

Theorem A matrix  $A$  is Hurwitz, i.e.  $\operatorname{Re}(\lambda_i) < 0 \quad \forall \lambda_i \in \sigma(A)$ , if (5.3) and only if for any given positive definite symmetric matrix  $Q$  there exists a positive definite symmetric matrix  $P$  that satisfies the Lyapunov equation (2). Moreover, if  $A$  is Hurwitz, then  $P$  is the unique solution to (2).

Proof The sufficiency follows from the Lyapunov theorem with  $V(x) = \frac{1}{2} x^T P x$ . To prove necessity, assume that all eigenvalues of  $A$  satisfy  $\operatorname{Re}(\lambda_i) < 0$  and consider the matrix  $P$  defined by

$$(3) \quad P = \int_0^{\infty} \exp(A^T t) Q \exp(At) dt$$

The integrand is a sum of terms  $t^{k-1} \exp(\lambda_i t)$ , where  $\operatorname{Re}(\lambda_i) < 0$ , and therefore the integral exists. The matrix  $P$  is symmetric and positive definite. In fact

$$\begin{aligned} \text{i) } P^T &= \int_0^{\infty} (\exp(A^T t) Q \exp(At))^T dt = \int_0^{\infty} \exp(\bar{A}^T t) Q^T \exp(At) dt = P, \quad Q = Q^T \\ \text{ii) } x^T P x &= \int_0^{\infty} x^T \exp(A^T t) Q \exp(At) x dt = \int_0^{\infty} \underbrace{y(t)^T Q y(t)}_{\geq 0 \text{ since } Q \succ 0} dt \geq 0 \end{aligned}$$

Positive  
Semi  
Definite

$y(t) := \exp(At) x$

To show that  $P$  is positive definite, we have to show that  $x=0$  is the only solution to  $y=0$ , which is implied by

$$\det(\exp(At)) \neq 0; \quad \det(\exp(At)) = \det(T \exp(\Lambda t) T^{-1}) \neq 0$$

$\Lambda = \begin{pmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_m \end{pmatrix}$

Now, by substituting (3) into (2) we obtain

$$\begin{aligned} & \int_0^{\infty} \exp(A^T t) Q \exp(At) A dt + \int_0^{\infty} A^T \exp(A^T t) Q \exp(At) dt = \\ & = \int_0^{\infty} \frac{d}{dt} \left[ \exp(A^T t) Q \exp(At) \right] dt = \exp(A^T t) Q \exp(At) \Big|_0^{\infty} = -Q, \end{aligned}$$

which shows that  $P$  is a solution to (2). To show that it is the unique solution, suppose there exists another solution  $\bar{P} \neq P$ . Then

$$(P - \bar{P})A + A^T(P - \bar{P}) = 0.$$

Pre-multiplying and post-multiplying by  $\exp(At)$  yields

$$0 = \exp(A^T t) \left[ (P - \bar{P})A + A^T(P - \bar{P}) \right] \exp(At)$$

$$= \frac{d}{dt} \left[ \exp(A^T t) (P - \bar{P}) \exp(At) \right] \Rightarrow$$

$\exp(A^T t) (P - \bar{P}) \exp(At) = a$ , a constant matrix. In particular, since

$\exp(A \cdot 0) = I$ , one has

$$P - \bar{P} = \exp(A^T t) (P - \bar{P}) \exp(At) \rightarrow 0 \Rightarrow P = \bar{P}.$$



Finding the matrix  $P$  is no easier than evaluating the eigenvalues of  $A$ . However, the above arguments can be used to assess the stability of  $x=0$  when  $\dot{x} = Ax$  is perturbed. This perturbation

Consider now

$$V(x) = \frac{1}{2} x^T P x \Rightarrow \dot{V}(x) = -|x|^2 + x^T P R(x) \Rightarrow$$

$$\dot{V}(x) \leq -|x|^2 + |x| |P| |R(x)|. \text{ The property that } \lim_{|x| \rightarrow 0} \frac{|R(x)|}{|x|} = 0 \Leftrightarrow$$

$$\forall \varepsilon > 0 \exists \delta(\varepsilon): |x| < \delta(\varepsilon) \Rightarrow \frac{|R(x)|}{|x|} < \varepsilon$$

This means that if  $x \in B_{\delta(\varepsilon)}$ , i.e. on hypersphere of radius  $\delta(\varepsilon)$ ,

then  $\frac{|R(x)|}{|x|} < \varepsilon$ . Choosing  $\varepsilon = \frac{1}{|P|}$ , there exists  $\delta_{\frac{1}{|P|}}$  such that if

$$|x| < \delta_{\frac{1}{|P|}}, \text{ then } \frac{|R(x)|}{|x|} < \frac{1}{|P|} \Rightarrow |R(x)| < \frac{|x|}{|P|} \Rightarrow$$

$$\dot{V}(x) < -|x|^2 + |x| |P| \frac{|x|}{|P|} = 0 \quad \text{if} \quad |x| < \delta_{\frac{1}{|P|}} \Rightarrow \text{P.A.S.}$$

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can represent higher order terms of the linearization of a nonlinear system.

Theorem Let  $x=0$  be an equilibrium point for the nonlinear system

$$\dot{x} = f(x)$$

where  $f: D \rightarrow \mathbb{R}^n$  is continuously differentiable and  $D$  a neighborhood of the origin. Let

$$A := \left. \frac{\partial f}{\partial x} \right|_{x=0}$$

Then,

- i) The origin is L.A.S. (locally asymptotically stable) if  $\text{Re}(\lambda_i) < 0$  for all eigenvalues of  $A$ .
- ii) The origin is unstable if  $\text{Re}(\lambda_i) > 0$  for one or more of the eigenvalues of  $A$ .

Proof of i) The dynamics  $\dot{x} = f(x)$  can be approximated as

$$\begin{aligned} \dot{x} &= f(0) + \left. \frac{\partial f}{\partial x} \right|_{x=0} x + R(x) \\ &= Ax + R(x) \quad \text{where } R(x) \text{ satisfies } \lim_{|x| \rightarrow 0} \frac{|R(x)|}{|x|} = 0 \end{aligned}$$

Now, by assumption all eigenvalues of  $A$  satisfy  $\text{Re}(\lambda_i) < 0$ . Hence,  $A$  is Hurwitz and there exists  $P$  such that  $P = P^T > 0$

$$PA + A^T P = -I$$