# CS302 - Data Structures using C++

Topic: Dictionaries and their Implementations

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A collection of data about certain cities (slide to be referenced later)

City	Country	Population	
Buenos Aires	Argentina 13,639,000		
Cairo	Egypt 17,816,000		
Johannesburg	South Africa 7,618,000		
London	England	8,586,000	
Madrid	Spain	5,427,000	
Mexico City	Mexico	19,463,000	
Mumbai	India 16,910,000		
New York City	U.S.A. 20,464,000		
Paris	France	10,755,000	
Sydney	Australia	3,785,000	
Tokyo	Japan	37,126,000	
Toronto	Canada 6,139,000		

- Consider need to search such a collection for
  - Name
  - Address
- Criterion chosen for search is search key
- The ADT dictionary uses a search key to identify its entries

- Consider need to search such a collection for
  - Name
  - Address

UML diagram for the class of dictionaries

# Dictionary +isEmpty(): boolean +getNumberOfEntries(): integer +add(searchKey: KeyType, newValue: ValueType): boolean +remove(targetKey: KeyType): boolean +clear(): boid +getValue(targetKey: KeyType): ValueType +contains(targetKey: KeyType): boolean +traverse(visit(value: ValueType): void): void

- Categories of linear implementations
  - Sorted by search key, array-based
  - Sorted by search key, link-based
  - Unsorted, array-based
  - Unsorted, link-based

A dictionary entry

Search key Data value

A header file for a class of dictionary entries

```
// An interface for the ADT dictionary
#ifndef DICTIONARY INTERFACE
#define DICTIONARY INTERFACE
#include "NotFoundException.h"
template < class KeyType, class ValueType >
class DictionaryInterface
public:
    // Sees whether this dictionary is empty
    // @return: True if the dictionary is empty
        otherwise returns false
    virtual bool isEmpty() const = 0;
    // Gets the number of entries in this dictionary
    // @return The number of entries in this dictionary
    virtual int getNumberOfEntries() const = 0;
```

• A header file for a class of dictionary entries

```
// Adds a new search key and associated value to this dictionary.
// @pre The new search key differs from all search keys presently in the dictionary
// @post If the addition is successful, the new key-value pair is in its proper position within the
// dictionary.
// @param searchKey The search key associated with the value to be added.
// @param newValue The value to be added
// @return True if the entry was successfully added, or false if not.
virtual bool add(const KeyType& searchKey, const ValueType& newValue) = 0;

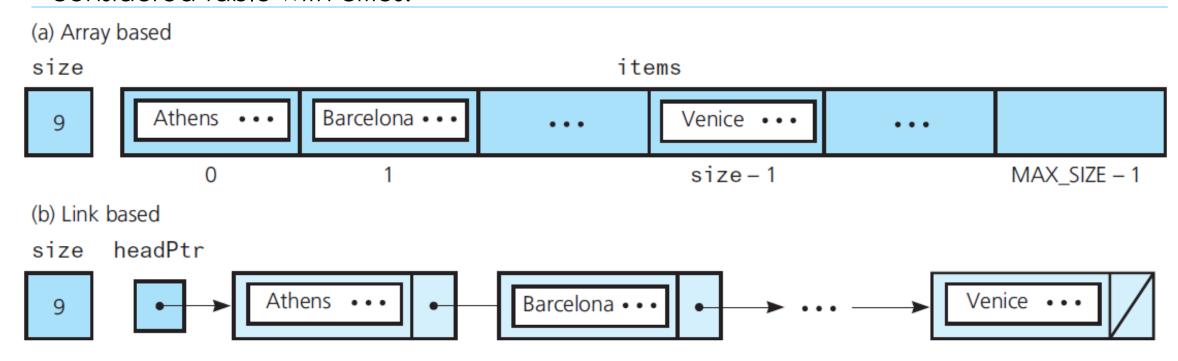
// Removes a key-value pair from this dictionary
// @post If the entry whose search key equals searchKey existed in the dictionary, the entry was removed.
// @param searchKey - The search key of the entry to be removed.
// @return True if the entry was successfully removed, or false if not.
virtual bool remove(const KeyType& searchKey) = 0;

// Removes all entries from this dictionary
virtual void clear() = 0;
```

• A header file for a class of dictionary entries

```
// Retrieves the value in this dictionary whose search key is given.
    // @post If the retrieval is successful, the value is returned.
    // @param searchKey The search key of the value to be retrieved.
    // @return The value associated with the search key.
    // @throw NotFoundException if the key-value pair does not exist
    virtual ValueType getValue(const KeyType& searchKey) const throw (NotFoundException) = 0;
    // Sees whether this dictionary contains an entry with a given search key.
    // @post The dictionary is unchanged.
    // @param searchKey The given search key.
    // @return True if an entry with the given search key exists in the dictionary.
    virtual bool contains(const KeyType& searchKey) const = 0;
    // Traverses this dictionary and calls a given client function once for each entry.
    // @post The given function's action occurs once for each entry in the dictionary and possibly alters the
    // entry.
    // @param visit A client function.
    virtual void traverse(void visit(ValueType&)) const = 0;
    virtual ~DictionaryInterface() { }
}; // end Dictionary Interface
#endif
```

 Data members for two sorted linear implementations of the ADT dictionary for the considered table with cities.



• A header file for a class of dictionary entries

```
// A clas of entries to add to an array-based implementation of the ADT dictionary
// @file Entry.h

#ifndef ENTRY_
#define ENTRY_

template<class KeyType, class ValueType>
class Entry
{
private:
    KeyType key;
    ValueType value;

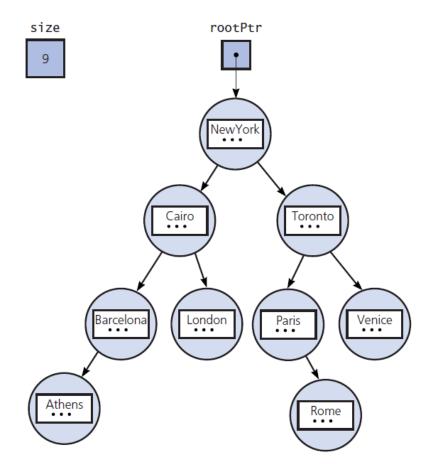
protected:
    void setKey(const KeyType& searchkey);
```

• A header file for a class of dictionary entries

```
public:
    Entry();
    Entry(const KeyType& searchKey, const ValueType& newValue);
    ValueType getValue() const;
    KeyType getKey() const;
    void setValue(const ValueType& newValue);

    bool operator == (const Entry<KeyType, ValueType>& rightHandValue) const;
    bool operator > (const Entry<KeyType, ValueType& rightHandValue) const;
}; // end Entry
#include "Entry.cpp"
#endif</pre>
```

• The data members for a binary search tree implementation of the ADT dictionary for the data in the considered table with cities.



A header file for the class ArrayDictionary

```
/** An array-based implementation of the ADT dictionary
that organizes its entries in sorted search-key order.
 Search keys in the dictionary are unique.
 @file ArrayDictionary.h */
#ifndef ARRAY DICTIONARY
#define ARRAY DICTIONARY
#include "DictionaryInterface.h"
#include "Entry.h"
#include "NotFoundException.h"
#include "PrecondViolatedExcept.h"
template < class KeyType, class ValueType >
class ArrayDictionary : public DictionaryInterface<KeyType, ValueType>
private:
   static const int DEFAULT CAPACITY = 21;
                                            // Small capacity to test for a full dictionary
   std::unique ptr<Entry<KeyType, ValueType>[]> entries; // Array of dictionary entries
                                                        // Current count of dictionary entries
   int entryCount;
   int maxEntries;
                                                         // Maximum capacity of the dictionary
  void destroyDictionary();
   int findEntryIndex(int firstIndex, int lastIndex, const KeyType& searchKey) const;
```

A header file for the class ArrayDictionary

```
public:
   ArrayDictionary();
   ArrayDictionary(int maxNumberOfEntries);
   ArrayDictionary(const ArrayDictionary<KeyType, ValueType>& dictionary);
   virtual ~ArrayDictionary();
   bool isEmpty() const;
   int getNumberOfEntries() const;
   bool add(const KeyType& searchKey, const ValueType& newValue) throw(PrecondViolatedExcept);
   bool remove(const KeyType& searchKey);
   void clear();
   ValueType getValue(const KeyType& searchKey) const throw(NotFoundException);
   bool contains(const KeyType& searchKey) const;
   /** Traverses the entries in this dictionary in sorted search-key order
    and calls a given client function once for the value in each entry. */
   void traverse(void visit(ValueType&)) const;
}; // end ArrayDictionary
#include "ArrayDictionary.cpp"
#endif
```

A header file for the class TreeDictionary

```
/** A binary search tree implementation of the ADT dictionary
 that organizes its entries in sorted search-key order.
 Search keys in the dictionary are unique.
 @file TreeDictionary.h */
#ifndef TREE DICTIONARY
#define TREE DICTIONARY
#include "DictionaryInterface.h"
#include "BinarySearchTree.h"
#include "Entry.h"
#include "NotFoundException.h"
#include "PrecondViolatedExcept.h"
template < class KeyType, class ValueType >
class TreeDictionary: public DictionaryInterface<KeyType, ValueType>
```

A header file for the class TreeDictionary

```
private:
    // Binary search tree of dictionary entries
    BinarySearchTree<Entry<KeyType, ValueType> > entryTree;

public:
    TreeDictionary();
    TreeDictionary(const TreeDictionary<KeyType, ValueType>& dictionary);
    virtual ~TreeDictionary();

    // The declarations of the public methods appear here and are the
    // same as given in Listing 18-3 for the class ArrayDictionary.

}; // end TreeDictionary
#include "TreeDictionary.cpp"
#endif
```

Method add which prevents duplicate keys.

```
template < class KeyType, class ValueType >
bool TreeDictionary<KeyType, ValueType>::add(const KeyType& searchKey,
                                             const ValueType& newValue)
                                             throw(PrecondViolatedExcept)
   Entry<KeyType, ValueType> newEntry(searchKey, newValue);
   // Enforce precondition: Ensure distinct search keys
     (!itemTree.contains(newEntry))
      // Add new entry and return boolean result
      return itemTree.add(Entry<KeyType, ValueType>(searchKey, newValue));
   else
      auto message = "Attempt to add an entry whose search key exists in dictionary.";
      throw(PrecondViolatedExcept(message)); // Exit the method
      // end if
      end add
```

### Selecting an Implementation

- Linear Implementations
  - Perspective
  - Efficiency
  - Motivation

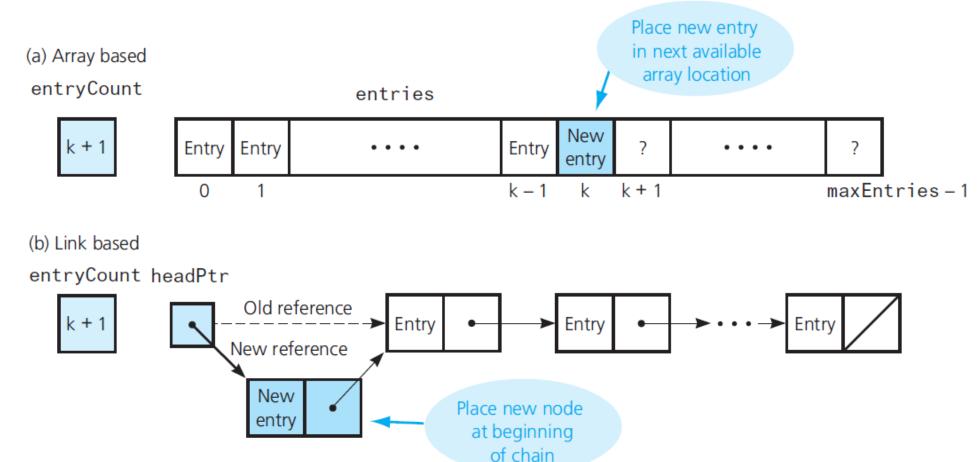
#### Selecting an Implementation

- Linear Implementations
  - Perspective
  - Efficiency
  - Motivation
- Consider
  - What operations are needed
  - · How often each operation is required

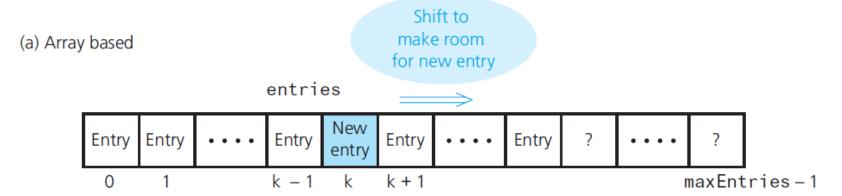
- Scenario A: Addition and traversal in no particular order
- Scenario B: Retrieval
- Scenario C: Addition, removal, retrieval, traversal in sorted order

- Scenario A: Addition and traversal in no particular order
  - Unsorted order is efficient
  - Array-based versus pointer-based
- Scenario B: Retrieval
  - Sorted array-based can use binary search
  - Binary search impractical for link-based
  - Max size of dictionary affects choice
- Scenario C: Addition, removal, retrieval, traversal in sorted order
  - Add and remove need to find position, then add or remove from that position
  - Array-based best for find tasks, link-based best for addition/removal

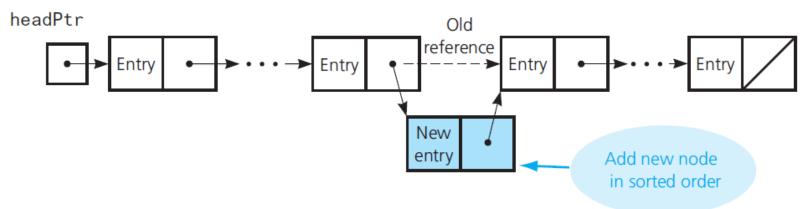
Addition for unsorted linear implementations



Addition for sorted linear implementations







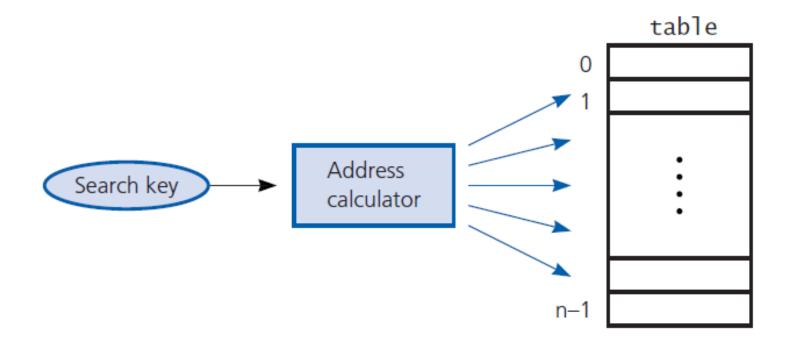
• The average-case order of the ADT dictionary operations for various implementations

Blank	Addition	Removal	Retrieval	Traversal
Unsorted array-based	O(1)	O(n)	O(n)	O(n)
Unsorted link-based	O(1)	O(n)	O(n)	O(n)
Sorted array-based	O(n)	O(n)	O(log n)	O(n)
Sorted link-based	O(n)	O(n)	O(n)	O(n)
Binary search tree	O(log n)	O(log n)	O(log n)	O(n)

- Situations occur for which search-tree implementations are not adequate.
- Consider a method which acts as an "address calculator" which determines an array index
  - Used for add, getValue, remove operations

- Situations occur for which search-tree implementations are not adequate.
- Consider a method which acts as an "address calculator" which determines an array index
  - Used for add, getValue, remove operations
- Called a hash function
  - Tells where to place item in a hash table

Address calculator

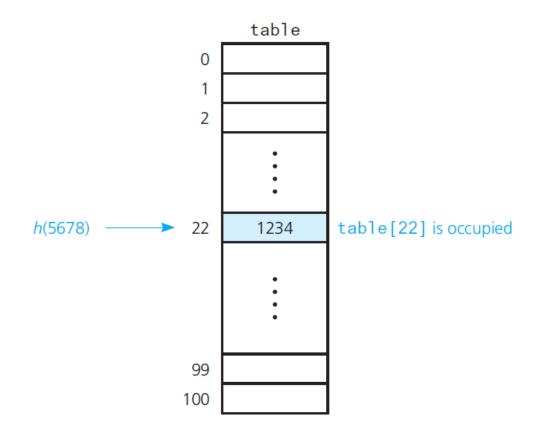


- Perfect hash function
  - Maps each search key into a unique location of the hash table
  - Possible if you know all the search keys
- Collision occurs when hash function maps more than one entry into the same array location
- Hash function should
  - Be easy, fast to compute
  - Place entries evenly throughout hash table

#### Hash Functions

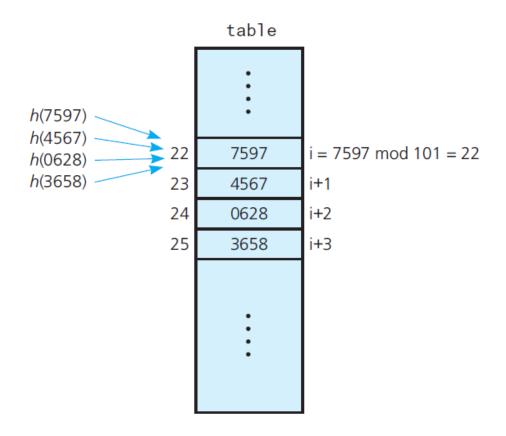
- Sufficient for hash functions to operate on integers examples:
  - Select digits from an ID number
  - Folding add digits, sum is the table location
  - Module arithmetic  $h(x) = x \mod tableSize$
  - Convert character string to an integer use ASCII values

A collision

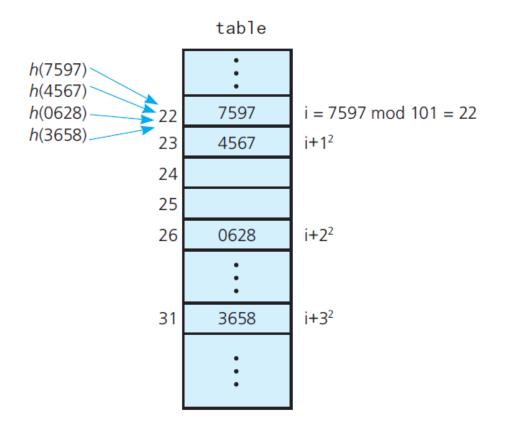


- Approach 1: Open addressing
  - Linear probing
  - Quadratic probing
  - Double hashing
  - Increase size of hash table

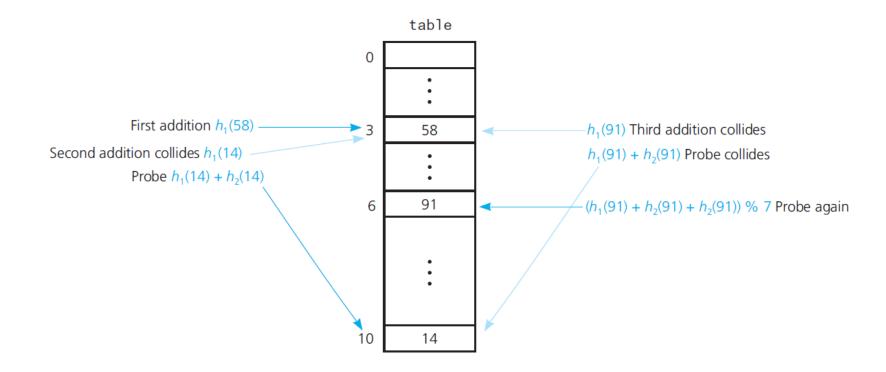
• Linear probing with  $h(x) = x \mod 101$ 



• Quadratic probing with  $h(x) = x \mod 101$ 



Double hashing during the addition of 58, 14, and 91

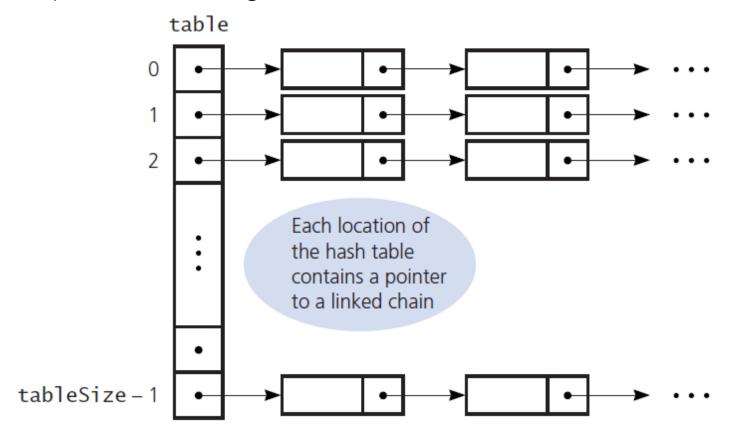


## Resolving Collisions with Open Addressing

- Approach 2: Resolving collisions by restructuring the hash table
  - Buckets
  - Separate chaining

## Resolving Collisions with Open Addressing

Separate chaining



Load factor measures how full a hash table is

$$a = \frac{Current\ number\ of\ table\ entries}{tableSize}$$

- Unsuccessful searchers
  - Generally require more time than successful
- Do not let the hash table get too full

Linear probing – average number of comparisons

$$\frac{1}{2} \left[ 1 + \frac{1}{1 - \alpha} \right]$$
 For a successful search

$$\frac{1}{2} \left[ 1 + \frac{1}{(1-\alpha)^2} \right]$$
 For an unsuccessful search

Quadratic probing and double hashing – average number of comparisons

$$\frac{-\log_{\rm e}(1-\alpha)}{\alpha}$$

For a successful search

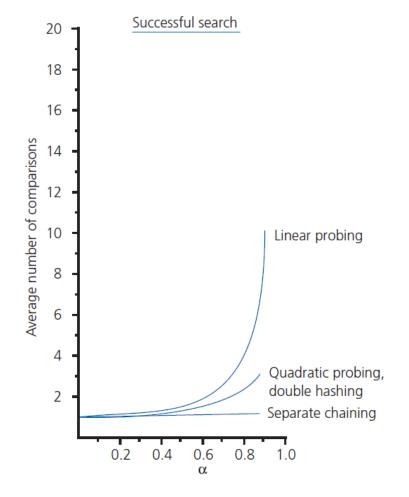
For an unsuccessful search

Efficiency of the retrieval and removal operations under the separate-chaining approach

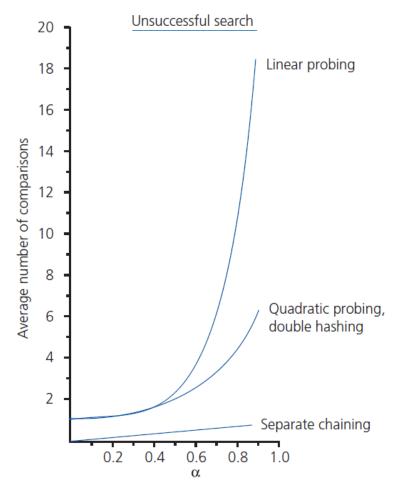
$$1 + \frac{\alpha}{2}$$
 For a successful search

C For an unsuccessful search

The relative efficiency of four collision-resolution methods



• The relative efficiency of four collision-resolution methods



Is the hash function easy and fast to compute?

- Is the hash function easy and fast to compute?
- Does the hash function scatter data evenly throughout the hash table?

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- How well does the hash function scatter random data?

- Is the hash function easy and fast to compute?
- Does the hash function scatter data evenly throughout the hash table?
- How well does the hash function scatter random data?
- How well does the hash function scatter non-random data?

# Dictionary Traversal: An Inefficient Operation Under Hashing

- Entries hashed into table[i] and table[i+1] have no ordering relationship
- Hashing does not support well traversing a dictionary in sorted order
  - Generally better to use a search tree
- In external storage possible to see
  - Hashing implementation of getValue
  - And search-tree for ordered operations simultaneously

# Using Hashing, Separate Chaining to Implement the ADT Dictionary

A dictionary entry when separate chaining is used



## Using Hashing, Separate Chaining to Implement the ADT Dictionary

A header file for the class HashedEntry

# Sorted Array-based Implementation of ADT Dictionary

A header file for the class HashedEntry

### Thank you