



THE UNIVERSITY OF THE WEST INDIES

EXAMINATIONS OF DECEMBER 2006

Code and Name of Course: ECNG 3006 Microprocessor Systems Design and Applications Paper:

Date and Time: Duration: Three Hours

INSTRUCTIONS TO CANDIDATES: This paper has 3 pages and 4 questions

Answer ALL questions.  
Q1 is worth 12 marks.  
Q2 is worth 13 marks.  
Q4 is worth 11 marks.  
Q4 is worth 14 marks.

- Q1. (a) The FreeRTOS real-time kernel allows the use of two types of scheduling algorithms: pre-emptive and cooperative. Its features include semaphores and message queues.
- i. Contrast the two types of scheduling algorithms that can be used in FreeRTOS. 2 marks
  - ii. Give an example each of the use of semaphores and message queues. 2 marks
- (b) The functions, xQueueSendFromISR and xSemaphoreGiveFromISR, return a value, which is either pdTRUE or pdFALSE.
- i. When this value is pdTRUE, what does it signify? 1 mark
  - ii. Create code to illustrate the use of the returned value from xSemaphoreGiveFromISR. Assume that there is a task waiting on the release of the semaphore **xSemaphoreEvent**. 5 marks
- (c) Code, created to service an external event, releases an aperiodic task. The task is currently on the message queue receive task-waiting list. When the event occurs, a message is posted on the empty message queue. What will happen after a message is posted on the message queue? 2 marks
- Q2. (a) Real-time systems can be classified according to their timing attributes as purely cyclic, mostly cyclic, asynchronous and somewhat predictable, and asynchronous and unpredictable. Describe **TWO** of these classifications. 2 marks
- (b) With respect to the periodic task model, give the meaning of the following terms:
- i. Release time,  $r_i$  of a job
  - ii. Absolute deadline,  $d_i$  of a job
  - iii. Relative deadline,  $D_i$  of a job
  - iv. Execution time,  $e_i$  of a job

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- v. Period,  $p_i$ , of periodic task

vi. Phase,  $\phi_i$ , of periodic task

vii. Hyperperiod,  $H_i$ , of periodic tasks
- 7 marks
- (c) There are four periodic tasks. The tasks have execution times of 1, 1, 2 and 3 respectively. The tasks have periods of 8, 8, 9 and 12 respectively. Calculate the total utilisation of all the tasks.

3 marks
- (d) Explain release-time jitter (or jitter in release time).

1 mark
- Q3. The Reference Model for real-time systems characterises each system according to a workload model, a resource model and scheduling algorithms.

(a) Name the graph, explored in this course, which can describe the resource model. Also, in your own words, explain how this graph describes the resource model.

2 marks

(b) Preemptivity and criticality are two functional parameters used to describe jobs. Explain these two parameters.

2 marks

(c) Contrast off-line and on-line scheduling.

3 marks

(d) In an article, an engineer wrote:  
"The application contains only hard real-time periodic jobs. A static, clock-driven scheduling approach is chosen to implement this application. This scheduling approach can be classified as an on-line scheduling approach."  
i. What additional information is needed to validate the engineer's choice of a static, clock-driven scheduling approach?

1 mark

ii. Do you agree or disagree with the engineer's view that this system uses on-line scheduling? Justify your answer.

1 mark

(e) Identify one dynamic priority-driven scheduling approach and state whether it typically uses on-line or off-line scheduling.

2 marks

Q4. (a) i. Explain the Latest Release Time (LRT) scheduling approach.

1 mark

ii. Is the Latest Release Time (LRT) scheduling approach a priority-driven algorithm? Justify your answer.

1 mark
- The diagram is a precedence graph with seven nodes representing jobs. Each node is labeled with its job ID, execution time, release time, and deadline in the format  $J_i, e_i (r_i, d_i]$ . The nodes are:  $J_1, 3 (0, 6]$ ,  $J_2, 3 (1, 9]$ ,  $J_3, 3 (1, 13]$ ,  $J_4, 2 (1, 10]$ ,  $J_5, 2 (2, 12]$ ,  $J_6, 1 (2, 11]$ , and  $J_7, 1 (3, 16]$ . Directed edges represent precedence constraints:  $J_1 \rightarrow J_2$ ,  $J_2 \rightarrow J_3$ ,  $J_4 \rightarrow J_5$ ,  $J_5 \rightarrow J_3$ , and  $J_6 \rightarrow J_7$ .
- Figure 1: Precedence Graph for Q4(b)i
- (b) In the precedence graph for a set of jobs shown in Figures 1 and 2, each job is given as  $J_i, e_i (r_i, d_i]$ , where  $e_i$  is the execution time,  $r_i$  is the release time and  $d_i$  is the deadline. Use the precedence graph in Figure 1 to answer part Q4(b)i. Use the precedence graph in Figure 2 to answer parts Q4(b)ii, Q4(b)iii .

i. Does a feasible schedule exist for the precedence graph in Figure 1? Show all reasoning.

4 marks

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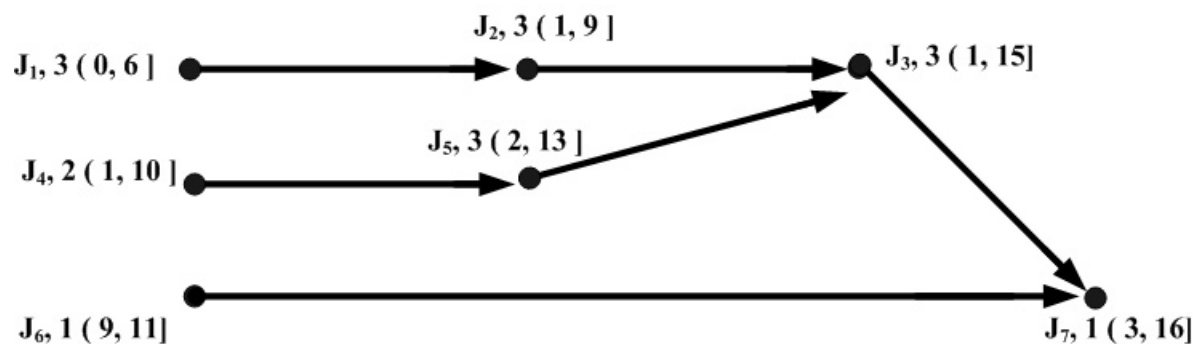


Figure 2: Precedence Graph for Q4(b)ii, Q4(b)iii

- ii. Using a non-preemptive Earliest Deadline First(EDF) scheduling algorithm produce the schedule for the precedence graph in Figure 2.

4 marks
- iii. Using a pre-emptive Least Slack Time First(LST) scheduling algorithm produce the schedule for the precedence graph in Figure 2.

4 marks

END OF QUESTION PAPER

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