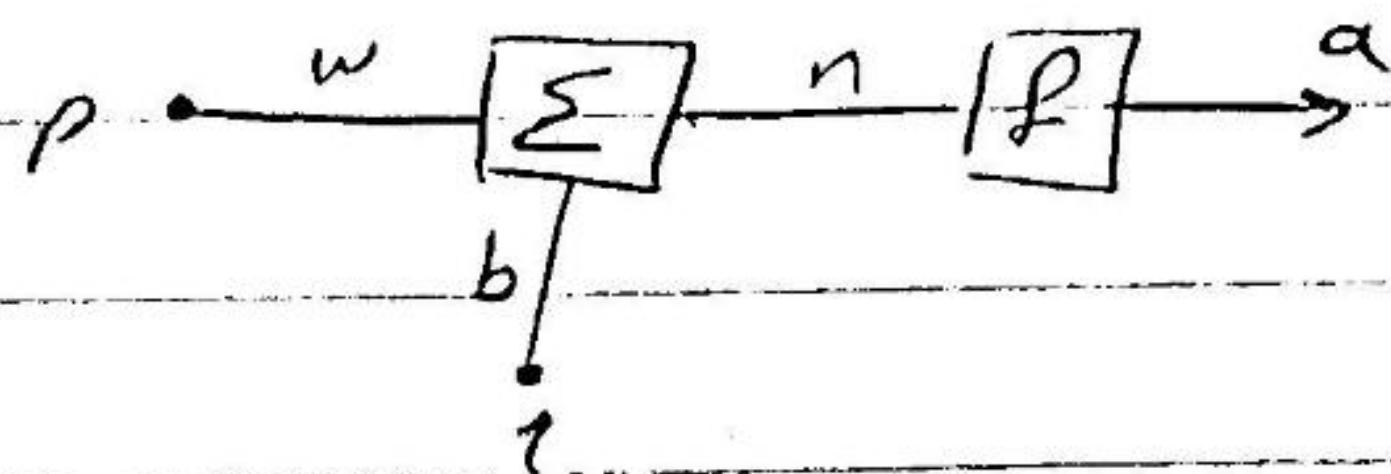


E2.1



$$w=1.3 \quad b=3.0$$

$$f = wp + b = (1.3)p + 3.0$$

(i) 1.6 → purelin, logsig, tanSig, poslin

(ii) 1.0 → hardlim, hardlims, purelin, satlin, satlims, logsig, transig, poslin, compet

(iii) 0.9963 → purelin, satlin, satlims, logsig, transig, poslin

(iv) -1.0 → hardlims, purelin, satlims, logsig, transig

E2.2

single neuron with bias output

$$\begin{cases} -1 & \text{input} < 3 \\ +1 & \text{input} \geq 3 \end{cases}$$

(i) hardlims function can be applied to this problem

(ii) if we write the single neuron with hardlims transfer function formula:

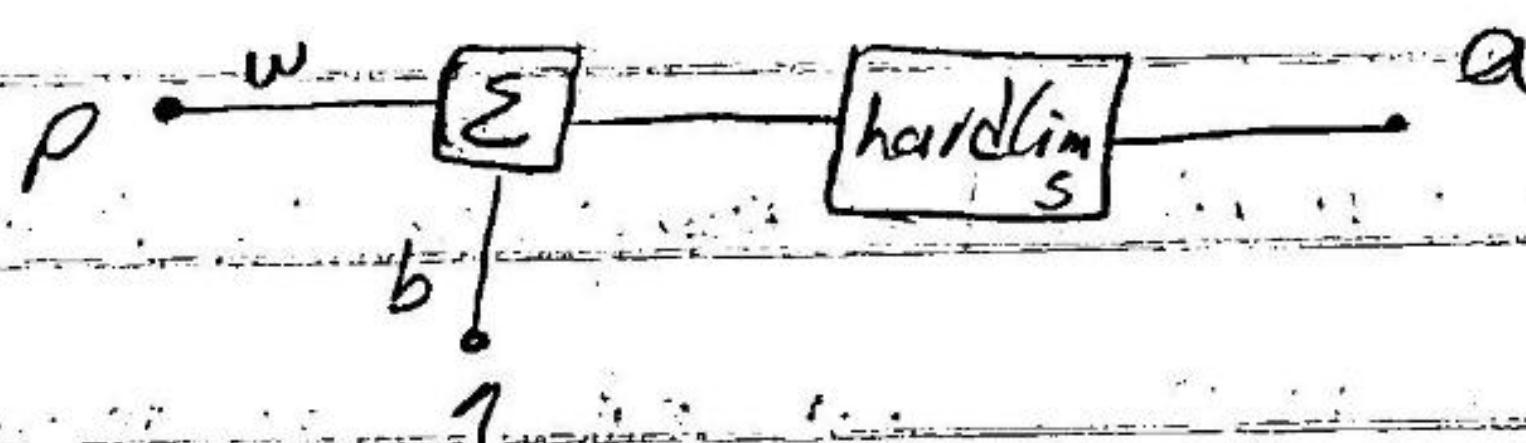
$$\text{out} = \text{hardlims}(wp + b)$$

the parameters to get the requested output can be: $b = -3$, $\text{weight} > 0$

E22 Continues.

- (ii) The bias can be related to input weights with the condition of
- (a) first of all weight must be not zero!
 - (b) second, if weight is set to positive numbers then bias can be -3,
 - (c) third, if weight is set to a negative number, then any bias won't satisfy our problem.

(iii)



$$a = \text{hardlims}(w_p + b)$$

Code is attached in the file named E212.py

E2.3

two neuron $w = [3 \ 2]$

$$p = [-5 \ 7]^T$$

$$a = 0.5$$

$$a = f(wp + b)$$

(i) if bias = 0 →

$$a = f([3 \ 2] \begin{bmatrix} -5 \\ 7 \end{bmatrix} + 0) = f(-15 + 14) = f(-1)$$

X there is no transfer function defined in chapter 2
that outputs 0.5 for the input number -1.

(ii) transfer function purelin

Yes

$$a = \text{purelin}(wp + b) = \text{purelin}(-1 + b) = 0.5$$

if we define $b = 1.5 \rightarrow$ then purelin will work

(iii) transfer function logsig

No

$$a = \text{logsig}(wp + b) = \text{logsig}(-1 + b) = 0.5$$

$$\frac{1}{1 + e^{(1-b)}} = 0.5 \Rightarrow \frac{1}{2} + \frac{1}{2} e^{(1-b)} = 1 \Rightarrow e^{(1-b)} = -1 \quad \textcircled{A}$$

Ⓐ → e to the power of any number cannot be a negative value, so there is no answer for b .

X in result we cannot define

logsigmoid transfer function here.



E2.3 continue

(iv) transfer function, hard lims

NO

If we look at the hard lims transfer function closely, we can find that there is no way to use this function in this problem, because the possible outputs in this function are -1, 0, 1.

E2.4

(i) we have four input and six output

(a) for the second layer six neuron are sufficient.

(b) for the first layer any number of neurons between 1 to 4 can be used.

(ii) first layer weight matrix:

rows: count of neurons \rightarrow 1 to 4 = ④

columns: 11 inputs = 4

Size(first layer weight matrix) = ④, 4

second layer weight matrix:

rows: count of the layer neurons: 6

columns: " n neurons in the last layer \rightarrow 15 "

size(second layer weight matrix) = 6, ④

E2.4 continue

(iii) for the second layer logsig function can be applied here.

for the first layer any transfer function can be applied!

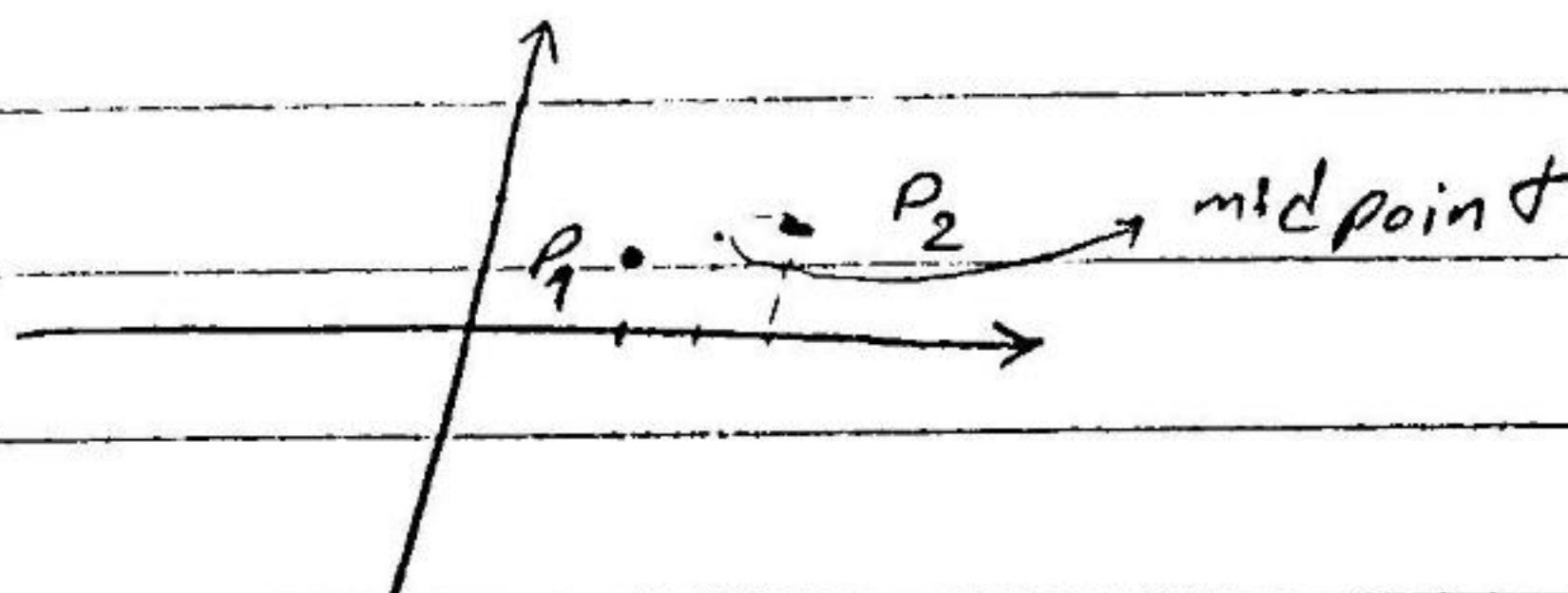
(iv) with respect to the first layer transfer function and if more information was given, we could answer this part.

Neural Network

E3.2

$$P_1 = \begin{bmatrix} 1 \\ 0.5 \end{bmatrix} \quad P_2 = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

(i)



$$a = \text{hardlims}(wP + b)$$

we must make a boundary that separate P_1 and P_2 well. we will try the graphical method used in book.

$$\text{For } P_1 \quad a=1 \quad \text{then} \quad wP_1 + b < 0$$

$$\text{For } P_2 \quad a=1 \quad wP_2 + b > 0$$

$$\Rightarrow [w_{11} \quad w_{12}] \begin{bmatrix} 1 \\ 0.5 \end{bmatrix} + b < 0 \Rightarrow w_{11} + \frac{1}{2}w_{12} + b < 0$$

$$\Rightarrow [w_{11} \quad w_{12}] \begin{bmatrix} 2 \\ 1 \end{bmatrix} + b > 0 \rightarrow 2w_{11} + w_{12} + b > 0$$

$$\text{with bias } = 0 \Rightarrow w_{11} + \frac{1}{2}w_{12} < 0$$

$$2w_{11} + w_{12} > 0$$

composing equations. $\begin{cases} w_{11} + \frac{1}{2}w_{12} = 0 \\ 2w_{11} + w_{12} = 0 \end{cases} \rightarrow$ there is no answer for the equation

because two equations are both equal

so we try a different bias

As we know from the mid point method
the line must go through the point $\begin{bmatrix} 1.5 \\ 0.75 \end{bmatrix}$

$$P_1 = \begin{bmatrix} 1 \\ 0.5 \end{bmatrix}, \quad P_2 = \begin{bmatrix} 2 \\ 1 \end{bmatrix}, \quad x = \frac{2+1}{2} = 1.5$$

$$y = \frac{1+0.5}{2} = 0.75$$

So we can define the bias as -1.5 because
of the midpoint

let's try it

$$b = -1.5$$

$$[w_{11} \ w_{12}] \begin{bmatrix} 1 \\ 0.5 \end{bmatrix} + b \leq 0$$

$$[w_{11} \ w_{12}] \begin{bmatrix} 2 \\ 1 \end{bmatrix} + b \geq 0$$

$$w_{11} + \frac{1}{2}w_{12} - 1.5 \leq 0$$

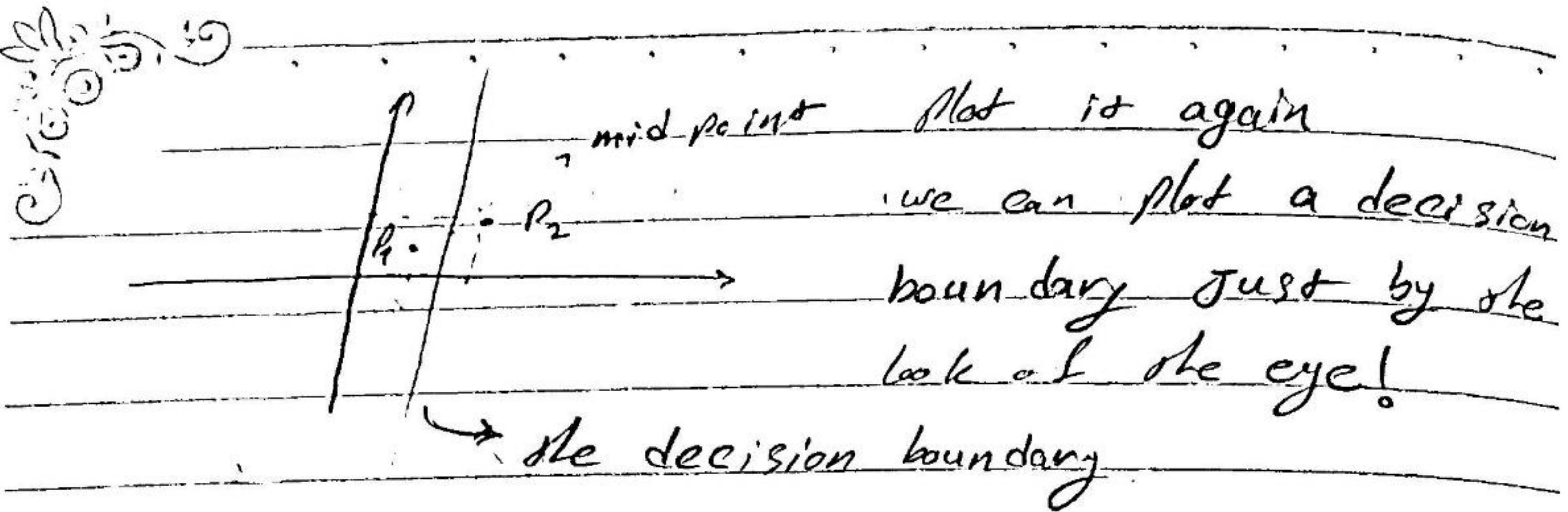
$$2w_{11} + w_{12} - 1.5 \geq 0$$

to find the points overlap:

$$\begin{cases} w_{11} + 0.5w_{12} - 1.5 \leq 0 \xrightarrow{x(2)} -2w_{11} - w_{12} + 3 \leq 0 \\ 2w_{11} + w_{12} - 1.5 \geq 0 \xrightarrow{} 2w_{11} + w_{12} - 1.5 \geq 0 \end{cases}$$

Again there is no way to find
an answer here.

So we try to look at the diagram and
plot a decision boundary for it.



(ii)

To find the weights we first write the line equation

$$x = +1.5 \rightarrow \text{the line}$$

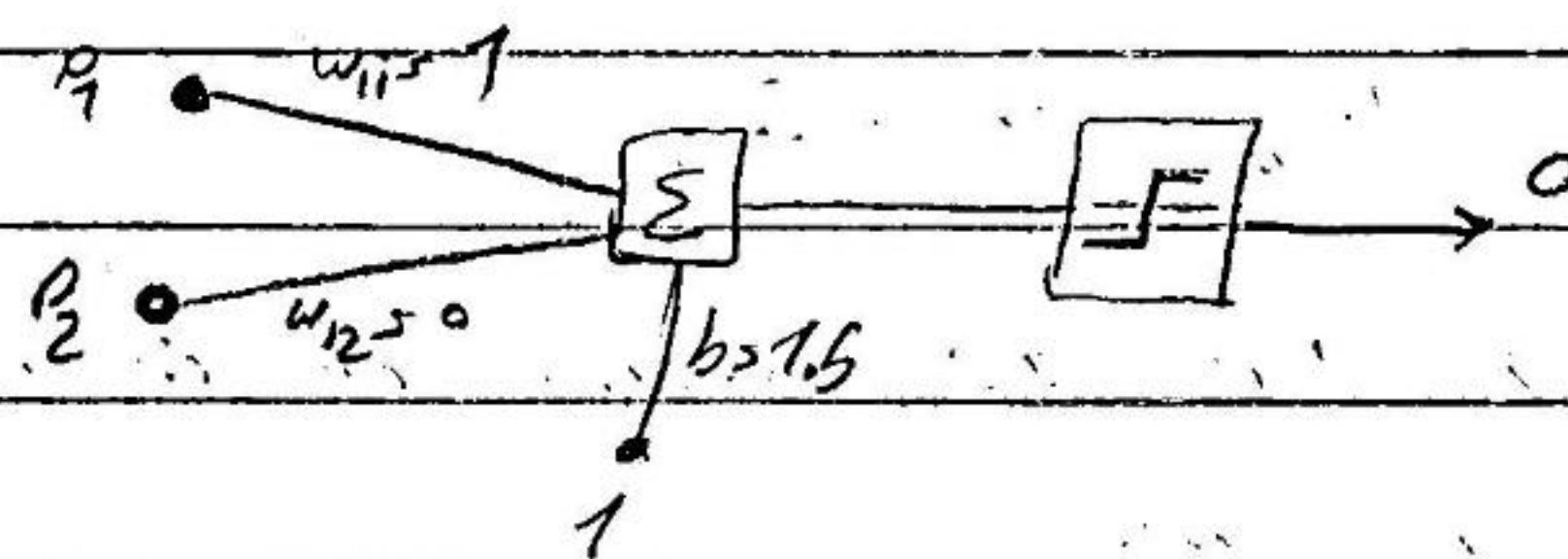
so it can be formulated with weights and biases as below:

(suppose w_{11} be the coefficient,
and w_{12} be the coefficient
and bias is just a number)

$$\text{So } w_{11} = 1, w_{12} = 0, \text{ bias} = 1.5$$

$$w_{11} = 1.5 = 0$$

to sketch the network diagram.



(iii)

$$\begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} ? \\ ? \end{bmatrix} - 1.5 = -0.5 \rightarrow \text{hardlim}(-0.5) = -1$$

w P bias

The point P is in the left side of decision boundary. So the expected output must be -1

And by the decision rule we made, the network response was reasonable

E3.4

$$w = \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix} \quad w.\text{shape} = (2, 2)$$

$$b = \begin{bmatrix} -2 \\ 0 \end{bmatrix} \quad b.\text{shape} = (2, 1)$$

S → neuron count → 2 neurons we have

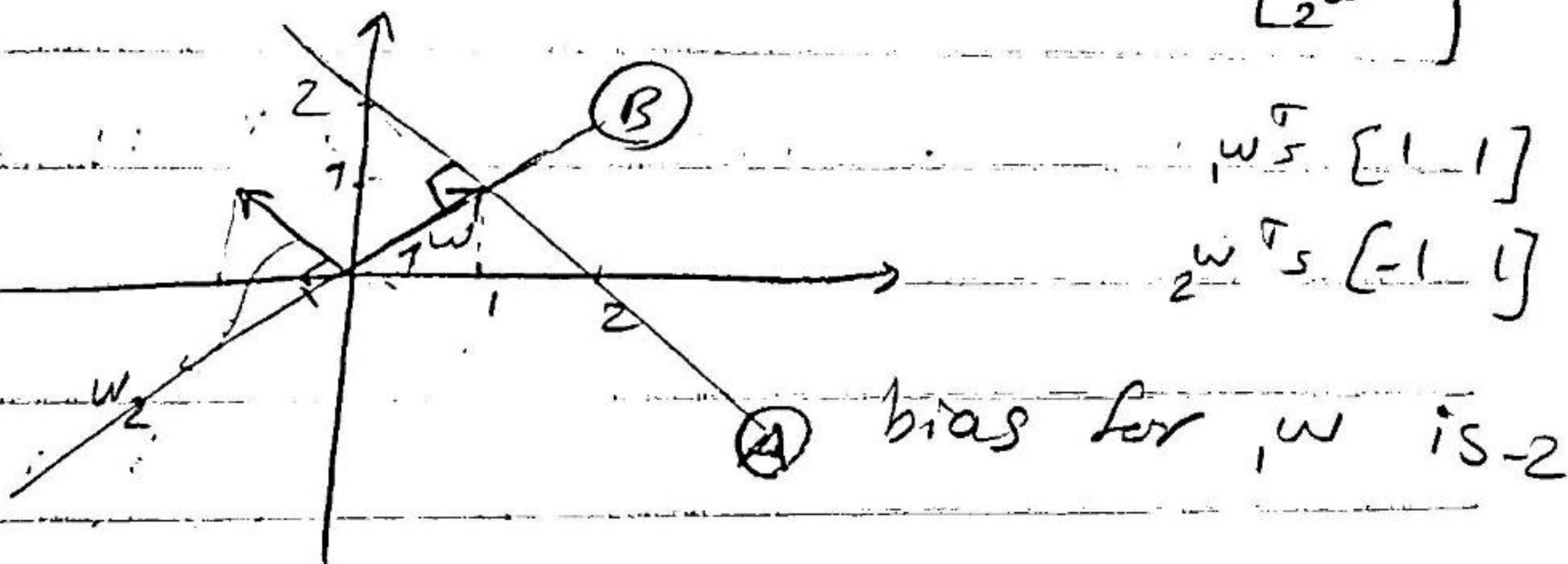
R → input count → 2 inputs x_1, x_2

2 neurons can classify up to 2^2 classes.

(i) so we have 4 classes!

$$w_s = \begin{bmatrix} 1, w^T \\ 2, w^T \end{bmatrix}$$

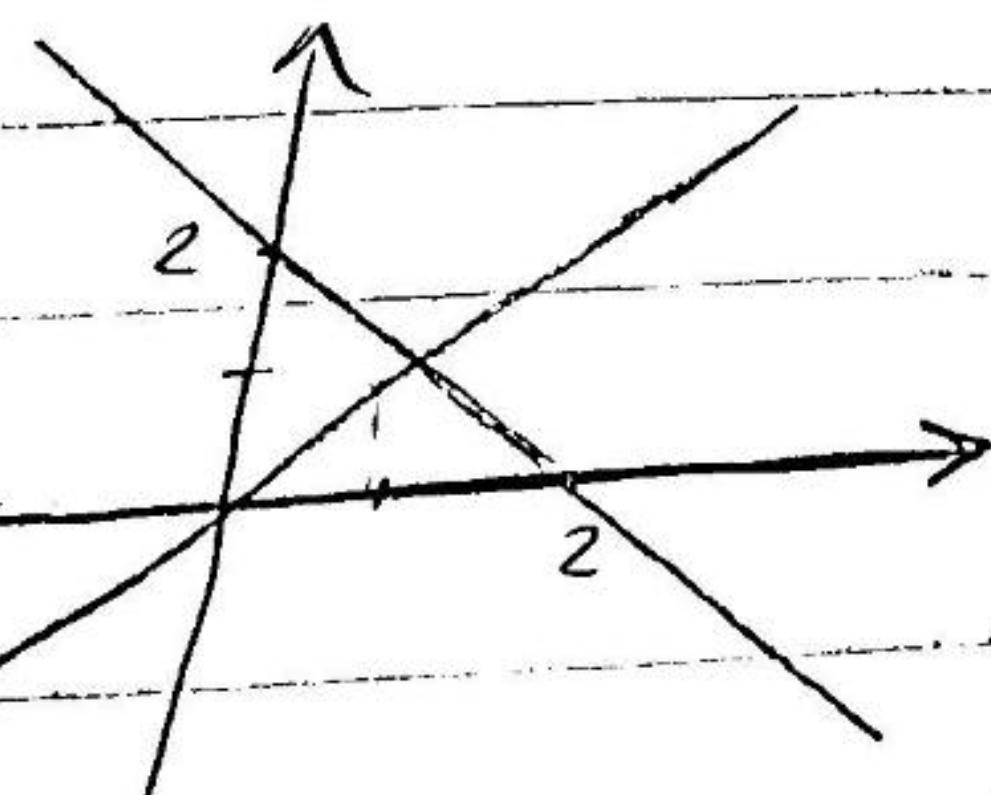
(ii)



A The first boundary $\rightarrow w_s[1, 1] \quad x + y - 2 = 0$

B bias for the second line is zero, So it will go through the origin. $-x + y = 0 \Rightarrow x = y$

draw the decision boundaries without weights to make it more transparent



(iii)

$$a = \text{hardlims}(w_p + b)$$

$$a = \text{hardlims} \left(\begin{bmatrix} 1 & 1 \\ -1 & 1 \\ -2 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} + \begin{bmatrix} -2 \\ -1 \end{bmatrix} \right) = \text{hardlims} \left(\begin{bmatrix} -2 \\ -2 \end{bmatrix} \right) = \begin{bmatrix} -1 \\ -1 \end{bmatrix}$$

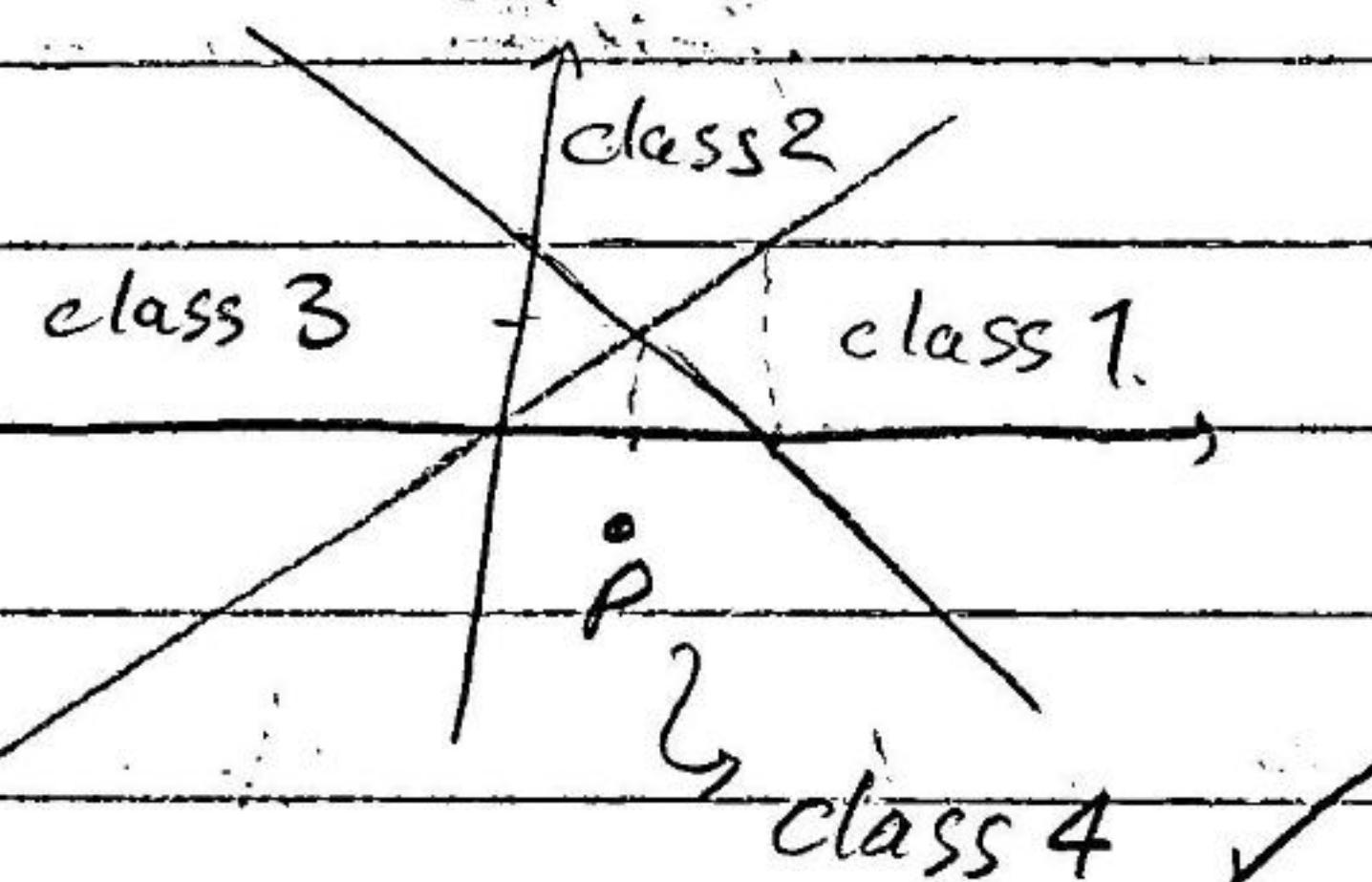
If we define the classes table as below

$$\begin{bmatrix} 1 \\ 1 \end{bmatrix} \rightarrow \text{class 1} \quad \begin{bmatrix} 1 \\ -1 \end{bmatrix} \rightarrow \text{class 2} \quad \begin{bmatrix} -1 \\ 1 \end{bmatrix} \rightarrow \text{class 3}$$

$$\begin{bmatrix} -1 \\ -1 \end{bmatrix} \rightarrow \text{class 4}$$

The label for input p will be class 4

(iv)



It is correctly in its labeled region

63.5)

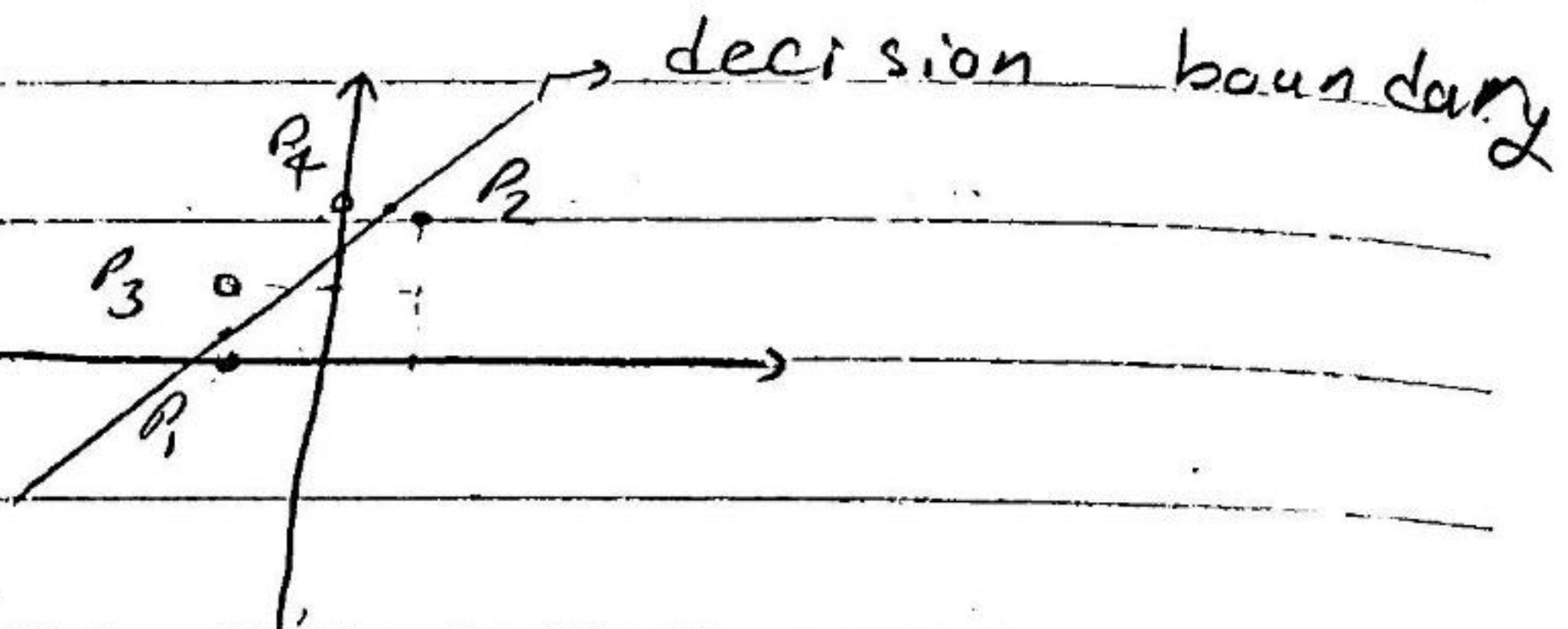
we can define hardlims Function

so its output (-1 and 1) is equal to our need.

(i)

$$P_1 = \begin{bmatrix} -1 \\ 0 \end{bmatrix}, P_2 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$P_3 = \begin{bmatrix} -1 \\ 1 \end{bmatrix}, P_4 = \begin{bmatrix} 0 \\ 2 \end{bmatrix}$$



(ii)

we can define the decision boundaries in the midpoint of P_1, P_3 and P_2, P_4

$$\text{mid point } (P_1, P_3) = \begin{bmatrix} \frac{P_1^x + P_3^x}{2} \\ \frac{P_1^y + P_3^y}{2} \end{bmatrix} = \begin{bmatrix} -1 \\ 0.5 \end{bmatrix}$$

$$\text{slope } m = \frac{\bar{y}_1 - \bar{y}_2}{\bar{x}_1 - \bar{x}_2} = \frac{1.5 - 0}{1 - (-1)} = 1.5$$

$$\text{mid point } (P_2, P_4) = \begin{bmatrix} \frac{P_2^x + P_4^x}{2} \\ \frac{P_2^y + P_4^y}{2} \end{bmatrix} = \begin{bmatrix} 0.5 \\ 2 \end{bmatrix}$$

so the slope of the weight matrix is inverse negative of the decision boundary \rightarrow slope weight = -1

decision boundary equation $\rightarrow (\bar{y} - \bar{c}) = 1(\bar{x} - \bar{b}) \Rightarrow \bar{y} = \bar{x} + \frac{3}{2}$

weight equation $\rightarrow (\bar{y} - c) = -1(x - b) \Rightarrow y = -x$
(it goes from the origin)

$$w = [-1 \quad 1]$$

(iii) to find the bias

$$w^T P + b = 0 \Rightarrow b = -w^T P \Rightarrow b = -[-1 \quad 1] \begin{bmatrix} -1 \\ 0.5 \end{bmatrix}$$

$$\Rightarrow b = -(1 + 0.5) = -1.5$$

as hardlims $(w^T P + b)$ \Rightarrow hardlims $(-P_x + P_y - 1.5)$

(iv)

a must be 1 for P_1, P_2

lets test it $P_1 \rightarrow a = \text{hardlims}(-(-1)+0) = 1 \checkmark$

$P_2 \rightarrow a = \text{hardlims}(-1+2) = 1 \checkmark$

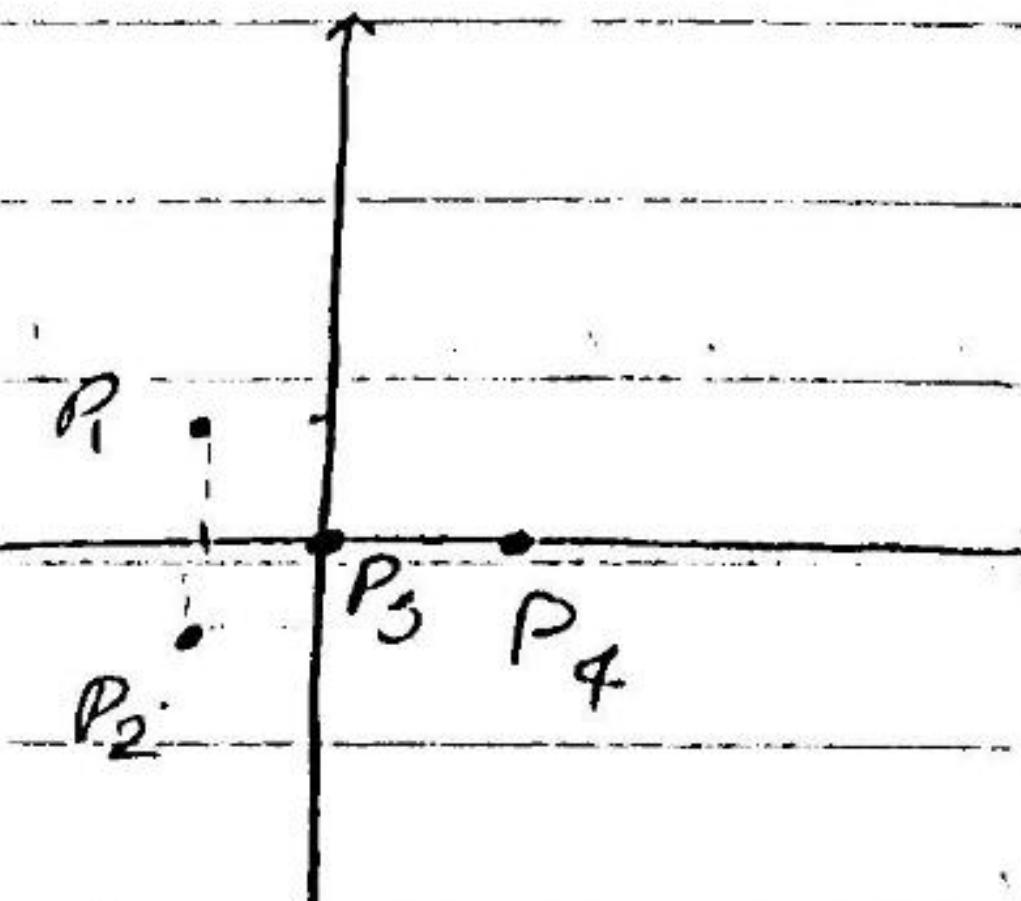
a must be -1 for P_3, P_4

lets test 1s:

$P_3 \rightarrow a = \text{hardlims}(1+1) = 1 \times \sim$

E 9.21

(i)



it can be known as the outputs for neurons
are 1 and zero. the activation function
that can be used here is hardlim.

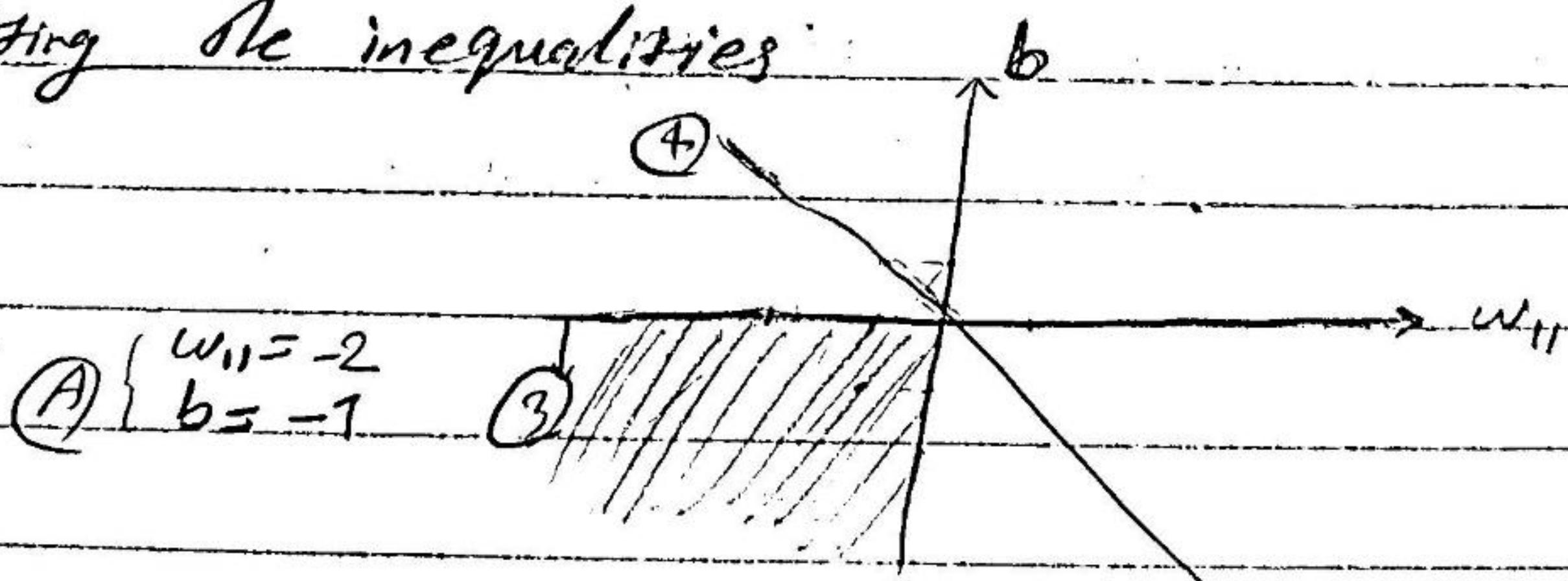
as hardlim($w^T p + b$)

for P_1, P_2 the $w^T p + b$ must be semi-positive

for P_3, P_4 " $w^T p + b$ is negative

$$\left. \begin{array}{l} P_1 \rightarrow w_{11}P_{1x} + w_{12}P_{1y} + b > 0 \\ P_2 \rightarrow w_{11}P_{2x} + w_{12}P_{2y} + b > 0 \\ P_3 \rightarrow w_{11}P_{3x} + w_{12}P_{3y} + b < 0 \\ P_4 \rightarrow w_{11}P_{4x} + w_{12}P_{4y} + b < 0 \end{array} \right\} \Rightarrow \left. \begin{array}{l} -w_{11} + w_{12} + b > 0 \\ -w_{11} - w_{12} + b > 0 \\ w_{11} + w_{12} + b < 0 \\ w_{11} + w_{12} - b < 0 \end{array} \right\} \quad \begin{array}{l} ① \\ ② \\ ③ \\ ④ \end{array}$$

Plotting the inequalities



$$① \left\{ \begin{array}{l} w_{11} = -2 \\ b = -1 \end{array} \right.$$

③

$$\begin{aligned} ② \rightarrow 2 - w_{12} - 1 > 0 \Rightarrow w_{12} < 1 &\quad \text{we define it} \\ ① \rightarrow 2 + w_{12} - 1 > 0 \Rightarrow w_{12} > -1 &\quad \text{as } w_{12} = 0 \end{aligned}$$

So the results are:

$$w^T = [-2 \ 0] \quad b = -1$$

(ii) test the results

$$P_1 \rightarrow \text{hardlim}(w^T P_1 + b) = \text{hardlim}([-2 \ 0] \begin{bmatrix} -1 \\ 1 \end{bmatrix} - 1) = \text{hardlim}(1) = 1$$

$$P_2 \rightarrow \text{hardlim}([-2 \ 0] \begin{bmatrix} -1 \\ -1 \end{bmatrix} - 1) = \text{hardlim}(-1) = 1 \checkmark$$

$$P_3 \rightarrow \text{hardlim}([-2 \ 0] \begin{bmatrix} 0 \\ 0 \end{bmatrix} - 1) = \text{hardlim}(-1) = 0 \checkmark$$

$$P_4 \rightarrow \text{hardlim}([-2 \ 0] \begin{bmatrix} 1 \\ 0 \end{bmatrix} - 1) = \text{hardlim}(-3) = 0 \checkmark$$

So training set had no errors.

(iii)

$$P_5 \rightarrow \text{hardlim}([-2 \ 0] \begin{bmatrix} 2 \\ 0 \end{bmatrix} - 1) = \text{hardlim}(3) = 1$$

$$P_6 \rightarrow \text{hardlim}([-2 \ 0] \begin{bmatrix} 1 \\ 1 \end{bmatrix} - 1) = \text{hardlim}(-3) = 0$$

$$P_7 \rightarrow \text{hardlim}([-2 \ 0] \begin{bmatrix} 0 \\ 1 \end{bmatrix} - 1) = \text{hardlim}(-1) = 0$$

$$P_8 \rightarrow \text{hardlim}([-2 \ 0] \begin{bmatrix} -1 \\ -2 \end{bmatrix} - 1) = \text{hardlim}(1) = 1$$

(iv)

P_7 depends on the bias because the inner product of it with weights will be always zero.

E4.3

The Answer to E4.2 question was using inequality method. we can define a range of values $[-1, 1]$ for $w_{1,2}$ until $w_{1,1} = -2$ and $b = -1$.

So we try $w = [-2 \ -1]$, $b = -1$

$$P_1 \rightarrow a = \text{hardlim}([-2 \ -1] \begin{bmatrix} -1 \\ 1 \end{bmatrix} - 1) = \text{hardlim}(0) = 1 \quad \checkmark$$

$$P_2 \rightarrow a = \text{hardlim}([-2 \ -1] \begin{bmatrix} -1 \\ -1 \end{bmatrix} - 1) = \text{hardlim}(2) = 1 \quad \checkmark$$

$$P_3 \rightarrow a = \text{hardlim}([-2 \ -1] \begin{bmatrix} 0 \\ 0 \end{bmatrix} - 1) = \text{hardlim}(-1) = 0 \quad \checkmark$$

$$P_4 \rightarrow a = \text{hardlim}([-2 \ -1] \begin{bmatrix} 1 \\ 0 \end{bmatrix} - 1) = \text{hardlim}(-3) = 0 \quad \checkmark$$

we can define other values for weights and bias since we have inequalities.

E 4.7

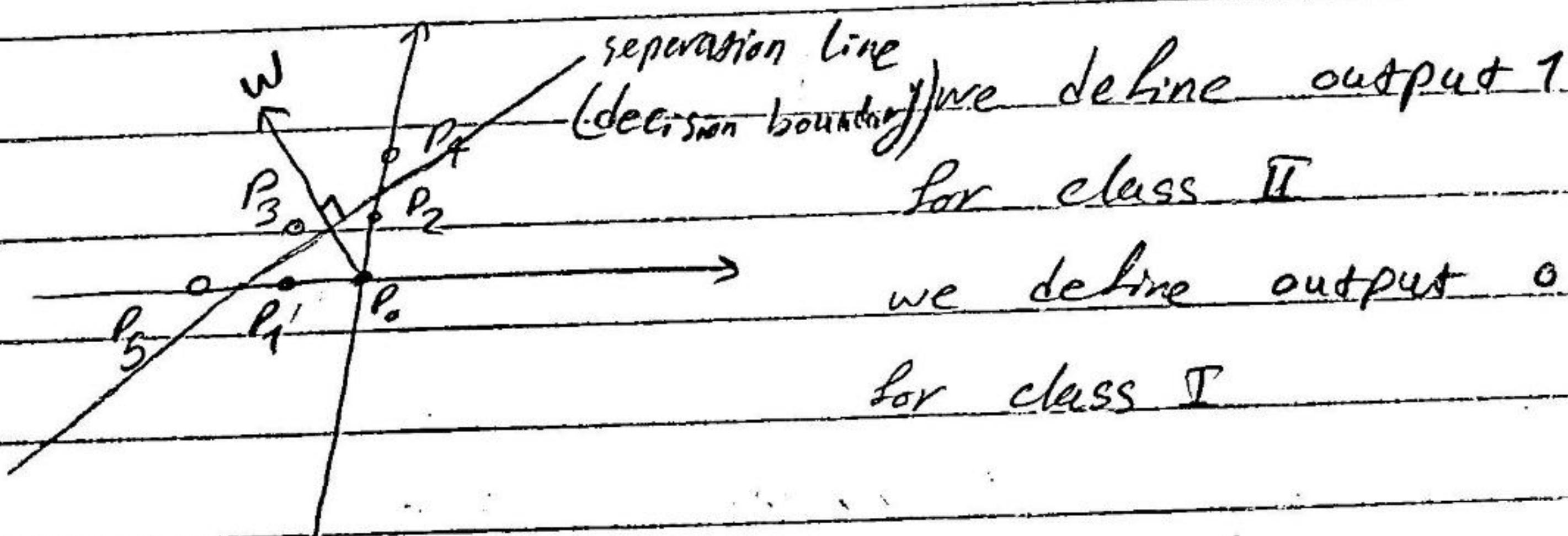
To go with perceptron learning rule
it would be cost a lot of time.

So we will try the graphical method.

At first we sketch the points and
try to find a separation line in the middle
of the classes.

class I points $\rightarrow P_0 = [0] \quad P_1 = [-1] \quad P_2 = [1]$

class II points $\rightarrow P_3 = [1] \quad P_4 = [0] \quad P_5 = [-2]$



From the plot it's easy to find the separation line. The separation line is between the two classes and for that we can say it goes through $[0, -1.5], [0, 1.5]$ So the line can be formulated

$$\text{as: } m_{\text{line}} = \frac{0 - 1.5}{1.5 - 0} = -1 \Rightarrow y - 0 = -1(x - (-1.5))$$

$$y = -x - 1.5$$

weights are orthogonal so its slope is -1

weights equation: $y = -x$

64.7 Continued

So the equation of weights is

$$y = -x \text{ or } w_1 = -w_{12}$$

$$w^T = [-1 \ 1]$$

To find the biases we try one of the points on the decision boundary

$$w^T p + b = 0 \Rightarrow b = -w^T p$$

$$b = -[-1 \ 1] \begin{bmatrix} -1.5 \\ 0 \end{bmatrix} = 1.5$$

So let's test $w^T = [1 \ 1]$, bias = -1.5

Before we start the test it's important to note that we use hardlim transfer function and the output is 1 for class I and 0 for class II

$$a_0 = \text{hardlim} \left(\underbrace{[1 \ 1]^T \begin{bmatrix} 0 \\ 0 \end{bmatrix}}_{-1.5} - 1.5 \right) = 0 \quad \checkmark \quad \left\{ \begin{array}{l} a_2 = \text{hardlim} \left(\underbrace{[1 \ 1]^T \begin{bmatrix} 0 \\ 1 \end{bmatrix}}_{-2.5} - 1.5 \right) \\ \Rightarrow a_2 = 0 \end{array} \right. \quad \checkmark$$

$$a_1 = \text{hardlim} \left(\underbrace{[1 \ 1]^T \begin{bmatrix} -1 \\ 0 \end{bmatrix}}_{-0.5} - 1.5 \right) = 0 \quad \checkmark$$

$$a_3 = \text{hardlim} \left(\underbrace{[1 \ 1]^T \begin{bmatrix} 1 \\ 1 \end{bmatrix}}_{0.5} - 1.5 \right) = 1 \quad \checkmark$$

$$a_4 = \text{hardlim} \left(\underbrace{[1 \ 1]^T \begin{bmatrix} 0 \\ 2 \end{bmatrix}}_{0.8} - 1.5 \right) = 1 \quad \checkmark$$

$$a_5 = \text{hardlim} \left(\underbrace{[1 \ 1]^T \begin{bmatrix} -2 \\ 0 \end{bmatrix}}_{-1.5} - 1.5 \right) = 1 \quad \checkmark$$

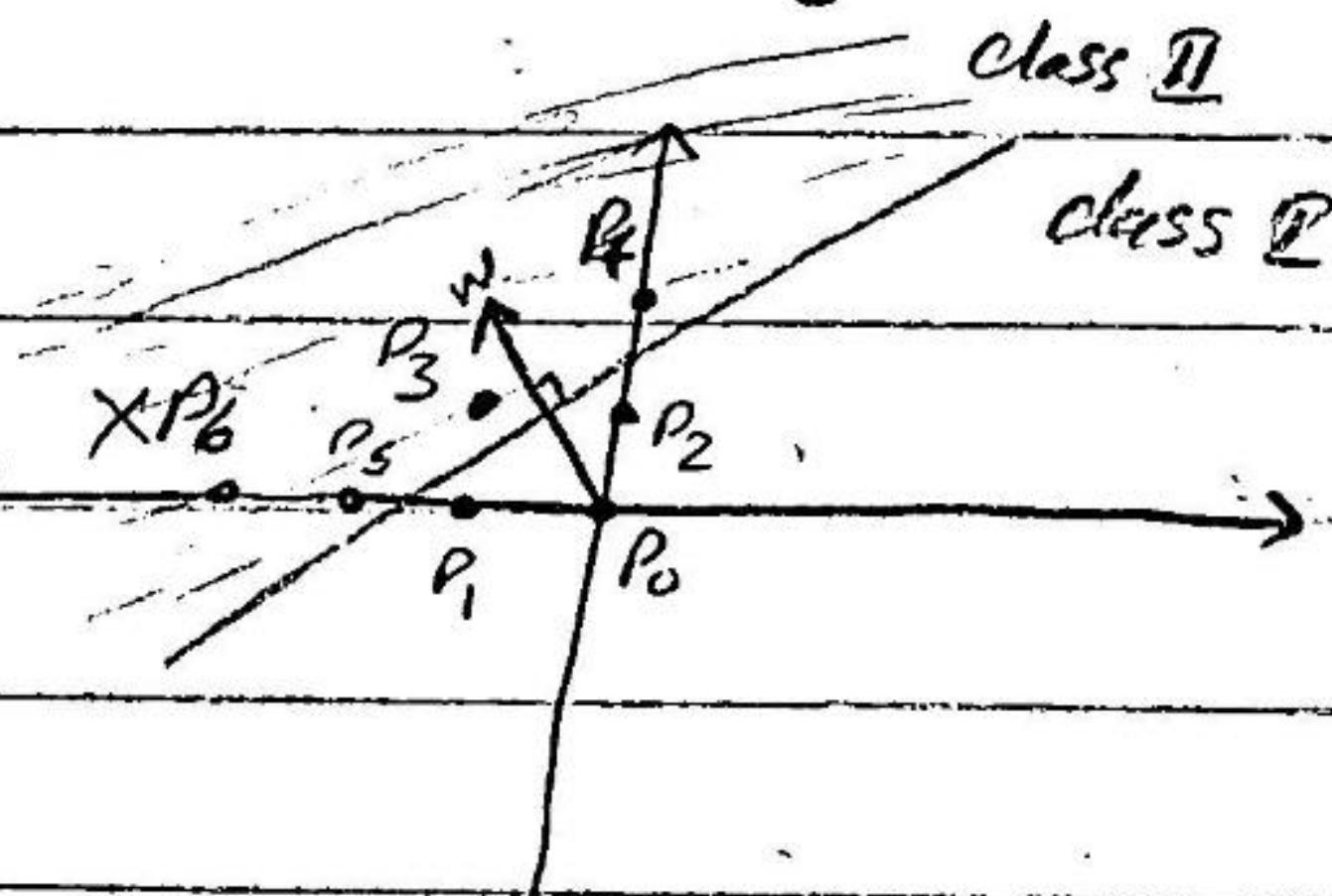
E4. F continue

(iv) $P_6 = \begin{bmatrix} -3 \\ 0 \end{bmatrix}$

$$a_6 = \text{hardlim}\left(E_1 \cdot [1] \begin{bmatrix} -3 \\ 0 \end{bmatrix} - 1.5\right) = \text{hardlim}(1.5) = 1$$

The output was incorrect!

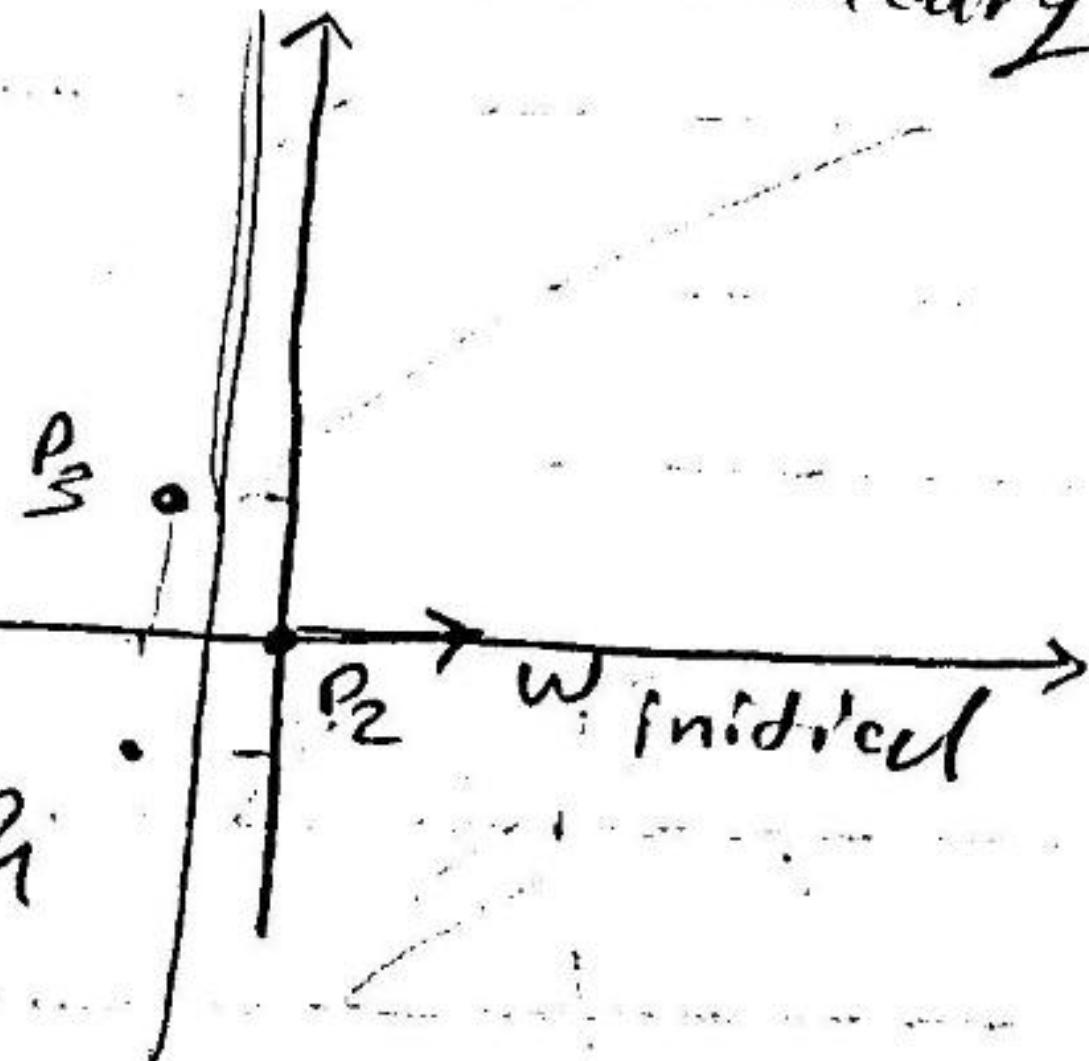
(v) To demonstrate the condition we first plot the points and decision boundary



If we include P_6 to the dataset, they could not be able to be linearly separated. So the answer is No, we cannot classify P_6 correctly while the others outputs are classified correct!

Ex. 8

initial decision boundary



(i)

P_1 is correctly classified and P_2, P_3 are misclassified

(ii)

From the training set it is obvious that hardlim function is used.

$$a_1 = \text{hardlim}(w^T P_1 + b) = \text{hardlim}([1 \ 0] [1 \ 0] + 0.5) = 0 \checkmark$$

-0.5

$$\text{as } b - a_1 = 0 - 0.5 = 0.5 \Rightarrow w^{\text{new}} = w^{\text{old}} + e P_1$$

$$b^{\text{new}} = b^{\text{old}} + e^0$$

$$a_2 = \text{hardlim}([1 \ 0] [0 \ 1] + 0.5) = 1 \times$$

0.5

$$\text{as } 0 - 1 = -1$$

$$w^{\text{new}} = [1 \ 0] - [0 \ 1] = [1 \ -1]$$

$$a_3 = \text{hardlim}([1 \ 0] [-1 \ 1] + 0.5) = 0 \times$$

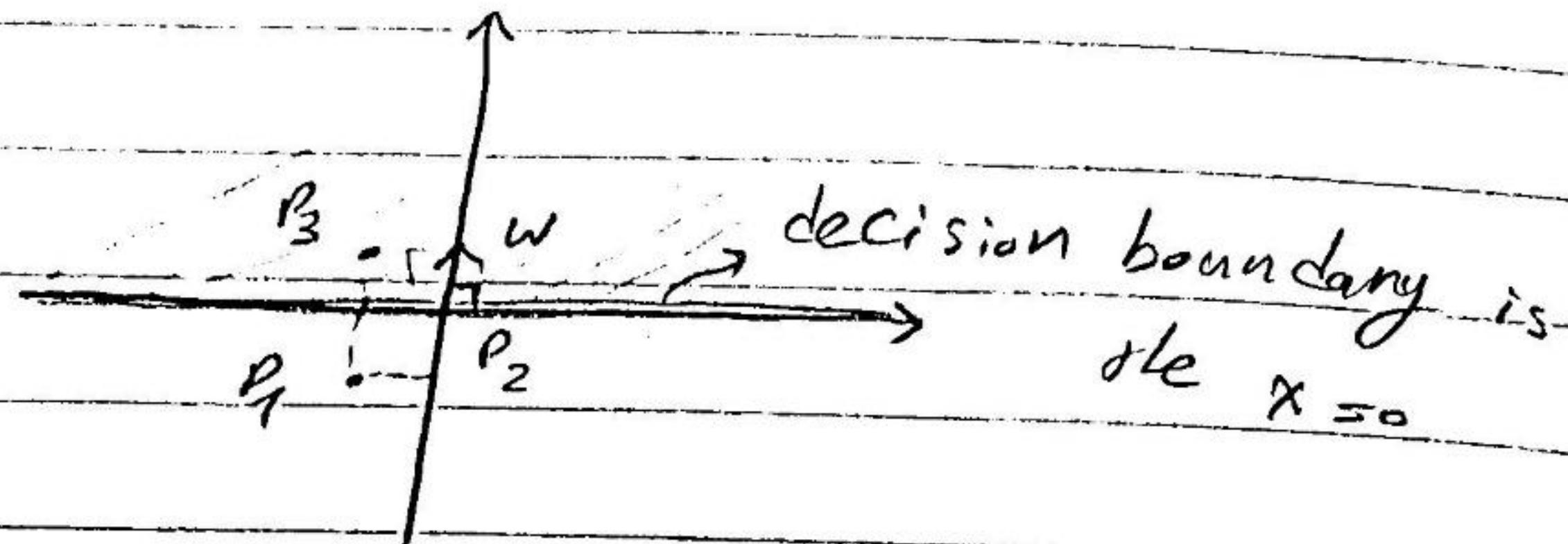
-1.5

$$\text{as } 1 - 0 = 1$$

$$w^{\text{new}} = [1 \ 0] + 1[-1 \ 1] = [1 \ 1] \quad b^{\text{new}} = -1 + 1 = 0$$

64.8 Continue

(iii)



here P_3 and P_1 was correctly classified
But P_2 wasn't because it is on the decision boundary.

(iv)

of course it will learn the pattern. Because
the training data is linearly separable.

The answer to the question here is also Yes.
No matter the initial weight are eventually
the perceptron rule will learn the data patterns.
The difference between weights are the
various

learning process may take longer time or less.

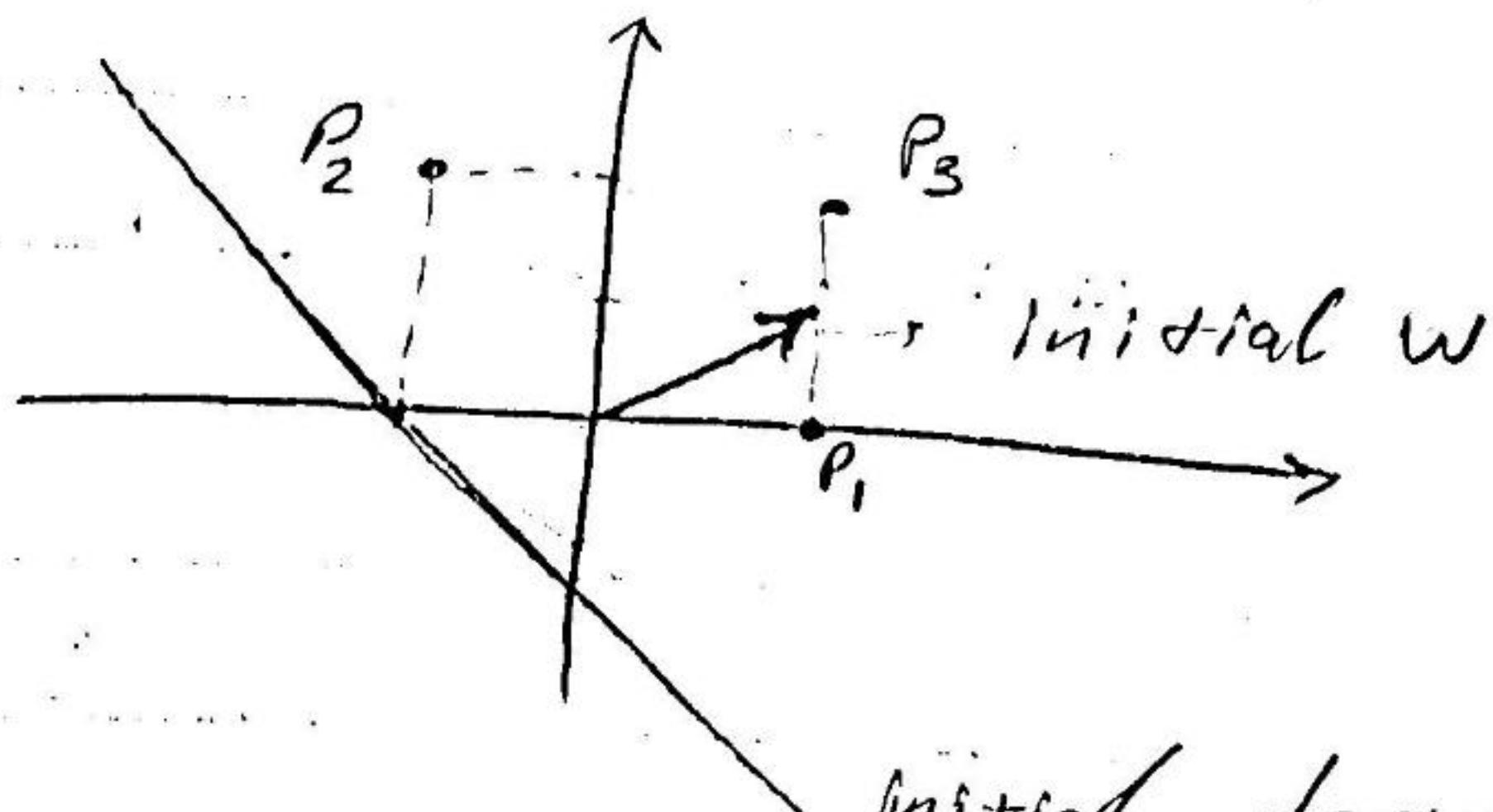
E4.9

(i)

$$P_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}, t_1 = 0$$

$$P_2 = \begin{bmatrix} -1 \\ 2 \end{bmatrix}, t_2 = 0$$

$$P_3 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}, t_3 = 1$$



Initial decision boundary

$$w^T P_3 + b = [0 \ 1] \begin{bmatrix} 1 \\ 2 \end{bmatrix} + 1 = 3 \xrightarrow{\text{hardlim function}} a_3 = 1$$

Only the third point is correctly classified.

$$w^T P_2 + b = [0 \ 1] \begin{bmatrix} -1 \\ 2 \end{bmatrix} + 1 = 3 \xrightarrow{\text{hardlim}} a_2 = 1 \quad X \quad \text{does not correctly classify}$$

$$w^T P_1 + b = [0 \ 1] \begin{bmatrix} 1 \\ 0 \end{bmatrix} + 1 = 1 \xrightarrow{\text{hardlim}} a_1 = 1 \quad X \quad \text{correctly classified}$$

(ii) To reform weight vector we define

The weight again by perceptron learning rule

$$w_{\text{new}} = w_{\text{old}} + e \rho$$

$$e = t - a$$

For P_1 :

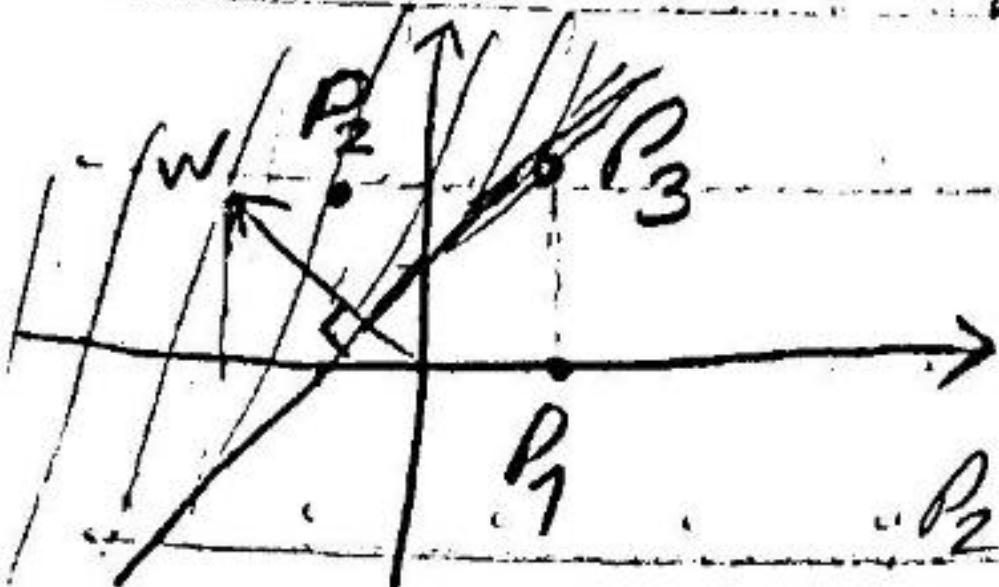
$$w_{\text{new}} = \begin{bmatrix} 0 \\ 1 \end{bmatrix} + (0-1) \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \end{bmatrix}$$

$$(iii) b_{\text{new}} = b_{\text{old}} + e = 1 - 1 = 0$$

Then for P_2 :

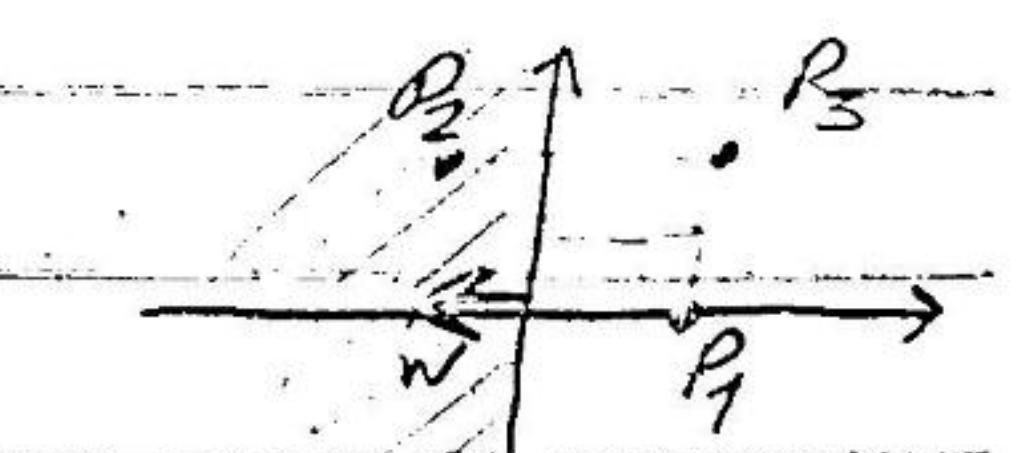
$$a_2 = \text{hardlim} \left([-1 \ 0] \begin{bmatrix} -1 \\ 2 \end{bmatrix} + 0 \right) = \text{hardlim} (1) = 1$$

$$w_{\text{new}} = \begin{bmatrix} -1 \\ 0 \end{bmatrix} + (1-0) \begin{bmatrix} -1 \\ 2 \end{bmatrix} = \begin{bmatrix} -2 \\ 2 \end{bmatrix}$$



$$b = 0 + 1 = 1$$

P_2 and P_1 are misclassified.



P_1, P_2, P_3 are misclassified!

 (iv)

try P_3 :

$$a_3 = \text{hardlim}([-2 \ -2] \begin{bmatrix} 1 \\ 2 \end{bmatrix} + 1) = \text{hardlim}(3) = 1$$

$$e = b - a = 1 - 1 = 0 \Rightarrow w^{\text{new}} = w^{\text{old}}$$

(v) $\rightarrow P_1$ and P_2 are misclassified
try the points:

P_1 :

$$a_1 = \text{hardlim}([-2 \ -2] \begin{bmatrix} 1 \\ 0 \end{bmatrix} + 1) = \text{hardlim}(-1) = 0$$

$$e = b - a = 0 - 0 = 0 \Rightarrow w^{\text{new}} = w^{\text{old}}, b^{\text{new}} = b^{\text{old}}$$

P_2 :

$$a_2 = \text{hardlim}([-2 \ -2] \begin{bmatrix} -1 \\ 2 \end{bmatrix} + 1) = \text{hardlim}(6) = 1$$

$$e = a - 1 = -1 \Rightarrow w^{\text{new}} = \begin{bmatrix} -2 \\ 2 \end{bmatrix} - \begin{bmatrix} -1 \\ 2 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \end{bmatrix}$$

$$b^{\text{new}} = b^{\text{old}} + e = 1 - 1 = 0$$

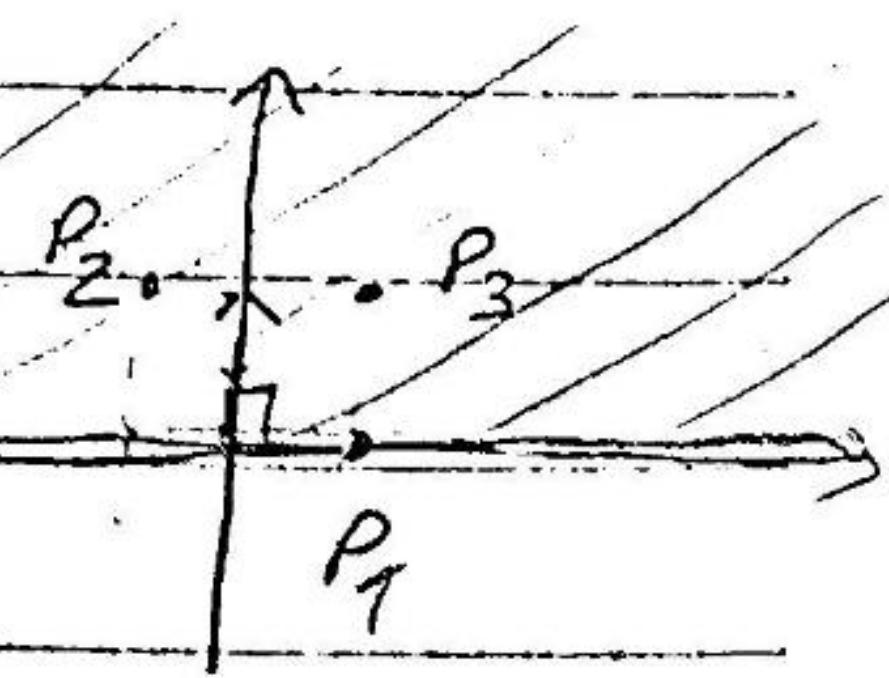
P_3 :

$$a_3 = \text{hardlim}([1 \ 0] \begin{bmatrix} 1 \\ 2 \end{bmatrix} + 0) = \text{hardlim}(-1) = 0$$

$$e = b - a = 0 - 0 = 0$$

$$w^{\text{new}} = \begin{bmatrix} -1 \\ 0 \end{bmatrix} + \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 0 \\ 2 \end{bmatrix} \quad b^{\text{new}} = 0 + 1 = 1$$

$P_2, P_1 \rightarrow$ are misclassified



(vi)

If we continue the loop of learning
eventually we can find the answer.

Because the points can be linearly separated

Section 6.8

Ex 1

To test that any ^{vector} vectors are independent we must prove that the matrix has inverse and coefficients are set to zero.

(i) $\begin{bmatrix} 1 & 1 & 1 \\ 2 & 0 & 2 \\ 3 & 1 & 1 \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix} = 0$

A

$$\det(A) = \begin{vmatrix} 1 & 1 & 1 \\ 2 & 0 & 2 \\ 3 & 1 & 1 \end{vmatrix} = 2 - 2 = 0$$

as we can see here the determinant of A is zero! so its values meaning the vectors in part (i) are correlated. we can say they are dependent.

(ii)

$\sin t, \cos t, \cos 2t$

we can say that if we find one of the vectors that can be the result of sum of the other vectors, then there is an answer that we can project vectors into less vector space

$$\begin{aligned} \cos(2t) &= \cos(t+t) = \cos(t)\cos(t) - \sin(t)\sin(t) \\ &= \cos^2(t) - \sin^2(t) \end{aligned}$$

The combination is not linear so we cannot find a vector from the others. therefore vectors are independent



b b. 8 continue

(ii) Let $t = 1-t$

there is no way we could find one from the other, so we can say these vectors are independent.

$$(iv) \quad x_1 = \begin{bmatrix} 1 \\ 2 \\ 2 \\ 1 \end{bmatrix}, \quad x_2 = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \end{bmatrix}, \quad x_3 = \begin{bmatrix} 3 \\ 4 \\ 4 \\ 3 \end{bmatrix}$$

we create the gramian matrix

Gramian matrix $\rightarrow A$,
(it is the inner product
of each vector)

$$A = \begin{bmatrix} x_1 \cdot x_1 & x_1 \cdot x_2 & x_1 \cdot x_3 \\ x_2 \cdot x_1 & x_2 \cdot x_2 & x_2 \cdot x_3 \\ x_3 \cdot x_1 & x_3 \cdot x_2 & x_3 \cdot x_3 \end{bmatrix}$$

$$A = \begin{bmatrix} 10 & 2 & 22 \\ 2 & 2 & 6 \\ 22 & 6 & 50 \end{bmatrix}$$

$$\det(A) = \begin{vmatrix} 10 & 2 & 22 & | & 2 & 22 \\ 2 & 2 & 6 & | & 2 & 6 \\ 22 & 6 & 50 & | & 6 & 50 \end{vmatrix} =$$

$$= (1000 + 72 + 2200) - (44 * 22 + 72 + 2200) \neq 0$$

so as we can see determinant is not zero
in result it can be said that vectors are
independent!

E 5.10

$$\mathcal{Z}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \quad \mathcal{Z}_2 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \quad \mathcal{Z}_3 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

In Gram-Schmidt orthogonalization the first vector was equal to \mathcal{Z}_1 , so

$$v_1 = \mathcal{Z}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

then to find other vectors:

$$v_k = \mathcal{Z}_k - \sum_{i=1}^{k-1} \frac{v_i^T \mathcal{Z}_k}{v_i^T v_i} v_i \quad \text{we remove the projection of the other vectors!}$$

$$v_2 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} - \frac{v_1^T \mathcal{Z}_2}{v_1^T v_1} v_1 \Rightarrow v_2 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} - \frac{\begin{bmatrix} 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}}{\begin{bmatrix} 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 0 & 0 \end{bmatrix}} \begin{bmatrix} 1 \\ 0 & 0 \end{bmatrix}$$

$$\Rightarrow v_2 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} - \frac{1}{1} \begin{bmatrix} 1 \\ 0 & 0 \end{bmatrix} \Rightarrow v_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

$$v_3 = \mathcal{Z}_3 - \frac{v_2^T \mathcal{Z}_3}{v_2^T v_2} v_2 - \frac{v_1^T \mathcal{Z}_3}{v_1^T v_1} v_1$$

$$\Rightarrow v_3 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} - \frac{\begin{bmatrix} 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}}{\begin{bmatrix} 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 & 0 \end{bmatrix}} \begin{bmatrix} 0 & 1 & 0 \end{bmatrix} - \frac{\begin{bmatrix} 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}}{\begin{bmatrix} 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 0 & 0 \end{bmatrix}} \begin{bmatrix} 1 & 0 & 0 \end{bmatrix}$$

$$\Rightarrow v_3 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} - \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} - \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

So the $\mathcal{Z}_1, \mathcal{Z}_2, \mathcal{Z}_3$ was projected onto v_1, v_2, v_3



Ex. 11

(i) To show that f_1, f_2, f_3 are linearly independent, we must prove that one of them cannot be calculated from the other.

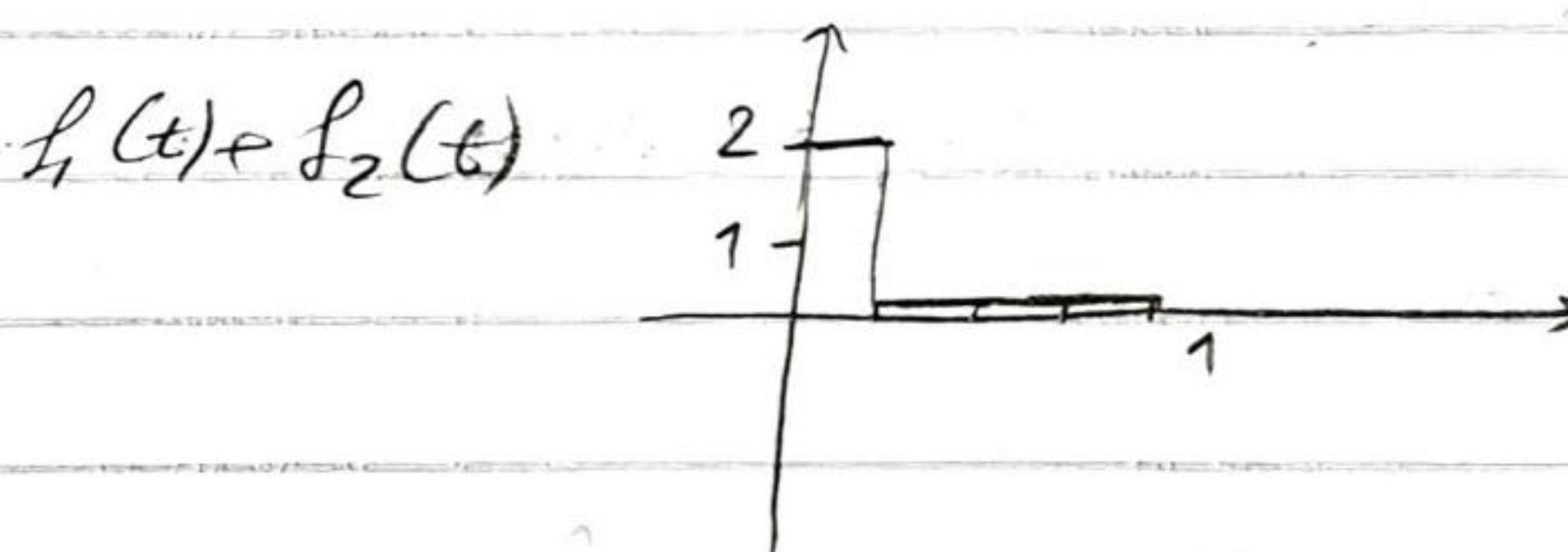
There are 3 combination of f functions than can show they are dependent.

$$a_1 f_1(t) + a_2 f_2(t) = f_3(t) \quad (1)$$

$$a_2 f_2(t) + a_3 f_3(t) = f_1(t) \quad (2)$$

$$a_1 f_1(t) + a_3 f_3(t) = f_2(t) \quad (3)$$

We try (1) with coefficients equal to 1



In general with unknown coefficients

$a_1 f_1(t) + a_2 f_2(t)$ equation will be:

$$a_1 f_1(t) + a_2 f_2(t) = \begin{cases} a_1 + a_2 & 0 \leq t \leq \frac{1}{4} \\ a_1 - a_2 & \frac{1}{4} < t \leq 1 \\ 0 & \text{o.w.} \end{cases}$$

$$f_3(t) = \begin{cases} 1 & 0 \leq t < \frac{3}{4} \\ -1 & \frac{3}{4} \leq t < 1 \end{cases}$$

there is no linear combination for (1).

$$0 \leq t \leq \frac{3}{4} \rightarrow \begin{cases} a_1 + a_2 = 1 \\ a_1 + a_2 = -1 \end{cases}$$

equation

6.5.11 continued

The equation (1) would not be ever satisfied so we try the (2) and

$$a_2 f_2(t) + a_3 f_3(t) = \begin{cases} a_2 + a_3 & 0 \leq t \leq \frac{1}{4} \\ a_3 - a_2 & \frac{1}{4} < t \leq \frac{3}{4} \\ -a_3 - a_2 & \frac{3}{4} < t \leq 1 \\ 0 & \text{o.w.} \end{cases}$$

$$f_2(t) = \begin{cases} 1 & 0 \leq t \leq 1 \\ 0 & \text{o.w.} \end{cases}$$

, so the equations below must be satisfied,

$$\begin{cases} a_2 + a_3 = 1 \\ a_3 - a_2 = 1 \\ -a_3 - a_2 = 1 \Rightarrow a_2 + a_3 = -1 \end{cases}$$

∴ there is no answer for a_3 and a_2

So until now equations (1) and (2) was incorrect! we try the 3rd to show the functions are dependent.

$$(2) \rightarrow a_1 f_1(t) + a_3 f_3(t) = \begin{cases} a_1 + a_3 & 0 \leq t \leq \frac{3}{4} \\ a_1 - a_3 & \frac{3}{4} < t \leq 1 \\ 0 & \text{o.w.} \end{cases}$$

$$f_2(t) = \begin{cases} 1 & 0 \leq t \leq \frac{1}{4} \\ -1 & \frac{1}{4} < t \leq 1 \\ 0 & \text{o.w.} \end{cases}$$

so for $a_1 + a_3$ we find 1 and Again there is no answer for this equation

E6.11 Continue

we proved that there is no answer for (1), (2) and (3). In the results we can determine that the set $\{f_1, f_2, f_3\}$ are linearly independent.

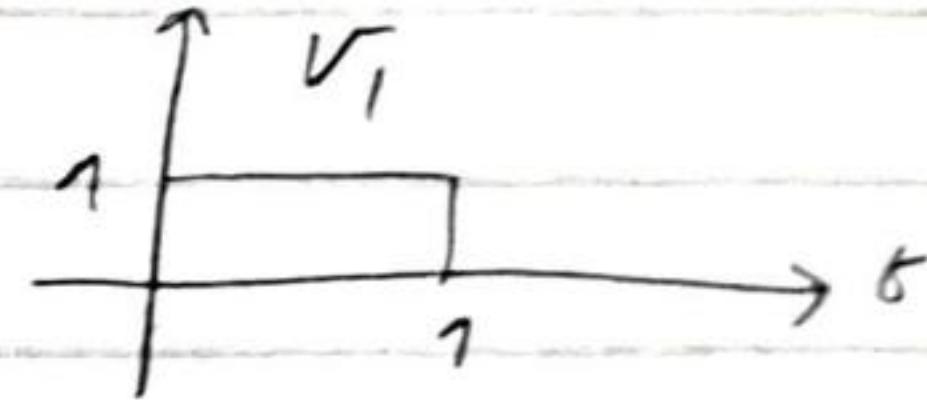
(ii)

Gram-schmidt procedure

$$v_i = y_i \quad v_k = y_k - \sum_{i=1}^{k-1} \frac{v_i y_k}{v_i \cdot v_i} v_i$$

$$\text{as the question said} \rightarrow (Lg) = \int_0^1 L(t) g(t) dt$$

$$\text{so for } v_1 = f_1(t)$$



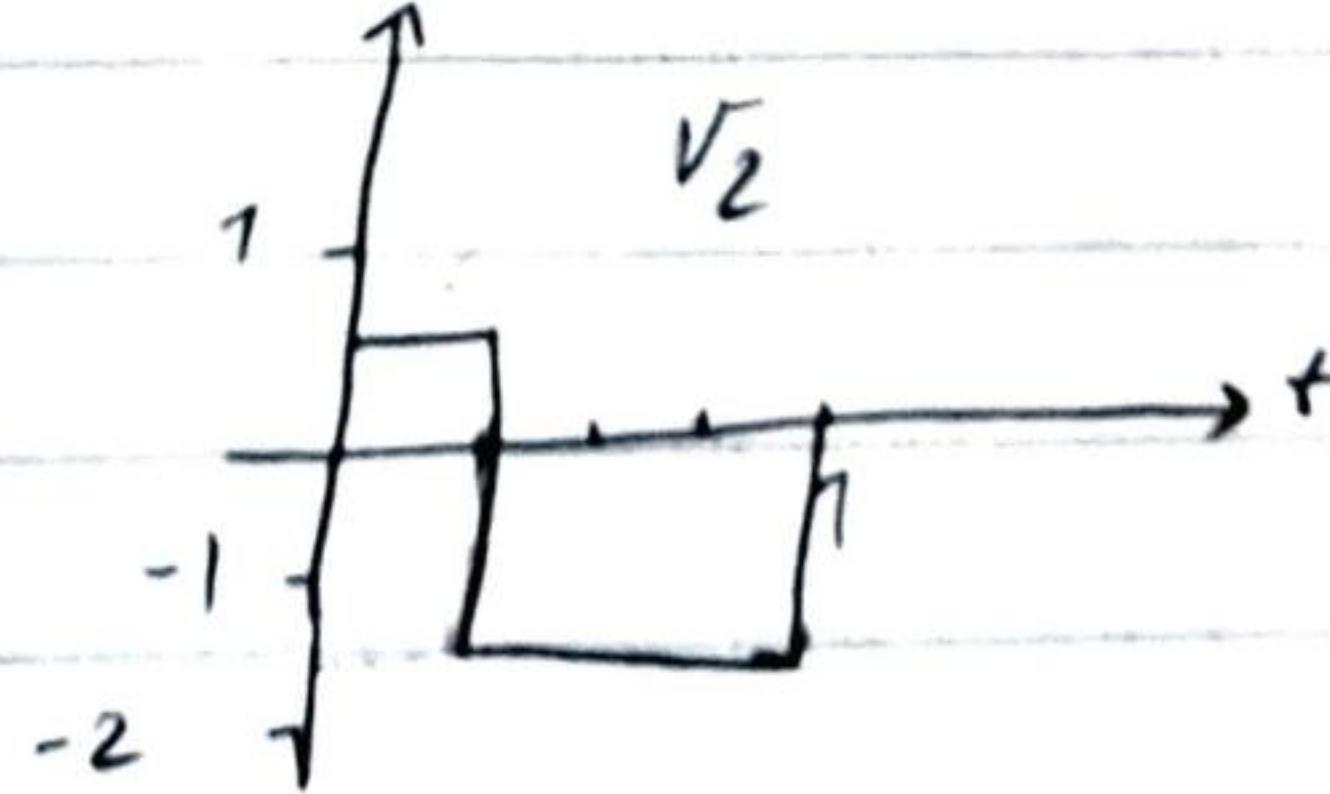
$$v_2 = f_2(t) - \frac{v_1 \cdot f_2(t)}{v_1 \cdot v_1} \cdot v_1$$

$$v_1 \cdot f_2(t) = \int_0^1 f_1(t) f_2(t) dt = \int_0^{\frac{1}{4}} 1 dt + \int_{\frac{1}{4}}^1 2x-1 dt$$

$$= \frac{1}{4} + \left(-1 + \frac{1}{4} \right) = -\frac{1}{2}$$

$$v_1 \cdot v_1 = \int_0^1 1 \cdot 1 dt = 1$$

$$v_2 = f_2(t) - \frac{1}{2} v_1$$



Ex. 11 continue

$$v_3 = f_3(t) - \frac{v_1 f_3(t)}{v_1 \cdot v_2} v_1 - \frac{v_2 f_3(t)}{v_2 \cdot v_2} v_2$$

$$\begin{aligned} v_1 \cdot f_3(t) &= \int_0^1 v_1 f_3(t) dt = \int_0^{\frac{3}{4}} 1 \cdot 1 dt + \int_{\frac{3}{4}}^1 1 \cdot (-1) dt \\ &= \frac{3}{4} + \left(-1 - \left(-\frac{3}{4} \right) \right) = \frac{2}{4} = \frac{1}{2} \end{aligned}$$

$v_1, v_2 = 1 \rightsquigarrow$ as we calculated before.

$$\begin{aligned} v_2 \cdot f_3(t) &= \int_0^1 v_2 \cdot f_3(t) dt = \int_0^{\frac{1}{4}} 1 \cdot 1 dt + \int_{\frac{1}{4}}^{\frac{3}{4}} -\frac{3}{2} \cdot 1 dt \\ &\quad + \int_{\frac{3}{4}}^1 -\frac{3}{2} \cdot -1 dt = \frac{1}{4} - \frac{3}{2} \left(\frac{3}{4} - \frac{1}{4} \right) + \frac{3}{2} \left(1 - \frac{3}{4} \right) \end{aligned}$$

$$\Rightarrow v_2 \cdot f_3(t) = \frac{1}{4} - \frac{3}{4} + \frac{3}{8} = \frac{2-6+3}{8} = -\frac{1}{8}$$

$$\begin{aligned} v_2 \cdot v_2 &= \int_0^1 v_2 \cdot v_2 dt = \int_0^{\frac{1}{4}} 1 dt + \int_{\frac{1}{4}}^1 -\frac{3}{2} \cdot -\frac{3}{2} dt \\ &= \frac{1}{4} + \frac{9}{4} \left(1 - \frac{1}{4} \right) = \frac{1}{4} + \frac{27}{16} = \frac{31}{16} \end{aligned}$$

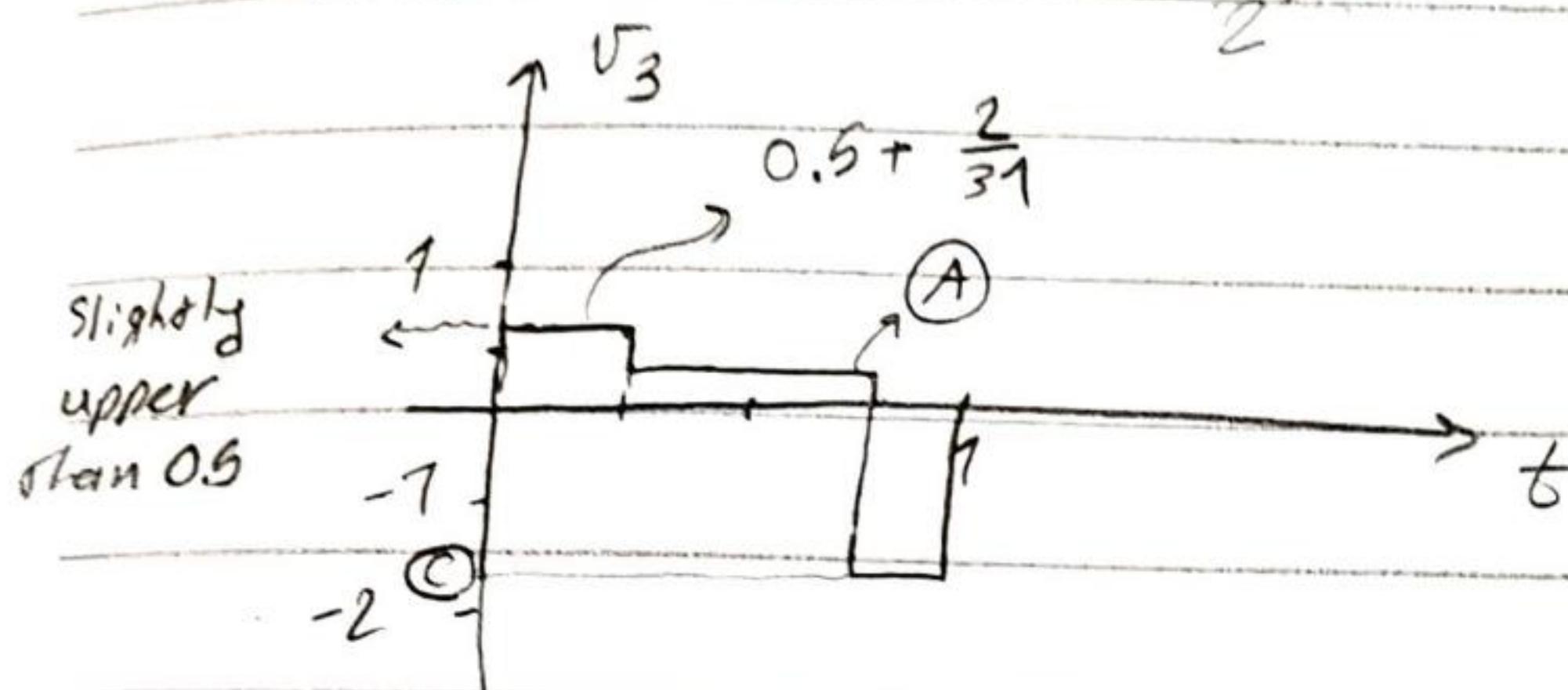
So v_3 now can be found as

$$v_3 = f_3(t) - \frac{1}{2} v_1 - \frac{-\frac{1}{8}}{\frac{31}{16}} v_2 \Rightarrow \text{next page}$$

E5.11 Continue

$$\frac{2}{31}$$

$$v_3 = f_3(t) - \frac{1}{2} v_1 + \frac{\frac{1}{8}}{\frac{31}{16}} v_2$$



$$-\frac{3}{2} \times \frac{2}{31} = -\frac{3}{31}$$

$$A \rightarrow 0.5 - \frac{3}{31}$$

$$C \rightarrow -\frac{3}{2} - \frac{2}{31} \times \frac{3}{2}$$

E5.15

orthogonal

(i) In Gram Schmidt method the first vector is the same as the first vector of the question. So we have

$$g_1 = f_1$$

$$g_k = f_k - \sum_{i=1}^{k-1} \frac{g_i f_k}{g_i \cdot g_i} g_i$$

$$g_2 = f_2 - \frac{g_1 \cdot f_2}{g_1 \cdot g_1} g_1$$

$$g_1 \cdot f_2 = \int_0^1 g_1(t) f_2(t) dt = \int_0^1 1(1-t) dt = t - \frac{t^2}{2} \Big|_0^1$$

$$\Rightarrow g_1 \cdot f_2 = (1 - \frac{1}{2}) - 0 = \frac{1}{2}$$

$$g_1 \cdot g_1 = \int_0^1 g_1(t) g_1(t) dt = \int_0^1 1 dt = 1$$

$$g_2(t) = \begin{cases} 1-t - \frac{1}{2}(1) = 0.5 - t & 0 < t < 1 \\ 0 & \text{otherwise} \end{cases}$$

E5.14



(i)

$$v_1 = \begin{bmatrix} 1 \\ -1 \end{bmatrix} \quad v_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

transform
matrix

$$A = \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix}$$

$$x = v_1 + v_2 \rightsquigarrow \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

expansion for $x \rightarrow \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 2 \\ 0 \end{bmatrix}$

$$\Rightarrow x = 2s_1 + 0(s_2)$$

(ii)

$$y = 1s_1 + 1s_2 \rightsquigarrow \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

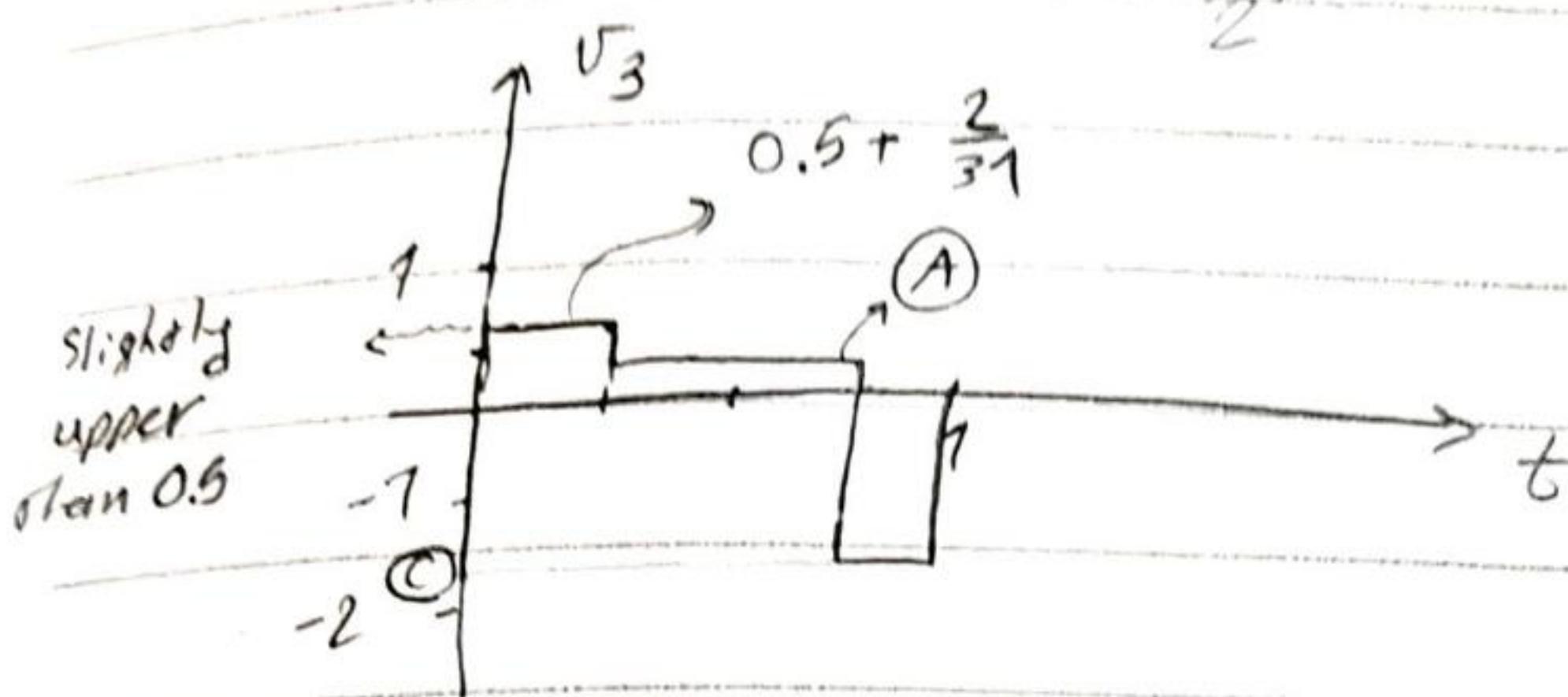
$$\bar{A}^{-1} = \frac{1}{1-(-1)} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & -\frac{1}{2} \\ \frac{1}{2} & 1 \end{bmatrix}$$

$$\bar{A}^{-1} y = \begin{bmatrix} \frac{1}{2} & -\frac{1}{2} \\ \frac{1}{2} & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ \frac{3}{2} \end{bmatrix} \Rightarrow y = (0)v_1 + \frac{3}{2}v_2$$

66.11 (continue)

2
31

$$v_3 = f_3(t) - \frac{1}{2} v_1 + \frac{\frac{1}{8}}{\frac{31}{16}} v_2$$



$$-\frac{3}{2} \times \frac{1}{31} = -\frac{3}{31}$$

$$\textcircled{A} \rightarrow 0.5 - \frac{3}{31}$$

$$\textcircled{C} \rightarrow -\frac{3}{2} - \frac{2}{31} \times \frac{3}{2}$$

66.19

orthogonal

(i) In Gram Schmidt method the first vector is the same as the first vector of the question. So we have

$$g_1 = f_1$$

$$g_k = f_k - \sum_{i=1}^{k-1} \frac{g_i f_k}{g_i \cdot g_i} g_i$$

$$g_2 = f_2 - \frac{g_1 \cdot f_2}{g_1 \cdot g_1} g_1$$

$$g_1 \cdot f_2 = \int_0^1 g_1(t) f_2(t) dt = \int_0^1 1(1-t) dt = t - \frac{t^2}{2} \Big|_0^1$$

$$\Rightarrow g_1 \cdot f_2 = (1 - \frac{1}{2}) - 0 = \frac{1}{2}$$

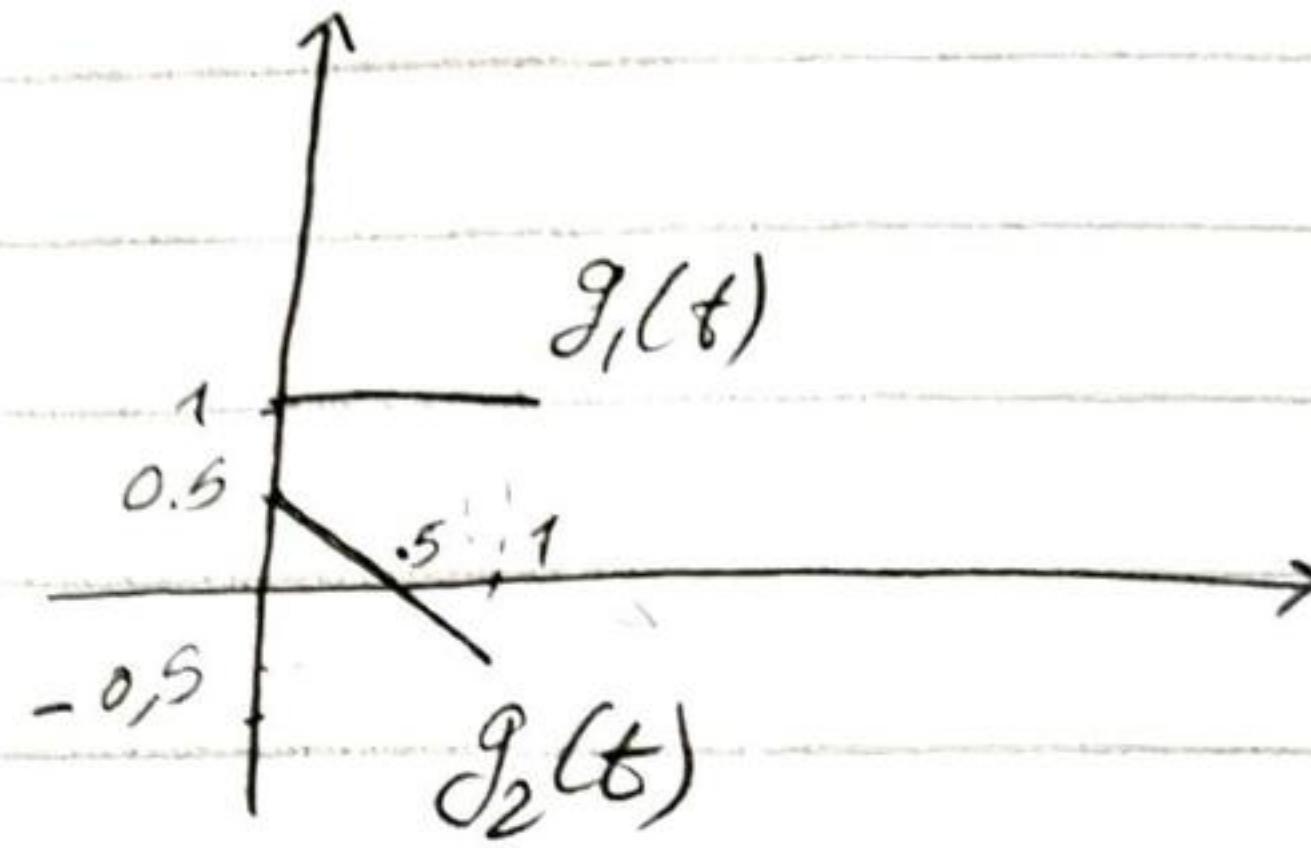
$$g_1 \cdot g_1 = \int_0^1 g_1(t) g_1(t) dt = \int_0^1 1 dt = 1$$

$$g_2(t) = \begin{cases} 1-t - \frac{1}{2}(1) = 0.5 - t & 0 < t < 1 \\ 0 & \text{otherwise} \end{cases}$$



Continue

65.15 (



(ii)

$$x_j = \frac{v_j \cdot x}{(v_j \cdot v_j)}$$

$$h_1(t) = \frac{g_1(t) \cdot h(t)}{g_1(t) \cdot g_1(t)}$$

$$h_2(t) = \frac{g_2(t) \cdot h(t)}{g_2(t) \cdot g_2(t)}$$

$$g_1(t) \cdot h(t) = \int_0^t (t-1) \cdot 1 dt = \left[\frac{t^2}{2} - t \right]_0^1 = \frac{1}{2} - 1 = -\frac{1}{2}$$

$$g_1(t) \cdot g_1(t) = \int_0^1 1 \cdot 1 dt = 1$$

$$h_1(t) = \frac{-\frac{1}{2}}{1} = -\frac{1}{2} \quad \checkmark$$

$$g_2(t) \cdot h(t) = \int_0^1 (\frac{1}{2}-t)(t-1) dt = \int_0^1 -t^2 + \frac{3}{2}t - \frac{1}{2} dt$$

$$= \left[-\frac{t^3}{3} + \frac{3t^2}{4} - \frac{t}{2} \right]_0^1 = \left(-\frac{1}{3} + \frac{3}{4} - \frac{1}{2} \right) - 0 = \frac{-4+9-6}{12} = -\frac{1}{12}$$

$$g_2(t) \cdot g_2(t) = \int_0^1 \left(\frac{1}{2} - \frac{1}{2}(t-\frac{1}{2}) \right)^2 dt = \int_0^1 \frac{1}{4} + t^2 - t dt = \left[\frac{t}{4} + \frac{t^3}{3} - \frac{t^2}{2} \right]_0^1$$

$$= \frac{1}{4} + \frac{1}{3} - \frac{1}{2} = \frac{3+4-6}{12} = \frac{1}{12}$$

$$\Rightarrow h_2(t) = \frac{-\frac{1}{12}}{\frac{1}{12}} = -1$$

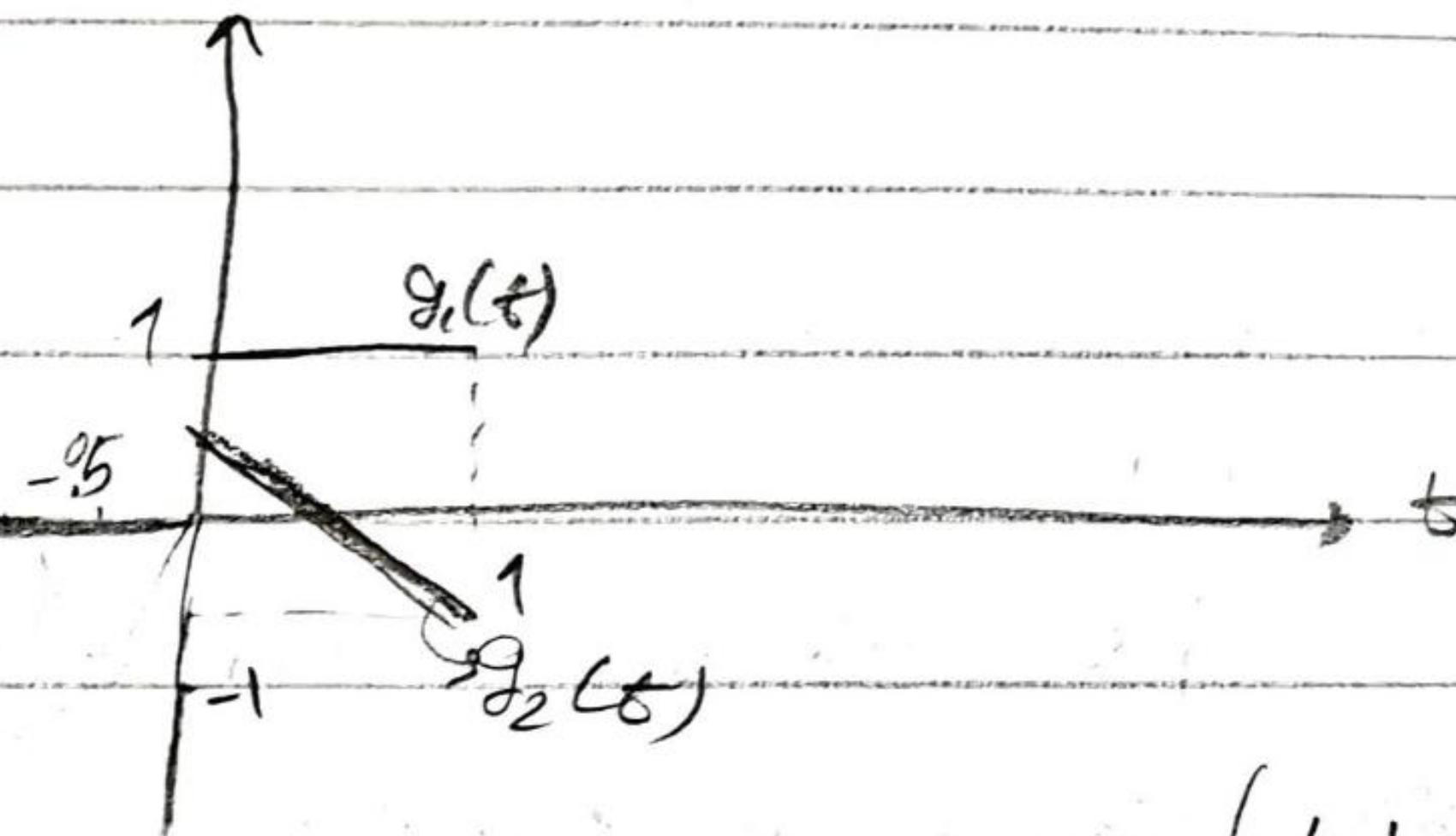
6.6.15 continue

we have found:

$$h_1 = -\frac{1}{2} \quad h_2 = -1$$

$$g_1(t) = \begin{cases} 1 & 0 < t < 1 \\ 0 & \text{o.w.} \end{cases}$$

$$g_2(t) = \begin{cases} \frac{1}{2} - t & 0 < t < 1 \\ 0 & \text{o.w.} \end{cases}$$



$$h_{\text{new}}(t) = -0.5g_1(t) - g_2(t) \Rightarrow h_{\text{new}}(t) = \begin{cases} -\frac{1}{2} - \frac{1}{2} + t = t - 1 & 0 < t < 1 \\ 0 & \text{o.w.} \end{cases}$$

As we can see we again find "t-1" for h function! this shows that our calculation is completely correct!

E6.1F(

$$S_1^t = \begin{bmatrix} 1 & 0 \\ 1 & 0 \end{bmatrix} \quad S_2^t = \begin{bmatrix} 0 & 1 \\ 0 & 1 \end{bmatrix}$$

$$u_1^t = \begin{bmatrix} 2 & 0 \\ 0 & 0 \end{bmatrix} \quad u_2^t = \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix} \quad x = \begin{bmatrix} -2 \\ 2 \end{bmatrix}$$

(i)

$$x_1 = \frac{S_1^t \cdot x}{S_1^t \cdot S_1} \rightarrow x_1 = \frac{\begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} -2 \\ 2 \end{bmatrix}}{\begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 \end{bmatrix}} = \frac{-2}{1} \quad \rightarrow x = \begin{bmatrix} -2 \\ 2 \end{bmatrix}$$

$$x_2 = \frac{S_2^t \cdot x}{S_2^t \cdot S_2} = \frac{\begin{bmatrix} 0 & 1 \end{bmatrix} \begin{bmatrix} -2 \\ 2 \end{bmatrix}}{\begin{bmatrix} 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 \end{bmatrix}} = \frac{2}{1}$$

we can see that the expansion with basis set would result the same vector.

(ii)

$$u_{11} = \frac{S_1^t \cdot u_1}{S_1^t \cdot S_1} = \frac{\begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} 2 \\ 0 \end{bmatrix}}{\begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 \end{bmatrix}} = \frac{2}{1} \quad u_{12} = \frac{S_2^t \cdot u_1}{S_2^t \cdot S_2} = \frac{\begin{bmatrix} 0 & 1 \end{bmatrix} \begin{bmatrix} 2 \\ 0 \end{bmatrix}}{\begin{bmatrix} 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 \end{bmatrix}} = 0$$

$$u_1^t = [u_{11} \ u_{12}] = [2 \ 0] \rightsquigarrow \text{the same as before}$$

$$u_{21} = \frac{S_1^t \cdot u_2}{S_1^t \cdot S_1} = \frac{\begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} -1 \\ 1 \end{bmatrix}}{\begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 \end{bmatrix}} = \frac{-1}{1} = -1 \quad \rightarrow u_2^t = [-1 \ -1]$$

$$u_{22} = \frac{S_2^t \cdot u_2}{S_2^t \cdot S_2} = \frac{\begin{bmatrix} 0 & 1 \end{bmatrix} \begin{bmatrix} -1 \\ 1 \end{bmatrix}}{\begin{bmatrix} 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 \end{bmatrix}} = \frac{1}{1} = 1 \quad \text{the same as before}$$

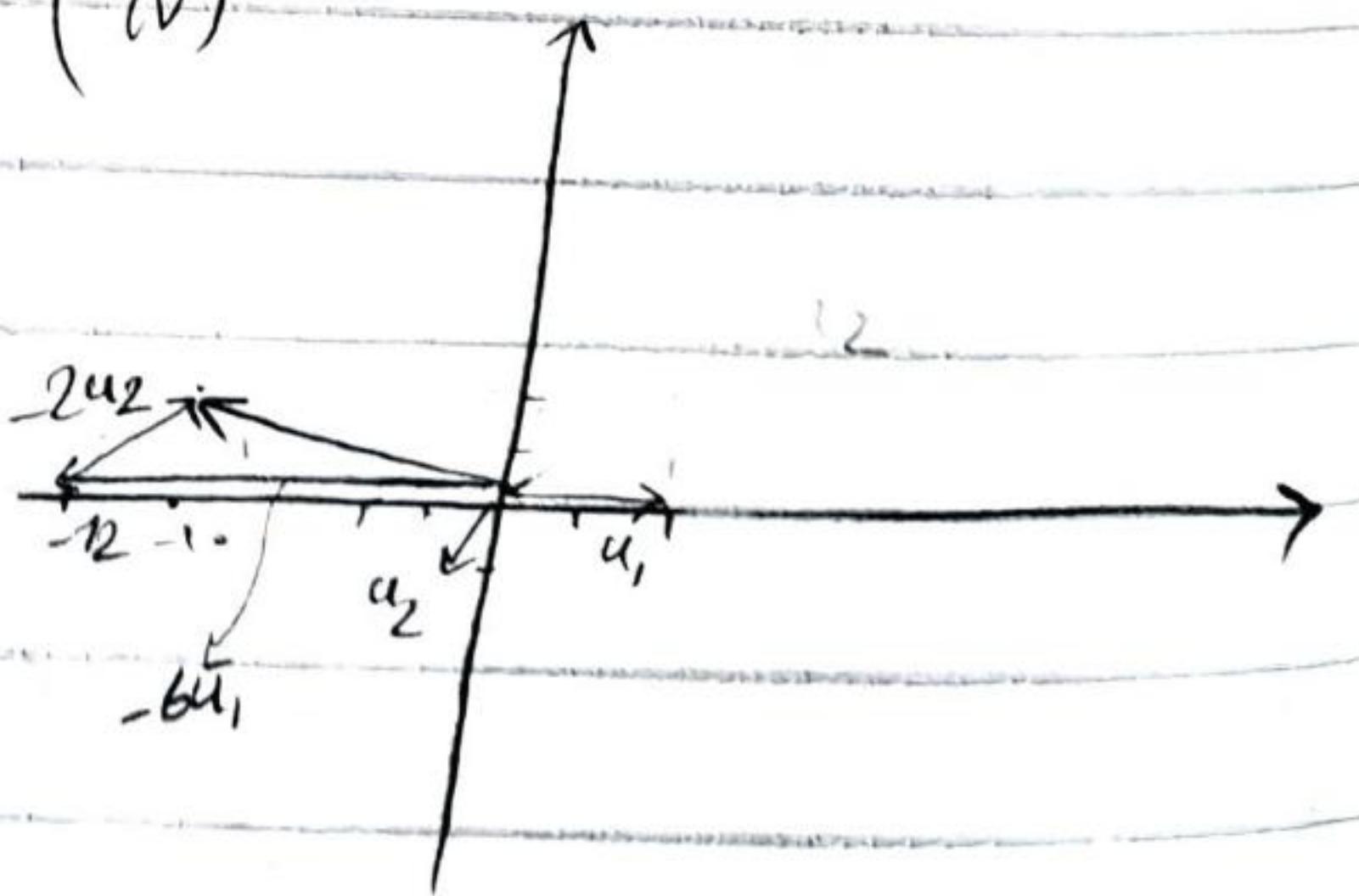
(iii)

$$R^T = B^{-1} = \begin{bmatrix} 2 & -1 \\ 0 & -1 \end{bmatrix} \quad \text{(iv)}$$

u_1 u_2

$$x_{\text{projected}} = \begin{bmatrix} 2 & -1 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} -2 \\ 2 \end{bmatrix} = \begin{bmatrix} -6 \\ -2 \end{bmatrix}$$

$$x_{\text{projected}} = -6u_1 - 2u_2$$



6.6.3)

$$A(v_1) = S_1 + S_2 \rightsquigarrow \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

(i) $A(v_2) = -S_2 + (-)S_1 \rightsquigarrow \begin{bmatrix} -1 \\ 1 \end{bmatrix}$

$$A = \begin{bmatrix} 1 & 0 \\ 1 & -1 \end{bmatrix}$$

(ii)

$$v_1 = 2S_1 + S_2$$

$$v_2 = -S_1 + 2S_2 \rightsquigarrow B_E = \begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix}$$

$$A' = \begin{bmatrix} B_E^{-1} & A & B_E \end{bmatrix}$$

$$B_E = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \xrightarrow{\theta=90^\circ} \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$$

$$\bar{B}^{-1} = \frac{1}{|B|} \begin{bmatrix} 2 & 1 \\ -1 & 2 \end{bmatrix} \quad |B| = 4 - (-1) = 5$$

$$\Rightarrow \bar{B}^{-1} = \begin{bmatrix} \frac{2}{5} & \frac{1}{5} \\ -\frac{1}{5} & \frac{2}{5} \end{bmatrix}$$

$$\bar{B}^{-1} A = \begin{bmatrix} \frac{2}{5} & \frac{1}{5} \\ -\frac{1}{5} & \frac{2}{5} \end{bmatrix} \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} \frac{1}{5} & \frac{2}{5} \\ \frac{2}{5} & \frac{1}{5} \end{bmatrix}$$

$$\bar{B}^{-1} A B = \begin{bmatrix} \frac{1}{5} & \frac{2}{5} \\ \frac{2}{5} & \frac{1}{5} \end{bmatrix} \begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix} = \begin{bmatrix} \frac{4}{5} & \frac{3}{5} \\ \frac{3}{5} & \frac{4}{5} \end{bmatrix} = I$$

$$\Rightarrow A' = \begin{bmatrix} \frac{4}{5} & \frac{3}{5} \\ \frac{3}{5} & \frac{4}{5} \end{bmatrix}$$

$$x = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \quad x' = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$j = Ax = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

$$j' = A'x' = \begin{bmatrix} \frac{4}{5} & \frac{3}{5} \\ \frac{3}{5} & \frac{4}{5} \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} \frac{4}{5} \\ \frac{3}{5} \end{bmatrix}$$

E6.3 continue{

To verify the results we calculate $y' = B^{-1}y$

As we have before

$$\hookrightarrow B^{-1} = \begin{bmatrix} \frac{2}{5} & \frac{1}{5} \\ -\frac{1}{5} & \frac{2}{5} \end{bmatrix}$$

$$y' = B^{-1}y \Rightarrow y' = \begin{bmatrix} \frac{2}{5} & \frac{1}{5} \\ -\frac{1}{5} & \frac{2}{5} \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} \frac{3}{5} \\ \frac{3}{5} \end{bmatrix}$$

E6.4

$$s_1 = 1+j$$

$$A(s_1) = (1+j)(1+j) = j^2 + 1 + 2j = 2j$$

$$s_2 = 1-j$$

$$(i) \quad A(s_2) = (1+j)(1-j) = 1 - j^2 = 1 - (-1) = 2$$

$$\Rightarrow A(s_1) = 2j \quad \text{can be} \quad A(s_1) = s_1 - s_2$$

$$A(s_2) = 2 \quad \xrightarrow{\text{written as}} \quad A(s_2) = s_1 + s_2$$

$$\Rightarrow A = \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix}$$

(ii) From the formula $Az = \lambda z$ we can calculate both eigen values and eigen vectors.

$$(A - \lambda B)z = 0 \Rightarrow |A - \lambda B| = 0$$

$$\left| \begin{bmatrix} 1-\lambda & 1 \\ -1 & 1-\lambda \end{bmatrix} \right| = 0 \Rightarrow (1-\lambda)^2 - 1 = 0 \Rightarrow \lambda^2 - 2\lambda + 1 - 1 = 0$$

$$\lambda^2 - 2\lambda + 2 = 0$$

$$\Delta = 4 - 4(1)(2) = -4 \rightarrow$$

$$\lambda = \frac{2 \pm \sqrt{-4}}{2} \rightarrow \lambda_1 = 1+j$$

$$\lambda_2 = 1-j$$

66.4 continued

$$A = \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix}$$

for $\lambda_1 = 1+j$

$$\begin{bmatrix} 1-(1+j) & 1 \\ -1 & 1-(1+j) \end{bmatrix} \begin{bmatrix} e_1 \\ e_2 \end{bmatrix} = 0 \Rightarrow \begin{cases} -e_1 - e_2 = 0 \xrightarrow{x(j)} e_1 + e_2 = 0 \\ -e_1 - e_2 = 0 \xrightarrow{-} -e_1 - e_2 = 0 \end{cases}$$

both equations will give the same results. so we use one of them to find the suitable answer.

$$e_1 = -e_2 \xrightarrow{e_2 = 1} \begin{bmatrix} -j \\ 1 \end{bmatrix} \rightarrow \text{first eigen vector}$$

for $\lambda_2 = 1-j$

$$\begin{bmatrix} 1-1+j & 1 \\ -1 & 1-1+j \end{bmatrix} \begin{bmatrix} e_1 \\ e_2 \end{bmatrix} = 0 \rightarrow \begin{cases} j e_1 + e_2 = 0 \xrightarrow{x(j)} -e_1 + j e_2 = 0 \\ -e_1 + j e_2 = 0 \end{cases}$$

so again the two equations are dependent. So one of them is used to find from the infinite solution set.

$$-e_1 + j e_2 = 0 \Rightarrow e_1 = j e_2 \rightarrow \begin{bmatrix} j \\ 1 \end{bmatrix}$$

so the second eigen vector was calculated

as $\begin{bmatrix} j \\ 1 \end{bmatrix}$ by $e_2 = 1$

continue

c6.4(

(iii)

$$A = [B^{-1} \hat{A} B]$$

$$\rightarrow B = \begin{bmatrix} -j & j \\ 1 & 1 \end{bmatrix}$$

$$B^{-1} = \frac{1}{-2j} \begin{bmatrix} 1 & -j \\ -1 & -j \end{bmatrix} =$$

the eigen vectors matrix

$$A = -\frac{1}{2j} \begin{bmatrix} 1 & -j \\ -1 & -j \end{bmatrix} \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} -j & j \\ 1 & 1 \end{bmatrix}$$

$$\Rightarrow A = -\frac{1}{2j} \begin{bmatrix} 1+j & 1-j \\ j-1 & -1-j \end{bmatrix} \begin{bmatrix} -j & j \\ 1 & 1 \end{bmatrix}$$

$$\Rightarrow A = -\frac{1}{2j} \begin{bmatrix} -j - j^2 + 1 - j & j^2 + j + 1 - j \\ -j^2 + j - 1 - j & j^2 - j - 1 - j \end{bmatrix} = \begin{bmatrix} 1+j & 0 \\ 0 & 1-j \end{bmatrix}$$

we know that $j^2 = -1$

And the eigen values is found!

E6. 8)

$$D(1+e^{2t}) = 2e^{2t} = \circ(\alpha) + (2)e^{2t}$$

$$D(1-e^{2t}) = -2e^{2t} = \circ(\alpha) + (-2)e^{2t}$$

$$A_2 = \begin{bmatrix} 0 & 0 \\ 2 & -2 \end{bmatrix}$$

(ii)

$$D(s_1) = \circ(0) + 1(2e^{2t})$$

$$D(s_2) = \circ(0) + (-1)(2e^{2t}) \rightarrow \begin{bmatrix} 0 & 0 \\ 1 & -1 \end{bmatrix}$$

(iii)

$$A_2 = \lambda I \rightarrow (A - \lambda I) = 0 \rightarrow |A - \lambda I| = 0$$

$$|A - \lambda I| = \begin{vmatrix} -\lambda & 0 \\ 2 & -2-\lambda \end{vmatrix} = 0 \Rightarrow (-2-\lambda)(-\lambda) = 0$$

$$\rightarrow \lambda(\lambda+2) = 0 \xrightarrow{\lambda_1=0} \lambda_2 = -2$$

for $\lambda_1 = 0$

$$\begin{bmatrix} 0 & 0 \\ 2 & -2 \end{bmatrix} \begin{bmatrix} e_1 \\ e_2 \end{bmatrix} = 0 \rightarrow 2e_1 - 2e_2 = 0 \rightarrow e_1 = e_2$$

first eigen vector = $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$

for $\lambda_2 = -2$

$$\begin{bmatrix} -2 & 0 \\ 2 & 0 \end{bmatrix} \begin{bmatrix} e_1 \\ e_2 \end{bmatrix} = \begin{bmatrix} -2e_1 \\ 2e_1 \end{bmatrix} = 0 \rightarrow e_1 = 0$$

we define e_2 as 1 so $\begin{bmatrix} 0 \\ 1 \end{bmatrix}$

FE 6.8, continue

(iv) eigen vectors matrix $\rightarrow B = \begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix}$

$$\bar{B}^{-1} = \frac{1}{1} \begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix}$$

$$A' = (\bar{B}^{-1} A B) = \begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 2 & -2 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix}$$

$$A' = \begin{bmatrix} 0 & 0 \\ 2 & -2 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & -2 \end{bmatrix}$$

//

We can see that the eigen values
is on the main diagonal!

E 6.10

$$s_1 = t$$

$$A(s_1) = t = v_1$$

$$s_2 = t$$

$$A(s_2) = \frac{1}{2}t^2 = v_2$$

(i)

$$v_1 = 0s_1 + 1s_2$$

$$v_2 = 0s_1 + \frac{1}{2}ts_2$$

$$A = \begin{bmatrix} 0 & 0 \\ 1 & \frac{1}{2}t \end{bmatrix}$$

(ii)

$$q = 6 + 8t$$

$$A(q) = 6t + 4t^2$$

$$\begin{bmatrix} 0 & 0 \\ 1 & \frac{1}{2}t \end{bmatrix} \begin{bmatrix} 6 \\ 8 \end{bmatrix} = \begin{bmatrix} 6 \\ 4t \end{bmatrix} \Rightarrow 6t + 4t^2 \checkmark$$

(iii)

$$A(s_1) = t + \frac{1}{2}t^2 = v_1 \Rightarrow v_1 = s_1 + \frac{1}{2}ts_2$$

$$A(s_2) = t - \frac{1}{2}t^2 = v_2 \Rightarrow v_2 = s_1 - \frac{1}{2}ts_2$$

$$A = \begin{bmatrix} 1 & 1 \\ \frac{1}{2}t & -\frac{1}{2}t \end{bmatrix}$$

E 6.11

$$(i) D(t) = \frac{dt}{dt}$$

$$D(u_1) = 6e^{5t} \quad \widetilde{v_1} \quad D(u_2) = e^{5t} + 5te^{5t} \quad \widetilde{v_2}$$

$$v_1 = 5u_1 + t u_2 \quad v_2 = u_1 + 5u_2$$

we can see that v_1 and v_2 are calculated from u_1 and u_2 by coefficients that are numbers. So the transformation D is a linear transformation.

(ii)

As we had v_1 and v_2 in before the combination of u_1 and u_2 . we can find the transformation matrix by the coefficients

As :

$$A = \begin{bmatrix} 5 & 1 \\ 0 & 5 \end{bmatrix}$$

(iii) From the formula $Az = \lambda z$ we can get

$$(A - \lambda I)z = 0 \Rightarrow |A - \lambda I| = 0$$

$$\begin{vmatrix} 5-\lambda & 1 \\ 0 & 5-\lambda \end{vmatrix} = 0 \Rightarrow (5-\lambda)^2 - 0 = 0 \Rightarrow \lambda = 5$$

The eigen vectors: $\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} e_1 \\ e_2 \end{bmatrix} = 0 \Rightarrow e_2 = 0$

so the eigen vectors $\begin{bmatrix} e_1 \\ 0 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 1 \\ 0 \end{bmatrix}$