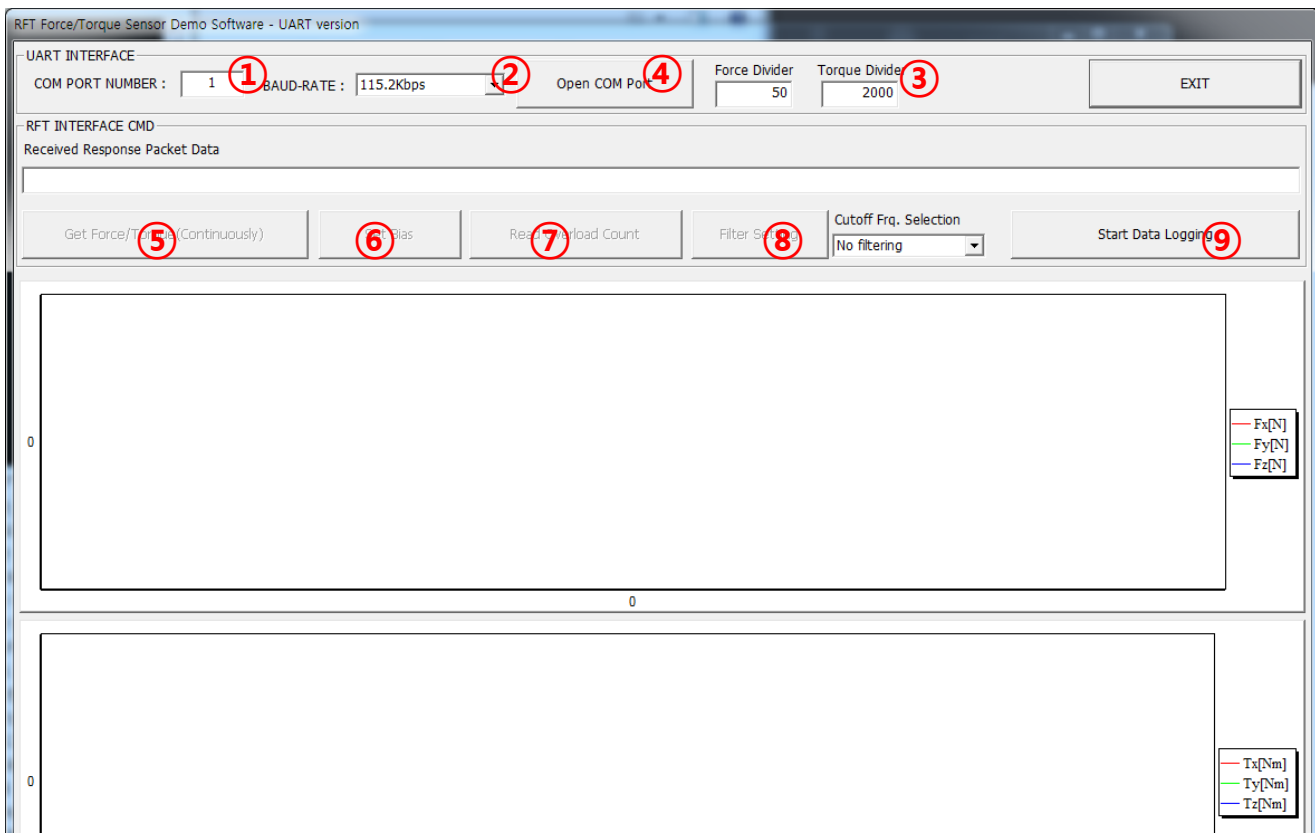


How to Use the Sample Program UI

ROBOTOUS
FORCE/TORQUE SENSOR

For COM Port Only, Windows OS



- ① Modify the COM Port Number
- ② Select the baud-rate(Default baud-rate: 115.2kpbs)
- ③ Enter a force/torque divider parameters. Refer to the user's manual
- ④ Open the COM Port, which makes the buttons below enabled.
- ⑤ Start/Stop F/T data output from the sensor
- ⑥ Send bias/un-bias command to the sensor
- ⑦ Read overload count from the sensor
- ⑧ Set a low-pass filter of the sensor using the selected cutoff frequency in the combo box
- ⑨ Start/Stop saving F/T output data to a file in the current directory

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