



# **N83624 Series Programming Guide Modbus Protocol**

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# 1 Preface

Dear Customers,

First of all, we greatly appreciate your choice of N83624 series battery simulator (N83624 for short). We are also honored to introduce our company, Hunan Next Generation Instrumental T&C Tech. Co.,Ltd. ( NGI for short).

## **About Company**

NGI is a professional manufacturer of intelligent equipment and test & control instruments, committed to developing, manufacturing battery simulators, power supplies, electronic loads, and many more instruments. The products can be widely used in the industries of battery, power supply, fuel cell, consumer electronics, new energy vehicle, semiconductor, etc.

NGI maintains close cooperation with many universities and scientific research institutions, and maintains close ties with many industry leaders. We strive to develop high-quality, technology-leading products, provide high-end technologies, and continue to explore new industry measurement and control solutions.

## **About Manual**

This manual is applied to N83624 series battery simulator, including programming guide based on standard Modbus protocol. The copyright of the manual is owned by NGI. Due to the upgrade of instrument, this manual may be revised without notice in future versions.

This manual has been reviewed carefully by NGI for the technical accuracy. The manufacturer declines all responsibility for possible errors in this operation manual, if due to misprints or errors in copying. The manufacturer is not liable for malfunctioning if the product has not correctly been operated.

To ensure the safety and correct use of N83624, please read this manual carefully, especially the safety instructions.

Please keep this manual for future use.

Thanks for your trust and support.

## 2 Safety Instructions

In the operation and maintenance of the instrument, please strictly comply with the following safety instructions. Any performance regardless of attentions or specific warnings in other chapters of the manual may impair the protective functions provided by the instrument.

NGI shall not be liable for the results caused by the neglect of those instructions.
















### 2.1 Safety Notes

- **Confirm the AC input voltage before supplying power.**
- **Reliable grounding:** Before operation, the instrument must be reliably grounded to avoid the electric shock.
- **Confirm the fuse:** Ensure to have installed the fuse correctly.
- **Do not open the chassis:** The operator cannot open the instrument chassis. Non-professional operators are not allowed to maintain or adjust it.
- **Do not operate under hazardous conditions:** Do not operate the instrument under flammable or explosive conditions.
- **Confirm the working range:** Make sure the DUT is within N83624's rated range.

### 2.2 Safety Symbols

Please refer to the following table for definitions of international symbols used on the instrument or in the user manual.

Table 1

Symbol	Definition	Symbol	Definition
	DC (direct current)	N	Null line or neutral line
	AC (alternating current)	L	Live line
	AC and DC	I	Power-on
	Three-phase current		Power-off
	Ground		Back-up power
	Protective ground		Power-on state
	Chassis ground		Power-off state
	Signal ground		Risk of electric shock
WARNING	Hazardous sign		High temperature warning
Caution	Be careful		Warning

### 3 Modbus Overview

Modbus protocol was originally developed by Modicon. At the end of 1979, Modicon became part of Schneider Automation. Now Modbus is the most popular protocol in industrial field. This protocol supports traditional serial link RS-232, RS-422, RS-485 and Ethernet. Many industrial equipment including PLC, DCS, smart meters, etc. are adopting Modbus protocol as the communication standard among them.

Modbus protocol includes ASCII, RTU, TCP, etc., which does not specify the physical layer. This protocol defines the message structure which the controller can recognize and use, regardless of what kind of network they communicate through. The standard Modicon controller uses RS232C to achieve serial Modbus. Modbus's ASCII and RTU protocols stipulate the structure of messages and data, the way of inquiry and answer. The data communication adopts master/slave method. The master station sends out a data request message. The slave station sends data to the master station for responding to the request after receiving the correct message. The master station can also directly send messages to modify the data of slave station to realize bidirectional reading and writing.

If the data format is not easy for understanding, it is recommended to use the tools "Modbus Poll", "Modbus Slave" to send and receive data packets, and "AccessPort" to capture the contents of data packets for analysis.

### 4 Communication Configuration

Communication protocol: standard Modbus

Communication method: LAN, RS232

Default IP address: 192.168.0.123 (It can be adjusted. It will take effect after restart.)

Channel ID: 1-24S

UDP port number: 7000-7024

Note: Port 7000 is communication board, which can also control 24 channels. Port 7001 to 7024 corresponds to channel 1 to 24. It is recommended that users who have requirements for data collection speed communicate through ports 7001-7024.

TCP port number: 7000-7024

Default baud rate: 115200

### 5 Modbus RTU/TCP Description

1) Multiple bytes apply **Big-Endian**.

- 2) The starting addresses of all readable and writable registers are **even** numbers.
- 3) The readable and writable numbers are **even** numbers.
- 4) 4 bytes are applied.  
For example, the value of register address 2 is written as 0x12345678. Then the hexadecimal number of the written data packet is:  
01 10 00 02 00 02 04 **56 78 12 34** EE 90
- 5) The read register adopts the function code 0x03. The write register adopts the function code 0x10. Other function codes are reserved.
- 6) ID in the following ranges from **1 to 248**. Value 255 means a broadcast packet which does not need to be returned.

## 6 Modbus RTU Protocol Format

### 6.1 Master Computer Reading Multiple Registers (0x03)

#### 6.1.1 Master Computer Sending

ID	FunctionCode	StartReg	RegCount	Checksum
----	--------------	----------	----------	----------

Field	No. of Bytes	Definition
ID	1	Device/card ID
FunctionCode	1	Fixed as 0x03
StartReg	2	To read start register
RegCount	2	To read register counts
Checksum	2	CRC value of all data except itself

#### 6.1.2 Slave Computer Correct Return

ID	FunctionCode	RegDataBytes	RegData	Checksum
----	--------------	--------------	---------	----------

Field	No. of Bytes	Definition
ID	1	Device/card ID
FunctionCode	1	Fixed as 0x03
RegDataBytes	1	Register data bytes, RegCount*2 in practice
RegData	2* RegCount	Register data
Checksum	2	CRC value of all data except itself



## 6.2 Master Computer Writing Multiple Registers (0x10)

### 6.2.1 Master Computer Sending

ID	FunctionCode	StartReg	RegCount	RegDataBytes	RegData	Checksum
----	--------------	----------	----------	--------------	---------	----------

Field	No. of Bytes	Definition
ID	1	Device/card ID
FunctionCode	1	Fixed as 0x10
StartReg	2	To write start register
RegCount	2	To write register counts
RegDataBytes	1	Register data bytes, RegCount*2 in practice
RegData	2* RegCount	Register data
Checksum	2	CRC value of all data except itself

### 6.2.2 Slave Computer Correct Return

ID	FunctionCode	StartReg	RegCount	Checksum
----	--------------	----------	----------	----------

Field	No. of Bytes	Definition
ID	1	Device/card ID
FunctionCode	1	Fixed as 0x10
StartReg	2	To write start register
RegCount	2	To write register counts
Checksum	2	CRC value of all data except itself

## 7 Operation

### 7.1 Basic Operation

#### 7.1.1 Status Register

Address: 2

Attribute: RO

Type: Uint32

Byte: 4Byte

Parameters: Bit0: OnOff state

Bit1: ovp (over voltage protection)

Bit2: ocp (over current protection)

Bit3: opp (over power protection)

Bit4: otp (over temperature protection)

Bit5: ofp (Voltage and current present at port when operating fault simulation relay)

Bit6: omp (Allows operation of fault simulation relays in power mode only, other modes are not supported.)

Bit16-18: Real-time range of readback value (0-high range, 2-low range)

### **7.1.2 Event Register**

Address: 2

Attribute: WR

Type: Uint32

Byte: 4Byte

Parameters: Bit0: OnOff state

Bit1: ovp (over voltage protection)

Bit2: ocp (over current protection)

Bit3: opp (over power protection)

Bit4: otp (over temperature protection)

Bit5: ofp (Voltage and current present at port when operating fault simulation relay)

Bit6: omp (Allows operation of fault simulation relays in power mode only, other modes are not supported.)

Bit16-18: Real-time range of readback value (0-high range, 2-low range)

### **7.1.3 Readback Voltage**

Address: 6

Attribute: RO

Type: Float

Byte: 4Byte

### **7.1.4 Readback Current**

Address: 8

Attribute: RO

Type: Float

Byte: 4Byte

### **7.1.5 Readback Power**

Address: 10

Attribute: RO

Type: Float

Byte: 4Byte

### **7.1.6 Readback Resistance**

Address: 12

Attribute: RO

Type: Float

Byte: 4Byte

### **7.1.7 Charging Capacity**

Address: 14

Attribute: RO

Type: Float

Byte: 4Byte

### **7.1.8 ON/OFF Switch**

Address: 20

Attribute: WR

Type: Uint32

Byte: 4Byte

Parameters: 0 for disabling output, 1 for enabling output

### **7.1.9 Function Mode**

Address: 22

Attribute: WR

Type: UInt32

Byte: 4Byte

Parameters: 0: source mode

1: charge mode

3: SOC test mode.

128: SEQ test

Note: Users can select current range in source mode. For other modes, it defaults as high range.

## **7.2 Source Mode**

### **7.2.1 Current Range**

Address: 24

Attribute: WR

Type: UInt32

Byte: 4Byte

Parameters: 0: high range

2: low range

3: auto range

### **7.2.2 Constant Voltage Value**

Address: 40

Attribute: WR

Type: Float

Byte: 4Byte

### **7.2.3 Current Limit Value**

Address: 42

Attribute: WR

Type: Float

Byte: 4Byte

## 7.2.4 Example

Select Source mode and set constant voltage value to 5V, output current limit to 1000mA and current range to auto.

Address	Data Type	Read/Write	Register Value	Description
20	n	WR	0	Shut off output for the selected channel
22	n	WR	0	Set operation mode to Source mode
40	f	WR	5	Set constant voltage value to 5V
42	f	WR	1000	Set output current limit to 1000mA
24	n	WR	3	Select current range to Auto
20	n	WR	1	Enable the output for the selected channel

Note: The ID is same as the selected channel. It is corresponding. For example, the selected channel is 2. The ID is also 2.

## 7.3 Charge Mode

### 7.3.1 Output Voltage Value

Address: 60  
Attribute: WR  
Type: Float  
Byte: 4Byte

### 7.3.2 Output Current Limit Value

Address: 62  
Attribute: WR  
Type: Float  
Byte: 4Byte

### 7.3.3 Resistance Value

Address: 64

Attribute: WR

Type: Float

Byte: 4Byte

### 7.3.4 Readback Voltage

Address: 66

Attribute: RO

Type: Float

Byte: 4Byte

### 7.3.5 Example

Charge mode includes constant voltage value, current limit value and resistance value. Under Charge mode, the current range defaults to high range and nonadjustable.

Select Charge mode and set constant voltage value to 5V, output current limit value to 1000mA and resistance to 3.0mΩ.

Address	Data Type	Read/Write	Register Value	Description
20	n	WR	0	Shut off output for the selected channel
22	n	WR	1	Set operation mode to Charge mode
60	f	WR	5	Set constant voltage value to 5V
62	f	WR	1000	Set output current limit to 1000mA
64	f	WR	3	Set resistance to 3mΩ
20	n	WR	1	Enable the output for the selected channel

Note: The ID is same as the selected channel. It is corresponding. For example, the selected channel is 2. The ID is also 2.

## 7.4 SOC Edit

### 7.4.1 File No.

Address: 98  
Attribute: WR  
Type: Uint32  
Byte: 4Byte  
Parameter: 1-8

### 7.4.2 Total Steps

Address: 100  
Attribute: WR  
Type: Uint32  
Byte: 4Byte  
Parameter: 0-200

### 7.4.3 Step No.

Address: 104  
Attribute: WR  
Type: Uint32  
Byte: 4Byte  
Parameters: 1-200

### 7.4.4 Present Step Capacity

Address: 106  
Attribute: WR  
Type: Float  
Byte: 4Byte  
Parameters: less than capacity value of the previous step

## 7.4.5 Constant Voltage Value

Address: 108

Attribute: WR

Type: Float

Byte: 4Byte

## 7.4.6 Output Current Limit

Address: 116

Attribute: WR

Type: Float

Byte: 4Byte

## 7.4.7 Simulation Internal Resistance

Address: 110

Attribute: WR

Type: Float

Byte: 4Byte

## 7.4.8 Example

SOC simulates battery discharge function by battery simulator output. The parameters for battery discharge need to be set, such as capacity, constant voltage and resistance.

Select SOC mode, set total steps to 3, set below parameters for total three steps.

Step No.	Capacity(mAh)	Constant Voltage(V)	Output Current Limit(mA)	Resistance(mΩ)
1	14	5.0	1200	100
2	13	4.0	1100	100
3	12	3.0	1000	100

Address	Data Type	Read/Write	Register Value	Description
20	n	WR	0	Shut off output for the selected channel
22	n	WR	3	Set operation mode to SOC mode



100	n	WR	3	Set the total steps to 3
104	n	WR	1	Set step No. to 1
106	f	WR	14	Set capacity to 14mAh for step 1
108	f	WR	5	Set constant voltage value to 5.0V for step 1
116	f	WR	1200	Set output current limit to 1200mA for step 1
110	f	WR	100	Set resistance to 100mΩ for step 1
104	n	WR	2	Set step No. to 2
106	f	WR	13	Set capacity to 13mAh for step 2
108	f	WR	4	Set constant voltage value to 4.0V for step 2
116	f	WR	1100	Set output current limit to 1100mA for step 2
110	f	WR	100	Set resistance to 100mΩ for step 2
104	n	WR	3	Set step No. to 3
106	f	WR	12	Set capacity to 12mAh for step 3
108	f	WR	3	Set constant voltage value to 3.0V for step 3
116	f	WR	1000	Set output current limit to 1000mA for step 3
110	f	WR	100	Set resistance to 100mΩ for step 3
118	f	WR	4.8	Set initial voltage to 4.8V
20	n	WR	1	Enable the output for the selected channel
112	n	RO		Obtain present operation step
114	f	RO		Obtain present capacity

## 7.5 SOC Test

### 7.5.1 Initial Capacity

Address: 102

Attribute: RO

Type: Float

Byte: 4Byte

### 7.5.2 Present Step

Address: 112

Attribute: OR

Type: Uint32

Byte: 4Byte

### 7.5.3 Present Step Capacity

Address: 118  
Attribute: WR  
Type: Float  
Byte: 4Byte

### 7.5.4 Open Circuit Voltage

Address: 92  
Attribute: OR  
Type: Float  
Byte: 4Byte

### 7.5.5 Resistance Value for Present Step

Address: 96  
Attribute: OR  
Type: Float  
Byte: 4Byte

## 7.6 SEQ Test

### 7.6.1 SEQ File No.

Address: 120  
Attribute: WR  
Type: Uint32  
Byte: 4Byte  
Parameters: 1-10

### 7.6.2 Total Steps

Address: 126  
Attribute: WR  
Type: Uint32

Byte: 4Byte

Parameters: 0-200

### 7.6.3 File Cycle Times

Address: 128

Attribute: WR

Type: Uint32

Byte: 4Byte

Parameters: 0-100

### 7.6.4 Step No.

Address: 130

Attribute: WR

Type: Uint32

Byte: 4Byte

Parameters: 1-200

### 7.6.5 Constant Voltage Value of Editing Step

Address: 132

Attribute: WR

Type: Float

Byte: 4Byte

### 7.6.6 Current Limit of Editing Step

Address: 134

Attribute: WR

Type: Float

Byte: 4Byte

### 7.6.7 Resistance Value of Editing Step

Address: 136  
Attribute: WR  
Type: Float  
Byte: 4Byte

### 7.6.8 Dwell Time of Editing Step

Address: 138  
Attribute: WR  
Type: Uint32  
Byte: 4Byte

### 7.6.9 Link Start Step

Address: 140  
Attribute: WR  
Type: Uint32  
Byte: 4Byte  
Parameters: -1 to 200. -1 means no link.

### 7.6.10 Link Stop Step

Address: 142  
Attribute: WR  
Type: Uint32  
Byte: 4Byte  
Parameters: -1 to 200. -1 means no link.

### 7.6.11 Link Cycle Times

Address: 144  
Attribute: WR  
Type: Uint32  
Byte: 4Byte  
Parameters: range: 0-100

## 7.6.12 Example

SEQ mode will perform the operation steps one by one in the selected SEQ file. One step can link to another step. Cycle times can also be adjustable.

Select SEQ mode and set SEQ file No. to 1, total steps to 3 and cycle times to 1.

Step No.	Constant Voltage	Current Limit	Resistance	Dwell Time	Link Start Step	Link Stop Step	Link Cycle Times
1	5	500	50	10	-1	-1	0
2	4	800	50	15	-1	-1	0
3	3	1000	50	20	-1	-1	0

Address	Data Type	Read/Write	Register Value	Description
20	n	WR	0	Shut off output for the selected channel
22	n	WR	128	Set operation mode to SEQ Edit
120	n	WR	1	Set SEQ file No. to 1
126	n	WR	3	Set total steps to 3
128	n	WR	1	Set SEQ file cycle times to 1
130	n	WR	1	Set step No. to 1
132	f	WR	5	Set voltage to 5V for step 1
134	f	WR	500	Set current to 500mA for step 1
136	f	WR	50	Set resistance to 50mΩ for step 1
138	f	WR	10	Set dwell time to 10s for step 1
140	n	WR	-1	Set link start step number to -1 for step 1
142	n	WR	-1	Set link stop step number to -1 for step 1
144	n	WR	0	Set link cycle times to 0 for step 1. Zero means no link.
130	n	WR	2	Set step No. to 2
132	f	WR	4	Set voltage to 4V for step 2
134	f	WR	800	Set current to 800mA for step 2
136	f	WR	50	Set resistance to 50mΩ for step 2
138	f	WR	15	Set dwell time to 15s for step 2
140	n	WR	-1	Set link start step number to -1 for step 2
142	n	WR	-1	Set link stop step number to -1 for step 2
144	n	WR	0	Set link cycle times to 0 for step 2. Zero means no link.
130	n	WR	3	Set step No. to 3
132	f	WR	3	Set voltage to 3V for step 3
134	f	WR	1000	Set current to 1000mA for step 3

136	f	WR	50	Set resistance to 50mΩ for step 3
138	f	WR	20	Set dwell time to 20s for step 3
140	n	WR	-1	Set link start step number to -1 for step 3
142	n	WR	-1	Set link stop step number to -1 for step 3
144	n	WR	0	Set link cycle times to 0 for step 3. Zero means no link.

## 7.7 SEQ Test

### 7.7.1 SEQ File No.

Address: 122  
Attribute: WR  
Type: Uint32  
Byte: 4Byte  
Parameters: 1-10

### 7.7.2 Present Step No.

Address: 124  
Attribute: RO  
Type: Uint32  
Byte: 4Byte

### 7.7.3 Present Step Dwell Time

Address: 146  
Attribute: RO  
Type: Float  
Byte: 4Byte

### 7.7.4 Present File Cycle Times

Address: 148  
Attribute: RO  
Type: Uint32

Byte: 4Byte

## 7.7.5 Example

Run SEQ file No. 1 and obtain the corresponding parameters.

Address	Data Type	Read/Write	Register Value	Description
20	n	WR	0	Shut off output for the selected channel
22	n	WR	128	Set operation mode to SEQ Test
122	n	W	1	Set SEQ file No. to 1
20	n	WR	1	Enable the output for the selected channel
122	n	R		Obtain SEQ file No.
124	n	RO		Obtain present step No.
146	f	RO		Obtain the dwell time
148	n	RO		Obtain the cycle times

## 7.8 CAN Setting

### 7.8.1 Sense Rate

Address: 228

Attribute: WR

Type: Uint32

Byte: 4Byte

Parameter: 0-10ms; 1-120ms; 2-480ms

### 7.8.2 CAN ID

Address: 210

Attribute: RO

Type: Uint32

Byte: 4Byte

Default: CH ID, 1 to 24

Note: When changing CAN setting, users need to turn on power-off memory first, and then reboot the device after modifying the CAN setting parameters.

### 7.8.3 Active Upload Time

Address: 212  
Attribute: WR  
Type: Uint32  
Byte: 4Byte  
Parameter: 0 for off, minimum time interval over 60  
Unit: ms

### 7.8.4 CAN Baud Rate

Address: 214  
Attribute: WR  
Type: Uint32  
Byte: 4Byte  
Parameter: Default as 50k

### 7.8.5 Extension ID Address

Address: 216  
Attribute: RO  
Type: Uint32  
Byte: 4Byte  
Default: CH ID, 1 to 24

## 7.9 Protection

### 7.9.1 OVP

Address: 200  
Attribute: WR  
Type: Float  
Byte: 4Byte

### 7.9.2 OCP

Address: 202  
Attribute: WR



Type: Float

Byte: 4Byte

### 7.9.3 OPP

Address: 204

Attribute: WR

Type: Float

Byte: 4Byte

## 7.10 Fault Simulation (Optional)

Address: 180

Attribute: WR

Type: Uint32

Byte: 4Byte

Parameters: 0 for Normal

1 for Open positive

4 for Open negative

8 for Output shorted

96 for Reverse polarity

Note: Fault simulation is only allowed to operate in power mode, other modes are not supported, otherwise the Bit6 bit omp of the channel event return value will be set to 1;

Please make sure that there is no voltage or current at the port when starting fault simulation; it is recommended to turn off the output first and wait until the voltage or current is 0 before operating the fault simulation relay; otherwise, the Bit5 bit ofp will be set to 1 to indicate that the user is not permitted to operate the fault simulation relay electrically, so as to prevent permanent damage to the relay.

## 7.11 Factory Reset

Address: 382

Attribute: WR

Type: Uint32

Byte: 4Byte

Parameters: 1

Executing the Factory Reset command resets the following parameters of the device:

1. Resets the voltage and output current limit to 0 in power mode;

2. Reset the voltage, current and internal resistance to 0 under charging mode;
3. Reset file to the default file under SOC Edit;
4. Reset protection value (over-voltage, over-current, over-power protection, etc.) to 0;
5. Clear all the sequence running files, and set SEQ file step to 0;
6. Reset CANID to channel ID, baud rate to 250K, and active upload time to 0.
7. Reset the device IP to 192.168.0.123, device ID to 1, serial port rate to 115200, sampling speed to medium speed, power-off memory off.

Note: After restoring the factory settings, it takes about 10s because it needs to save the data to the memory.

## **7.12 System Setting**

### **7.12.1 IP**

Address: 61512

Attribute: WR

Type: int

Byte: 4Byte

Parameter: Dot decimal representation: such as IP for 192.168.0.123, converted to hexadecimal as: C0 A8 00 7B; then read the data as: 7B 00 A8 C0, the big-end format.

If users want to set the IP to 192.168.0.124, converted to hexadecimal as: C0 A8 00 7C, then the data written is: 7C 00 A8 C0.

Note: Effective for channel 1 write only

### **7.12.2 Baud Rate**

Address: 17996

Attribute: WR

Type: int

Byte: 4Byte

Parameter: series baud rate setting : 9600, 19200, 38400 ,57600, 115200

Note: Effective for channel 1 write only

### **7.12.3 Beeper**

Address: 24000

Attribute: WR

Type: int  
Byte: 4Byte  
Parameter: 0-OFF; 1-ON  
Note: Effective for channel 1 write only

#### **7.12.4 Language**

Address: 24002  
Attribute: WR  
Type: int  
Byte: 4Byte  
Parameter: 0- Chinese, 1-English  
Note: Effective for channel 1 write only

#### **7.12.5 Network Connection**

Address: 17990  
Attribute: WR  
Type: int  
Byte: 4Byte  
Parameter: 0-UDP, 1-TCP  
Note: Effective for channel 1 write only

#### **7.12.6 Power-off Memory**

Address: 62374  
Attribute: WR  
Type: int  
Byte: 4Byte  
Parameter: 0-unsave; 1-save