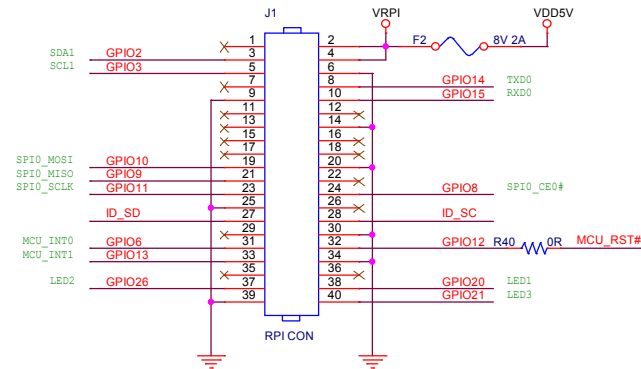
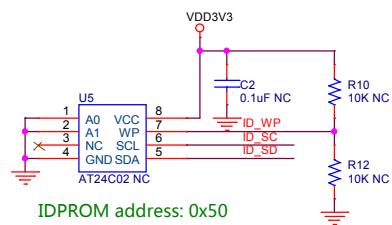
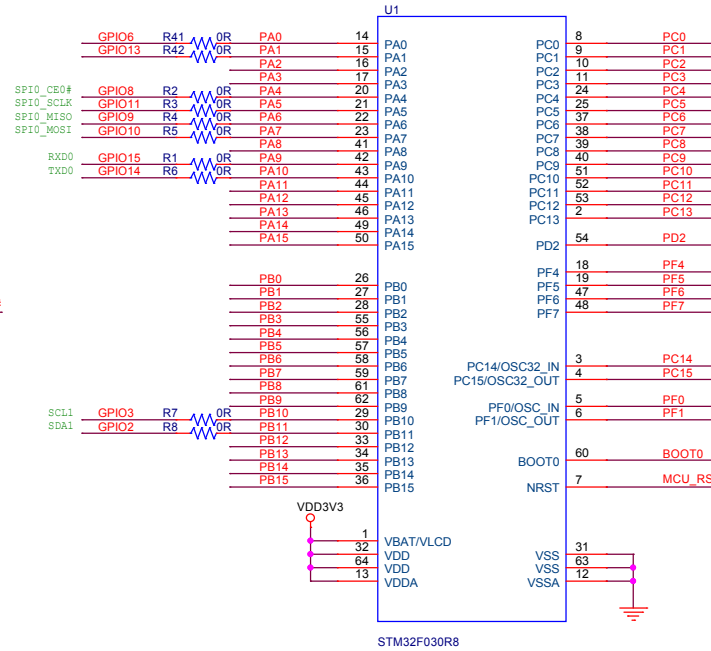
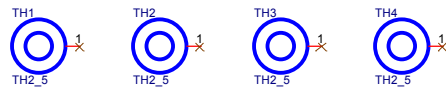


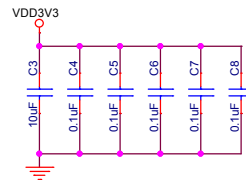
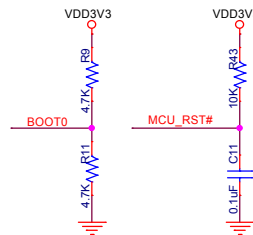
NC unused GPIO pins and the 3.3V power pins.
RPI only needs 5V external supply.



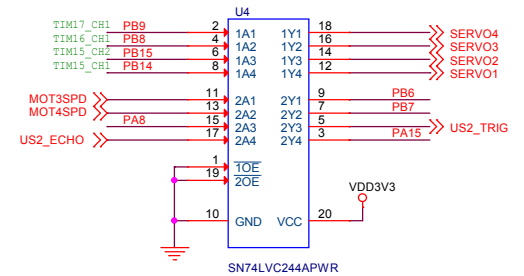
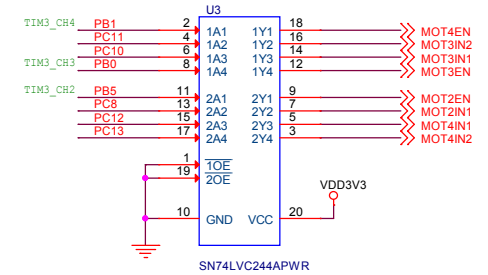
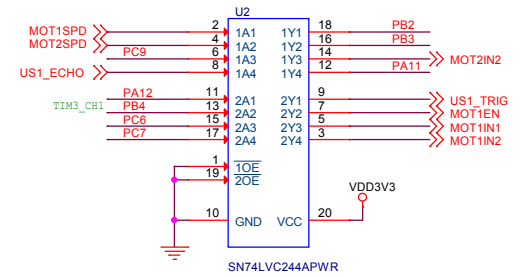
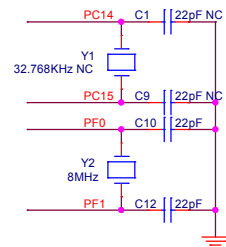
Pinout can be found on this website: pi.gadgetoid.com/pinout



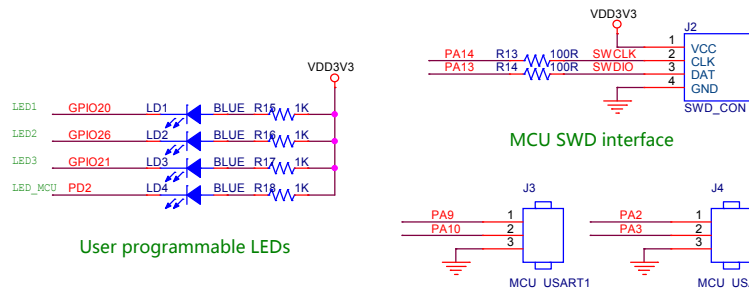
IDPROM address: 0x50



For MCU power pins

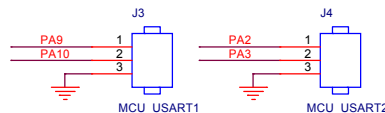


These 244s work as IO buffers for the MCU
MCU -> MOT/SRV: driver & isolator
MOT/US -> MCU: 5V to 3.3V converter

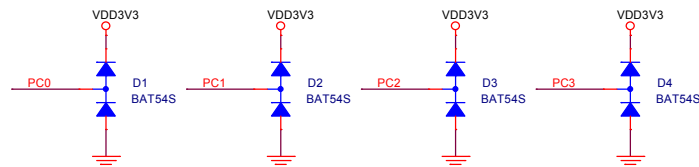


MCU SMD interface

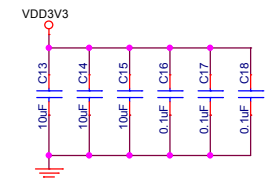
User programmable LEDs



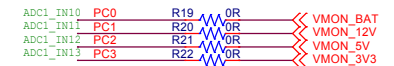
MCU USART interfaces



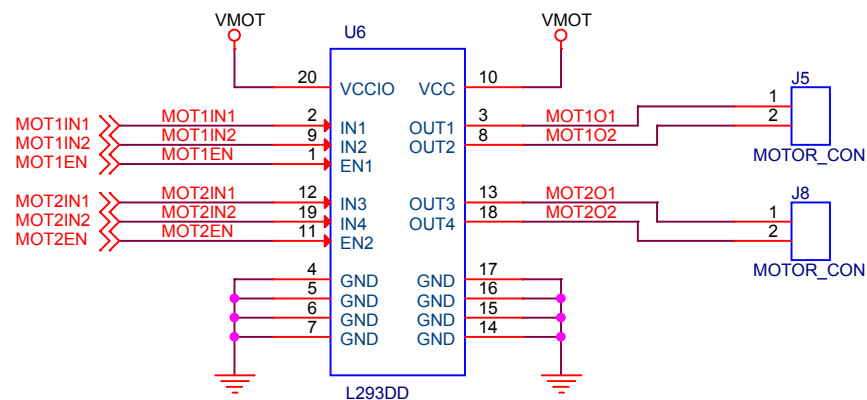
Protect the analog input channels



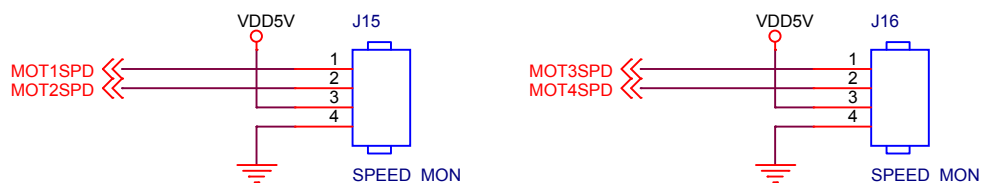
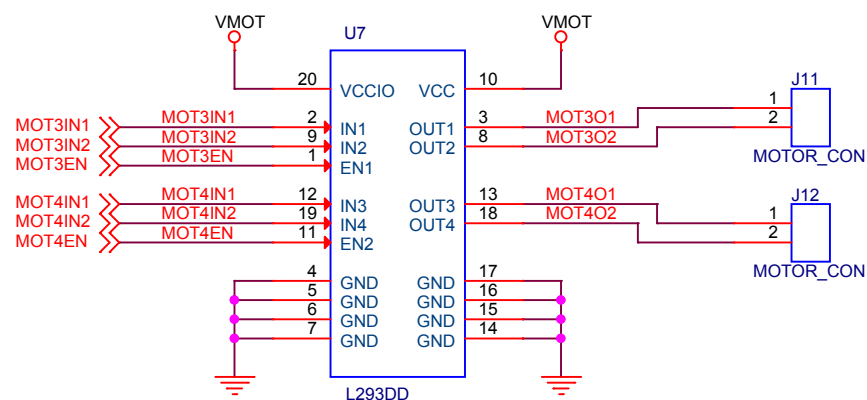
For 244 power pins



Title			MOT HAT for Raspberry Pi		
Size	A3	Document Number	MCU		
Date:	Wednesday, August 05, 2015	Sheet	1	of	3



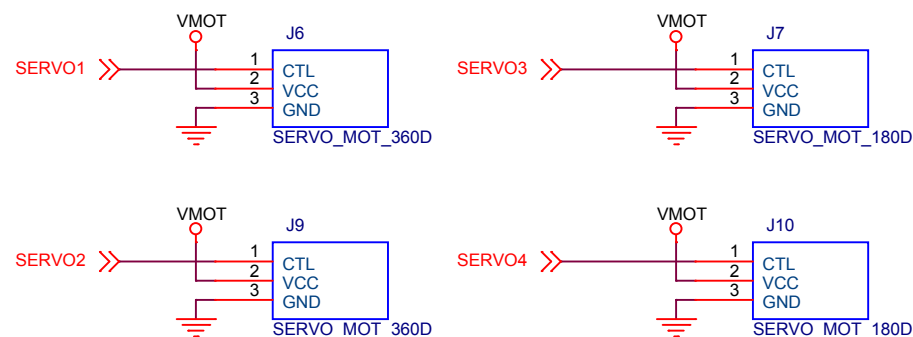
MOTxIN1 & IN2: direction control (GPIO)
MOTxEN: speed control (PWM)



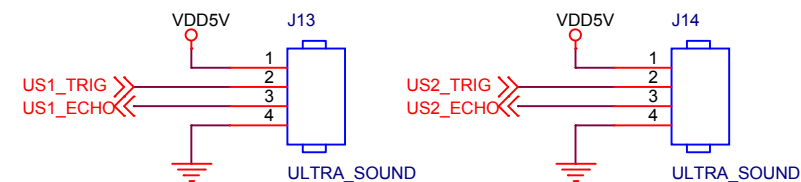
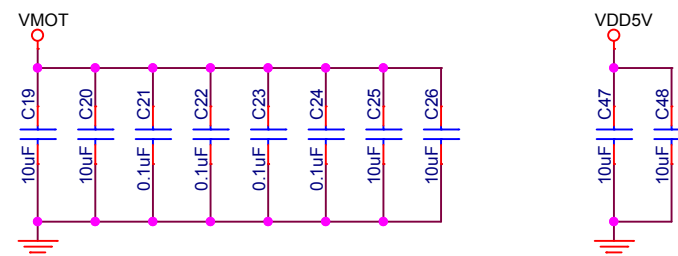
IR motor velometer interface

[DC Geared Motor]
Voltage: 3~6V
Current: 100~120mA
Speed: 100~240rpm

[MG995 Servo]
Torque: 13KG/cm
Voltage: 3~7V
Current: ~100mA



4-channel servos for robotic arm



Ultrasound sensor module interface

Title			
MOT HAT for Raspberry Pi			
Size	Document Number		Rev
A4	Motors		R0A
Date:	Wednesday, August 05, 2015		Sheet 2 of 3

