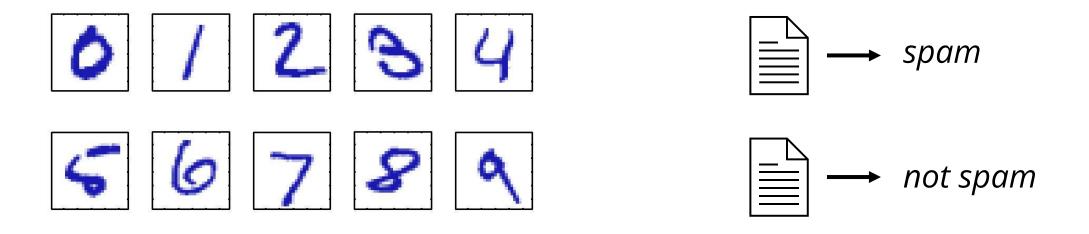
CSE 575 Statistical Machine Learning

Lecture 7 YooJung Choi Fall 2022

Classification

• Assign each input \mathbf{x} to one of K discrete classes $\mathcal{C}_1, \dots, \mathcal{C}_K$



Classification

• Assign each input \mathbf{x} to one of K discrete classes $\mathcal{C}_1, \dots, \mathcal{C}_K$

- 1. Discriminant functions. directly map $\mathbf{x} \mapsto \mathcal{C}_k$
- 2. Probabilistic generative models. model $p(\mathbf{x}, \mathcal{C}_k)$ to compute $p(\mathcal{C}_k|\mathbf{x})$
- 3. Probabilistic discriminative models. model $p(C_k|\mathbf{x})$ only

Linear models for classification

• Functions of the form:

$$y(\mathbf{x}) = f(\mathbf{w}^T \mathbf{x} + w_0)$$

- Generalized linear models (given some assumptions)
- $f(\cdot)$ is a fixed non-linear "activation" function:

• Example:
$$f(u) = \begin{cases} 1 \text{ if } u \ge 0 \\ 0 \text{ otherwise} \end{cases}$$

- Linear decision boundary
- Note: can also apply non-linear basis functions $\phi_j(\mathbf{x})$

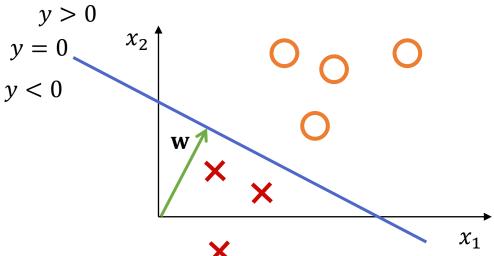
Linear discriminant: binary case

- Start with binary class: $t \in \{0,1\}$
- Simplest form of discriminant function:

$$y(\mathbf{x}) = \mathbf{w}^T \mathbf{x}$$

again, assume a dummy feature $x_0 = 1$.

- Apply threshold function to get classification
- Terminology: decision boundary: $\{\mathbf{x}|y(\mathbf{x})=0\}$ decision regions: $\{\mathbf{x}|y(\mathbf{x})\geq 0\}, \{\mathbf{x}|y(\mathbf{x})< 0\}$



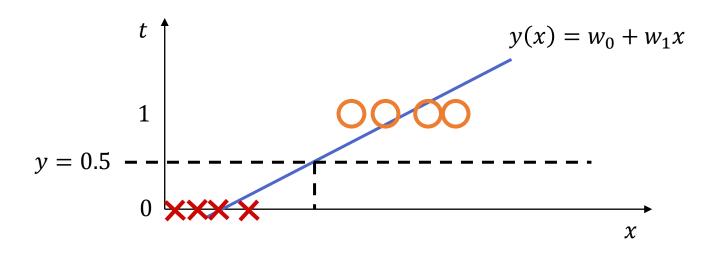
Least squares for classification

- How to learn the decision boundary w?
- Minimize sum-of-squares error:

$$E(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^{N} (\mathbf{w}^T \mathbf{x}_n - t_n)^2$$

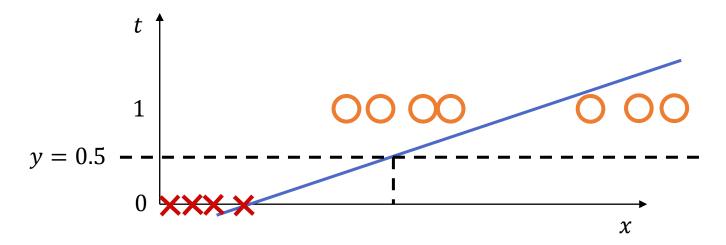
- i.e. linear regression except $t_n \in \{0,1\}$
- Threshold $\mathbf{w}^T \mathbf{x} \ge 0.5$ to get classification
- Close-form solution as in regression

Problems with least squares



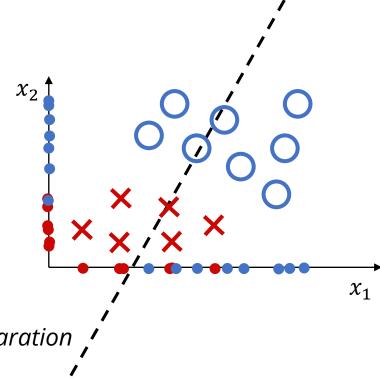
Problems with least squares

Let's add more easy examples



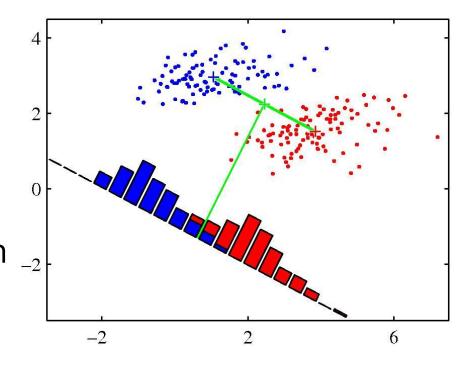
- Decision boundary got worse! Incorrectly classifies previously correct examples
- Problem: function can return values outside [0,1]

- Main idea: interpret $\mathbf{w}^T \mathbf{x}$ as projection of inputs onto a line
- i.e. reduce the dimension to 1
- Threshold $y(\mathbf{x}) = \mathbf{w}^T \mathbf{x} \ge y_0$ for classification
- What is the best direction w for projection?



Projection for perfect separation

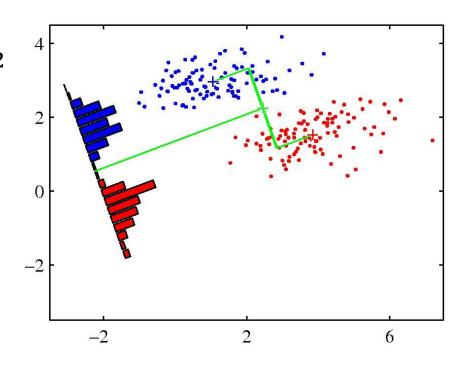
- Attempt 1: project s.t. the "average" points of each class are far apart i.e. project onto the line connecting the class means
- Maximize $\mathbf{w}^T(\mathbf{m}_2 \mathbf{m}_1)$ where $\mathbf{m}_k = \frac{1}{N_k} \sum_{n \in \mathcal{C}_k} \mathbf{x}_n$
- $\mathbf{w}^* \propto \mathbf{m}_2 \mathbf{m}_1$
- Problem: may overlap if there is within-class variance is in this direction



- (1) maximize the separation of means between classes, as well as (2) minimize the variance within each class
- Projected means: $m_k = \mathbf{w}^T \mathbf{m}_k$
- Projected variance: $s_k^2 = \sum_{n \in \mathcal{C}_k} (\mathbf{w}^T \mathbf{x}_n m_k)^2$
- Fisher criterion:

$$J(\mathbf{w}) = \frac{(m_2 - m_1)^2}{s_1^2 + s_2^2}$$

maximize w.r.t. w



- Fisher criterion: $J(\mathbf{w}) = \frac{(m_2 m_1)^2}{s_1^2 + s_2^2}$
- In matrix notation:

$$J(\mathbf{w}) = \frac{\mathbf{w}^T \mathbf{S}_B \mathbf{w}}{\mathbf{w}^T \mathbf{S}_W \mathbf{w}}$$

Between-class covariance matrix:

$$\mathbf{S}_B = (\mathbf{m}_2 - \mathbf{m}_1)(\mathbf{m}_2 - \mathbf{m}_1)^T$$

Total within-class covariance matrix:

$$S_W = \sum_{n \in \mathcal{C}_1} (\mathbf{x}_n - \mathbf{m}_1)(\mathbf{x}_n - \mathbf{m}_1)^T + \sum_{n \in \mathcal{C}_2} (\mathbf{x}_n - \mathbf{m}_2)(\mathbf{x}_n - \mathbf{m}_2)^T$$

Fisher criterion is maximized when:

$$\mathbf{w}^T \mathbf{S}_B \mathbf{w} (\mathbf{S}_W \mathbf{w}) = \mathbf{w}^T \mathbf{S}_W \mathbf{w} (\mathbf{S}_B \mathbf{w})$$

• We only care about the direction of **w**, and not its magnitude: drop the scalar factors:

$$S_W \mathbf{w} = S_B \mathbf{w}$$

- $S_B \mathbf{w} = (\mathbf{m}_2 \mathbf{m}_1)(\mathbf{m}_2 \mathbf{m}_1)^T \mathbf{w} = \text{scalar} \times (\mathbf{m}_2 \mathbf{m}_1) \propto (\mathbf{m}_2 \mathbf{m}_1)$
- Therefore: $\mathbf{w} \propto S_W^{-1}(\mathbf{m_2} \mathbf{m_1})$
- If $S_W^{-1} = \lambda I$ (i.e. isotropic), then $\mathbf{w} \propto (\mathbf{m_2} \mathbf{m_1})$

Within-class covariance is spherical

- Foundations for neural networks
- Limited to binary class.
- For ease of notation: t = 1 for class 1, t = -1 for class 2
- Discriminant model of the form:

$$y(\mathbf{x}) = f(\mathbf{w}^T \mathbf{x})$$
 where $f(a) = \begin{cases} +1, a \ge 0 \\ -1, a < 0 \end{cases}$

- Recall: sum-of-squares error was problematic (penalizes predictions outside of (0,1) range even though correctly classified)
- Main idea: penalize only misclassified examples

$$y(\mathbf{x}) = f(\mathbf{w}^T \mathbf{x})$$
 where $f(a) = \begin{cases} +1, a \ge 0 \\ -1, a < 0 \end{cases}$

• An example \mathbf{x}_n is misclassified iff

$$\mathbf{w}^T \mathbf{x}_n \cdot t_n < 0$$

- Goal: if possible, find **w** s.t. $\mathbf{w}^T \mathbf{x}_n \cdot t_n \ge 0$ for all n
- Perceptron criterion:

$$E_P(\mathbf{w}) = -\sum_{n \in \mathcal{M}} \mathbf{w}^T \mathbf{x}_n t_n$$

• \mathcal{M} is the set of misclassified examples

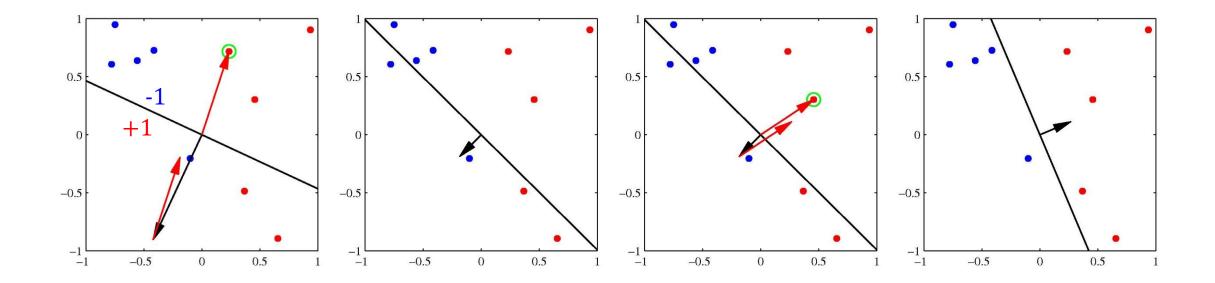
• Perceptron rule: iterative update using a misclassified example \mathbf{x}_n (c.f. minimizing the perceptron criterion using stochastic gradient descent):

$$\mathbf{w}^{(k+1)} \leftarrow \mathbf{w}^{(k)} - \eta \nabla E_p(\mathbf{w}) = \mathbf{w}^{(k)} + \eta \mathbf{x}_n t_n$$
 traditionally $\eta = 1$

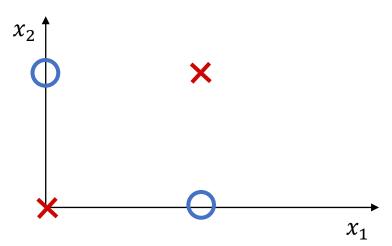
• After a single update using \mathbf{x}_n , its contribution to the error is reduced:

$$-\mathbf{w}^{(k+1)T}\mathbf{x}_{n}t_{n} = -\mathbf{w}^{(k)T}\mathbf{x}_{n}t_{n} - \eta(\mathbf{x}_{n}t_{n})^{T}\mathbf{x}_{n}t_{n} < -\mathbf{w}^{(k)T}\mathbf{x}_{n}t_{n}$$

• However, the changed weight vector could cause previously correct examples to be misclassified. I.e., the total error is not guaranteed to decrease after every iteration.



- The perceptron convergence theorem: if the data is linearly separable, the perceptron learning algorithm finds the solution in a finite number of steps.
- But it may take very long...
- If the data is not linearly separable, perceptron algorithm will never converge



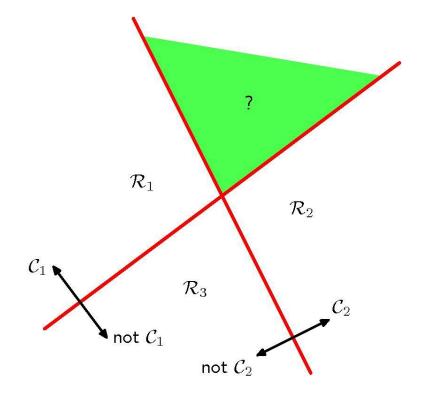
Discriminant functions: multi-class

How do we extend linear discriminants to K > 2 classes?

• 1st attempt: use K-1 binary classifiers, each classifying \mathcal{C}_k vs. not \mathcal{C}_k

"one-vs-the-rest"

Does not work!
 May lead to ambiguous regions

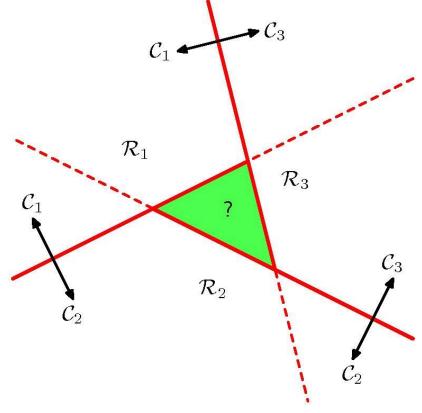


Discriminant functions: multi-class

• 2nd attempt: use K(K-1)/2 binary classifiers, each classifying C_j vs. C_k for a pair $j \neq k$

"one-vs-one"

- Classify according to a majority vote
- Does not work either!
 May lead to ambiguous regions



Discriminant functions: multi-class

• A single *K*-class discriminant comprising *K* linear functions:

$$y_k(\mathbf{x}) = \mathbf{w}_k^T \mathbf{x} + w_{k0}$$

• Assign \mathbf{x} to $\operatorname{argmax}_k y_k(\mathbf{x})$

i.e.
$$\mathbf{x} \mapsto \mathcal{C}_k$$
 if $y_k(\mathbf{x}) > y_j(\mathbf{x})$ for all $j \neq k$

- The decision boundary between \mathcal{C}_j and \mathcal{C}_k is given by a (D-1)-dimensional hyperplane $y_k(\mathbf{x}) = y_j(\mathbf{x})$
- Decision regions are convex

