Applied Data Science Capstone Presentation

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Executive Summary

► This presentation outlines the complete Data Science workflow applied to a real-world problem, starting with data collection via the SpaceX API and web scraping, and progressing through exploratory data analysis (EDA), data visualization, and predictive modeling.



Introduction

In this course, I applied and walked through the following key steps in the Data Science process:

- Collecting data by making requests to the SpaceX API.
- Handling missing values and filtering the relevant subset of the data.
- **Gathering additional data** through web scraping and converting HTML content into a structured pandas DataFrame.
- **Performing exploratory data analysis (EDA)** and applying feature engineering to define the final labels.
- Creating visualizations to explore and interpret relationships between various features.
- Implementing multiple predictive modeling algorithms and evaluating their performance.



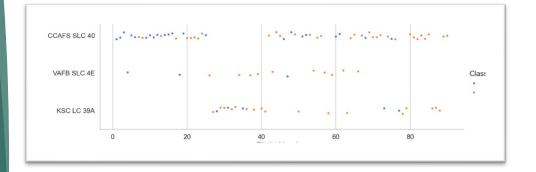
Data Collection and Wrangling Methodology

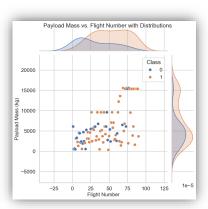
▶This is an example on how we interact with API requests. Here we are taking the dataset by using the cores column to append the data in lists. And some screen shots for parts of EDA, where we count the unique values of outcomes and saving the dataframe using csv format.

```
df.to_csv("dataset_part\_2.csv", index=False)
```

EDA & Interactive Visual Analytics Methodology

▶This scatter plot shows the relationship between Flight Number and Launch Site, with colors representing different launch outcomes. The pattern suggests that Logistic Regression could be a strong starting point for predicting launch outcomes based on these variables.





Predictive Analysis Methodoloav

The right image shows how we built a Logistic Regression model and used gridsearch to find the best paramters to be used in the predictive analysis.

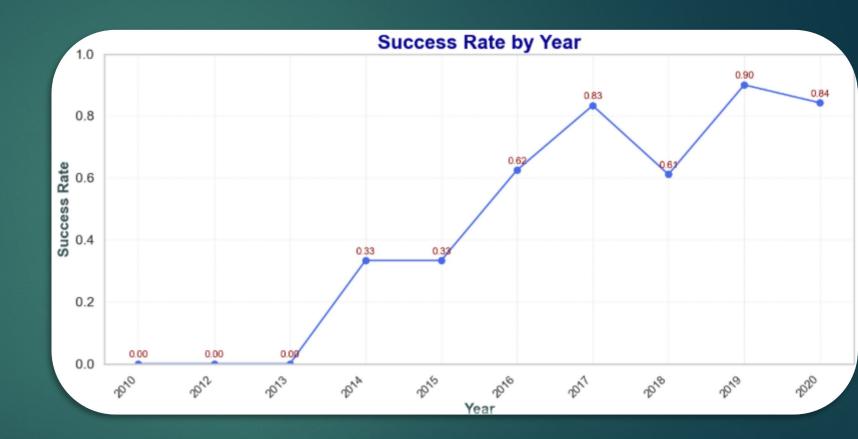
The below image shows the evaluation metric, which is accuracy. Where we have around 85%, which is a very good score that ensures we do not have overfitting and our models works well

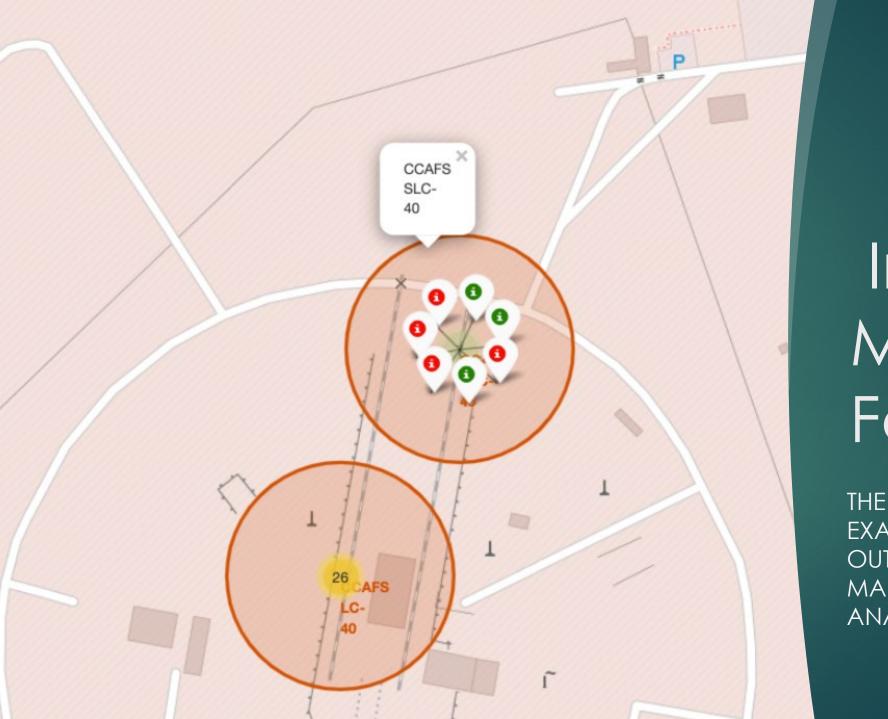
```
# Create Logistic Regression object
   logreg = LogisticRegression()
   # Define the parameter grid
   parameters = {
        'C': [0.01, 0.1, 1],
        'penalty': ['12'],
        'solver': ['lbfgs']
11
   # Create GridSearchCV object with 10-fold cross-validation
   logreg cv = GridSearchCV(estimator=logreg, param grid=parameters, cv=10)
   # Fit the GridSearchCV object to the training data
   logreg cv.fit(X train, Y train)
17
                                (i) (?)
           GridSearchCV
best_estimator_: LogisticRegression

    LogisticRegression ②
```

EDA with Visualization Results

- One of the results we had after the Visualization EDA step is plotting the success rate for 10 years.
- We can clearly observe the rate increases with time, which reflects correctly the learning curve theory where errors will be minimized by time





Interactive Map with Folium

THE IMAGE SHOWS AN EXAMPLE OF A FOLIUM CODE OUTPUT, WHERE WE CAN MARK FOR GEOSPATIAL DATA ANALYSIS

Predictive Analysis Results

I am sharing the code for the comparison I made among the following predictive algorithms:

- Logistic Regression
- Support Vector Machine (SVM)
- Decision Tree
- •k-Nearest Neighbors (KNN)
 In this comparison, I have used several performance metrics, including Precision, Recall, F1-score, and the AUC-ROC curve, to evaluate and compare the effectiveness of each algorithm.

```
1 from sklearn.metrics import precision score, recall score, f1 score, roc auc so
    # Get predictions for each model
    y pred logreg = logreg cv.predict(X test)
    y pred svm = svm cv.predict(X test)
    y pred tree = tree cv.predict(X test)
    y pred knn = knn cv.predict(X test)
    # Calculate Precision, Recall, F1-Score, and AUC-ROC for each model
    metrics = {}
     for model name, y pred in zip(["Logistic Regression", "SVM", "Decision Tree", "KNN"],
                                    [y pred logreg, y pred svm, y pred tree, y pred knn]):
        precision = precision_score(Y_test, y_pred, average='binary') # Adjust for binary/multi-cl
        recall = recall score(Y test, v pred, average='binary') # Adjust for binary/multi-class cl
        f1 = f1 score(Y test, y pred, average='binary') # Adjust for binary/multi-class classification
        auc roc = roc auc score(Y test, y pred)
        metrics[model name] = {
             'Precision': precision,
             'Recall': recall,
            'F1-Score': f1,
             'AUC-ROC': auc roc
26 # Print the evaluation metrics for each model
    for model name, model metrics in metrics.items():
        print(f"Evaluation metrics for {model name}:")
        for metric name, value in model metrics.items():
            print(f"{metric name}: {value:.4f}")
        print() # Add a blank line between models
32
✓ 0.0s
```

Precision: 0.8000

Recall: 1.0000

F1-Score: 0.8889

AUC-ROC: 0.7500

Evaluation metrics for Decisi

Precision: 0.8000

Recall: 1.0000

F1-Score: 0.8889

AUC-ROC: 0.7500

Evaluation metrics for KNN:

Precision: 0.8000

Recall: 1.0000

F1-Score: 0.8889

Predictive Analysis Results

Surprisingly, all algorithms yielded identical evaluation metrics. After reviewing my code multiple times, I confirmed there were no errors. As noted in my notebook, the model selection can be based on the simplest and lightest option for production and deployment.

The project followed a structured Data Science pipeline: data ingestion through the SpaceX API and web scraping, preprocessing (including handling missing values and feature selection), exploratory data analysis (EDA) and feature engineering for label creation, and the application of multiple classification models (Logistic Regression, SVM, Decision Tree, KNN). Model evaluation was performed using accuracy, precision, recall, F1-score, and AUC-ROC. Despite identical metrics across all models, Logistic Regression was chosen due to its simplicity and efficiency, making it ideal for deployment constraints.

Conclusion

Insights and Future Work

▶ To enhance model performance and generalizability, future work could involve hyperparameter tuning with GridSearchCV or RandomizedSearchCV, applying ensemble methods like Random Forest or XGBoost, and incorporating additional features such as payload mass, orbit type, or weather data via external APIs. Additionally, deploying the final model using Flask or Streamlit would enable real-time predictions, completing the MLOps cycle.

