



LECTURE 9 OF 42

Game Tree Search: Minimax and Alpha-Beta ($\alpha - \beta$) Pruning

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KSOL course page: <http://snipurl.com/v9v3>

Course web site: <http://www.kddresearch.org/Courses/CIS730>

Instructor home page: <http://www.cis.ksu.edu/~bhsu>

Reading for Next Class:

Section 7.1 – 7.4, p. 194 - 210, Russell & Norvig 2nd edition

Outside reference:

University of Alberta GAMES page – <http://www.cs.ualberta.ca/~games/>



LECTURE OUTLINE

- **Reading for Next Class:** 7.1 – 7.4 (p. 194 – 210), R&N 2^e
- **Last Class,** 5.4-5.5, p. 151-158; Games Intro, 6.1-6.3, p. 161-174
 - * Third CSP algorithm: constraint propagation by arc consistency (AC-3)
 - * “One-step” vs. “all-steps” lookahead
- **Today: Game Tree Search**
 - * Rudiments of game theory
 - * Minimax with alpha-beta ($\alpha - \beta$) pruning
 - * Perfect information vs. imperfect information
- **Need for Expectiminimax**
 - * Games of chance: dealing with nondeterminism
 - * Imperfect information
- **Game Analysis**
 - * Quiescence
 - * Horizon effect
 - * “Averaging over clairvoyance” and when/why it fails
- **Next Class: From Search to Knowledge Representation**



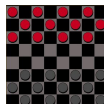


TYPES OF GAMES: REVIEW

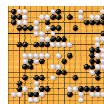
	deterministic	chance
perfect information	chess, checkers, go, othello	backgammon monopoly
imperfect information	battleship, blind tictactoe	bridge, poker, scrabble nuclear war



Chess
<http://tr.im/zdTD>



Checkers
<http://tr.im/zdTW>



Go
<http://tr.im/zdVn>



Reversi (Othello)
<http://tr.im/zdVr>



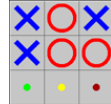
Backgammon
<http://tr.im/ze1P>



Monopoly © Parker Brothers
<http://tr.im/ze2F>



Battleship © Milton Bradley
<http://tr.im/zdWK>



Tic-Tac-Toe
<http://tr.im/zdXB>



Contract Bridge
<http://tr.im/ze5D>



Poker (Texas Hold 'Em)
<http://tr.im/ze7W>



Scrabble © Hasbro
<http://tr.im/ze90>

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ALPHA-BETA (α - β) PRUNING — EXAMPLE: REVIEW

What are α , β values here?

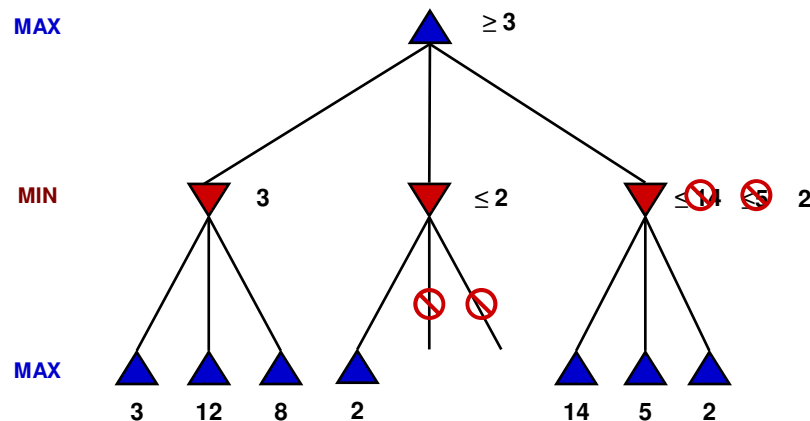


Figure 6.5 p. 168 R&N 2^e

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MINIMAX WITH α - β PRUNING – ALGORITHM: REVIEW

function **ALPHA-BETA-DECISION**(*state*) returns an action
 return the *a* in **ACTIONS**(*state*) maximizing **MIN-VALUE**(**RESULT**(*a*, *state*))

function **MAX-VALUE**(*state*, α , β) returns a utility value
 inputs: *state*, current state in game
 α , the value of the best alternative for MAX along the path to *state*
 β , the value of the best alternative for MIN along the path to *state*
 if **TERMINAL-TEST**(*state*) then return **UTILITY**(*state*)
 $v \leftarrow -\infty$
 for *a*, *s* in **SUCCESSORS**(*state*) do
 $v \leftarrow \text{MAX}(v, \text{MIN-VALUE}(s, \alpha, \beta))$
 if $v \geq \beta$ then return *v*
 $\alpha \leftarrow \text{MAX}(\alpha, v)$
 return *v*

function **MIN-VALUE**(*state*, α , β) returns a utility value
 same as **MAX-VALUE** but with roles of α , β reversed

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WHY IS IT CALLED α - β ?

MAX

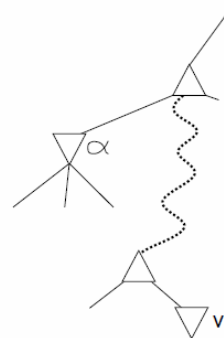
MIN

...

...

MAX

MIN



α is the best value (to MAX) found so far off the current path

If V is worse than α , MAX will avoid it \Rightarrow prune that branch

Define β similarly for MIN

Figure 6.6 p. 169 R&N 2^e

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DEPTH LIMIT RATIONALE: REVIEW

Pruning **does not** affect final result

Good move ordering improves effectiveness of pruning

With “perfect ordering,” time complexity = $O(b^{m/2})$
 \Rightarrow **doubles** solvable depth

A simple example of the value of reasoning about which computations are relevant (a form of metareasoning)

Unfortunately, 35^{50} is still impossible!

- **Can We Do Better?**
- **Idea: Adapt Resource-Bounded Heuristic Search Techniques**
 - * **Depth-limited**
 - * **Iterative deepening**
 - * **Memory-bounded**

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RESOURCE LIMITS AND LIMITED-PLY SEARCH

Standard approach:

- Use CUTOFF-TEST instead of TERMINAL-TEST
e.g., depth limit (perhaps add quiescence search)
- Use EVAL instead of UTILITY
i.e., **evaluation function** that estimates desirability of position

Suppose we have 100 seconds, explore 10^4 nodes/second

$\Rightarrow 10^6$ nodes per move $\approx 35^{8/2}$

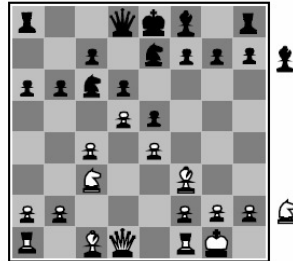
$\Rightarrow \alpha\text{-}\beta$ reaches depth 8 \Rightarrow pretty good chess program

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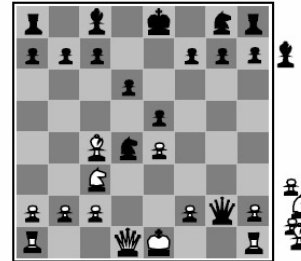


STATIC EVALUATION FUNCTIONS: REVIEW



Black to move

White slightly better



White to move

Black winning

For chess, typically linear weighted sum of features

$$Eval(s) = w_1 f_1(s) + w_2 f_2(s) + \dots + w_n f_n(s)$$

e.g., $w_1 = 9$ with

$f_1(s) = (\text{number of white queens}) - (\text{number of black queens}), \text{ etc.}$

Figure 6.8 p. 173 R&N 2^e

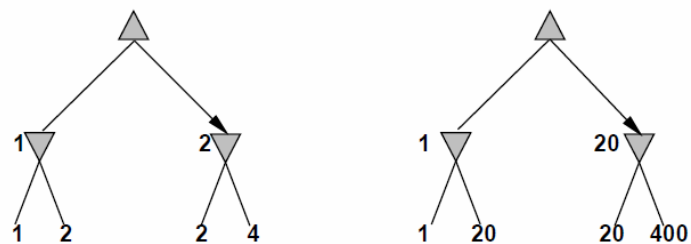
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DIGRESSION: EXACT VALUES DON'T MATTER

MAX

MIN



Behaviour is preserved under any **monotonic** transformation of EVAL

Only the order matters:

payoff in deterministic games acts as an **ordinal utility** function

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QUIESCENCE AND THE HORIZON EFFECT

- **Issues**

- * **Quiescence**

- ⇒ Play has “settled down”
 - ⇒ Evaluation function unlikely to exhibit wild swings in value in near future

- * **Horizon effect**

- ⇒ “Stalling for time”
 - ⇒ Postpones inevitable win or damaging move by opponent
 - ⇒ See: Figure 6.9, p. 175 R&N 2^e

- **Solutions?**

- * **Quiescence search: expand non-quiet positions further**
 - * **No general solution to horizon problem at present**

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DETERMINISTIC GAMES IN PRACTICE

Checkers: Chinook ended 40-year-reign of human world champion Marion Tinsley in 1994. Used an endgame database defining perfect play for all positions involving 8 or fewer pieces on the board, a total of 443,748,401,247 positions.

Chess: Deep Blue defeated human world champion Gary Kasparov in a six-game match in 1997. Deep Blue searches 200 million positions per second, uses very sophisticated evaluation, and undisclosed methods for extending some lines of search up to 40 ply.

Othello: human champions refuse to compete against computers, who are too good.

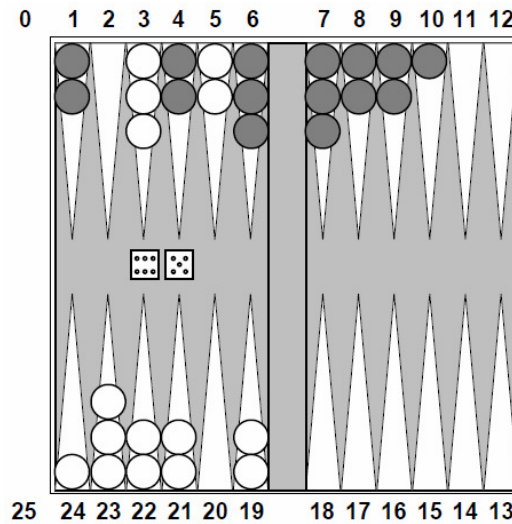
Go: human champions refuse to compete against computers, who are too bad. In go, $b > 300$, so most programs use pattern knowledge bases to suggest plausible moves.

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NONDETERMINISTIC GAMES: BACKGAMMON



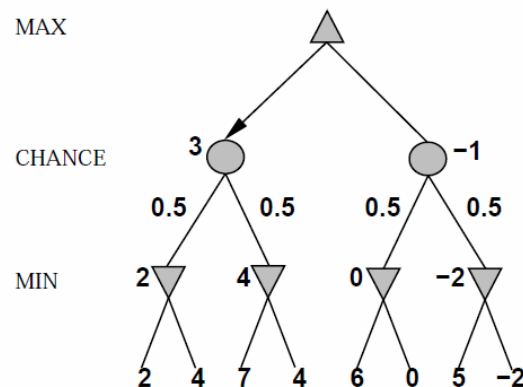
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NONDETERMINISTIC GAMES IN GENERAL

In nondeterministic games, chance introduced by dice, card-shuffling

Simplified example with coin-flipping:



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EXPECTIMINIMAX: ALGORITHM FOR NONDETERMINISTIC GAMES

EXPECTIMINIMAX gives perfect play

Just like MINIMAX, except we must also handle chance nodes:

```
...
if state is a MAX node then
    return the highest EXPECTIMINIMAX-VALUE of SUCCESSORS(state)
if state is a MIN node then
    return the lowest EXPECTIMINIMAX-VALUE of SUCCESSORS(state)
if state is a chance node then
    return average of EXPECTIMINIMAX-VALUE of SUCCESSORS(state)
...
```

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NONDETERMINISTIC GAMES IN PRACTICE

Dice rolls increase b : 21 possible rolls with 2 dice

Backgammon ≈ 20 legal moves (can be 6,000 with 1-1 roll)

$$\text{depth } 4 = 20 \times (21 \times 20)^3 \approx 1.2 \times 10^9$$

As depth increases, probability of reaching a given node shrinks

\Rightarrow value of lookahead is diminished

α - β pruning is much less effective

TDGAMMON uses depth-2 search + very good EVAL

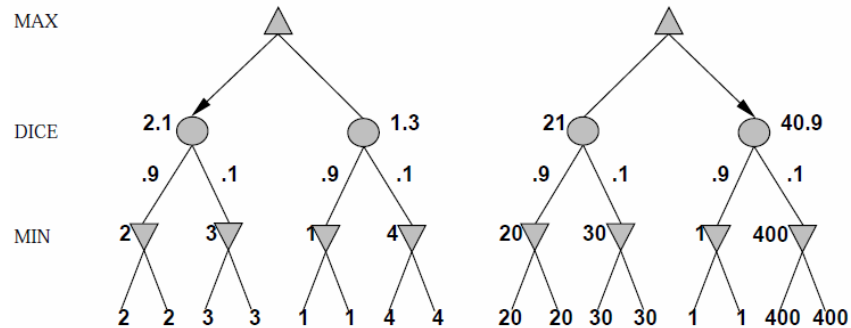
\approx world-champion level

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DIGRESSION: EXACT VALUES DO MATTER



Behaviour is preserved only by positive linear transformation of EVAL

Hence EVAL should be proportional to the expected payoff

Figure 6.12 p. 178 R&N 2^e

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GAMES OF IMPERFECT INFORMATION [1]: SOLUTION APPROACH

E.g., card games, where opponent's initial cards are unknown

Typically we can calculate a probability for each possible deal

Seems just like having one big dice roll at the beginning of the game*

Idea: compute the minimax value of each action in each deal,
then choose the action with highest expected value over all deals*

Special case: if an action is optimal for all deals, it's optimal.*

GIB, current best bridge program, approximates this idea by

- 1) generating 100 deals consistent with bidding information
- 2) picking the action that wins most tricks on average

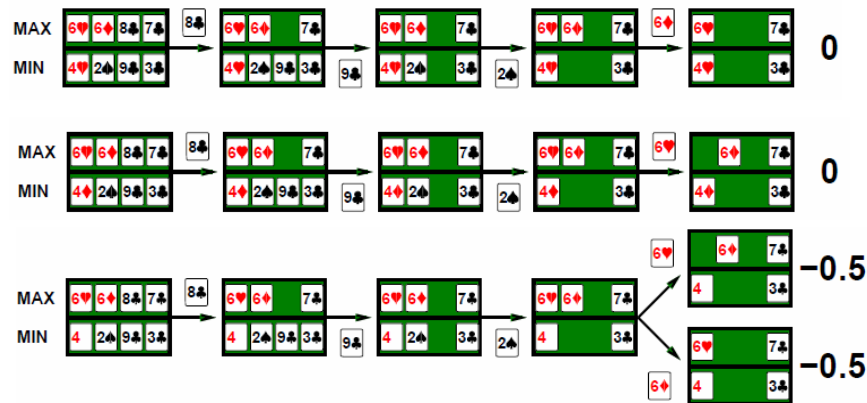
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GAMES OF IMPERFECT INFORMATION [2]: EXAMPLE

Four-card bridge/whist/hearts hand, MAX to play first



Similar to example on p. 179 R&N 2^e

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COMMONSENSE EXAMPLE [1]: STATEMENT

Day 1 Road A leads to a small heap of gold pieces
Road B leads to a fork:
take the left fork and you'll find a mound of jewels;
take the right fork and you'll be run over by a bus.

Day 2 Road A leads to a small heap of gold pieces
Road B leads to a fork:
take the left fork and you'll be run over by a bus;
take the right fork and you'll find a mound of jewels.

Day 3 Road A leads to a small heap of gold pieces
Road B leads to a fork:
guess correctly and you'll find a mound of jewels;
guess incorrectly and you'll be run over by a bus.

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COMMONSENSE EXAMPLE [2]: PROPER ANALYSIS

* Intuition that the value of an action is the average of its values in all actual states is **WRONG**

With partial observability, value of an action depends on the information state or belief state the agent is in

Can generate and search a tree of information states

Leads to rational behaviors such as

- ◇ Acting to obtain information
- ◇ Signalling to one's partner
- ◇ Acting randomly to minimize information disclosure

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GAMES: SUMMARY

Games are fun to work on! (and dangerous)

They illustrate several important points about AI

- ◇ perfection is unattainable \Rightarrow must approximate
- ◇ good idea to think about what to think about
- ◇ uncertainty constrains the assignment of values to states
- ◇ optimal decisions depend on information state, not real state

Games are to AI as grand prix racing is to automobile design

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TERMINOLOGY

- **Game Tree Search**
 - * Zero-sum games
 - * 2-player vs. n -player
- **Minimax Algorithm: Alternates between MAX and MIN Players**
- **Alpha-Beta Pruning (α - β Pruning)**
 - * α : best value to MAX found so far *off* current path (v worse than $\alpha \Rightarrow$ prune)
 - * β : best value to MIN found so far *off* current path
- **Resource-Bounded Minimax**
 - * Static evaluation function
 - * Limited-ply search (compare: depth-limited search *aka* DLS)
 - * Iterative deepening search (compare: ID-DFS, IDA*)
- **Expectiminimax**
 - * Based on expectation
 - * Games with chance
 - * Games with imperfect information



SUMMARY POINTS

- **Game Theory Continued**
 - * Game tree representation
 - * Perfect play: Minimax algorithm, speedup with alpha-beta (α - β) pruning
 - * Resource-bounded Minimax: static evaluation functions, iterative deepening
 - * Emphasis: two-player (with exceptions), zero-sum, perfect info
- **Alpha-Beta Pruning (α - β Pruning)**
- **Resource-Bounded Minimax**
 - * Need for static evaluation (compare: heuristics)
 - * Limited-ply search (compare: depth-limited search *aka* DLS)
 - * Iterative deepening search (compare: ID-DFS, IDA*)
- **Expectiminimax**
 - * Based on expectation
 - * Games with chance
 - * Games with imperfect information
- **Significance of Games to AI**
 - * Understanding representation, reasoning, and learning
 - * Finding out what approximations, refinements, abstractions work

