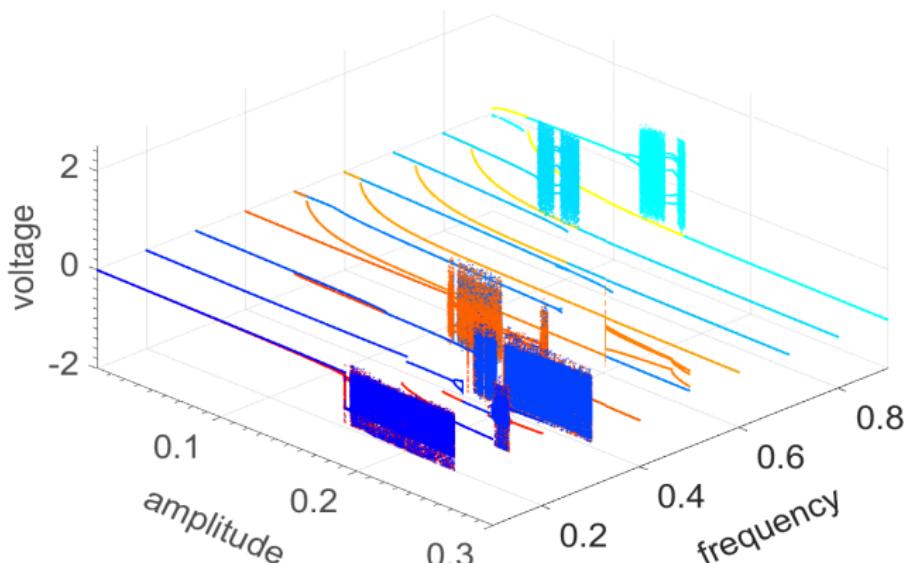
A. Erturk, J. Hoffmann and D. J. Inman, *A piezomagnetoelastic structure for broadband vibration energy harvesting*. **Applied Physics Letters**, 94: 254102, 2009.

Nonlinear dynamics animation

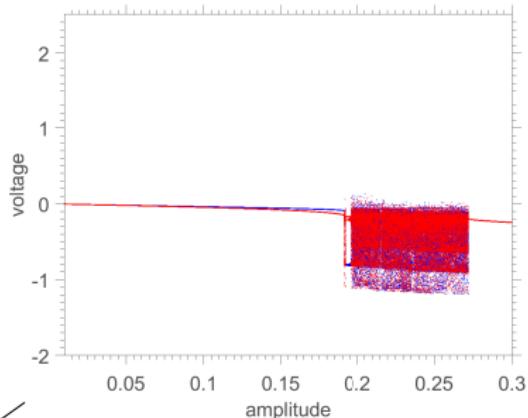
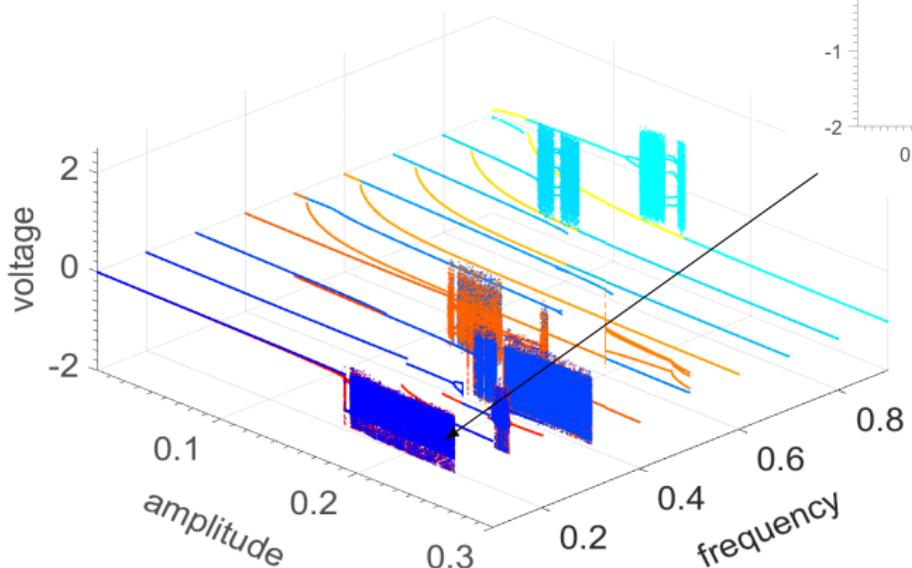
Global overview of force amplitude effect



Bifurcation diagrams: voltage × amplitude



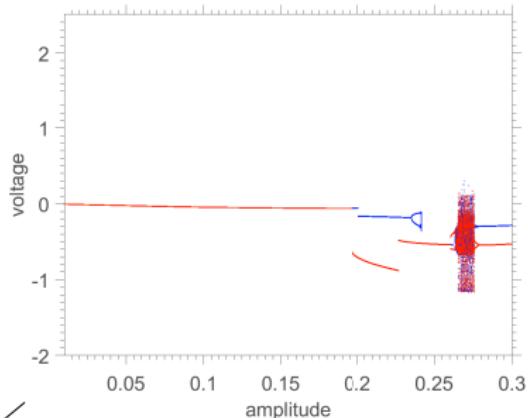
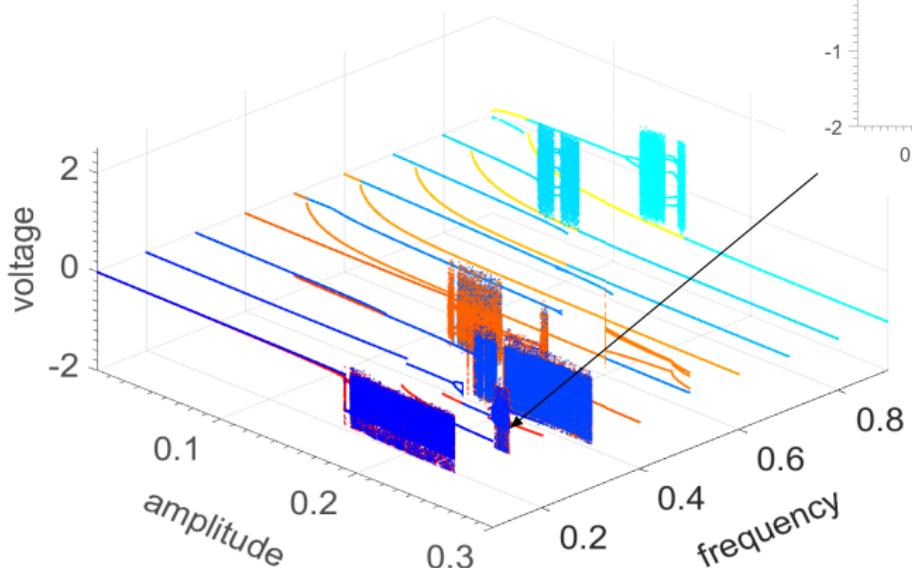
Bifurcation diagrams: voltage × amplitude



$$\Omega = 0.1$$



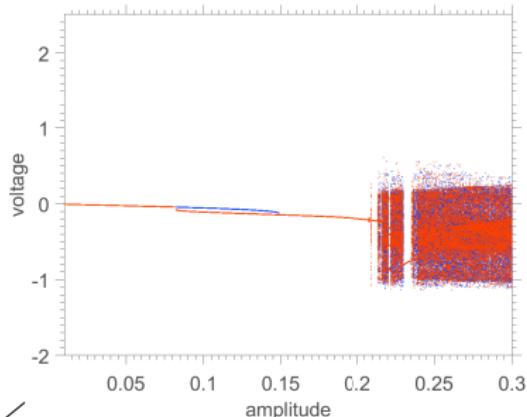
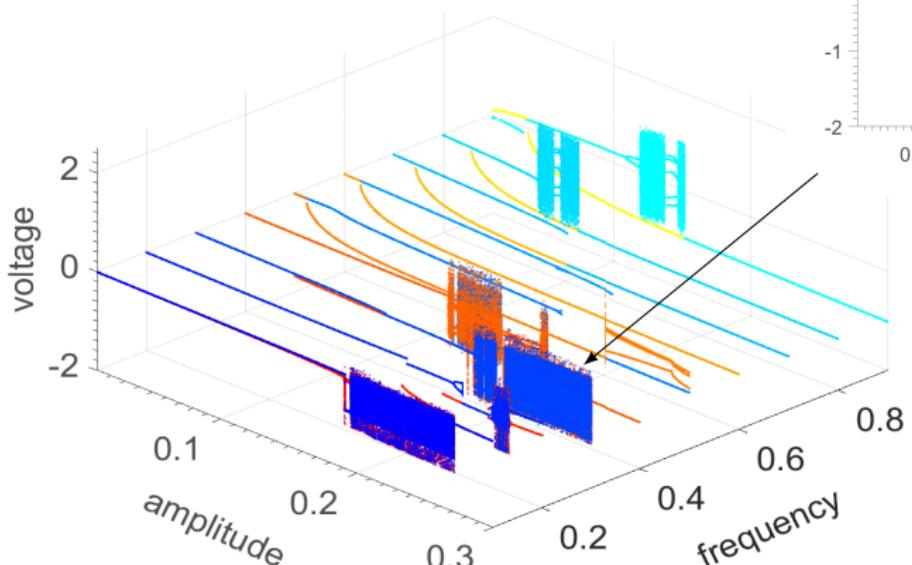
Bifurcation diagrams: voltage × amplitude



$$\Omega = 0.2$$



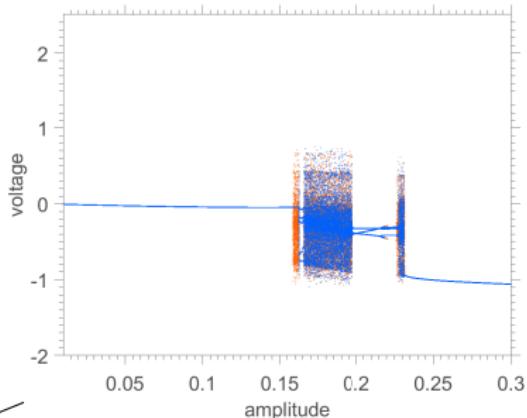
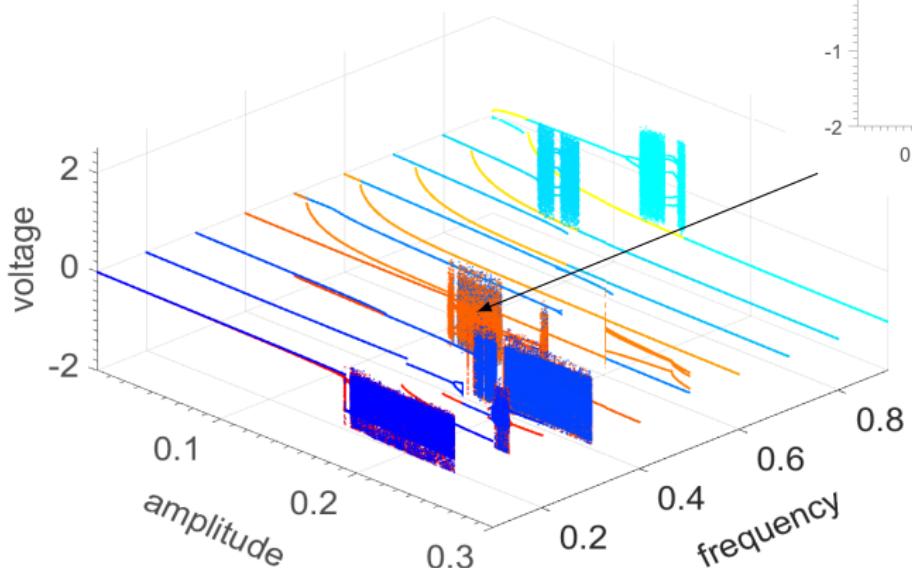
Bifurcation diagrams: voltage × amplitude



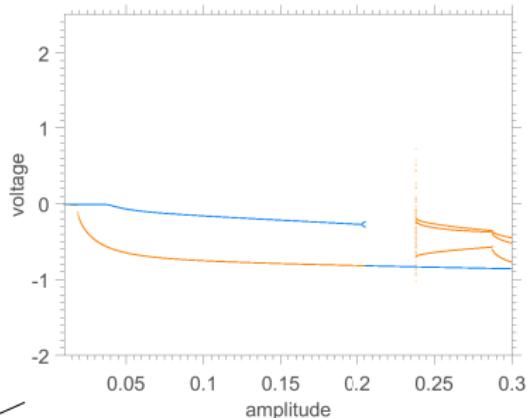
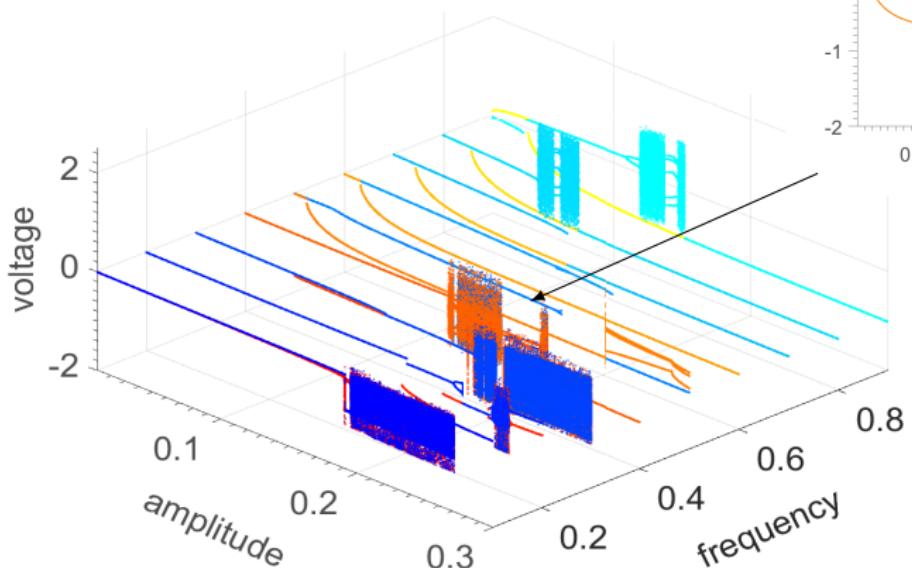
$$\Omega = 0.3$$



Bifurcation diagrams: voltage × amplitude



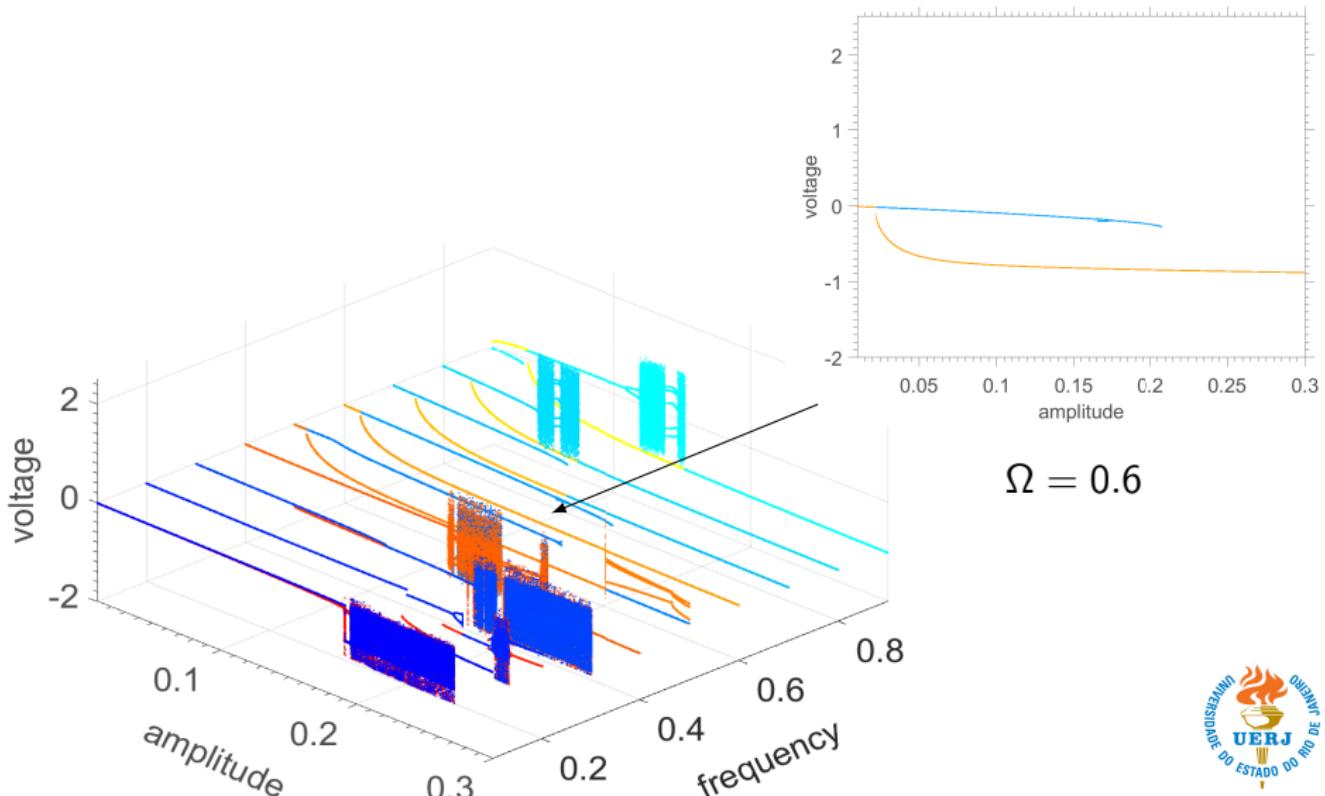
Bifurcation diagrams: voltage × amplitude



$$\Omega = 0.5$$



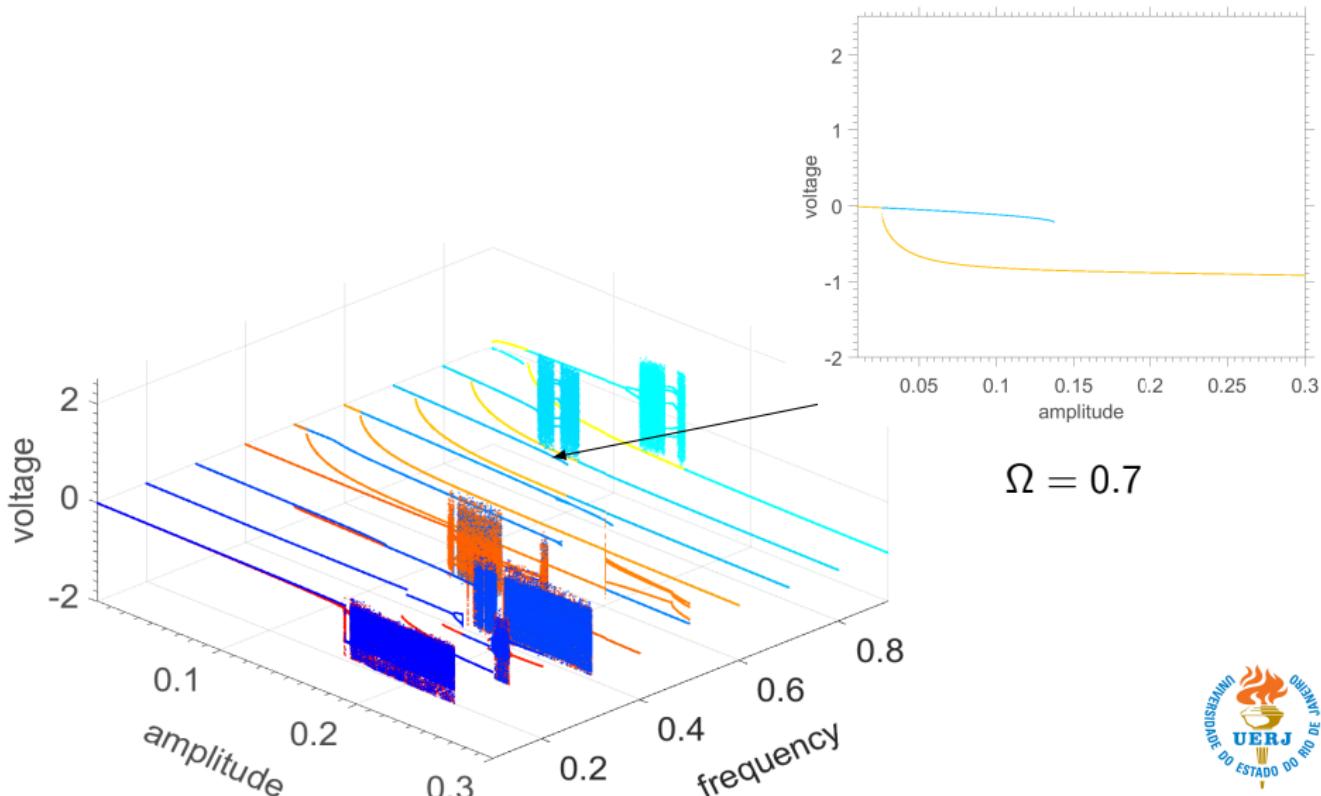
Bifurcation diagrams: voltage × amplitude



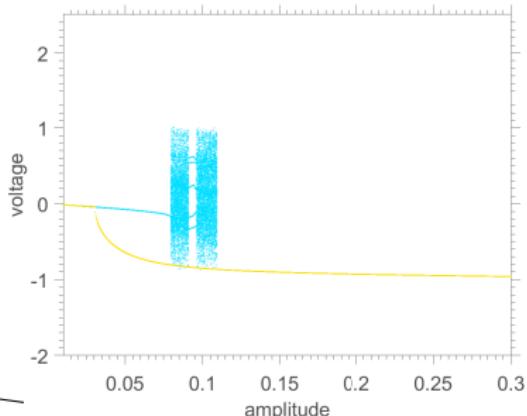
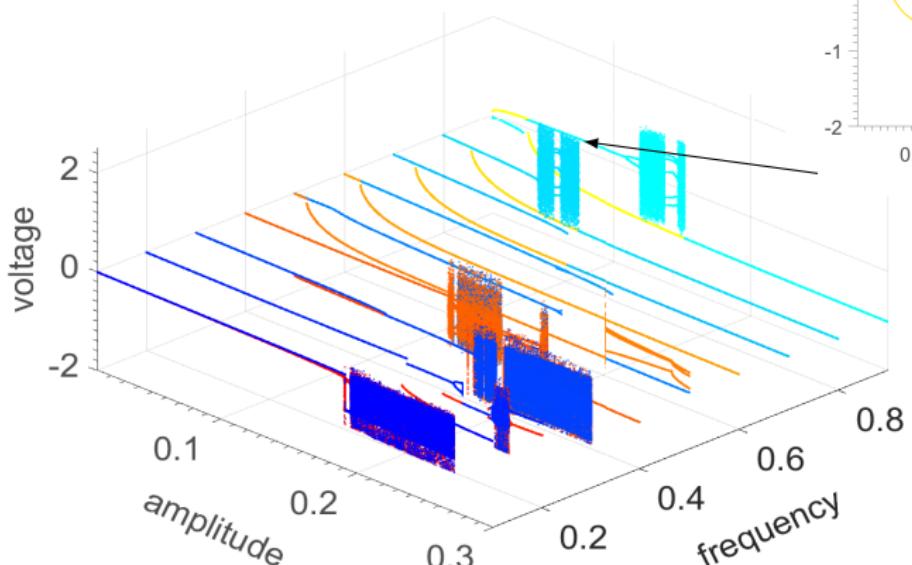
$$\Omega = 0.6$$



Bifurcation diagrams: voltage × amplitude



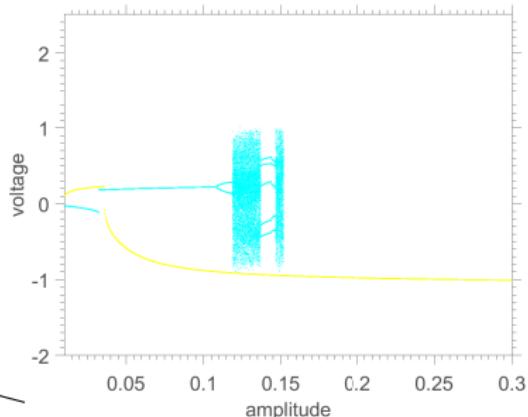
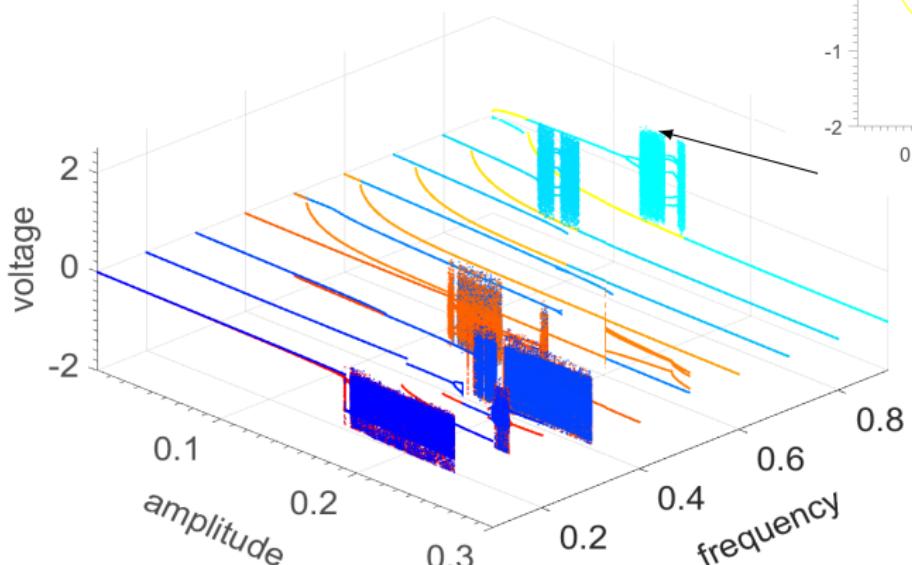
Bifurcation diagrams: voltage × amplitude



$$\Omega = 0.8$$



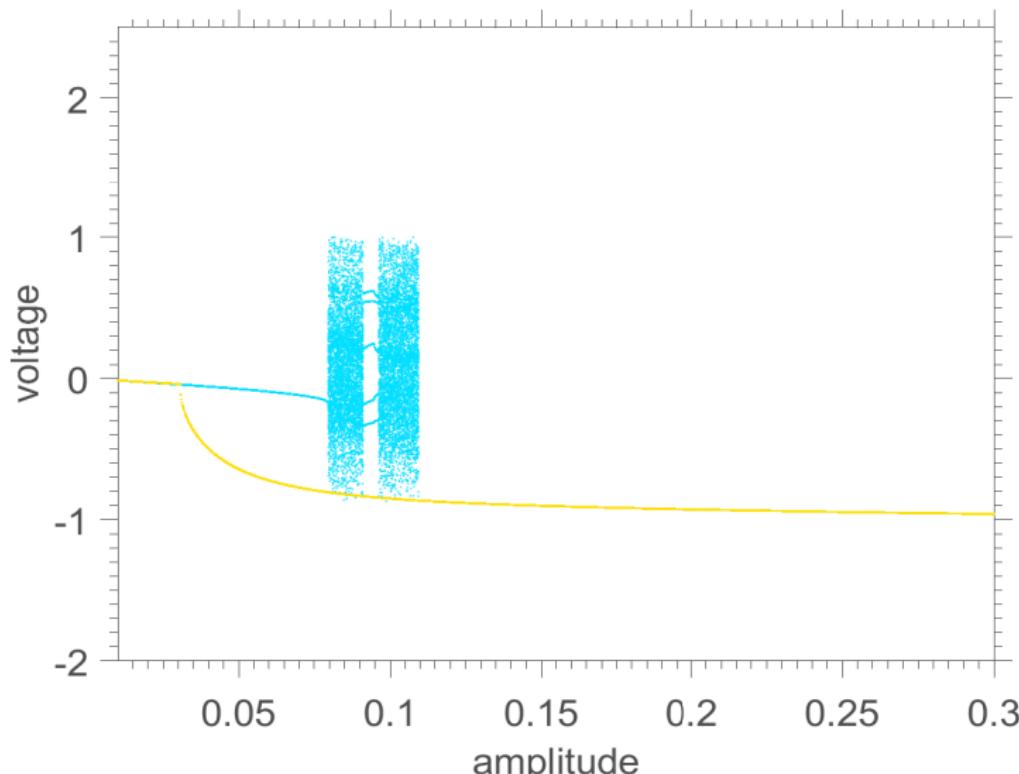
Bifurcation diagrams: voltage × amplitude



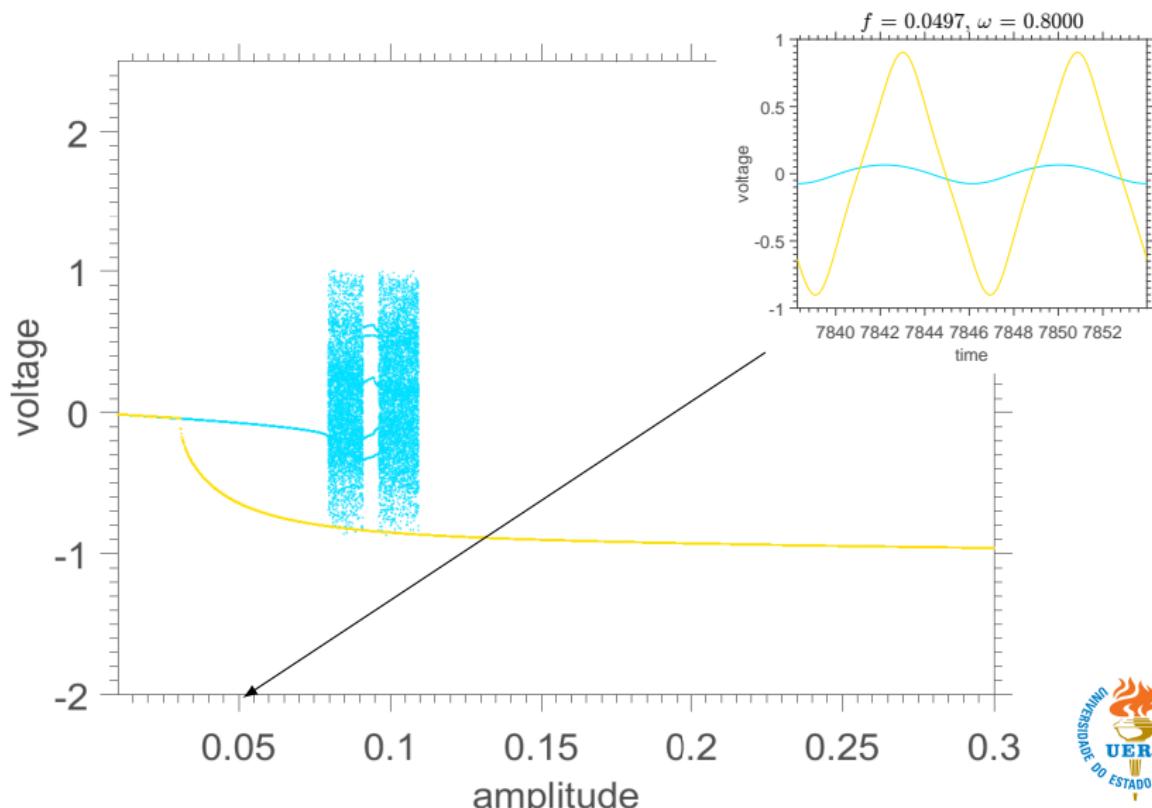
$$\Omega = 0.9$$



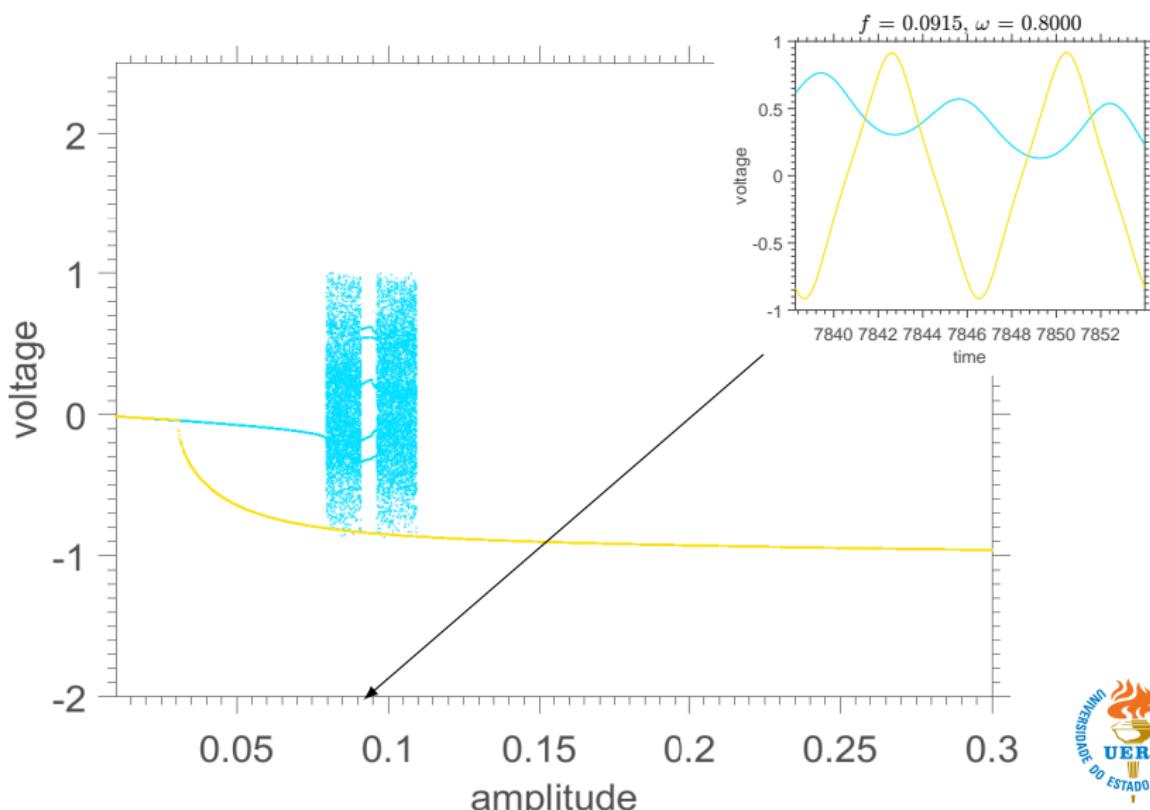
Forward and backward bifurcation diagrams ($\Omega = 0.8$)



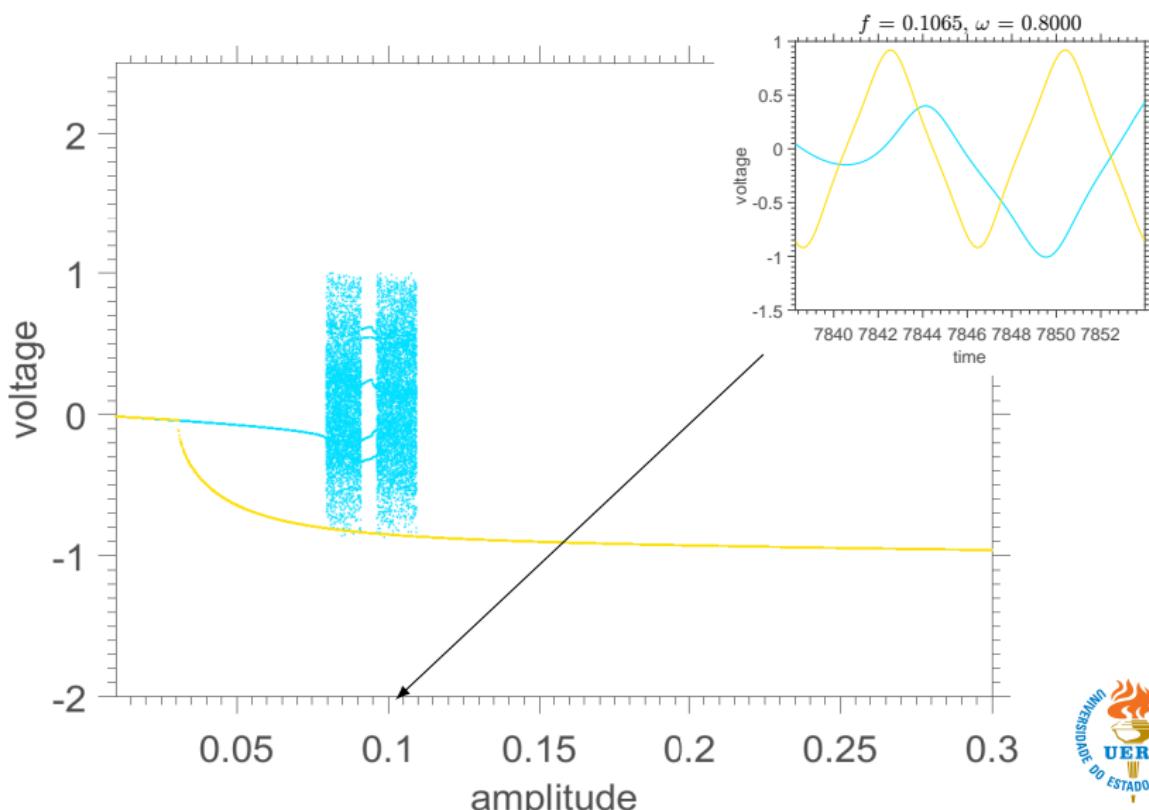
Forward and backward bifurcation diagrams ($\Omega = 0.8$)



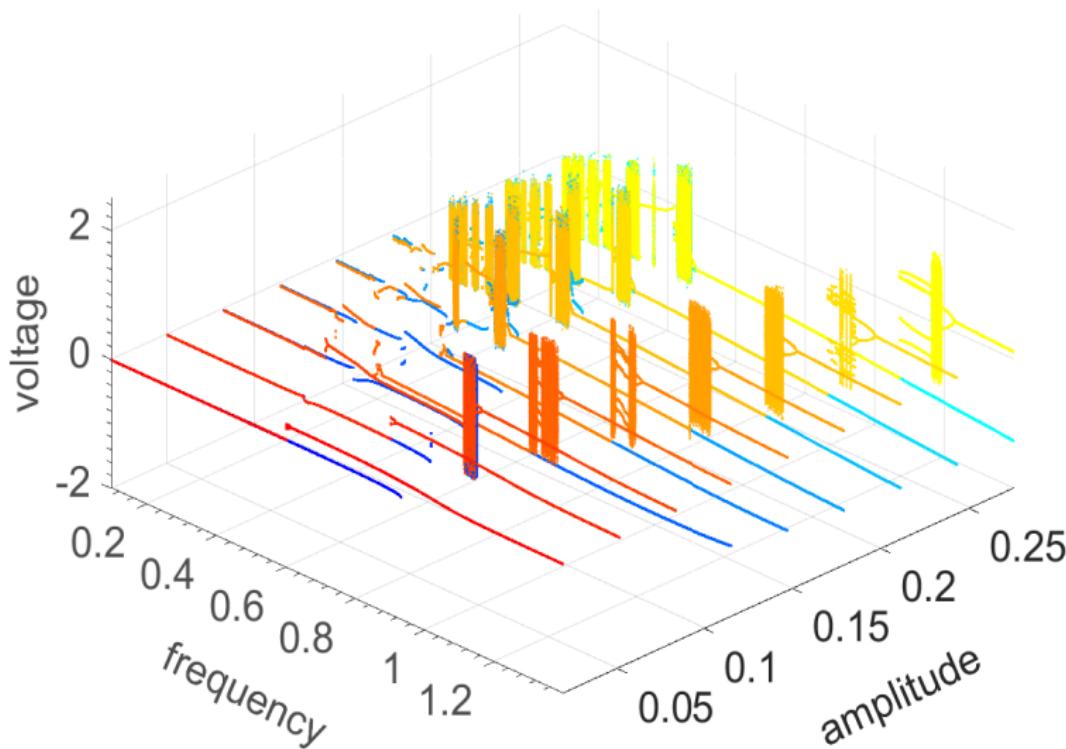
Forward and backward bifurcation diagrams ($\Omega = 0.8$)



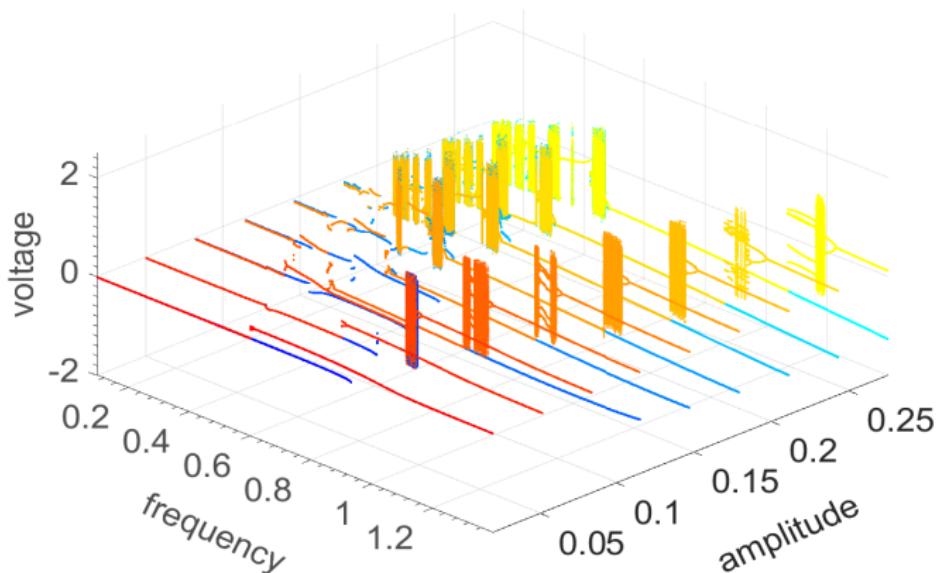
Forward and backward bifurcation diagrams ($\Omega = 0.8$)



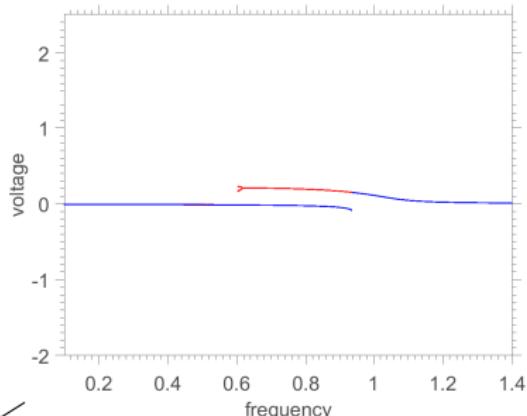
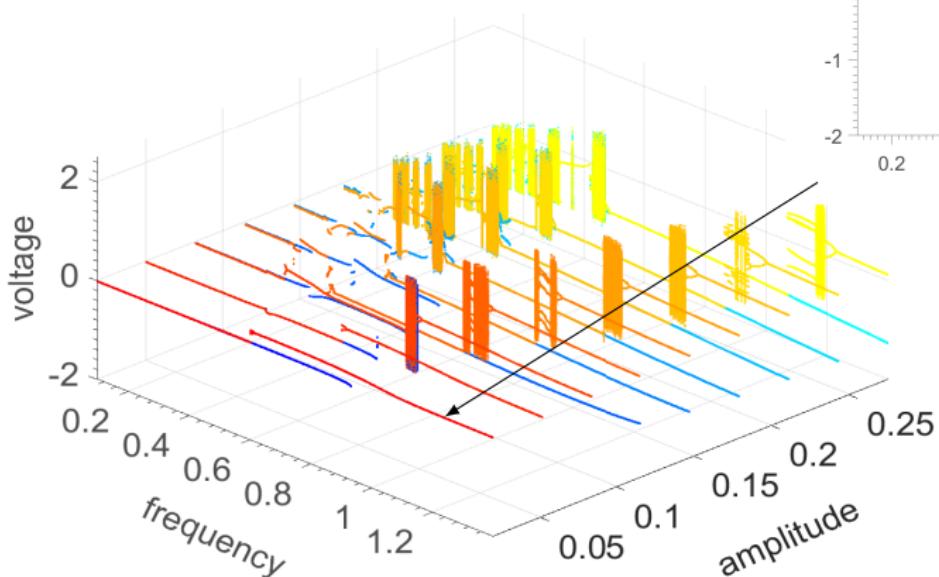
Global overview of force frequency effect



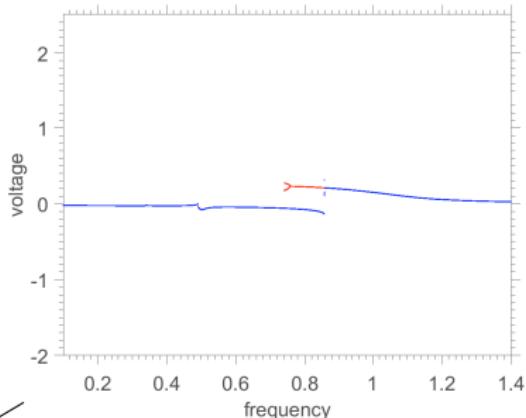
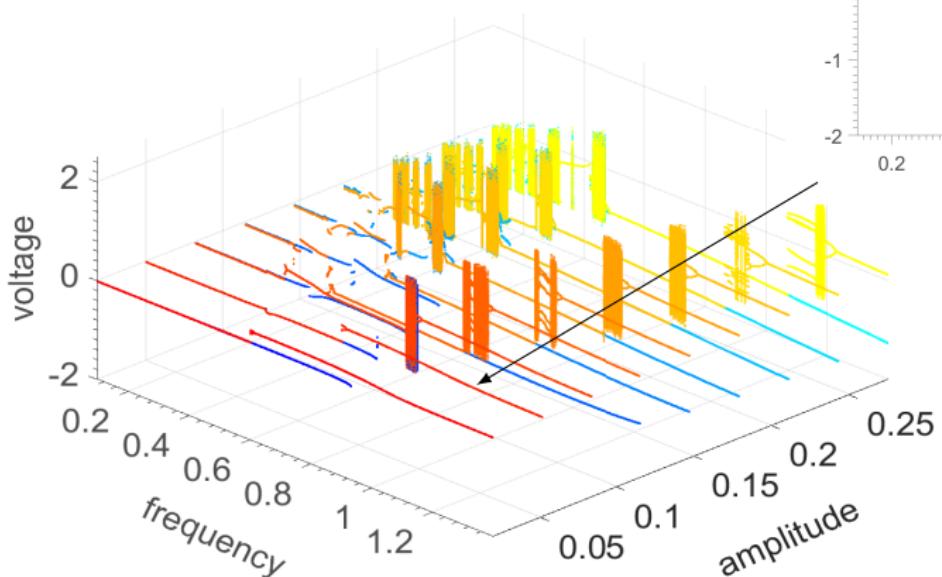
Bifurcation diagrams: voltage × frequency



Bifurcation diagrams: voltage × frequency

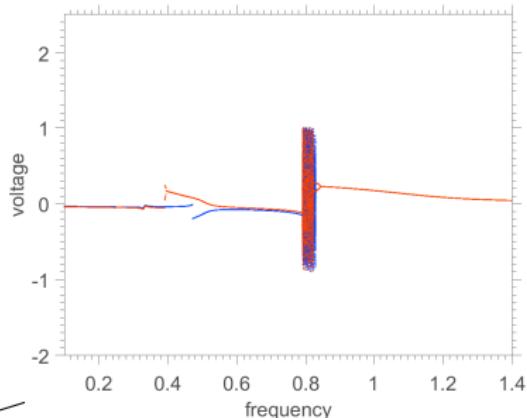
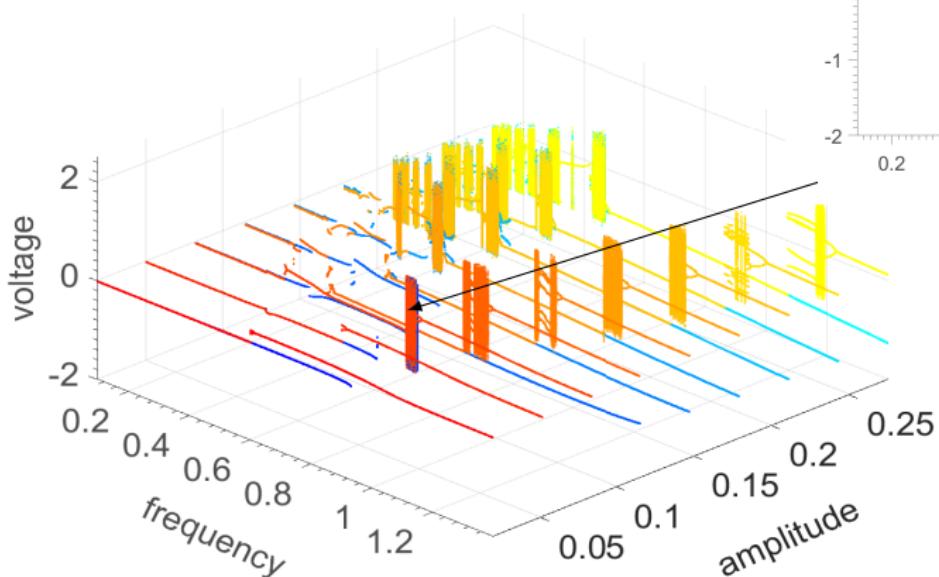


Bifurcation diagrams: voltage × frequency

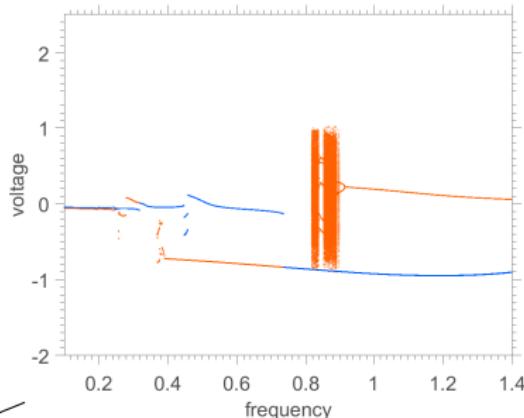
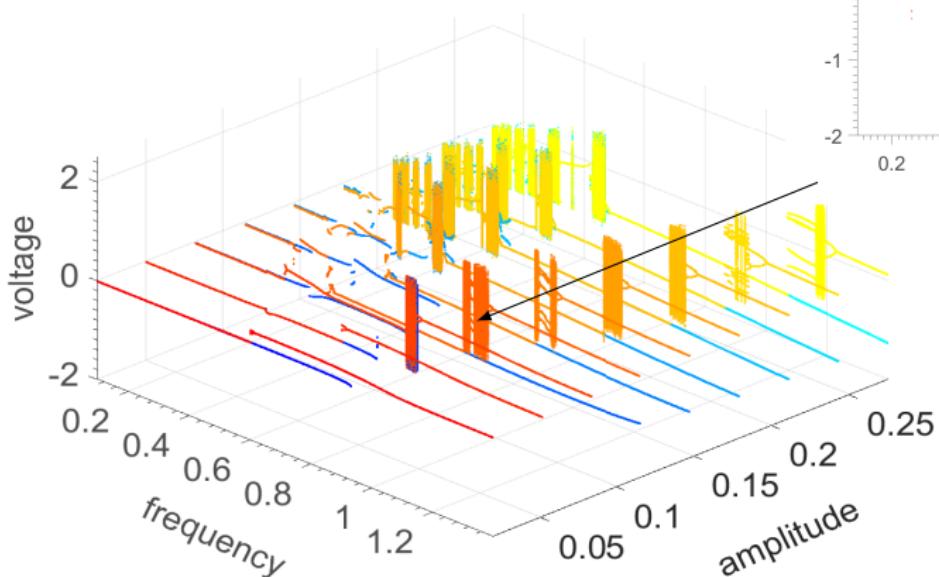


$$f = 0.051$$

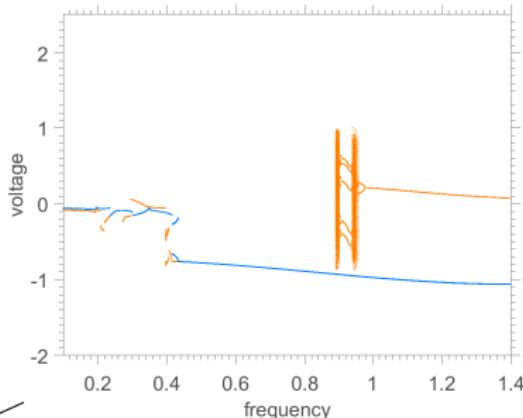
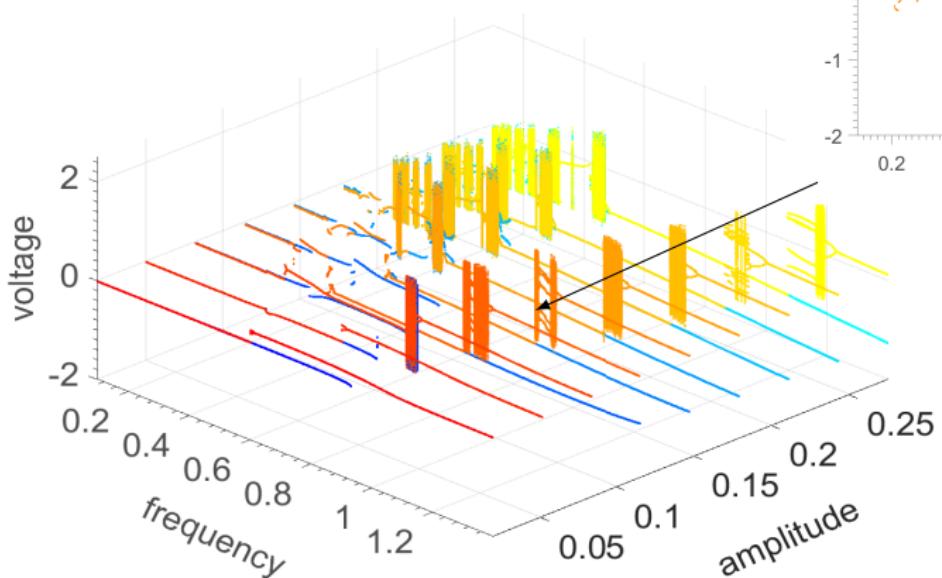
Bifurcation diagrams: voltage × frequency



Bifurcation diagrams: voltage × frequency



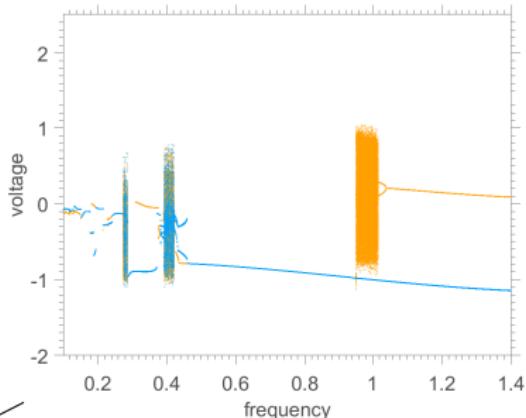
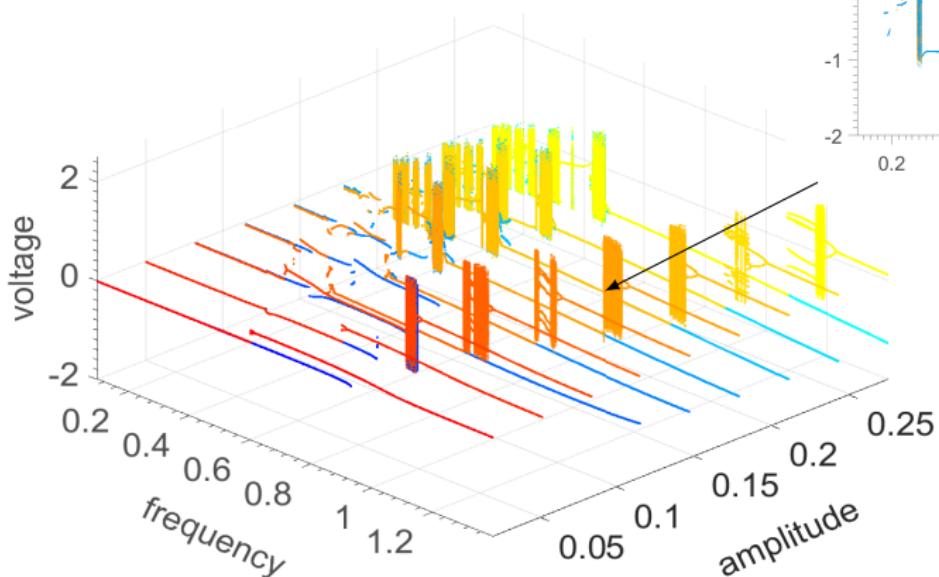
Bifurcation diagrams: voltage × frequency



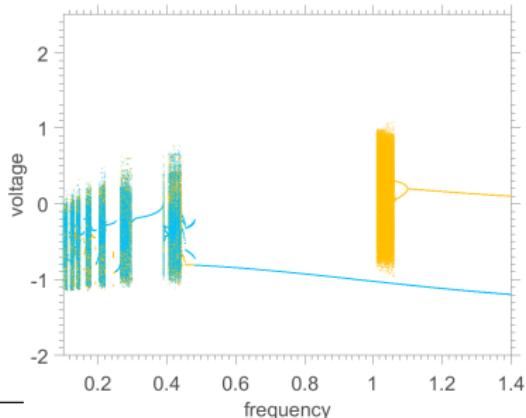
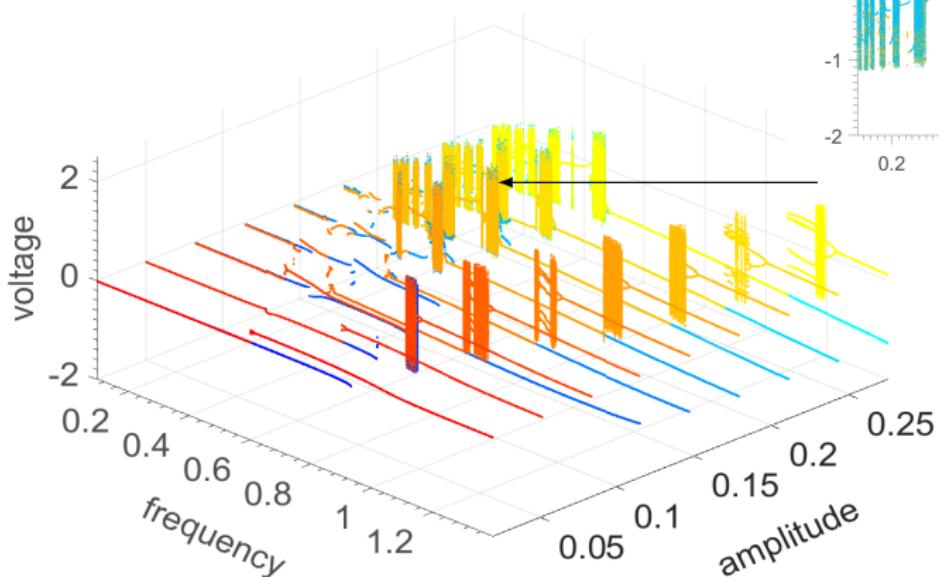
$$f = 0.147$$



Bifurcation diagrams: voltage × frequency

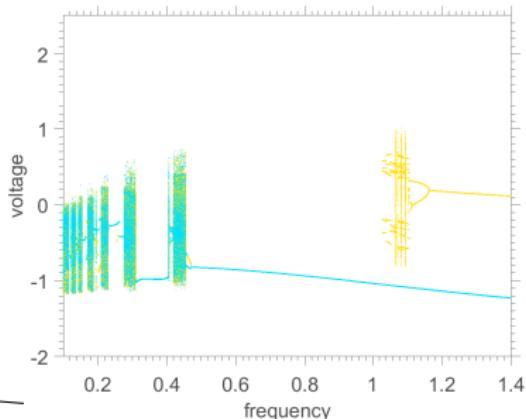
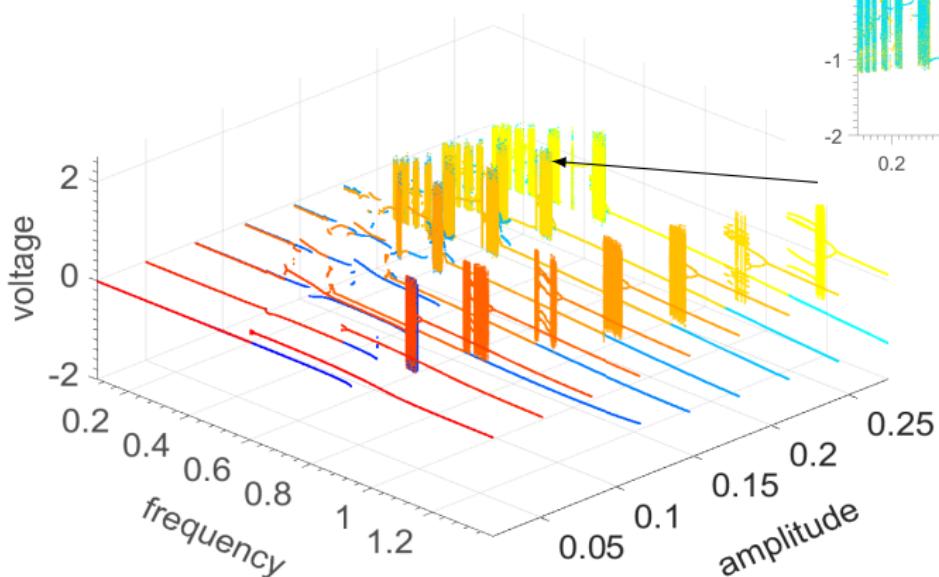


Bifurcation diagrams: voltage × frequency



$$f = 0.211$$

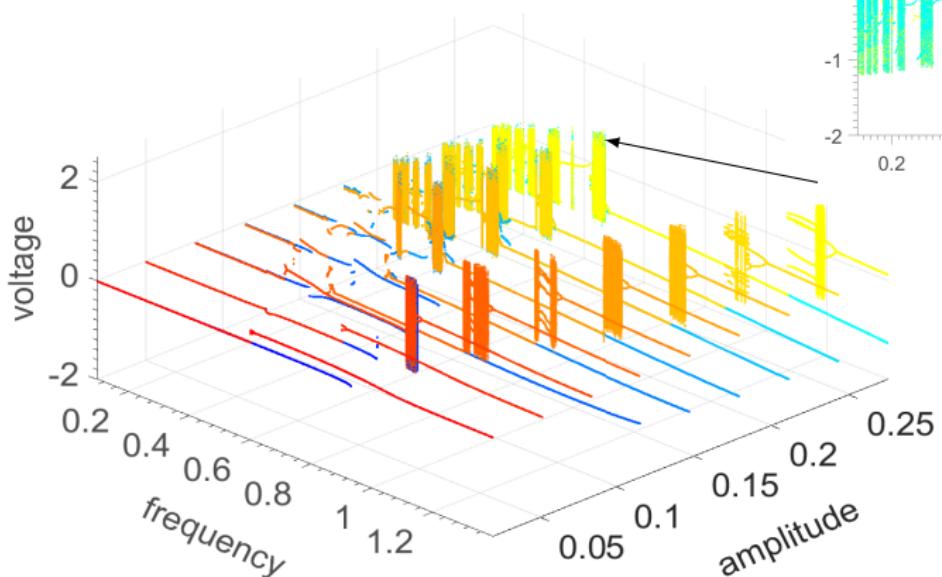
Bifurcation diagrams: voltage \times frequency



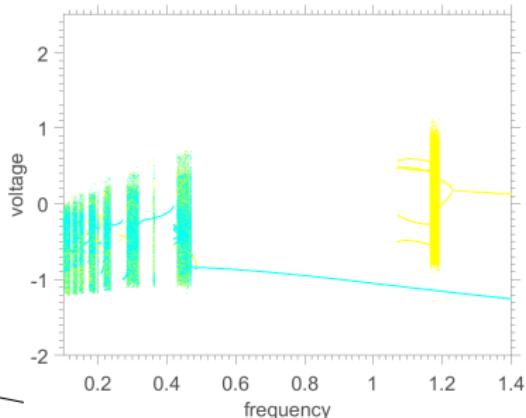
$$f = 0.243$$



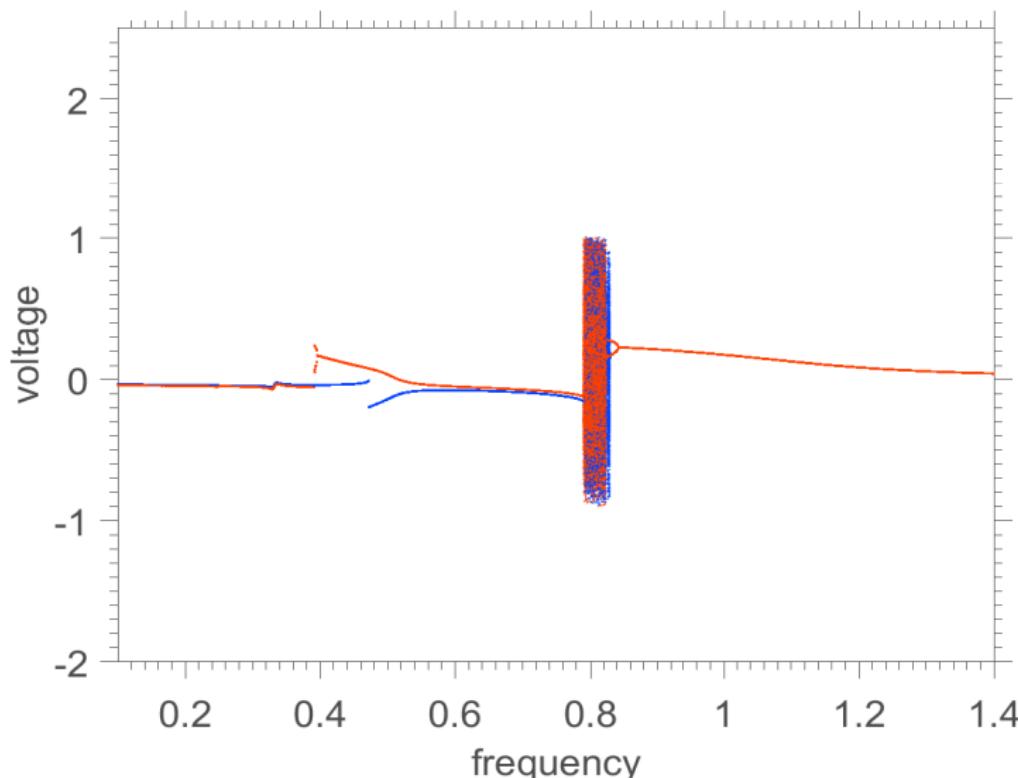
Bifurcation diagrams: voltage × frequency



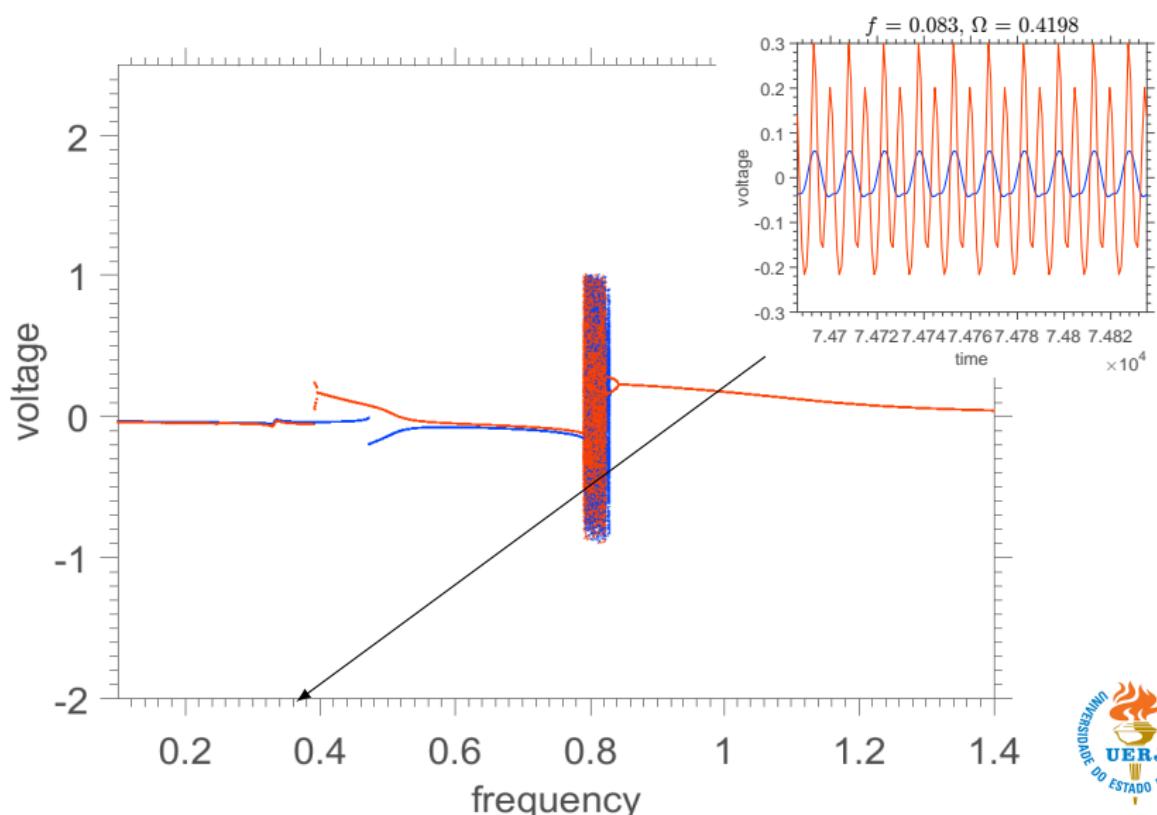
$$f = 0.275$$



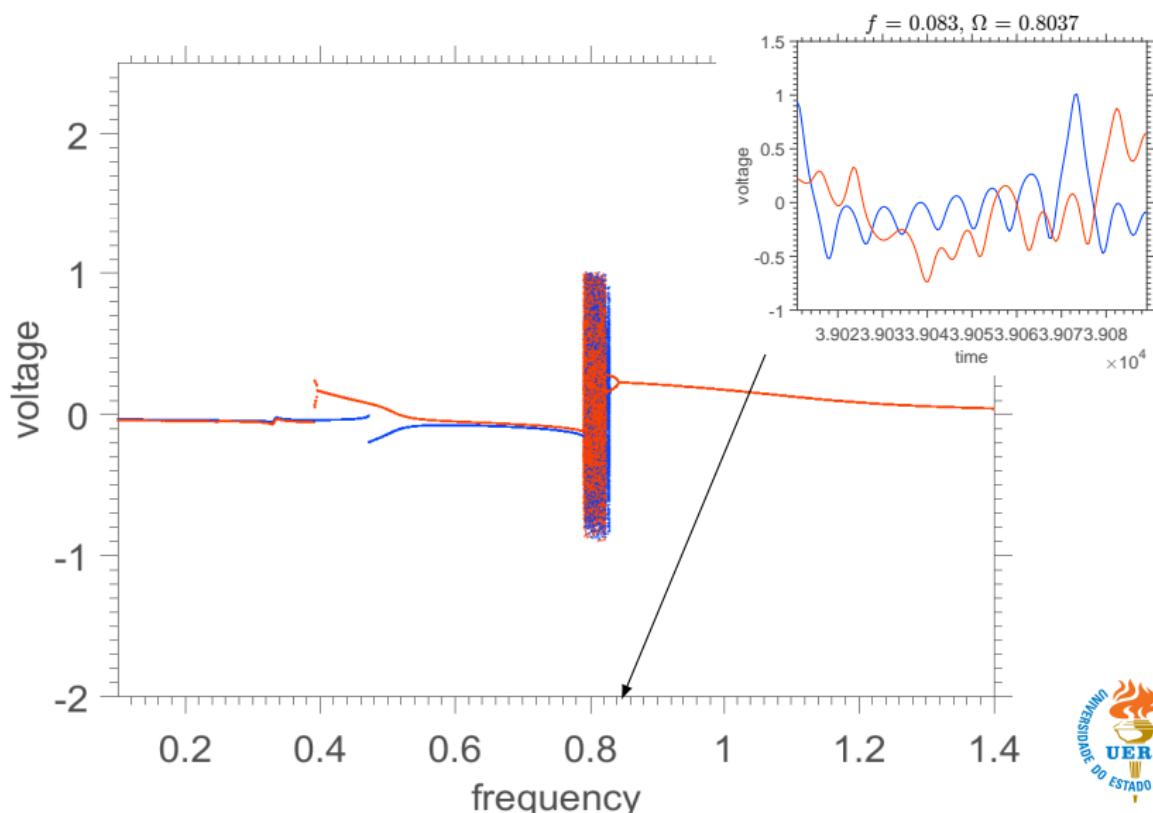
Forward and backward diagrams ($f = 0.083$)



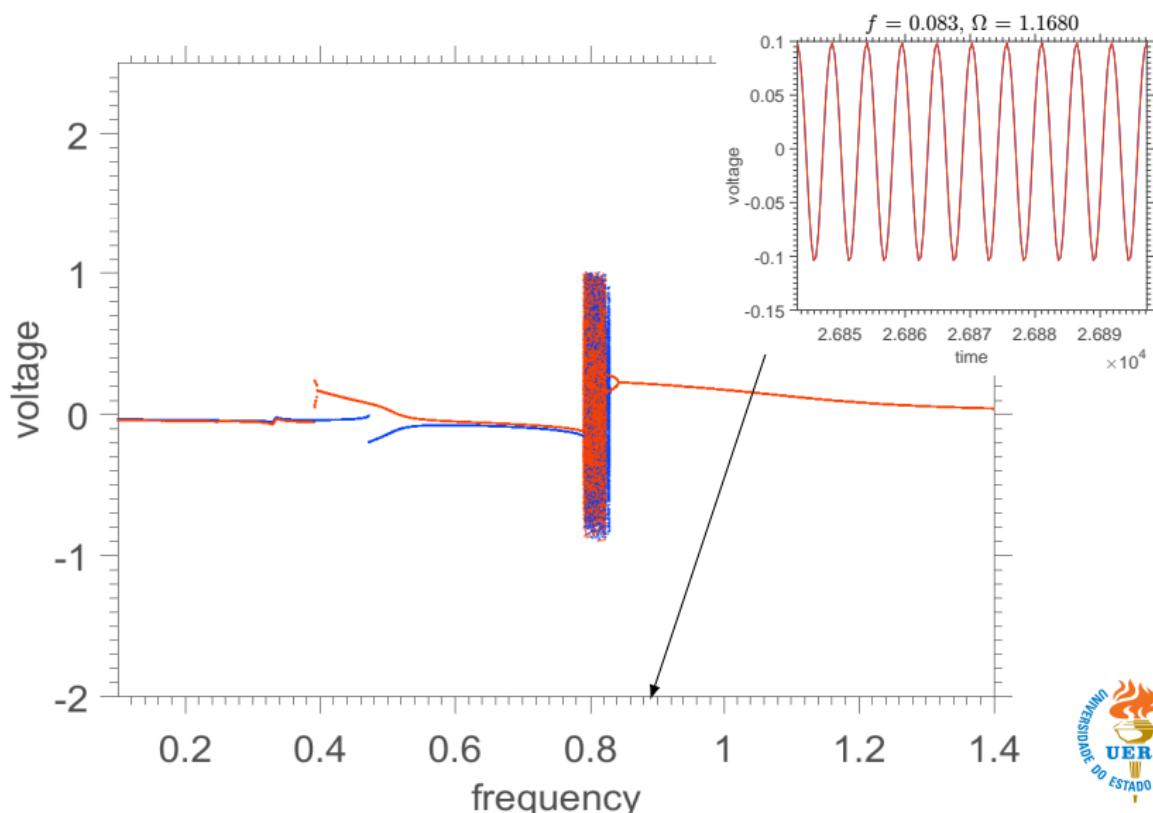
Forward and backward diagrams ($f = 0.083$)



Forward and backward diagrams ($f = 0.083$)



Forward and backward diagrams ($f = 0.083$)



Basins of attraction

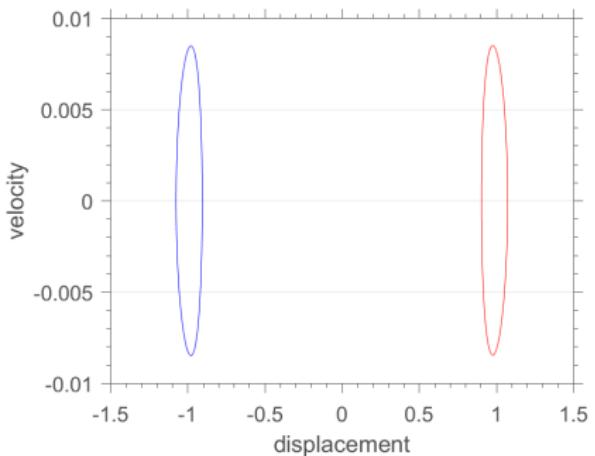
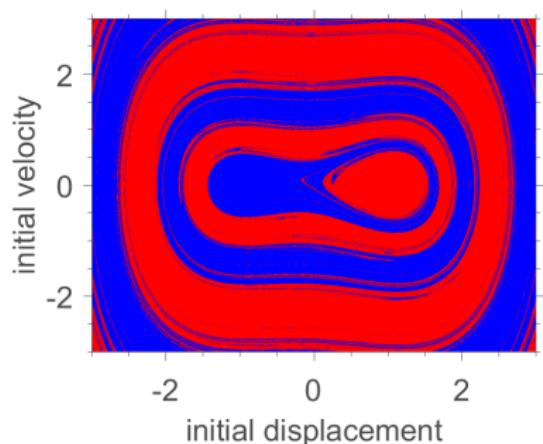


Figure: $f = 0.083$ and $\Omega = 0.1$

Basins of attraction

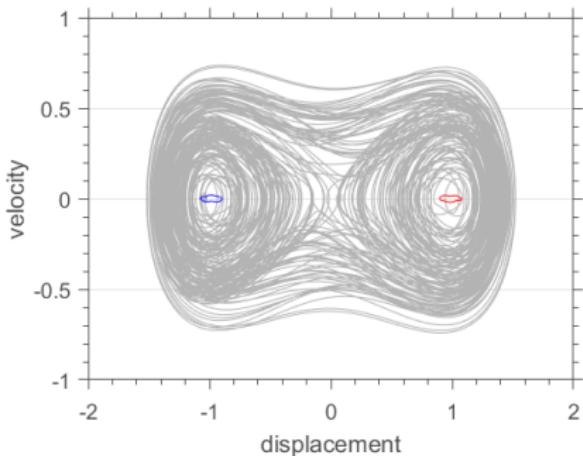
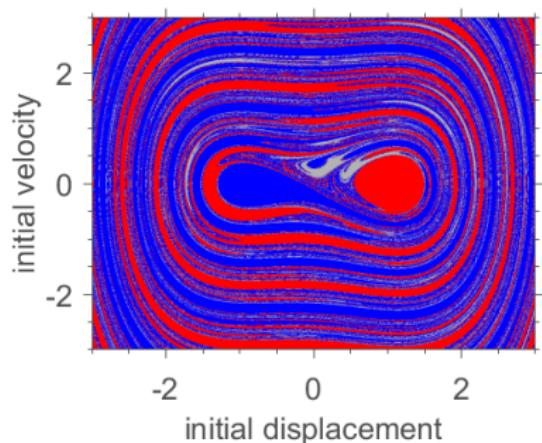


Figure: $f = 0.083$ and $\Omega = 0.2$

Basins of attraction

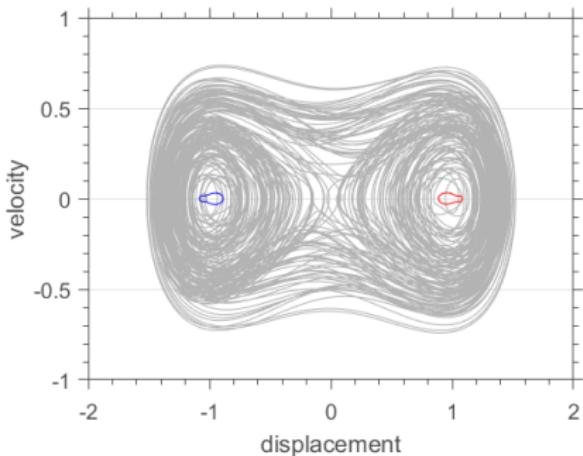
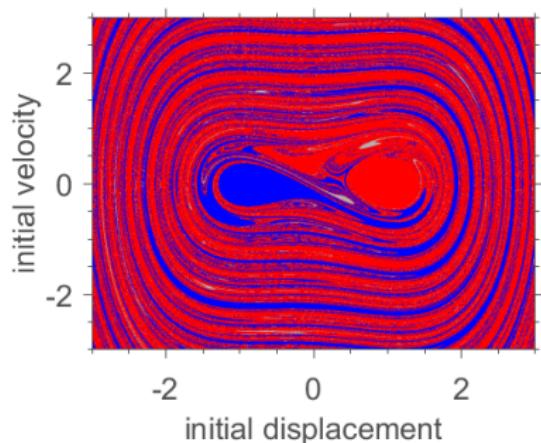


Figure: $f = 0.083$ and $\Omega = 0.3$

Basins of attraction

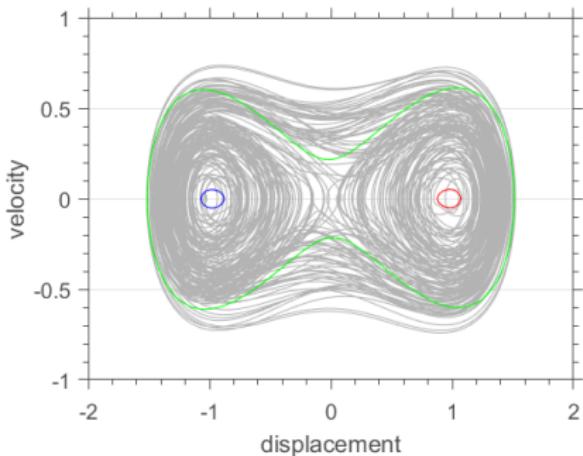
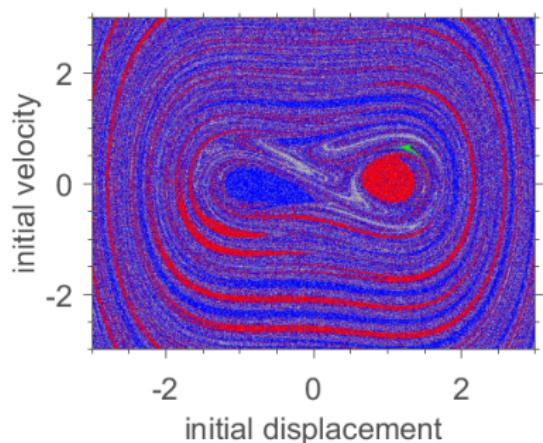


Figure: $f = 0.083$ and $\Omega = 0.4$

Basins of attraction

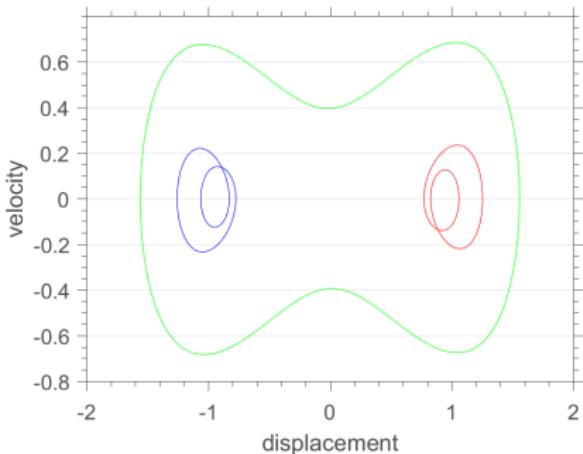
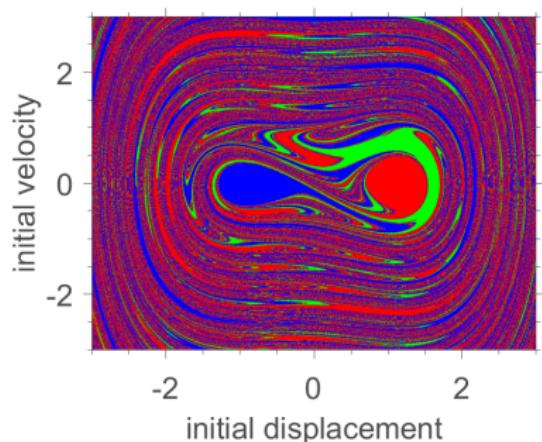


Figure: $f = 0.083$ and $\Omega = 0.5$

Basins of attraction

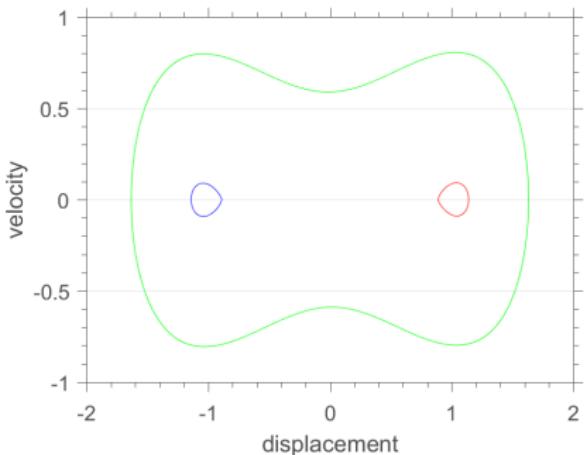
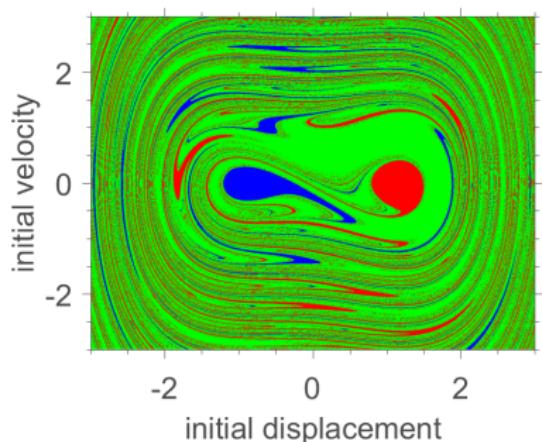


Figure: $f = 0.083$ and $\Omega = 0.6$

Basins of attraction

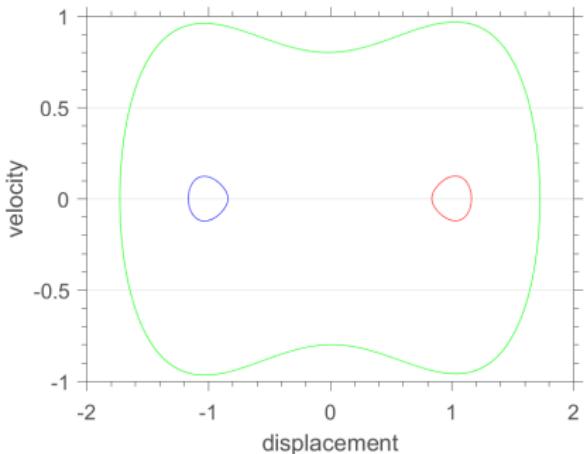
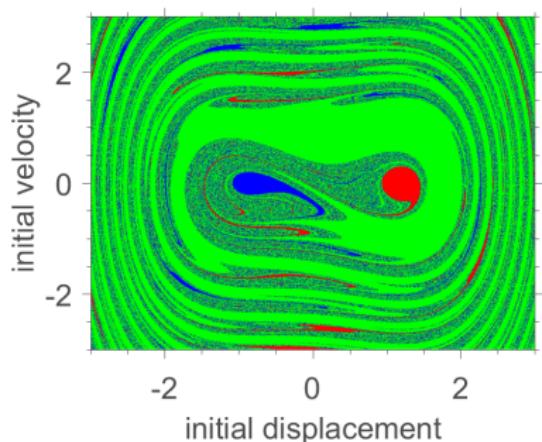


Figure: $f = 0.083$ and $\Omega = 0.7$

Basins of attraction

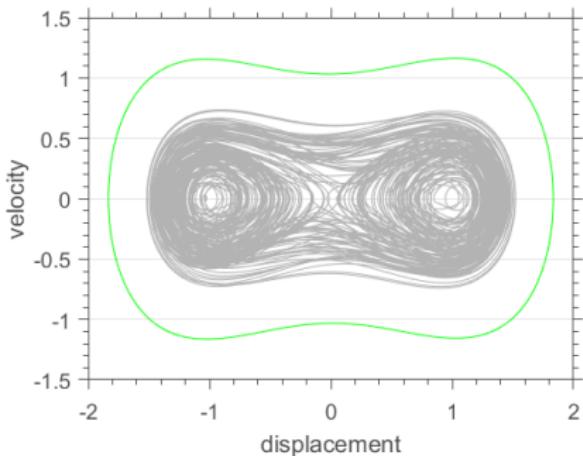
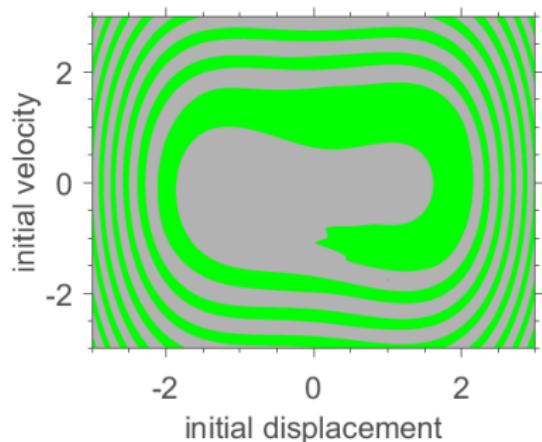


Figure: $f = 0.083$ and $\Omega = 0.8$

Basins of attraction

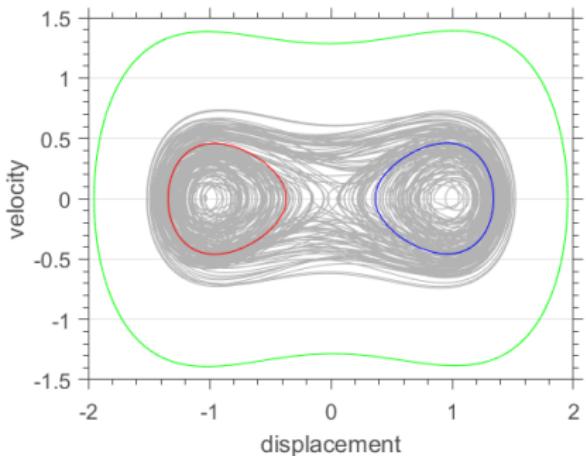
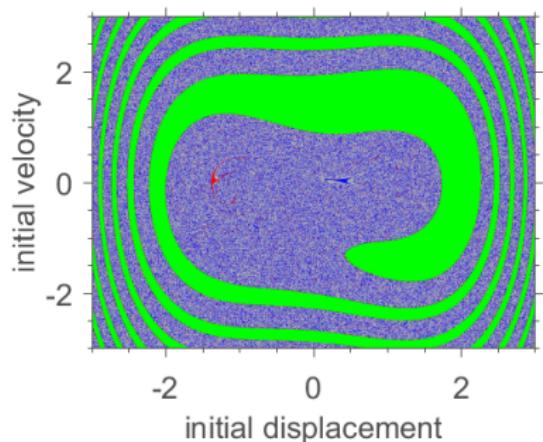


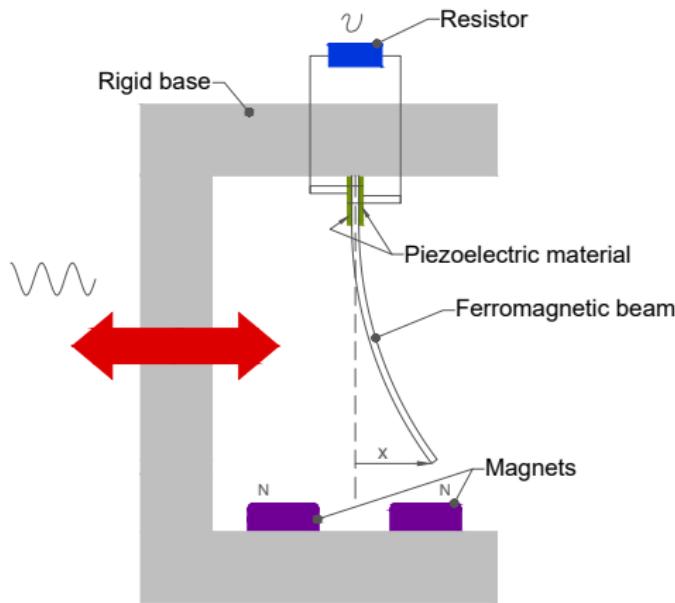
Figure: $f = 0.083$ and $\Omega = 0.9$

Stochastic Dynamics (ongoing research)



Nonlinear Vibratory Harvester

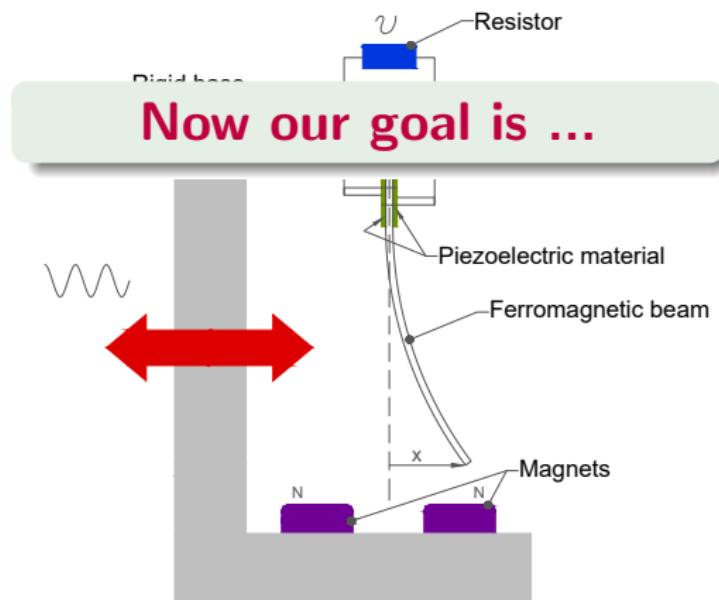
Bistable system driven by regular signal



A. Erturk, J. Hoffmann and D. J. Inman, *A piezomagnetoelastic structure for broadband vibration energy harvesting*. *Applied Physics Letters*, 94: 254102, 2009.

Nonlinear Vibratory Harvester

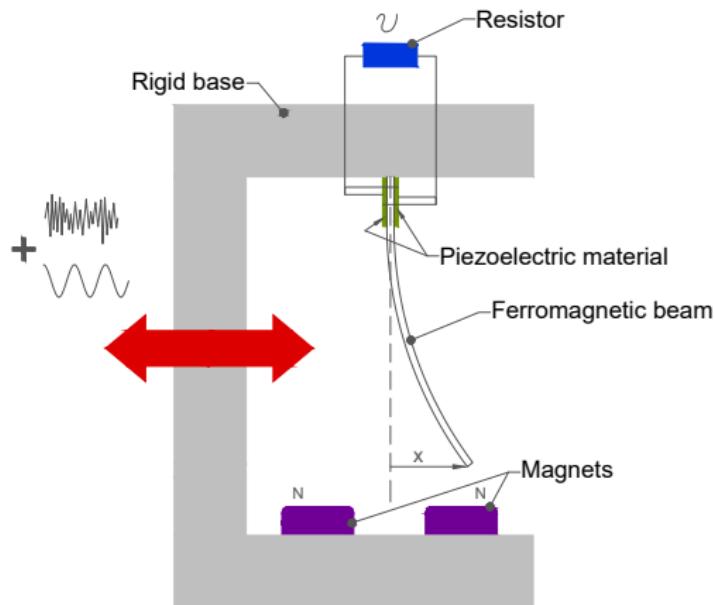
Bistable system driven by regular signal



A. Erturk, J. Hoffmann and D. J. Inman, *A piezomagnetoelastic structure for broadband vibration energy harvesting*. *Applied Physics Letters*, 94: 254102, 2009.

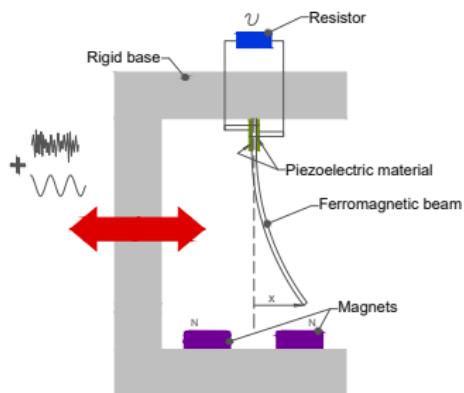
Nonlinear Vibratory Harvester

Bistable system driven by regular **and noisy** signals



V. G. Lopes, J. V. L. L. Peterson, and A. Cunha Jr, **On the nonlinear stochastic dynamics of piezo-magneto-elastic energy harvester driven by colored noise**, (in preparation) 2019.

Bistable harvester driven by regular and noisy signals



$$\ddot{x} + 2\xi\dot{x} - \frac{1}{2}x(1-x^2) - \chi v = f \cos \Omega t + \text{"noise"}$$

$$\dot{v} + \lambda v + \kappa \dot{x} = 0$$

$$x(0) = x_0, \quad \dot{x}(0) = \dot{x}_0, \quad v(0) = v_0$$



V. G. Lopes, J. V. L. L. Peterson, and A. Cunha Jr, **On the nonlinear stochastic dynamics of piezo-magneto-elastic energy harvester driven by colored noise**, (in preparation) 2019.

Nonlinear stochastic dynamical system

- external excitation N_t :

- zero-mean stationary Gaussian process
- covariance function:

$$\text{cov}_{N_t}(t_1, t_2) = \sigma \exp\left(-\frac{|t_2 - t_1|}{\tau_{corr}}\right), \quad \frac{\sigma^2}{\tau_{corr}} = \text{constant}$$

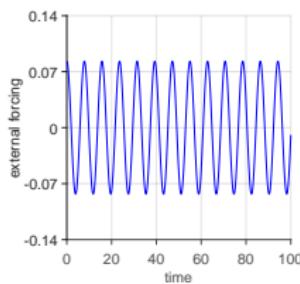
- stochastic evolution law:

$$\ddot{X} + 2\xi \dot{X} - \frac{1}{2}x(1 - X^2) - \chi V = f \cos \Omega t + N_t$$

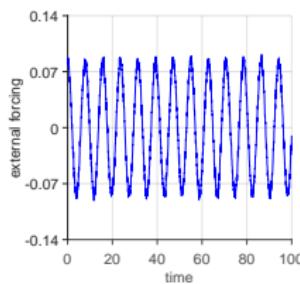
$$\dot{V} + \lambda V + \kappa \dot{X} = 0$$

$$X(0) = x_0, \quad \dot{X}(0) = \dot{x}_0, \quad V(0) = v_0$$

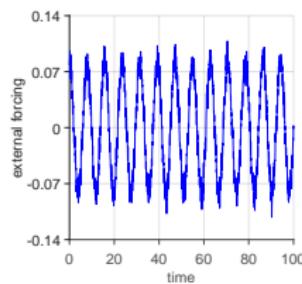
Realizations of random external force



(a) 1% of noise



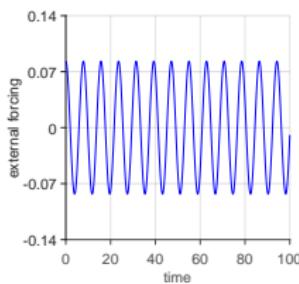
(b) 25% of noise



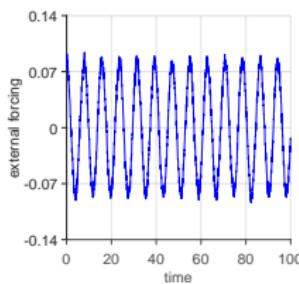
(c) 50% of noise

$$\sigma^2 / \tau_{cor} = 1$$

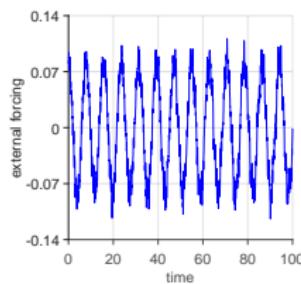
Realizations of random external force



(a) 1% of noise



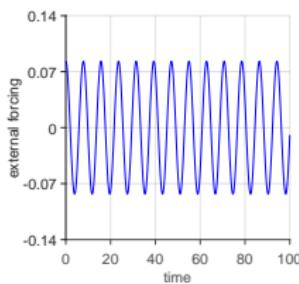
(b) 25% of noise



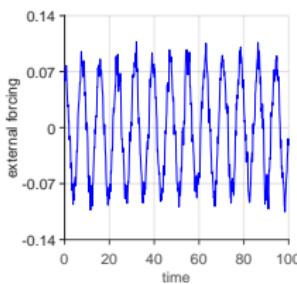
(c) 50% of noise

$$\sigma^2 / \tau_{cor} = 0.5$$

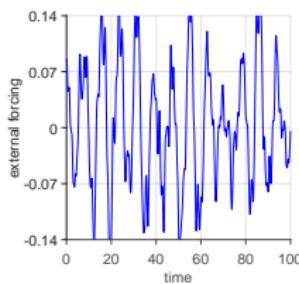
Realizations of random external force



(a) 1% of noise



(b) 25% of noise



(c) 50% of noise

$$\sigma^2/\tau_{cor} = 0.1$$

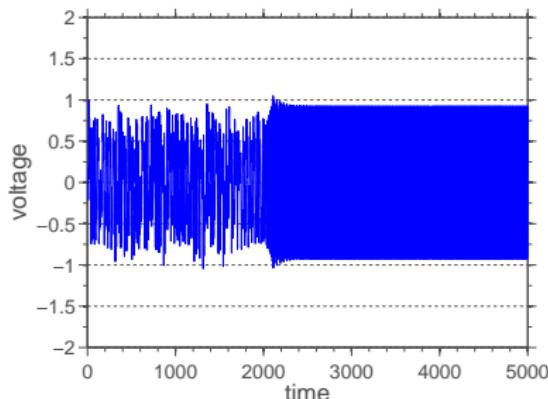
Nonlinear stochastic dynamics animation

Section 3

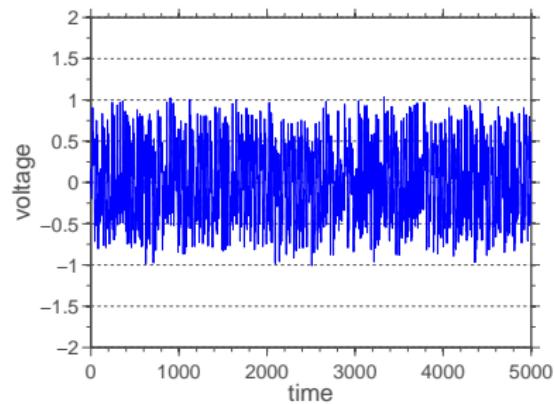
Controlling Chaos



Typical time series for the bistable harvester

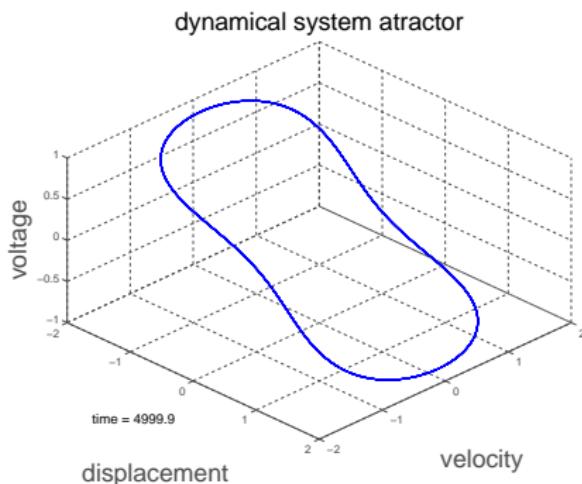


(a) regular (after chaotic transient)

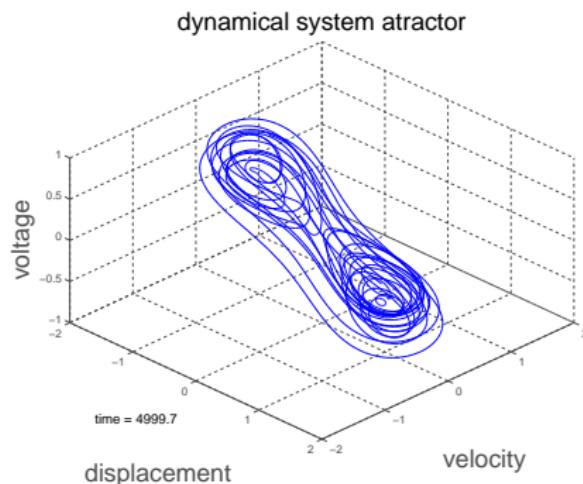


(b) strange attractor

Typical attractors for the bistable harvester

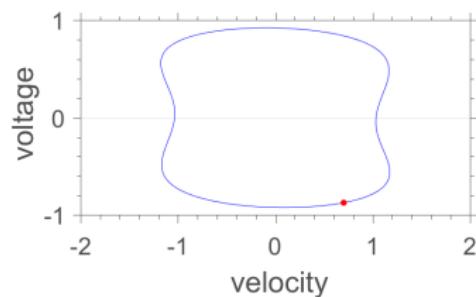


(a) regular limit cycle

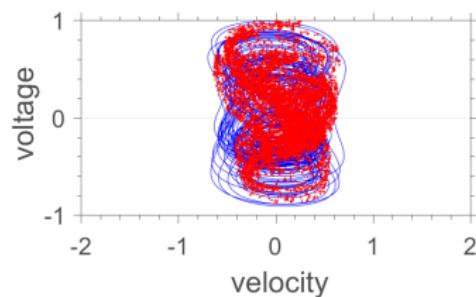


(b) strange attractor

Typical Poincaré sections for the bistable harvester



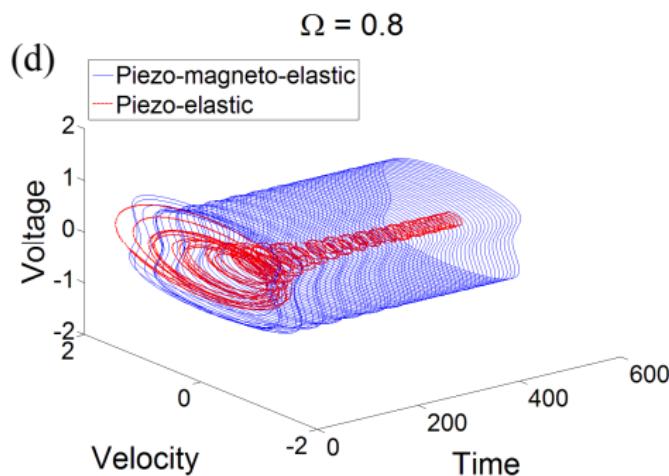
(a) regular limit cicle



(b) strange attractor

Nonlinearity and efficiency

Nonlinearity of this dynamical system may enhance output power.

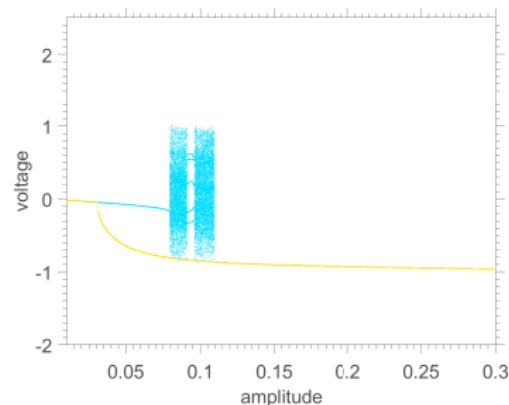
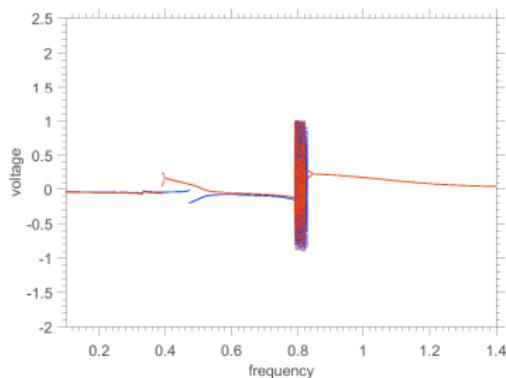


A. Erturk, *Electromechanical Modeling of Piezoelectric Energy Harvesters*, PhD Thesis, Virginia Tech, 2009.

*Picture from the above reference.

Nonlinearity and chaos

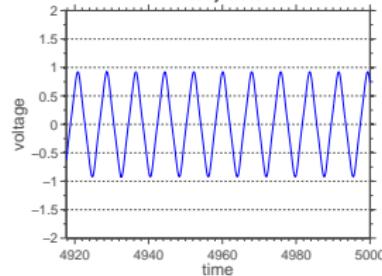
Nonlinearity of this dynamical system may also induce chaos.



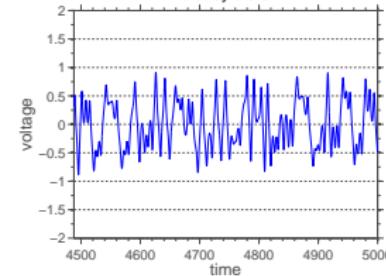
For operation of electrical devices ...



steady state

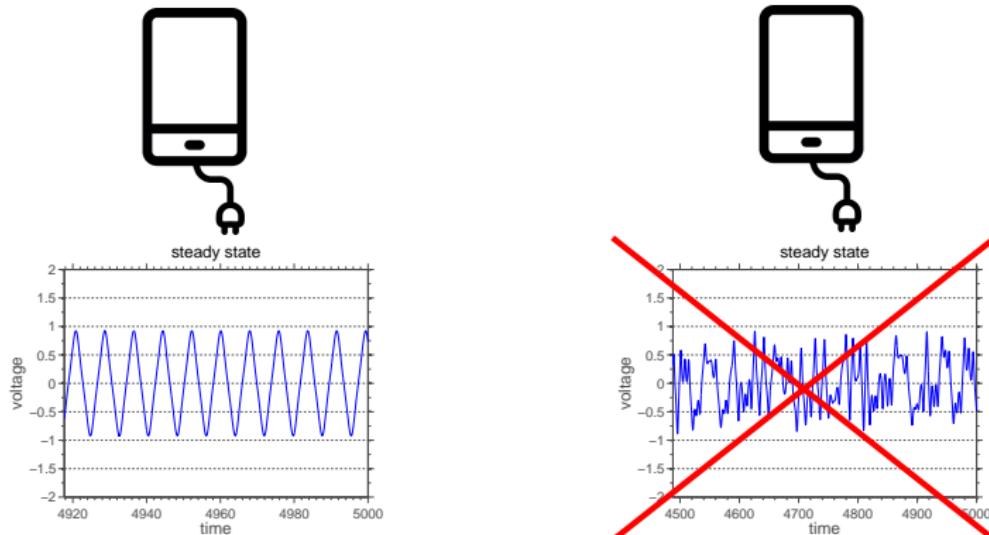


steady state



*Phone picture from <http://freevector.co/vector-icons/technology/charging-phone.html>

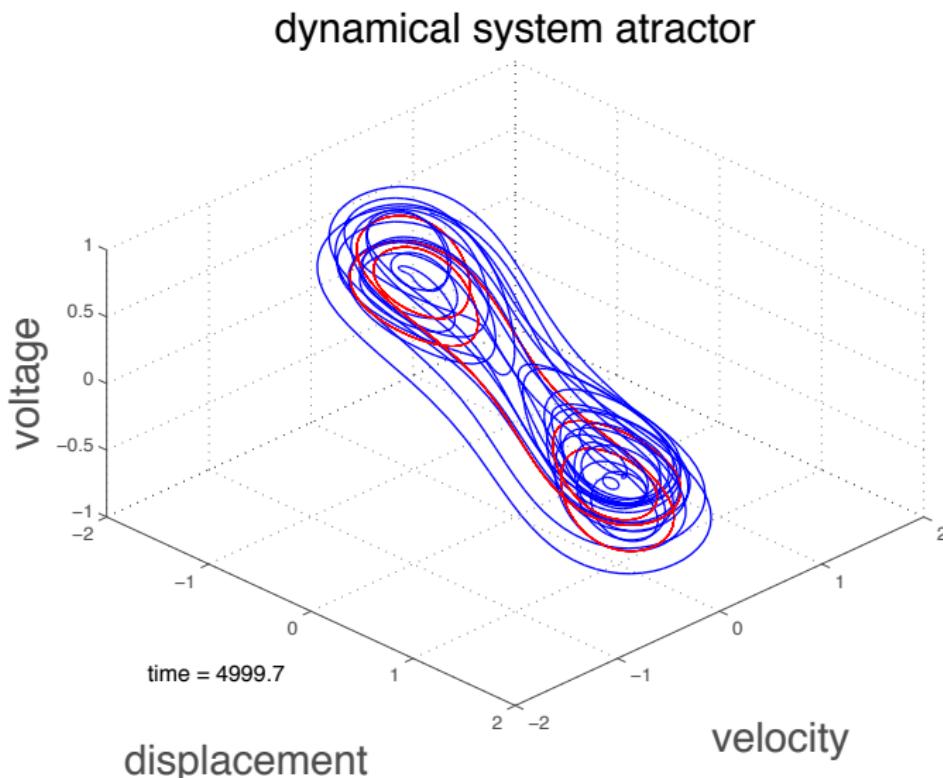
For operation of electrical devices ...



... irregular voltage is undesirable!

*Phone picture from <http://freevector.co/vector-icons/technology/charging-phone.html>

UPO embedded into a chaotic attractor



How to explore these unstable periodic orbits?

⇒ **Techniques for control of chaos**
(known UPO is required)

OGY:

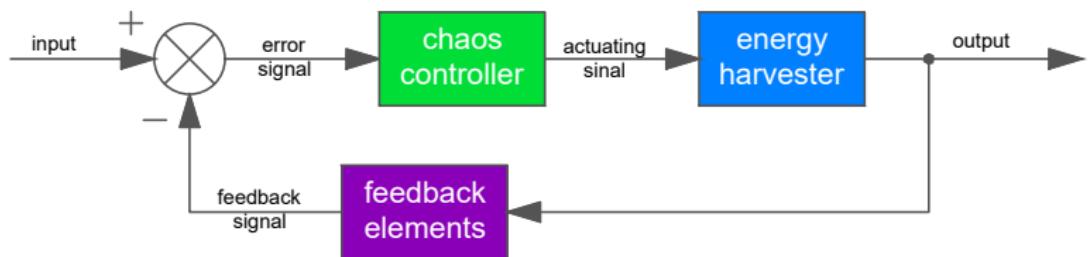
- Control performed by a sequence of (discrete) small “kicks” that forces the system trajectory to stay in the target orbit

Pyragas:

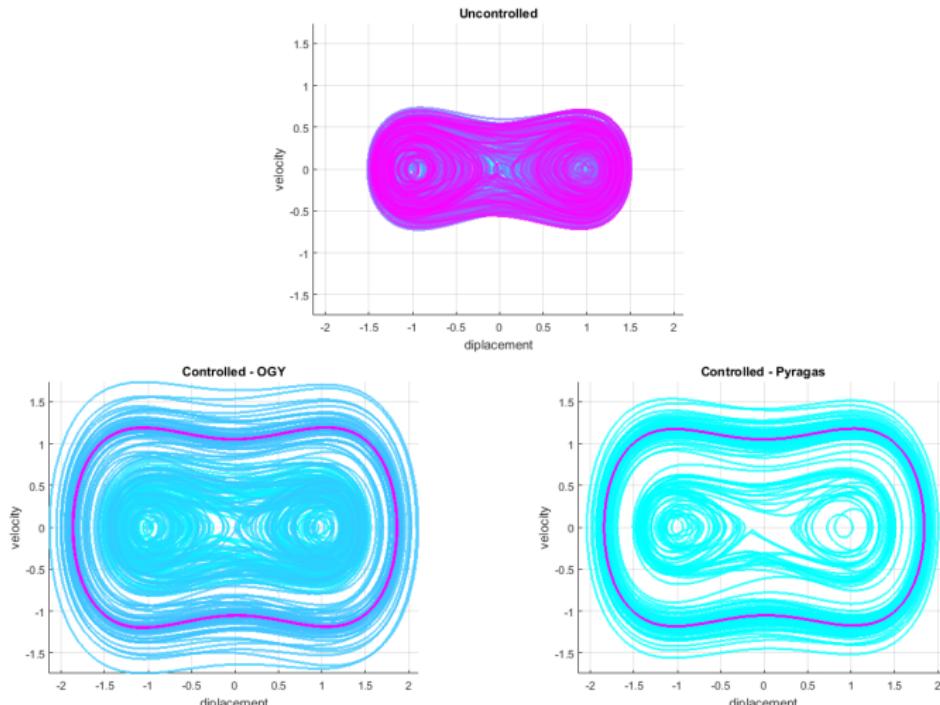
- Control performed by a (continuous) low intensity signal which is almost zero if the system evolves close to the target orbit, and increases when it starts to drift way



Feedback control law

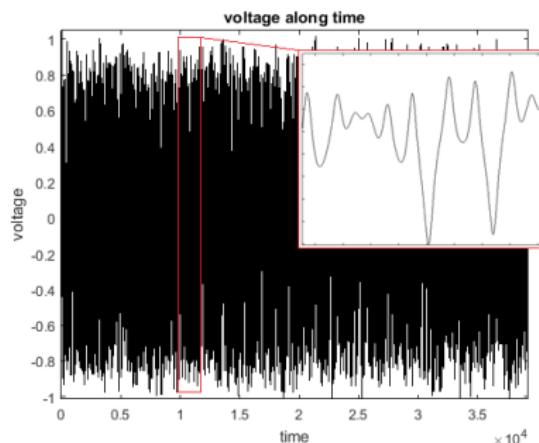


Stabilization via control of chaos ($f = 0.083$, $\Omega = 0.8$)

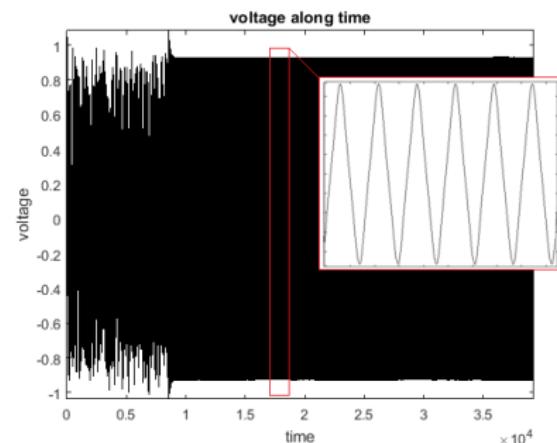


*The colors represent the evolution of the system, from blue to pink, as the time progresses.

Voltage time series ($f = 0.083$, $\Omega = 0.8$)



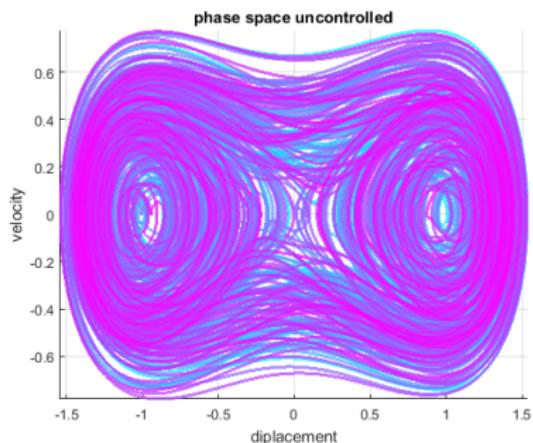
uncontrolled dynamics



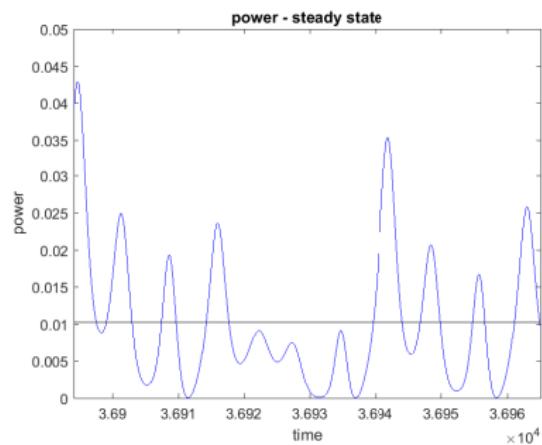
OGY controlled dynamics

OGY control with different orbits ($f = 0.090$, $\Omega = 0.8$)

uncontrolled dynamics



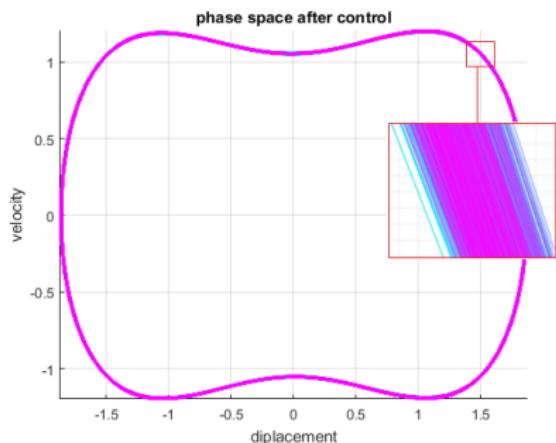
system trajectory



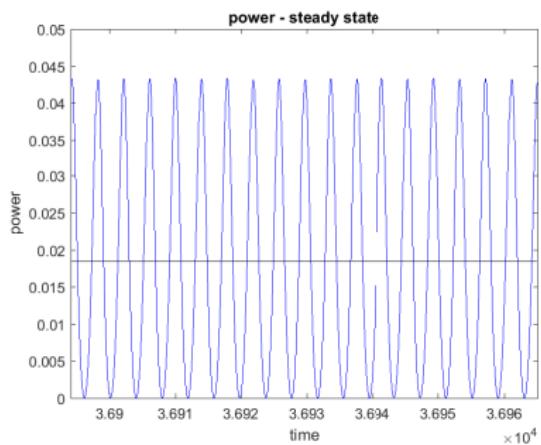
output power

OGY control with different orbits ($f = 0.090$, $\Omega = 0.8$)

controlled dynamics in a period 1 orbit



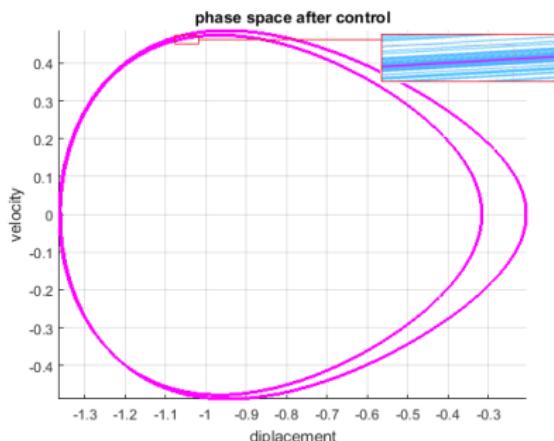
system trajectory



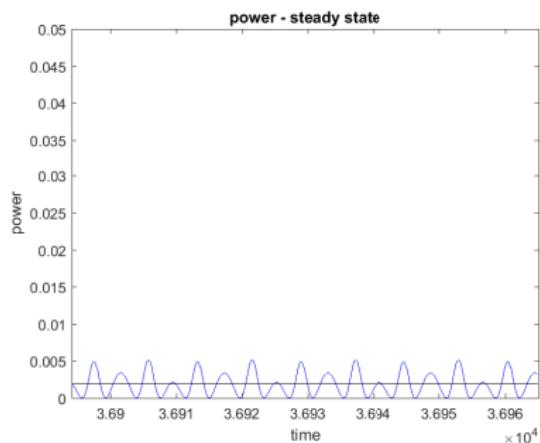
output power

OGY control with different orbits ($f = 0.090$, $\Omega = 0.8$)

controlled dynamics in a period 2 orbit



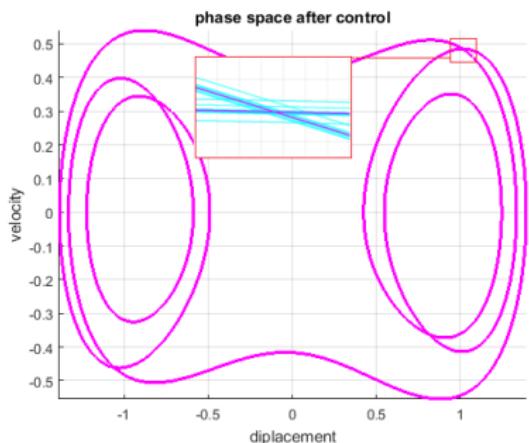
system trajectory



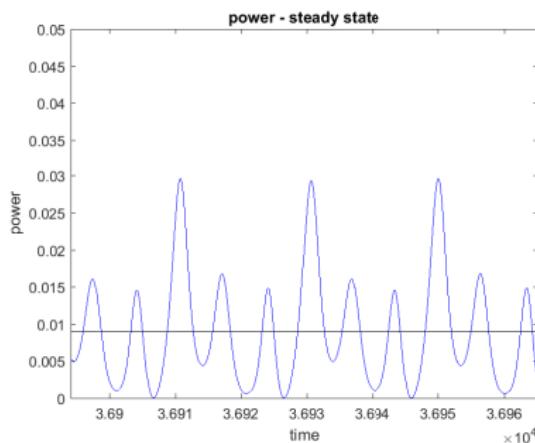
output power

OGY control with different orbits ($f = 0.090$, $\Omega = 0.8$)

controlled dynamics in a period 5 orbit



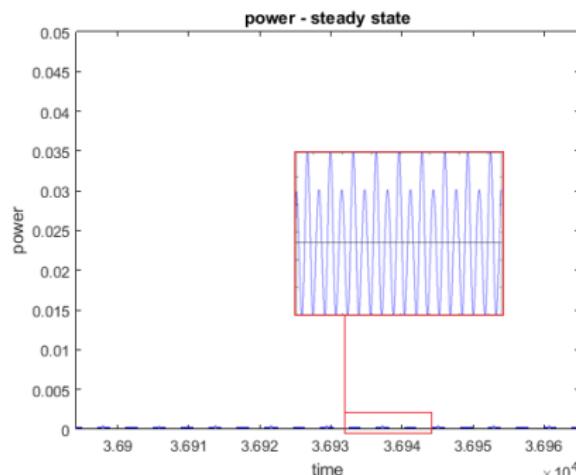
system trajectory



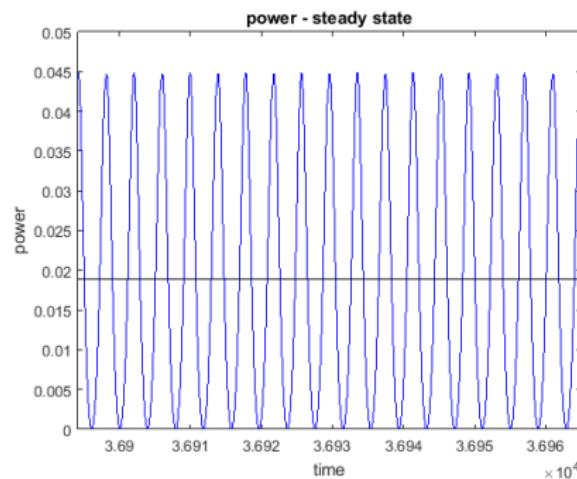
output power

Astonishing improvements are possible: Good!

$$f = 0.050, \Omega = 0.8$$



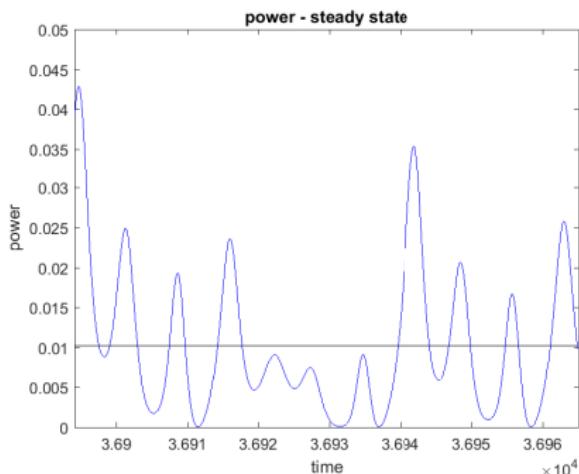
uncontrolled system



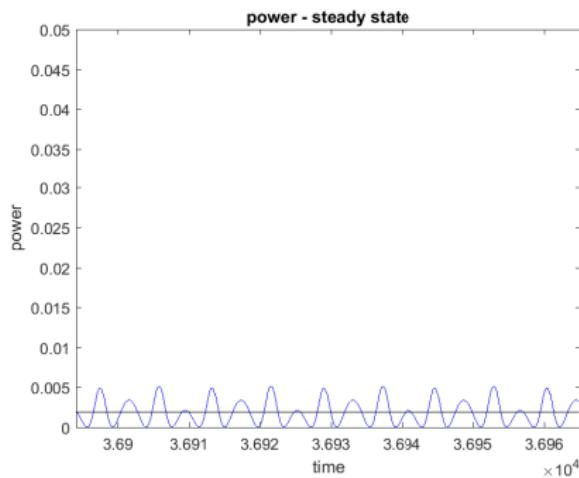
controlled system

Catastrophic effects too: Bad!

$$f = 0.090, \Omega = 0.8$$



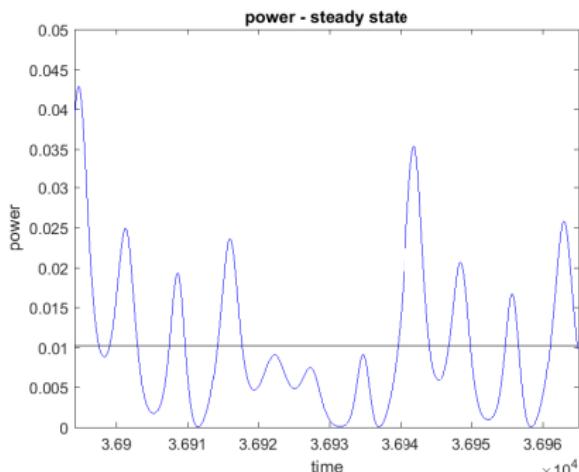
uncontrolled system



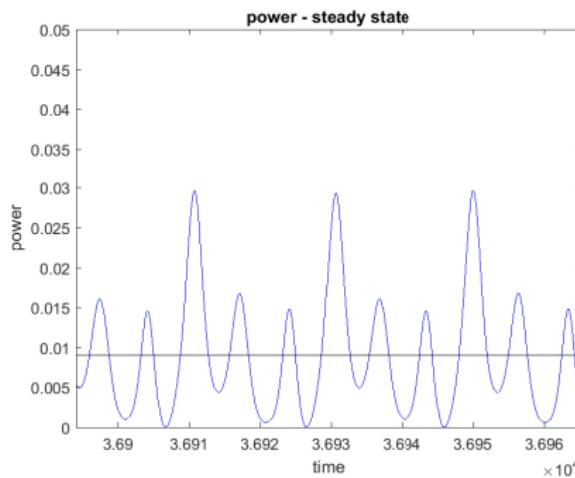
controlled system

And no significative change: Ugly!

$$f = 0.090, \Omega = 0.8$$



uncontrolled system



controlled system

Enhancement of power recovery

$\Omega = 0.8$ – steady state

f	uncontrolled	controlled	controller ($\times 10^{-4}$)	effective	enhancement
0.050	0.0001	0.0068	- 0.0005	0.0068	68 ✕
0.083	0.0073	0.0131	- 0.0006	0.0131	1.8 ✕
0.090 1-p	0.0077	0.0154	- 0.0001	0.0154	2 ✕
0.090 2-p	0.0077	0.0037	- 0.0002	0.0037	0.5 ✕
0.090 5-p	0.0077	0.0084	- 0.0001	0.0084	1.1 ✕

Section 4

Final Remarks



Final remarks

Some conclusions:

- Nonlinearity is a powerful ingredient for harvesters efficiency:
 - May induce large amplitude responses
 - A plenty of energy is available in nonlinear responses
- Nonlinearity may also be an enemy:
 - May induce (very irregular) chaotic responses
 - Irregular voltage is undesirable for electronic powering
- Control of chaos may be good, bad and ugly:
 - Astonishing improvements in efficiency are possible
 - Significative reductions of efficiency too
 - Controll of chaos may also be inert to efficiency

Ongoing research:

- Further studies in stochastic dynamics
- Further studies with Pyragas control of chaos
- Construction of an experimental apparatus



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C A P E S



Thank you for your attention!

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