RFT Series

Innovative Low-cost 6-Axis F/T Sensor

RFT series is a capacitive F/T sensor that can measure the six components of force and torque simultaneously. The sensor has an innovative structure design and a robust calibration algorithm to achieve both of cost competitiveness and reliable performance. It provides users with various interface options to support a wide range of automation and research applications. It also has an internal overload protection to avoid damage from external impact or excessive load.



Capacitive Type

Sensing capacitance variation by structural deformation



High Durability

Mechanical overload protection, no adhesive



Low Cost

Simple structure, simplified fabrication process



Reliable Performance

Immunity to electrical noise, robust calibration, no sensor drift Easy Installation All-in-one device with embedded signal processing, interface software support



Various Output Options

RS422, RS232, CAN, USB, and EtherCAT

Customization Service

User defined mechanical interface, Special specification

Applications

Force/torque monitoring & inspection, Force control of industrial robots and service robots, Force sensing in medical or rehabilitation devices, Haptic devices for teleoperation



RFT Series

◆Compact Size Type ◆Hollow Core Type ◆Dust Seal Type ◆High Resolution Type

SENSOR SPECIFICATIONS

Sensor Model	Dimension		Weight	Data Rate	Load Capacity			Resolution			
	Ø	н	Except Cable	Maximum	Fx, Fy	Fz	Tx, Ty, Tz	Fx, Fy	Fz	Tx, Ty, Tz	
	mm	mm	g	Hz	N	N	Nm	mN	mN	mNm	
RFT80-6A02	80	30	294	1,000	400	400	20	80	80	4	
RFT80-6A01	80	22	226	1,000	400	400	20	100	100	5	
RFT64-6A01	64	30	175	1,000	200	200	10	80	80	4	
RFT64-SB01	64	20	140	1,000	150	200	4	150	200	5	
RFT60-HA01	60	18.5	120	1,000	150	200	4	150	200	5	
RFT44-SB01	44	20	70	200	100	150	2.5	200	200	8	
RFT40-SA01	40	18.5	60	200	100	150	2.5	200	200	8	

Resolution : The standard deviation of each six components of force and torque for 10second, the data through internal 1^{st} -order low pass filter which has cutoff frequency 100Hz

	Dimension		Hysteresis			Overload Capacity				Cross Talk		
Sensor Model	Ø	Н	Fx, Fy	Fz	Tx, Ty, Tz	Fx, Fy	Fz+	Fz-	Tx, Ty, Tz	Fx, Fy	Fz	Tx, Ty, Tz
	mm	mm	%FS			%				%FS		
RFT80-6A02	80	30	1	1.5	2	300	300	300	300	3	3	3
RFT80-6A01	80	22	2.5	1	1	150	200	400	200	3	3	3
RFT64-6A01	64	30	1	1.5	2	300	300	300	300	3	3	3
RFT64-SB01	64	20	3	2	2	150	150	300	150	3	3	3
RFT60-HA01	60	18.5	2.5	1	1	150	150	300	150	3	3	3
RFT44-SB01	44	20	2.5	1	3	150	150	300	150	3	3	3
RFT40-SA01	40	18.5	2	0.5	1	150	150	300	150	3	3	3

Fz+: Tensile force, Fz-: Compressive force . The capacity of compressive force is more capacity than the capacity of tensile force

ODERING INFORMATION

RFT	_							
Sensor Feature								
RFT80-6A02 = Ø80mm, High resolution, Temp. compensation RFT80-6A01 = Ø80mm, High resolution RFT64-6A01 = Ø64mm, High resolution, Temp. compensation RFT64-SB01 = Ø64mm, Dust seal RFT60-HA01 = Ø60mm, Hollow core RFT44-SB01 = Ø44mm, Dust seal RFT40-SA01 = Ø40mm, Solid core								
A = CAN								
B = RS-232 C = RS-422								
D = USB								
E = EtherCAT (External board) (Embedded for RFT80-6A02 and RFT64-6A01)								
Cable Option								

" " = Default, Shielded, General signal cable, 2 meters

R3 = Shielded, Robot cable, 3 meters

R5 = Shielded, Robot cable, 5 meters

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