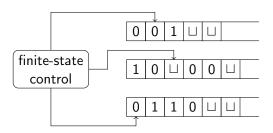
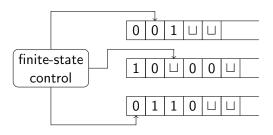
# CIS 770: Formal Language Theory

Pavithra Prabhakar

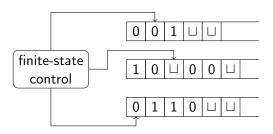
Kansas State University

Spring 2016

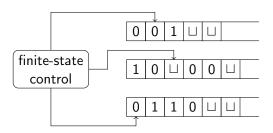




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- $\delta: (Q \setminus \{q_{acc}, q_{rej}\}) \times \Gamma^k \to Q \times (\Gamma \times \{L, R\})^k$  is the transition function.

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### Challenges

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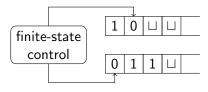
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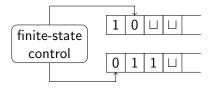
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Multi-tape TM M

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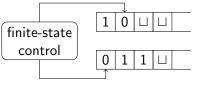
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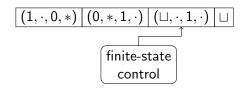
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1-tape equivalent single(M)

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• Once again, scan the tape, change all relevant contents, "move" heads (i.e., move \*s), and change state.

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Formal construction in notes.



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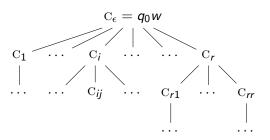
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- Idea 1: det(M) tries to keep track of all possible "configurations" that M could possibly be after each step.
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- Idea 2: det(M) will simulate M on each possible sequence of computation steps that M may try in each step.

# Nondeterministic Computation

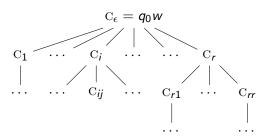
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- Input w is accepted iff  $\exists$  accepting configuration in tree.



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Observe that det(M) may not terminate if w is not accepted.

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- Tape 1, called input tape, will always hold input w
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- Tape 3, called choice tape, will store the current sequence of nondeterministic choices

# Execution of det(M)

- Initially: Input tape contains w, simulation tape and choice tape are blank
- Copy contents of input tape onto simulation tape
- $\odot$  Simulate M using simulation tape as its (only) tape
  - At the next step of M, if state is q, simulation tape head reads X, and choice tape head reads i, then simulate the ith possibility in  $\delta(q,X)$ ; if i is not a valid choice, then goto step 4
  - ② After changing state, simulation tape contents, and head position on simulation tape, move choice tape's head to the right. If Tape 3 is now scanning □, then goto step 4
  - **9** If M accepts then accept and halt, else goto step 3(1) to simulate the next step of M.
- Write the lexicographically next choice sequence on choice tape, erase everything on simulation tape and goto step 2.



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- If M does not accept w then no sequence of choices leads to acceptance. det(M) will therefore never halt!

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• Initially, the program instructions are stored in a contiguous block of memory locations starting at location 1. All registers and memory locations, other than those storing the program, are set to 0.

#### Instruction Set

- add X, Y: Add the contents of registers X and Y and store the result in X.
- loadc X, I: Place the constant I in register X.
- load X, M: Load the contents of memory location M into register X.
- loadI X, M: Load the contents of the location "pointed to" by the contents of M into register X.
- store X, M: store the contents of register X in memory location M.
- jmp M: The next instruction to be executed is in location M.
- jmz X, M: If register X is 0, then jump to instruction M.
- halt: Halt execution.



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Proof sketch in the notes.

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- Enhanced Turing Machine models: TM with 2-way infinite tape, multi-tape TM, nondeterministic TM, probabilistic Turing Machines, quantum Turing Machines . . .
- Restricted Turing Machine models: queue machines, 2-stack machines, 2-counter machines, . . .

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- To show that something can be solved on Turing machines, you can use any programming language of choice, unless the problem specifically asks you to design a Turing Machine